Biological Modeling of Neural Networks



Week 3 – Reducing detail:

Two-dimensional neuron models

Wulfram Gerstner

EPFL, Lausanne, Switzerland

Reading for week 3: NEURONAL DYNAMICS - Ch. 4.1- 4.3

Neuronal Dynamics

From Single Neurons to Networks and Models of Cognition

CAMBRIDGE

Neuronal Dynamics

From Single Neurons to Networks and Models of Cognition

3.1 From Hodgkin-Huxley to 2D

- Overview: From 4 to 2 dimensions
- MathDetour 1: Exploiting similarities
- MathDetour 2: Separation of time scales

3.2 Phase Plane Analysis

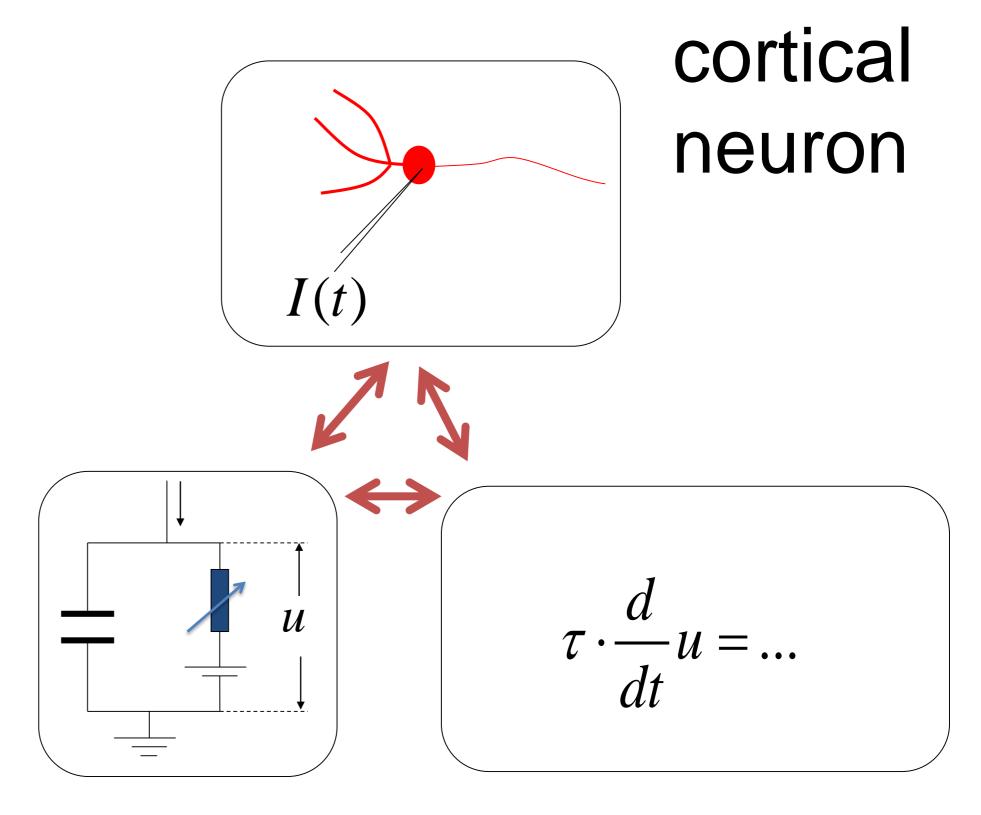
- Role of nullclines

3.3 Analysis of a 2D Neuron Model

- constant input vs pulse input
- MathDetour 3: Stability of fixed points

Cambridge Univ. Press

3.1. Review of week 2: Hodgkin-Huxley Model



- → Hodgkin-Huxley model
- → Compartmental models

3.1 Review of week 2: Hodgkin-Huxley Model

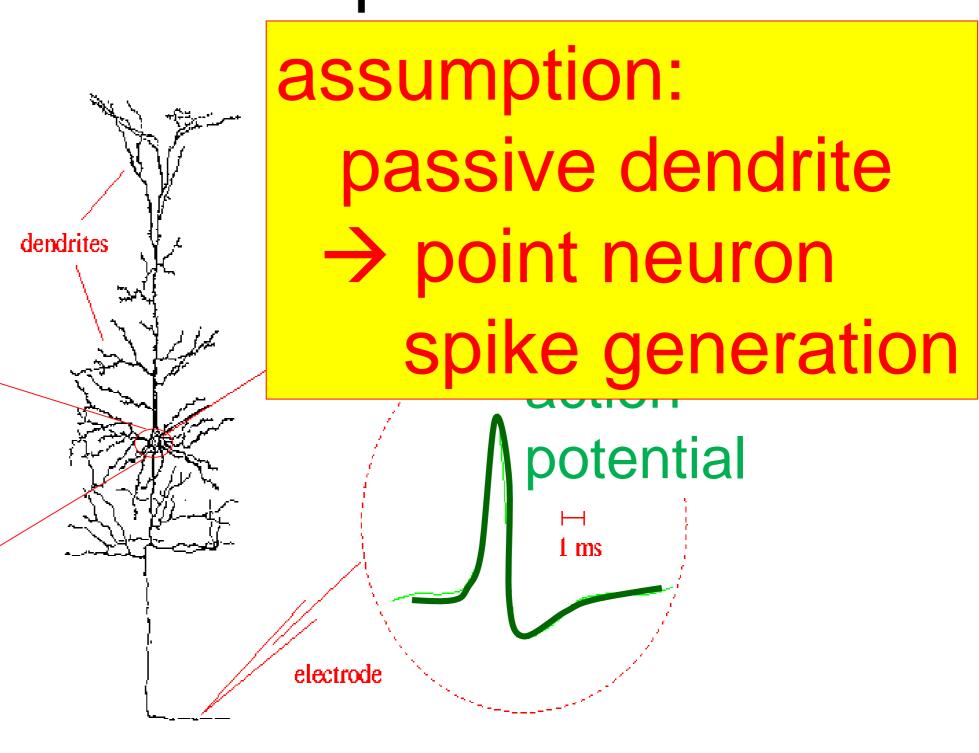
Week 2:

Cell membrane contains

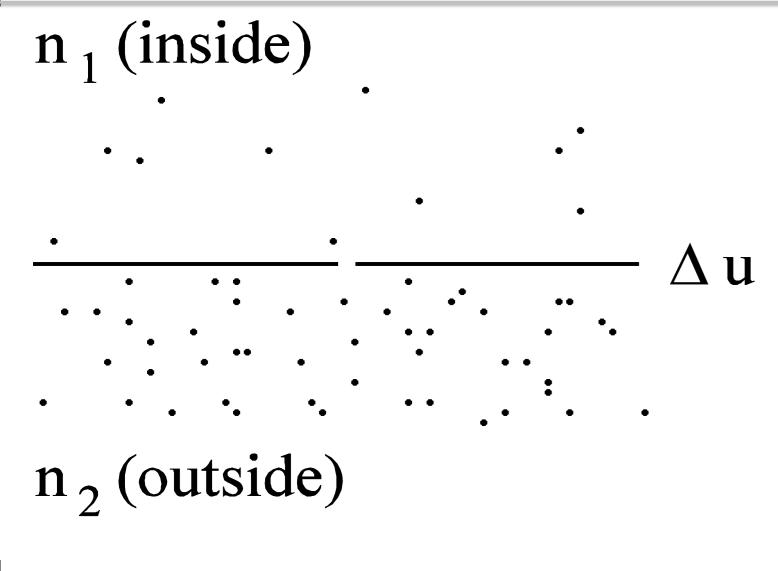
- ion channels

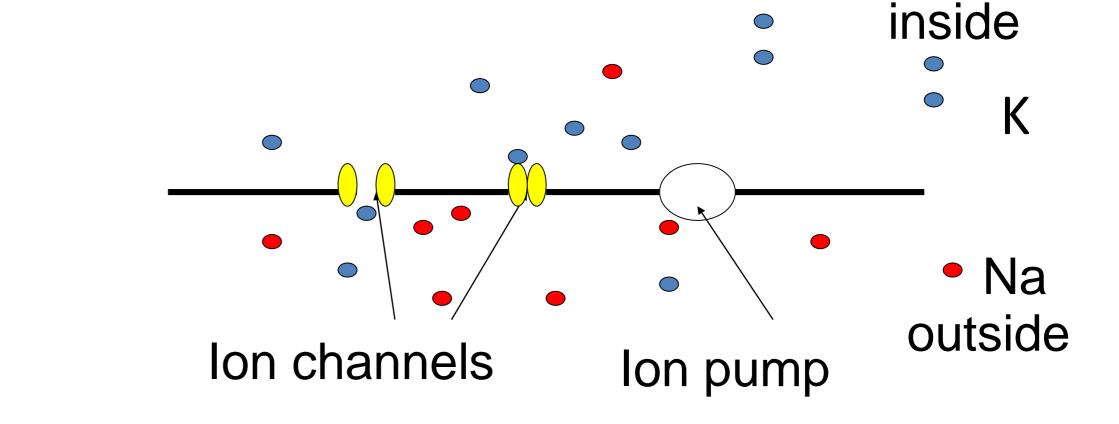
- ion pumpsa

-70mV Na* Ions/proteins Dendrites (week x:video): Active processes?



