

ITCT Lecture 2: Entropy, Relative Entropy and Mutual Information

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1

- Definition: The **Entropy** $H(X)$ of a discrete random variable X is defined by

$$H(x) = - \sum_{x \in X} P(x) \log P(x)$$

$(H(P))$

\log : base 2 $\rightarrow H(P)$: bits

$0 \log 0 = 0$ (xlogx as $x \rightarrow 0$)

: adding terms of zero probability does not
change the entropy

Information Theory



2

Note that entropy is a function of the distribution of X . It does not depend on the actual values taken by the *r.v.* X , but only on the probabilities.

If $(X, P(x))$, then the expected value of the *r.v.* $g(x)$ is written as

$$E_{\substack{p \\ (Eg(x))}} g(x) = \sum_{x \in X} g(x) P(x)$$

Expectation value

Remark : The entropy of $X \rightarrow$ the expected value of $\log \frac{1}{P(x)}$

$$H(x) = E \left[\log \frac{1}{P(x)} \right]$$

Self-information

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3

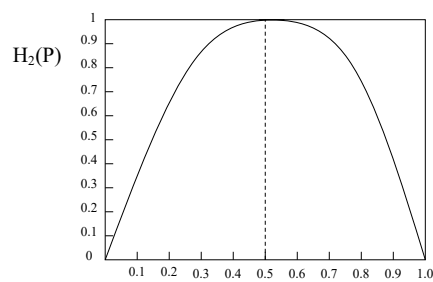
■ Lemma 1.1: $H(x) \geq 0$

■ Lemma 1.2: $H_b(x) = (\log_b a) H_a(x)$

Ex:

$$X = \begin{cases} 0 & , \quad P(0) = P \\ 1 & , \quad P(1) = 1 - P \end{cases}$$

$$H(X) = -P \log P - (1 - P) \log(1 - P) \stackrel{\text{def}}{=} H_2(P)$$



- 1) $H(x) = 1$ bits when $P = 1/2$
- 2) $H(x)$ is a **concave** function of P
- 3) $H(x) = 0$ if $P = 0$ or 1
- 4) $\max H(x)$ occurs when $P = 1/2$

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4

Joint Entropy and Conditional Entropy

- Definition: The **joint entropy** $H(X, Y)$ of a pair of discrete random variables (X, Y) with a joint distribution $P(x, y)$ is defined as

$$H(X, Y) = - \sum_{x \in X} \sum_{y \in Y} P(x, y) \log P(x, y)$$

or

$$H(X, Y) = -E \log P(X, Y)$$

- Definition: The **conditional entropy** $H(Y|X)$ is defined as

$$H(Y|X) = \sum_{x \in X} P(x) H(Y|X=x)$$

$$= - \sum_{x \in X} P(x) \sum_{y \in Y} P(y|x) \log P(y|x)$$

$$= - \sum_{x \in X} \sum_{y \in Y} P(x, y) \log P(y|x)$$

$$= -E_{P(x,y)} \log P(Y|X)$$

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5

- Theorem 1.1 (Chain Rule):**

$$H(X, Y) = H(X) + H(Y|X)$$

pf :

$$H(X, Y) = - \sum_{x \in X} \sum_{y \in Y} P(x, y) \log P(x, y)$$

$$= - \sum_{x \in X} \sum_{y \in Y} P(x, y) \log P(x) P(y|x)$$

$$= - \sum_{x \in X} \sum_{y \in Y} P(x, y) \log P(x) - \sum_{x \in X} \sum_{y \in Y} P(x, y) \log P(y|x)$$

$$= - \sum_{x \in X} P(x) \log P(x) - \sum_{x \in X} \sum_{y \in Y} P(x, y) \log P(y|x)$$

$$= H(X) + H(Y|X)$$

or equivalently, we can write

$$\log P(X, Y) = \log P(X) + \log P(Y|X)$$

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6

Corollary:

$$H(X, Y|Z) = H(X|Z) + H(Y|X, Z)$$

Remark:

(i) $H(Y|X) \neq H(X|Y)$

(II) $H(X) - H(X|Y) = H(Y) - H(Y|X)$

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7

Relative Entropy and Mutual Information

- The entropy of a random variable is a measure of the uncertainty of the random variable; it is a measure of the amount of information required on the average to describe the random variable.
- The relative entropy is a measure of the distance between two distributions. In statistics, it arises as an expected logarithm of the likelihood ratio. The relative entropy $D(p||q)$ is a measure of the inefficiency of assuming that the distribution is q when the true distribution is p.

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8

- Ex: If we knew the true distribution of the *r.v.*, then we could construct a code with average description length $H(p)$. If instead, we used the code for a distribution q , we would need $H(p)+D(p||q)$ bits on the average to describe the *r.v.*.

