

2.1

2.1.1

To solve this problem, we need to find the closest shopping center with the best revenue, which placed before X_i . For each place we try to find the best revenue.

Pseudocode:

```
int FindBest(i)
    if i == -1
        return 0
    j = 0
    while (j < i)
        if  $x[i] - x[j] \geq d$ 
            break
        j++
    return  $\max(\text{FindBest}(i-1), r[i] + \text{FindBest}(j))$ 
```

2.1.2

Recurrence formula for FindBest(N):

$$T(n) = 2T(n-1) + n, \quad n > 0$$

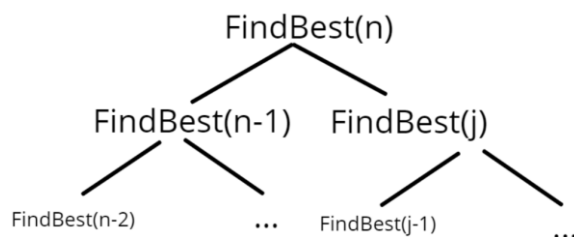
$$T(1) = 1, \quad n = 0$$

$$T(n) = 2T(n-1) + n = \sum_{i=0}^{n-1} 2^i * (n-i) = n(2^0 + 2^1 + \dots + 2^{n-1})$$

$$n(2^0 + 2^1 + \dots + 2^{n-1}) < 2^n n$$

$$T(n) = \theta(2^n n)$$

2.1.3



$(n-k)$ and $(i-p)$ can be equal (k and p some constants). Therefore FindBest($n-k$) and FindBest($i-p$) can be overlap.

2.1.4

We can use top-down approach. Pseudocode:

max_rev[N+1] last [N+1] max_rev[1] = r[1] last[1] = -1	C
for i = 1 to N+1	$N + 2$
best = 0 best_l = -1	$N + 1$
for j = 1 to i -1	$\sum_{i=1}^{N+1} i$
if x[i] - x[j] >= d if best < max_rev[j] best = max_rev[j] best_l = j	$\sum_{i=0}^N i$
if i <= N max_rev[i] = best + r[i] else max_rev[i] = best last[i] = best_l	$N + 1$
ans = max_rev[N] //maximum revenue locations = [] cur = N + 1	C
while last[cur] != -1	$N + 1$
cur = last[cur] locations.push_back(x[cur])	N

2.1.5

We can see amount of operations in the table. Therefore:

$$T(n) = c + bN + \frac{(N + 1)(N + 2)}{2} + \frac{N(N + 1)}{2} = c + bN + aN^2 = O(N^2)$$

2.2

2.2.1

In insertion sort we start from the second element and go through all elements(j – index of element). We get previous element and this index(l = index) (*all elements before j are sorted). While this element lower than previous one, we make index l lower (l = l -1) and next element for l replace by this element (We insert our j-th element on correct position in j-1 sorted elements). When our cycle stop – we replace element with index l+1 by taken element (that was with index j at the beginning) – **You can see pseudocode in 2.2.2**

2.2.2

Insertion Sort (Pseudocode)	Cost	Times (Worst Case)	Times (Best Case)
for j = 2 to A.length	C1	n	n
key = A[j]	C2	$n - 1$	$n - 1$
i = j - 1	C3	$n - 1$	$n - 1$
while i > 0 and A[i] > key	C4	$\sum_{j=2}^n t_j$	$n - 2$
A[i + 1] = A[i]	C5	$\sum_{j=2}^n (t_j - 1)$	0
i = i - 1	C6	$\sum_{j=2}^n (t_j - 1)$	0
A[i + 1] = key	C7	$n - 1$	$n - 1$

Worst-case time complexity:

$$\begin{aligned}
 T(n) &= c_1 n + c_2(n - 1) + c_3(n - 1) + c_4 \left(\frac{n(n+1)}{2} - 1 \right) + c_5 \left(\frac{n(n-1)}{2} \right) + c_6 \left(\frac{n(n-1)}{2} \right) + \\
 &+ c_7(n - 1) = \left(\frac{c_4 + c_5 + c_6}{2} \right) n^2 + \left(c_1 + c_2 + c_3 + c_7 + \frac{c_4 - c_5 - c_6}{2} \right) n - (c_2 + c_3 + c_4 + c_7) \\
 &= \theta(n^2)
 \end{aligned}$$

Best-case time complexity:

$$\begin{aligned}
 T(n) &= c_1 n + c_2(n - 1) + c_3(n - 1) + c_4(n - 2) + c_7(n - 1) = (c_1 + c_2 + c_3 + c_4 + \\
 &+ c_7)n - (c_2 + c_3 + 2c_4 + c_7) \\
 &= \theta(n)
 \end{aligned}$$

2.2.3

k -sorted array - is an array where each element is at most k distance away from its target position in the sorted array.

Worst-case of Insertion sort for k -sorted array = $\theta(nk)$. In worst case inner cycle runs k times (Elements placed in k distance from correct places). To move every element to its correct place, at most k elements need to be moved.

Insertion Sort (Pseudocode)	Cost	Times (Worst Case)
for j = 2 to A.length	C1	n
key = A[j]	C2	$n - 1$
i = j - 1	C3	$n - 1$
while i > 0 and A[i] > key	C4	$\sum_{j=2}^n k$
A[i + 1] = A[i]	C5	$\sum_{j=2}^n k - 1$
i = i - 1	C6	$\sum_{j=2}^n k - 1$
A[j + 1] = key	C7	$n - 1$

$$T(n) = c_1n + c_2(n - 1) + c_3(n - 1) + c_4(n(k - 1)) + c_5((n - 1)(k - 1)) + c_6((n - 1)(k - 1)) + c_7(n - 1) = (c_4 + c_5 + c_6)nk + (c_1 + c_2 + c_3 - c_4 - c_5 - c_6 + c_7)n - (c_5 + c_6)k - (c_2 + c_3 - c_5 - c_6 + c_7)$$

$$= \theta(nk)$$

$$* n \geq k > 0$$

Insertion sort works faster (in worst-case) for k -sorted array: $\theta(nk) \leq \theta(n^2)$

2.2.4

Here you can see pseudocode with structure which represent given data, function that compare two objects (by code, date_start, date_end, sponsor and description) and function that sort array with objects

