### Real-world Games

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### Games in the real world

- Agents do not know each others' payoff matrices.
- Agents can cooperate to do better than a Nash equilibrium.
- Agents learn to select the best strategies, or...
- Agents negotiate to select their strategies.

### Auction game

- auction for one single item. Agent A bids one of {1.5, 2.5, 3.5}, agent B bids one of {1, 2, 3}.
- the agent with the higher bid gets the item and pays its bid.
- let the value of the item be value(A)=3.5, value(B)=2.5.

#### $\Rightarrow$ game:

			В	
		1	2	3
	1.5	(2,0)(A)	(0,0.5)(B)	(0,-0.5)(B)
Α	2.5	(1,0)(A)	(1,0)(A)	(0,-0.5)(B)
	3.5	(0,0)(A)	(0,0)(A)	(0,0)(A)

NE: A plays 2.5, B plays 2

...but A and B do not know each other's values!

### Games with uncertain utilities

Many games have uncertain utilities, for example trading or auctions:

- utility for each agent depends on its value for the item.
- this is *private* information.
- agents type: all information that only the agent knows.
- probability distribution of other agents' types is common knowledge.

How can agents play an equilibrium when utilities are not known?



### Uncertain utilities

3 different ways of computing strategies with uncertain utility:

- Ex ante: assumes no knowledge of any agent's type.
   (what is known before the game even starts)
- Ex interim: assumes knowledge of own type.
   (what is known during the game)
- Ex post: assumes knowledge of all agents' types.
   (what will be known in hindsight after the game)

### Bayes-Nash equilibrium

Bayes-Nash equilibrium: Nash equilibrium in game with ex ante expected utilities.

Example: assume p(1) = 0, p(2) = p(3) = 1/2 for both A & B.  $E[value(A)] = E[value(B)] = p(1) \cdot 1 + p(2) \cdot 2 + p(3) \cdot 3 = 2.5$ .  $\Rightarrow$  expected game:

			В	
		1	2	3
	1.5	(1,0)(A)	(0,0.5)(B)	(0,-0.5)(B)
Α	2.5	(0,0)(A)	(0,0)(A)	(0,-0.5)(B)
	3.5	(-1,0)(A)	(-1,0)(A)	(-1,0)(A)

(weakly) dominated actions: A=3.5, A=2.5, B=3 Bayes-Nash Equilibrium: A plays 1.5, B plays 2.

# Ex-post Nash equilibrium?

- Ex-post Nash equilibrium: strategies that gives the highest utilities no matter what the uncertain information will turn out to be.
- Does not necessarily exist: strategies may be different depending on other agents' types.
- Auction game: equilibrium is for A to bid min(value(A), bid(B) + 1)
- But bid(B) changes with value(B), so A's best strategy can not be the same for all value(B).

## Ex-post Nash equilibrium

- Consider auction rule: winner pays second highest price.
- Claim: bidding true value is an ex-post Nash equilibrium.
- Assume bid(B) = value(B). Then only two payoffs for A:
  - bid(A) > value(B) have the same payoff value(A) value(B),
  - $bid(A) \leq value(B)$  have payoff zero.

#### Now consider the cases:

- value(A) > value(B): payoff of bid(A) = value(A) is > 0: best response.
- value(A) ≤ value(B): payoff of bid(a) > value(B) is < 0;</li>
   bid(A) = value(A) is a best response.
- Same reasoning for B.



## General-sum games

- In general-sum games, agents should cooperate to obtain a higher payoff.
- Cooperation may not be a Nash equilibrium ⇒ players need to cooperate to achieve the best result.
- Joint plan and payoffs can be fixed by a contract that punishes deviation.
- Agents have to negotiate to agree on a joint strategy.