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9

- Definition:
The relative entropy or **Kullback Liebler distance** between two probability mass functions $p(x)$ and $q(x)$ is defines as

$$\begin{aligned}
 D(p \parallel q) &= \sum_{x \in X} p(x) \log \frac{p(x)}{q(x)} \\
 &= E_p \log \frac{p(x)}{q(x)} = E_p \left[\log \frac{1}{q(x)} - \log \frac{1}{p(x)} \right] \\
 &= E_p \left[\log \frac{1}{q(x)} \right] - E_p \left[\log \frac{1}{p(x)} \right]
 \end{aligned}$$

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10

■ Definition:

Consider two *r.v.*'s X and Y with a joint probability mass function $p(x,y)$ and **marginal probability** mass functions $p(x)$ and $p(y)$. The **mutual information** $I(X;Y)$ is the **relative entropy** between the joint distribution $p(x,y)$ and the product distribution $p(x)p(y)$ i.e.,

$$\begin{aligned} I(X;Y) &= \sum_{x \in X} \sum_{y \in Y} p(x,y) \log \frac{p(x,y)}{p(x)p(y)} \\ &= D(p(x,y) \parallel p(x)p(y)) \\ &= E_{p(x,y)} \left[\log \frac{P(X,Y)}{P(X)P(Y)} \right] \end{aligned}$$

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11

- Ex: Let $X = \{0, 1\}$ and consider two distributions p and q on X . Let $p(0)=1-r$, $p(1)=r$, and let $q(0)=1-s$, $q(1)=s$. Then

$$D(p \parallel q) = p(0) \log \frac{p(0)}{q(0)} + p(1) \log \frac{p(1)}{q(1)}$$

$$= (1-r) \log \frac{1-r}{1-s} + r \log \frac{r}{s}$$

$$\text{and } D(q \parallel p) = q(0) \log \frac{q(0)}{p(0)} + q(1) \log \frac{q(1)}{p(1)}$$

$$= (1-s) \log \frac{1-s}{1-r} + s \log \frac{s}{r}$$

\Rightarrow If $r=s$, then $D(p \parallel q) = D(q \parallel p) = 0$

While, in general,

$$D(p \parallel q) \neq D(q \parallel p)$$

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12

Relationship between Entropy and Mutual Information

Rewrite $I(X;Y)$ as

$$\begin{aligned} I(X;Y) &= \sum_{x,y} p(x,y) \log \frac{p(x,y)}{p(x)p(y)} \\ &= \sum_{x,y} p(x,y) \log \frac{p(x|y)}{p(x)} \\ &= -\sum_{x,y} p(x,y) \log p(x) + \sum_{x,y} p(x,y) \log p(x|y) \\ &= -\sum_x p(x) \log p(x) - \left(-\sum_{x,y} p(x,y) \log p(x|y) \right) \\ &= H(X) - H(X|Y) \end{aligned}$$

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13

Thus the mutual information $I(X;Y)$ is the reduction in the uncertainty of X due to the knowledge of Y .

By symmetry, it follows that

$$I(X;Y) = H(Y) - H(Y|X)$$

→ X says much about Y as Y says about X

Since $H(X;Y) = H(X) + H(Y|X)$

$$\rightarrow I(X;Y) = H(X) + H(Y) - H(X,Y)$$

$$I(X;X) = H(X) + H(X|X) = H(X)$$

The mutual information of a r.v. with itself is the entropy of the r.v. ---> entropy : self-information

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14

■ Theorem: (Mutual information and entropy):

- i. $I(X;Y) = H(X) - H(X|Y)$
 $= H(Y) - H(Y|X)$
 $= H(X) + H(Y) - H(X,Y)$
- ii. $I(X;Y) = I(Y;X)$
- iii. $I(X;X) = H(X)$

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15

Chain Rules for Entropy, Relative Entropy and Mutual Information


■ Theorem: (Chain rule for entropy)

Let X_1, X_2, \dots, X_n , be drawn according to $P(x_1, x_2, \dots, x_n)$.

Then

$$H(X_1, X_2, \dots, X_n) = \sum_{i=1}^n H(X_i | X_{i-1}, \dots, X_1)$$

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16

■ Proof

(1)

$$\begin{aligned}
 H(X_1, X_2) &= H(X_1) + H(X_2 | X_1) \\
 H(X_1, X_2, X_3) &= H(X_1) + H(X_2, X_3 | X_1) \\
 &= H(X_1) + H(X_2 | X_1) + H(X_3 | X_2, X_1) \\
 &\vdots \\
 H(X_1, X_2, \dots, X_n) &= H(X_1) + H(X_2 | X_1) + \dots + H(X_n | X_{n-1}, \dots, X_1) \\
 &= \sum_{i=1}^n H(X_i | X_{i-1}, \dots, X_1)
 \end{aligned}$$

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17

(2) We write

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | x_{i-1}, \dots, x_1)$$

then

$$\begin{aligned}
 H(X_1, X_2, \dots, X_n) &= - \sum_{X_1, X_2, \dots, X_n} P(x_1, x_2, \dots, x_n) \log P(x_1, x_2, \dots, x_n) \\
 &= - \sum_{X_1, X_2, \dots, X_n} P(x_1, x_2, \dots, x_n) \log \prod_{i=1}^n P(x_i | x_{i-1}, \dots, x_1) \\
 &= - \sum_{X_1, X_2, \dots, X_n} \sum_{i=1}^n P(x_1, x_2, \dots, x_n) \log P(x_i | x_{i-1}, \dots, x_1) \\
 &= - \sum_{i=1}^n \sum_{X_1, X_2, \dots, X_n} P(x_1, x_2, \dots, x_n) \log P(x_i | x_{i-1}, \dots, x_1) \\
 &= - \sum_{i=1}^n \sum_{X_1, X_2, \dots, X_i} P(x_1, x_2, \dots, x_i) \log P(x_i | x_{i-1}, \dots, x_1) \\
 &= \sum_{i=1}^n H(X_i | X_{i-1}, \dots, X_1)
 \end{aligned}$$

