# **Modal Logic Part1**

Dr. Igor Ivkovic

iivkovic@uwaterloo.ca

[with material from "Mathematical Logic for Computer Science", by Zhongwan, published by World Scientific; and "Modal Logic Tutorial", by N. Alechina, Midlands Graduate School in Foundations of CS, Online]

### **Objectives**

- Defining Modal Logic Formulas
- Satisfiability of Modal Logic
- Kripke Structures
- Using Modal Logic to Represent Programs

### In Classical Propositional Logic

Propositions are true or false

### In Modal Propositional Logic

- We distinguish between necessarily true and necessarily false propositions
- That is, each proposition is evaluated in a particular mode or context of interpretation
- Necessarily true propositions are said to be necessary
- Necessarily false propositions are said to be impossible
- Not impossible propositions are said to be possible ◊
- Possible propositions are all true propositions, either necessary or not necessary

#### What We Can and What We Cannot Assert?

- From the truth of A, we can assert the truth of "A is possible" but we cannot assert if "A is necessary"
  - Hmmm, why is that?
- From the falsehood of A, we can assert the falsehood of "A is necessary" but we cannot assert if "A is possible"
- As shown above, we shall use □ (instead of L in your textbook) to mean "necessary" or "always"
- And we shall use ◊ (instead of M in your textbook) to mean "possible" or "eventually"

- The Modal Propositional Language L<sup>pm</sup>
  - lacktriangle Created by adding the symbols  $\Box$  and  $\Diamond$  to  $L^{
    m p}$ 
    - □ Formally, only □ is added and ◊ is derived as ◊A ⇔ ¬□¬A
- **Definition 6.1. Form**( $L^{pm}$ ): (Section 8.1)
  - An expression of L<sup>pm</sup> is a formula of L<sup>pm</sup> iff it can be generated using the following (formation) rules:
    [1] Atom(L<sup>pm</sup>) ⊆ Form(L<sup>pm</sup>),
    [2] If A ∈ Form(L<sup>pm</sup>) then (¬A) ∈ Form(L<sup>pm</sup>),
    (□A) ∈ Form(L<sup>pm</sup>), and (◊A) ∈ Form(L<sup>pm</sup>)
    [3] If A, B ∈ Form(L<sup>pm</sup>) then (A \* B) ∈ Form(L<sup>pm</sup>), where \* stands for any of the standard binary connectives, from {∧, ∨, ⇒, ⇔}
  - Form( $L^{pm}$ ) can be abbreviated as WFMF

### ■ (Modal Logic) World:

- A conceivable state of affairs
- Also referred to as modal logic interpretation, or as valuation in the textbook

#### Definition 6.2. Values of Formulas: (Definition 8.2.3)

- Let K be a set of valuation for  $L^{pm}$  and let  $t \in K$  be the valuation of a formula; and let R be an equivalence relation on K
- $p^t \in \{1,0\}$  for atom p
- $\neg$  ( $\neg$ A)<sup>t</sup> = {1 if A<sup>t</sup> = 0; 0 otherwise}
- $(\Box A)^t = \{1 \text{ if for every } t_i \in K \text{ where } tRt_i, A^{ti} = 1; 0 \text{ otherwise} \}$
- $(\lozenge A)^t = \{1 \text{ if for some } t_i \in K \text{ where } tRt_i, A^{tj} = 1; 0 \text{ otherwise} \}$
- $(A \land B)^t = \{1 \text{ if } A^t = B^t = 1; 0 \text{ otherwise} \}$
- $(A \lor B)^t = \{1 \text{ if } A^t = 1 \text{ or } B^t = 1; 0 \text{ otherwise} \}$
- $(A \Rightarrow B)^t = \{1 \text{ if } A^t = 0 \text{ or } B^t = 1; 0 \text{ otherwise} \}$
- $(A \Leftrightarrow B)^t = \{1 \text{ if } A^t = B^t; 0 \text{ otherwise}\}$

### Definition 6.3. The Kripke Structure:

- Kripke structure (or modal interpretation) is a triple
   I = (W, R, V) such that
- W is a non-empty set of possible Worlds
- R ⊆ W x W is an accessibility Relation
- V: (Prop x W)  $\rightarrow$  {0, 1} is a Valuation function that assigns a propositional interpretation to each world
- Prop is a set of propositional symbols
- The pair (W, R) is called the frame of I
- Kripke Structure is just a graph with W defining the graph nodes and R defining the graph edges

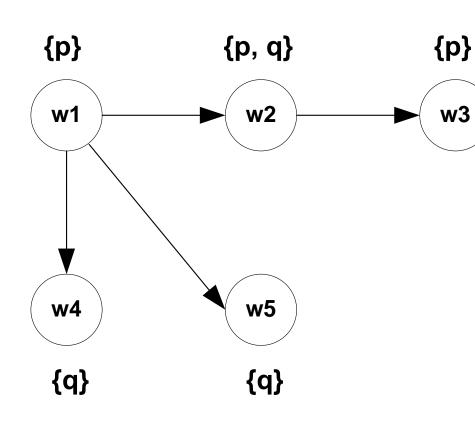
- Definition 6.4. Satisfiability and Validity: (Def. 8.2.4)
  - A set of formulas  $\Sigma \in \text{Form}(L^{\text{pm}})$  is satisfiable if there are truth valuations K, an equivalence relation R, and some truth valuation  $t \in K$ , such that  $\Sigma^{t} = 1$  by Def. 6.2 above
  - A formula  $A \in Form(L^{pm})$  is valid if for all truth valuations K, an equivalence relation R, and all truth valuation  $t \in K$ , it holds that  $A^t = 1$  as defined in Definition 6.2 above
- Framed differently, for a modal interpretation I, a world w, and well-formed formula A
  - If I satisfies A in the world w, this is denoted as I, w ⊨ A
     I, w can then be referred to as a (pointed) model of A
  - If I does not satisfy A in the world w, this is denoted as I, w ⊭ A

