

COM303: Digital Signal Processing

Lecture 2: Discrete-Time Signals

Module Overview:

- ► discrete-time signals
- ▶ elementary signal operations
- ▶ the Karplus-Strong algorithm

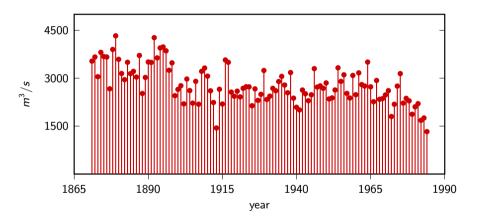
Discrete-time signals have a long tradition...

Meteorology (limnology): the floods of the Nile



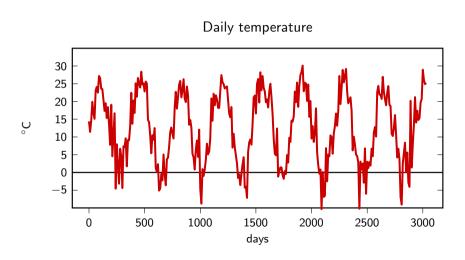
Representations of flood data: circa 2500 BC

Discrete-time signals have a long tradition...

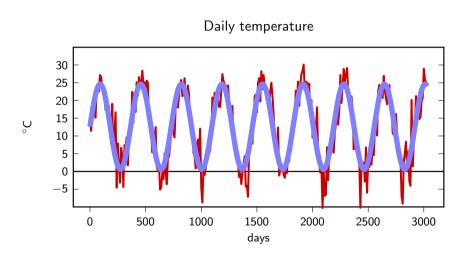


Representations of flood data: circa AD 2000

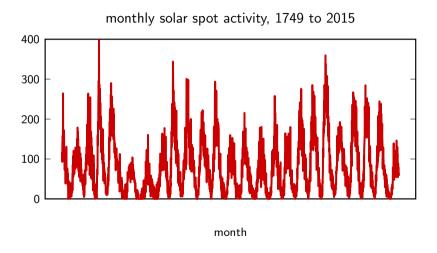
Probably your first scientific experiment...



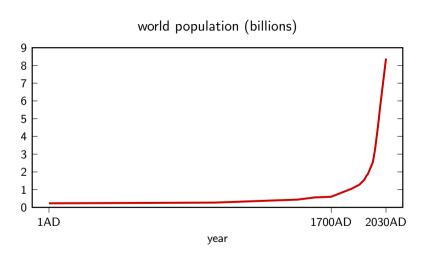
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Astronomy

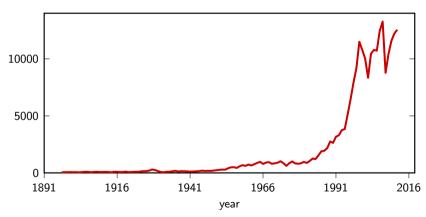


History and sociology



Economics

a purely man-made signal: the Dow Jones industrial average



discrete-time signal: a sequence of complex numbers

- ▶ one dimension (for now)
- ▶ notation: x[n]
- ightharpoonup two-sided sequences: $x: \mathbb{Z} \to \mathbb{C}$
- ▶ n is a-dimensional "time"
- analysis: periodic measurement
- synthesis: stream of generated samples

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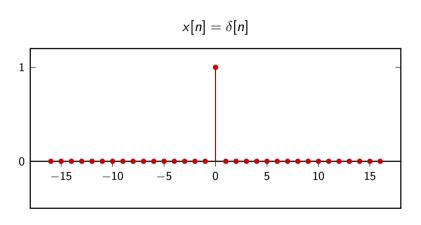
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The delta signal

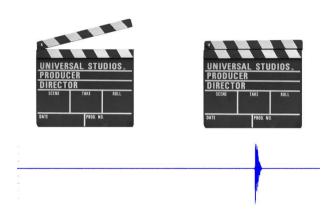


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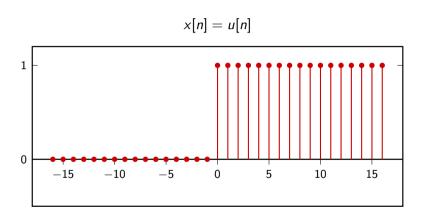
How do you synchronize audio and video...



