Approximation Algorithms

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Review: Decision Problems vs Optimization Problems in NP

Given any **Opt** Problem Min-P = (X, Y(x), m(x, Y(x)), MIN/MAX) we can always define the corresponding **Decision Problem** k-P = (X, Y(x), m(x, Y(x)), <= k (>= k))

FACT (Definition).

the corresponding **Opt** problem **Min-P** is **NP-hard IFF**the decision problem **k-P** is **NP-Hard**

COR. IF P # NP and Min-P is NP-hard, THEN there is no poly-time deterministic algorithm for it.

Approximation Ratio (Error)

Optimization Problem

Given an optimization problem P = (X, Y(x), m(x, Y(x)), MIN/MAX), we say A is an r-approximation algorithm for P if, for any instance $x \in X$, the computation A(x) returns a <u>feasible</u> solution y^A such that:

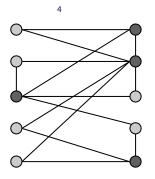
$$\frac{m(x, y^A)}{\operatorname{opt}(x)} \ge r$$
 (in the case of **MAX**)

Min-Vertex Cover

k-VC: Given a graph G = (V, E) and an integer k, is there a **k-size VC**, i.e., a subset of vertices $S \subseteq V$ such that $|S| \le k$, and for each edge, at least one of its endpoints is in S?

Min-VC: Given a graph G = (V, E), find a VC S^* for G of minimum size

Ex. there min-VC for the graph below has size 4.



vertex cover

A lower bound for optimal VC

Matching and Covering

FACT 1: Given any graph G(V, E), consider any **Maximal Matching** $M \subseteq E$. Then, any VC for G must contain at least 1 vertex for every edge in M.

Proof.

immediate consequence of def.s of Matching and VC.

- Remind: Matching = any subset of **disjoint** edges

Lower Bound for the Optimum

FACT 2:

opt(G) | M



An apx algorithm for Min VC

Matching Algorithm M - ALG

- ▶ Input: G(V, E);
- ► Find (any) Maximal Matching M;
- ▶ Return C = { all nodes touched by M};

DEFINITIONS

An apx algorithm for Min VC

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- ▶ Input: G(V, E);
- ► Find (any) Maximal Matching *M*;
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THM 3.

M-ALG is a 2-apx algorithm for Min-VC.

Proof of THM 3

M-ALG

FACT 4. The returned solution C(i) is always a Vertex Cover for GAND (ii) |C| = 2|M|.

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$$\frac{|C|}{\mathsf{opt}(G)} \qquad \frac{2|M|}{|M|}$$

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