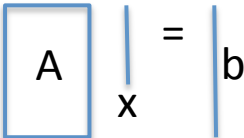


Least Squares Problems

- First posed and formulated by Gauss.
- Surveyors tried to identified boundaries lie between plots and land by measuring certain angles and distances from known landmarks.
- To update the location of landmarks, new measurements of angles and distances between landmarks.
- Given a set of old locations $\{(x_i, y_i)\}$, find corrections $\{(\delta x_i, \delta y_i)\}$ such that $\{(x_i + \delta x_i, y_i + \delta y_i)\}$ better match new measurements.
- In general,

$$\text{constraints} \left\{ \begin{array}{l} a_{1,1}x_1 + a_{1,2}x_2 + \cdots + a_{1,n}x_n = b_1 \\ \vdots \\ a_{m,1}x_1 + a_{m,2}x_2 + \cdots + a_{m,n}x_n = b_m \end{array} \right\} \text{ observations}$$

i.e. $Ax = b$



In general, $r = b - Ax \neq 0$.

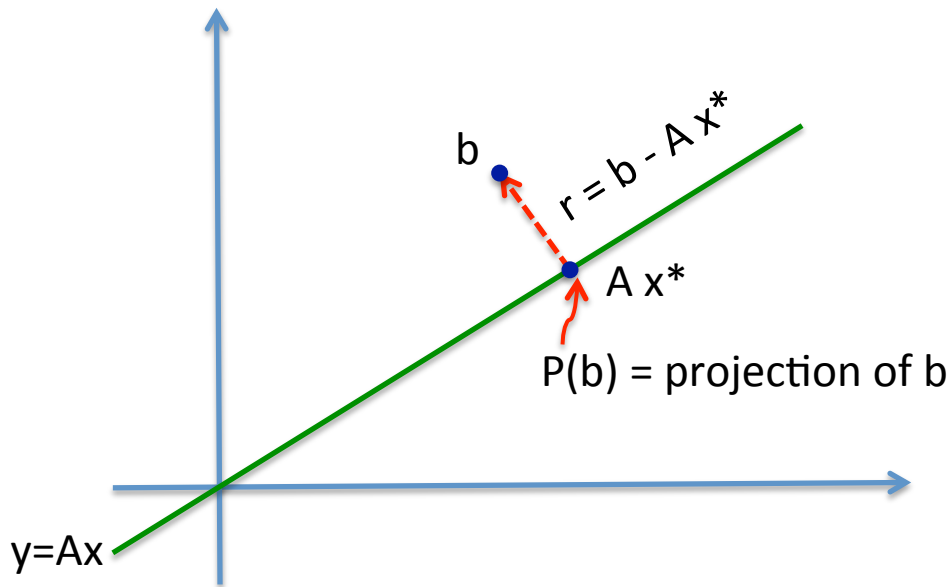
Idea: min the residual vector r

$$\min_{x \in R^n} \|b - Ax\|_2^2 \quad A \in R^{m \times n}, \quad b \in R^m, \quad m \geq n$$

- Least squares (LS) problems.

Solving LS problems

Geometric interpretation:



Theorem: Let $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$, $m \geq n$ and A has full rank. A vector $x \in \mathbb{R}^n$ minimizes

$$\|r\|^2 = \|b - Ax\|^2$$

if and only if $r \perp \text{range}(A)$.

Hence $r^T A = 0 \Leftrightarrow A^T r = 0 \Leftrightarrow A^T (b - Ax) = 0$

$$\Leftrightarrow A^T A x = A^T b$$

Def: $A^+ = (A^T A)^{-1} A^T$ is called the pseudoinverse of A .

The least squares solution is given by:

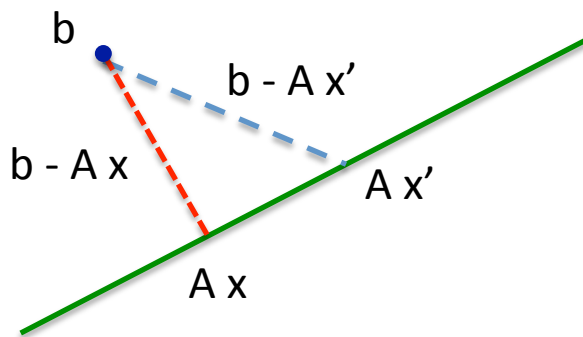
$$x = (A^T A)^{-1} A^T b = A^+ b$$

Why is x the minimizer of $||b - Ax||^2$?

Let $x' = x + e$ be another point.

$$\begin{aligned}
 ||b - Ax'||^2 &= (b - Ax')^T (b - Ax') \\
 &= (b - Ax - Ae)^T (b - Ax - Ae) \\
 &= (b - Ax)^T (b - Ax) + 2(Ae)^T (b - Ax) + (Ae)^T (Ae) \\
 &= ||b - Ax||^2 + ||Ae||^2 + 2e^T (A^T b - A^T A x) \\
 &= ||b - Ax||^2 + ||Ae||^2
 \end{aligned}$$

Hence $||b - Ax'||^2 > ||b - Ax||^2$ if $e \neq 0$



Method 1: Normal equations

Solve $A^T A x = A^T b$

- Compute Cholesky factorization $A^T A = GG^T$, $G = \text{lower } \Delta$
- Compute x by forward and backward solves

Complexity

$\text{flops}(A^T A) \sim mn^2$, $\text{flops}(GG^T) \sim \frac{1}{3} n^3$

Total flops $\sim mn^2 + \frac{1}{3} n^3$ ($m \geq n$)

