THE MAP WON'T SHOW BECAUSE IM USING A WEBSITE

Learn Robotics from Zero - Robotics & ROS Online Courses

#581   +

```
process[master]: started with pid [30329]
ROS_MASTER_URI=http://localhost:11311

setting /run_id to c7ff4e56-d409-11eb-96a7-0242c0a84007
process[rosout-1]: started with pid [30357]
started core service [/rosout]
process[turtlebot3_teleop_keyboard-2]: started with pid [30360]

Control Your TurtleBot3!
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Moving around:
        w
   a    s    d
        x

w/x : increase/decrease linear velocity (Burger : ~ 0.22, Waffle and
Waffle Pi : ~ 0.26)
a/d : increase/decrease angular velocity (Burger : ~ 2.84, Waffle and
 Waffle Pi : ~ 1.82)

space key, s : force stop

CTRL-C to quit
```