How do you synchronize audio and video...



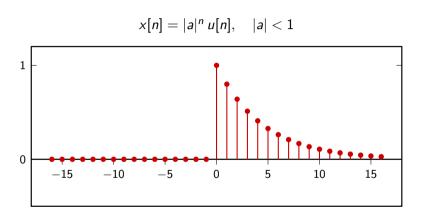
The unit step



The Frankenstein switch...



The exponential decay



How fast does your coffee get cold...



How fast does your coffee get cold...

Newton's law of cooling:

$$\frac{dT}{dt} = -c(T - T_{\mathsf{env}})$$

$$T(t) = T_{\mathsf{env}} + (T_0 - T_{\mathsf{env}})e^{-ct}$$

In practice:

- must have convection only
- must have large conductivity

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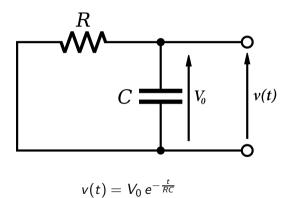
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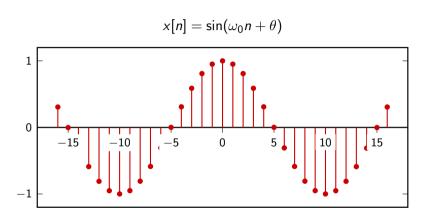
In practice:

- must have convection only
- must have large conductivity

Also, how fast your capacitor discharges

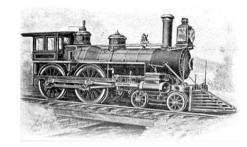


The sinusoid



Oscillations are everywhere!









- ▶ finite-length
- ▶ infinite-length
- periodic
- ► finite-support

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Finite-length signals

- ▶ sequence notation: x[n], n = 0, 1, ..., N 1
- ightharpoonup vector notation: $\mathbf{x} = [x_0 x_1 \dots x_{N-1}]^T$
- practical entities, good for numerical packages (e.g.numpy)

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Periodic signals

- ▶ *N*-periodic sequence: $\tilde{x}[n] = \tilde{x}[n + kN], \quad n, k, N \in \mathbb{Z}$
- ▶ same information as finite-length of length *N*
- "natural" bridge between finite and infinite lengths

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► Finite-support sequence:

$$ar{x}[n] = \left\{ egin{array}{ll} x[n] & ext{if } 0 \leq n < N \ 0 & ext{otherwise} \end{array}
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scaling:

$$y[n] = \alpha x[n]$$

▶ sum:

$$y[n] = x[n] + z[n]$$

product:

$$y[n] = x[n] \cdot z[n]$$

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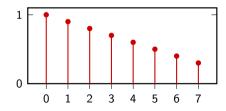
product:

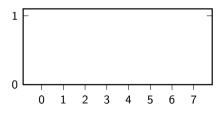
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▶ shift by *k* (delay):

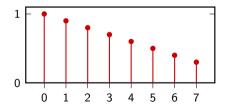
$$y[n] = x[n-k]$$

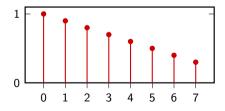
$$[x_0 \quad x_1 \quad x_2 \quad x_3 \quad x_4 \quad x_5 \quad x_6 \quad x_7]$$

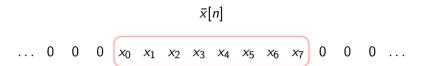


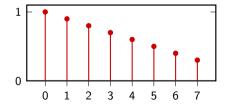


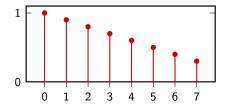
$$x[n]$$
... $x_0 \quad x_1 \quad x_2 \quad x_3 \quad x_4 \quad x_5 \quad x_6 \quad x_7$...

