02 Dec 2021

## 1. Vector Space

Let V be a vector space over F.

**Theorem 1.1.** Let  $S = \{v_1, v_2, ..., v_n\}$ . Then S is a linearly dependent set in V if and only if some one of the vectors in S can be expressed as a linear combination of the remaining vectors.

**Proof:** 

Assume that S'is Imearly dependent. Then 3 scalars  $\alpha_1, \alpha_2, --- \alpha_n$  in F (not all zeros) such that  $\alpha_1 V_1 + \alpha_2 V_2 + - - - + \alpha_n V_n = 0 -$ Let k be the largest such that  $\alpha_{k} \neq 0$ .

... O can be written as,

9/1/1+921/2+---+9/K-1/K-1+9/K/K+9/K+1/K+1 + 9/2 = 0

 $\Rightarrow \alpha_{K} V_{K} = -\alpha_{1} V_{1} + -\alpha_{2} V_{2} + -\alpha_{3} V_{3} + \cdots$  $-\alpha_{k-1}V_{k-1}+-\alpha_{k+1}V_{k+1}+\cdots$ 

 $\Rightarrow V_{k} = \left(\frac{-\alpha_{1}}{\alpha_{k}}\right)V_{1} + \left(\frac{-\alpha_{2}}{\alpha_{k}}\right)V_{2} + \cdots + \left(\frac{-\alpha_{k-1}}{\alpha_{k}}\right)V_{k-1}$ 

 $+\left(-\frac{\alpha_{K+1}}{\alpha_{K}}\right)V_{K+1}+\cdots+\left(\frac{\alpha_{N}}{\alpha_{K}}\right)V_{N}$ ie, lk is a linear combination of

V<sub>1</sub>,V<sub>2</sub>, ---, V<sub>K-1</sub>, V<sub>K+1</sub>, - --- V<sub>M</sub>

Conversely, assume that some one of the vector in S is a linear combination of remaining vectors ins To prove S is linearly dependent. Let  $V_j = \alpha_1 V_1 + \alpha_2 V_2 + \cdots + \alpha_{j-1} V_{j-1} + \alpha_{j+1} V_{j+1}$ 

Let  $V_j = \alpha_1 V_1 + \alpha_2 V_2 + \cdots + \alpha_{j-1} V_{j-1} + \alpha_{j+1} V_{j+1}$   $+ \cdots + \alpha_n V_n$ where  $\alpha_1, \alpha_2, \cdots, \alpha_{i-1}, \alpha_{i+1}$ 

where  $\alpha_{1,\alpha_{2}} - \cdots - \alpha_{j-1,\alpha_{j+1}}$   $-\cdots - \alpha_{n} \in F$ 

Then  $\alpha_1 V_1 + \alpha_2 V_2 + \cdots + \alpha_{j-1} V_{j-1} + (-1) V_j + \alpha_{j+1} V_{j+1} + \cdots + \alpha_n V_n = 0$ 

.. S= { V1, V2, --- W} is L.D.

Let V be a vector space over the field F.

**Theorem 1.2.** Let S be a linearly independent subset of V and  $T \subset S$  then T is linearly independent.

In other words, Every subset of a linearly independent set in V is linearly independent.

**Proof:** 

Let S= {V1, V2, --- Vn} be a linearly independent Subset of X.

Let  $T = \{V_1, V_2, --V_K\}$  where  $1 \le K < n$ Then  $T \subset S$ .

To prove T is linearly independent. Assume that T is linearly dependent. I scalars  $\alpha_1, \alpha_2, - \cdots - \alpha_k$  in F

(not all zeros) such that

 $\alpha_1 V_1 + \alpha_2 V_2 + - - - + \alpha_K V_K = 0$ 

 $\Rightarrow \alpha_1 V_1 + \alpha_2 V_2 + - - + \alpha_K V_K + 0 V_{K+1} + 0 V_{K+2} /$ 

+--.+ OVn = 0

Where some of the ois are non zero.

which is a contradiction to S is linearly independent.

1. Our assumption is wrong.
Tis linearly independent.

# of 
$$S = \{V_1, V_2 - \cdots V_n\} \subseteq V$$
  
then, the linear span of  $S$ ,
$$L(S) = \{k_1 V_1 + k_2 V_2 + \cdots + k_n V_n \mid k_1, \cdots k_2 \in F\}$$

$$E_{\underline{q}} : \text{ We know that } V = \mathbb{R}^2 \text{ is a}$$

$$\text{Vector space over } F = \mathbb{R}$$

$$\text{Consider } S = \{(I_1 I), (I_2 I_2)\} \subset \mathbb{R}$$
Then the linear span of  $S$  is
$$L(S) = \{k_1 V_1 + k_2 V_2 \mid k_1, k_2 \in \mathbb{R}\}$$

$$= \{k_1 (I_1 I_1) + k_2 (I_2 I_2) \mid k_1, k_2 \in \mathbb{R}\}$$

$$= \{(k_1 + k_2, k_1 + 2k_2) \mid k_1, k_2 \in \mathbb{R}\} \subseteq \mathbb{R}^2$$

**Theorem 1.3.** If  $S = \{v_1, v_2, ..., v_n\}$  is a linearly independent in V then every element in the linear span of S has a unique representation of the form  $\alpha_1v_1+\alpha_2v_2+...+\alpha_nv_n$  where  $\alpha_i \in F$ ,  $1 \le i \le n$ .