3.1. Review of week 2: Hodgkin-Huxley Model



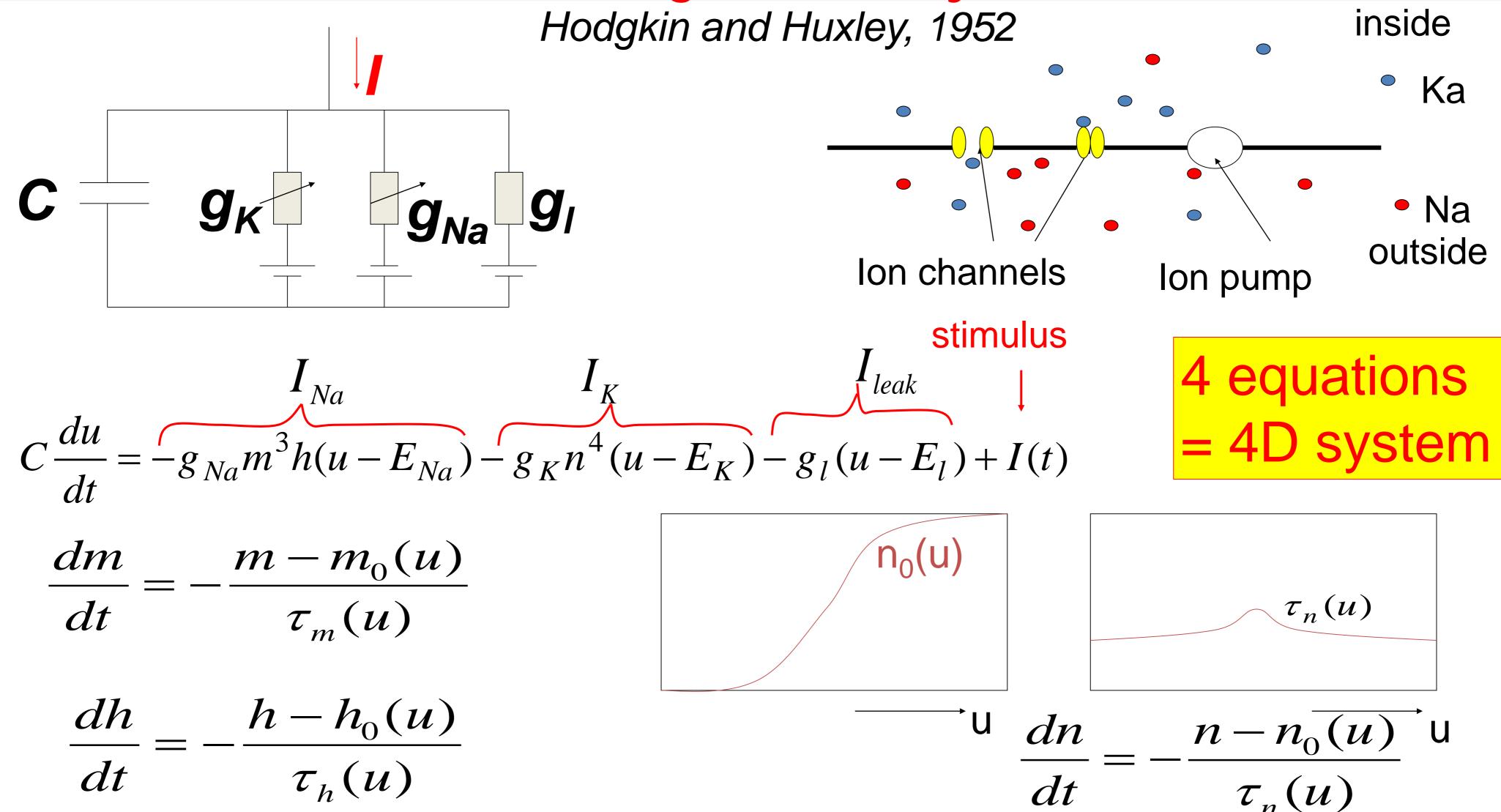


$$\Delta u = u_1 - u_2 = \frac{-kT}{q} \ln \frac{n(u_1)}{n(u_2)}$$

Reversal potential

ion pumps →concentration difference ⇔ voltage difference

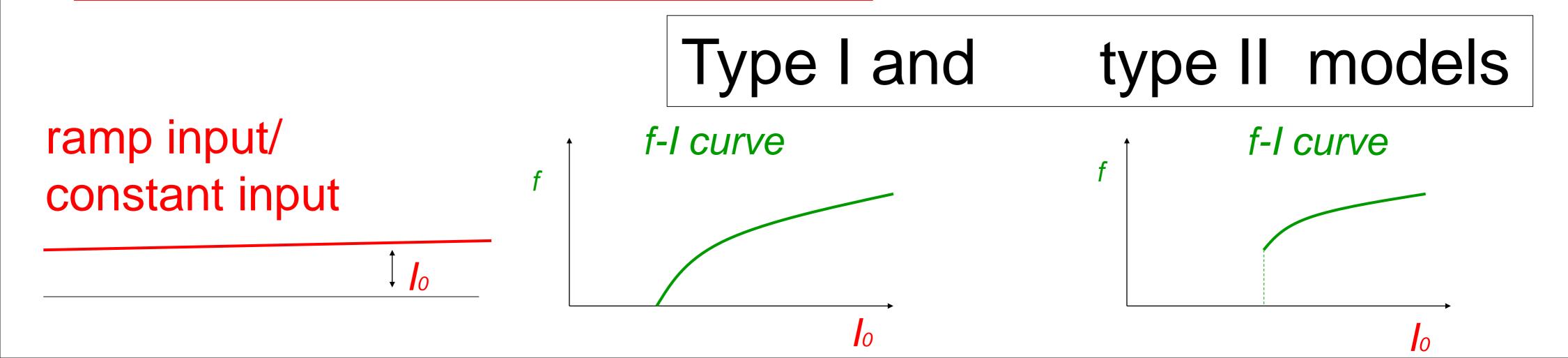
3.1. Review of week 2: Hodgkin-Huxley Model



Week 3 – 3.1. Overview and aims

Can we understand the dynamics of the HH model?

- mathematical principle of Action Potential generation?
- constant input current vs pulse input?
- Types of neuron model (type I and II)? (next week)
- threshold behavior? (next week)
- → Reduce from 4 to 2 equations



Week 3 – 3.1. Overview and aims

Can we understand the dynamics of the HH model?

Reduce from 4 to 2 equations

Week 3 – Quiz 3.1.

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A - A biophysical point neuron model with 3 ion channels, each with activation and inactivation, has a total number of equations equal to [] 3 or [] 4 or [] 6 or [] 7 or [] 8 or more
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Week 3 – 3.1. Overview and aims

Toward a two-dimensional neuron model

-Reduction of Hodgkin-Huxley to 2 dimension

-step 1: separation of time scales

-step 2: exploit similarities/correlations

$$C\frac{du}{dt} = -g_{Na}m^{3}h(u - E_{Na}) - g_{K}n^{4}(u - E_{K}) - g_{I}(u - E_{I}) + I(t)$$

$$\frac{dm}{dt} = -\frac{m - m_{0}(u)}{\tau_{m}(u)}$$

$$\frac{dh}{dt} = -\frac{h - h_{0}(u)}{\tau_{h}(u)}$$

$$\frac{dn}{dt} = -\frac{n - n_{0}(u)}{\tau_{n}(u)}$$

$$\frac{dn}{dt} = -\frac{n - n_{0}(u)}{\tau_{n}(u)}$$

$$\frac{dn}{dt} = -\frac{m - n_{0}(u)}{\tau_{n}(u)}$$

1) dynamics of *m* are fast

$$\rightarrow m(t) = m_0(u(t))$$

Reduction of dimensionality: Separation of time scales

$$\tau_1 \frac{dx}{dt} = -x + c(t)$$

Exercise 1 (week 3) (later today!)

Two coupled differential equations

$$\tau_1 \frac{dx}{dt} = -x + h(y)$$

$$\tau_2 \frac{dy}{dt} = f(y) + g(x)$$

Separation of time scales

$$\tau_1 \ll \tau_2 \rightarrow x = h(y)$$

Reduced 1-dimensional system

$$\tau_2 \frac{dy}{dt} = f(y) + g(h(y))$$

$$C\frac{du}{dt} = -g_{Na}m^{3}h(u - E_{Na}) - g_{K}n^{4}(u - E_{K}) - g_{I}(u - E_{I}) + I(t)$$

$$\frac{dm}{dt} = -\frac{m - m_{0}(u)}{\tau_{m}(u)}$$

$$\frac{dh}{dt} = -\frac{h - h_{0}(u)}{\tau_{h}(u)}$$

$$\frac{dn}{dt} = -\frac{n - n_{0}(u)}{\tau_{n}(u)}$$

 $m(t) = m_0(u(t))$

- 1) dynamics of *m* are fast
- 2) dynamics of h and n are similar

Reduction of Hodgkin-Huxley Model to 2 Dimension

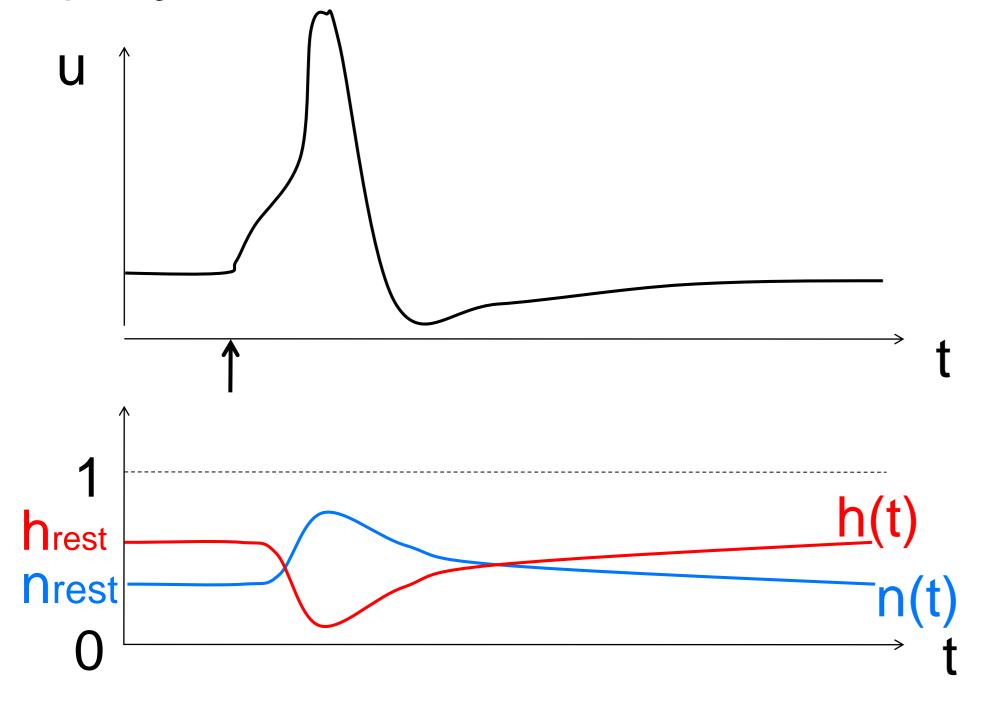
-step 1: separation of time scales

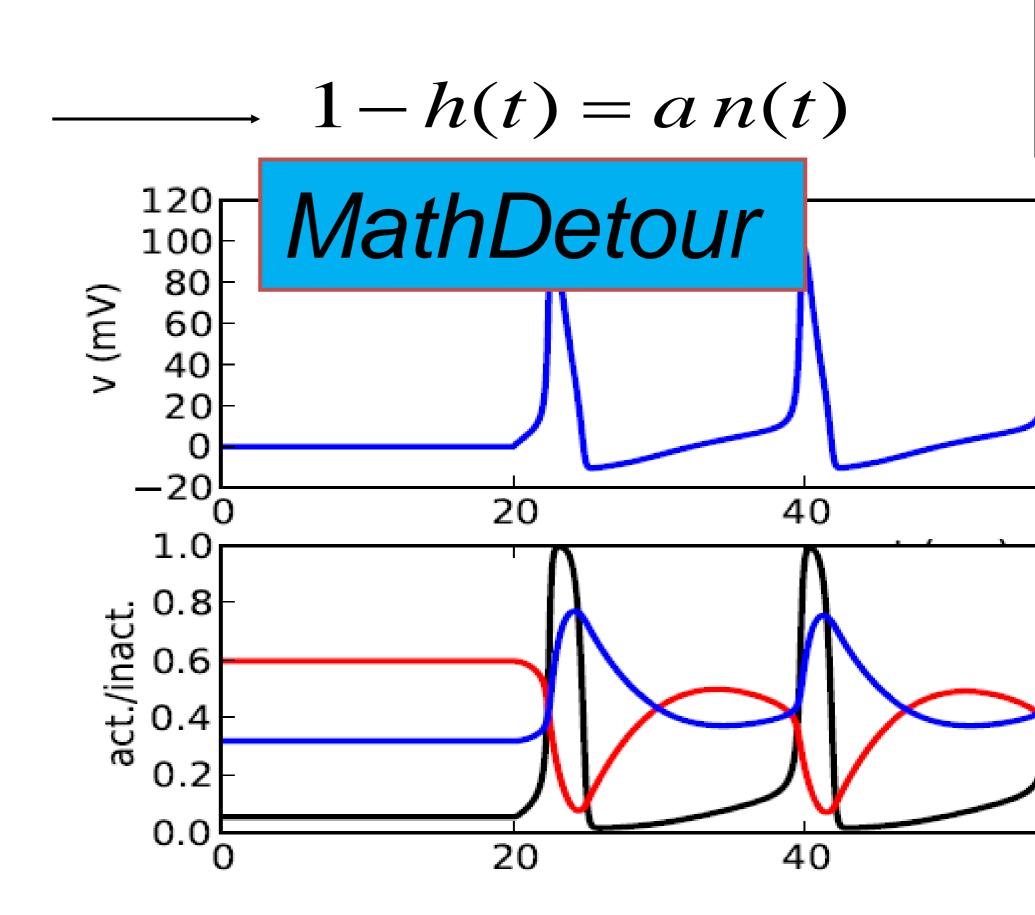
-step 2: exploit similarities/correlations

