

Tikhonov regularization

- $R(u) = \int_{\Omega} |u|^2 dx = \|u\|^2$

i.e.

$$\min_u \alpha \|u\|^2 + \|u - u^0\|^2$$

- Euler-Lagrange equation:

$$\alpha u + (u - u^0) = 0$$

$$(\alpha + 1)u = u^0$$

$$u = \frac{1}{\alpha + 1} u^0$$

- $\alpha \approx 0 \rightarrow u \approx u^0$
- $\alpha \approx \infty \rightarrow u \approx 0$

Laplacian regularization

- $R(u) = \int_{\Omega} |\nabla u|^2 dx$

i.e.

$$\min_u \alpha \|\nabla u\|^2 + \|u - u^0\|^2$$

The idea is to have small slopes, not small pixel values.

For noisy images, slopes are large.

- Euler-Lagrange equation:

$$\begin{aligned} -\alpha \Delta u + (u - u^0) &= 0 \\ -\alpha \Delta u + u &= u^0 \end{aligned}$$

- Finite difference approximation:

$$\frac{\alpha}{h^2} (4u_{i,j} - u_{i-1,j} - u_{i+1,j} - u_{i,j-1} - u_{i,j+1}) + u_{ij} = u_{i,j}^0$$

Matrix form:

$$\begin{aligned} \alpha A u + u &= u^0 \\ (\alpha A + I) u &= u^0 \end{aligned}$$

- If the solution u is still too noisy, repeat the procedure:

for $k = 0, 1, \dots, K$

Solve $(\alpha A + I) u^{k+1} = u^k$

end

Drawback: it tends to smear edges

Total variation regularization

- $R(u) = \int_{\Omega} |\nabla u| dx$

i.e. $\min_u \alpha \int_{\Omega} |\nabla u| dx + \|u - u^0\|^2$

Idea: still min the slopes, but don't get punished too much by it.

- Euler-Lagrange equation:

$$\begin{aligned} -\alpha \nabla \cdot \left(\frac{1}{|\nabla u|} \right) \nabla u + (u - u^0) &= 0 \\ -\alpha \nabla \cdot \left(\frac{1}{|\nabla u|} \right) \nabla u + u &= u^0 \end{aligned}$$

Note: in previous approach, the term $1/|\text{grad } u|$ is replaced by 1.

Near edges: $|\nabla u_{i,j}|$ is large $\Rightarrow \frac{1}{|\nabla u_{i,j}|}$ is small

$$\Rightarrow -\alpha \nabla \cdot \left(\frac{1}{|\nabla u_{i,j}|} \right) \nabla u \approx -\frac{\alpha}{|\nabla u_{i,j}|} \Delta u_{i,j} \approx 0$$

$$\Rightarrow u_{i,j} \approx u_{i,j}^0$$

On flat surfaces: $|\nabla u_{i,j}| \approx 0 \Rightarrow \frac{1}{|\nabla u_{i,j}|}$ is large

$$\Rightarrow -C \Delta u_{i,j} + u_{i,j} = u_{i,j}^0 \quad (C = \text{large constant})$$

\Rightarrow more diffusion at (i,j)

$\Rightarrow u_{i,j}$ is flat

- Euler-Lagrange is a nonlinear equation; the PDE coefficients depend on the solution.
- Finite difference approximation:

$$\begin{aligned}\alpha A(u) + u &= u^0 \\ (\alpha A(u) + I)u &= u^0\end{aligned}$$

Matrix entries depend on the solution u .

- One solution method for solving nonlinear equations is fixed point iteration.
- Fix the coefficients to make the equation linear and then update the coefficients iteratively.

for $k = 0, 1, \dots, K$

Solve $(\alpha A(u^k) + I) u^{k+1} = u^k$

end

- In general, pick an initial guess, compute an approx. solution by a simple procedure, then repeat this process iteratively.

Iterative Methods

Splitting

Let $A = M - N$ $M \approx A$

Then $Ax = b$

$$(M - N)x = b$$

$$Mx = Nx + b$$

Define an iterative method by:

$$Mx^{k+1} = Nx^k + b$$

Then
$$\begin{aligned}x^{k+1} &= M^{-1}Nx^k + M^{-1}b \\&= M^{-1}(M - A)x^k + M^{-1}b \\&= x^k + M^{-1}(b - Ax^k)\end{aligned}$$

Note: If $M = A$, then
$$\begin{aligned}x^{k+1} &= x^k + A^{-1}(b - Ax^k) \\&= x^k + x - x^k = x\end{aligned}$$

-> one step convergence

But one needs to compute $A^{-1}(b - Ax^k)$

Goals:

(1) $M \approx A$

(2) M^{-1} is easy to compute

Richardson iteration

- $M = 1/\theta I$ (θ is appropriately chosen)

Then $M^{-1} = \theta I$

Thus $x^{k+1} = x^k + \theta I (b - A x^k)$

Consider the i -th entry of x^{k+1} :

$$x_i^{k+1} = x_i^k + \theta(b_i - \sum_{j=1}^n a_{i,j} x_j^k)$$

Algorithm

x^0 = initial guess

for $k = 0, 1, 2, \dots$

for $i = 1, 2, \dots, n$

$$x_i^{k+1} = x_i^k + \theta(b_i - \sum_{j=1}^n a_{i,j} x_j^k)$$

end

end

Note

Need 2 separate vectors x^k, x^{k+1} .