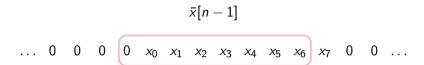


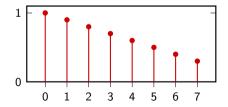


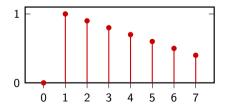


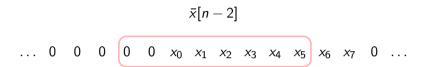


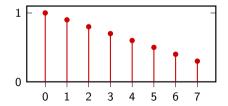


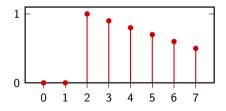


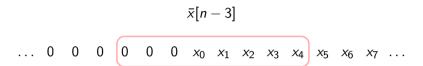


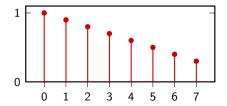


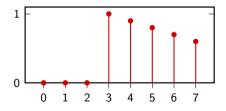


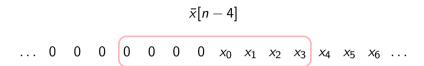


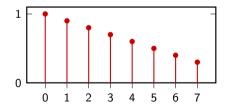


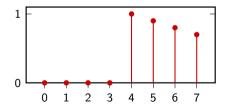




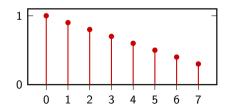


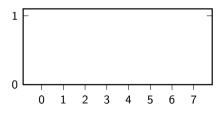


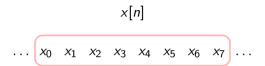


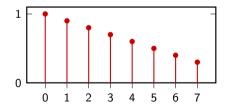


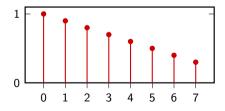
$$\begin{bmatrix} x_0 & x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 \end{bmatrix}$$

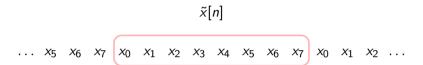


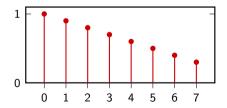


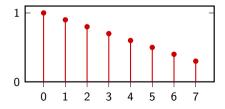




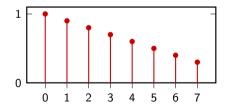


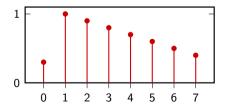




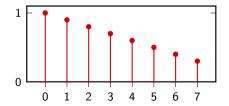


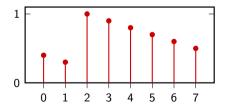
$$\tilde{x}[n-1]$$
 ... x_4 x_5 x_6 x_7 x_0 x_1 x_2 x_3 x_4 x_5 x_6 x_7 x_0 x_1 ...



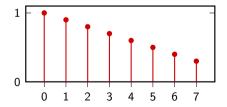


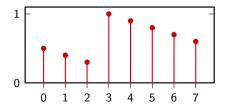
$$\tilde{x}[n-2]$$
 ... x_3 x_4 x_5 x_6 x_7 x_0 x_1 x_2 x_3 x_4 x_5 x_6 x_7 x_0 ...



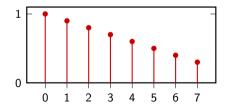


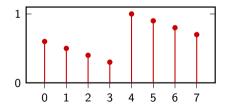
$$\tilde{x}[n-3]$$
 ... x_2 x_3 x_4 x_5 x_6 x_7 x_0 x_1 x_2 x_3 x_4 x_5 x_6 x_7 ...





$$\tilde{x}[n-4]$$
 ... x_1 x_2 x_3 x_4 x_5 x_6 x_7 x_0 x_1 x_2 x_3 x_4 x_5 x_6 ...





