

# **IoT Soft Box Starter Kit**

User Manual for iotsoftbox-mqtt library

Arduino Edition





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# 1. Introduction

# 1.1. Document purpose

This document is a complete guide to IoT Soft Box SDK for Arduino presenting the following:

- Overview
- Getting started
- Detailed Features
- Additional Information

## 1.2. Reference documents

#	Origin	Title
1	Orange	Datavenue Live Objects - complete guide (1.4.1.)



### 2. Overview

## 2.1. What is Live Objects?

Live Objects is one of the products belonging to Orange Datavenue service suite.

**Live Objects** is a software suite for IoT / M2M solution integrators offering a set of tools to facilitate the interconnection between **devices** or **connected « things »** and **business applications**.

The main features provided are:

- Connectivity interfaces (public and private) to collect data, send command or notification from/to IoT/M2M devices,
- Device management (supervision, configuration, resources, firmware, etc.),
- Message Routing between devices and business applications,
- Data Management and Data Storage with Advanced Search features.

Read <u>Datavenue Live Objects - complete guide</u> to have a full description of services and architecture provided by Live Objects platform.

### 2.2. Arduino

Arduino is a well known platform for educational purpose. It is also widely used for testing and prototyping projects, so Orange worked on a new version of the Live Objects iotsoftbox-mqtt library compatible with Arduino platforms.

Also, as Arduino is open-source hardware, many manufacturers are building compatible variant of original Arduino designs. One good example is the <a href="Mediatek LinkIt-ONE">Mediatek LinkIt-ONE</a>. It uses a Mediatek MT2502A SoC which supports GSM/GPRS and Wi-Fi as communication connectivities. This card provides good connectivity and enough RAM for security functions.

### 2.3. IoT Soft Box

The Live Objects IoT Soft Box is a library to help developers make easy usage of Live Objects platform.



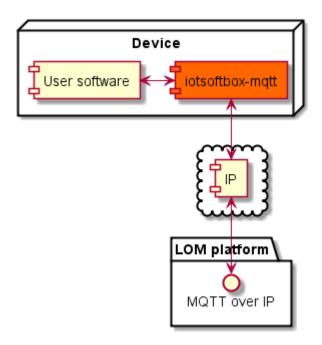


Figure 1 – IoT Soft Box integration in a system

The Live Objects platform is able to manage different formats (MQTT, HTTP, ...) and several low level protocols (SMS, IP, ...). The Live Objects IoT Soft Box is designed to work with MQTT over TCP w/wo TLS.

The IoT Soft Box can run on devices connected to Internet through Ethernet, Wifi, GPRS or any other IP connection.

The library (iotsoftbox-mqtt) is linked to the following third-party existing libraries:

- Embedded MQTT C/C++ Client Libraries (eclipse paho). This library is available here.
- <u>JSMN</u>, a simple C library only used to parse the received JSON messages. The JSMN is available here.
- Mbed TLS is used to include cryptographic and SSL/TLS capabilities in embedded devices.



# 3. Getting started

## 3.1. Hardware Environment and compatibility

As for today, we are compatible with the following equipments:

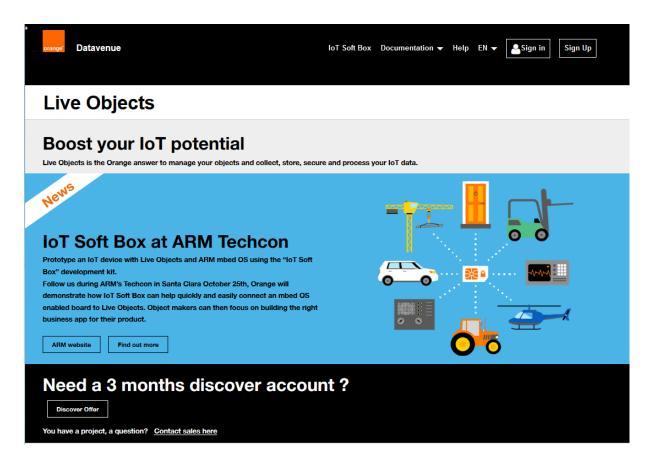
- Mediatek LinkIt One: Other cards may be compatible but were not tested.

### 3.2. Access to Live Objects

### 3.2.1. Account creation

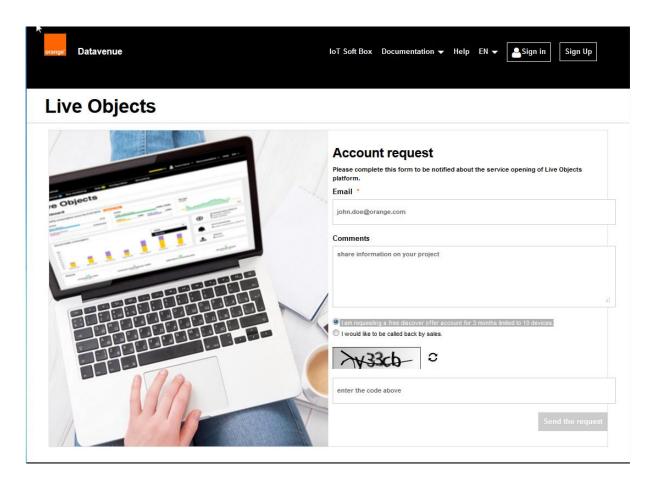
In order to use Live Objects, you need to have a dedicated account on the service.

1. Go to Live Objects portal (<a href="https://liveobjects.orange-business.com/">https://liveobjects.orange-business.com/</a>).

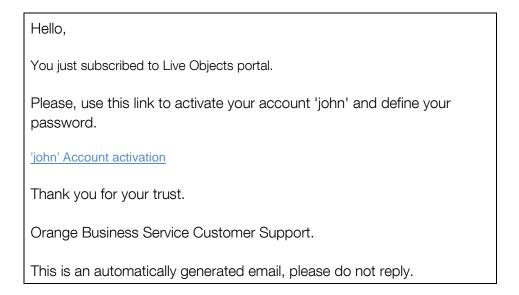




2. Click on 'Discover Offer' button (or Sign Up) and fill the form, checking option 'I am requesting a free discover offer account for 3 months limited to 10 devices'.

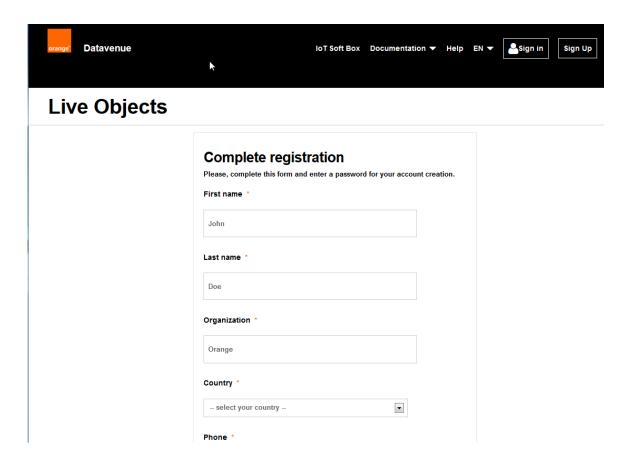


3. Then you will receive an e-mail to activate your Live Objects account.





4. Follow the link, fill the form, and click on 'Validate'.

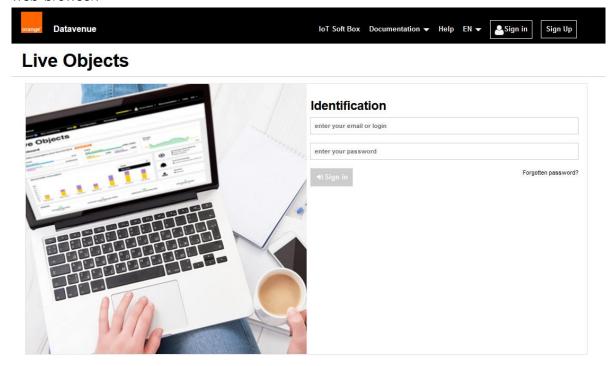


5. Now, you can go back to Datavenue Live Objects portal and sign in. Once logged, select the 'configuration' tab to create a new API key.



