A:twoDMotion
A:cartSys
A:cartSysR
A:yAxisDir
A:startOrigin
DD:positionIX
DD:positionIY
DD:frequencyDD
DD:angFrequencyDD
DD:periodSHMDD
TM:acceleration
TM:velocity
TM:NewtonSecLawMot
TM:NewtonSecLawRotMot
GD:velocityIX
GD:velocityIY
GD:accelerationIX
GD:accelerationIY
GD:hForceOnPendulum
GD:vForceOnPendulum
GD:angFrequencyGD
GD:periodPend
IM:calOfAngularDisplacement
FR:inputValues
FR:verifyInptVals
FR:calcAngPos
FR:outputValues
NFR:correct
NFR:portable