Energy and power

$$E_{x} = \sum_{n=-\infty}^{\infty} |x[n]|^{2}$$

$$P_{x} = \lim_{N \to \infty} \frac{1}{2N+1} \sum_{n=-N}^{N} |x[n]|^{2}$$

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Energy and power: periodic signals

$$E_{\tilde{x}}=\infty$$

$$P_{\tilde{x}} \equiv \frac{1}{N} \sum_{n=0}^{N-1} |\tilde{x}[n]|^2$$

Energy and power: periodic signals

$$\textit{E}_{\tilde{x}} = \infty$$

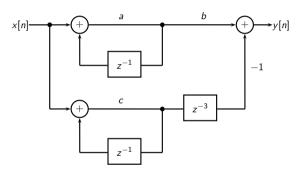
$$P_{\tilde{x}} \equiv \frac{1}{N} \sum_{n=0}^{N-1} |\tilde{x}[n]|^2$$

Overview:

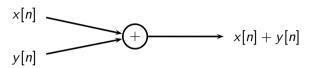
- ▶ DSP as Lego: The fundamental building blocks
- Averages and moving averages
- ▶ Recursion: Revisiting your bank account
- ▶ Building a simple recursive synthesizer
- Examples of sounds

DSP as Lego

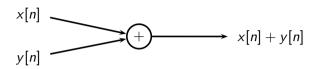


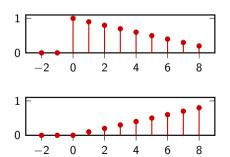


Building Blocks: Adder

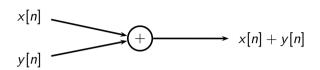


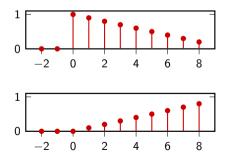
Building Blocks: Adder

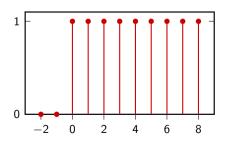




Building Blocks: Adder





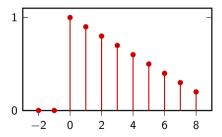


Building Blocks: Multiplier

$$x[n] \xrightarrow{\alpha} \alpha x[n]$$

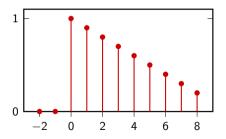
Building Blocks: Multiplier

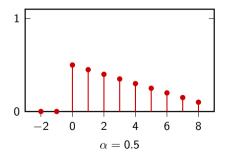
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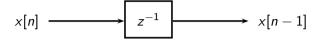
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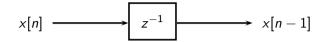


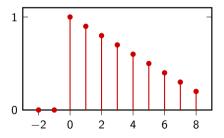


Building Blocks: Unit Delay

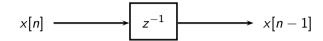


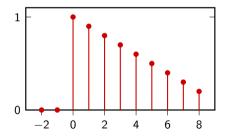
Building Blocks: Unit Delay

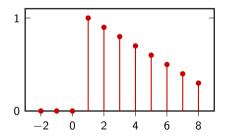




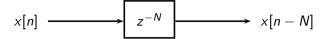
Building Blocks: Unit Delay



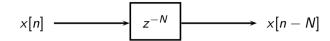


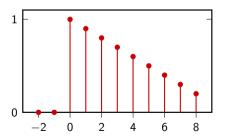


Building Blocks: Arbitrary Delay

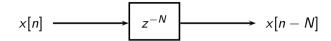


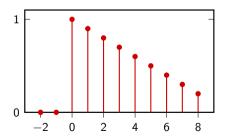
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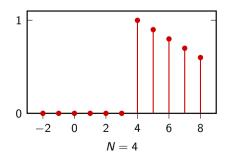




Building Blocks: Arbitrary Delay







The 2-point Moving Average

simple average:

$$m=\frac{a+b}{2}$$

▶ moving average: take a "local" average

$$y[n] = \frac{x[n] + x[n-1]}{2}$$

The 2-point Moving Average

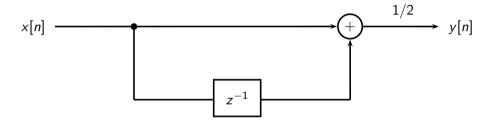
simple average:

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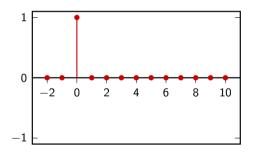
▶ moving average: take a "local" average

$$y[n] = \frac{x[n] + x[n-1]}{2}$$

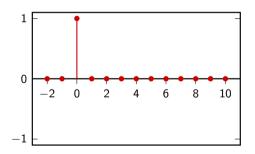
The 2-point Moving Average Using Lego

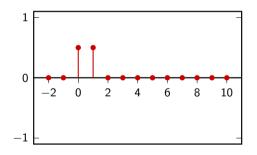


$$x[n] = \delta[n]$$

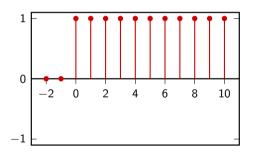


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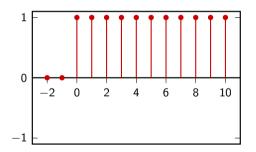


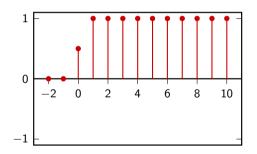
$$x[n] = u[n]$$



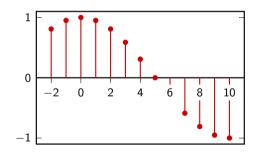
39

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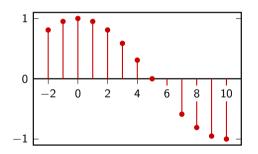


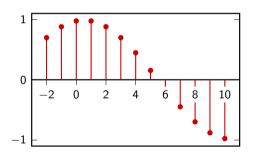
$$x[n] = \cos(\omega n), \quad \omega = \pi/10$$



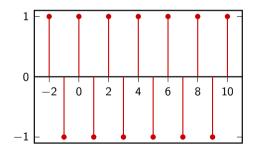
40

$$x[n] = \cos(\omega n), \quad \omega = \pi/10$$

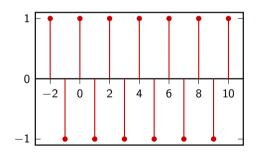


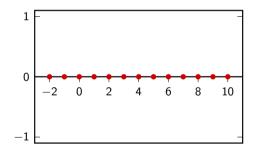


$$x[n] = (-1)^n$$

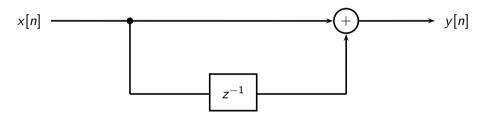


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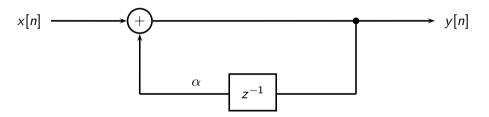




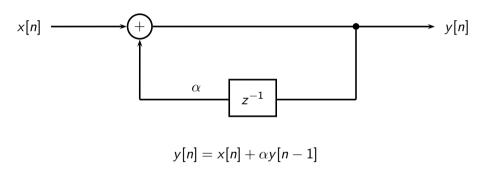
What if we reverse the loop?



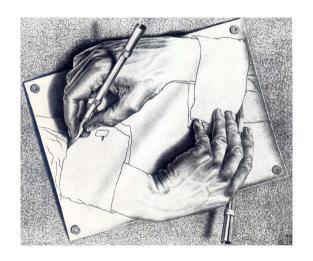
What if we reverse the loop?



What if we reverse the loop?



A powerful concept: recursion



How we solve the chicken-and-egg problem

Zero Initial Conditions

- set a start time (usually $n_0 = 0$)
- ightharpoonup assume input and output are zero for all time before n_0

- ► constant interest/borrowing rate of 5% per year
- ▶ interest accrues on Dec 31
- ightharpoonup deposits/withdrawals during year n: x[n]
- ▶ balance at year *n*

$$y[n] = 1.05 y[n-1] + x[n]$$

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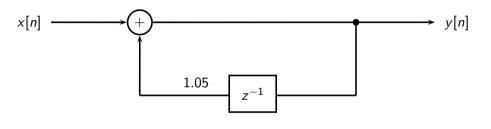
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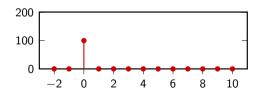
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Accumulation of interest: first-order recursion



