



Real Time Operating Systems

UNIVERSITY OF IDAHO – JOHN C. SHOVIC, PHD

COEUR D'ALENE

Assignment #16/17 Discussion

- ▶ I2C issues
- ▶ Stepper Motors
- ▶ Buttons

IOT Presentations



IOT Presentation Schedule ▾

John Shovic

All Sections

Last Name	First Name	IOT Presentation Date
Fredrickson	Samuel	April 21st
Harris	Justin	April 21st
Hawkins-Start	Hunter	April 21st
McVickar	Christopher	April 21st
Nardi	Gage	April 21st
Olds	Kristie	April 21 st (1:45pm)
Palmer	Nathaniel	April 26 th
Preston	Zachariah	April 26th
Prestwitch	Ross	April 26th
Shoup	Scott	April 26th
Wells	Garret	April 26th
Williams	Taegan	April 26 th (1:45pm)



New Appliances – I lied.

- ▶ We bought 4 new medium high end GE Café Appliances
- ▶ Dishwasher
- ▶ Gas Stove
- ▶ Microwave
- ▶ Refrigerator

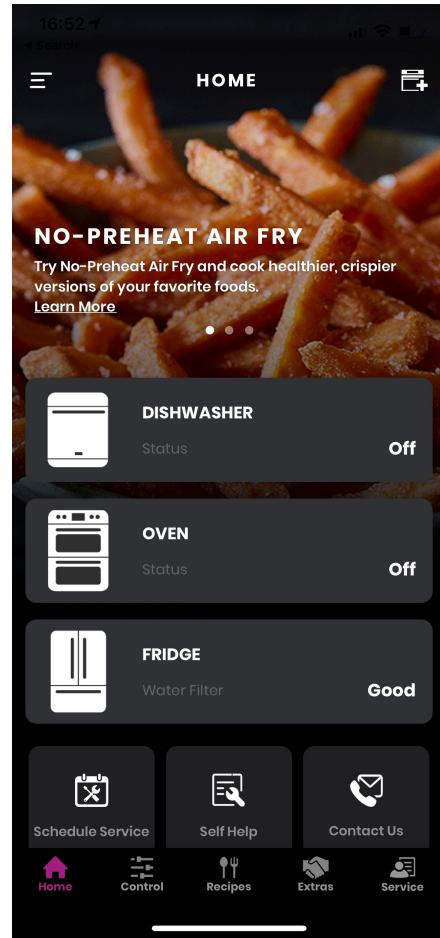
- ▶ Ack! They are all connected appliances!

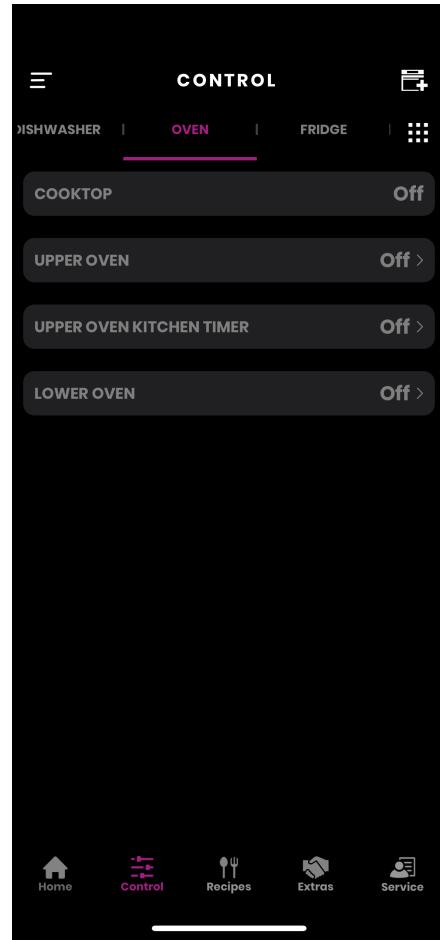
- ▶ The setup was a different screen and flow for each one! No commonality except for password length