### Prisoner's dilemma

- 2 suspects are arrested after a bank robbery and questioned (individually) by the police.
- Actions: choose between
  - cooperation (with the other suspect): deny all involvement in the crime.
  - defection: blame the other suspect for the crime.
- Knowledge:
   A et B don't know the other's choice!
- Payoffs: if A and B both cooperate, they are held by police for 1 year, and then can go off to enjoy their loot (utility 9). If both defect, they get 5 years in prison before (utility 5). If only one cooperates, he gets 10 years in prison (utility 0) while the other goes free (utility 10).

### **Business version**

- 2 partners each put in 5 CHF in a joint effort
- Actions: choose between
  - cooperation: carry out the business together and each gain 9 CHF if successful.
  - defection: take the money and disappear.
- If both defect, they just get their money back.
- This is a very common business scenario.

## Strategies

		В		
		C	D	
	С	(9,9)	(0,10)	
Α	D	(9,9) (10,0)	(5,5)	

#### Choice:

- cooperate: possible payoff = 0 or 9.
- defect: possible payoff = 5 or 10.
- ⇒ dominant strategies: both defect

# Local and global optimality

- Dominant strategies: both players defect and get 5
- However, if both would agree to cooperate, the gain could be
   9 for both of them.
- Not an equilibrium: either player can increase its gain from 9 to 10 by changing strategy.
- $\Rightarrow$  requires a *contract* between players so that defection carries a punishment > 1.

## Mediated Equilibrium

#### Assume we have a *mediator*.

- agents can ask the mediator to play or play themselves.
- the mediator plays a known strategy as a function of the agents who asked it to play.
- mediator can be a vehicle to enforce a contract.

## Example: Prisoner's dilemma

		В		
		C	D	
	С	(9,9)	(0,10)	
Α	D	(9,9) (10,0)	(5,5)	

Dominant strategy equilibrium at (D,D) Suppose a mediator plays:

- (C,C) if both players ask the mediator to play.
- D if only one of the players asks the mediator to play.

### Prisoners' Dilemma with Mediator

			В	
		М	C	D
	М	(9,9)	(10,0)	(5,5)
Α	C	(0,10)	(9,9)	(0,10)
	D	(5,5)	(10,0)	(5,5)

New dominant strategy equilibrium: (M,M) Computers offer many possibilities to introduce mediators!

### Correlated Equilibrium

Consider the "battle of the sexes":

		В		
		0	S	
	0	(2,1) (0,0)	(0,0)	
Α	S	(0,0)	(1,2)	

- 2 pure strategy Nash equilibria: (O,O) and (S,S): unfair!
- 1 mixed strategy Nash equilibrium: ([2/3, 1/3], [1/3, 2/3]): fair, but expected payoff is only 4/3.

Can we do better?

## Correlated Equilibrium

Assume that there is a "trusted" coordinator that proposes to each agent i a choice of strategy  $s_i$ .

(the player does not have to follow the suggestion) Original definition:

A correlated equilibrium is a set of strategies  $\{s_i\}$  such that for each agent i, choosing  $s_i$  as suggested by the coordinator is a best response to the strategies of the other agents  $(S_{-i})$ .

#### Example:

- fair coin flip  $\Rightarrow$  (O, O) or (S, S)
- Equilibrium for player to stay with suggested strategy.
- $\Rightarrow$  correlated equilibrium with expected payoffs (1.5, 1.5).



# More complex situation

		В		
		0	S	
	0	(2,1)	(0,0)	
Α	S	(2,1) $(0,0)$	(1,2)	

- Let signal be (O,O), (S,S), (S,O) each with probability 1/3.
- When A is assigned O, B will play O for sure. ⇒ best
- If A is assigned S, B plays O or S with equal probability.
- $\Rightarrow$  better to play O and get  $1/2 \cdot 2$  rather than  $1/2 \cdot 1!$
- ⇒ not a correlated equilibrium!
- However, (O,O), (S,S), (O,S) with 1/3 each *is* a CE.