<pre>struct object string code string date_start string date_end string sponsor string description bool a_more_than_b(object a, object b) if a.code.size > b.code.size return true else if a.code.size < b.code.size return false else for i = 1 to a.code.size if a.code[i] < b.code[i] return false if a.code[i] > b.code[i] return true for i = 7 to 10 if a.date_start[i] < b.date_start[i] return false if a.date_start[i] > b.date_start[i] return true for i = 4 to 5 if a.date_start[i] < b.date_start[i] return false if a.date_start[i] > b.date_start[i] return true for i = 1 to 2 if a.date_start[i] < b.date_start[i] return false if a.date_start[i] > b.date_start[i] return true for i = 7 to 10 if a.date_end[i] < b.date_end[i] return false if (a.date_end[i] > b.date_end[i]) return true</pre>	<pre>for i = 4 to 5 if a.date_end[i] < b.date_end[i] return false if a.date_end[i] > b.date_end[i] return true for i = 1 to 2 if a.date_end[i] < b.date_end[i] return false if a.date_end[i] > b.date_end[i] return true if a.sponsor.size > b.sponsor.size return true else if a.sponsor.size < b.sponsor.size return false else for i = 1 to a.sponsor.size if a.sponsor[i] < b.sponsor[i] return false if a.sponsor[i] > b.sponsor[i] return true if a.description.size > b.description.size return true else if a.description.size < b.description.size return false else for i = 1 to a.description.size if a.description[i] < b.description[i] return false if a.description[i] > b.description[i] return true return false void sort(object A[]) for j = 2 to A.length key = A[j]; i = j - 1; while i > 0 and a_more_than_b(A[i], key) A[i + 1] = A[i] i = i - 1 A[i + 1] = key</pre>
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2.2.5

Recursive

```
bool belongs(A, from, to, x)
    if (to >= from)
        mid = from + (to - from)/2
        if (A[mid] == x)
            return true
        if (A[mid] > x)
            return belongs(A, from, mid - 1, x)
        else
            return belongs(A, mid + 1, to, x)
    return false
```

Iterative

```
bool belongs(A, from, to, x)
    while (to >= from)
        mid = from + (to - from)/2
        if (A[mid] == x)
            return true
        if (A[mid] > x)
            to = mid - 1
        else
            from = mid + 1
    return false
```

2.2.6

```
int search(A, from, to, x)
    if (to >= from)
        mid = from + (to - from)/2
        if (A[mid] == x)
            return mid
        if (A[mid] > x)
            return search(A, from, mid - 1, x)
        else
            return search(A, mid + 1, to, x)
    return null
```

2.2.7

$$T(n) = T \times \left(\frac{n}{2}\right) + 1$$

$$a = 1, b = 2, f(n) = 1$$

$$n^{\log_b a} = n^{\log_2 1} = n^0 = 1$$

$$f(n) = n^{\log_b a} \rightarrow 2nd \text{ Case}$$

$$T(n) = \theta(n^{\log_b a} \log n) = \theta(\log n)$$

2.2.8

Search (Binary search) helps to reduce the number of comparisons. We can use Search to find location to insert the selected element at each iteration. In normal insertion sort, it takes $O(n)$ comparisons (at n th iteration) in the worst case. We can reduce it to $O(\log n)$ by using binary search.

Pseudocode:

```
int search(A, from, to, x)
    if (to >= from)
        mid = from + (to - from)/2
        if (A[mid] == x)
            return mid
        if (A[mid] > x)
            return search(A, from, mid - 1, x)
        else
            return search(A, mid + 1, to, x)
    return null
```

```
void insertionSort(A)
    for j = 2 to A.length
        key = A[j]
        i = j - 1
        loc = search(A, 0, i, key)
        if (loc == null)
            while i > 0 and A[i] > key
                A[i+1] = A[i]
                i = i - 1
            A[i+1] = key
        else
            while i >= loc
                A[i+1] = A[i]
                i = i - 1
            A[i+1] = key
```

Time Complexity: The algorithm as a whole still has a running worst-case running time of $\theta(n^2)$ because of the series of swaps required for each insertion.

2.2.9

Bubble sort is easy to parallelize. We need to sort subarrays in different threads and after that we should merge with 2 pointers. Execution time = $\frac{n^2}{2} + n$:

<pre>void bubble(A, from, to) for (j = from; j < to - 1; j++) for (i = from; i < to-1; i++) if A[i] > A[i+1] swap(A[i], A[i+1]) void sort(A) int ans[A.size] i = 0 j = A.size / 2 thread1(bubble, A, 0, j) thread2(bubble, A, j, A.size) thread1.wait</pre>	<pre>thread2.wait k = 0 while i != A.size / 2 and j != A.size if A[i] < A[j] ans[k++] = A[i++] else ans[k++] = A[j++] while i != A.size / 2 ans[k++] = A[i++] while j != A.size ans[k++] = A[j++] A = ans</pre>
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2.3

2.3.1

AVL tree's properties:

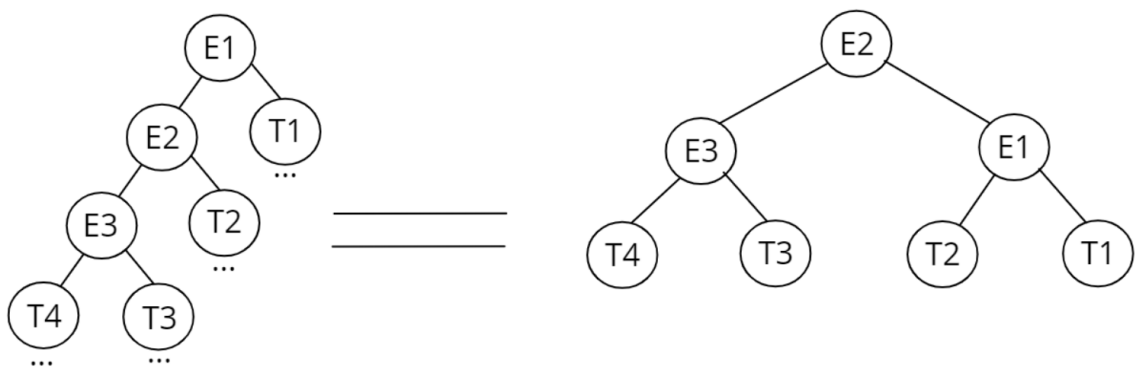
1. Each tree has a root node
2. Each node has 0, 1 or 2 child nodes
3. For each node maximum count of child = 2
4. $| \text{height}(\text{left subtree}) - | \text{height}(\text{right subtree}) | = \{-1, 0, 1\}$