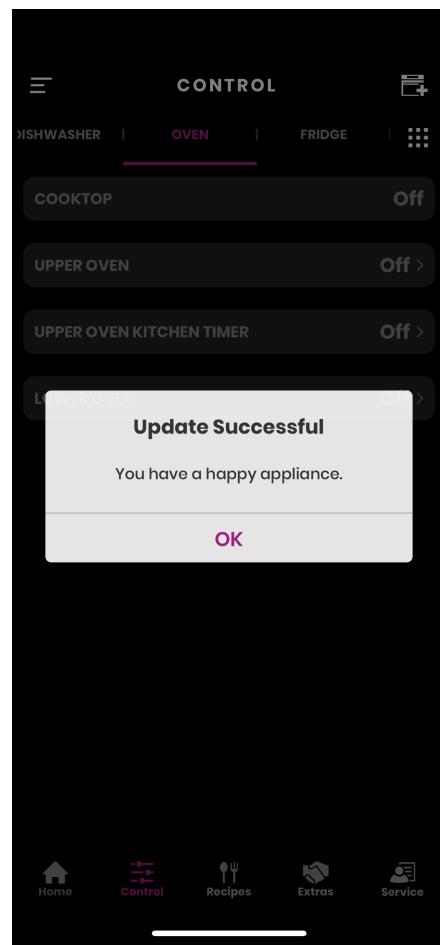


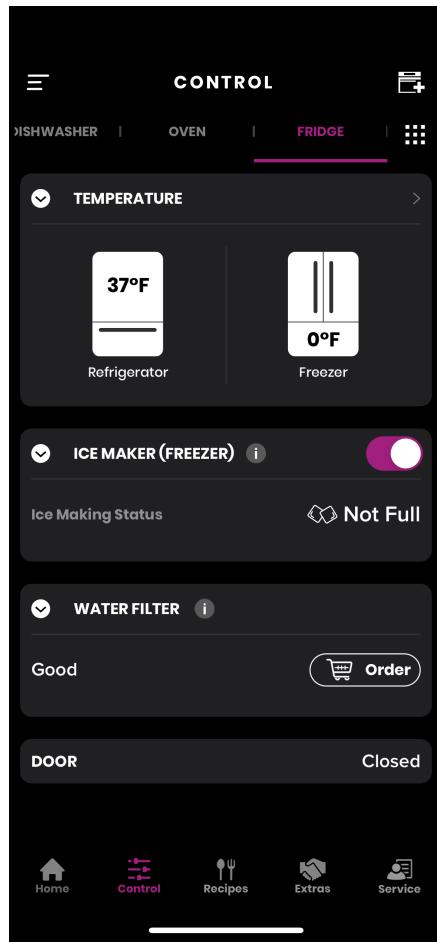


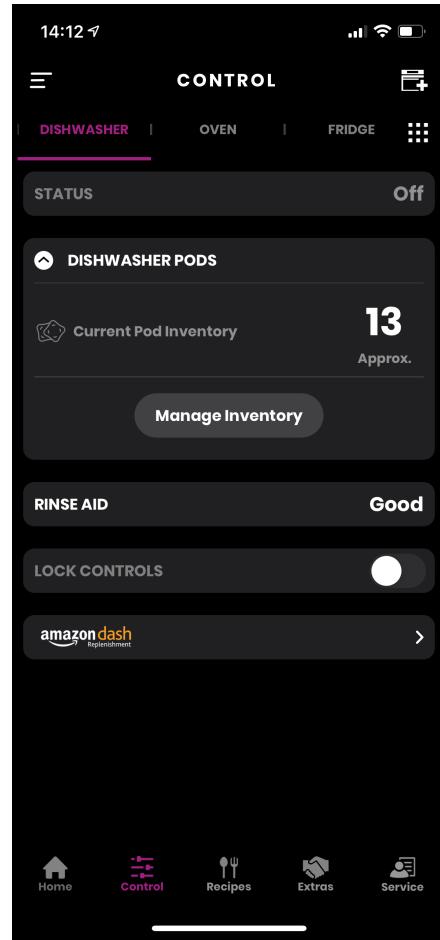






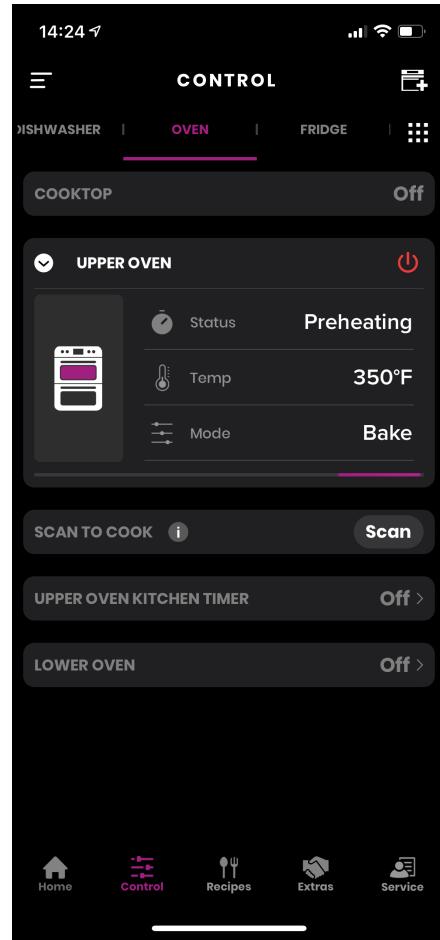








Error 400: 09c42a59-cebe-4f01-b973-5a78c7eddefc



Comparing freeRTOS to other mainstream RTOS products

- ▶ There are dozens of RTOS systems out in the wild
- ▶ Major differentiator?
 - ▶ Closed
 - ▶ Open Source

Some Major Open Source RTOS

- ▶ freeRTOS (stewardship by Amazon now)
- ▶ uCOS
- ▶ DSPnano RTOS
- ▶ Trampoline Operating System (just like the name)
- ▶ TI-RTOS Kernel
- ▶ Real-time Linux
- ▶ eCOS
- ▶ Micro C/OS-II

Some Major Closed Source RTOS Systems

- ▶ vXWorks
- ▶ Windows 10 IoT
- ▶ Transaction Processing Facility
- ▶ RTOS-32
- ▶ RedHawk Linux (RHEL, CentOS; Ubuntu compatible)
- ▶ QNX (Blackberry, Ford Cars) - went OS to CS
- ▶ Phoenix-RTOS (IOT)
- ▶ Flexible Safety RTOS

Advanced RTOS Topics

Synchronization Techniques

- ▶ Unilateral rendezvous
- ▶ Credit Tracking (token passing)
- ▶ Bilateral Rendezvous
- ▶ Client-Server
- ▶ Synchronizing multiple tasks
- ▶ Selecting the right synchronization method

RTOS Pitfalls and Issues

- ▶ Complexity
- ▶ Issues – Task Jitter
- ▶ Issues – Thread Starvation
- ▶ Issues – Priority Inversion
- ▶ Issues – Deadlock

Debugging RTOS Applications

- ▶ Printf
- ▶ ITM Instrumentation Trace Macrocell – printf through hardware
- ▶ ASSERT
- ▶ SWD (JTAG requires 4 signal lines, SWD only requires 2 signal lines)
- ▶ OS-Aware Debugging
- ▶ Real-time Tracing (needs hardware support for good accuracy)