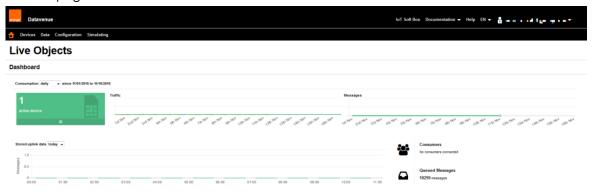
### 3.2.2. Log in

To log in to Live Objects web portal, connect to <u>liveobjects.orange-business.com</u> using your web-browser:



- 1. Fill the "Log in" form with your credentials:
  - your email address,
  - the password set during the activation phase,
- 2. Then click on the "Log in" button.

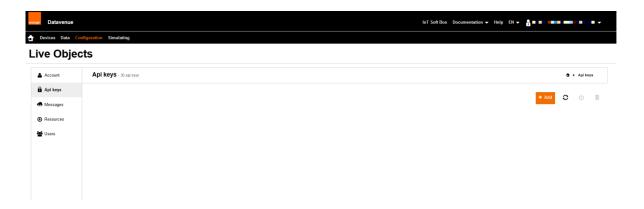
If the credentials are correct, a success message is displayed and you are redirected to your "home" page:





### 3.2.3. API Key creation

To get a device or an application communicating with Live Objects, you will need to create an API Key in the "Configuration" menu. On the left menu, click on "Api keys" and create a new API key. This key will be necessary to set up a connection with the public interfaces (MQTT and REST) of Live Objects.



As a security measure, you cannot retrieve the API Key again after closing the API key creation results page. So, note it down to work with the MQTT client, during the scope of this getting started.





## 3.3. Live Objects IoT examples using iotsoftbox-mqtt library

### 3.3.1. Introduction

A good way to discover Live Objects features is to use our Live Objects IoT examples.

When running on a development board, the embedded 'basic' application:

- Connects to <u>Datavenue Live Objects Plaftorm</u>, using:
  - o an optional secure connection (TLS)
  - o the Live Objects mode: <u>Json+Device</u>
- Publishs
  - o The current Status/Info
  - o The current Configuration Parameters
  - o The current Resources
- Subscribes to Live Objects topics to receive notifications
  - o Configuration Parameters update request
  - o Resource update request
  - Command request
- then the application waits for an event:
  - From Live Objects platform to:
    - Update "Configuration Parameters"
    - Update one "Resource": message or image
    - Process a "Command": RESET or LED
  - o From application simulating some data publish operations.
  - And if the connection is lost, restart at the first step trying to connect again to the Live Objects platform.

### Note:

Live Objects features (status, configuration, collected data, commands, resources) can be implemented or not according to the characteristics of your board (mainly the RAM size).

		LinkIt One
Hardware	Flash	16 MB
	RAM	4 MB
Live Objects	Status	Yes
Feature	Configuration	Yes
	Collected Data	Yes
	Commands	Yes
	Resources	Yes
Security	TLS	Yes



### 3.3.2. Packages dependences

The example applications have been built and tested with the following packages:

#### 1) Mbed-tls, version 2.1.6

https://github.com/ARMmbed/mbedtls.git/#c60c31226fa746a363acb5a92ebb5d61d0d9de06

Modified files:

- platform.h
- config.h

Added files:

- \_config\_all\_disabled.h
- \_config\_mdk.h
- \_config\_mdk\_min.h
- \_config\_samd.h
- \_entropy\_poll\_alt.c

#### 2) Paho MQTT embedded-c (MQTTPacket and MQTTClient)

https://github.com/eclipse/paho.mqtt.embeddedc/#02323e1093f0414c1adcf03559e03a890b5f3a84

3) jsmn

https://github.com/zserge/jsmn/#1682c32e9ae5990ddd0f0e907270a0f6dde5cbe9

4) LiveObjects-iotSoftbox-matt-core (the Delivery1.0 release of library on github)

https://github.com/Orange-OpenSource/LiveObjects-iotSoftbox-mqtt-core.git/#b18c7e1e0d7d2281848e22acbe45aa45c7d8d9af

Note that these packages are included in the ZIP file of the iotsoftbox-mgtt library.

## 3.3.3. Configure workstation

Using the Arduino IDE allows to abstract the host platform.

This example is given for a Generic Arduino device as a target. Step 2 is only if you're using a Mediatek LinkIt<sup>tm</sup> ONE as a target.

1. Install the Arduino IDE (tested version: 1.8.1)

Get it from : <a href="https://www.arduino.cc/en/Main/Software">https://www.arduino.cc/en/Main/Software</a>

- 2. Launch Arduino IDE
- 3. Install additional packages/libraries (to use your boards and shields)
- If you're using the LinkIt One board, you will need to download a SDK



Get it from : https://docs.labs.mediatek.com/resource/linkitone/en/getting-started/get-started-on-windows/install-the-arduinoide-and-linkit-one-sdk

4. Install the iotsoftbox-mqtt library

To install the library follow the procedure :

- Download the ZIP file from <a href="https://github.com/Orange-OpenSource/LiveObjects-iotSoftbox-mqtt-arduino">https://github.com/Orange-OpenSource/LiveObjects-iotSoftbox-mqtt-arduino</a>
- Open your Arduino IDE and add this library Sketch -> Include Library -> Add .ZIP Library and Select the zip file (iotsoftbox\_mqtt\_arduino.zip)
- Update the iotsoftbox library configuration files located in the directory

<Arduino user dir>\libraries\iotsoftbox mqtt arduino\src\config

- o *liveobjects\_dev\_params.h* to set your Live Objects Tenant API key.
- Liveobjects\_dev\_config.h, optionally to change some parameters to tune the iotsoftbox library.
- Open example sketch File -> Examples -> LiveObjects iotsoftbox library -> liveobjects\_sample\_basic\_mdk
- For LinkIt One board, edit liveobjects\_sample\_basic\_mdk.h file to set your SIM parameters: GPRS\_APN, GPRS\_USERNAME, GPRS\_PASSWORD
- Don't forget to select the correct board
  - o Mediatek LinkIt One:
    - Tools -> Boards -> LinkIt One

Tools -> Programmer -> LinkIt Firmware Updater

#### 3.3.4. Build

To build an example in the IDE, just use Sketch -> Verify/Compile.