# Choosing the mapping signal $\rightarrow$ strategy

Suppose both players observe a binary random variable  $r \in \{0,1\}$  (for example, a coin flip) and choose mapping to strategies:

		В			
	always O	$0  o  extit{O,1}  o  extit{S}$	0 o S, $1 o O$	always S	
always O	(2,1)	(1,0.5)	(1,0.5)	(0,0)	
$egin{array}{l} 0  ightarrow O \ 1  ightarrow S \end{array}$	(1,0.5)	(1.5,1.5)	(0,0)	(0.5,1)	
$\begin{array}{cc} A & \overset{0}{\longrightarrow} S \\ 1 \to O \end{array}$	(1,0.5)	(0,0)	(1.5,1.5)	(0.5,1)	
always S	(0,0)	(0.5,1)	(0.5,1)	(1,2)	
Note that Calculate and Albahama Market and Miller and Market and					

 $\Rightarrow$  two fair pure-strategy Nash equilibria with payoff (1.5, 1.5)!



### Latent Coordinator

- Suppose correlation signal is *latent*, i.e. players know its distribution but cannot observe it.
- ⇒ Bayesian game: signal value is unknown.
  - Agents choose action that is best response to opponents' observed play.
- ⇒ equilibrium can be found through learning: always play best response to strategies observed from others.
  - Much easier and realistic to reach than Nash equilibria!

### No-Regret

- Let s denote a joint strategy vector, i.e.  $s \in S = \times_i S_i$
- A sequence of plays {s<sup>0</sup>, s<sup>1</sup>,..., s<sup>T</sup>} is said to be *no-regret* for *i* iff:

$$\sum_{t=0}^{T} u_i(s^t) \geq \max_{x \in S_i} \sum_{t=0}^{T} u_i(x, s_{-i}^t)$$

At least as good as any fixed strategy in hindsight!

## Coarse Correlated Equilibrium

• A coarse correlated equilibrium is a probability distribution p over the strategy vectors such that  $\forall i$ 

$$\sum_{s} p(s)u_i(s) \geq \max_{x \in S_i} \sum_{s} p(s)u_i(x, s_{-i})$$

 $\Rightarrow$  for all agents i, induces a sequence of plays that are no-regret.

# Coarse Correlated Equilibria (Examples)

Correlation device samples with equal probability from distributions:

- (O,O), (S,S): both play O, S with probability 1/2 each.
   Expected payoff: (1.5, 1.5)
   Better than best fixed strategy for A (O, average payoff = 1).
   Better than best fixed strategy for B (S, average payoff = 1).
- (O,O), (S,S), (O,S), (S,O): both play O,S with probability 1/2.
   Expected payoff: (0.75, 0.75)
   A is better off by always playing O, B by always playing S.
   ⇒ not a CCE!
- (O,O), (S,S), (O,S): A plays O with prob. 2/3, B with prob. 1/3. Expected payoff: (2/3,2/3) = the mixed Nash equilibrium.

### CCE ⊃ CE

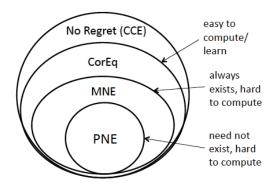
			В	
		1	2	3
	1	(1,1)	(-1,-1)	(0,0)
Α	2	(1,1) $(-1,-1)$ $(0,0)$	(1,1)	(0,0)
	3	(0,0)	(0,0)	(-1.1,-1.1)

Consider playing (1,1), (2,2), (3,3) each with probability 1/3.

$$E[payoff] = 1/3 \cdot 1 + 1/3 \cdot 1 + 1/3 \cdot (-1.1) = 0.3$$

Best fixed actions (1 or 2):  $E[payoff] = 0 \Rightarrow$  Coarse CE. But not CE: when device suggests to play 3, agent is better off playing 1 or 2.

### Hierarchy



### The Price of Anarchy

- Explicit coordination: agents can coordinate on any strategy profile  $\underline{s} \in \mathbf{S}$  with the highest joint reward  $R(\underline{s})$ .
- No coordination (anarchy): limited to equilibria  $\underline{s}^i \in E$ .
- Worst-case efficiency loss characterized by Price of Anarchy:

$$PoA = \frac{max_{\underline{s} \in S}R(\underline{s})}{min_{\underline{s} \in E}R(\underline{s})}$$

• Alternative for best-case: Price of Stability:

$$PoA = \frac{max_{\underline{s} \in S} R(\underline{s})}{max_{\underline{s} \in E} R(\underline{s})}$$

• Works for any kind of equilibria.

