EECS 127: Optimization Models in Engineering Homework 2

Your Name

Problem 1. Consider the subspace $S = (\mathbf{x}^{(1)}, \mathbf{x}^{(2)}, \mathbf{x}^{(3)})$, where

$$\mathbf{x}^{(1)} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \quad \mathbf{x}^{(2)} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, \quad \mathbf{x}^{(3)} = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$$

- (i) Find the dimension of S.
- (ii) Calculate the projection of the point $\begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}$ on \mathcal{S} .

Solution 1. (i) Dimension of S:

To find the dimension of S, we'll perform Gaussian elimination on the matrix **A** formed by the given vectors:

$$\mathbf{A} = \begin{pmatrix} 1 & -1 & 0 \\ 1 & 0 & 1 \\ 1 & 1 & 2 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \end{pmatrix} \quad (R2 \to R2 - R1, R3 \to R3 - R1)$$

$$\sim \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \quad (R3 \to R3 - 2R2)$$

The rank of the matrix is equal to the number of non-zero rows in this row echelon form, which is 2. Therefore, $\dim(\mathcal{S}) = 2$.

(ii) Projection onto S:

Let $\mathbf{b} := \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}$. We'll use the Gram-Schmidt process to find an orthonormal basis for \mathcal{S} , then project \mathbf{b} onto this basis.

1. Apply Gram-Schmidt process:

$$\begin{aligned} \mathbf{u}_1 &= \mathbf{x}^{(1)} = \begin{pmatrix} 1\\1\\1 \end{pmatrix} \\ \mathbf{u}_2 &= \mathbf{x}^{(2)} - \mathrm{proj}_{\mathbf{u}_1}(\mathbf{x}^{(2)}) = \begin{pmatrix} -1\\0\\1 \end{pmatrix} - 0\mathbf{u}_1 = \begin{pmatrix} -1\\0\\1 \end{pmatrix} \\ \mathbf{u}_3 &= \mathbf{x}^{(3)} - \mathrm{proj}_{\mathbf{u}_1}(\mathbf{x}^{(3)}) - \mathrm{proj}_{\mathbf{u}_2}(\mathbf{x}^{(3)}) = \begin{pmatrix} 0\\0\\0 \end{pmatrix} \end{aligned}$$

2. Normalize the basis vectors:

$$\mathbf{v}_1 = \frac{\mathbf{u}_1}{\|\mathbf{u}_1\|} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1\\1\\1 \end{pmatrix}$$
$$\mathbf{v}_2 = \frac{\mathbf{u}_2}{\|\mathbf{u}_2\|} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1\\0\\1 \end{pmatrix}$$

3. Calculate the projection:

$$\operatorname{proj}_{\mathcal{S}}(\mathbf{b}) = \langle \mathbf{b}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{b}, \mathbf{v}_2 \rangle \mathbf{v}_2$$

$$= \frac{7}{\sqrt{3}} \cdot \frac{1}{\sqrt{3}} \begin{pmatrix} 1\\1\\1\\1 \end{pmatrix} + \frac{3}{\sqrt{2}} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} -1\\0\\1 \end{pmatrix}$$

$$= \frac{7}{3} \begin{pmatrix} 1\\1\\1 \end{pmatrix} + \frac{3}{2} \begin{pmatrix} -1\\0\\1 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{7}{3} - \frac{3}{2}\\\frac{7}{3} + \frac{3}{2} \end{pmatrix} = \begin{pmatrix} \frac{5}{6}\\\frac{7}{3}\\\frac{17}{6} \end{pmatrix}$$

Problem 2. Consider the box S_1 and ball S_2 defined as

$$S_1 = \{ \mathbf{x} \in \mathbb{R}^2 \mid -2 \le x_1 \le 2, -0.5 \le x_2 \le 0.5 \}, \quad S_2 = \{ \mathbf{x} \in \mathbb{R}^2 \mid x_1^2 + x_2^2 \le 1 \}$$

Given a point $\mathbf{z} \in \mathbb{R}^2$, write an optimization problem in standard form that finds the projection of \mathbf{z} onto the set $\mathcal{S}_1 \cap \mathcal{S}_2$.