#### 3.3.5. Launch

#### 3.3.5.1. Upload the sample on your Arduino (or Mediatek) through the IDE

- Connect your board to your computer USB port running the Arduino IDE.
- Check that the correct board is chosen in Tools -> Boards.
- Verify that the IDE is using the correct COM port (Tools -> Port).
- To upload a program to your board: **Sketch** -> **Upload**.

### 3.3.5.2. Excute the application

After uploading the board, click on 'Serial Monitor' button (or CTRL+SHIFT+M).



```
| Serial Monitor | Seri
```

The following window is open (with Mediatek Linklt One board):

```
AMBUTHO MENSIC SAMPLE VOS.02
Start after S secondes ..
AMBUTHO MEN BASIC SAMPLE VOS.02
Start after S secondes ..
AMBUTHO MEN BASIC SAMPLE VOS.02
START after S secondes ..
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AMBUTHO MEN BASIC SAMPLE VOS.02
START after S secondes ..

AMBUTHO MEN BASIC SAMPLE VOS.02
START After S secondes ..

AMBUTHO MEN BASIC SAMPLE VOS.02
START S
```

### 3.3.5.3. Application Monitoring/Testing

There is several ways to monitor or/and to test the embedded sample application:

- Go to your Live Objects user account on Live Objects Portal.
- Go to Live Objects Swagger User Interface.



• Serial Terminal is used by embedded sample application to print debug/trace messages.

From Live Objects you can see your board, check the status, check/change configuration parameters, send commands, update resources and more.

To find out more about Live Objects capabilities, see: Live Objects User manual.



### 4. Detailed Features

### 4.1. General

The Live Objects IoT Soft Box is a library providing features to connect embedded device to the Datavenue Live Objects platform.

Today, a library dedicated to Arduino boards is available <u>here</u>, library called **LiveObjects-iotSoftbox-mqtt-arduino**.

The **LiveObjects-iotSoftbox-mqtt** library provides APIs to help developers create their embedded IoT applications. The API is written in C.

The **LiveObjects-iotSoftbox-mqtt** library uses Live Objects 'Device' mode: a single MQTT connection is associated with the device, and JSON messages can be exchanged to support various *Device Management* and *Data* features. See "Device" mode paragraph in Live Objects User Manual to have a full description.

IoT Soft Box available features are:

- Connection to the user tenant of Live Objects platform w/wo security (TLS)
- Device Management
- Status
- Configuration Parameters
- Collected data
- Commands
- Resources

## 4.2. Connectivity

The endpoint (Live Objects server) is defined at compile time.

The default values are defined in the iotsoftbox-mqtt library as:

- Server Name: liveobjects.orange-business.com
- IP Address: 84.39.42.214 or 84.39.42.208
- TCP Port:
  - o 1883 for non SSL connection (without security),
  - o 8883 for TLS/SSL connection.
- If TLS is enabled.
  - o Public Root Certificate
  - o Certificate Common Name 'm2m.orange.com'

Therefore the user has only to define in the main file:

• Tenant *ApiKey* parameter



• if the TLS is enabled (value: 1) or not (value: 0)

### To enable security:

You just have to set the SECURITY\_ENABLED flag to 1 in liveobjects\_dev\_param.h

When TLS is enabled, security parameters must be defined/updated in the following header file liveobjects\_dev\_security.h.

Also if necessary, the endpoint parameters can be overwritten by parameters defined in this user header file: **liveobjects\_dev\_params.h**.

```
/* Only used to overwrite the LiveOjects Server settings :*/
/* IP address, TCP port, Connection timeout in milliseconds.*/
#define LOC_SERV_IP_ADDRESS "XXXX"
#define LOC_SERV_PORT XXXX
#define LOC_SERV_TIMEOUT XXXX
```

#### 4.3. Device

Within Datavenue Live Objects platform, the device is identified by its URN:

```
urn:lo:nsid:{namespace}:{id}
```

The device has to specify:

- Namespace identifier, used to avoid conflicts between various families of identifier (ex: device model, identifier class "imei", msisdn", "mac", etc.).
   Should preferably only contain alphanumeric characters (a-z, A-Z, 0-9).
- Id (ex: IMEI, serial number, MAC address, etc.)
  Should only contain alphanumeric characters (a-z, A-Z, 0-9) and/or any special characters amongst: \_ | + and must avoid # / !.

These two parameters are specified in the user header file liveobjects\_dev\_params.h:



```
/* Default LiveObjects device settings : name space and device identifier*/
#define LOC_CLIENT_DEV_NAME_SPACE "LiveObjectsDomain"

#define LOC_CLIENT_DEV_ID "LO_softboxlinux_01"
```

### 4.4. Thread Models: Multi-thread or single thread.

The library offers both thread models to build the user embedded application:

- 1. Single thread. The user application has to schedule all tasks (or to call functions) in one same thread.
- 2. Multi-thread: A function of iotsoftbox-mqtt library allows the creation/activation of specific thread:
  - o To maintain the TCP connection (w/wo TLS) to the Live Objects platform
  - To process all events from/to the Live Objects platform.

Note: that our samples running with Arduino uses the single-thread model. The multi-thread model is available in our ARM mbed and Linux libraries.

### 4.5. Status

Status gives information about the device states, i.e. Software version, IP address, connection state, statistic counters.

#### 4.5.1. Attach a set of 'status' data

At any moment, the application can attach one or many set (or group) of 'status' data by calling the function:

In the sample application:

```
appv_hdl_status = LiveObjectsClient_AttachStatus(appv_set_status, SET_STATUS_NB);
```

The set of 'status' data is defined by an array of LiveObjectsD Data t elements. For example:



```
{ LOD_TYPE_STRING_C, "sample_message", appv_status_message, 1 }
};
```

### 4.5.2. Push a set of 'status' data

When 'status' data change, the application must call the LiveObjectsClient\_PushStatus() function to notify the Datavenue Live Objects platform (publishing a MQTT message on the dev/info topic):

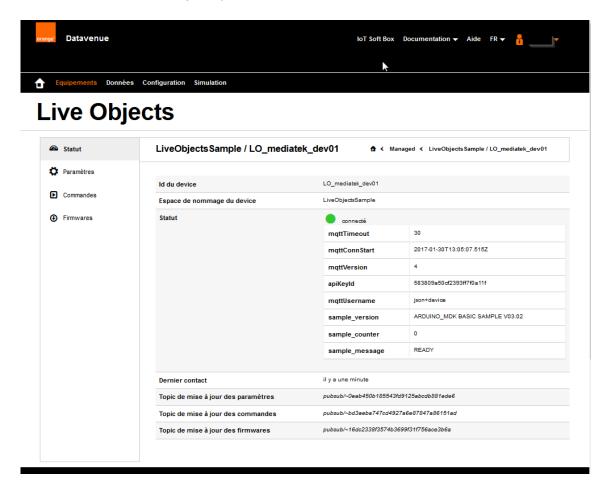
```
ret = LiveObjectsClient_PushStatus(appv_hdl_status);
```

#### Note:

• if the status data is attached before connecting to the platform, the 'status' data will be automatically pushed as soon as the MQTT connection is established with the Live Objects platform.