2.3.2

1. Perform standard Binary Search tree insert for new element (we use search algorithm until no child, and put at that point) (N)
2. Count all differences between the height of left subtree and the height of right subtree, starting with the element N
 - a. Find the first unbalanced node
 - b. Let E1 be the first unbalanced node. E2 be the child of this node that is on the path from N to E1. E3 be the grandchild of E1 that is on the path from N to E1
 - c. Rebalance tree (4 cases):
 - i. Left Left Rotation (E2 is left child of E1 and E3 is left child of E2)
 - ii. Left Right Rotation (E2 is left child of E1 and E3 is right child of E2)
 - iii. Right Left Rotation (E2 is right child of E1 and E3 is left child of E2)
 - iv. Right Right Rotation (E2 is right child of E1 and E3 is right child of E2)

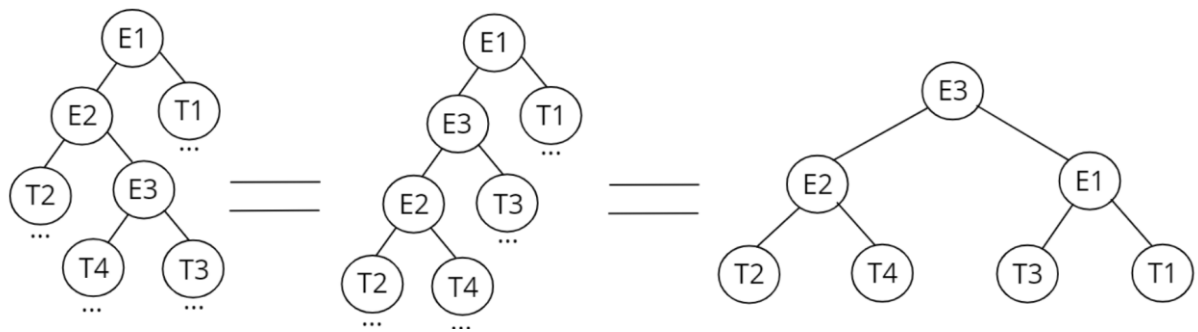
Left Left Rotation

T1, T2 ... - subtrees



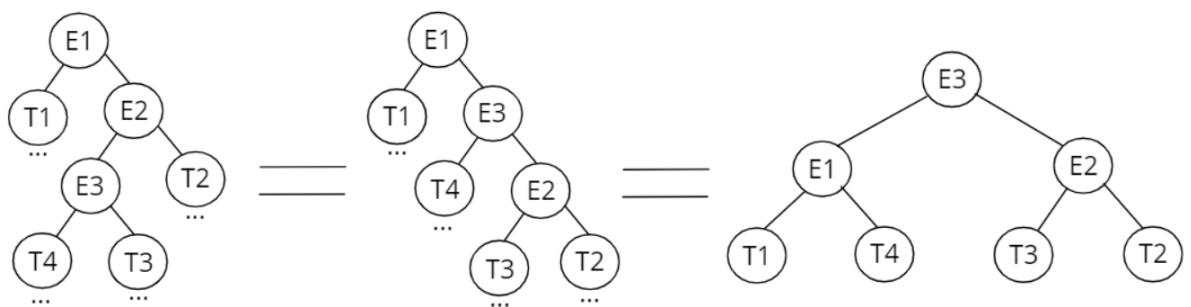
Left Right Rotation

T1, T2 ... - subtrees



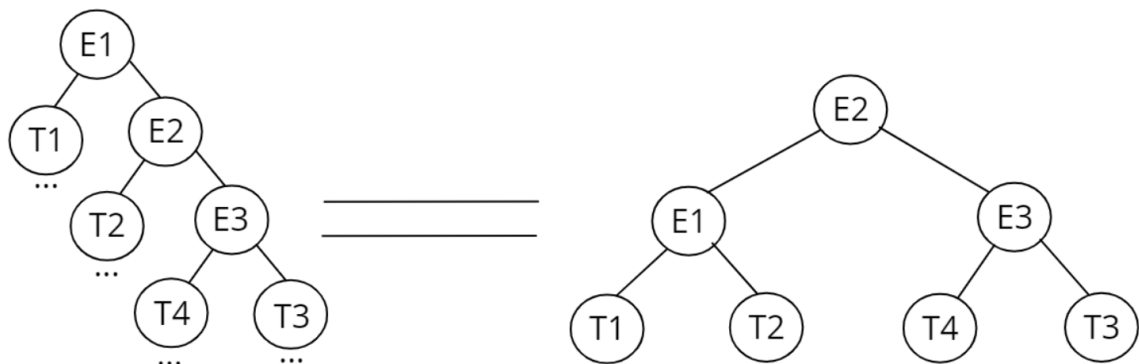
Right Left Rotation

T1, T2 ... - subtrees

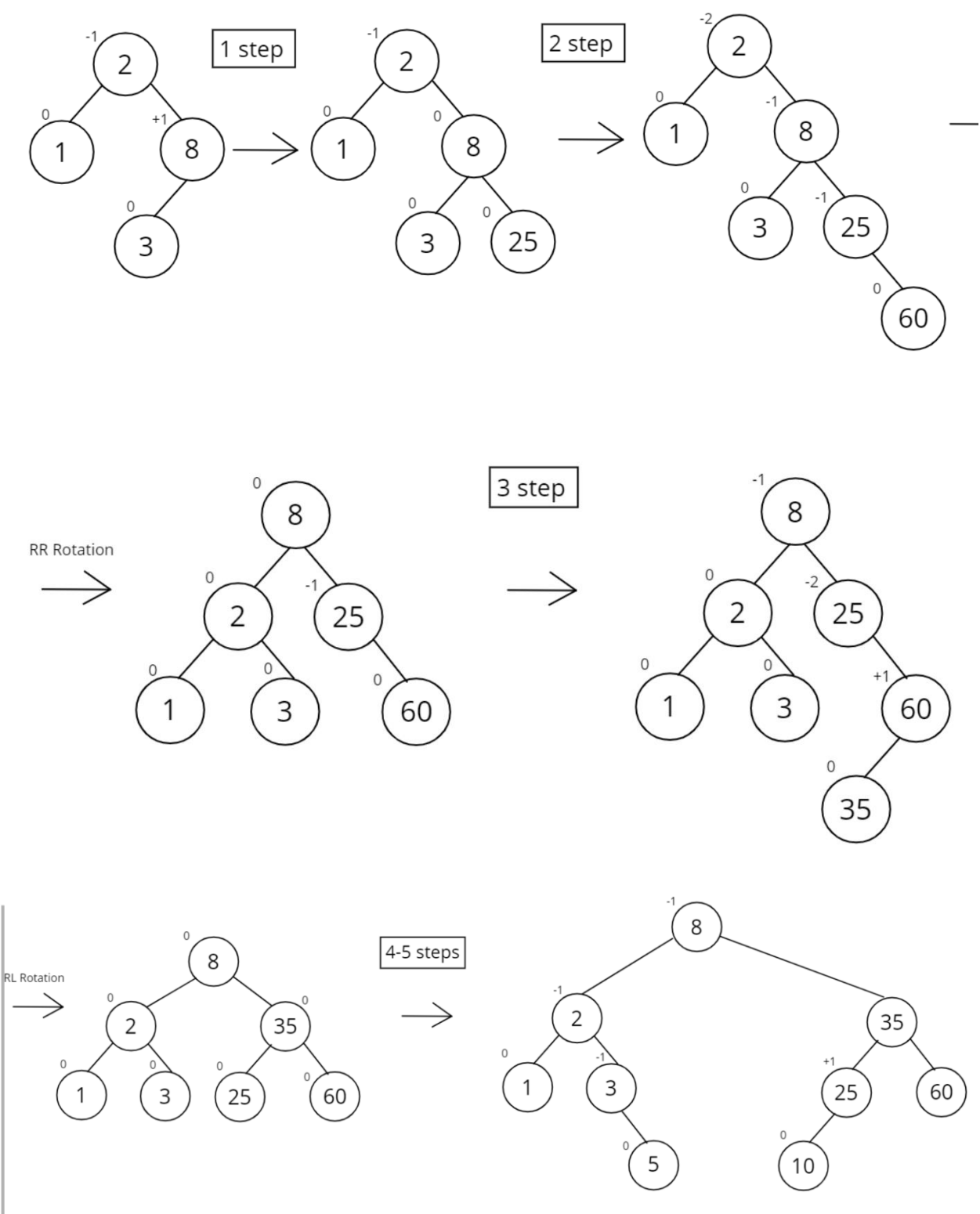


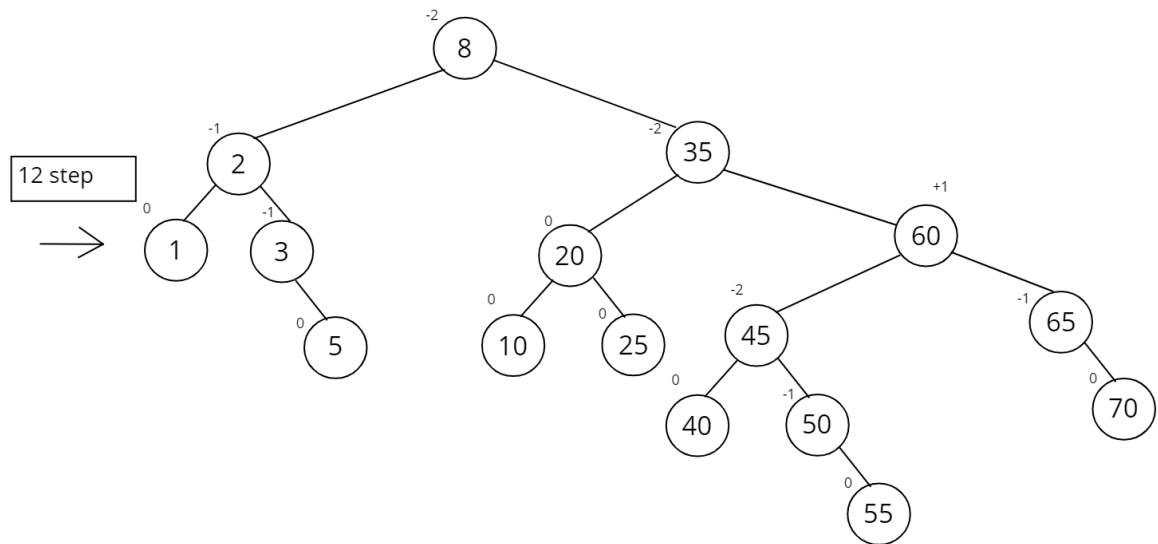
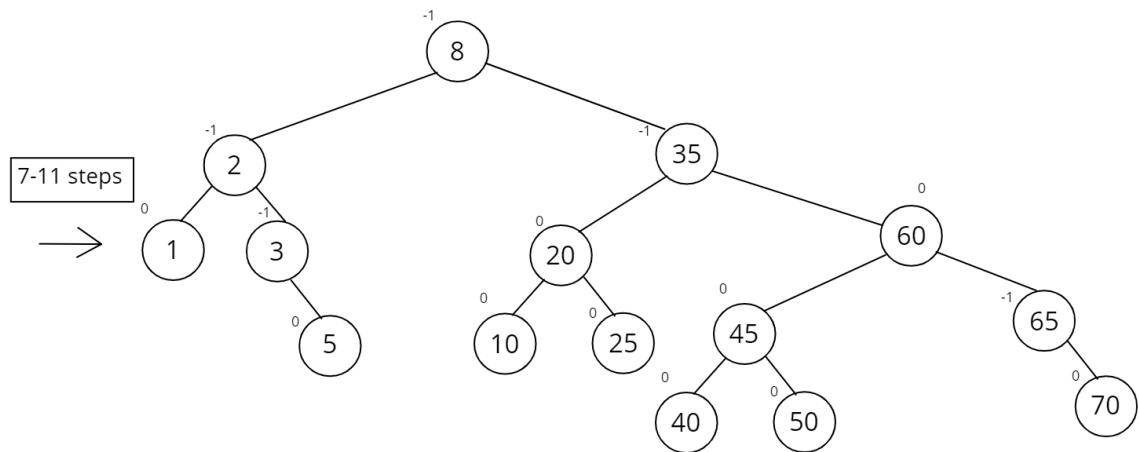
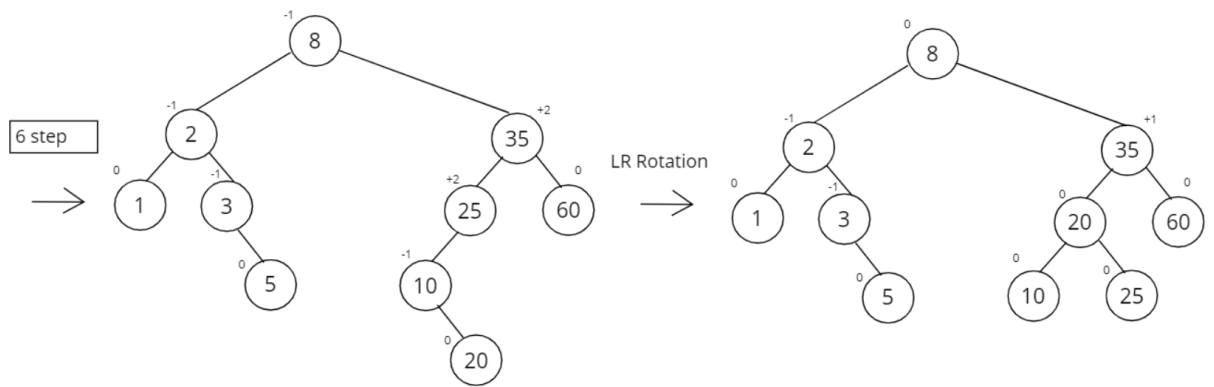
Right Right Rotation