Jacobi iteration

• $M = D = \text{diagonal of } A = \begin{bmatrix} a_{1,1} & & \\ & \ddots & \\ & & a_{n,n} \end{bmatrix}$

Then

$$M^{-1} = \begin{bmatrix} a_{1,1}^{-1} & & \\ & \ddots & \\ & & a_{n,n}^{-1} \end{bmatrix}$$

Thus

$$x^{k+1} = x^k + D^{-1}(b - Ax^k)$$

$$x_i^{k+1} = x_i^k + \frac{1}{a_{i,i}}(b_i - \sum_{j=1}^n a_{i,j}x_j^k)$$

$$= x_i^k + \frac{1}{a_{i,i}}(b_i - \sum_{j \neq i} a_{i,j}x_j^k - a_{i,i}x_i^k)$$

$$= \frac{1}{a_{i,i}}(b_i - \sum_{j \neq i} a_{i,j}x_j^k)$$

Interpretation

Let $r^k = b - Ax^k$ (residual vector of x^k)

Then $x^k = x \iff r^k = 0$

Thus $\|r^k\|_2 \approx 0 \Rightarrow x^k \approx x$

Consider
$$r_i^k = b_i - \sum_{j=1}^n a_{i,j}x_j^k = b_i - \sum_{j \neq i} a_{i,j}x_j^k - a_{i,i}x_i^k$$

In general, $r_i^k \neq 0$

Now modifying x_i^k so that $r_i^k = 0$.

i.e.

$$b_i - \sum_{j \neq i} a_{i,j} x_j^k - a_{i,i} x_i^{k+1} = 0$$

$$x_i^{k+1} = \frac{1}{a_{i,i}} (b_i - \sum_{j \neq i} a_{i,j} x_j^k)$$

-> Jacobi iteration

Algorithm

x^0 = initial guess

for $k = 0, 1, 2, \dots$

for $i = 1, 2, \dots, n$

$$x_i^{k+1} = \frac{1}{a_{i,i}} (b_i - \sum_{j \neq i} a_{i,j} x_j^k)$$

end

end

Note: need separate storage for x^k, x^{k+1} .

Gauss-Seidel iteration

Let $A = D - L - U$, where D = diagonal of A , L = strictly lower Δ part, U = strictly upper Δ part

i.e.

$$A = \begin{bmatrix} \cdot & \cdot & & -U \\ & D & & \\ -L & & \cdot & \cdot \end{bmatrix}$$

Then GS iteration: $M = D - L$ = lower Δ part of A .

i.e.
$$x^{k+1} = x^k + (D-L)^{-1} (b - A x^k)$$

Interpretation

Modify x_i^k so that $r_i^k = 0$. Use the new x_j^{k+1} , $j < i$, from the previous updates.

i.e.
$$r_i^k = b_i - \sum_{j < i} a_{i,j} x_j^{k+1} - a_{i,i} x_i^{k+1} - \sum_{j > i} a_{i,j} x_j^k = 0$$

Thus
$$x_i^{k+1} = \frac{1}{a_{i,i}} (b_i - \sum_{j < i} a_{i,j} x_j^{k+1} - \sum_{j > i} a_{i,j} x_j^k)$$

Algorithm

x^0 = initial guess

for $k = 0, 1, 2, \dots$

for $i = 1, 2, \dots, n$

$$x_i^{k+1} = \frac{1}{a_{i,i}} (b_i - \sum_{j < i} a_{i,j} x_j^{k+1} - \sum_{j > i} a_{i,j} x_j^k)$$

end

end

Note: No extra storage for x^{k+1} . x^{k+1} can be overwritten immediately.

Backward GS

- $M = D - U: \quad x^{k+1} = x^k + (D-U)^{-1} (b - Ax^k)$

Symmetric GS

A forward sweep followed by a backward sweep:

$$\begin{cases} x^{k+1/2} = x^k + (D-L)^{-1}(b - Ax^k) \\ x^{k+1} = x^{k+1/2} + (D-U)^{-1}(b - Ax^{k+1/2}) \end{cases}$$

$$\Leftrightarrow x^{k+1} = x^k + (D-U)^{-1} D(D-L)^{-1} (b - Ax^k)$$