Method 2: QR factorization

Def: Q is orthogonal if $Q^{-1} = Q^T$

i.e. $Q^T Q = Q Q^T = I$

Theorem: $||Qx||_2 = ||x||_2$

Pf: $||Qx||^2 = (Qx)^T (Qx) = x^T Q^T Q x = x^T x = ||x||^2$

Note:
multiplication by Q = $\begin{cases} \text{rotation} & \text{if } \det(Q) = 1 \\ \text{reflection} & \text{if } \det(Q) = -1 \end{cases}$

Theorem: Suppose $A \in \mathbb{R}^{m \times n}$ has full rank. Then there exist a unique orthogonal matrix $\hat{Q} \in \mathbb{R}^{m \times n}$ ($Q^T Q = I$) and a unique upper Δ matrix $\hat{R} \in \mathbb{R}^{n \times n}$ with positive diagonals ($r_{ii} > 0$) such that

$$A = \hat{Q} \hat{R} \quad \text{i.e.} \quad \boxed{A} = \boxed{\hat{Q}} \boxed{\begin{array}{c} \text{0} \\ \hat{R} \end{array}}$$

Note:

The column of \hat{Q} are orthogonal to each other and their norm = 1.

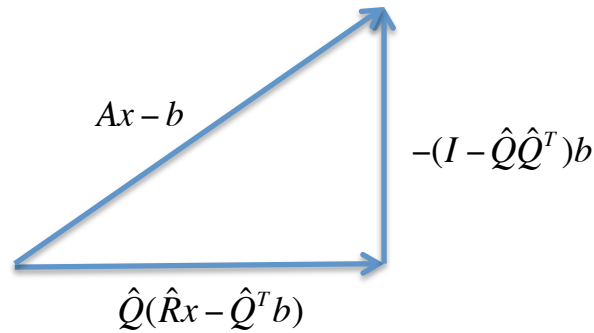
Consider the LS problem:

$$\min ||Ax - b||^2$$

- $$\begin{aligned} Ax - b &= \hat{Q} \hat{R} x - b \\ &= \hat{Q} \hat{R} x - (\hat{Q} \hat{Q}^T + I - \hat{Q} \hat{Q}^T) b \\ &= \hat{Q} (\hat{R} x - \hat{Q}^T b) - (I - \hat{Q} \hat{Q}^T) b \end{aligned}$$

Note: $\hat{Q}(\hat{R}x - \hat{Q}^T b) \perp (I - \hat{Q}\hat{Q}^T)b$

Pf:
$$\begin{aligned} & [\hat{Q}(\hat{R}x - \hat{Q}^T b)]^T (I - \hat{Q}\hat{Q}^T)b \\ &= (\hat{R}x - \hat{Q}^T b) \hat{Q}^T (I - \hat{Q}\hat{Q}^T)b \\ &= (\hat{R}x - \hat{Q}^T b) (\hat{Q}^T - \cancel{\hat{Q}^T \hat{Q}} \hat{Q}^T)b \quad (\because \hat{Q}^T \hat{Q} = I) \end{aligned}$$



Pythagoras thm:
$$\begin{aligned} \|Ax - b\|^2 &= \|\hat{Q}(\hat{R}x - \hat{Q}^T b)\|^2 + \|(I - \hat{Q}\hat{Q}^T)b\|^2 \\ &= \|\hat{R}x - \hat{Q}^T b\|^2 + \|(I - \hat{Q}\hat{Q}^T)b\|^2 \end{aligned}$$

The RHS is min if the first term is 0.

i.e.
$$\hat{R}x = \hat{Q}^T b \implies x = \hat{R}^{-1} \hat{Q}^T b$$

Notes

1) $A^+ = \hat{R}^{-1} \hat{Q}^T$

2) $A^T Ax = A^T b \iff (\hat{R}^T \hat{Q}^T)(\hat{Q} \hat{R})x = (\hat{R}^T \hat{Q}^T)b$

$$\hat{R}^T \hat{R}x = \hat{R}^T \hat{Q}^T b$$

$$\hat{R}x = \hat{Q}^T b$$

$$x = \hat{R}^{-1} \hat{Q}^T b$$

QR factorization (reduced version)

Let $A = [a_1 \ a_2 \ \dots \ a_n]$. Want to find orthogonal vectors $\{q_i\}$ such that

$$\text{span} \{q_1, \dots, q_j\} = \text{span} \{a_1, \dots, a_j\} \quad j = 1, 2, \dots, n.$$

This amounts to:

$$\begin{bmatrix} a_1 & a_2 & \cdots & a_n \end{bmatrix} = \begin{bmatrix} q_1 & q_2 & \cdots & q_n \end{bmatrix} \begin{bmatrix} r_{11} & \cdots & r_{1n} \\ & \ddots & \vdots \\ & & r_{nn} \end{bmatrix}$$

i.e.

$$\begin{aligned} a_1 &= r_{11} q_1 \\ a_2 &= r_{12} q_1 + r_{22} q_2 \\ &\vdots \end{aligned}$$

Matrix form: $A = \hat{Q}\hat{R}$

- \hat{Q} has orthonormal columns, \hat{R} upper Δ .

QR factorization (full version)

- Append additional $m-n$ orthonormal columns to

i.e.

$$[q_{n+1} \ q_{n+2} \ \cdots \ q_m] \equiv \hat{Q}_{m-n}$$

Then

$$\begin{bmatrix} A \end{bmatrix}_{m \times n} = \begin{bmatrix} \hat{Q} & \hat{Q}_{m-n} \end{bmatrix}_{m \times m} \begin{bmatrix} \hat{R} \\ 0 \end{bmatrix}_{m \times n} \quad \left. \vphantom{\begin{bmatrix} \hat{R} \\ 0 \end{bmatrix}} \right\} \text{m-n zero rows}$$

- Usually for theoretical purpose.