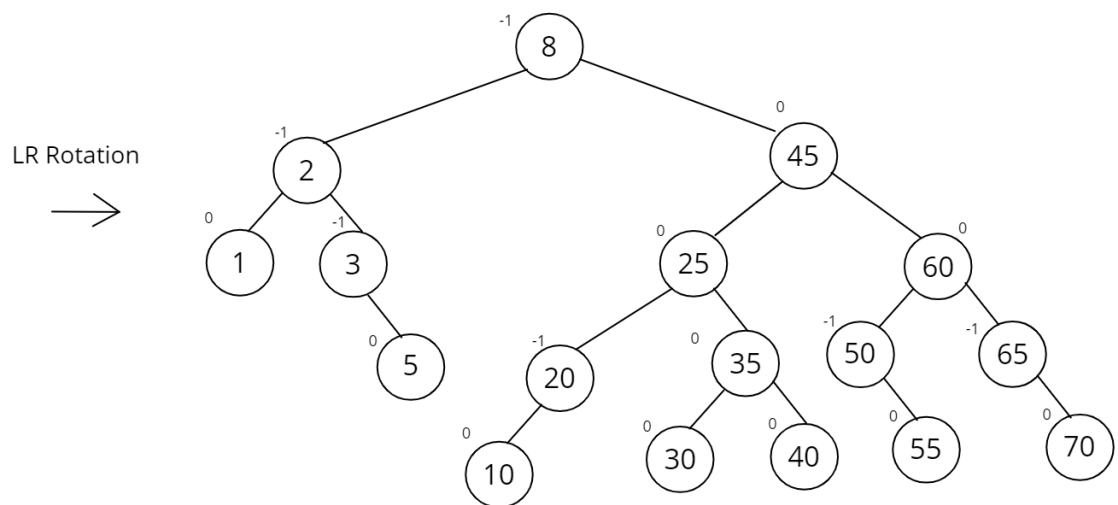
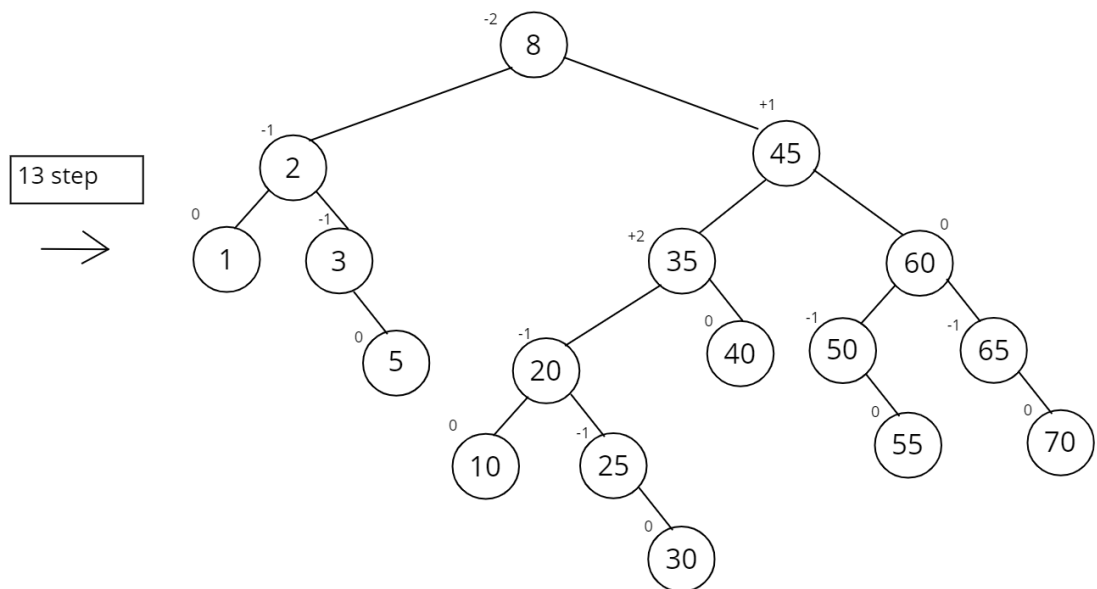
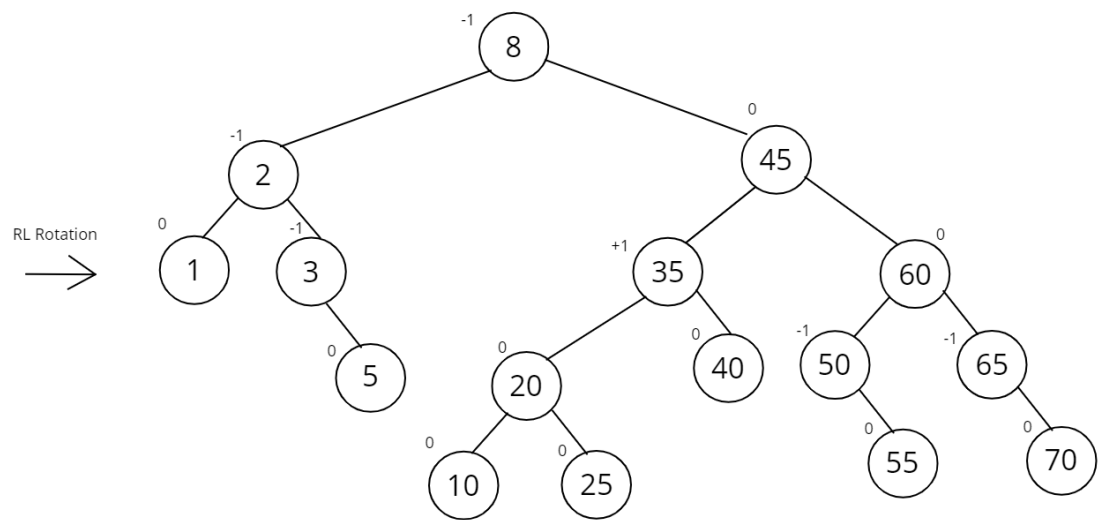
T1, T2 ... - subtrees