Now!

$$C\frac{du}{dt} = -g_{Na}m^{3}h(u - E_{Na}) - g_{K}n^{4}(u - E_{K}) - g_{l}(u - E_{l}) + I(t)$$

2) dynamics of h and n are similar

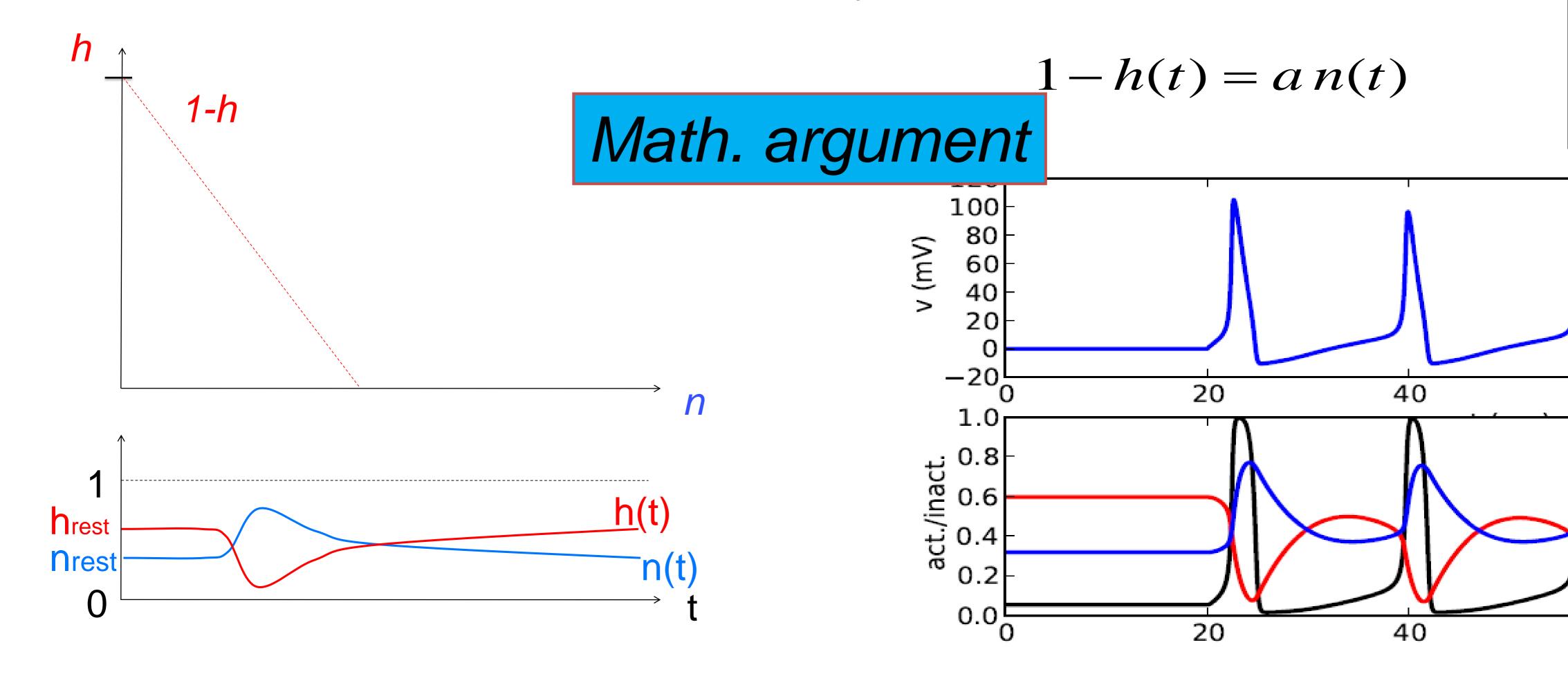




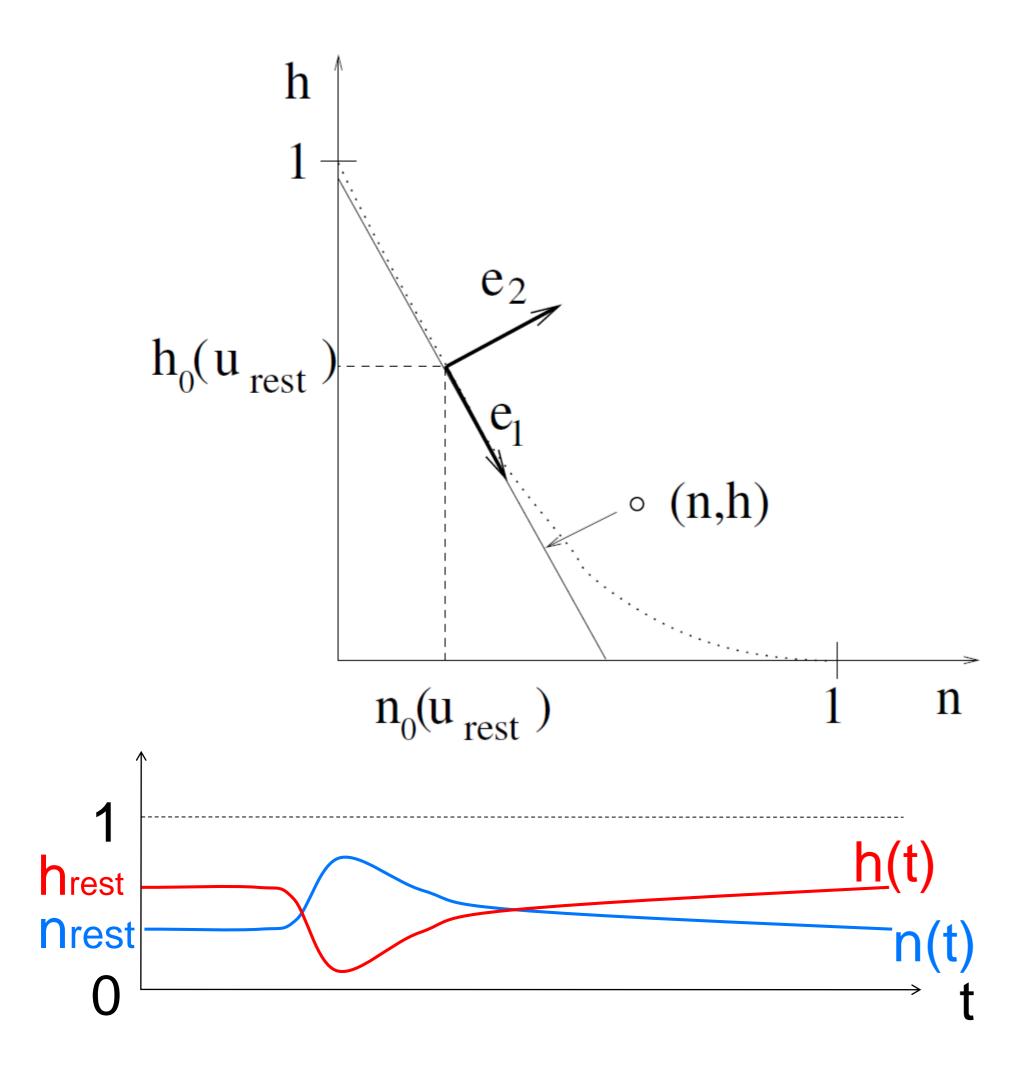
stimulus

3.1 Detour 1. Exploit similarities/correlations

dynamics of h and n are similar



3.1 Detour 1. Exploit similarities/correlations



dynamics of h and n are similar

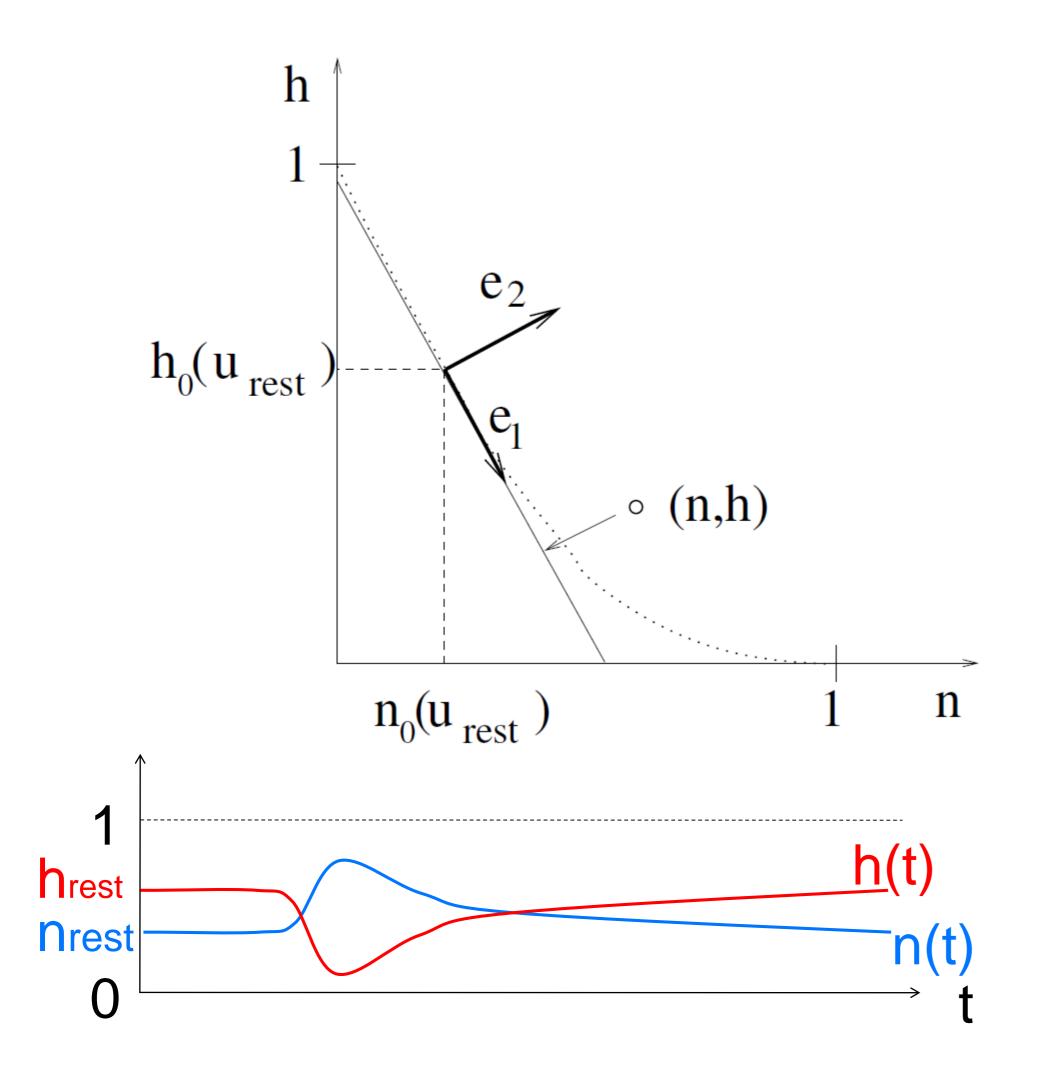
$$1 - h(t) = a n(t)$$

at rest

$$\frac{dh}{dt} = -\frac{h - h_0(u)}{\tau_h(u)}$$

$$\frac{dn}{dt} = -\frac{n - n_0(u)}{\tau_n(u)}$$

3.1 Detour 1. Exploit similarities/correlations



dynamics of h and n are similar

- (i) Rotate coordinate system
- (ii) Suppress one coordinate
- (iii) Express dynamics in new variable

$$1 - h(t) = a n(t) = w(t)$$

$$\frac{dh}{dt} = -\frac{h - h_0(u)}{\tau_h(u)} \qquad \frac{dw}{dt} = -\frac{w - w_0(u)}{\tau_{eff}(u)}$$

$$\frac{dn}{dt} = -\frac{n - n_0(u)}{\tau_n(u)}$$

$$C\frac{du}{dt} = -g_{Na}[m(t)]^{3}h(t)(u(t) - E_{Na}) - g_{K}[n(t)]^{4}(u(t) - E_{K}) - g_{l}(u(t) - E_{l}) + I(t)$$

$$C\frac{du}{dt} = -g_{Na} m_0(u)^3 (1-w)(u-E_{Na}) - g_K \left[\frac{w}{a}\right]^4 (u-E_K) - g_I(u-E_I) + I(t)$$