## **Bounding PoA**

- can we bound PoA for a certain type of game?
- define: game with optimal strategy profile  $\underline{s}^*$  is  $(\lambda, \mu)$ -smooth iff for every strategy profile  $\underline{s}$ :

$$\sum_{i\in\mathcal{A}} r_i(s_i^*,\underline{s}_{-i}) \geq \lambda R(\underline{s}^*) - \mu R(\underline{s})$$

- $\Rightarrow$  PoA of a  $(\lambda, \mu)$ -smooth game is at most  $\lambda/(1 + \mu)$ .
  - many examples of smooth games: routing, facility location, simultaneous auctions, etc.

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# Improving beyond PoA

To implement a coordinated solution, we need:

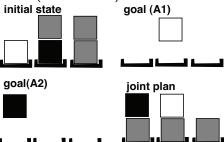
- get agents to agree with prescribed strategy even when it is not a Nash equilibrium.
- find a solution that is fair to all agents.
- ⇒ negotiation to find an agreement.



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### Example: warehouse robots

Slotted blocks world (Rosenschein):



Each agent gets utility 5 when its goal is achieved.

# Negotiation setting

One joint plan:

Agent A1 lifts white block, A2 moves three blocks around.

Cost: 2 operations (agent A1) vs. 6 operations (agent A2)

			В	
		N	A1	A2
	N	(0,0)	(0,-2)	(0,-6)
Α	A1	(-2,0)	(-2,-2)	(3,-1)
	A2	(0,0) (-2,0) (-6,0)	(-1,3)	(-6,-6)

Equilibrium (conflict deal): (N,N) Negotiation should reach (A1,A2) or (A2,A1) and side payment to compensate.

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## Example 2: Sharing wireless spectrum

- 2 agents A and B share a sequence of timeslots on a wireless channel to transmit sensor data.
- if they both transmit at the same time, most of transmission is lost (simultaneous defection).
- $\Rightarrow$  use a time-division scheme so that A gets  $\alpha$  and B  $1-\alpha$  of the slots.
  - Strategies:
    - cooperate: agents transmit only in the assigned slots.
    - defect: agents transmit all the time.
  - Defection is the dominant strategy (as in Prisoner's dilemma).
  - Mediation requires agreement on  $\alpha$ : negotiation.



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# Types of Negotiation

- Strategic negotiation: agents make and accept/reject offers in an unconstrained and self-interested manner.
- Axiomatic negotiation: agents agree on a set of axioms that the outcome should satisfy, then negotiate according to a protocol that guarantees the axioms.

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# Strategic negotiation

- Negotation = sequence of rounds.
- Round: agent 1 makes an offer, agent 2 accepts or rejects.
- Next round: agent 2 makes offer, agent 1 accepts or rejects.
- Ends when an offer is accepted.

# Alternating offers

- Consider scenario with 2 agents A and B.
- Protocol proceeds in n rounds:
  - **1** agent 1 makes a proposal  $P_1$  for joint strategy  $S(P_1)$  and payoffs  $U_1(P_1)$ ,  $U_2(P_1)$ .
  - 2 agent 2 accepts or rejects the proposal.

where A and B take turns as agents 1 and 2.

- If negotiation fails, agents get conflict payoffs  $U_1(C)$ ,  $U_2(C)$  = payoffs without coalition.
- Example: cutting a cake
  - Agent 1 proposes  $\alpha \in [0..1]$ ,  $U_1(\alpha) = \alpha$ ,  $U_2(\alpha) = 1 \alpha$
  - If no agreement, the cake is lost and both agents get 0.