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18

- **Definition:**
The conditional mutual information of rv's. X and Y given Z is defined by

$$\begin{aligned} I(X; Y | Z) &= H(X | Z) - H(X | Y, Z) \\ &= E_{p(x,y,z)} \log \frac{P(X, Y | Z)}{P(X | Z) \cdot P(Y | Z)} \end{aligned}$$

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19

- **Theorem: (chain rule for mutual-information)**

$$I(X_1, X_2, \dots, X_n; Y) = \sum_{i=1}^n I(X_i; Y | X_{i-1}, \dots, X_1)$$

proof:

$$\begin{aligned} &I(X_1, X_2, \dots, X_n; Y) \\ &= H(X_1, X_2, \dots, X_n) - H(X_1, X_2, \dots, X_n | Y) \\ &= \sum_{i=1}^n H(X_i | X_{i-1}, \dots, X_1) - \sum_{i=1}^n H(X_i | X_{i-1}, \dots, X_1, Y) \\ &= \sum_{i=1}^n I(X_i; Y | X_1, X_2, \dots, X_{i-1}) \end{aligned}$$

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20

- **Definition:**

The conditional relative entropy $D(p(y|x) \parallel q(y|x))$ is the average of the relative entropies between the conditional probability mass functions $p(y|x)$ and $q(y|x)$ averaged over the probability mass function $p(x)$.

$$D(p(y|x) \parallel q(y|x)) = \sum_x p(x) \sum_y p(y|x) \log \frac{p(y|x)}{q(y|x)}$$

$$= E_{p(x,y)} \log \frac{p(Y|X)}{q(Y|X)}$$

- **Theorem: (Chain rule for relative entropy)**

$$D(p(x,y) \parallel q(x,y)) = D(p(x) \parallel q(x)) + D(p(y|x) \parallel q(y|x))$$

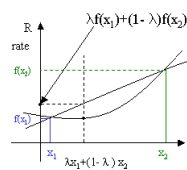
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21

Jensen's Inequality and Its Consequences

- **Definition:** A function is said to be **convex** over an interval (a,b) if for every $x_1, x_2 \in (a,b)$ and $0 \leq \lambda \leq 1$, $f(\lambda x_1 + (1-\lambda)x_2) \leq \lambda f(x_1) + (1-\lambda)f(x_2)$.
A function f is said to be strictly convex if equality holds only if $0 < \lambda < 1$.



- **Definition:** A function is **concave** if $-f$ is convex.

Ex: convex functions: X^2 , $|X|$, e^X , $X \log X$ (for $X \geq 0$)

concave functions: $\log X$, $X^{1/2}$ for $X \geq 0$

both convex and concave: $ax+b$; linear functions

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22

- Theorem:
If the function f has a second derivative which is non-negative (positive) everywhere, then the function is convex (strictly convex).

$$\begin{cases} EX = \sum_{x \in X} p(x)x & : \quad \text{discrete case} \\ EX = \int p(x)x dx & : \quad \text{continuous case} \end{cases}$$

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23

- Theorem : (Jensen's inequality):
If $f(x)$ is **convex** function and X is a random variable, then $Ef(X) \geq f(EX)$.

Proof: For a two mass point distribution, the inequality becomes

$$p_1 f(x_1) + p_2 f(x_2) \geq f(p_1 x_1 + p_2 x_2), \quad p_1 + p_2 = 1$$

which follows directly from the definition of convex functions.

Suppose the theorem is true for distributions with $K-1$ mass points.

Then writing $P'_i = P_i / (1 - P_K)$ for $i = 1, 2, \dots, K-1$, we have

$$\begin{aligned} \sum_{i=1}^k p_i f(x_i) &= p_k f(x_k) + (1 - p_k) \sum_{i=1}^{k-1} p'_i f(x_i) \\ &\geq p_k f(x_k) + (1 - p_k) f\left(\sum_{i=1}^{k-1} p'_i x_i\right) \\ &\geq f\left(p_k x_k + (1 - p_k) \sum_{i=1}^{k-1} p'_i x_i\right) \\ &= f\left((1 - p_k) \sum_{i=1}^{k-1} p'_i x_i + p_k x_k\right) \\ &= f\left((1 - p_k) \sum_{i=1}^k p'_i x_i\right) \\ &= f\left(\sum_{i=1}^k (1 - p_k) p'_i x_i\right) \\ &= f\left(\sum_{i=1}^k p_i x_i\right) \end{aligned}$$

The proof can be extended to continuous distributions by continuity arguments.
(Mathematical Induction)

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24

■ Theorem: (**Information inequality**):

Let $p(x)$, $q(x)$ ($x \in X$), be two probability mass functions. Then

$$D(p||q) \geq 0$$

with equality iff $p(x)=q(x)$ for all x .

Proof: Let $A=\{x:p(x)>0\}$ be the support set of $p(x)$. Then

$$\begin{aligned} -D(p||q) &= -\sum_{x \in A} p(x) \log \frac{p(x)}{q(x)} \\ &= \sum_{x \in A} p(x) \log \frac{q(x)}{p(x)} = E \left\{ \log \frac{q(x)}{p(x)} \right\} \leq \left\{ \log E \left(\frac{q(x)}{p(x)} \right) \right\} \\ &= \log \sum_{x \in A} p(x) \frac{q(x)}{p(x)} \quad (\log t \text{ is concave}) \\ &= \log \sum_{x \in A} q(x) \\ &\leq \log \sum_{x \in X} q(x) \\ &= \log 1 = 0 \end{aligned}$$

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25

■ Corollary: (**Non-negativity of mutual information**):

For any two rv's., X , Y ,

$$I(X;Y) \geq 0$$

with equality iff X and Y are independent.

