Meanshift

1.0

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# **Contents**

# Mean shift implementation

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Mean shift algorithm represent a general non-parametric mode finding procedure. It's a hill-climbing algorithm on the density defined by a finite mixture or a kernel density estimate. Mean shift can be used as a non-parametric clustering method, for object tracking, image segmentation.

## **Todo List**

```
File io_png.c
handle lossless 16bit data
add a test suite
internally handle RGB/gray conversion in io_png_read_raw()
handle deinterlacing as a libpng transform function

Member io_png_read_u8 (const char *fname, size_t *nxp, size_t *nyp, size_t *ncp)
don't downscale 16bit images.

Member io_png_write_f32 (const char *fname, const float *data, size_t nx, size_t ny, size_t nc)
handle 16bit images and flexible min/max
```

4 Todo List

# **Class Index**

3 1	Class	1 : - +
-5	22RL1	LPI

Here are the classes, structs, unions and interfaces with brief descriptions:		
MSPoint	??	

6 Class Index

# File Index

## 4.1 File List

Here is a list of all documented files with brief descriptions:

src/meanshift.cpp
Main program for Meanshift segmentation
src/msfilter.cpp
Main program for Meanshift filtering
src/image/image.cpp
Image helper functions
src/image/image.h
src/io_png/io_png.c
PNG read/write simplified interface
src/io_png/ <b>io_png.h</b>
src/ms/ <b>ms.h</b>
src/ra/RAList.h
src/ra/TransitiveClosure.h

8 File Index

# **Class Documentation**

## 5.1 MSPoint Struct Reference

## **Public Attributes**

- int x
- int y

The documentation for this struct was generated from the following file:

• src/ms/ms.h

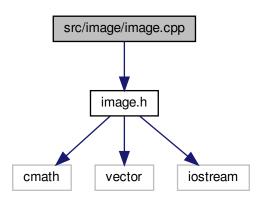
10 Class Documentation

## **File Documentation**

## 6.1 src/image/image.cpp File Reference

Image helper functions.

#include "image.h"
Include dependency graph for image.cpp:



### **Functions**

- uchar \* AllocateUcharImage (int width, int height, int nchannel)
  - Allocate space for the uchar image,.
- int \*\* GenerateLabels (int width, int height)

Generate labels for clustering.

- vector< int > GenerateRandomNumbers (int count)
  - Function generate random numbers.
- void Labellmage (uchar \*image, int width, int height, int \*\*labels, int regCount)

Function Labellmage in RGB colors.

void RGB2LUV (float r, float g, float b, uchar \*I, uchar \*u, uchar \*v)

Function RGB2LUV converts RGB pixel value to LUV pixel value.

void LUV2RGB (float L, float u, float v, uchar \*R, uchar \*G, uchar \*B)

Function LUV2RGB converts LUV pixel value to RGB pixel value.

uchar \* ConvertRGB2LUV (uchar \*rgb, int width, int height, int nchannel)

Function ConvertRGB2LUV convert RGB image to LUV.

uchar \* ConvertLUV2RGB (uchar \*luv, int width, int height, int nchannel)

Function ConvertLUV2RGB converts input image image from LUV to RGB color space.

void SetPixel (uchar \*im, int width, int height, int x, int y, const uchar val, int nchannel)

Set Pixel at channel component of image at postition given with x and y.

• uchar GetPixel (uchar \*im, int width, int height, int x, int y, int nchannel)

Get Pixel at channel component of image at postition given with x and y.

• int range\_distance (uchar \*image, int width, int height, int x1, int y1, int x2, int y2)

Function range\_distance calculate range distance between two pixels.

float color\_distance (const float \*a, const float \*b)

Function color\_distance calculate color distance between the two pixels.

#### 6.1.1 Detailed Description

Image helper functions.

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## 6.1.2 Function Documentation

#### 6.1.2.1 AllocateUcharlmage()

```
uchar* AllocateUcharImage (
    int width,
    int height,
    int nchannel)
```

Allocate space for the uchar image,.

**Parameters** 

```
width, height | and nchannel
```

Returns

img - allocated image

### 6.1.2.2 color\_distance()

```
float color_distance (  {\rm const\ float\ *\ a,}   {\rm const\ float\ *\ b\ )}
```

Function color\_distance calculate color distance between the two pixels.

#### **Parameters**

```
a,b input images
```

#### Returns

the color distance

#### 6.1.2.3 ConvertLUV2RGB()

Function ConvertLUV2RGB converts input image image from LUV to RGB color space.

### **Parameters**

luv	LUV image to convert
width	width of the image
height	gheight of the image
nchannel	number of image channels

#### Returns

The input character

## 6.1.2.4 ConvertRGB2LUV()

Function ConvertRGB2LUV convert RGB image to LUV.