**Proof:** 

Given 
$$S = \{V_1, V_2 - \cdots V_n\}$$
 then

$$L(S) = \{\alpha_1 V_1 + \alpha_2 V_2 + \cdots + \alpha_n V_n \mid \alpha_1 \in \mathbb{F} \}$$

Let  $V \in L(S)$  then

$$V = \alpha_1 V_1 + \alpha_2 V_2 + \cdots + \alpha_n V_n \qquad D$$

Assume that  $V = \beta_1 V_1 + \beta_2 V_2 + \cdots + \beta_n V_n$ 

where  $\beta_1, \beta_2 - \cdots \beta_n \in F$ 

$$D - Q \Rightarrow O = (\alpha_1 - \beta_1) V_1 + (\alpha_2 - \beta_2) V_2 + \cdots + (\alpha_n - \beta_n) V_n$$

$$\Rightarrow \alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_3 - \beta_1 = O$$

$$\alpha_4 - \beta_1 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_3 - \beta_1 = O$$

$$\alpha_4 - \beta_1 = O$$

$$\alpha_5 - \beta_1 = O$$

$$\alpha_1 - \beta_1 = O$$

$$\alpha_2 - \beta_2 = O$$

$$\alpha_3 - \beta_1 = O$$

$$\alpha_4 - \beta_1 = O$$

$$\alpha_5 - \beta_1 = O$$

$$\alpha_5$$

The representation in L(S) is unique.

**Theorem 1.4.** If  $S = \{v_1, v_2, ..., v_n\}$  is a subset of the vector space V. If  $v_j$  is a linear combination of its preceding ones, then

$$L\{v_1, v_2, ..., v_{j-1}, v_{j+1}, ...v_n\} = L(S).$$

**Proof:** Since  $V_j$  is the linear combination of  $V_1, V_2, -... V_{j-1}$ , we can write  $\sqrt{j} = \alpha_1 V_1 + \alpha_2 V_2 + \cdots + \alpha_{j-1} V_{j-1}$  Where  $\alpha_1, \alpha_2 - \cdots - \alpha_{j-1} \in F$ To prove,  $L\{v_{1},v_{2},--v_{j-1},v_{j+1}--v_{n}\}\subseteq L(S)$ 

Let VE L\{\f\ V\_1,\f\ 2,---\f\ -1,\f\ j+1,---\f\ \}

then  $V = \beta_1 V_1 + \beta_2 V_2 + - - + \beta_{j-1} V_{j-1} + \beta_{j+1} V_{j+1}$ 

+--- + Bn Vn  $\Rightarrow V = \beta_1 V_1 + \beta_2 V_2 + - - - \beta_{j-1} V_{j-1} + 0 V_j +$ Bj+1 Vj+1 + -- + BnVn

 $\Rightarrow$   $V \in L(S)$   $\therefore L\{v_1, v_2, \dots v_{j-1}, v_{j+1}, \dots v_n\} \subseteq L(S) \longrightarrow (D)$ 

To prove,  $L(S) \subseteq L\{v_1, v_2, --- v_{j-1}, v_{j+1} --- v_n\}$ Let u ∈ L(S) then U= B1V1 +B2V2 +-- PBj-1Vj-1 +BjVj +Bj+1Vj+1+-.. + BnVn where B11B2 - - Bn ← F  $\Rightarrow U = \beta_1 V_1 + \beta_2 V_2 + \cdots + \beta_{j-1} V_{j-1} + \beta_j (\alpha_1 V_1 + \alpha_2 V_2 + \cdots + \alpha_{j-1} V_{j-1})$ +BjtyVjty + --- + Bn Vn EF  $\Rightarrow U = (\beta_1 + \beta_1 \alpha_1) V_1 + (\beta_2 + \beta_3 \alpha_2) V_2 + \cdots + (\beta_{j-1} + \beta_j \alpha_{j-1}) V_j$ EF +Bj+1Vj+1 +--- + BnVn le, UIS a linear combination of V1, V2, --- Vj-1, Vj+1 --- Vn  $\Rightarrow$   $u \in L \left\{ v_{1,1}v_{2,1}, ---v_{j-1}, v_{j+1}, --- v_{m} \right\}$ ⇒ L(S) ⊆ L {V1, V2 - - - Vj-1, Vj+1 - - - Vn3 -...(542) => L{V1--..Vj-1,Vj+1,---Vn} = L(S)//

**Theorem 1.5.** If  $S = \{v_1, v_2, ..., v_n\}$  is a basis for the vector space V then the representation of any element in V in terms of basis elements is unique.