Solution 2. The optimization problem can be formulated as:

$$\min_{\mathbf{z}^*} \quad \|\mathbf{z} - \mathbf{z}^*\|_2^2$$
s.t. $(z_1^*)^2 + (z_2^*)^2 \le 1$

$$-2 \le z_1^* \le 2$$

$$-0.5 \le z_2^* \le 0.5$$

Note: We use the squared norm to simplify calculations, as it doesn't change the optimal solution.

Problem 3. A company has n factories. Factory i (for i = 1, 2, ..., n) is located at point (a_i, b_i) in the two-dimensional plane \mathbb{R}^2 . The company wants to locate a warehouse at a point (x_1, x_2) that minimizes

$$\sum_{i=1}^{n} (\text{distance from factory } i \text{ to the warehouse})^2$$

Find all possible values of the point (x_1^*, x_2^*) that satisfy the necessary condition for local optimality.

Solution 3. Let's formulate the minimization above as follows:

$$\sum_{i=1}^{n} (\text{distance from factory } i \text{ to the warehouse})^2 = \sum_{i=1}^{n} \left[(a_i - x_1)^2 + (b_i - x_2)^2 \right]$$

We need to solve for the necessary condition of local optimality where

$$\nabla f(\mathbf{x}) = \begin{pmatrix} 2nx_1 - 2\sum_{i=1}^n a_i \\ 2nx_2 - 2\sum_{i=1}^n b_i \end{pmatrix} = \mathbf{0}$$

This means

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{n} \sum_{i=1}^n a_i \\ \frac{1}{n} \sum_{i=1}^n b_i \end{pmatrix}$$

Problem 4. Given a natural number $k \in \{1, 2, ...\}$, a symmetric matrix $\mathbf{P} \in \mathbb{R}^{n \times n}$, a vector $\mathbf{q} \in \mathbb{R}^n$ and a scalar $r \in \mathbb{R}$, consider the optimization problem

$$\min_{\mathbf{x} \in \mathbb{R}^n} \ (\mathbf{x}^\top \mathbf{P} \mathbf{x})^k + \mathbf{q}^\top \mathbf{x} + r$$

Assume that \mathbf{q} is a nonzero vector.

- (i) Calculate the gradient of the function $\mathbf{q}^{\top}\mathbf{x}$.
- (ii) Calculate the gradient of the function $\mathbf{x}^{\top} \mathbf{P} \mathbf{x}$.
- (iii) Calculate the gradient of the objective function of the optimization problem.
- (iv) Given a point \mathbf{x}^* , write the necessary optimality condition for \mathbf{x}^* to be a local minimum of the optimization problem.
- (v) Assume that \mathbf{q} is not in the range of \mathbf{P} . Prove that the optimization problem cannot have any local minimum.
- (vi) Assume that **P** is invertible. Given a local minimum \mathbf{x}^* of the optimization problem, show that there is a scalar α such that $\mathbf{x}^* = \alpha \mathbf{P}^{-1} \mathbf{q}$.
- (vii) Again assume that **P** is invertible. Solve for α in Part (vi) and calculate it in terms of only the known parameters **P**, **q**, r, k.

Solution 4. (i)
$$\nabla \mathbf{q}^{\top} \mathbf{x} = \mathbf{q}$$

(ii) $\nabla \mathbf{x}^{\mathsf{T}} \mathbf{P} \mathbf{x}$

Step 1: Expand the quadratic form

First, let's write out what $\mathbf{x}^{\top} \mathbf{P} \mathbf{x}$ means: $\mathbf{x}^{\top} \mathbf{P} \mathbf{x} = \sum_{i=1}^{n} \sum_{j=1}^{n} x_i p_{ij} x_j$ where p_{ij} is the element

in the i-th row and j-th column of P.

Step 2: Calculate the partial derivatives

To find the gradient, we need to calculate the partial derivative with respect to each x_k : $\frac{\partial}{\partial x_k}(\mathbf{x}^{\top}\mathbf{P}\mathbf{x}) = \frac{\partial}{\partial x_k}\sum_{i=1}^n\sum_{j=1}^n x_i p_{ij} x_j$

Using the product rule and noting that p_{ij} is constant: $\frac{\partial}{\partial x_k}(\mathbf{x}^{\top}\mathbf{P}\mathbf{x}) = \sum_{i=1}^n p_{ik}x_i + \sum_{j=1}^n p_{kj}x_j$

Step 3: Simplify using matrix notation

We can write this more compactly as: $\frac{\partial}{\partial x_k}(\mathbf{x}^{\top}\mathbf{P}\mathbf{x}) = (\mathbf{P}\mathbf{x})_k + (\mathbf{P}^{\top}\mathbf{x})_k$ where $(\mathbf{P}\mathbf{x})_k$ denotes the k-th element of the vector $\mathbf{P}\mathbf{x}$.

