Parallelism in Four Numerical Computational Algorithms

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Intro

Non-parallel and parallel numerical algorithms are very important to every aspect of computer science in today's world.

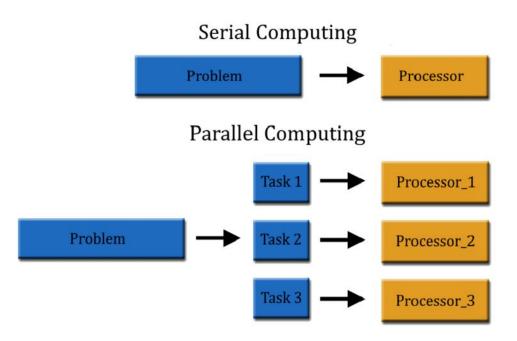
There are countless applications that require parallel computation to efficiently complete a goal.

My Plan

- The study focuses on implementing four different algorithms:
 - Matrix-matrix multiplication with a simple algorithm
 - Solving a linear system with Gaussian Elimination
 - LU decomposition with Doolittle's Algorithm
 - Approximating the largest eigenvalue with the Power Method
- Compare each algorithms performance and accuracy between parallel and non-parallel implementations.

What does "parallel" mean

Parallel processing refers to the use of multiple processors or cores within a computer system to simultaneously execute multiple tasks or parts of a single task.



MPI & C/C++

- MPI (Message Passing Interface) is a standard library for parallel computing that enables communication between processes running on different nodes in a distributed system.
- C/C++ are programming languages commonly used for system programming,
 software development, and numerical computing.
- Can use MPI in C/C++ to make parallel numerical algorithms, you can divide the tasks into smaller subtasks that can be solved concurrently on different nodes using MPI calls





Matrix-Matrix Multiplication

Matrix-matrix multiplication is the process of multiplying two matrices together to produce a third matrix by taking the dot product of each row of the first matrix with each column of the second matrix.

```
procedure MATMAT_SERIAL(A,B,C,n) for i \leftarrow 0 to n-1 do for j \leftarrow 0 to n-1 do C_{i,j} \leftarrow 0 for k \leftarrow 0 to n-1 do C_{i,j} \leftarrow C_{i,j} \leftarrow C_{i,j} + A_{i,k} \times B_{k,j} end for end for end procedure
```

Flops $\sim O(n^3)$

Matrix-Matrix Multiplication

```
procedure MATMAT PARALLEL(A, B, C, n, rank, size)
    rows per proc \leftarrow n/size
    leftover\ rows \leftarrow n \mod size
    C\_local \leftarrow matrix of size rows\_per\_proc \times n and 0
    start\_row \leftarrow rank \times rows\_per\_proc
    end\_row \leftarrow start\_row + rows\_per\_proc
    if rank = size - 1 then
        end \ row \leftarrow end \ row + leftover \ rows
    end if
   for i \leftarrow start\_row to end\_row - 1 do
        for j \leftarrow 0 to n-1 do
            for k \leftarrow 0 to n-1 do
                C\_local_{i-start\ row.i} \leftarrow
                C_{local_{i-start\ row,i}} + A_{i,k} \times B_{k,i}
            end for
        end for
    end for
    MPI_Allreduce combines the local to global result
    for i \leftarrow start\_row to end\_row - 1 do
        for j \leftarrow 0 to n-1 do
            C_{i,j} \leftarrow C\_local_{i-start\_row,j}
        end for
    end for
end procedure
```

Flops ~ O(n³ / p)
Where p is the the
total number of
processes.