#### **Parameters**

rgb	RGB image to convert
width	width of the image
height	gheight of the image
nchannel	number of image channels

## Returns

luv the converted image

## 6.1.2.5 GenerateLabels()

Generate labels for clustering.

Function generate labels.

## **Parameters**

width,height

#### Returns

labels

## 6.1.2.6 GenerateRandomNumbers()

```
\label{eq:cont_decomposition} \mbox{vector} < \mbox{int} > \mbox{GenerateRandomNumbers (} \\ \mbox{int } \mbox{\it count )}
```

Function generate random numbers.

### **Parameters**

count - Count of numbers to be generated

### Returns

number as vector<int>

## 6.1.2.7 GetPixel()

Get Pixel at channel component of image at postition given with x and y.

#### **Parameters**

im	image to convert
width	width of the image
height	gheight of the image
Х	x position in the image $0 < x < width$
У	y position in the image $0 < y < \text{height}$
nchannel	number of image channels

#### Returns

pixel value

### 6.1.2.8 LabelImage()

Function LabelImage in RGB colors.

#### **Parameters**

image	image to be labeled
width	width of the image
height	heighto of the image
labels	color labels
regCount	regions to be labeled

## 6.1.2.9 LUV2RGB()

```
void LUV2RGB (
    float L,
    float u,
    float v,
    uchar * R,
    uchar * G,
    uchar * B ) [inline]
```

Function LUV2RGB converts LUV pixel value to RGB pixel value.

## **Parameters**

L	component of input image
и	component of input image
V	component of input image
r	component of output image
g	component of output image
b	component of output image

## 6.1.2.10 range\_distance()

Function range\_distance calculate range distance between two pixels.

## Parameters

image	image to calculate
width	width of the image
height	height of the image
x1	first x position in the image
y1	first y position in the image
x2	second x position in the image
y2	second y position in the image

#### Returns

squared sum of distances

#### 6.1.2.11 RGB2LUV()

```
void RGB2LUV (
    float r,
    float g,
    float b,
    uchar * l,
    uchar * u,
    uchar * v ) [inline]
```

Function RGB2LUV converts RGB pixel value to LUV pixel value.

#### **Parameters**

r	component of input image
g	component of input image
b	component of input image
1	component of output image
и	component of output image
V	component of output image 0<=l<=100, 134<=u<=220, 140<=v<=122

## 6.1.2.12 SetPixel()

Set Pixel at channel component of image at postition given with x and y.

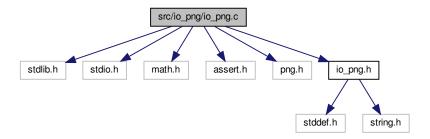
## Parameters

im	image to convert
width	width of the image
height	gheight of the image
X	x position in the image
У	y position in the image
val	value to set at pixel location
nchannel	number of image channels

## 6.2 src/io\_png/io\_png.c File Reference

PNG read/write simplified interface.

```
#include <stdlib.h>
#include <stdio.h>
#include <math.h>
#include <assert.h>
#include <png.h>
#include "io_png.h"
Include dependency graph for io_png.c:
```



#### **Macros**

- #define PNG SIG LEN 4
- #define IO\_PNG\_U8 0x0001 /\* 8bit unsigned integer \*/
- #define IO\_PNG\_F32 0x0002 /\* 32bit float \*/

#### **Functions**

- char \* io\_png\_info (void)
  - helps tracking versions, via the string tag inserted into the library
- unsigned char \* io\_png\_read\_u8 (const char \*fname, size\_t \*nxp, size\_t \*nyp, size\_t \*ncp)
   read a PNG file into a 8bit integer array
- unsigned char \* io\_png\_read\_u8\_rgb (const char \*fname, size\_t \*nxp, size\_t \*nyp)
   read a PNG file into a 8bit integer array, converted to RGB
- unsigned char \* io\_png\_read\_u8\_gray (const char \*fname, size\_t \*nxp, size\_t \*nyp)
- read a PNG file into a 8bit integer array, converted to gray
- float \* io\_png\_read\_f32 (const char \*fname, size\_t \*nxp, size\_t \*nxp,
- float \* io\_png\_read\_f32\_rgb (const char \*fname, size\_t \*nxp, size\_t \*nyp)
  - read a PNG file into a 32bit float array, converted to RGB
- float \* io\_png\_read\_f32\_gray (const char \*fname, size\_t \*nxp, size\_t \*nyp)
  - read a PNG file into a 32bit float array, converted to gray
- int io\_png\_write\_u8 (const char \*fname, const unsigned char \*data, size\_t nx, size\_t ny, size\_t nc) write a 8bit unsigned integer array into a PNG file
- int io\_png\_write\_f32 (const char \*fname, const float \*data, size\_t nx, size\_t ny, size\_t nc) write a float array into a PNG file

## 6.2.1 Detailed Description

PNG read/write simplified interface.