#### Satisfiability for the Kripke Structures:

- Given I = (W, R, V) and w ∈ W, we define what it means for a formula to be satisfied in a world w of I
- I,  $w \models p \text{ iff } V(p, w) = 1 \text{ for } p \in Prop$
- I,  $w \models \neg A \text{ iff } I, w \not\models A$
- I,  $w \models A \Rightarrow B$  iff either I,  $w \not\models A$  or I,  $w \models B$
- I, w  $\vDash$  ( $\square$ A) iff for all worlds  $v \in W$  accessible from w it holds that I,  $v \vDash A$
- I, w ⊨ (◊A) iff for some world v ∈ W accessible from w it holds that I, v ⊨ A

#### In addition:

- Modal formula A is valid if I, w ⊨ A holds for all interpretations I and all w ∈ W
- Modal formula A is satisfiable if I,  $w \models A$  holds for some interpretation I and some  $w \in W$
- Modal formula A is unsatisfiable otherwise



Example I (on the left):

- I, w1 ⊨ p
- I, w1 ⊨ □q
- I, w1 ⊨ ¬□p
- I, w1 ⊨ ¬□¬p
- I, w1 ⊨ ◊p
- I, w1 ⊨ ◊□p (why?)
- Valid:

  - $\blacksquare$   $\Box p \Rightarrow \Box p$
- Satisfiable:
  - $\square p \Rightarrow p$

### Definition 6.5. Modal Logic Frames:

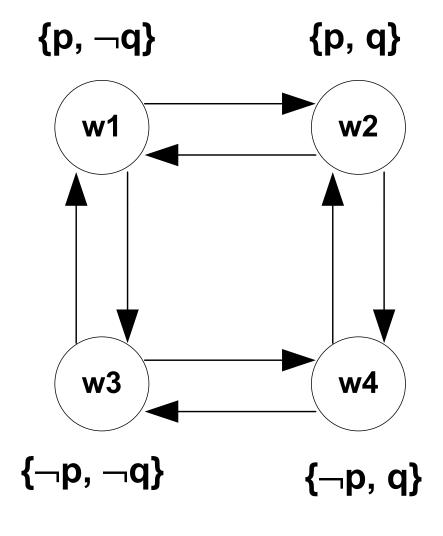
- A modal formula A characterizes a class of frames F if
   I, w ⊨ A for all I and w ∈ W where the frame (W, R) ∈ F
- And J, w ⊭ A for some J and w ∈ W where (W, R) ∉ F

### Some important formula that characterize frames:

- $\blacksquare$   $\Box$ p  $\Rightarrow$  p; defines reflexive frames (T)
- $\blacksquare$   $\Box$ p  $\Rightarrow$   $\Box$ p; defines transitive frames (4)
- $p \Rightarrow \Box \Diamond p$ ; defines symmetric frames (B)
- $\Box p \Rightarrow \Diamond p$ ; defines serial frames (D)
- □□p ⇒ □p; defines dense frames

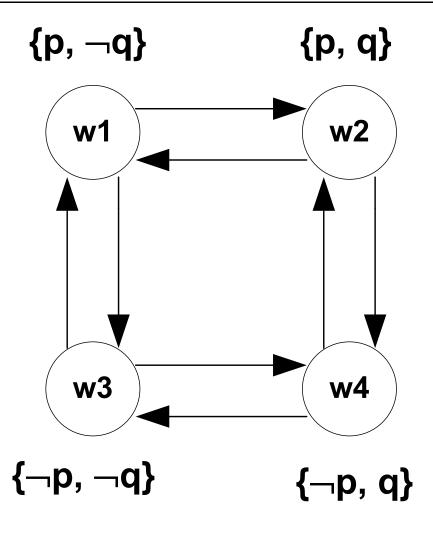
### Using Modal Logic:

- One can define possible worlds as states in computation
- R, the accessibility relation, can be viewed as a transition relation between states
- V, the valuation function, tells us which variables are set in which state
- That is, we can define a program and its states as a Kripke structure, and use the modal logic to formally define the properties of the program



### Expressing Program Structure Example:

- Let us assume that
   Boolean variables p and q
   are used in this program
- As the program
   transitions from one state
   (world) to another, it flips
   the parity of one variable,
   as shown on the left
- For instance, as it moves from w2 to w4 it makes p become not true



- What can you say about this program that holds true in all states?

  - Can you think of anything else?

### Food for Thought

#### Read:

- Chapter 8, Sections 8.1 and 8.2 from Zhongwan
  - Read the material discussed in class in more detail
  - Skip the material not mentioned in class
- Handout on "Modal Logic"
  - Available from the course schedule web page or through LEARN

### Answer Assignment #3 questions

- Assignment #3 includes several practice exercises related to Modal Logic
- The assignment will be posted by Thursday but it will be due after the midterm exam