Proof:

$$I(X;Y) = D(p(x,y)||p(x)p(y)) \geq 0 \text{ with equality iff } p(x,y)=p(x)p(y), \text{ i.e., } X \text{ and } Y \text{ are independent}$$

■ Corollary:

$$D(p(y|x)||q(y|x)) \geq 0$$

with equality iff $p(y|x)=q(y|x)$ for all x and y with $p(x)>0$.

■ Corollary:

$$I(X;Y|Z) \geq 0$$

with equality iff X and Y are conditionally independent given Z .

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26

■ Theorem:

$H(x) \leq \log|\mathbf{X}|$, where $|\mathbf{X}|$ denotes the number of elements in the range of X , with equality iff X has a uniform distribution over \mathbf{X} .

Proof:

Let $u(x) = 1/|\mathbf{X}|$ be the uniform probability mass function over \mathbf{X} , and let $p(x)$ be the probability mass function for X . Then

$$D(p \parallel u) = \sum p(x) \log \frac{p(x)}{u(x)} = \log|\mathbf{X}| - H(x)$$

Hence by the non-negativity of relative entropy

$$0 \leq D(p \parallel u) = \log|\mathbf{X}| - H(x)$$

Information Theory



27

■ Theorem: (conditioning reduces entropy):

$$H(X|Y) \leq H(X)$$

with equality iff X and Y are independent.

Proof: $0 \leq I(X;Y) = H(X) - H(X|Y)$

Note that this is true only on the average; specifically, $H(X|Y=y)$ may be greater than or less than or equal to $H(X)$, but on the average $H(X|Y) = \sum p(y)H(X|Y=y) \leq H(X)$.

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28

- Ex: Let (X,Y) have the following joint distribution

		x	
		1	2
y	1	0	3/4
	2	1/8	1/8

Then, $H(X)=H(1/8, 7/8)=0.544$ bits

$H(X|Y=1)=0$ bits

$H(X|Y=2)=1$ bits $> H(X)$

However, $H(X|Y) = 3/4 H(X|Y=1) + 1/4 H(X|Y=2)$
 $= 0.25$ bits $< H(X)$

Information Theory



29

- Theorem: (Independence bound on entropy):

Let X_1, X_2, \dots, X_n be drawn according to $p(x_1, x_2, \dots, x_n)$.

Then

$$H(X_1, X_2, \dots, X_n) \leq \sum_{i=1}^n H(X_i)$$

with equality iff the X_i are independent.

Proof: By the chain rule for entropies,

$$\begin{aligned} H(X_1, X_2, \dots, X_n) &= \sum_{i=1}^n H(X_i | X_{i-1}, \dots, X_1) \\ &\leq \sum_{i=1}^n H(X_i) \end{aligned}$$

with equality iff the X_i 's are independent.

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30

The LOG SUM INEQUALITY AND ITS APPLICATIONS

■ Theorem: (Log sum inequality)

For non-negative numbers, a_1, a_2, \dots, a_n and b_1, b_2, \dots, b_n

$$\sum_{i=1}^n a_i \log \frac{a_i}{b_i} \geq \left(\sum_{i=1}^n a_i \right) \log \frac{\sum_{i=1}^n a_i}{\sum_{i=1}^n b_i}$$

with equality iff $a_i/b_i = \text{constant}$.

$$\left(\begin{array}{l} \text{some conventions : } 0 \log 0 = 0, a \log \frac{a}{0} = \infty \text{ if } a > 0 \\ 0 \log \frac{0}{0} = 0 \end{array} \right)$$

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31

Proof:

Assume w.l.o.g that $a_i > 0$ and $b_i > 0$. The function $f(t) = t \log t$ is strictly convex, since $f''(t) = \frac{1}{t} \log e > 0$ for all positive t . Hence by Jensen's inequality, we have

$$\sum \alpha_i f(t_i) \geq f\left(\sum \alpha_i t_i\right)$$

for $\alpha_i \geq 0, \sum_i \alpha_i = 1$. Setting $\alpha_i = \frac{b_i}{\sum_{i=1}^n b_i}$ and $t_i = \frac{a_i}{b_i}$,

$$\text{we obtain } \sum \frac{b_i}{\sum b_i} \cdot \frac{a_i}{b_i} \log \frac{a_i}{b_i} \geq \sum \frac{b_i}{\sum b_i} \cdot \frac{a_i}{b_i} \log \left(\sum \frac{b_i}{\sum b_i} \cdot \frac{a_i}{b_i} \right)$$

$$\sum \frac{b_i}{\sum b_i} \cdot \frac{a_i}{b_i} \log \frac{a_i}{b_i} \geq \sum \frac{a_i}{\sum b_i} \log \sum \frac{a_i}{\sum b_i} \quad (\text{note that } \sum_i b_i = 1)$$

$$\Rightarrow \sum a_i \log \frac{a_i}{b_i} \geq \sum a_i \log \frac{\sum a_i}{\sum b_i}$$

which is the log sum inequality. (Sum b_i greater than 0)

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32

- Repeating the theorem that $D(p||q) \geq 0$, with equality iff $p(x)=q(x)$

$$\begin{aligned} D(p || q) &= \sum p(x) \log \frac{p(x)}{q(x)} \\ &\geq \left(\sum p(x) \right) \log \frac{\sum p(x)}{\sum q(x)} \quad (\text{from log - sum inequality}) \\ &= 1 \log \frac{1}{1} = 0 \end{aligned}$$

with equality iff $p(x)/q(x)=c$. Since both p and q are probability mass functions, $c=1 \Rightarrow p(x)=q(x), \forall x$.

