

Another derivation

Let  $F = I - 2(vv^T/v^Tv)$ . Find  $v$  s.t.  $Fx \in \text{span}\{e_1\}$ .

$$\begin{aligned} Fx &= x - 2(v^Tx/v^Tv)v \\ &\in \text{span}\{e_1\} \quad \Leftrightarrow \quad v \in \text{span}\{x, e_1\} \end{aligned}$$

Let  $v = x + \alpha e_1$

$$\begin{aligned} v^Tx &= x^Tx + \alpha e_1^Tx = x^Tx + \alpha x_1 \\ v^Tv &= (x + \alpha e_1)^T(x + \alpha e_1) \\ &= x^Tx + 2\alpha x_1 + \alpha^2 \end{aligned}$$

$$\begin{aligned} \therefore Fx &= x - 2 \frac{v^Tx}{v^Tv} (x + \alpha e_1) \\ &= (1 - 2 \frac{v^Tx}{v^Tv})x - 2\alpha \frac{v^Tx}{v^Tv} e_1 \\ &= (1 - 2 \frac{x^Tx + \alpha x_1}{x^Tx + 2\alpha x_1 + \alpha^2})x - 2\alpha \frac{v^Tx}{v^Tv} e_1 \\ &= \underbrace{\frac{x^Tx + 2\alpha x_1 + \alpha^2 - 2x^Tx - 2\alpha x_1}{x^Tx + 2\alpha x_1 + \alpha^2}}_{=0} x - 2\alpha \frac{v^Tx}{v^Tv} e_1 \\ &\quad \quad \quad \alpha^2 - x^Tx = 0 \\ &\quad \quad \quad \alpha = \pm \|x\| \end{aligned}$$

Hence  $v = x \pm \|x\| e_1$

and  $Fx = \mp \|x\| e_1$

### Example

$$x = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$$

$$v = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} + (1)\sqrt{1+2^2+2^2} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix}$$

$$F = I - 2 \frac{vv^T}{v^T v}$$

$$= \frac{1}{3} \begin{bmatrix} -1 & -2 & -2 \\ -2 & 2 & -1 \\ -2 & -1 & 2 \end{bmatrix}$$

$$Fx = \begin{bmatrix} -3 \\ 0 \\ 0 \end{bmatrix}$$

- Note: no need to actually perform  $Fx$  to compute the product.
- For convenience,  $v$  is sometimes normalized; i.e.  $\|v\| = 1$ .  
In this case,

$$\begin{aligned} Fx &= x - 2v(v^T x / v^T v) \\ &= x - 2v(v^T x) \end{aligned}$$

## Householder QR factorization algorithm (full version)

```
for k = 1, 2, . . . , n
    x = A(k:m, k)
    vk = x + sign(x1) ||x|| e1
    vk = vk / ||vk||
    for j = k, k+1, . . . , n
        A(k:m, j) = A(k:m, j) - 2 vk (vkT A(k:m, j))
    end
end
```

(Notation:  $A(k:m, j)$  =  $j$ -th column of  $A$  from row  $k$  to row  $m$ .)

### Notes

- 1) At the end of the algorithm,  $A$  is reduced to  $R$ .
- 2)  $Q$  is not constructed. In fact, only  $v_k$ 's are kept.

Note:

$$Q^T = Q_n \dots Q_2 Q_1$$
$$Q = Q_1 Q_2 \dots Q_n \quad (Q_k = Q_k^T)$$

To compute  $Q^T b$ :

```
for k = 1, 2, . . . , n
    b(k:m) = b(k:m) - 2 vk (vkT b(k:m))
end
```

To compute  $Qx$ :

```
for k = n, n-1, . . . , 1
    x(k:m) = x(k:m) - 2 vk (vkT x(k:m))
end
```

3) To compute the reduced QR, i.e.  $A = \hat{Q}\hat{R} = \begin{bmatrix} & \\ & \end{bmatrix} \begin{bmatrix} \\ \\ \end{bmatrix}_{m \times n}$

