Challenge 8 Rubric: Autonomous

What the scores mean

General (0-5, 5 is highest)	Rating	Max	0	1	2	3	4	5
Quality of solution		5	Nonfunctional	Some elements	Meets	Meets	Exceeds	Well thought
				missing or	requirements,	requirements	requirements.	out, design
				nonfunctional,	but possibly	and performs	Evidence of	decisions
				unreliable	flaky	function as	solution going	supported;
					performance	specified. Robust	beyond baseline.	extensible for
								future challenge
Quality of written		3	Not posted	Lack of depth	Evidence of	Clear, consise,		
presentation				on content. Just	technical	complete,		
				repeating the	knowledge and	articulate. Depth		
				assignment	challenges	of technical		
				statement.	solved shown	discourse.		
					above baseline			
Quality of code		3	Not posted	Little or no	Average	Exceptional.		
management on github				management		Show branching,		
						merging,		
						commits		
Quality of oral presentation		3	Not posted	Long,	Average	Clear, concise,		
(presenter only)				disorganized,		complete,		
				incomplete,		articulate		
				incoherent				
Quality of video		3	Not posted	Long,	Average	Clear, concise,		
				disorganized,		complete,		
				incomplete,		articulate		
				incoherent				
Other qualitative							_	
Integrates beacons for		3	No	Tripwires	Plus	Plus Knn		
finding waypoints using					Trilateration			
trilateration and/or knn								
positioning.								
Quality of driving, speed,		3	Jerky or	Slow but steady	Avg	Fast and steady		
jerkyness			erratic					
Quality of UI at remote		3	None	Basic UI but	Avg	Responsive to		
terminal including				control issues or		actual position,		
positioning and latency				unsuable		able to control		
				latency		car successfully		
Evidence of adaptability to		1	No	Yes				
other track configurations	l	1				I	I	

Required elements (0/1, 1=met)

1=met)			
PPT, video, link to github	1	No	Yes
provided in single posting			
Drives without hitting walls	1	No	Yes
between waypoints and is			
stable within epsilon			
Successfully makes turns at	1	No	Yes
waypoints.			
Completes entire course	1	No	Yes
without human			
intervention in one try (first			
lap)			
Car controllable from	1	No	Yes
remote terminal in other			
location and network			
(second lap)			
Position and FPV reported	1	No	Yes
in real time on remote			
display			

itative 0	21
Requirements 0	6
Requirements	

Quintile (1/2/3/4/5), 1 is	1
highest	