Solve Linear System with Gaussian Elimination

Gaussian elimination is an algorithm used to solve a system of linear equations by transforming the augmented matrix into an upper triangular matrix through a series of row operations. Once the matrix is in upper triangular form, back substitution can be used to solve for the unknown variables.

```
procedure GE SERIAL(A, b, x, n)
    for k \leftarrow 0 to n-1 do
         for i \leftarrow k+1 to n do
              xmult \leftarrow A_{i,k}/A_{k,k}
              for j \leftarrow k to n do
                   A_{i,j} \leftarrow A_{i,j} - xmult \times A_{k,j}
              end for
              b_i \leftarrow b_i - xmult \times b_k
         end for
    end for
    x_{n-1} \leftarrow b_{n-1}/A_{n-1,n-1}
    for i \leftarrow n-2 down to 0 do
         s \leftarrow b_i
         for j \leftarrow i+1 to n do
              s \leftarrow s - A_{i,j} \times x_j
         end for
         x_i \leftarrow s/A_{i,i}
    end for
end procedure
```

Flops $\sim O(n^3)$

Solve Linear System with Gaussian Elimination

```
procedure GE\_PARALLEL(A, b, x, n, rank, size)
    chunk\_size \leftarrow n/size
    start \leftarrow rank \cdot chunk \ size
    end \leftarrow start + chunk \ size
    if rank = size - 1 then
        end \leftarrow n
    end if
    for k \leftarrow 0 to n-1 do
        pivot\_row \leftarrow array of n zeros
        if rank = k/chunk\_size then
            for j \leftarrow 0 to n-1 do
                pivot\_row_i \leftarrow A_{k,i}
            end for
        end if
        MPI_Bcast to all processes
```

```
for i \leftarrow start to end - 1 do
             if i \le k then
                  continue
             end if
             xmult \leftarrow A_{i,k}/pivot\_row_k
             for j \leftarrow k to n-1 do
                  A_{i,j} \leftarrow A_{i,j} - xmult \cdot pivot\_row_i
             end for
             b_i \leftarrow b_i - xmult \cdot b_k
         end for
         MPI_Barrier to halt processes
    end for
    for i \leftarrow end - 1 down to start do
         s \leftarrow b_i
         for j \leftarrow i+1 to n-1 do
             s \leftarrow s - A_{i,j} \cdot x_i
         end for
         x_i \leftarrow s/A_{i,i}
    end for
    MPI Allgather to gather solutions
end procedure
```

Flops ~ O(n³ / p)
Where p is the the
total number of
processes.

LU Factorization with Doolittle's Algorithm

Doolittle's algorithm for LU factorization is a numerical method that decomposes a matrix into a lower triangular matrix and an upper triangular matrix such that the product of these two matrices is equal to the original matrix. The algorithm is based on the Gaussian elimination method and uses partial pivoting to avoid division by small numbers.

procedure DOOLITTLE_SERIAL(A, L, U, n)for $k \leftarrow 0$ to n-1 do for $j \leftarrow k$ to n-1 do $sum \leftarrow 0$ for $p \leftarrow 0$ to k-1 do $sum \leftarrow sum + L_{k,n} \times U_{n,i}$ end for $U_{k,j} \leftarrow A_{k,j} - sum$ end for for $i \leftarrow k+1$ to n-1 do $sum \leftarrow 0$ for $p \leftarrow 0$ to k-1 do $sum \leftarrow sum + L_{i,p} \times U_{p,k}$ end for $L_{i,k} \leftarrow (L_{i,k} - sum)/U_{k,k}$ end for end for end procedure

