Alexander Hay

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Education

Northwestern University Evanston, IL

Northwestern University M.S. Robotics

Expected 2020

Iowa State UniversityB.S. Mechanical Engineering

Ames, IA

2014

Skills

• Coding: Python, C, C++, OpenCV, Git, ROS, MatLab

- Design: AutoCAD, Solidworks, Inventor, Onshape
- Relevant Classwork: Neural Mechanics, Biomechanics, Machine Design, Biomedical Mfg & Design, Multidisciplinary Design

Projects Portfolio: <u>alexanderhay2020.github.io</u>

Rethink Robotics Baxter Object Manipulation and Target Acquisition - Embedded Systems

- Utilized apriltags ros and darknet ros for object detection and tracking
- Applied moveit_ros inverse kinematics for motion control and planning

Learning Motion Model using Neural Network - ML/AI for Robots

• Implemented a neural network from scratch using gradient descent to generate a motion model of a roomba-like robot exploring its space

Biomimicry using SMA - Winter Project 2020

- Utilized shape memory alloy actuators to mimic the movement of a human elbow joint
- Apparatus used four actuators as analogues to the tricep, bicep, and brachialis muscles

Experience

Pearce Services - Des Moines, IA

Apr 2016 - Aug 2019

Design Engineer

- Created infrastructure plans and designs for subdivisions, banks, and clinics for construction crews
- Project Management; responsible for defining scope and cost of the project
- Collaborated with lead and field engineers to ensure the project met city/county/state reqs

Drive Spotter - Omaha, NE

Jun 2015 - Jan 2016

Product Engineer

- Developed a working prototype using OpenCV and cascade classifiers to identify traffic signs and zones
- Acted as many roles within a startup company, addressing CEOs, investors, and vendors
- Conducted prior art research; assisted in writing, editing, and revising patents and proposals

Medline Industries - Mundelein, IL

Jan 2015 – May 2015

R&D Material Technician

- Conducted tests evaluating material properties of medical products for manufacturers
- Constructed new testing procedures in compliance with relevant ISO regulations
- Quantified experimental data using Excel in final report of quality assurance investigation

Rehabilitation Institute of Chicago - Chicago, IL

Jun 2014 - Sep 2014

Research Intern

- Developed an adaptive wheelchair controller for spinal cord injury patients
- Implemented a machine learning algorithm to calibrate and integrate IMU data streams
- Utilized Matlab to analyze the efficacy of the human-computer-interface