Qiyu Dai

No.5 Yiheyuan Road, Beijing, China

② Contact: (+86) 13534865062

□ qiyudai@pku.edu.cn

□ https://daiqy.github.io/

Education

Sept. 2024 - Peking University, Beijing, China

Present Ph.D. in Intelligence Science and Technology

Advisor: Prof. Baoquan Chen

Sept. 2019 - Peking University, Beijing, China

Jun. 2022 M.Eng. in Computer Technology

Advisors: Prof. He Wang, Prof. Qi Jing

Sept. 2015 - Wuhan University, Wuhan, China

Jun. 2019 B.Eng. in Energy Chemical Engineering with Minor in Computer Science

Advisor: Prof. Qin Zou

Research Interests

3D/4D Reconstruction, Neural Rendering, World Simulator

Publications

* denotes equal contribution, † denotes corresponding author.

Representative Publications

2025 RainyGS: Efficient Rain Synthesis with Physically-Based Gaussian Splatting Qiyu Dai*, Xingyu Ni*, Qianfan Shen, Mengyu Chu†, Wenzheng Chen†, Baoquan Chen†

IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)

2024 4D-Rotor Gaussian Splatting: Towards Efficient Novel View Synthesis for Dynamic Scenes

Yuanxing Duan*, Fangyin Wei*, **Qiyu Dai**, Yuhang He, Wenzheng Chen†, Baoquan Chen†

ACM SIGGRAPH Conference Papers

2023 GraspNeRF: Multiview-based 6-DoF Grasp Detection for Transparent and Specular Objects Using Generalizable NeRF

Qiyu Dai*, Yan Zhu*, Yiran Geng, Ciyu Ruan, Jiazhao Zhang, He Wang† *IEEE International Conference on Robotics and Automation (ICRA)*

2022 Domain Randomization-Enhanced Depth Simulation and Restoration for Perceiving and Grasping Specular and Transparent Objects

Qiyu Dai*, Jiyao Zhang*, Qiwei Li, Tianhao Wu, Hao Dong, Ziyuan Liu, Ping Tan, He Wang†

European Conference on Computer Vision (ECCV)

All Other Publications

2024 Open6DOR: Benchmarking Open-instruction 6-DoF Object Rearrangement and A VLM-based Approach

Yufei Ding*, Haoran Geng*, Chaoyi Xu, Xiaomeng Fang, Jiazhao Zhang, Songlin Wei, Qiyu Dai, Zhizheng Zhang, He Wang†

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Oral

2024 STOPNet: Multiview-based 6-DoF Suction Detection for Transparent Objects on Production Lines

Yuxuan Kuang*, Qin Han*, Danshi Li, Qiyu Dai, Lian Ding, Dong Sun, Hanlin Zhao, He Wang†

IEEE International Conference on Robotics and Automation (ICRA)

2021 Edit Like A Designer: Modeling Design Workflows for Unaligned Fashion Editing

Qiyu Dai, Shuai Yang, Wenjing Wang, Wei Xiang, Jiaying Liu† ACM International Conference on Multimedia (MM)

2019 Robust Lane Detection From Continuous Driving Scenes Using Deep Neural Networks

Qin Zou, Hanwen Jiang, Qiyu Dai, Yuanhao Yue, Long Chen, Qian Wang† IEEE Transactions on Vehicular Technology

Selected Research Experience

Jun. 2023 – Visual Computing and Learning (VCL) Lab, Peking University

Present Ph.D Student, Research Assistant

Advisors: Prof. Baoquan Chen, Prof. Wenzheng Chen, Prof. Mengyu Chu

Research: Building world simulators with 3D/4D reconstruction, physics, and generative models, including 4DRotorGS [SIGGRAPH'24] for dynamic novel view synthesis, and RainyGS [CVPR'25] for realistic dynamic rain effects in real-world scenes.

Nov. 2022 - Embodied AI Center, Beijing Academy of Artificial Intelligence

Jun. 2023 Research Intern

Advisor: Prof. He Wang

Research: Worked on Neural Radiance Fields for robotics, developing GraspNeRF [ICRA'23] for material-agnostic grasp detection in 90ms from sparse multi-view images.

Mar. 2021 - Embodied Perception and InteraCtion (EPIC) Lab, Peking University

Jun. 2023 Research Assistant

Advisor: Prof. He Wang

Research: Proposed DREDS [ECCV'22], the first to show that physics-based depth sensor simulation and domain randomization significantly bridge the sim-to-real gap in material-agnostic depth estimation and grasping — one early tech origin of GALBOT

Services

Reviewer

Conference CVPR, ECCV, ICCV, AAAI, ICRA, IROS

Journal	SIGGRAPH,	IEEE	Robotics	and	Automation	Letters
Reviewer						

Invited Talks

- Jan. 2025 Enhancing Gaussian Splatting with Dynamics Tsinghua AGI Seminar
- Dec. 2024 **Physics-based Open-World Rain Synthesis** Huawei Cloud
- Aug. 2022 Depth Simulation and Restoration for Specular and Transparent Objects ECCV Pre-Workshop, China Society of Image and Graphics (CSIG)

Awards and Honors

- 2022 Outstanding Master's Thesis, Peking University
- 2021 Social Work Award, Peking University
- 2020 Merit Student Award, Peking University
- 2019 Excellent Graduate Award, Wuhan University
- 2018 The Beijing CM Scholarship, Wuhan University
- 2017 The Goaland Scholarship, Wuhan University
- 2017 Merit Student Award, Wuhan University
- 2016 The Cnhili Scholarship, Wuhan University
- 2016 The Relations Instruments Scholarship, Wuhan University
- 2016, 2018 Excellent Student Award, Wuhan University
- 2016 2018 Excellent Student Scholarship, Wuhan University