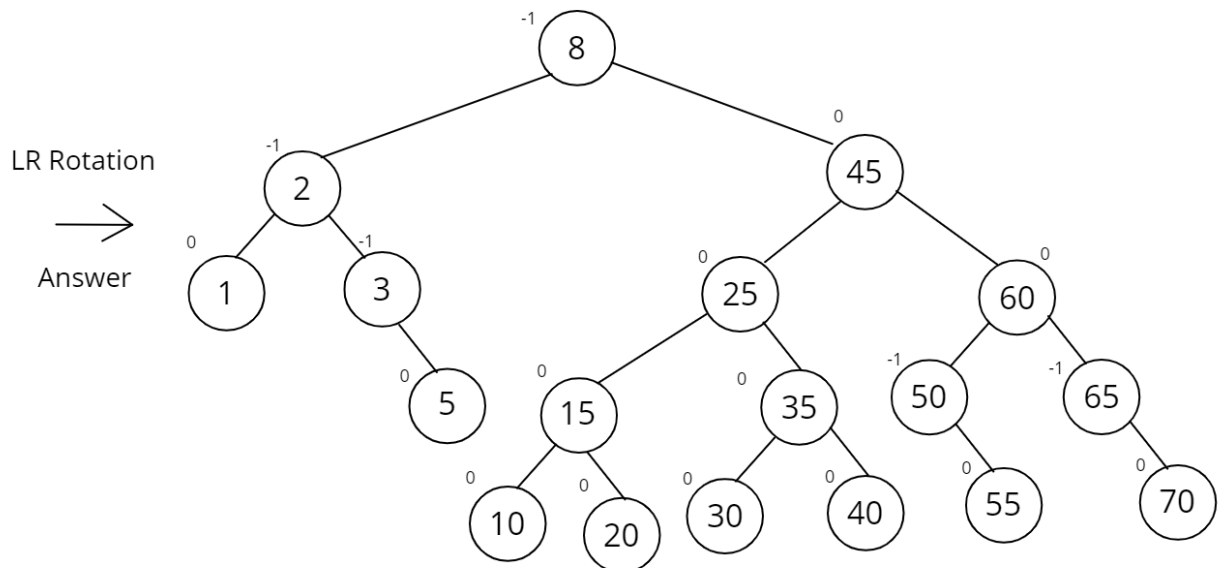
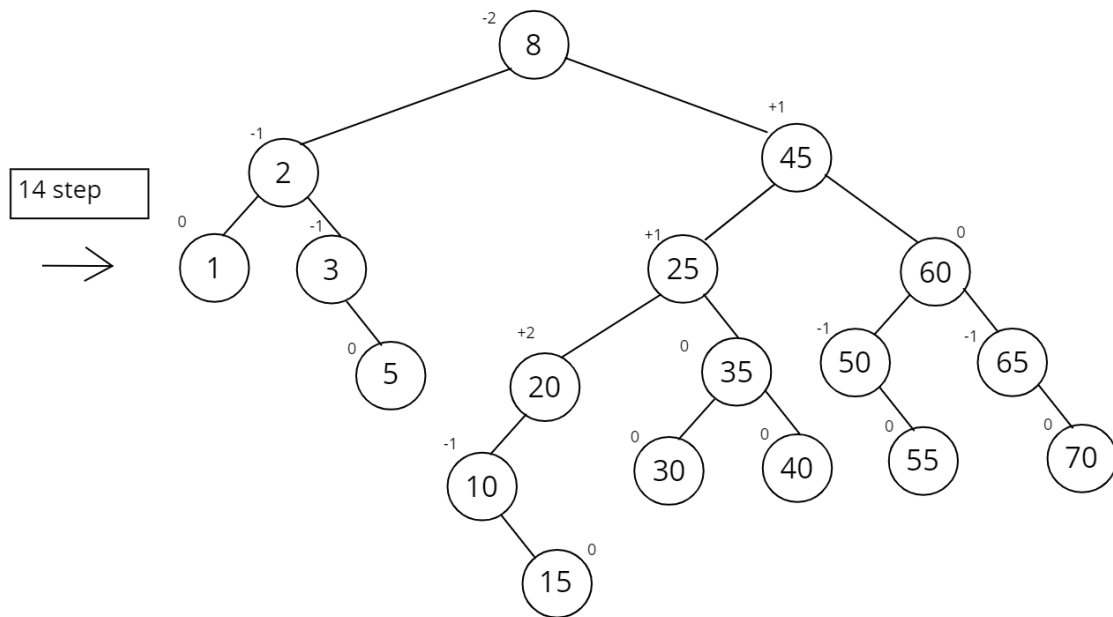