### 4.5.3. Use of Live Objects portal to view/check the set of status

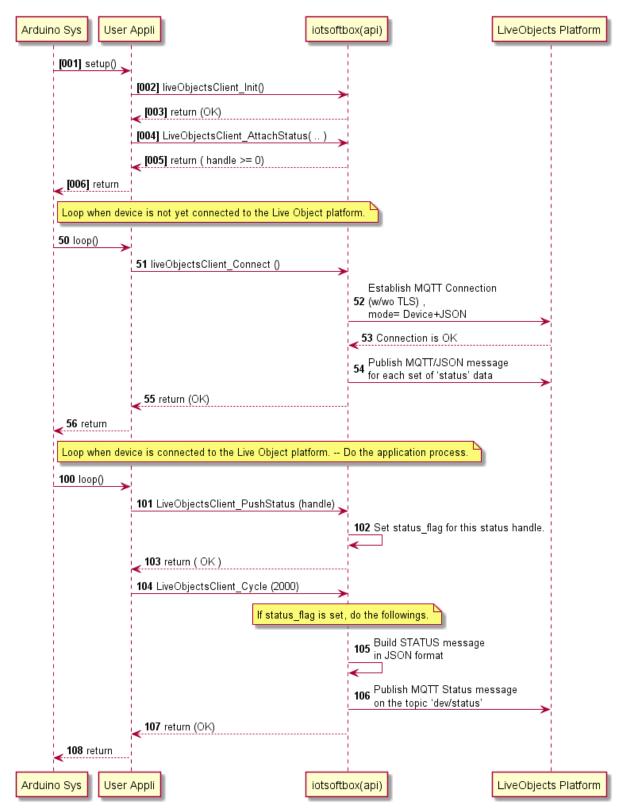
On the Datavenue Live Objects portal, the user can check the 'status' of its connected device:





# 4.5.4. Sequence Diagram







### 4.6. Parameters

The device can declare one or many Live Objects "parameters" of device configurations.

Then, Live Objects can track the changes of the current value of device parameters, and allow users to set different target values for those parameters. Live Objects will then update the parameters on the device once it's connected and available.

### 4.6.1. Attach a set of configuration parameters

Application can declare/attach only one set of configuration parameters to the iotsoftbox-mqtt library by calling the function:

In the sample application:

```
ret = LiveObjectsClient_AttachCfgParams(appv_set_param, SET_PARAM_NB,
    main_cb_param_udp);
```

Where:

1. The set of 'parameters' data is defined by an array of LiveObjectsD\_Param\_t elements. In the sample application:

And the configuration parameters are defined and initialized as:



```
// a structure containing various kind of parameters (char[], int and float)
struct conf_s {
    char name[20];
    int32_t threshold;
    float gain;
} appv_conf = { "TICTAC", -3, 1.05 };
```

2. The application specifies the callback function (i.e. paramudpdatecb) which will be called when a request is received from the Live Objects platform to change the value of parameter.

```
int main_cb_param_udp(const LiveObjectsD_Param_t *param_ptr, const void *value,
       int len) {
       if (param_ptr == NULL) {
              return -1;
       switch (param_ptr->parm_uref) {
       case PARM_IDX_NAME: {
              if (paramIsOk) {
                     return 0;
              break;
       case PARM IDX TIMEOUT: {
              if (paramIsOk) {
                     return 0;
              break;
       case PARM IDX THRESHOLD: {
              if (paramIsOk) {
                      return 0;
              }
              break;
       case PARM_IDX_GAIN: {
              if (paramIsOk) {
                     return 0;
              break;
       return -1;
```

With the Switch statement you can adapt the behavior of your app for each param.

#### Notes:

- When the user callback returns 0 to accept the new value for a 'primitive' parameter (integer, float ...), the iotsoftbox-mqtt library updates the value of this configuration parameter. But for the 'c-string' parameter, the user application has to copy the value in the good memory place (with the good size).
- The 'parameters' data will be automatically pushed as soon as the MQTT connection is established with the LiveObjects platform.



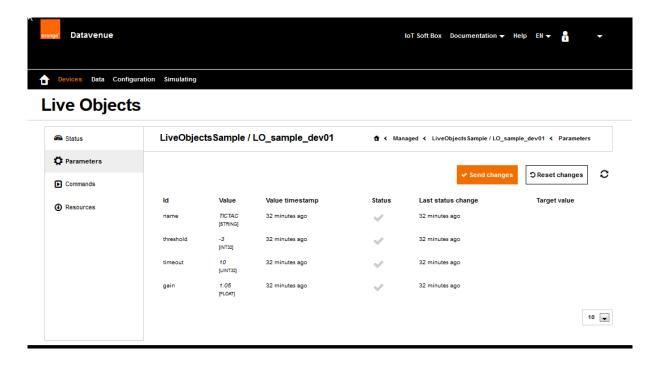
# 4.6.2. Push a set of configuration parameters

The application can call the LiveObjectsClient\_PushCfgParams() function to notify the Datavenue Live Objects platform (publishing a MQTT message on the dev/cfg topic) that the current configuration is updated:

int LiveObjectsClient\_PushCfgParams(void);

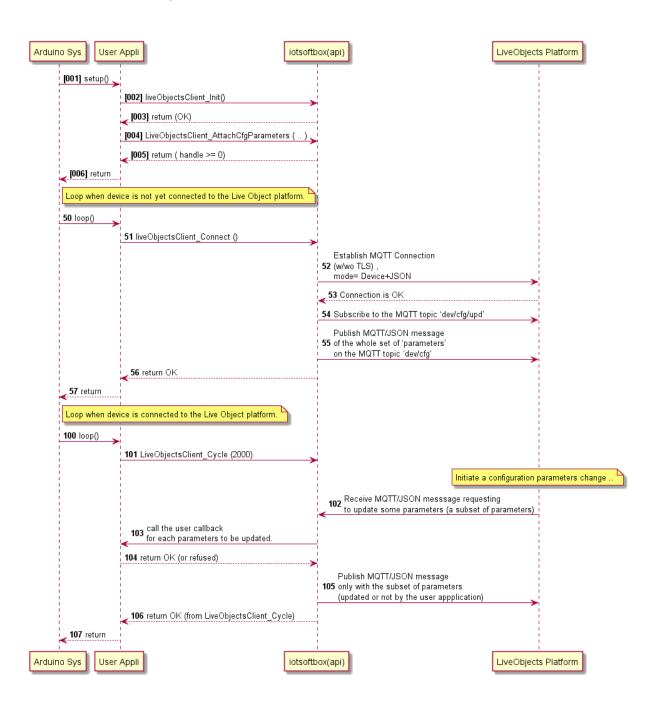
### 4.6.3. Use of Live Objects Portal to set/change parameters

On the Datavenue Live Objects portal, the user can check the 'Parameters' of its connected device, but also change these initial values:





### 4.6.4. Sequence Diagram



### 4.7. Collected Data

The device can declare one or many Live Objects "collected data".

A collected data is defined by:

- streamld: identifier of the timeseries this message belongs to.
- Value: a set of user values (i.e.: temperature ...)
- Additional (and optional) information associated to this data stream:



- model: a string identifying the schema used for the "value" part of the message, to avoid conflict at data indexing,
- o tags: list of strings associated to the message to convey extra-information.
- At each message published to the Live Objects platform, optional information
  - timestamp: data/time associated with the message (using ISO 8601 format).
     If the timestamp is not specified, the data will be timestamped at the receipt by the Live Objects platform.
  - o **latitude, longitude**: details of the geo location associated with the message (in degrees).

