Estimating Fractional Brownian Motion With Noise

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Introduction

Suppose we have some unknown fBM with stochastic volatility, X_t , and some process with added noise that we are able to observe: $Y_t = X_t + \rho Z_t$. We would like to be able to extract the signal from the noise, and to somehow estimate both H and σ . To do so, we will consider weighted averages of Y_t at different time-points to eliminate the noise. Estimators of H and the integrated volatility have been previously shown for fBM without noise and standard Brownian motion with noise; the main result of this project is to combine both generalizations.

Background and Setup

► The Riemann-Liouville fractional Brownian motion with Hurst Index *H* is the process given by the stochastic integral

$$B_t^H := \int_0^t (t-s)^{H-\frac{1}{2}} dB_s.$$

- ► Measurement noise will be considered as random normal variables with variance ρ^2 .
- ► We consider the following process:

$$Y_t = X_0 + \int_0^t b_s ds + K_H^{-\frac{1}{2}} B_t^H + \rho Z_t,$$

where $\int_0^t b_s ds$ is some drift process, $K_H^{-\frac{1}{2}}$ is a normalizing constant, and $(Z_t)_{t>0}$ are i.i.d. N(0,1) variables.

Pre-Averaging

We attempt to remove the error from the process by considering weighted averages of the increments of Y_t to try and smooth out the random noise. The variation from these *pre-averages* are then used to construct estimators for H and $\int_0^T \sigma^2 ds$. Formally, for $g:[0,1] \to \mathbb{R}$, some constant θ , and some stochastic process W_t , put

$$k_{n} = \frac{n^{\kappa}}{\theta}, \ g_{j}^{n} = g\left(\frac{j}{k_{n}}\right)$$

$$\overline{W}(g)_{i}^{n} = \sum_{j=1}^{k_{n}-1} g_{j}^{n} \left(W_{\frac{i+j-1}{n}} - W_{\frac{i+j-2}{n}}\right) = \sum_{j=1}^{k_{n}-1} g_{j}^{n} \Delta_{i+j-1}^{n} W$$

$$\widehat{W}(g)_{i}^{n} = \sum_{j=1}^{k_{n}} \left(g_{j}^{n} - g_{j-1}^{n}\right)^{2} \left(\Delta_{i+j-1}^{n} W\right)^{2} = \sum_{j=1}^{k_{n}} \left(\Delta g_{j}^{n}\right)^{2} \left(\Delta_{i+j-1}^{n} W\right)^{2}.$$
We n

Main Theorem

Given some fBM with measurement error,

$$Y_t = X_t + \rho Z_t$$

if we have the following conditions,

- 1. $f: \mathbb{R}^L \to \mathbb{R}$ is C^2 with all partial derivatives up to order 2 of at most polynomial growth.
- 2. $g:[0,1] \to \mathbb{R} \text{ is } C^2$.
- 3. b, σ are of size 1 (that is, $||b_s||_{L_p}$, $||\sigma_s||_{L_p}$ are bounded) and adapted.
- 4. σ is L^2 -continuous.
- 5. $\kappa \in (\frac{2H}{2H+1}, 1)$.

then we get the following convergence:

$$V(g)_{T}^{n,f}(Y) = \frac{1}{n} \sum_{i=1}^{\lfloor nT \rfloor} f\left(\frac{\overline{Y}(g)_{i}^{n}}{(k_{n}/n)^{H}}, \frac{\widehat{Y}(g)_{i}^{n}}{(k_{n}/n)^{2H}}\right) \xrightarrow{\mathbb{P}} \int_{0}^{T} \mu_{f}\left(\sigma_{s}^{2} \eta\left(g\right), \Theta^{2} \rho^{2} \int_{0}^{1} g'(r)^{2} dr\right) ds$$

where

$$\Theta = \begin{cases} 0 & \kappa \neq \frac{2H}{2H+1} \\ \theta & \kappa = \frac{2H}{2H+1} \end{cases}$$

$$\eta(g) = 2H \int_0^1 g(x) \left(g(1)(1-x)^{2H-1} dx + \int_x^1 (y-x)^{2H-1} g'(y) dy \right) dx$$

Sketch of the Proof

We make a series of adjustments to $V(g)_T^{n,f}(Y)$ to get closer to our final result. We first remove the drift: if $U_t = K_H^{-\frac{1}{2}} B_t^H + \rho Z_t$,

$$\lim_{n\to\infty} \mathbb{E}\left[\left|V(g)_T^{n,f}(Y) - V(g)_T^{n,f}(U)\right|\right] = 0.$$

Next, we *truncate* the domain of integration in the stochastic integral to ϵ of where we begin averaging; a truncated increment of fBM is defined as

$$\Delta_{i+j-1}^{n,\epsilon}B_t^H=\int_{rac{i}{n}-\epsilon}^{rac{i+j-1}{n}}\left[\left(rac{i+j-1}{n}-s
ight)^{H-rac{1}{2}}-\left(rac{i+j-1}{n}-s
ight)^{H-rac{1}{2}}
ight]\sigma_sdB_s.$$

With this, we get

$$\limsup_{n\to\infty} \mathbb{E}\left[\left|V(g)_T^{n,f}(U) - \frac{1}{n}\sum_{i=\lfloor n\epsilon\rfloor+1}^{\lfloor nT\rfloor} f\left(\frac{\overline{U}(g)_i^{n,\epsilon}}{(k_n/n)^H}, \frac{\widehat{U}(g)_i^{n,\epsilon}}{(k_n/n)^{2H}}\right)\right|\right] < C\epsilon$$

We now discretize the volatitlity by showing that

$$\lim_{\epsilon \to 0} \lim_{n \to \infty} \mathbb{E} \left[\left| \frac{1}{n} \sum_{i=\lfloor n\epsilon \rfloor + 1}^{\lfloor nT \rfloor} \left[f\left(\frac{\overline{U}(g)_i^{n,\epsilon}}{(k_n/n)^H}, \frac{\widehat{U}(g)_i^{n,\epsilon}}{(k_n/n)^{2H}} \right) - f\left(\frac{\sigma_{\frac{i}{n} - \epsilon} \overline{B^H}(g)_i^{n,\epsilon} + \rho \overline{Z}(g)_i^n}{(k_n/n)^H}, \frac{\rho^2 \widehat{Z}(g)_i^n}{(k_n/n)^{2H}} \right) \right] \right] = 0$$

Sketch of the Proof (Cont.)

We now center to the conditional expectation:

$$\frac{1}{n} \sum_{i=\lfloor n\epsilon \rfloor+1}^{\lfloor nT \rfloor} \left[f\left(\frac{\sigma_{\frac{i}{n}-\epsilon} \overline{B^H}(g)_i^{n,\epsilon} + \rho \overline{Z}(g)_i^n}{(k_n/n)^{2H}}, \frac{\rho^2 \widehat{Z}(g)_i^n}{(k_n/n)^H} \right) - \mathbb{E} \left[f\left(\frac{\sigma_{\frac{i}{n}-\epsilon} \overline{B^H}(g)_i^{n,\epsilon} + \rho \overline{Z}(g)_i^n}{(k_n/n)^H}, \frac{\rho^2 \widehat{Z}(g)_i^n}{(k_n/n)^{2H}} \right) \middle| \mathcal{F}_{\frac{i-1}{n}} \right] \right] \xrightarrow{\mathbb{P}} 0$$

Once we compute the expectation and take limits $(n \to \infty, \epsilon \to 0)$, we arrive at what we wanted.

Example

TODO

Simulations

TODO code vaguely works? maybe prob not ill do it later

Acknowledgements

TODO

contact info TODO