Then

$$\hat{Q} = \begin{bmatrix} Qe_1 & Qe_2 & \cdots & Qe_n \end{bmatrix} \quad e_j = j\text{-th col of } I$$

### Complexity

- The work is dominated by the inner-most loop:

$$A(k:m, j) = A(k:m, j) - 2 v_k (v_k^T A(k:m, j))$$

$$\text{flops}(v_k^T A(k:m, j)) \sim 2(m-k+1)$$

$$\text{flops}(2 v_k (v_k^T A(k:m, j))) \sim m-k+1$$

$$\text{flops}(\text{subtraction}) \sim m-k+1$$

$$\therefore \quad \text{subtotal} \sim 4(m-k+1)$$

This operation is done  $n-k+1$  times (j-loop)

$$\text{i.e. flops} = 4(m-k+1)(n-k+1)$$

$$\begin{aligned} \therefore \text{Total flops} &= \sum_{k=1:n} 4(m-k+1)(n-k+1) \\ &\sim 2mn^2 - \frac{2}{3} n^3 \end{aligned}$$

When  $m = n$ ,  $\text{flops}(\text{QR}) \sim \frac{4}{3} n^3 = 2 \times \text{flops}(\text{LU})$

**Note:** It does not include the computation of Q

Example: Find the QR factorization of  $A = \begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix}$

$$x = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} \quad v_- = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} + \sqrt{1+2^2+2^2} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix}$$

$$\text{or } v_+ = -\begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} + \sqrt{1+2^2+2^2} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ -2 \\ -2 \end{bmatrix}$$

$$F = \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix} - \frac{2}{v_+^T v_+} \begin{bmatrix} 2 \\ -2 \\ -2 \end{bmatrix} \begin{bmatrix} 2 & -2 & -2 \end{bmatrix} = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} & \frac{-2}{3} \\ \frac{2}{3} & \frac{-2}{3} & \frac{1}{3} \end{bmatrix} = Q_1$$

$$Q_1 A = Q_1 \begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ 0 & -3 \\ 0 & -4 \end{bmatrix}$$

$$x = \begin{bmatrix} -3 \\ -4 \end{bmatrix} \quad v = -\begin{bmatrix} -3 \\ -4 \end{bmatrix} + \sqrt{3^2+4^2} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 8 \\ 4 \end{bmatrix}$$

$$F_2 = \begin{bmatrix} 1 & \\ & 1 \end{bmatrix} - \frac{2}{v^T v} \begin{bmatrix} 8 \\ 4 \end{bmatrix} \begin{bmatrix} 8 & 4 \end{bmatrix} = \begin{bmatrix} \frac{-3}{5} & \frac{-4}{5} \\ \frac{-4}{5} & \frac{2}{5} \end{bmatrix}$$

$$Q_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & & \\ 0 & F_2 & \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{-3}{5} & \frac{-4}{5} \\ 0 & \frac{-4}{5} & \frac{2}{5} \end{bmatrix}$$

$$Q_2(Q_1 A) = Q_2 \begin{bmatrix} 3 & 2 \\ 0 & -3 \\ 0 & -4 \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ 0 & 5 \\ 0 & 0 \end{bmatrix} = R$$

$$A = Q_1 Q_2 R$$

$$= \begin{bmatrix} \frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} & \frac{-2}{3} \\ \frac{2}{3} & \frac{-2}{3} & \frac{1}{3} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{-3}{5} & \frac{-4}{5} \\ 0 & \frac{-4}{5} & \frac{2}{5} \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 0 & 5 \\ 0 & 0 \end{bmatrix}$$

$$= \underbrace{\frac{1}{15} \begin{bmatrix} 5 & -14 & -2 \\ 10 & 5 & -10 \\ 10 & 2 & 11 \end{bmatrix}}_Q \underbrace{\begin{bmatrix} 3 & 2 \\ 0 & 5 \\ 0 & 0 \end{bmatrix}}_R$$