- 1) dynamics of *m* are fast

$$\longrightarrow m(t) = m_0(u(t))$$

$$\frac{dh}{dt} = -\frac{h - h_0(u)}{\tau_h(u)}$$

$$\frac{dn}{dt} = -\frac{n - n_0(u)}{\tau_n(u)}$$

$$\frac{dw}{dt} = -\frac{w - w_0(u)}{\tau_{eff}(u)}$$

$$C\frac{du}{dt} = -g_{Na} m_0(u)^3 (1-w)(u-E_{Na}) - g_K(\frac{w}{a})^4 (u-E_K) - g_I(u-E_I) + I(t)$$

$$\frac{dw}{dt} = -\frac{w-w_0(u)}{\tau_{eff}(u)}$$

$$\tau \frac{du}{dt} = F(u(t), w(t)) + RI(t)$$

$$\tau_w \frac{dw}{dt} = G(u(t), w(t))$$

3.1. Reduction to 2 dimensions

2-dimensional equation

$$C\frac{du}{dt} = f(u(t), w(t)) + I(t)$$
$$\frac{dw}{dt} = g(u(t), w(t))$$

Enables graphical analysis!

Phase plane analysis

- -Discussion of threshold
- Constant input current vs pulse input
- -Type I and II
- Repetitive firing

Week 3 – Quiz 3.2-similar dynamics

Exploiting similarities:

A sufficient condition to replace two gating variables r,s by a single gating variable w is [] Both r and s have the same time constant (as a function of u) [] Both r and s have the same activation function ![] Both r and s have the same time constant (as a function of u) AND the same activation function Both r and s have the same time constant (as a function of u) AND activation functions that are identical after some additive rescaling [] Both r and s have the same time constant (as a function of u) AND activation functions that are identical after some multiplicative rescaling

NOW Exercise 1.1-1.4: separation of time scales

$$C\frac{du}{dt} = -g_{Na}m^{3}h(u - E_{Na}) - g_{K}n^{4}(u - E_{K}) - g_{l}(u - E_{l}) + I(t)$$

$$\frac{dm}{dt} = -\frac{m - m_0(u)}{\tau_m(u)}$$

Exercises:

1.1-1.4 now!

1.5 homework

Exerc. 10h15-10h30

Next lecture:

10h30

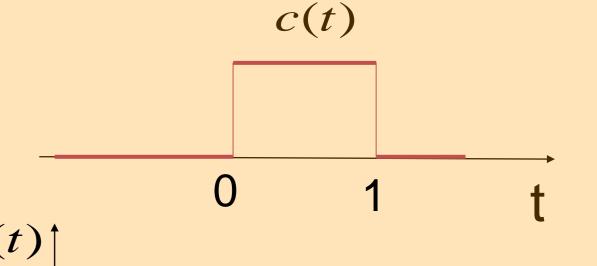
$$\frac{dx}{dt} = -\frac{x - c(t)}{\tau}$$

- calculate x(t)!

- what if τ is small?

$$\frac{dm}{dt} = -\frac{m - c(u)}{\tau_m}$$

$$\frac{du}{dt} = f(u) - m$$



B: -calculate m(t)if τ is small! - reduce to 1 eq.

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Week 3 – Reducing detail:

Two-dimensional neuron models

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3.1 From Hodgkin-Huxley to 2D

- Overview: From 4 to 2 dimensions
- MathDetour 1: Exploiting similarities
- MathDetour 2: Separation of time scales

3.2 Phase Plane Analysis

- Role of nullclines

3.3 Analysis of a 2D Neuron Model

- constant input vs pulse input
- MathDetour 3: Stability of fixed points

Discussion Exercise 1 – MathDetour 3.1: Separation of time scales

Exercise 1 (week 3)

Two coupled differential equations

Draw graph,
$$\frac{dx}{dt} = -x + c(t)$$
 blackboard
$$\tau_2 \frac{dy}{dt} = f(y) + g(x)$$

$$\tau_2 \frac{dy}{dt} = f(y) + g(x)$$

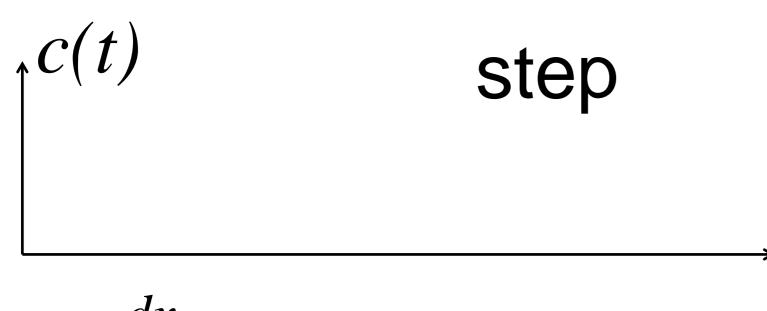
Separation of time scales

$$au_1 \ll au_2$$

Reduced 1-dimensional system

$$\tau_2 \frac{dy}{dt} = f(y) + g(c(t))$$

Ex. 1-A



$$\tau_1 \frac{dx}{dt} = -x + c(t)$$

Discussion Exercise 1 – MathDetour 3.1 Separation of time scales

Two coupled differential equations

$$\tau_1 \frac{dx}{dt} = -x + c(t)$$

$$\tau_2 \frac{dc}{dt} = -c + f(x) \mathbf{a} + I(t)$$

$$\mathbf{a} = 0$$

$$\mathbf{a} = 1$$

$$\tau_1 \ll \tau_2$$

Two cases:

$$I(t) = 'slow'$$

$$I(t) = q \, \delta(t - t_0)$$

Draw graph, blackboard



Discuss Exercise 1 – MathDetour 3.1: Separation of time scales

Exercise 1 (week 3)

even more general

Two coupled differential equations

$$\tau_1 \frac{dx}{dt} = -x + h(y)$$

$$\tau_2 \frac{dy}{dt} = f(y) + g(x)$$

Separation of time scales

$$\tau_1 \ll \tau_2 \rightarrow x = h(y)$$

Reduced 1-dimensional system

$$\tau_2 \frac{dy}{dt} = f(y) + g(h(y))$$

Discuss exercise 1 – Reduction of Hodgkin-Huxley model

$$C\frac{du}{dt} = -g_{Na}m^{3}h(u - E_{Na}) - g_{K}n^{4}(u - E_{K}) - g_{l}(u - E_{l}) + I(t)$$

$$\frac{dm}{dt} = -\frac{m - m_{0}(u)}{\tau_{m}(u)}$$

$$\frac{dh}{dt} = -\frac{h - h_{0}(u)}{\tau_{h}(u)}$$

$$\frac{dn}{dt} = -\frac{n - n_{0}(u)}{\tau_{n}(u)}$$

dynamics of m is fast

$$\longrightarrow m(t) = m_0(u(t))$$

Fast compared to what?

Neuronal Dynamics – Quiz 3.3.

A- Separation of time scales:

We start with two equations

$$\tau_1 \frac{dx}{dt} = -x + y + I(t)$$

$$\tau_2 \frac{dy}{dt} = -y + x^2 + A$$

[] If $\tau_1 \ll \tau_2$ then the system can be reduded to

$$\tau_2 \frac{dy}{dt} = -y + [y + I(t)]^2 + A$$

[] If $\tau_2 \ll \tau_1$ then the system can be reduded to

$$\tau_1 \frac{dx}{dt} = -x + x^2 + A + I(t)$$
[] None of the above is correct.

Pay attention to *I(t)*: We assume that I(t) is slow compared to both time constants.

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3.2 Phase Plane Analysis

- Role of nullclines

3.3 Analysis of a 2D Neuron Model

- constant input vs pulse input
- MathDetour 3: Stability of fixed points

3.2. Reduced Hodgkin-Huxley model

$$C\frac{du}{dt} = -g_{Na} m_0(u)^3 (1-w)(u-E_{Na}) - g_K(\frac{w}{a})^4 (u-E_K) - g_l(u-E_l) + I(t)$$

$$\frac{dw}{dt} = -\frac{w - w_0(u)}{\tau_w(u)}$$

stimulus
$$\tau \frac{du}{dt} = F(u, w) + RI(t)$$

$$\tau_{w} \frac{dw}{dt} = G(u, w)$$

3.2. Phase Plane Analysis/nullclines

First step:

u-nullcline: all points with *du/dt=0*

w-nullcline:
all points with dw/dt=0

2-dimensional equation stimulus

$$\tau \frac{du}{dt} = F(u, w) + RI(t)$$

$$\tau_w \frac{dw}{dt} = G(u, w)$$

Enables graphical analysis!