This is a front-end to libpng, with routines to:

- · read a PNG file as a deinterlaced 8bit integer or float array
- · write a 8bit integer or float array to a PNG file

Multi-channel images are handled: grey, grey+alpha, rgb and rgb+alpha, as well as on-the-fly color model conversion

Todo handle lossless 16bit data

```
add a test suite
```

internally handle RGB/gray conversion in io\_png\_read\_raw()

handle deinterlacing as a libpng transform function

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#### 6.2.2 Function Documentation

#### 6.2.2.1 io\_png\_info()

helps tracking versions, via the string tag inserted into the library

This function is not expected to be used in real-world programs.

Returns

a pointer to a version info string

## 6.2.2.2 io\_png\_read\_f32()

read a PNG file into a 32bit float array

The array contains the deinterlaced channels. 1, 2, 4 and 8bit images are converted to float values between 0. and 1., 3., 15. or 255. 16bit images are also downscaled to 8bit before conversion.

#### **Parameters**

fname	PNG file name
nxp,nyp,ncp	pointers to variables to be filled with the number of columns, lines and channels of the image

#### Returns

pointer to an allocated unsigned char array of pixels, or NULL if an error happens

#### 6.2.2.3 io\_png\_read\_f32\_gray()

read a PNG file into a 32bit float array, converted to gray

See io\_png\_read\_f32() for details.

#### 6.2.2.4 io\_png\_read\_f32\_rgb()

read a PNG file into a 32bit float array, converted to RGB

See io\_png\_read\_f32() for details.

#### 6.2.2.5 io\_png\_read\_u8()

read a PNG file into a 8bit integer array

The array contains the deinterlaced channels. 1, 2 and 4bit images are converted to 8bit. 16bit images are previously downscaled to 8bit.

Todo don't downscale 16bit images.

#### **Parameters**

fname	PNG file name
nxp,nyp,ncp	pointers to variables to be filled with the number of columns, lines and channels of the image

#### Returns

pointer to an allocated unsigned char array of pixels, or NULL if an error happens

#### 6.2.2.6 io\_png\_read\_u8\_gray()

read a PNG file into a 8bit integer array, converted to gray

See io\_png\_read\_u8() for details.

#### 6.2.2.7 io\_png\_read\_u8\_rgb()

read a PNG file into a 8bit integer array, converted to RGB

See io\_png\_read\_u8() for details.

#### 6.2.2.8 io\_png\_write\_f32()

write a float array into a PNG file

The float values are rounded to 8bit integers, and bounded to [0, 255].

Todo handle 16bit images and flexible min/max

#### **Parameters**

fname	PNG file name
data	array to write
nx,ny,nc	number of columns, lines and channels of the image

#### Returns

0 if everything OK, -1 if an error occured

#### 6.2.2.9 io\_png\_write\_u8()

write a 8bit unsigned integer array into a PNG file

#### **Parameters**

fname	PNG file name
data	array to write
nx,ny,nc	number of columns, lines and channels of the image

#### Returns

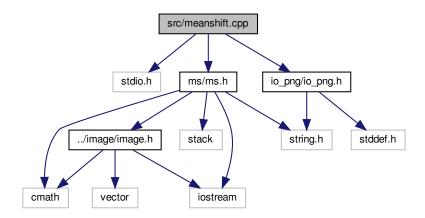
0 if everything OK, -1 if an error occured

## 6.3 src/meanshift.cpp File Reference

Main program for Meanshift segmentation.

```
#include <stdio.h>
#include "ms/ms.h"
#include "io_png/io_png.h"
```

Include dependency graph for meanshift.cpp:



## **Functions**

• int main (int argc, char \*argv[])

## 6.3.1 Detailed Description

Main program for Meanshift segmentation.

**Author** 

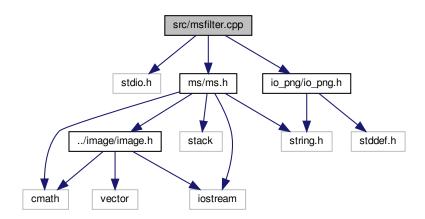
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## 6.4 src/msfilter.cpp File Reference

Main program for Meanshift filtering.

```
#include <stdio.h>
#include "ms/ms.h"
```

#include "io\_png/io\_png.h"
Include dependency graph for msfilter.cpp:



## **Functions**

• int main (int argc, char \*argv[])

## 6.4.1 Detailed Description

Main program for Meanshift filtering.

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