# Alternating offers with 1 round

- Assume selfish agents.
- Agent 2 accepts the offer  $P_1$  iff  $U_2(P_1) \geq U_2(C)$ .
- Agent 1 should make an offer so that  $U_1(P_1)$  is maximized and  $U_1(P_1) \geq U_1(C), U_2(P_1) \geq U_2(C)$
- Best cake-cutting strategy for agent 1: propose 1-  $\epsilon$ .

# Alternating offers with several rounds

- Let agent 1 be the one making the last offer.
- ullet  $\Rightarrow$  in the last round, agent 1 can force any  $\epsilon$  it wants!
- ullet  $\Rightarrow$  agent 1 will not accept any offer of agent 2.
- All rounds before the last one are irrelevant!



# Negotiation with time constraints

Suppose that the value of the cake decreases by factor  $\delta_A$  for agent A and  $\delta_B$  for agent B at each round.

- single round: agent 2 should accept anything.
- 2 rounds: agent 1 proposes  $\alpha \leq 1 \delta_2$ , agent 2 accepts, because even if it got the whole cake in the next round, it would not get more utility than  $\delta_2$  which is already gets.
- many rounds: analyze as equilibrium.



### Infinite duration with discount factors

- Agent A always offers x, agent B always offers y.
- Agent B should accept a offer that gives it at least  $\delta_B y$ :

$$(1-x) \geq \delta_B y$$

Symmetrically for agent A:

$$(1-y) \geq \delta_A x$$

 Equilibrium: maximize shares ⇒ inequalities hold with equality:

$$x = \frac{1 - \delta_B}{1 - \delta_A \delta_B}$$
 and  $y = \frac{1 - \delta_A}{1 - \delta_A \delta_B}$ 

- if  $\delta_A = \delta_B = \delta$ :  $x = y = \frac{1}{1+\delta}$
- Agreement in the first step: maximizes joint return.



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# Problem with alternating offers

- In all cases, the agent who makes the first offer (agent A) gets a bigger share of the pie!
- Who decides who gets to make the first offer? Choice of protocol is not in equilibrium.
- More realistic:
  - both offers are made in parallel.
  - if they are not compatible, negotiation fails.
- What are the best strategies in such a game?



# Framework for negotiation

- Agents have a set of goals  $G = \{g_1, ..., g_n\}$
- Agent i assigns each goal g a certain worth  $w_i(g)$
- Agent i assigns each goal g a standalone cost  $c_i^*(g)$
- Deals  $D_j$  are joint plans that achieve goals  $G(D_j)$  at a certain cost  $c_i(D_j)$  to agent i
- In the conflict deal  $D_c$  the agents do not cooperate and it has cost  $c_i(D_c) = \sum_{g \in G(D_c)} c_i^*(g)$

### Rational Action

Agents maximize their expected utility:

$$u_i(D_j) = \left[\sum_{g \in G(D_j)} w_i(g)\right] - c_i(D_j)$$

Agents do not have to cooperate: if negotiation does not succeed, they act independently and pursue the conflict deal.

Under what conditions is there a unique negotiation outcome?

# Criteria for a negotiation outcome

Chosen deal  $\overline{D}$  should satisfy the criteria:

- feasible through a joint plan of action.
- pareto-optimal (non-dominated): there does not exist another deal  $D_k$  such that for all agents,  $u_i(D_k) \geq u_i(\overline{D})$  and for at least one agent,  $u_i(D_k) > u_i(\overline{D})$
- individually rational: for all agents,  $u_i(\overline{D}) \geq u_i(D_c)$

# Criteria for the solution (Nash)

3 more technical conditions for a unique solution:

- Feasiblity.
- Pareto-Optimality.
- Rationality.
- Independence of sub-optimal alternatives: If  $\overline{D} \in T \subset S$ , and  $\overline{D}$  is optimal within the results in S, then  $\overline{D}$  is optimal in T.
- Independence of linear transformations: If gains and losses are linearly transformed  $(u' = \alpha u + \beta)$ , the new solution is the transformation of the old one.
- Symmetry: If the game is symmetric for both players, then all agents get the same expected payoff.