Information Theory



33

- Theorem:
 $D(p||q)$ is convex in the pair (p,q) , i.e., if (p_1, q_1) and (p_2, q_2) are two pairs of probability mass functions, then

$$D(\lambda p_1 + (1-\lambda)p_2 || \lambda q_1 + (1-\lambda)q_2) \leq \lambda D(p_1 || q_1) + (1-\lambda)D(p_2 || q_2)$$

for all $0 \leq \lambda \leq 1$

- Proof: $D(\lambda p_1 + (1-\lambda)p_2 || \lambda q_1 + (1-\lambda)q_2)$
 $= \sum (\lambda p_1 + (1-\lambda)p_2) \log \frac{\lambda p_1 + (1-\lambda)p_2}{\lambda q_1 + (1-\lambda)q_2} \dots (1)$

$$\text{Let } a_i = \lambda p_i, \quad a_2 = (1-\lambda)p_2 \\ b_i = \lambda q_i, \quad b_2 = (1-\lambda)q_2$$

$$\text{then (1)} \Rightarrow \sum \left(\sum_{i=1}^2 a_i \right) \log \frac{\left(\sum_{i=1}^2 a_i \right)}{\left(\sum_{i=1}^2 b_i \right)}$$

$$\stackrel{\text{log-sum}}{\leq} \sum \left[\sum_{i=1}^2 a_i \log \frac{a_i}{b_i} \right] = \sum \left(\lambda p_1 \log \frac{\lambda p_1}{\lambda q_1} + (1-\lambda)p_2 \log \frac{(1-\lambda)p_2}{(1-\lambda)q_2} \right)$$

$$= \lambda \sum p_1 \log \frac{p_1}{q_1} + (1-\lambda) \sum p_2 \log \frac{p_2}{q_2}$$

$$= \lambda D(p_1 || q_1) + (1-\lambda)D(p_2 || q_2)$$



34

- Theorem: (**concavity of entropy**):
 $H(p)$ is a concave function of P .
 That is: $H(\lambda p_1 + (1-\lambda)p_2) \geq \lambda H(p_1) + (1-\lambda)H(p_2)$

Proof:

$$H(p) = \log |\mathbf{X}| - D(p||u)$$

where u is the uniform distribution on $|\mathbf{X}|$ outcomes. The concavity of H then follows directly from the convexity of D .

Information Theory



35

- Theorem: Let $(X,Y) \sim p(x,y) = p(x)p(y|x)$.
 The mutual information $I(X;Y)$ is
 (i) a concave function of $p(x)$ for fixed $p(y|x)$
 (ii) a convex function of $p(y|x)$ for fixed $p(x)$.

Proof:

- (1) $I(X;Y) = H(Y) - H(Y|X) = H(Y) - \sum_x p(x)H(Y|X=x) \dots (\Delta)$
 if $p(y|x)$ is fixed, then $p(y)$ is a linear function of $p(x)$.
 ($p(y) = \sum_x p(x,y) = \sum_x p(x)p(y|x)$)
 Hence $H(Y)$, which is a concave function of $p(y)$, is a concave function of $p(x)$. The second term of (Δ) is a linear function of $p(x)$. Hence the difference is a concave function of $p(x)$.

Information Theory



36

(2) We fix $p(x)$ and consider two different conditional distributions $p_1(y|x)$ and $p_2(y|x)$. The corresponding joint distributions are $p_1(x,y)=p(x)p_1(y|x)$ and $p_2(x,y)=p(x)p_2(y|x)$, and their respective marginals are $p(x)$, $p_1(y)$ and $p(x)$, $p_2(y)$.

Consider a conditional distribution

$$p_\lambda(y|x) = \lambda p_1(y|x) + (1-\lambda)p_2(y|x)$$

that is a mixture of $p_1(y|x)$ and $p_2(y|x)$. The corresponding joint distribution is also a mixture of the corresponding joint distributions,

$$p_\lambda(x,y) = \lambda p_1(x,y) + (1-\lambda)p_2(x,y)$$

and the distribution of Y is also a mixture $p_\lambda(y) = \lambda p_1(y) + (1-\lambda)p_2(y)$. Hence if we let $q_\lambda(x,y) = p(x)p_\lambda(y) \Rightarrow q_\lambda(x,y) = \lambda q_1(x,y) + (1-\lambda)q_2(x,y)$.

The product of the marginal distributions

$q_\lambda(x,y)$ is also linear with $p_i(y|x)$ when $p(x)$ is fixed.

$I(X;Y) = D(p_\lambda||q_\lambda) \rightarrow$ convex of (p,q)

\Rightarrow the mutual information is a convex function of the conditional distribution. Therefore, the convexity of $I(X;Y)$ is the same as that of the $D(p_\lambda||q_\lambda)$ w.r.t. $p_i(y|x)$ when $p(x)$ is fixed.