Flops $\sim O(n^3)$

LU Factorization with Doolittle's Algorithm

end procedure

```
 \begin{array}{l} \textbf{procedure} \  \, \textbf{DOOLITTLE\_PARALLEL}(A,L,U,n,rank,size) \\ block\_size \leftarrow n/size \\ L\_local,U\_local \leftarrow \text{create} \ block\_size \times n \ \text{matrices} \\ \textbf{for} \ i \leftarrow 0 \ \text{to} \ block\_size - 1 \ \textbf{do} \\ L\_local_{i,i} \leftarrow 1 \\ \textbf{for} \ j \leftarrow 0 \ \text{to} \ n-1 \ \textbf{do} \\ U\_local_{i,j} \leftarrow 0 \\ \textbf{end for} \\ \textbf{end for} \\ A\_block \leftarrow \text{new double array of size} \ block\_size \times n \\ MPI \ Scatter \ \text{to} \ distribute} \ data \\ \end{array}
```

```
for k \leftarrow 0 to block size - 1 do
    for j \leftarrow k to n-1 do
        sum \leftarrow 0
        for p \leftarrow 0 to k-1 do
            sum \leftarrow sum + L \ local_{k,n} \times U \ local_{n,i}
        end for
        U_local_{k,i} \leftarrow A_block_{k*n+i} - sum
    end for
    for i \leftarrow k+1 to block size-1 do
        sum \leftarrow 0
        for p \leftarrow 0 to k-1 do
            sum \leftarrow sum + L\_local_{i,n} \times U\_local_{n,k}
        end for
        L\_local_{i,k} \leftarrow (A\_bloc_{i*n+k} - sum)/U\_local_{k,k}
    end for
end for
MPI_Barrier to halt processes
for i \leftarrow 0 to size - 1 do
    if i = rank then
        MPI Send local U block
        MPI Send local L block
    else if rank = 0 then
        MPI Recv local U block
        MPI_Recv local L block
    end if
end for
```

Flops ~ O(n³ / p)
Where p is the the
total number of
processes.

Largest Eigenvalue Approximation with Power Method

The Power method is an iterative numerical algorithm used to find the largest/dominant eigenvalue and corresponding eigenvector of a square matrix by repeatedly multiplying the matrix by a vector and normalizing the result. The algorithm is based on the fact that if the matrix is diagonalizable, then the dominant eigenvalue will be the one with the largest absolute value, and the corresponding eigenvector will be in the direction of the dominant eigenvector.

```
procedure POWER_SERIAL(A, n, iters, tol)
      \lambda \leftarrow 0.0
     \lambda_{old} \leftarrow 1.0
     x \leftarrow [1.0, 1.0, ..., 1.0]
     for iter \leftarrow 1 to iters and |\lambda - \lambda_{old}| > tol do
           \lambda_{old} \leftarrow \lambda
           for i \leftarrow 1 to n do
                 y_i \leftarrow 0.0
                 for j \leftarrow 1 to n do
                      y_i \leftarrow y_i + A_{i,j} \cdot x_j
                 end for
           end for
           \lambda \leftarrow 0.0
           norm_x \leftarrow 0.0
```

```
for i \leftarrow 1 to n do
               \lambda \leftarrow \lambda + y_i \cdot x_i
               norm_x \leftarrow norm_x + x_i^2
          end for
          \lambda \leftarrow \lambda/norm_x
          norm\_x_{new} \leftarrow 0.0
          for i \leftarrow 1 to n do
               x_i \leftarrow y_i/\lambda
               norm\_x\_new \leftarrow norm\_x\_new + x_i^2
          end for
          norm\_x\_new \leftarrow \sqrt{norm\_x\_new}
          for i \leftarrow 1 to n do
               x_i \leftarrow x_i/norm \ x_new
          end for
     end for
end procedure
```

Flops ~ O(kn²)
Where k is the the total number of iteration.

Largest Eigenvalue Approximation with Power Method

```
procedure POWER_PARALLEL(A, n, iters, tol, rank, size)
   double \lambda = 1.0, \lambda_{old} = 0.0
   for i = 0 to n - 1 do
       x_i = 1.0
   end for
   chunk \ size = n/size
   start\_index = rank * chunk\_size
   end index = start index + chunk size
   for iter = 0 to iters - 1 and |\lambda - \lambda_{old}| > eps do
       \lambda_{old} = \lambda
       for i = start index to end index -1 do
           y_i = 0.0
           for j=0 to n-1 do
              y_i = y_i + A_{i,j} * x_j
           end for
       end for
       double local lambda = 0.0, norm x = 0.0
```

```
for i = start\_index to end\_index - 1 do local\_lambda = local\_lambda + y[i] * x[i] norm\_x = norm_x + x[i] * x[i] end for MPI\_Allreduce sums local \lambda to global result MPI\_Allreduce sums local norm to global result \lambda = \lambda/norm\_x for i = start\_index to end\_index - 1 do x[i] = y[i]/\lambda end for MPI\_Allgather to gather solutions end for end procedure
```

Flops ~ O(kn² / p)
Where p is the the
total number of
processes.