# Nash Bargaining Solution

- If there is a strategy  $\overline{D}$  that dominates  $D_c$ : there is one single unique solution to the negotiation which satisfies all 6 criteria.
- It is characterized by the condition:

$$(u_1(\overline{D}),...,u_n(\overline{D})) = sup_D \prod_{i=1}^n (u_i(\overline{D}) - u_i(D_c)))$$

where the maximization is carried out over all feasible deals.

■ provided that agents agree on the axioms, this is the outcome of the negotiation!

## Implementing the Nash Bargaining Solution

- A mediator collects all utilities and computes the Nash bargaining solution. But often no mediator (e.g. wireless spectrum)!
- Alternative without mediator:
  - $\bullet$  each agent  $A_i$  proposes a deal  $D_i$ .
  - the plan that maximizes the product of agents' utility gains is chosen.

Each agent has an interest in proposing the best plan for everyone, since otherwise a suboptimal plan for itself might be chosen.

 Problem: every agent needs to know all others' utilities and strategies.



# Reaching the Nash Solution by Alternating Offers

- Centralized mediation is very complex and requires detailed knowledge of all possible agent strategies.
- Q: Can we reach the Nash bargaining solution using agent-to-agent negotiation?
- A: yes, if agents follow certain rules.



## Monotonic concession protocol (Zeuthen)

- Reach agreement through alternating offers.
- Offers from each agent must montonically improve, i.e. agents progress by making concessions.
- Negotiation either ends when an offer is accepted, or fails when no agent has an interest to make further concessions.
- The agent that has the most to loose by negotiation failure has to make the next concession.



### Risk indicators

- Suppose  $A_i$  rejects offer  $D_j$  and proposes  $D_i$  instead.
- This is rational only if:

$$u_i(D_j) - u_i(D_c) \le p_i(u_i(D_i) - u_i(D_c))$$

- p<sub>i</sub> = probability that negotiation will succeed in spite of rejecting D<sub>i</sub>.
- Risk tolerance of A<sub>i</sub>:

risk<sub>i</sub> = 
$$1 - p_i^*$$
  
=  $1 - \frac{u_i(D_j) - u_i(D_c)}{u_i(D_i) - u_i(D_c)} = \frac{u_i(D_i) - u_i(D_j)}{u_i(D_i) - u_i(D_c)}$ 

 $(p_i^* = limit at equality)$ 



## Monotonic concession protocol (Rosenschein)

#### Protocol:

- agents  $A_i, A_j$  both propose deals  $D_i, D_j$ .
- if one agrees to a proposal of the other, negotiation ends in agreement.
- otherwise, both calculate their risk tolerances risk<sub>i</sub> and risk<sub>j</sub>;
   the agent with the smallest risk tolerance makes a concession.
- if none of the agents can rationally make a sacrifice, negotiation fails.



#### Limit case

- When  $u_i(D_i) = u_i(D_c)$ , risk<sub>i</sub> is undefined
- Agent  $A_i$  cannot make any further concessions without violating rationality! When should  $A_j$  make a concession?

$$risk_j = \frac{u_j(D_j) - u_j(D_i)}{u_j(D_j) - u_j(D_c)}$$

- If risk<sub>j</sub> > 1, conflict deal offers better utility to A<sub>j</sub>, so A<sub>j</sub> should not make a concession and negotiation should end with conflict.
- If  $risk_j < 1$ ,  $D_i$  is still more interesting to  $A_j$  so it should make a concession to approach it.
- $\Rightarrow$  set  $risk_i = 1$  to get the correct behavior



### Properties of montonic concessions

Smallest risk makes concession: eliminate deal  $D_i$  with largest  $p_i$ :

$$\frac{u_i(D_j) - u_i(D_c)}{u_i(D_i) - u_i(D_c)} > \frac{u_j(D_i) - u_j(D_c)}{u_j(D_j) - u_j(D_c)}$$

$$(u_i(D_j) - u_i(D_c))(u_j(D_j) - u_j(D_c)) > (u_i(D_i) - u_i(D_c))(u_j(D_i) - u_j(D_c))$$

- ⇒ maximizes product of utility gains
- ⇒ converges towards Nash solution!