- -Discussion of threshold
- -Type I and II

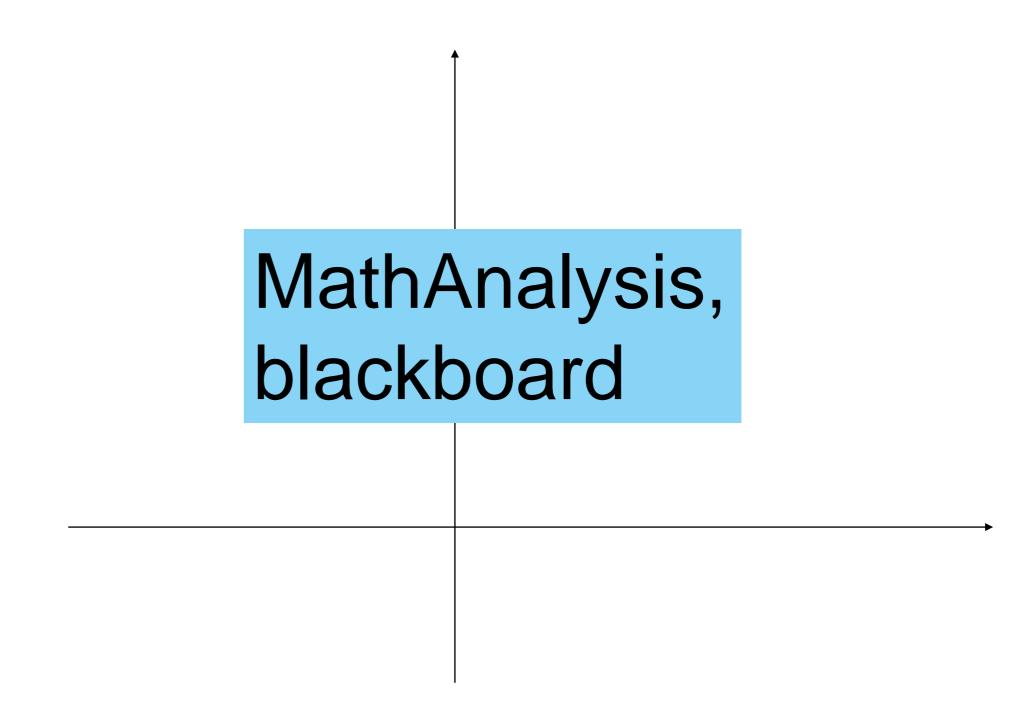
3.2. FitzHugh-Nagumo Model

$$\tau \frac{du}{dt} = F(u, w) + RI(t)$$
$$= u - \frac{1}{3}u^3 - w + RI(t)$$

$$\tau_{w} \frac{dw}{dt} = G(u, w) = b_0 + b_1 u - w$$

u-nullcline

w-nullcline



3.2. flow arrows

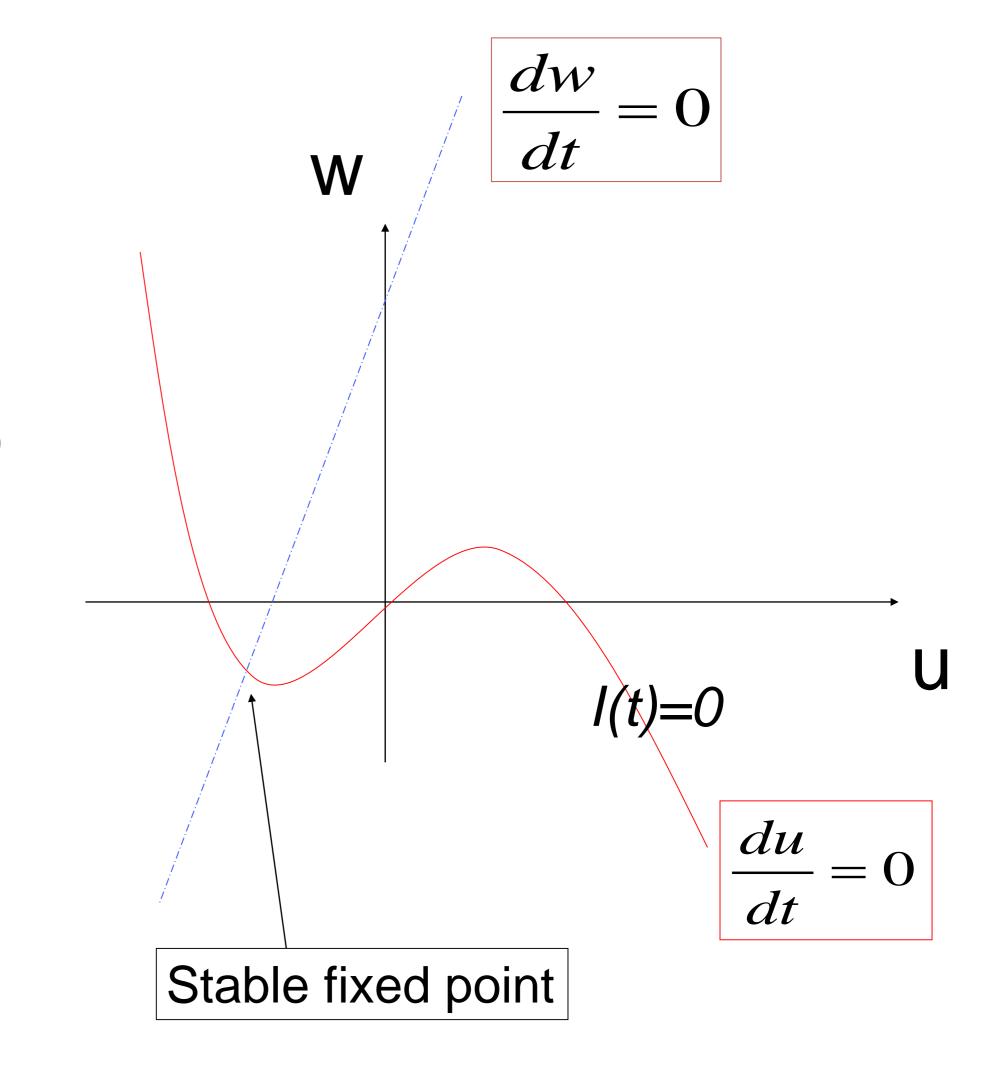
$$\tau \frac{du}{dt} = F(u, w) + RI(t)$$
 Stimulus I=0

$$\tau_{w} \frac{dw}{dt} = G(u, w)$$

Consider change in small time step

Flow on nullcline

Flow in regions between nullclines



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Two-dimensional neuron models

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3.3 Analysis of a 2D Neuron Model

- constant input vs pulse input
- MathDetour 3: Stability of fixed points

Neuronal Dynamics – 3.2. flow arrows

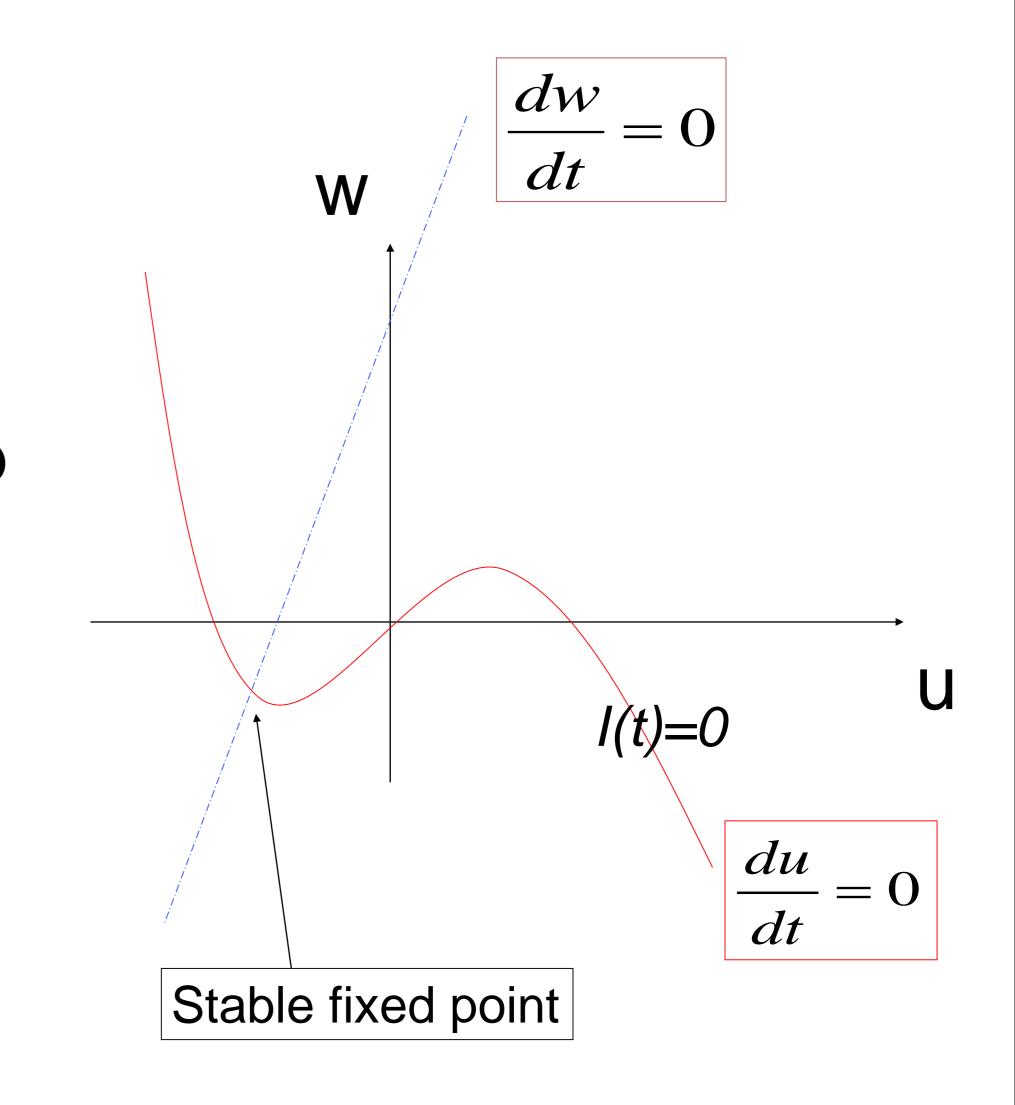
$$\tau \frac{du}{dt} = F(u, w) + RI(t)$$
 Stimulus I=0

$$\tau_{w} \frac{dw}{dt} = G(u, w)$$

Consider change in small time step

Flow on nullcline

Flow in regions between nullclines



Week 3 – Quiz 3.4

A. u-Nullclines

- [] On the u-nullcline, arrows are always vertical
- [] On the u-nullcline, arrows point always vertically upward
- [] On the u-nullcline, arrows are always horizontal
- [] On the u-nullcline, arrows point always to the left
- [] On the u-nullcline, arrows point always to the right

B. w-Nullclines

- [] On the w-nullcline, arrows are always vertical
- [] On the w-nullcline, arrows point always vertically upward
- [] On the w-nullcline, arrows are always horizontal
- [] On the w-nullcline, arrows point always to the left
- [] On the w-nullcline, arrows point always to the right
- [] On the w-nullcline, arrows can point in an arbitrary direction

Take 1 minute

3.2. FitzHugh-Nagumo Model

$$\tau \frac{du}{dt} = F(u, w) + RI(t)$$

$$= u - \frac{1}{3}u^3 + RI(t) - w$$

$$\tau_w \frac{dw}{dt} = G(u, w) = b_0 + b_1 u - w$$

$$/ /$$

$$change bo, b1$$

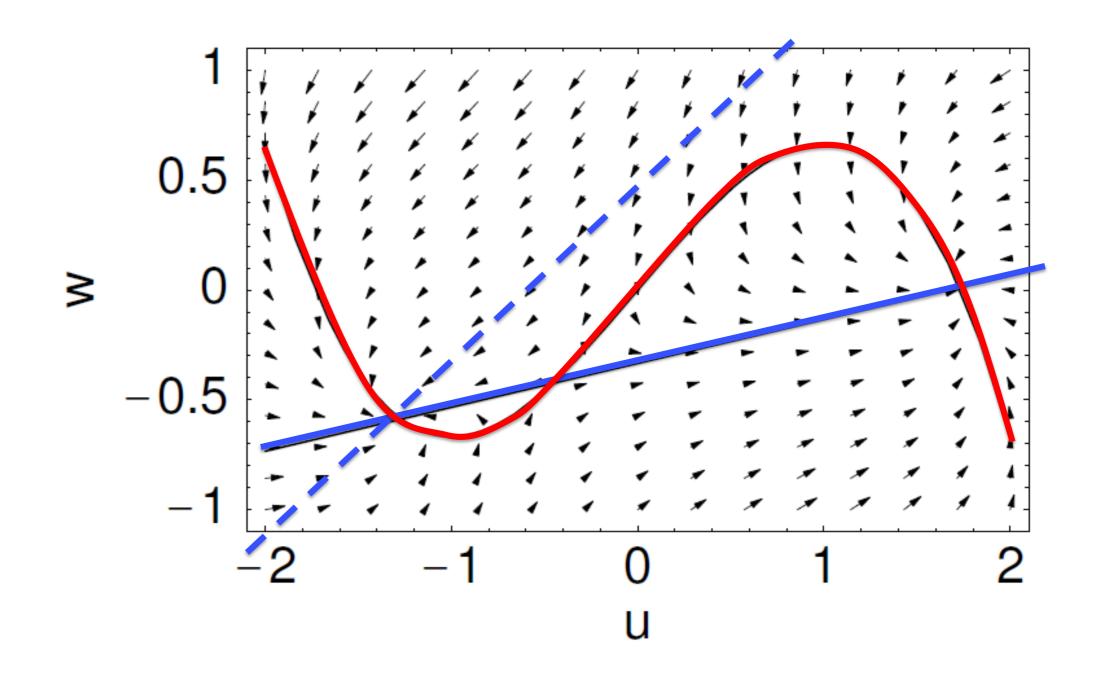


Image: Neuronal Dynamics, Gerstner et al., Cambridge Univ. Press (2014)