#### 4.7.1. Attach a set of collected data

At any moment, application can declare/attach one or many set of 'collected data' to the iotsoftbox-mqtt library by calling the function:

```
int LiveObjectsClient_AttachData(
    uint8_t prefix,
    const char* stream_id,
    const char* model, const char* tags,
    const LiveObjectsD_GpsFix_t* gps_ptr,
    const LiveObjectsD_Data_t* data_ptr, int32_t data_nb);
```

When there is no error, the function returns a handle (positive or null value) of the collected data stream.

In the sample application:

Where:



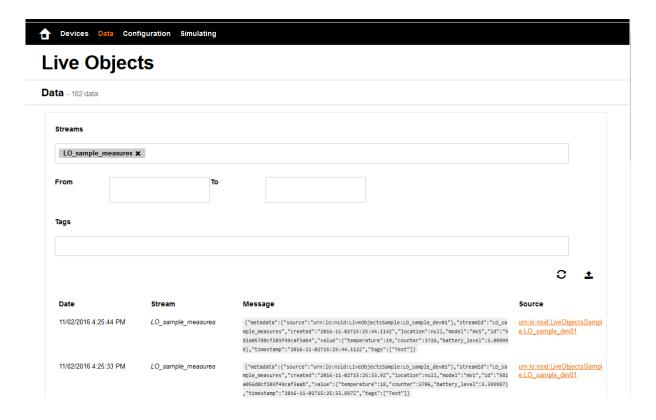
#### 4.7.2. Push the set of collected data

When 'collected data' must be *published*, the application must call the LiveObjectsClient\_PushData () function to notify the Datavenue LiveObjects platform (publishing a MQTT/JSON message on the dev/data topic):

LiveObjectsClient\_PushData(appv\_hdl\_data);

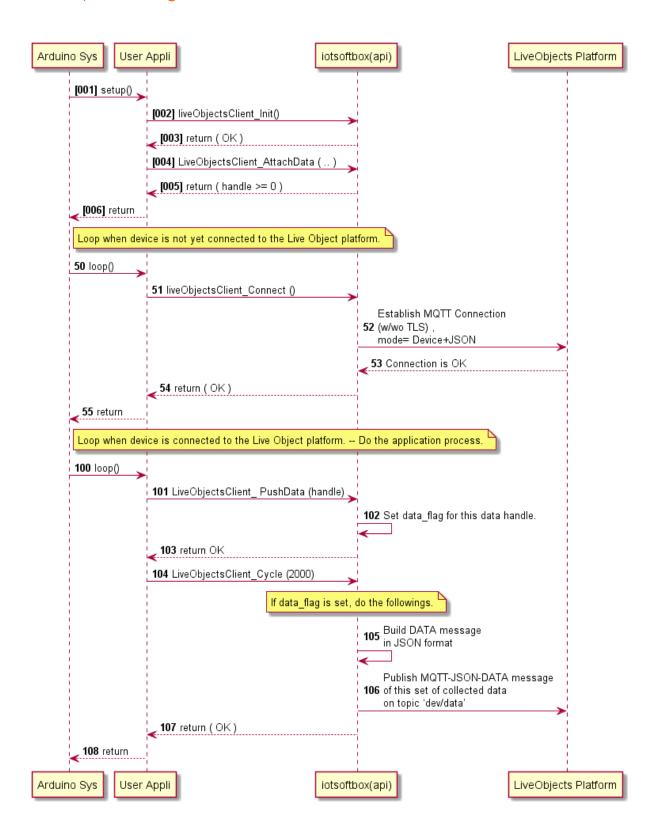
### 4.7.3. Use of Live Objects Portal to view data stream

On the Datavenue Live Objects portal, the user can check the 'Collected Data' published by its connected device (here, filter is set to get only stream = LO\_sample\_measures):





## 4.7.4. Sequence Diagram





### 4.8. Commands

### 4.8.1. Attach a set of commands

At any moment, the application can attach/declare only one set (or group) of 'commands' that the device is able to process. For that, the application calls the function:

In the sample application:

```
ret = LiveObjectsClient_AttachCommands(appv_set_commands, SET_COMMANDS_NB,
main_cb_command)
```

#### Where:

1. The set of 'commands' is defined by an array of LiveObjectsD\_Command\_t elements. In the sample application:

2. The application specifies the callback function (i.e. commandcb) which will be called when a command is received from the Live Objects platform.

```
int main_cb_command(LiveObjectsD_CommandRequestBlock_t *pCmdReqBlk) {
    int ret;
    const LiveObjectsD_Command_t *cmd_ptr;

    ... // Check input param

    cmd_ptr = pCmdReqBlk->hd.cmd_ptr;

switch (cmd_ptr->cmd_uref) {
    case CMD_IDX_RESET: // RESET
        ret = main_cmd_doSystemReset(pCmdReqBlk);
        break;
    case CMD_IDX_LED: // LED
        ret = main_cmd_doLED(pCmdReqBlk);
        break;
    default:
```



```
ret = -4;
}
return ret;
}
```

In the callback you can define the behavior of the application regarding the command called.

### 4.8.2. Enable/disable 'command' feature

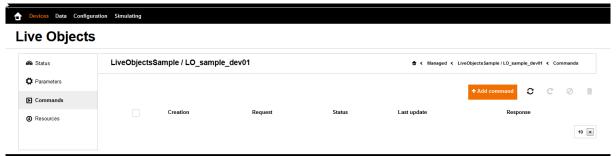
As soon as the device is ready (or not) to process commands, the application can enable (or disable) the 'command' feature by calling the function:

```
int LiveObjectsClient_ControlCommands(bool enable);
```

### 4.8.3. Use of Live Objects Portal to send a command

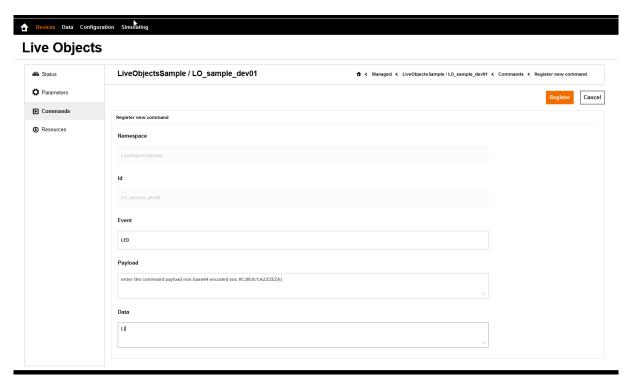
On the Live Objects Portal,

• Go to tab: Devices -> <your device> -> Commands

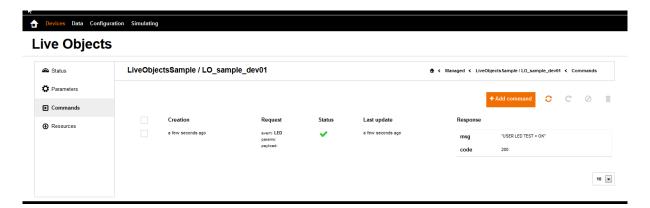


Click on button '+ Add command"