# Example: dividing wireless spectrum

- Agents goals: transmit one packet of data.
- Utility for agent A: 3 per unit of data, for agent B: 9 per unit of data.
- Cost of transmission (for each): 1
- Conflict deal: both transmit their data all the time, success rate = 10%  $\Rightarrow$  payoff = (-0.7,-0.1).
- Goal of negotiation: decide  $\alpha \in [0..1]$  so that A uses  $\alpha$  of the slots and B uses  $1 \alpha$ .



# Nash Bargaining Solution

- Utilities:  $U_A(\alpha) = \alpha(3-1), U_B(\alpha) = (1-\alpha)(9-1)$
- Nash solution: maximize  $(2\alpha-(-0.7))(8(1-\alpha)-(-0.1))$  $\Rightarrow \alpha=10.6/32=0.33$
- Note: A gets a smaller share of the spectrum.
- $\Rightarrow$  incentive to lie and declare higher value (A declares  $9 \Rightarrow \alpha = 0.5$ .
  - Makes sense only if claims can be verified.



# Fairness of the Nash Bargaining Solution

• Utility gains over the conflict deal:

$$U_A(0.33) - U_A(D_c) = 0.66 - (-0.7) = 1.36$$
  
 $U_B(0.33) - U_B(D_c) = 5.28 - (-0.1) = 5.38$ 

B gains about 4 times as much as A, since B's utility per slot (9-1=8) is 4 times that of A (3-1=2).

• Due to the scale-invariance property!

### Proposals...

- Initial proposals:  $D_A$ :  $\alpha = 1$ ,  $D_B$ :  $\alpha = 0$ .
- $\Rightarrow$  risks:

• 
$$u_A(D_B) = 0$$
,  $u_A(D_A) = 2 \Rightarrow risk_A = 2/2.7 = 0.74$ 

• 
$$u_B(D_A) = 0$$
,  $u_B(D_B) = 8 \Rightarrow risk_B = 8/8.1 = 0.99$ 

- ⇒ A has smaller tolerance and makes a concession!
- Next proposals:  $D_A$ :  $\alpha = 0.5$ ,  $D_B$ :  $\alpha = 0$
- $\Rightarrow$  risks:

• 
$$u_A(D_B) = 0$$
,  $u_A(D_A) = 2 \Rightarrow risk_A = 1/1.7 = 0.69$ 

• 
$$u_B(D_A) = 4$$
,  $u_B(D_B) = 8 \Rightarrow risk_B = 4/8.1 = 0.49$ 

- ⇒ B has smaller tolerance and makes a concession!
  - Next proposals:  $D_A$ :  $\alpha = 0.5$ ,  $D_B$ :  $\alpha = 0.25$
- $\Rightarrow$  risks:

• 
$$u_A(D_B) = 0.5$$
,  $u_A(D_A) = 1 \Rightarrow risk_A = 0.5/1.7 = 0.29$ 

• 
$$u_B(D_A) = 4$$
,  $u_B(D_B) = 6 \Rightarrow risk_B = 2/6.1 = 0.32$ 



# Generalization to > 2 agents

- Nash bargaining solution generalizes to n agents: maximize product of all agents' utility gains.
- Zeuthen protocol hard to extend,
- Use Nash formula to compute which proposal has lowest product of utility gains and ask that agent to make a concession.

#### **Conclusions**

- Uncertainty: ex-ante/ex-interim: Bayes-Nash equilibria. ex-post: only exists in certain cases.
- Correlated and Coarse correlated equilibria.
- The best coordinated strategies are often not equilibria ⇒ require agreement by agents to act other than self-interested.
- Alternating offers protocol.
- Nash bargaining solution, monotonic concession protocol.
- Incentives for lying.