3.2. Nullclines of reduced HH model

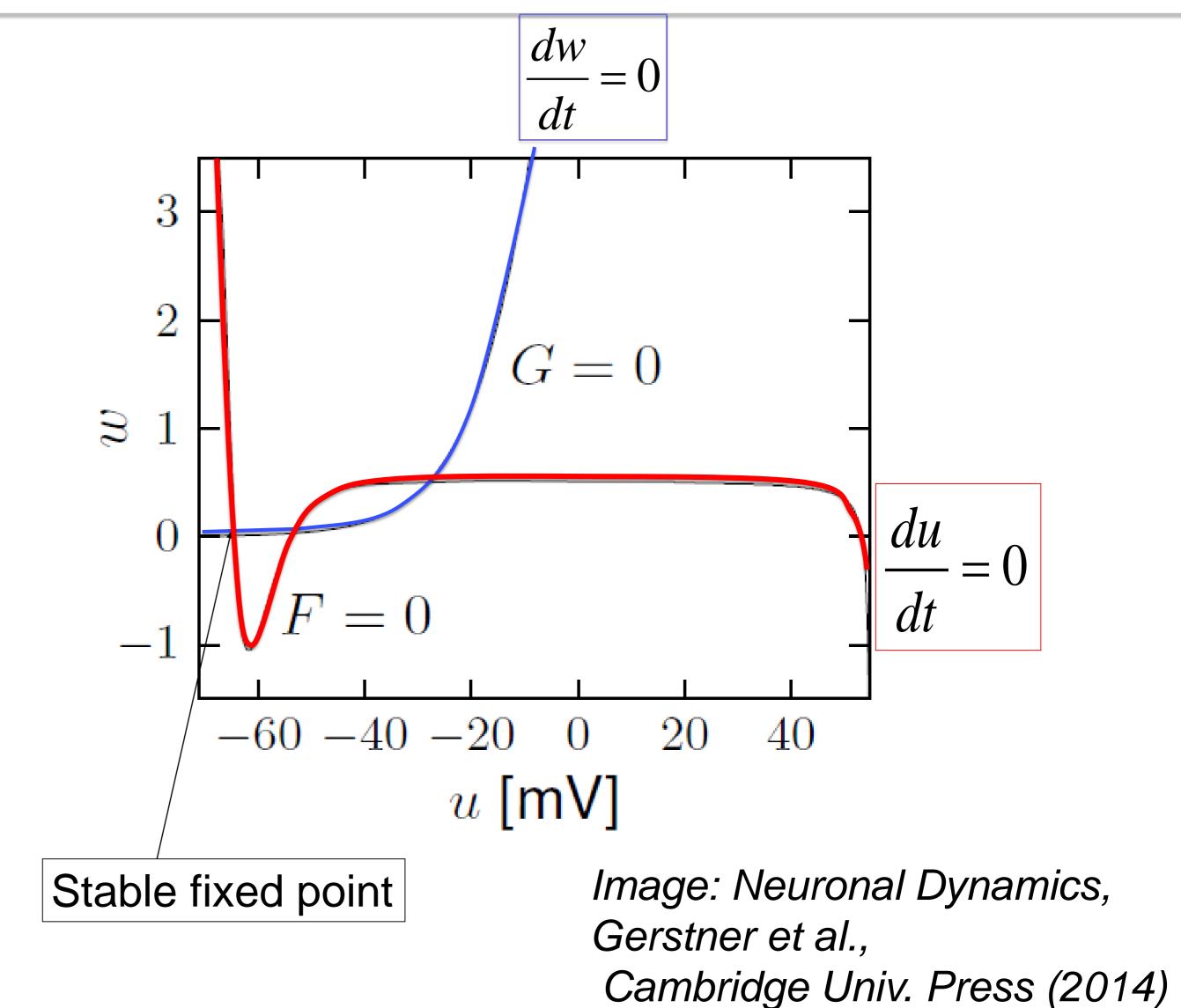
stimulus

$$\tau \frac{du}{dt} = F(u, w) + RI(t)$$

$$\tau_w \frac{dw}{dt} = G(u, w)$$

u-nullcline

w-nullcline



3.2. Phase Plane Analysis

2-dimensional equation

$$\tau \frac{du}{dt} = F(u, w) + RI(t)$$

$$\tau_{w} \frac{dw}{dt} = G(u, w)$$

Enables graphical analysis! Important role of

- nullclines
- flow arrows

Application to neuron models

Week 3 – part 3: Analysis of a 2D neuron model



3.1 From Hodgkin-Huxley to 2D

3.2 Phase Plane Analysis
- Role of nullcline

3.3 Analysis of a 2D Neuron Model

- pulse input
- constant input
- -MathDetour 3: Stability of fixed points

3.3. Analysis of a 2D neuron model

2 important input scenarios

- Pulse input
- Constant input

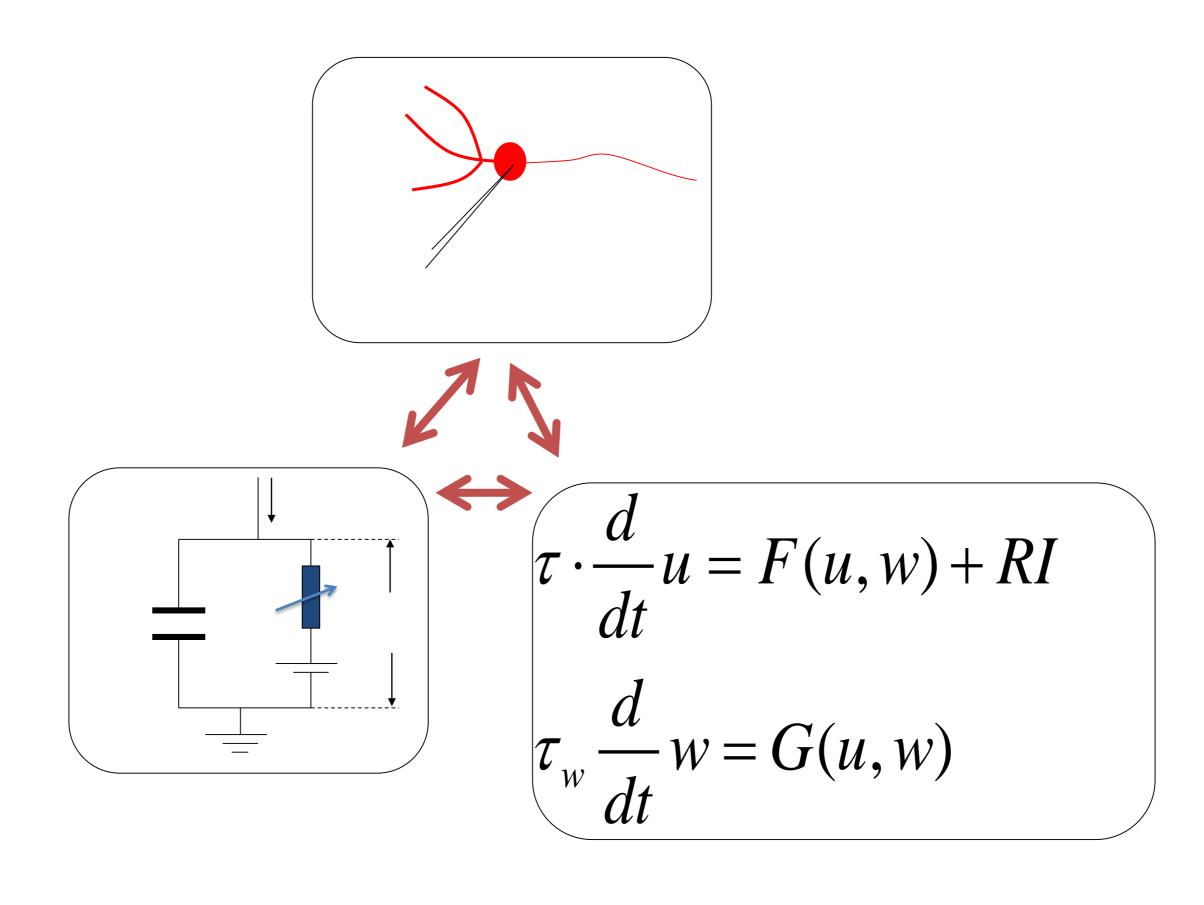
2-dimensional equation stimulus

$$\tau \frac{du}{dt} = F(u, w) + RI(t)$$

$$\tau_w \frac{dw}{dt} = G(u, w)$$

Enables graphical analysis!

3.3. 2D neuron model: Pulse input



pulse input

3.3. FitzHugh-Nagumo Model: Pulse input

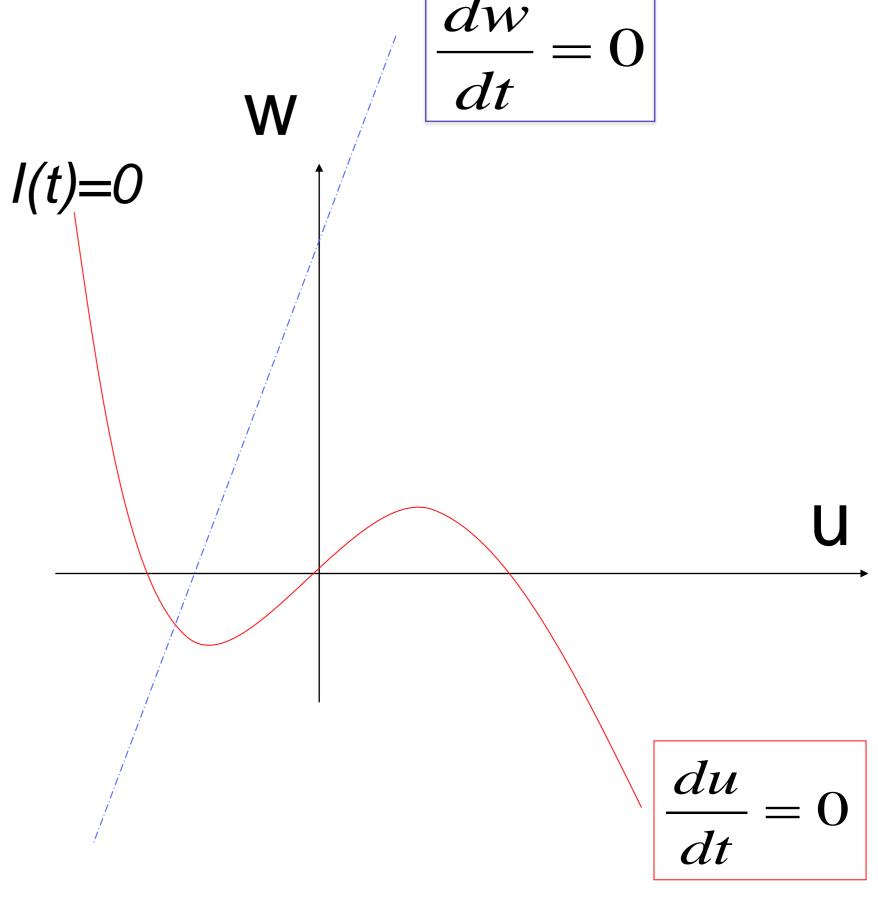
$$\tau \frac{du}{dt} = F(u, w) + RI(t) = u - \frac{1}{3}u^3 - w + RI(t)$$