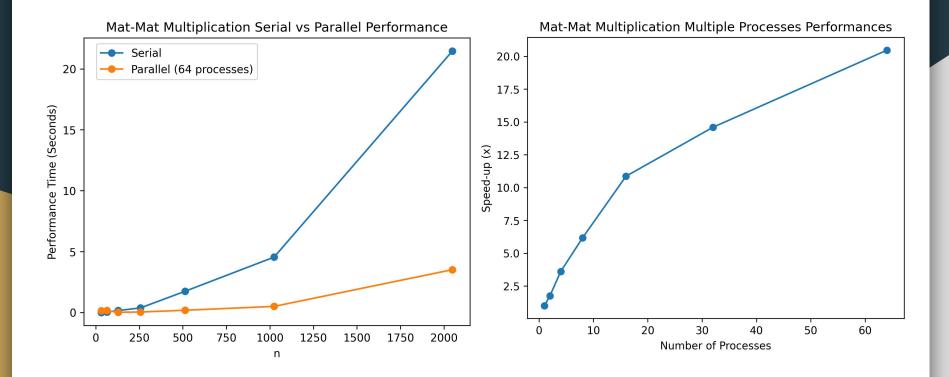
Results

Findings (Matrix-matrix multiplication)

n	Serial Error	Parallel Error
32	4.379e-13	2.309e-13
64	7.081e-13	6.714e-13
128	4.945e-12	8.226e-12
256	3.162e-11	1.492e-11
512	5.813e-11	5.824e-10
1024	1.247e-10	3.997e-10
2048	8.039e-10	1.784e-9

Smaller matrices of dimensions such as 10x10 to 25x25 matrices seemed to have very small numerical errors (~1e-13), but as the matrix increased, numerical errors also increased. Numerical errors seem to increase with at most of an error at the 2048x2048 matrices that had numerical errors or !1e-10 and no larger or smaller. As matrices grown, numerical errors increase.

Findings (Matrix-matrix multiplication)

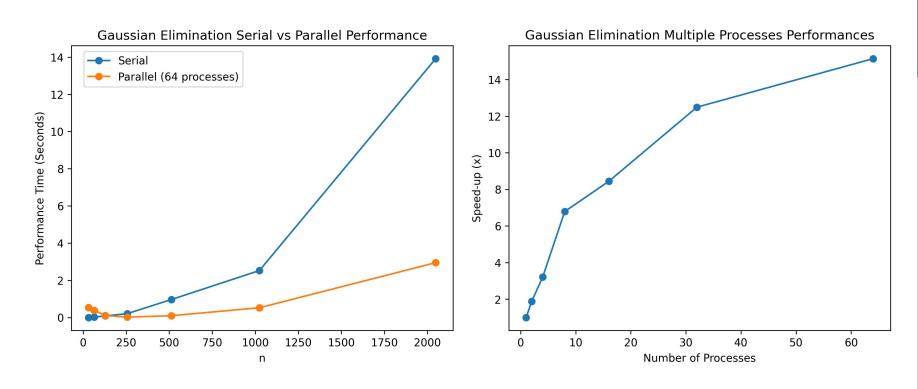


Findings (Gaussian Elimination)

n	Serial Error	Parallel Error
32	8.401e-11	7.135e-11
64	8.909e-10	2.673e-10
128	3.769e-10	7.008e-10
256	7.535e-10	4.921e-10
512	6.219e-10	2.755e-10
1024	8.814e-10	4.279e-10
2048	5.223e-9	3.439e-9

It was a pleasant surprise that there very little numerical errors in comparison to the serial version of the algorithm. In the table above, there is a significant drop in accuracy as the dimensions of the input matrix and vector increase, but both algorithms are very comparable in numerical accuracy.