- ▶ Debugging tools (CDB, etc. Need breakpoints!)
- ▶ Error Trapping

RTOS Application Design Patterns

- ▶ UART command processing
- ▶ Sensor Sampling Strategies
- ▶ Command Processing
- ▶ User Interactions
- ▶ TCP/IP Integration
- ▶ System Testing

Optimizing RTOS Applications

- ▶ RTOS Configuration
- ▶ Memory
- ▶ Performance
- ▶ Energy
- ▶ Trade-offs

Developing Secure RTOS Applications

- ▶ Using the MPU with Tasks
- ▶ Defining trusted and untrusted code
- ▶ Using Arm Trustzone with an RTOS
- ▶ Thinking like a hacker

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Debugging RTOS



- ▶ Overview of debugger for a embedded system
- ▶ Story of debugger development
- ▶ Architectural structure and motivation
- ▶ How is a Java debugger different?

What is a Debugger

- ▶ A tool to remove bugs from a program
- ▶ Used in program testing/inspection
- ▶ Used to test a module or algorithm

Current State of the Art

- ▶ GUI debugger that may be part of a larger development environment
- ▶ Many windows each of which supports different aspects of debugging
- ▶ Should have a non-GUI, script-driven mode for batch testing

Basic Principles

- ▶ Debugging a program affects the program
 - ▶ Debugger is present and running
 - ▶ On cross systems this often means a debug monitor is running on the target
 - ▶ On cross systems, the debugger may be “in control” of the target. It controls interrupts, I/O, etc.
 - ▶ On native systems, the program is sharing resources with the debugger
 - ▶ Stopping a program affects timing.