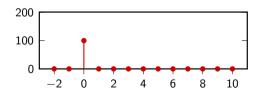
$$x[n] = 100 \delta[n]$$

- y[0] = 100
- y[1] = 105
- y[2] = 110.25, y[3] = 115.7625 etc.
- ► In general: $y[n] = (1.05)^n 100 u[n]$



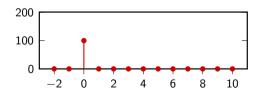
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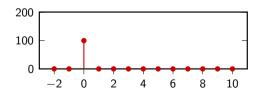
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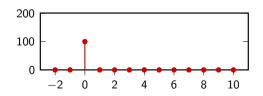
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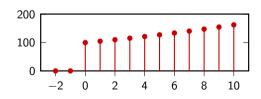
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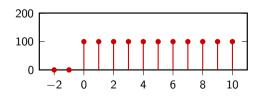




Example: the saver

$$x[n] = 100 u[n]$$

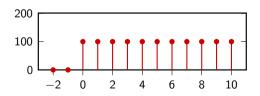
- y[0] = 100
- y[1] = 205
- y[2] = 315.25, y[3] = 431.0125 etc.
- ▶ In general: $y[n] = 2000((1.05)^{n+1} 1)u[n]$



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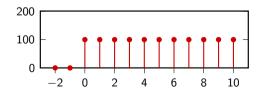
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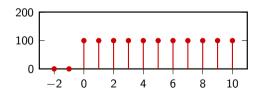
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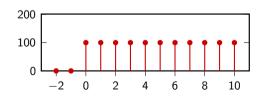
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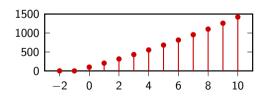


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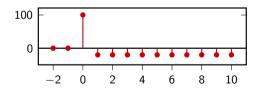
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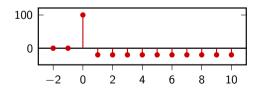
$$x[n] = 100 \delta[n] - 5 u[n-1]$$

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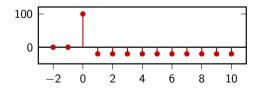
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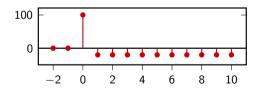
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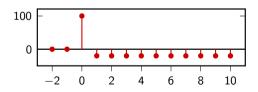
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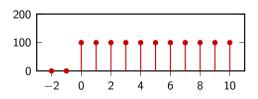
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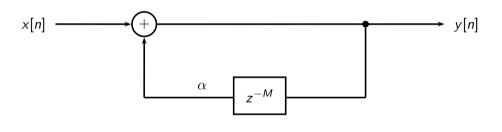
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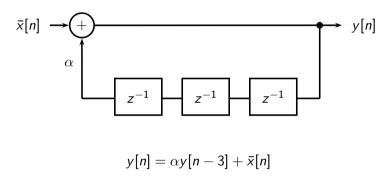


An interesting generalization



$$y[n] = \alpha y[n - M] + x[n]$$

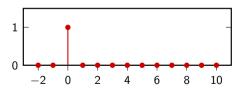
Creating loops



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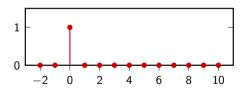
$$M = 3$$
, $\alpha = 0.7$, $x[n] = \delta[n]$

- y[0] = 1, y[1] = 0, y[2] = 0
- y[3] = 0.7, y[4] = 0, y[5] = 0
- $y[6] = 0.7^2$, y[7] = 0, y[8] = 0, etc.