Proof: Of Sis a basis for V

then (i) Sis linearly independent

(ii) S spans V

ie; L(S) = V:

Since the representation of elements
in L(S) is unique; we've,

The representation of elements in V

The representation of elements in V in terms of basis elements is unique Definition 1.7. (Minimal Spanning set)

let V be a vector space over filet SCV then S is said to be a minimal spanning set if (i) S is a spanning set for V.

(ii) S\{V\} donot span V for any V \in S

**Theorem 1.8.** In a vector spave V, a minimal spanning set of vectors forms a basis.

Let S'be a minimal spanning set for V. Then S spans V.é; L(s)=V In order to prove that S is a basis for V, it is enough to Show that S is linearly independent. Assume that S is linearly dependent. then there exists Vj (for some j, 1 \le j \le n) is a linear combination of its

preceeding ones.

ie;  $V_j = \alpha_1 V_1 + \alpha_2 V_2 + \cdots + \alpha_{j-1} V_{j-1}$ where  $\alpha_1, \alpha_2 - \cdots + \alpha_{j-1} \in F$ 

Then  $L\{V_1, \dots, V_{j-1}, V_{j+1}, \dots, V_n\} = L(S) = V$ 

⇒ {V<sub>1</sub>,V<sub>2</sub> -- V<sub>j-1</sub>, V<sub>j+1</sub> -- V<sub>n</sub>} 8 pans V
⇒ S\{v<sub>j</sub>} 8 pans V, contradiction to Sis a minimal - 8 panning set.

∴ Our assumption is wrong.

∴ Only possibility is Si8 linearly 9 ndependent.

∴ S forms a basis for V.

Definition 1.9. (Maximal linearly independent set)

Let V be a vector space over f. Let SSV then S is said to be a maximal linearly independent set if

(i) S is linearly independent ii) SU{V} is linearly dependent for any V ∈ VIS

**Theorem 1.10.** In a vector spave V, a maximal linearly indepen-

Proof: Let 
$$S = \{V_1, V_2, \dots, V_n\}$$
 be a maximal linearly independent set for  $V$ .

To prove  $S$  forms a basis for  $V$ .

Ot is enough to prove that  $S$ 

Suppose  $S = \{V_1, V_2, \dots, V_n\}$  be a maximal linearly independent set for  $V$ .

Take  $S = \{V_1, V_2, \dots, V_n\}$  be a maximal linearly independent set for  $V$ .

Suppose  $S = \{V_1, V_2, \dots, V_n\}$  be a maximal linearly independent  $S = \{V_1, V_2, \dots, V_n\}$  be a maximal linearly independent  $S = \{V_1, V_2, \dots, V_n\}$  be a maximal linearly independent; a

=> SU{v} is linearly independent; a contradiction to the maximality of S.

... The Only possibility is  $\alpha \neq 0$ 

 $\Rightarrow \forall V = -\alpha_1 V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + - - - + (-\alpha_3) V_n$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_2) V_2 + (-\alpha_3) V_1$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_3) V_3$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_3) V_3$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_3) V_3$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_3) V_3$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_2) V_3$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_2) V_3$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_2) V_3$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_2) V_3$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_2) V_3$   $\Rightarrow V = (-\alpha_1) V_1 + (-\alpha_2) V_2 + (-\alpha_2) V_3$ 

 $\times$  We know that  $\mathbb{R}^n$  is a vector space over  $\mathbb{R}$ . Also, we have,  $\dim(\mathbb{R}^n) = n$  (since, no of elements in the basis of  $\mathbb{R}^n$  is n')
So, the maximum number of linearly independent vectors in  $\mathbb{R}^n$  is 'n'.

... By the previous theorem, a linearly independent set with 'n' vectors in R<sup>n</sup> forms a basis for R<sup>n</sup>.

Eg: Let  $S = \{(1,-1), (-1,2)\} \subseteq \mathbb{R}^2$ 

Here, let  $\alpha_1 V_1 + \alpha_2 V_2 = 0$  then,  $\alpha_1 (1,-1) + \alpha_2 (-1,2) = 0 = (0,0)$ 

$$\Rightarrow (\alpha_1 - \alpha_2, -\alpha_1 - \alpha \alpha_2) = (0, 0)$$

$$\Rightarrow \frac{\alpha_1 - \alpha_2 = 0}{-\alpha_1 - \alpha_2 \alpha_2 = 0}$$
 
$$\Rightarrow \frac{\alpha_1 - \alpha_2 = 0}{-\alpha_1 - \alpha_2 \alpha_2 = 0}$$
 
$$\Rightarrow \frac{\alpha_1 - \alpha_2 = 0}{-\alpha_1 - \alpha_2 \alpha_2 = 0}$$

S is a linearly independent set in R2 with '2' vectors.

... S forms a basis for R<sup>2</sup>