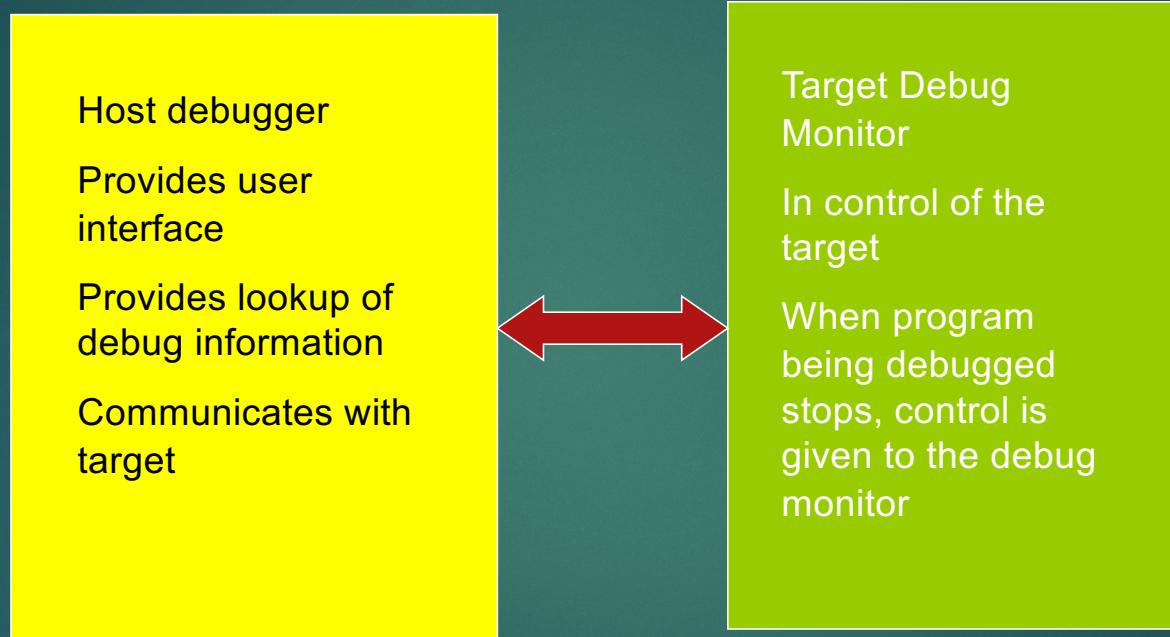
Basic Principles

- ▶ Debuggers should be truthful
 - ▶ Sounds simple, but can be very difficult, especially when compiler optimizations are involved.
 - ▶ Examples:
 - ▶ Code motion
 - ▶ Variable sometimes in register, sometimes in memory (sometimes in cache)

Basic Principles

- ▶ Context is important
 - ▶ When stopped, show associated source code
 - ▶ Provide ability to see call stack
 - ▶ Provide tracing mechanism (source and machine level)
 - ▶ When multiple threads are involved, provide information on the state of the threads.

Basic Debugger Division



Basic Requirements for Debug Monitor

- ▶ Set and delete breakpoints
 - ▶ Software breakpoints
 - ▶ Hardware breakpoints
- ▶ Single step one machine instruction
- ▶ Read and write memory
- ▶ Read and write registers

