Alexander Hay

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Education

Northwestern University Evanston, IL

M.S. Robotics Expected 2020

Iowa State UniversityAmes, IAB.S. Mechanical Engineering2014

Skills

• Coding: MatLab, Python, C, Git, OpenCV, ROS

- Design: Solidworks, AutoCAD, Inventor
- Relevant Classwork: Neural Control of Movement, Quantitative Methods in Neuroscience, Adv Mechatronics, Machine Learning and AI for Robotics, Biomechanics, Neurobiology

Projects Portfolio: <u>alexanderhay2020.github.io</u>

Development of an MRI-Compatible Mechatronic Tactile Stimulation Device - Thesis Project

- Built an MRI compatible pneumatic device to stimulate a sensory response at the fingertip
- Interdisciplinary approach involving embedded software design, modeling and fabrication, characterization and control

Learning Motion Model using Neural Network - ML/AI for Robots

• Implemented a neural network from scratch using gradient descent to generate a motion model of a roomba-like robot exploring its space

Biomimicry using SMA - Winter Project 2020

- Utilized shape memory alloy actuators to mimic the movement of a human elbow joint
- Apparatus used four actuators as analogues to the tricep, bicep, and brachialis muscles

Experience

Pearce Services - Des Moines, IA

Apr 2016 - Aug 2019

Desian Enaineer

- Created infrastructure plans for subdivisions, banks, and clinics for construction crews
- Project Management; responsible for defining scope and cost of the project; delegated field engineers
- Teamed with lead and field engineers to deliver on schedule and approved by city/county/state boards

Drive Spotter - Omaha, NE

Jun 2015 - Jan 2016

Product Engineer

- Developed a working prototype using OpenCV and cascade classifiers to identify traffic signs and zones
- Acted as many roles within a startup company; product development, R&D, project management
- Conducted prior art research; assisted in writing, editing, and revising patents and proposals

Medline Industries - Mundelein, IL

Jan 2015 - May 2015

R&D Material Technician

- Conducted tests evaluating material properties of medical products for manufacturers
- Constructed new testing procedures in compliance with relevant ISO regulations
- Quantified experimental data using Excel in the final report of quality assurance investigation

Rehabilitation Institute of Chicago - Chicago, IL

Jun 2014 – Sep 2014

Research Intern

• Worked with a team to develop an adaptive wheelchair controller for spinal cord injury patients

- Implemented a machine learning algorithm to calibrate and integrate IMU data streams
 Used Matlab to analyze the efficacy of the human-computer-interface