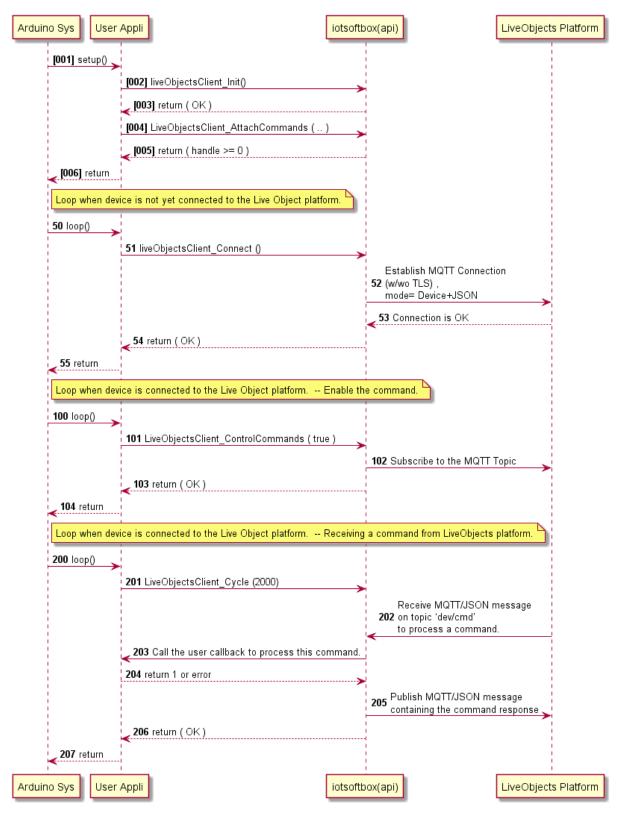


• Click on button 'Register'. And wait a few moment, refresh the web page

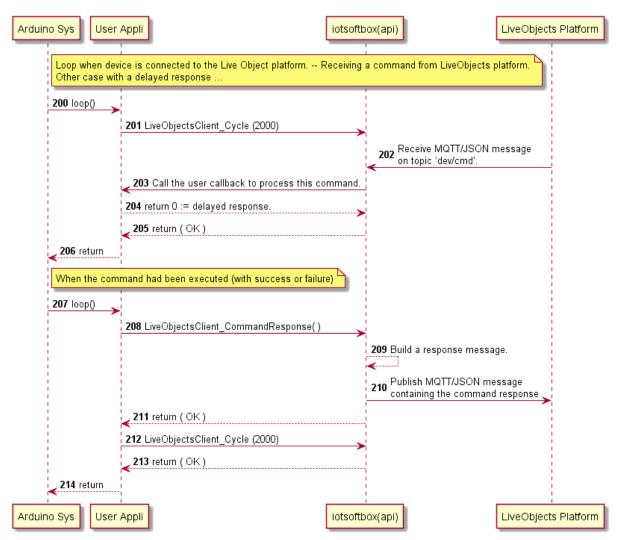


# 4.8.4. Sequence Diagram









## 4.9. Resources

### 4.9.1. Attach a set of resources

At any moment, the application can attach/declare only one set (or group) of 'resources' by calling the function:

```
int LiveObjectsClient AttachResources(
    const LiveObjectsD_Resource_t *rsc_ptr, int32_t rsc_nb,
    LiveObjectsD_CallbackResourceNotify_t ntfyCB,
    LiveObjectsD_CallbackResourceData_t dataCB);
```

In the sample application:



#### Where:

1. The set of 'resources' is defined by an array of LiveObjectsD Resource t elements.

In the sample application:

- 2. The application specifies a first callback function (i.e. commandcb) called by the iotsoftbox-mqtt library:
  - When a transfer request is received from the Live Objects platform
  - When the transfer is completed (with/without error)

In the sample application:



```
// Push Status (message has been updated or not)
               LiveObjectsClient_PushStatus(appv_hdl_status);
       } else {
               appv rsc offset = 0;
               ret = RSC RSP ERR NOT AUTHORIZED;
               switch (rsc_ptr->rsc_uref) {
               case RSC_IDX_MESSAGE:
                      if (size < (sizeof(appv_status_message) - 1)) {</pre>
                             ret = RSC RSP OK;
                      }
                      break;
               case RSC_IDX_IMAGE:
                      if (size < (sizeof(appv_rsc_image) - 1)) {</pre>
                             ret = RSC_RSP_OK;
                      }
                      break;
               if (ret == RSC_RSP_OK) { // Initialize the transfer
                      appv_rsc_size = size;
               } else { // Transfer is refused
                      appv_rsc_size = 0;
               }
} else {
       ret = RSC RSP ERR INVALID RESOURCE;
return ret;
```

In this callback you can handle the app behavior for each declared resource.

3. The application specifies a second callback function to receive the data from the Live Objects platform.

In the sample application:

```
int main_cb_rsc_data(const LiveObjectsD_Resource_t *rsc_ptr, uint32_t offset) {
    int ret;

if (rsc_ptr->rsc_uref == RSC_IDX_MESSAGE) {
        char buf[40];
        if (offset > (sizeof(appv_status_message) - 1)) {
            return -1;
        }
        ret = LiveObjectsClient_RscGetChunck(rsc_ptr, buf, sizeof(buf) - 1);
        if (ret > 0) {
            if ((offset + ret) > (sizeof(appv_status_message) - 1)) {
                return -1;
        }
}
```



```
}
    }
} else if (..) {
        ...
} else {
        ret = -1;
}
return ret;
}
```

In this callback, you can receive the data. You can get the data in one time if you have set a big enough buffer or in severals time if you're using a very low capacity device. Once you have the data you can process them.

#### 4.9.2. Enable/disable 'resources' feature

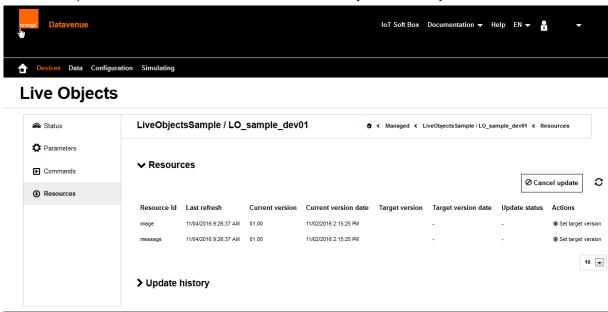
As soon as the device is ready (or not) to process the resource update request, the application can enable (or disable) the 'resources' feature by calling the function:

int LiveObjectsClient\_ControlResources(bool enable);



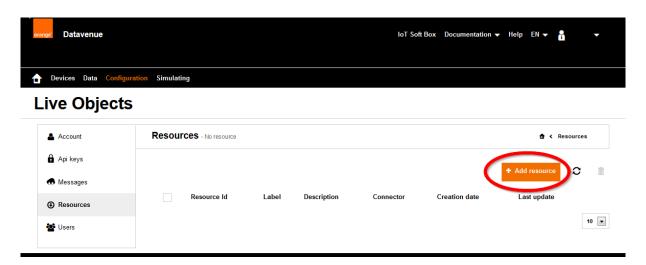
#### 4.9.3. Use of Live Objects Portal to create and update a resource

The first step is to check the list of resources declared by the Live Objects device.