Step 4: Combine results for all k

Combining the results for all k, we get the gradient vector: $\nabla \mathbf{x}^{\top} \mathbf{P} \mathbf{x} = \mathbf{P} \mathbf{x} + \mathbf{P}^{\top} \mathbf{x} = 2\mathbf{P} \mathbf{x}$ as P is symmetric.

(iii)
$$\nabla (\mathbf{x}^{\top} \mathbf{P} \mathbf{x})^k + \mathbf{q}^{\top} \mathbf{x} + r = 2k(\mathbf{x}^{\top} \mathbf{P} \mathbf{x})^{k-1} \mathbf{P} \mathbf{x} + \mathbf{q}$$

(iv) $2k(\mathbf{x}^{*\top} \mathbf{P} \mathbf{x}^*)^{k-1} \mathbf{P} \mathbf{x}^* + \mathbf{q} = \mathbf{0}$

Proof that no local minimum exists when \mathbf{q} is not in the range of \mathbf{P} :

Assume, for contradiction, that the problem has a local minimum. This means the necessary optimality condition has a solution \mathbf{x}^* such that:

$$2k(\mathbf{x}^{*\top}\mathbf{P}\mathbf{x}^{*})^{k-1}\mathbf{P}\mathbf{x}^{*} + \mathbf{q} = \mathbf{0}$$
$$-2k(\mathbf{x}^{*\top}\mathbf{P}\mathbf{x}^{*})^{k-1}\mathbf{P}\mathbf{x}^{*} = \mathbf{q}$$

This implies that \mathbf{q} is in the range of \mathbf{P} , contradicting our assumption. Therefore, the optimization problem cannot have any local minimum.

(vi)

Showing $\mathbf{x}^* = \alpha \mathbf{P}^{-1} \mathbf{q}$ for some scalar α :

From the necessary optimality condition:

$$2k(\mathbf{x}^{*\top}\mathbf{P}\mathbf{x}^*)^{k-1}\mathbf{P}\mathbf{x}^* + \mathbf{q} = \mathbf{0}$$
$$\mathbf{P}\mathbf{x}^* = -\frac{1}{2k(\mathbf{x}^{*\top}\mathbf{P}\mathbf{x}^*)^{k-1}}\mathbf{q}$$

Since **P** is invertible, we can multiply both sides by \mathbf{P}^{-1} :

$$\mathbf{x}^* = -\frac{1}{2k(\mathbf{x}^{*\top}\mathbf{P}\mathbf{x}^*)^{k-1}}\mathbf{P}^{-1}\mathbf{q}$$

Let
$$\alpha = -\frac{1}{2k(\mathbf{x}^{*\top}\mathbf{P}\mathbf{x}^{*})^{k-1}}$$
. Then $\mathbf{x}^{*} = \alpha\mathbf{P}^{-1}\mathbf{q}$. (vii)

Solving for α :

Substitute $\mathbf{x}^* = \alpha \mathbf{P}^{-1} \mathbf{q}$ into the optimality condition:

$$2k(\alpha^2 \mathbf{q}^{\mathsf{T}} \mathbf{P} \mathbf{P}^{-1} \mathbf{q})^{k-1} \mathbf{P} \alpha \mathbf{P}^{-1} \mathbf{q} + \mathbf{q} = \mathbf{0}$$
$$2k\alpha^{2k-1} \mathbf{P} \mathbf{q} + \mathbf{q} = \mathbf{0}$$
$$2k\alpha^{2k-1} \mathbf{q} + \mathbf{q} = \mathbf{0}$$
$$(2k\alpha^{2k-1} + 1)\mathbf{q} = \mathbf{0}$$

Since **q** is nonzero, we have $2k\alpha^{2k-1} + 1 = 0$. Solving for α :

$$\alpha^{2k-1} = -\frac{1}{2k}$$

$$\alpha = \left(-\frac{1}{2k}\right)^{\frac{1}{2k-1}}$$