## Dan Brogan

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**EDUCATION:** Dec. 2021 **University of Southern California (USC)** M.S. Astronautical Engineering **GPA: 3.96** Concentrations: Space Systems Design, Space Applications **University of Rhode Island (URI)** May 2020 B.S. Mechanical Engineering **GPA: 3.94** Minors: Robotics Engineering, Mathematics **ENGINEERING EXPERIENCE:** Fractal Forms USA LLC President 2022-Present Manages 5-Axis 3D printer company. Leads R&D efforts for software, hardware, and electronics **Roger Williams University** 2022 Adjunct Professor of Physics Taught physics labs for undergraduate Physics I and Physics II **USC Rocket Propulsion Lab (RPL)** 2021 Analysis Engineer for spaceshot launch vehicle project Used ANSYS & MATLAB to validate retention rings and carbon-composite rocket fins. Static fire test in Mojave Desert **Space Engineering Research Center** Structures Engineer for Lunar Lander Prototype Performed ANSYS structural analysis and hand calculation validation for flight vehicle and testing structures **NASA RI Space Grant** 2019-2020 Rhode Island Space Grant Researcher for Artificially Intelligent Satellite Servicing Worked with Dr. Jouaneh and Dr. DiFilippo to optimize a deep learning computer vision system for fastener detection **Lockheed Martin** Mechanical Engineering Intern (Secret Security Clearance) Technical Lead and Small Business Coordinator for hydrostatic composite overwrapped pressure vessel (COPV) **URI Artificial Intelligence Laboratory** 2018-2019 Roboticist Constructed robots, hosted Arduino workshops, and helped facilitate URI's new public AI lab Ravtheon 2018 Mechanical Engineering Intern Used CREO Parametric for modelling complex solids for several Internal Research & Development (IRAD) projects **PUBLICATION Elsevier: Array Journal** 2021 "Deep Learning Computer Vision for Robotic Disassembly and Servicing Applications" Title: Daniel P. Brogan, Nicholas M. DiFilippo, Musa K. Jouaneh Authors: Link: https://doi.org/10.1016/j.array.2021.100094 **ENGINEERING PROJECTS:** 5-Axis 3D Printer 2022-Present Using Python to develop 5-axis slicer, Arduino to develop firmware, and currently iterating on hardware prototype design **Lunar Rover Concept Architecture: Robotic Remote-Sensing Scout (R2-S2)** Developed lunar astronaut-assisting rover concept and presented to Buzz Aldrin as well as NASA NESF 2022 conference **Lunar South Pole Base Design** 2021 Designed lunar base including site selection, life support systems, EVA operations, among other considerations Titan (Moon of Saturn) Entry Descent & Landing (EDL) Mission Design • Used MATLAB to simulate hypersonic, supersonic, & subsonic regimes for entry vehicle splashdown into Kraken Mare 3-Body Problem Orbital Mechanics Numerical Solver 2020 • Used MATLAB to numerically integrate and animate 3 body motion given masses and initial position and velocity vectors **NASA Venus Rover Mechanical Sensors** Worked with Mitch Brogan to design mechanical obstacle avoidance sensors for the public NASA HeroX challenge 2018-2019 **Pulse Jet and Turbo Jet Engines** Fabrication and testing of a valveless pulse jet engine and a turbo jet engine PROFESSIONAL SKILLS:

ASSOCIATIONS:

URI Astroneering (Founder & President)2019-2020URI American Society of Mechanical Engineers (President)2017-2019

Mechatronics, Python, MATLAB, Arduino, Visual Basic for Forms Applications, ANSYS Workbench, ANSYS Composite PrepPost (ACP), CREO Parametric, Autodesk Inventor, SolidWorks, Microsoft Excel, TIG Welding, Metal Shaping, Propulsion, Composites