Findings (Gaussian Elimination)

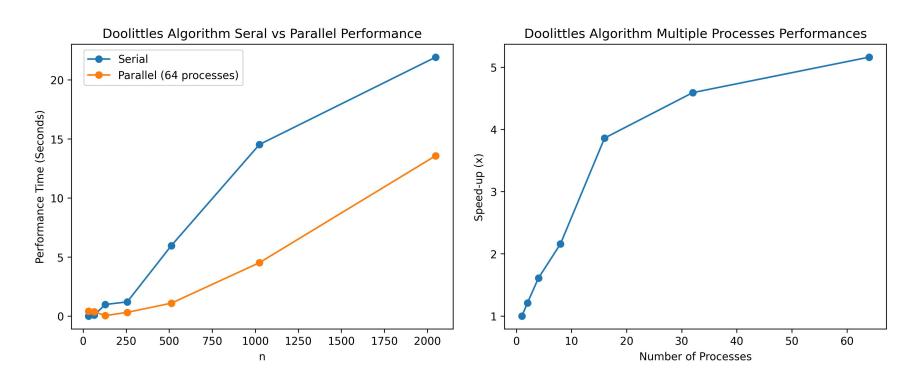


Findings (Doolittle's Algorithm)

n	Serial Error	Parallel Error
32	9.385e-11	8.762e-10
64	5.223e-11	3.891e-10
128	1.807e-11	5.924e-10
256	6.937e-10	2.546e-9
512	3.281e-10	2.506e-9
1024	2.451e-10	6.845e-8
2048	7.379e-9	1.064e-8

As you see in the table above, the numerical errors are notablably bigger for the parallel algorithm compared to the serial version of the algorithm. I believe that since I used point-to-point alongside the block method of distributing tasks, that there was some numerical errors that significantly impacted the algorithms accuracy itself.

Findings (Doolittle's Algorithm)

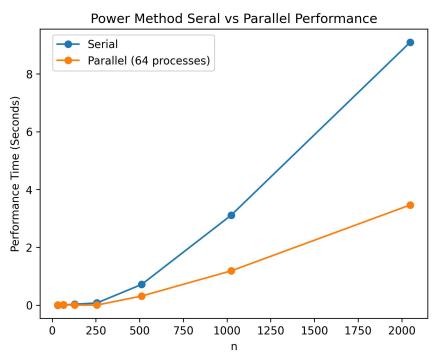


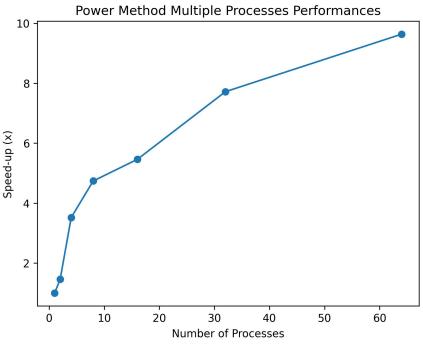
Findings (Power Method)

n	Serial Error	Parallel Error
32	4.735e-10	1.275e-10
64	0.944e-10	4.674e-10
128	7.019e-10	7.939e-10
256	1.803e-10	5.101e-10
512	5.610e-10	9.086e-10
1024	8.561e-8	3.370e-8
2048	2.001e-8	7.782e-8

With the tolerance level set to 1e-10 and maximum iteration number set to 10000, that allowed experimentation for both numerical accuracy and performance testing. Both algorithms are very comparable with some minor accuracy improvement in the serial algorithm, but nothing that will be concerning.

Findings (Power Method)





Conclusion & Takeaways

- MPI can be utilized in many ways to make serial numerical algorithms parallel.
- Speed up is guaranteed with a suitable parallel implementation.
- Performance of parallel numerical algorithms depends on many factors including hardware, communication overhead and many more.
- Parallel algorithms can potentially cause more numerical errors, but will never increase accuracy.
- Careful design and optimization practices must take place to ensure success.
- Parallel algorithms are not always the best fit for all situations.

Thank you!