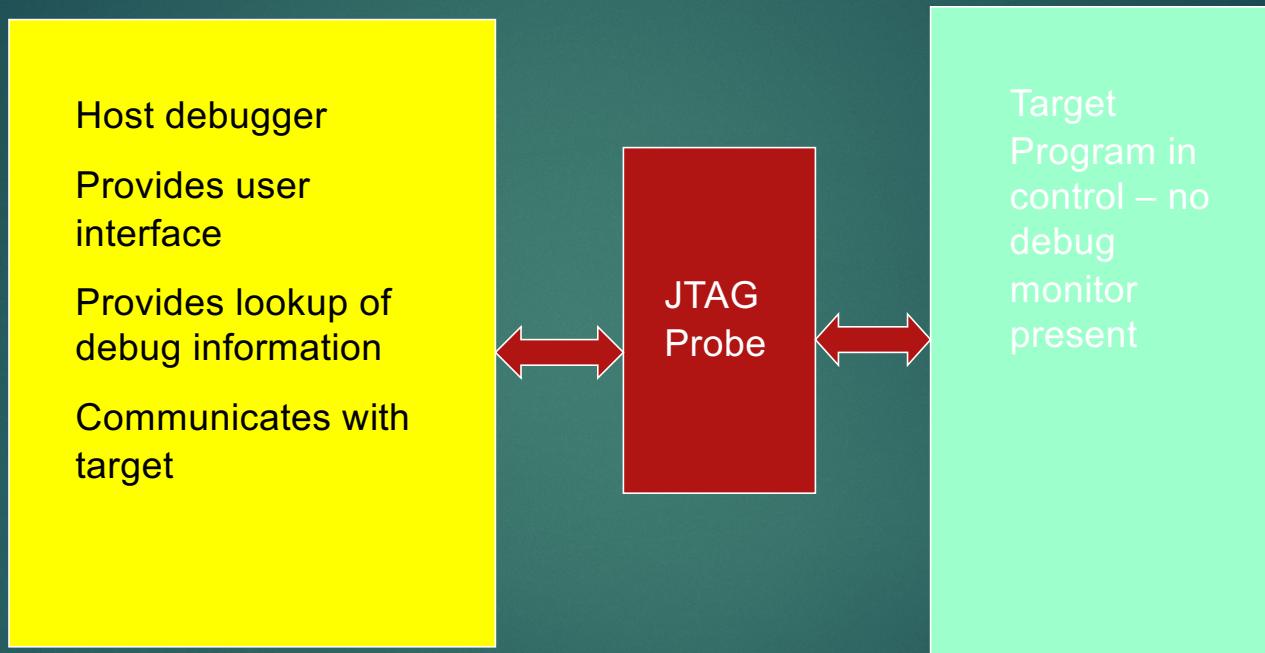
Debug Monitor Functionality

- ▶ Software breakpoint
 - ▶ Usually write some specific instruction in memory. Attempt to execute causes a trap. Trap handler gives control to D.M.
- ▶ Hardware breakpoint
 - ▶ Write an address in one of a number of special registers. When the instruction about to be executed is at an address in one of these registers, a Trap occurs.

Debug Monitor Functionality

- ▶ When trap occurs, D.M. must save context of program, so that its use of resources does not corrupt program. Probably needs to flush any data cache, invalidate instruction cache.
- ▶ Now can read/write any memory. Read/write registers by manipulating the saved context.