2.3.3









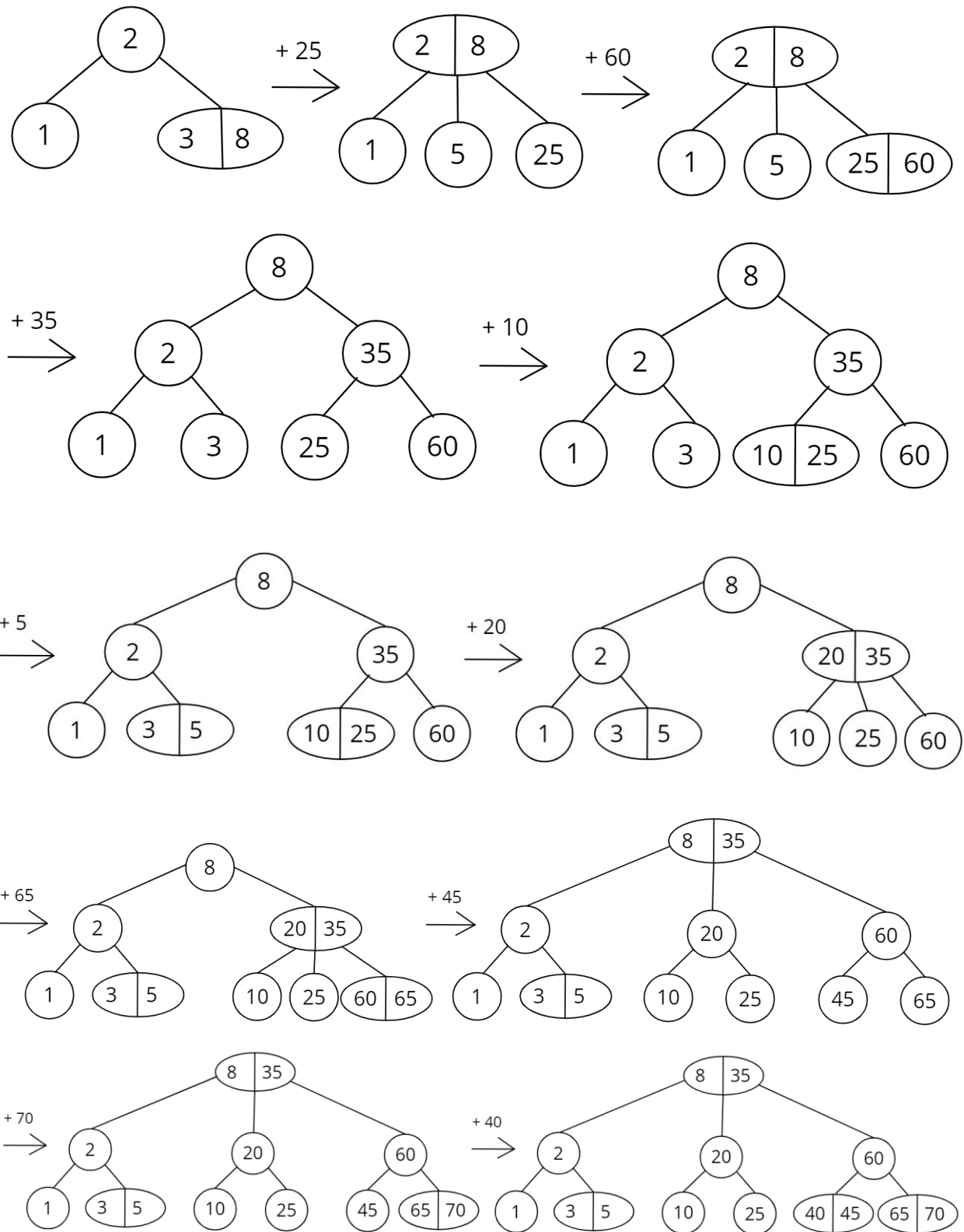
2.3.4

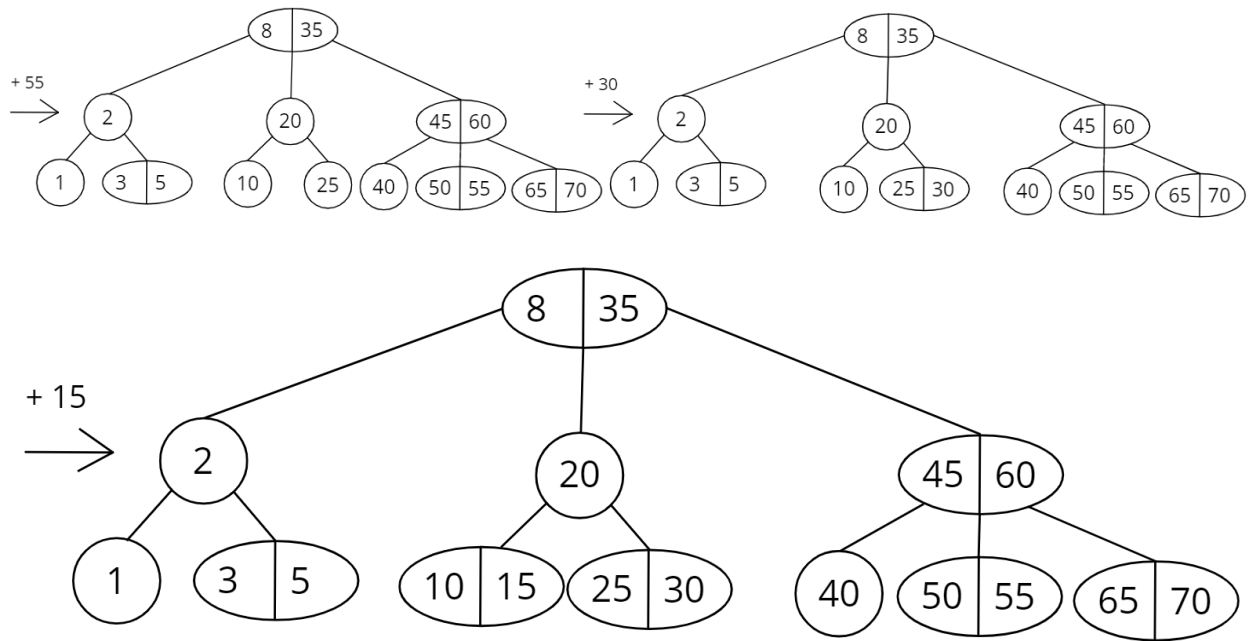
In-Order traversal of the tree:

1, 2, 3, 5, 8, 10, 15, 20, 25, 30, 35, 40, 45, 50, 55, 60, 65, 70

Numbers ordered in increasing order. But if we have equivalent nodes in our tree, order will be not-decreasing. Therefore it is not always the case.