Information Theory



37

Data processing inequality:

No clever manipulation of the data can improve the inferences that can be made from the data

■ Definition:

Rv's X, Y, Z are said to form a Markov chain in that order (denoted by $X \rightarrow Y \rightarrow Z$) if the conditional distribution of Z depends only on Y and is conditionally independent of X . That is $X \rightarrow Y \rightarrow Z$ form a **Markov chain**, then

(i) $p(x,y,z) = p(x)p(y|x)p(z|y)$

(ii) $p(x,z|y) = p(x|y)p(z|y)$: X and Z are conditionally independent given Y

■ $X \rightarrow Y \rightarrow Z$ implies that $Z \rightarrow Y \rightarrow X$

If $Z = f(Y)$, then $X \rightarrow Y \rightarrow Z$

Information Theory



38

■ **Theorem: (Data processing inequality)**

if $X \rightarrow Y \rightarrow Z$, then $I(X;Y) \geq I(X;Z)$

No processing of Y , deterministic or random, can increase the information that Y contains about X .

Proof:

$$I(X;Y,Z) = I(X;Z) + I(X;Y|Z) \quad \text{: chain rule}$$

$$= I(X;Y) + I(X;Z|Y) \quad \text{: chain rule}$$

Since X and Z are independent given Y , we have $I(X;Z|Y)=0$. Since $I(X;Y|Z) \geq 0$, we have $I(X;Y) \geq I(X;Z)$ with equality iff $I(X;Y|Z)=0$, i.e., $X \rightarrow Z \rightarrow Y$ forms a Markov chain. Similarly, one can prove $I(Y;Z) \geq I(X;Z)$

Information Theory



39

■ **Corollary:**

If $X \rightarrow Y \rightarrow Z$ forms a Markov chain and if $Z=g(Y)$, we have $I(X;Y) \geq I(X;g(Y))$

: functions of the data Y cannot increase the information about X .

■ **Corollary:** If $X \rightarrow Y \rightarrow Z$, then $I(X;Y|Z) \leq I(X;Y)$

Proof: $I(X;Y,Z) = I(X;Z) + I(X;Y|Z)$

$$= I(X;Y) + I(X;Z|Y)$$

By Markovity, $I(X;Z|Y)=0$

and $I(X;Z) \geq 0 \Rightarrow I(X;Y|Z) \leq I(X;Y)$

\Rightarrow The dependence of X and Y is decreased (or remains unchanged) by the observation of a “downstream” r.v. Z .

Information Theory



40

- Note that it is possible that $I(X;Y|Z) > I(X;Y)$ when X, Y and Z do not form a Markov chain.

Ex: Let X and Y be independent fair binary rv's, and let $Z = X + Y$. Then $I(X;Y) = 0$, but

$$\begin{aligned} I(X;Y|Z) &= H(X|Z) - H(X|Y,Z) \\ &= H(X|Z) \\ &= P(Z=1)H(X|Z=1) = 1/2 \text{ bit.} \end{aligned}$$

Information Theory



41

Fano's inequality:

- Fano's inequality relates the probability of error in guessing the r.v. X to its conditional entropy $H(X|Y)$.

Note that:

The conditional entropy of a r.v. X given another random variable Y is zero iff X is a function of Y .

proof: HW $H(X|Y)=0$ implies there is no uncertainty about X if we know Y
 \Rightarrow for all x with $p(x)>0$, there is only one possible value of y with $p(x,y)>0$

\Rightarrow we can estimate X from Y with zero probability of error iff $H(X|Y)=0$.

\Rightarrow we expect to be able to estimate X with a low probability of error only if the conditional entropy $H(X|Y)$ is small.

Fano's inequality quantifies this idea.

Information Theory



42

- Suppose we wish to estimate a r.v. X with a distribution $p(x)$. We observe a r.v. Y which is related to X by the conditional distribution $p(y|x)$. From Y , we calculate a function $g(Y) = \hat{X}$ which is an estimate of X . We wish to bound the probability that $\hat{X} \neq X$. We observe that $X \rightarrow Y \rightarrow \hat{X}$ forms a Markov chain. Define the probability of error

$$P_e = P_r \left\{ \hat{X} \neq X \right\} = P_r \{ g(Y) \neq X \}$$

Information Theory



43

- Theorem: (**Fano's inequality**)

For any estimator \hat{X} such that $X \rightarrow Y \rightarrow \hat{X}$ with $P_e = P_r(X \neq \hat{X})$, we have

$$H(P_e) + P_e \log(|\mathbf{X}| - 1) \geq H(X|Y)$$

$H(P_e) \leq 1$, E : binary r.v.
 $\log(|\mathbf{X}| - 1) \leq \log|\mathbf{X}|$

This inequality can be weakened to

$$1 + P_e \log(|\mathbf{X}|) \geq H(X|Y)$$

or

$$P_e \geq \frac{H(X|Y) - 1}{\log|\mathbf{X}|}$$

Remark: $P_e = 0 \Rightarrow H(X|Y) = 0$

Information Theory



44

Proof: Define an error rv.

$$E = \begin{cases} 1 & , \text{if } \hat{X} \neq X \\ 0 & , \text{if } \hat{X} = X \end{cases}$$

By the chain rule for entropies, we have

$$\begin{aligned} H(E, X | \hat{X}) &= H(X | \hat{X}) + H(E | X, \hat{X}) \\ &= H(E | \hat{X}) + H(X | E, \hat{X}) \\ &\leq H(P_e) \leq P_e \log(|\mathcal{X}| - 1) \end{aligned}$$

Since conditioning reduces entropy, $H(E | \hat{X}) \leq H(E) = H(P_e)$. Now since E is a function of X and $\hat{X} \Rightarrow H(E | X, \hat{X}) = 0$. Since E is a binary-valued r.v., $H(E) = H(P_e)$.