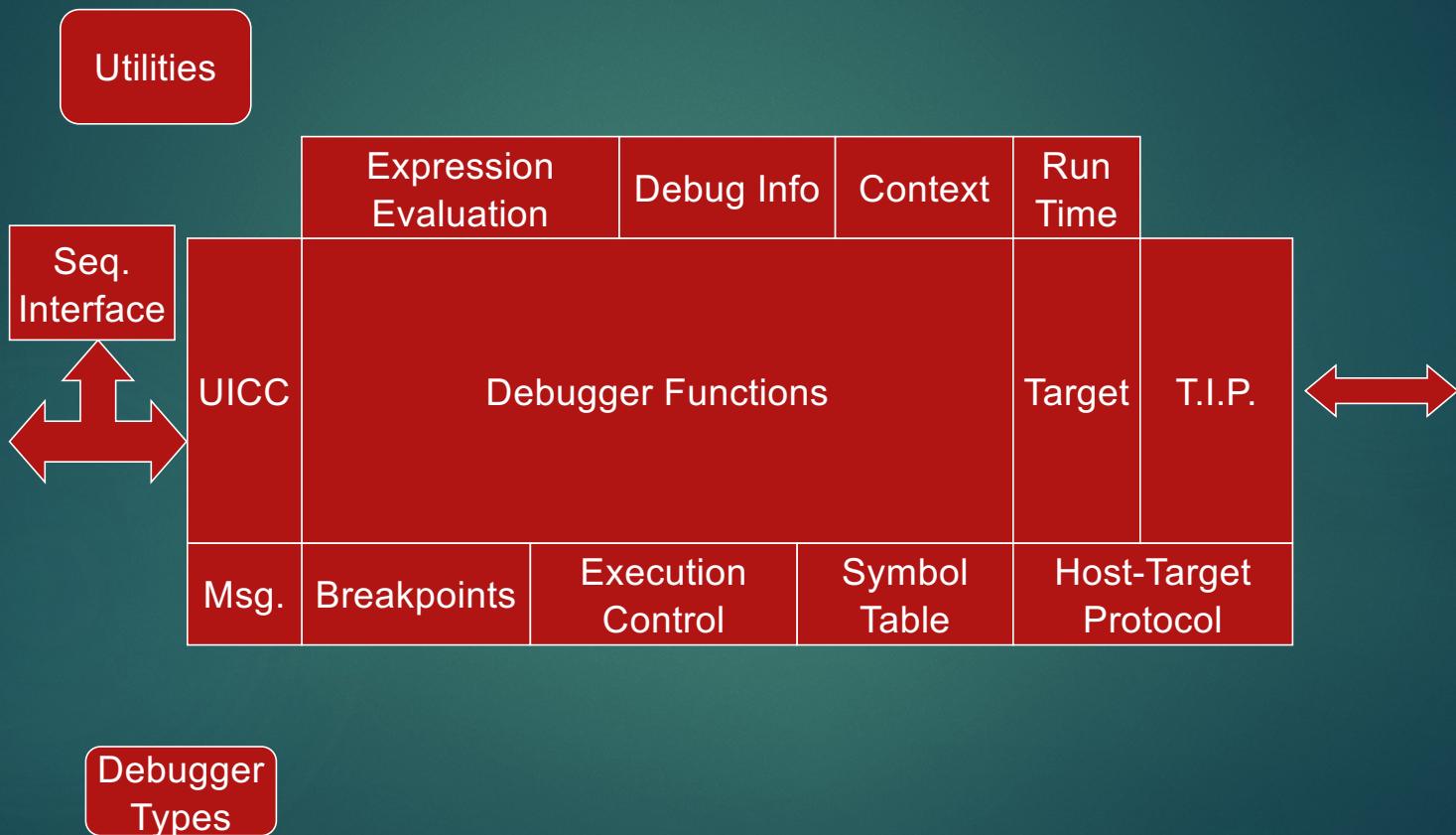
JTAG Debugging



JTAG Probe

- ▶ Provides direct access to the registers and memory of the target through the hardware. May be “smart enough” to know about cache.
- ▶ Using JTAG means program being debugged runs more normally – no debug monitor.

Host Debugger Components



Setting Breakpoints

- ▶ Find the address or addresses at which to set the breakpoint.
- ▶ Breakpoint Handler keeps track of breakpoints (inc. conditions, associated commands, etc.)
- ▶ Read memory at breakpoint address and save contents.
- ▶ Write breakpoint instruction to address

Evaluating an Expression

- ▶ Find appropriate debug information for current context.
- ▶ For each variable, look up.
 - ▶ Determine location, type info (for structs, this means finding offsets of each component)
- ▶ Read appropriate location (reg or mem) from target. Create appropriate “object”
- ▶ Perform appropriate operations on objects
- ▶ Format and display result

Modifying a Variable

- ▶ As with expression, get context, find variable, get its “shape” and location.
- ▶ If the location is not constant, create an appropriate “memory image” for the variable
- ▶ Write the memory (or register) on the target.

Showing a Call Stack

- ▶ Need to determine return address for a call
 - ▶ Can use debug information that tells where to find the return address
 - ▶ Can use architecture knowledge of how generated code is supposed to behave (if there is a standard).

Continuing from a Breakpoint

- ▶ If you continue from address, you will just trap again
- ▶ Get saved instruction for that address.
- ▶ Write that instruction to memory
- ▶ Do a machine singlestep away from the break location.
- ▶ Write the breakpoint instruction back.

Source Code SingleStep

- ▶ Find all locations where the execution can go next. (involves consulting debug information)
- ▶ Set a temporary breakpoint at address for each location.
- ▶ Go
- ▶ Delete the temporary breakpoints
- ▶ Report step completed

Other interesting actions

- ▶ Machine code tracing
- ▶ Source code tracing
- ▶ Breakpoints with conditions
- ▶ Parameters for a procedure or function
- ▶ Watching a set of registers
- ▶ Watching a number of expressions
- ▶ Watching memory

Other interesting actions

- ▶ Data access breakpoints
- ▶ Debugging code in ROM
- ▶ Supporting multiple languages

Coming Soon!

- ▶ IOT Device Presentations – schedule posted
- ▶ Oral Exams – Schedule Posted