2.3.5



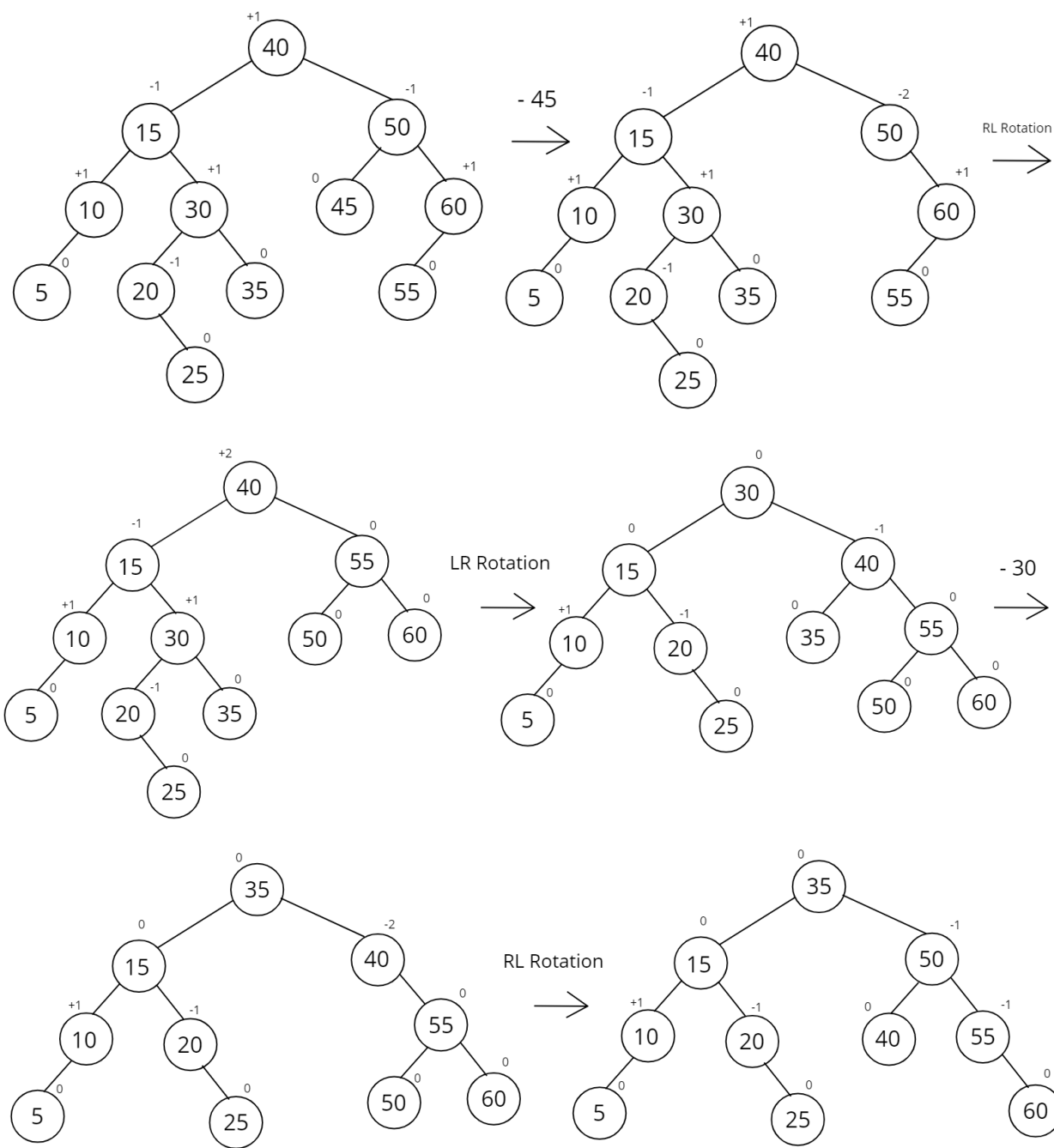


2.3.6

Delete operation for AVL trees:

1. Identify successor for given node, replace the node with successor, delete our new successor (given node – element N)
2. Count all differences between the height of left subtree and the height of right subtree, starting with the parent of successor (or with parent of N)
 - a. Find the first unbalanced node
 - b. Let E1 be the first unbalanced node. E2 be the larger height child of E1. E3 be the larger height child of E2.
 - c. Rebalance tree(4 cases):
 - i. Left Left Rotation (E2 is left child of E1 and E3 is left child of E2)
 - ii. Left Right Rotation (E2 is left child of E1 and E3 is right child of E2)
 - iii. Right Left Rotation (E2 is right child of E1 and E3 is left child of E2)
 - iv. Right Right Rotation (E2 is right child of E1 and E3 is right child of E2)

2.3.7



2.4

```
class midElement
private:
    minHeap min;
    maxHeap max;

public:
    midElement()

    void insert(int val)
        min.insert(val);
        if (min.size() - 1 > max.size())
            max.insert(min.pop());
        if (max.size() and min.size() and min.peak() < max.peak())
            int t_Min = max.pop();
            int t_Max = min.pop();
            max.insert(t_Max);
            min.insert(t_Min);

    int remove_median()
        int res = min.pop();
        if (min.size() < max.size())
            min.insert(max.pop());
        return res;

    int size()
        return min.size() + max.size();

    bool isEmpty()
        return !size();
```

Wors-Case time complexity	
insert()	$\theta(\log n)$
remove_median()	$\theta(\log n)$
size()	$\theta(1)$
isEmpty()	$\theta(1)$