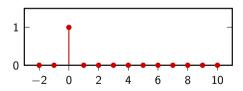
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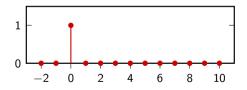
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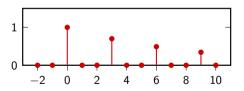
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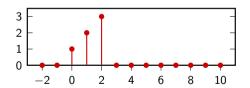
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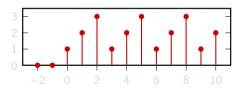




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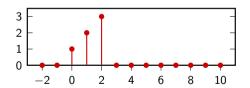
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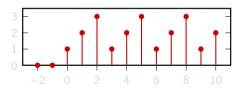




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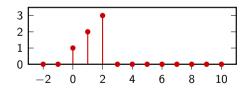
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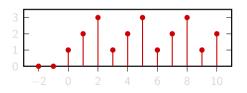




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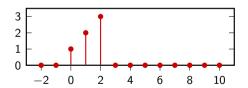
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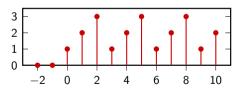




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- ▶ build a recursion loop with a delay of *M*
- ▶ choose a signal $\bar{x}[n]$ that is nonzero only for $0 \le n < M$
- choose a decay factor
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- ► *M*-tap delay → *M*-sample "periodicity"
- ▶ associate time *T* to sample interval
- periodic signal of frequency

$$f = \frac{1}{MT} Hz$$

$$f \approx 440 \text{Hz}$$

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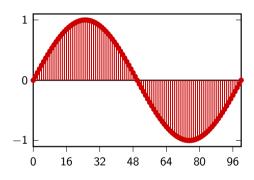
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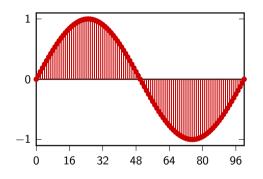
Playing a sine wave

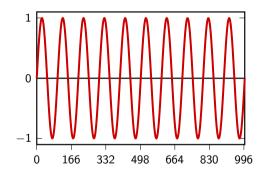
 $M=100,~\alpha=1,~\bar{x}[n]=\sin(2\pi~n/100)$ for $0\leq n<100$ and zero elsewhere



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 for $0\leq n<100$ and zero elsewhere







Introducing some realism

- ► *M* controls frequency (pitch)
- $ightharpoonup \alpha$ controls envelope (decay)
- $ightharpoonup \bar{x}[n]$ controls color (timbre)

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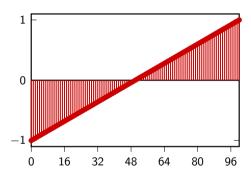
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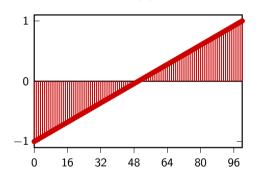
A proto-violin

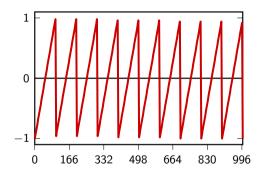
 $M=100,~\alpha=0.95,~ar{x}[n]$: zero-mean sawtooth wave between 0 and 99, zero elsewhere



A proto-violin

 $M=100,~\alpha=0.95,~ar{x}[n]$: zero-mean sawtooth wave between 0 and 99, zero elsewhere

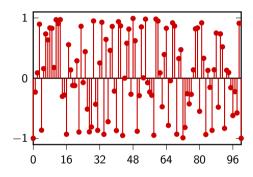






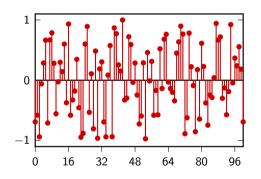
The Karplus-Strong Algorithm

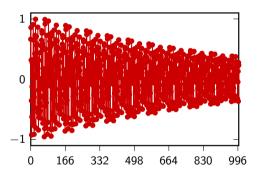
 $M=100,~\alpha=0.9,~\bar{x}[n]$: 100 random values between 0 and 99, zero elsewhere



The Karplus-Strong Algorithm

 $M=100, \ \alpha=0.9, \ \bar{x}[n]$: 100 random values between 0 and 99, zero elsewhere







Recap

- We have seen basic elements:
 - adders
 - multipliers
 - delays
- ▶ We have seen two systems
 - moving averages
 - recursive systems
- ▶ We were able to build simple systems with interesting properties
- ▶ to understand all of this in more details we need a mathematical framework!