The remaining term, $H(X | E, \hat{X})$, can be bounded as follows:

$$\begin{aligned} H(X | E, \hat{X}) &= P_r(E=0)H(X | \hat{X}, E=0) + P_r(E=1)H(X | \hat{X}, E=1) \\ &\leq (1 - P_e)0 + P_e \log(|\mathcal{X}| - 1), \end{aligned}$$

Information Theory



45

Since given $E=0$, $X=\hat{X}$, and given $E=1$, we can upper bound the conditional entropy by the log of the number of remaining outcomes $(|\mathcal{X}|-1)$.

$H(P_e) + P_e \log|\mathcal{X}| \geq H(X | \hat{X})$. By the data processing inequality, we have $I(X; \hat{X}) \leq I(X; Y)$ since $X \rightarrow Y \rightarrow \hat{X}$, and therefore $H(X | \hat{X}) \geq H(X | Y)$. Thus we have $H(P_e) + P_e \log|\mathcal{X}| \geq H(X | \hat{X}) \geq H(X | Y)$.

Remark:

Suppose there is no knowledge of Y . Thus X must be guessed without any information. Let $\hat{X} \in \{1, 2, \dots, m\}$ and $P_1 \geq P_2 \geq \dots \geq P_m$. Then the best guess of X is $X=1$ and the resulting probability of error is $P_e = 1 - P_1$.

Fano's inequality becomes

$$H(P_e) + P_e \log(m-1) \geq H(X)$$

The probability mass function

$$(P_1, P_2, \dots, P_m) = (1 - P_e, P_e/(m-1), \dots, P_e/(m-1))$$

achieves this bound with equality.

Information Theory



46

Some Properties of the Relative Entropy

1. Let μ_n and μ'_n be two probability distributions on the state space of a Markov chain at time n , and let μ_{n+1} and μ'_{n+1} be the corresponding distributions at time $n+1$. Let the corresponding joint mass function be denoted by p and q .

That is,

$$p(x_n, x_{n+1}) = p(x_n) r(x_{n+1} | x_n)$$

$$q(x_n, x_{n+1}) = q(x_n) r(x_{n+1} | x_n)$$

where

$r(\cdot | \cdot)$ is the probability transition function for the Markov chain.

Information Theory



47

Then by the chain rule for relative entropy, we have the following two expansions:

$$\begin{aligned} D(p(x_n, x_{n+1}) || q(x_n, x_{n+1})) \\ &= D(p(x_n) || q(x_n)) + D(p(x_{n+1} | x_n) || q(x_{n+1} | x_n)) \\ &= D(p(x_{n+1}) || q(x_{n+1})) + D(p(x_n | x_{n+1}) || q(x_n | x_{n+1})) \end{aligned}$$

Since both p and q are derived from the same Markov chain, so

$$p(x_{n+1} | x_n) = q(x_{n+1} | x_n) = r(x_{n+1} | x_n),$$

and hence

$$D(p(x_{n+1} | x_n) || q(x_{n+1} | x_n)) = 0$$

Information Theory



48

That is,

$$D(p(x_n) \parallel q(x_n)) \\ = D(p(x_{n+1}) \parallel q(x_{n+1})) + D(p(x_n|x_{n+1}) \parallel q(x_n|x_{n+1}))$$

Since $D(p(x_n|x_{n+1}) \parallel q(x_n|x_{n+1})) \geq 0$

$$\Rightarrow D(p(x_n) \parallel q(x_n)) \geq D(p(x_{n+1}) \parallel q(x_{n+1}))$$

or $D(\mu_n \parallel \mu'_n) \geq D(\mu_{n+1} \parallel \mu'_{n+1})$

Conclusion:

The distance between the probability mass functions is decreasing with time n for any Markov chain.

Information Theory



49

2. Relative entropy $D(\mu_n \parallel \mu)$ between a distribution μ_n on the states at time n and a stationary distribution μ decreases with n .

In the last equation, if we let μ'_n be any stationary distribution μ , then μ'_{n+1} is the same stationary distribution. Hence

$$D(\mu_n \parallel \mu) \geq D(\mu_{n+1} \parallel \mu)$$

\Rightarrow Any state distribution gets closer and closer to each stationary distribution as time passes. $\lim_{n \rightarrow \infty} D(\mu_n \parallel \mu) = 0$

Information Theory



50

3. Def: A probability transition matrix $[P_{ij}]$,
 $P_{ij} = P\{x_{n+1}=j|x_n=i\}$ is called **doubly stochastic** if
 $\sum_i P_{ij}=1, i=1,2,\dots, j=1,2,\dots$
 and
 $\sum_j P_{ij}=1, i=1,2,\dots, j=1,2,\dots$

The uniform distribution is a stationary distribution of P iff the probability transition matrix is doubly stochastic.

Information Theory



51

4. The conditional entropy $H(X_n|X_1)$ increase with n for a stationary Markov process.

If the Markov process is stationary, then $H(X_n)$ is constant. So the entropy is non-increasing. However, it can be proved that $H(X_n|X_1)$ increases with n . This implies that:

the conditional uncertainty of the future increases.