Here, the device 'LiveObjectsSample/LO\_sample\_dev01' has two resources identified by: *image* and *message*.

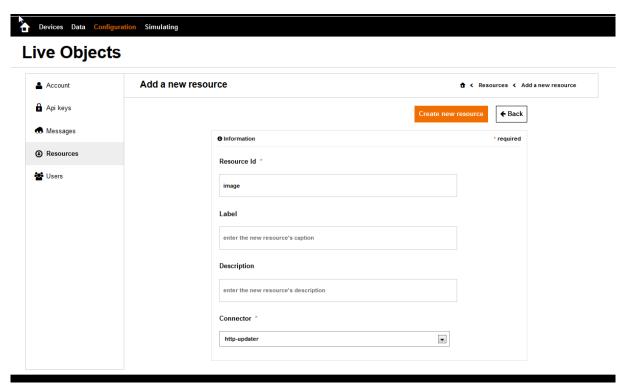
Now, the user can create a new resource on the Live Objects platform, in the tab 'Configuration->Resources', associated to these resources



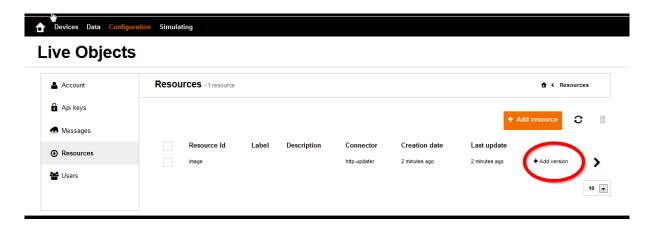
Two fields are mandatory

- Resource Id: set to 'image', resource identified by the device.
- Connector: set to http-updater.





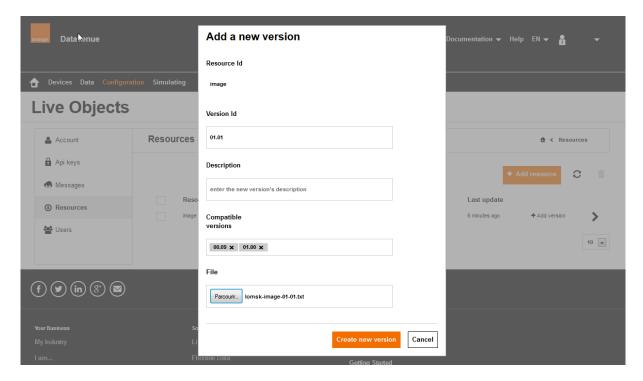
The result is the following:



Then, a new resource version can be attached to this resource 'image', by specifying:

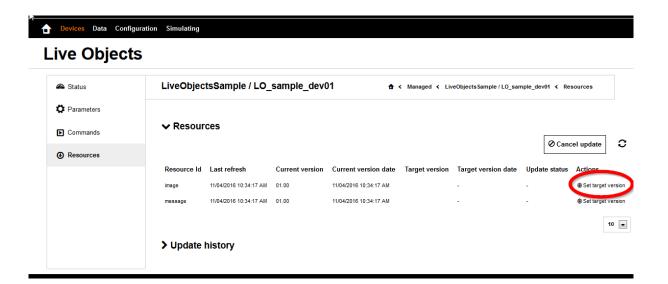
- Version id (i.e. 01.01) for this resource to download on devices
- Compatible versions (optional): the list of current versions deployed on devices which must be able to accept this new version (01.01).
- File, to download on the device





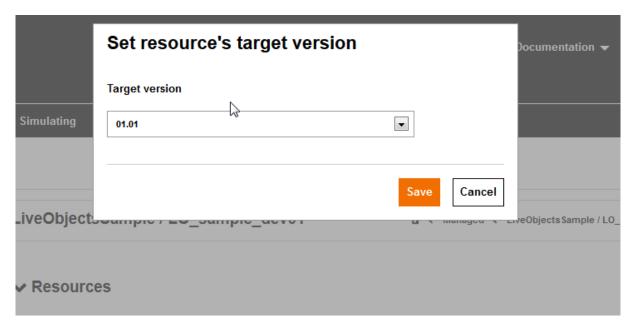
Now, the resource update request can be launched for this device:

- Go to the 'devices' tab.
- Select your connected device, here it is "LiveObjectsSample / LO\_sample\_dev01"
- Go to the 'resources' tab



- Click on 'Set target version'
- And select the resource version to download on device



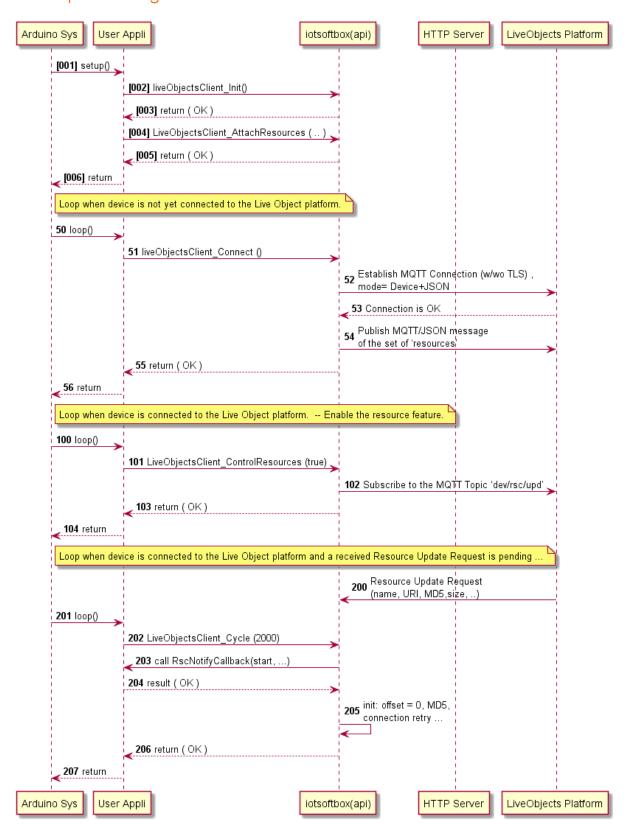


At the end of transfer, after refreshing the web page, the current version should be equal to the target version:



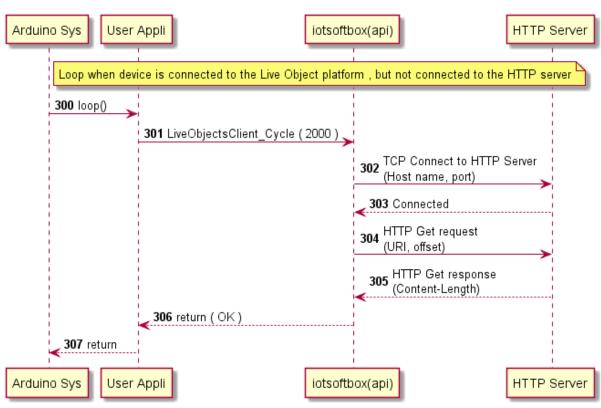


#### 4.9.4. Sequence diagram



When a resource download is running, first step is to establish a connection to the HTTP server.