Proof:

$$\begin{aligned} H(X_n|X_1) &\geq H(X_n|X_1, X_2) && \text{(conditioning reduces entropy)} \\ &= H(X_n|X_2) && \text{(by Markovity)} \\ &= H(X_{n-1}|X_1) && \text{(by stationarity)} \end{aligned}$$

Similarly: $H(X_0|X_n)$ is increasing in n for any Markov chain.

Information Theory



52

Sufficient Statistics

Suppose we have a family of probability mass function $\{f_\theta(x)\}$ indexed by θ , and let X be a sample from a distribution in this family. Let $T(X)$ be any statistic (function of the sample) like the sample mean or sample variance. Then

$$\theta \rightarrow X \rightarrow T(X),$$

And by the data processing inequality, we have

$$I(\theta; T(X)) \leq I(\theta; X)$$

for any distribution on θ . However, if equality holds, no information is lost.

A statistic $T(X)$ is called sufficient for θ if it contains all the information in X about θ .

Information Theory



53

■ Def:

A function $T(X)$ is said to be a sufficient statistic relative to the family $\{f_\theta(x)\}$ if X is independent of θ given $T(X)$, i.e., $\theta \rightarrow T(X) \rightarrow X$ forms a Markov chain.

or:

$$I(\theta; X) = I(\theta; T(X))$$

for all distributions on θ

Sufficient statistics preserve mutual information.

Information Theory



54

Some examples of Sufficient Statistics

1. Let $X_1, X_2, \dots, X_n, X_i \in \{0, 1\}$ be an i.i.d. sequence of coin tosses of a coin with unknown parameter $\theta = \Pr(X_i = 1)$.

Given n , the number of 1's is a sufficient statistics for θ .

$$\text{Here } T(X_1, X_2, \dots, X_n) = \sum_{i=1}^n X_i. \Rightarrow$$

Given T , all sequences having that many 1's are equally likely and independent of the parameter θ .

Information Theory



55

$$\Pr \left\{ (X_1, X_2, \dots, X_n) = (x_1, x_2, \dots, x_n) \middle| \sum_{i=1}^n x_i = k \right\} \\ = \begin{cases} \frac{1}{\binom{n}{k}}, & \text{if } \sum x_i = k \\ 0 & , \text{otherwise} \end{cases}$$

Thus, $\theta \rightarrow \sum X_i \rightarrow (X_1, X_2, \dots, X_n)$
and T is a sufficient statistics for θ .

Information Theory



56

2. If X is normally distributed with mean θ and variance 1; that is,

$$\text{if } f_{\theta} = \frac{1}{\sqrt{2\pi}} e^{-\frac{(x-\theta)^2}{2}} = N(\theta, 1)$$

and X_1, X_2, \dots, X_n are drawn independently according to f_{θ} ,

a sufficient statistic for θ is the sample mean

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i.$$

This can be verified that

$P(X_1, X_2, \dots, X_n | \bar{X}_n, n)$ is independent of θ .

Information Theory



57

The minimal sufficient statistics is a sufficient statistics that is a function of all other sufficient statistics.

Def:

A static $T(X)$ is a minimal sufficient statistic related to $\{f_{\theta}(X)\}$ if it is a function of every other sufficient statistic $U : \theta \rightarrow T(X) \rightarrow U(X) \rightarrow X$

Hence, a minimal sufficient statistic maximally compresses the information about θ in the sample. Other sufficient statistics may contain additional irrelevant information.

The sufficient statistics of the above examples are minimal.

Information Theory



58

Shuffles increase Entropy:

If T is a shuffle (permutation) of a deck of cards and X is the initial (random) position of the cards in the deck and if the choice of the shuffle T is independent of X , then

$$H(TX) \geq H(X)$$

where TX is the permutation of the deck induced by the shuffle T on the initial permutation X .

$$\begin{aligned} \text{Proof: } H(TX) &\geq H(TX|T) \\ &= H(T^{-1}TX|T) \quad (\text{why?}) \\ &= H(X|T) \\ &= H(X) \end{aligned}$$

if X and T are independent!

Information Theory



59

If X and X' are i.i.d. with entropy $H(X)$, then $P_r(X=X') \geq 2^{-H(X)}$ with equality iff X has a uniform distribution.

pf: suppose $X \sim p(x)$. By Jensen's inequality, we have $2^{E \log p(x)} \leq E 2^{\log p(x)}$

which implies that $2^{-H(X)} = 2^{\sum p(x) \log p(x)} \leq \sum p(x) 2^{\log p(x)} = \sum p^2(x) = P_r(X=X')$

(Let X and X' be two i.i.d. rv's with entropy $H(X)$. The prob. at $X=X'$ is given by $P_r(X=X') = \sum_x p^2(x)$)

Let X, X' be independent with $X \sim p(x), X' \sim r(x), x, x' \in \mathcal{X}$

Then $P_r(X=X') \geq 2^{-H(p)-D(p||r)}$

$$P_r(X=X') \geq 2^{-H(r)-D(r||p)}$$

pf: $2^{-H(p)-D(p||r)} = 2^{\sum p(x) \log p(x) + \sum p(x) \log r(x)/p(x)} = 2^{\sum p(x) \log r(x)} \leq \sum p(x) 2^{\log r(x)} = \sum p(x) r(x) = P_r(X=X')$

Information Theory



60