An example of URI is:

http://liveobjects.orange-business.com:80/dl/18p1bj775jhk0pj6p49076hk45

And the header of HTTP Get Response is similar to:

HTTP/1.1 200 OK

Server: nginx/1.4.6 (Ubuntu)

Date: Fri, 04 Nov 2016 10:34:50 GMT

Content-Type: application/force-download; charset=UTF-8

Content-Length: 1974
Connection: close

X-Application-Context: lo-http-updater:prod:8080

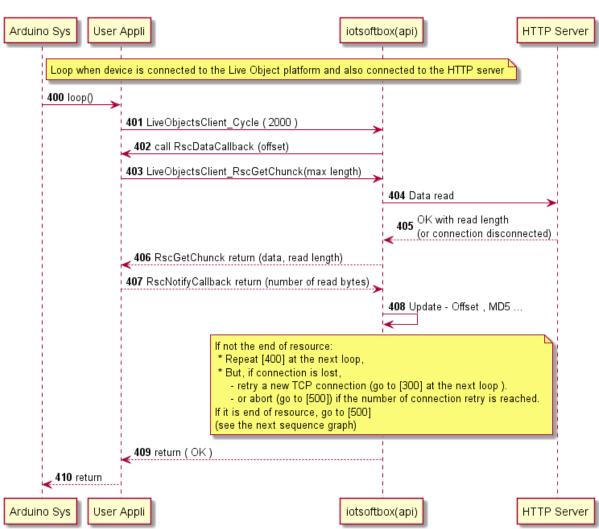
Access-Control-Allow-Headers: X-Requested-With, Content-Type

Access-Control-Allow-Credentials: true

Then, at each next loop, while the resource transfer is running, get data from the HTTP server ...

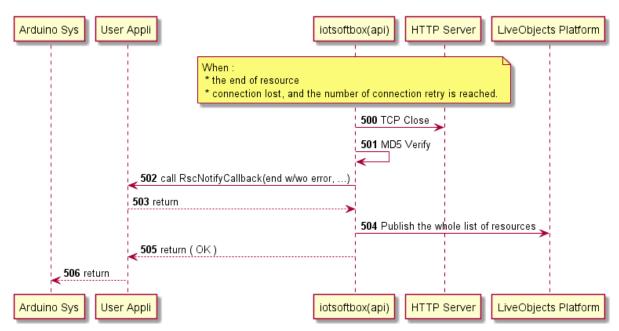
Note that the user application provides the data buffer to retrieve data from the TCP connection.





And when the resource transfer is completed (with success or failure), do the following:







### 5. Additional Information

## 5.1. Doxygen documentation

The iotsoftbox-mqtt library is documented using the Doxygen source code comments (mainly for the 'public' header files).

To generate the documentation, download <u>doxygen</u>, then:

1. Launch the following command in a command window:

cd <user arduino directory>libraries\iotsoftbox\_mqtt\_arduino\doxygen doxygen.exe liveobjects\_iotsoftbox.doxyfile

2. Or you can also use a GUI: doxywizard

Step 2: Go to the Run tab and press Run Doxygen.

The doc will be generate into an apidoc folder. Open `apidoc/html/index.html` to start browsing the doc.

# 5.2. Debug

The iotsoftbox-mqtt library uses MACRO definitions to print traces. Theses MACROs are defined in the **loc\_trace.h** header file depending on platform.

- LOTRACE ERR
- LOTRACE\_WARN
- LOTRACE NOTICE
- LOTRACE INF
- LOTRACE\_DBG1
- LOTRACE DBG2
- LOTRACE DBG VERBOSE



### 5.3. IoT Soft Box Library Configuration

The iotsoftbox-mqtt library can be tuned according to the target and/or application constraints (memory, network, use or not of Live Objects features...) All tunable parameters are defined with theirs default values in the header file liveobjects-client/LiveObjectsClient\_Config.h.

Then, the user application can overwrite theses values in the header file liveobjects\_dev\_config.h

#### Tunable parameters are:

LOC MQTT DUMP MSG  $\overline{\text{Dump MQTT message}}$  - set to 1 = text only, 2 = hexa only, 3 = text+hexa LOC FEATURE MBEDTLS Implement or not the mbedtls feature LOC FEATURE LO STATUS Support or not the Live Objects 'Status' feature. LOC FEATURE LO PARAMS Support or not the Live Objects 'Configuration Parameters' feature. LOC FEATURE LO DATA Support or not the Live Objects 'Collected Data' feature. LOC FEATURE LO COMMANDS Support or not the Live Objects 'Commands' feature. LOC FEATURE LO RESOURCES Support or not the Live Objects 'resources' feature. LOC MOUEUE Implement or not the message queue (default: 1) LOM PUSH ASYNC Enable or not the 'asynchronous' mode. (default 0). Set to 1 when board has a small size of RAM. Therefore o No memory allocation o No message queue LOC SERV TIMEOUT Connection Timeout in milliseconds (default 20 seconds) LOC MQTT API KEEPALIVEINTERVAL SEC Period of MQTT Keepalive message (default: 30 seconds) LOC MQTT DEF COMMAND TIMEOUT Timeout in milliseconds to wait for a MQTT ACK/NACK response after sending MQTT request (default: 5 seconds) LOC\_MQTT\_DEF\_SND\_SZ Size (in bytes) of static MQTT buffer used to send a MQTT message (default: 2 K bytes) LOC MQTT DEF RCV SZ Size (in bytes) of static MQTT buffer used to receive a MQTT message (default: 2 K bytes) • LOC\_MQTT\_DEF\_TOPIC\_NAME\_SZ Max Size (in bytes) of MQTT Topic name (default: 40 bytes) LOC\_MQTT\_DEF\_DEV\_ID\_SZ Max Size (in bytes) of Device Identifier (default: 20 bytes) LOC\_MQTT\_DEF\_NAME\_SPACE\_SZ Max Size (in bytes) of Name Space (default: 20 bytes) LOC MOTT DEF PENDING MSG MAX Max Number of pending MQTT Publish messages (default: 5 messages)

LOM\_SETOFDATA\_STREAM\_ID\_SZ

LOC\_MAX\_OF COMMAND ARGS

LOC\_MAX\_OF\_STATUS\_SET

LOC MAX\_OF\_DATA\_SET

streams)

Max Number of status sets (default: 1)

Max Number of arguments in command (default: 5 arguments)

Max Number of collected data streams (or also named 'data sets') (default: 5 data



- Max Size (in bytes) of Data stream Id (default: 80 bytes)
- LOM\_SETOFDATA\_MODEL\_SZ Max Size (in bytes) of Model defined in a data stream (default: 80 bytes). If set to 0, no model field.
- LOM\_SETOFDATA\_TAGS\_SZ
  Max Size (in bytes) of Data Tags defined in a data stream (default: 80 bytes).
  If set to 0, no tags field.
- LOM\_JSON\_BUF\_SZ Size (in bytes) of static JSON buffer used to encode the JSON payload to be sent (default: 1 K bytes)
- LOM\_JSON\_BUF\_USER\_SZ
  Size (in bytes) of static JSON buffer used to encode a user JSON payload (default: 1 K bytes)
  Note: this buffer is not instantied when the MQUEUE is not implemented.