$$\tau_{w} \frac{dw}{dt} = G(u, w) \qquad = b_0 + b_1 u - w$$

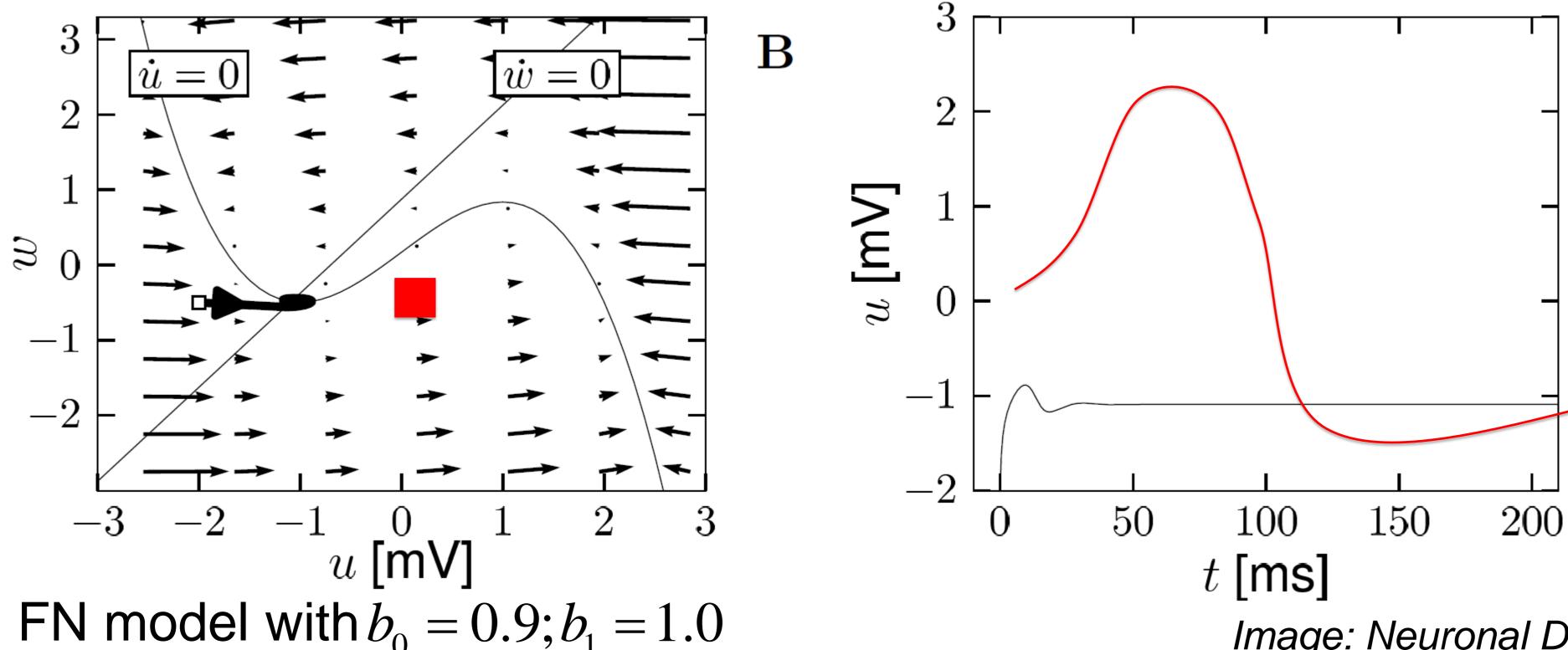


pulse input

Pulse input: jump of voltage



3.3. FitzHugh-Nagumo Model: Pulse input



Pulse input: jump of voltage/initial condition

Image: Neuronal Dynamics, Gerstner et al., Cambridge Univ. Press (2014)

3.3. FitzHugh-Nagumo Model – 2 different inputs

Pulse input:

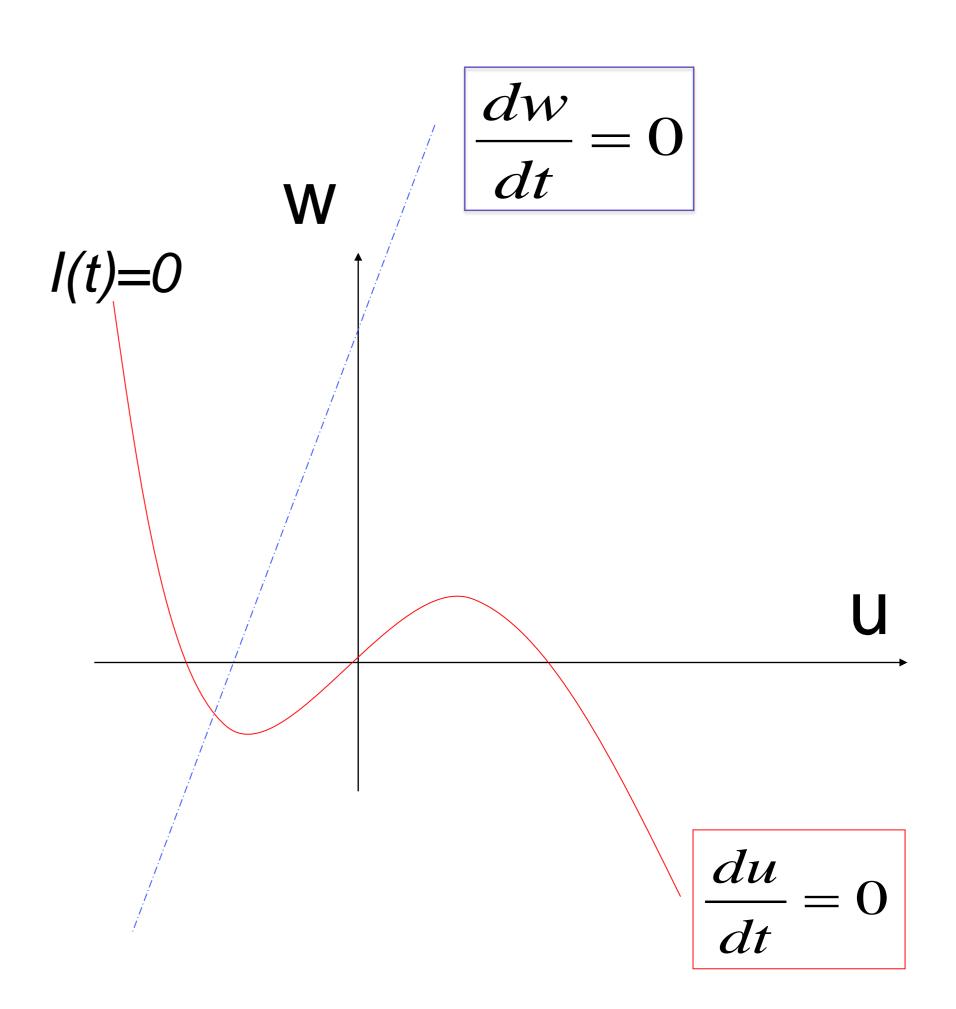
DONE!

- jump of voltage
- 'new initial condition'
- spike generation for large input pulses
- 2 important input scenarios

constant input:

- graphics?
- spikes?
- repetitive firing?

Now

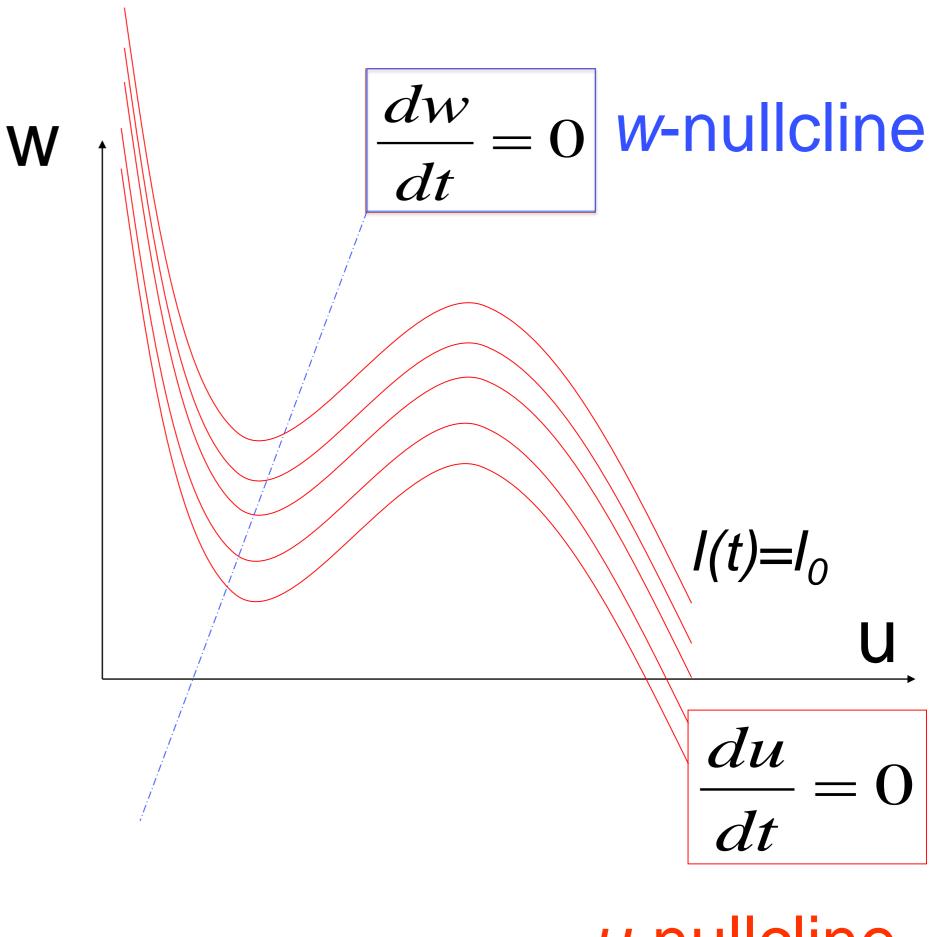


$$\tau \frac{du}{dt} = F(u, w) + RI_0$$
$$= u - \frac{1}{3}u^3 - w + RI_0$$

$$\tau_{w} \frac{dw}{dt} = G(u, w) = b_0 + b_1 u - w$$

Intersection point (fixed point)

- -moves
- -changes Stability



u-nullcline

NOW Exercise 2.1: Stability of Fixed Point in 2D

$$\frac{du}{dt} = \alpha u - w$$

$$\frac{dw}{dt} = \beta u - w$$

$$W$$

- calculate stability

Exercises:

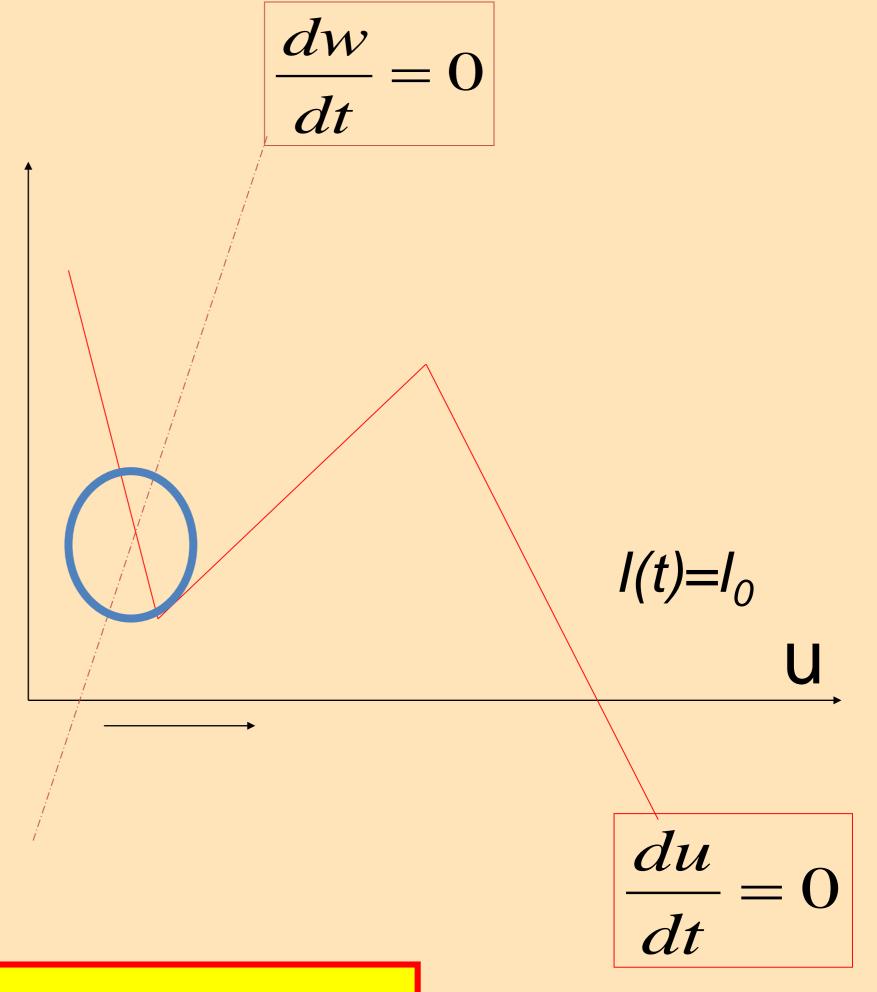
- compare

2.1 start now!

2.2 homework

(you may start if you have time)

 $\frac{dx}{dt} = -\frac{x}{\tau}$



oroioo: lotor

Exercise: later

Week 3 – part 3: Analysis of a 2D neuron model



- 3.1 From Hodgkin-Huxley to 2D
- 3.2 Phase Plane Analysis
 - Role of nullcline
 - 3.3 Analysis of a 2D Neuron Model
 - pulse input
 - constant input
 - -MathDetour 3: Stability of fixed points

Discussion of exercise 2 Detour. Stability of fixed points

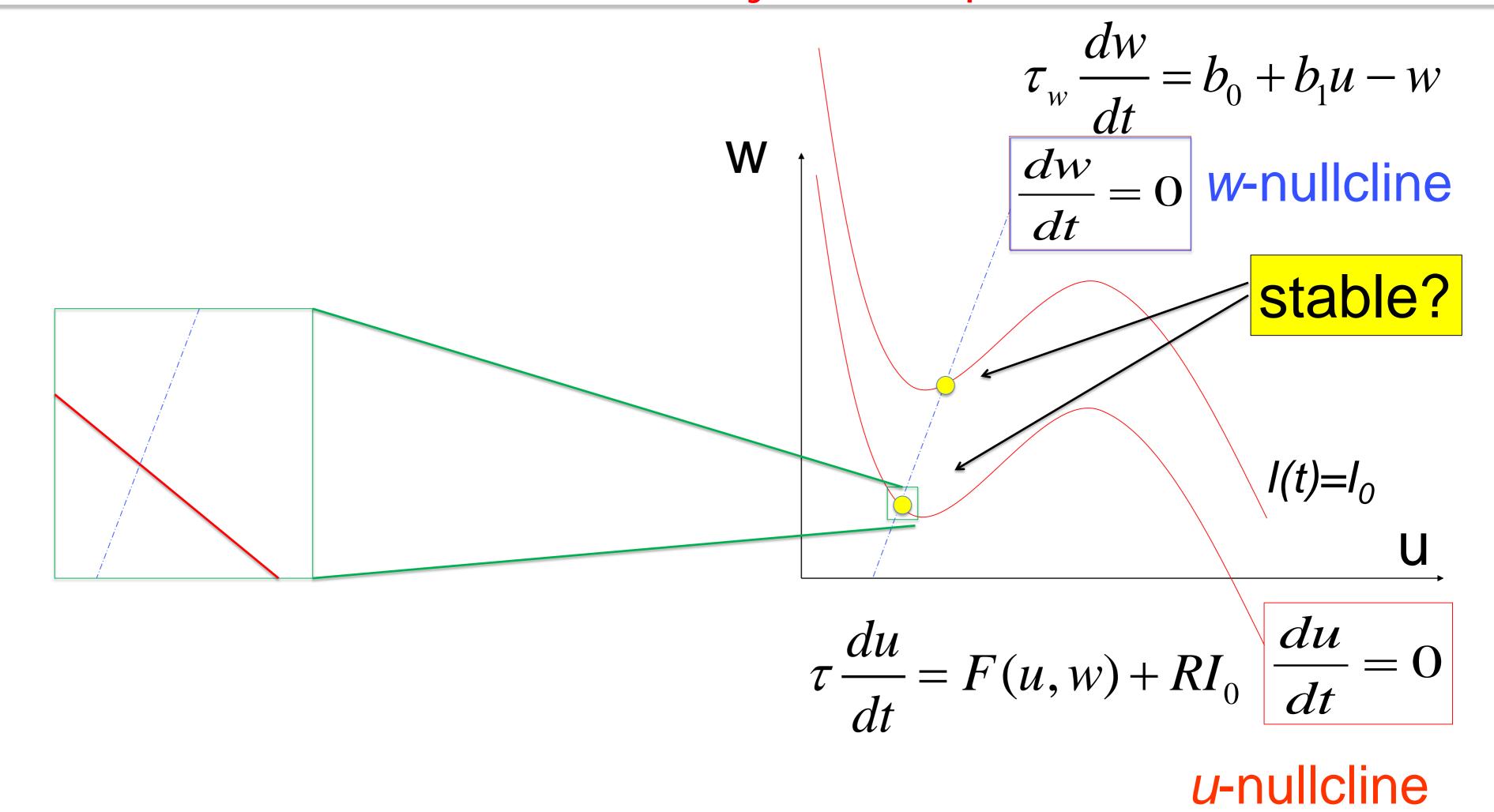
2-dimensional equation stimulus

$$\tau \frac{du}{dt} = F(u, w) + RI_0$$

$$\tau_w \frac{dw}{dt} = G(u, w)$$

How to determine stability of fixed point?

Discussion of exercise 2 - Detour: Stability of fixed points.

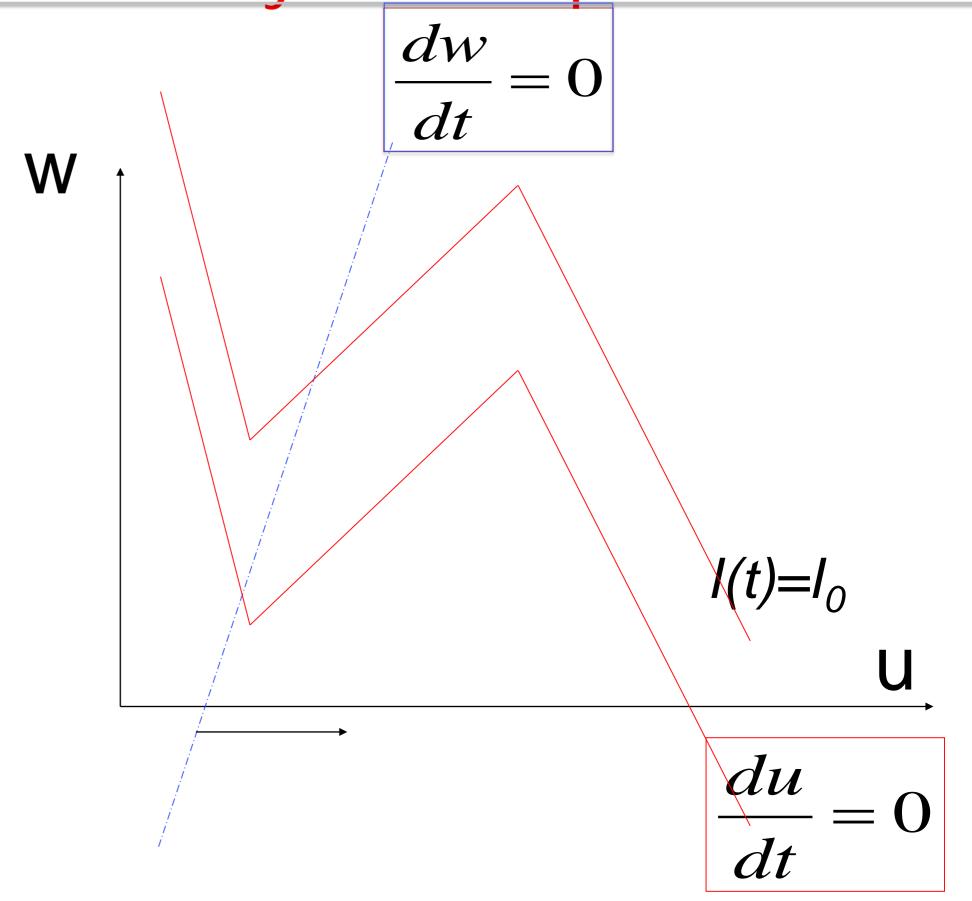


Discussion of Exercise 2: Detour - Stability of fixed points

stimulus

$$\tau \frac{du}{dt} = au - w + I_0$$

$$\tau_w \frac{dw}{dt} = c \, u - w$$

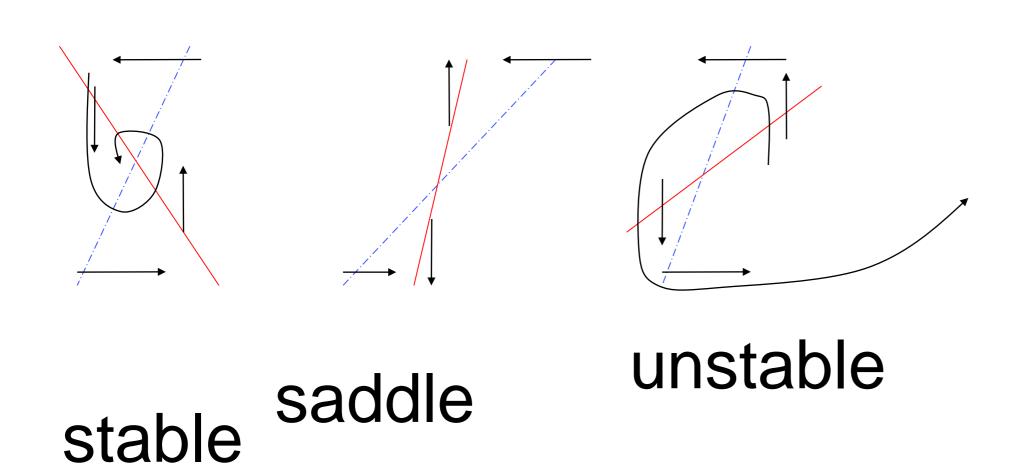


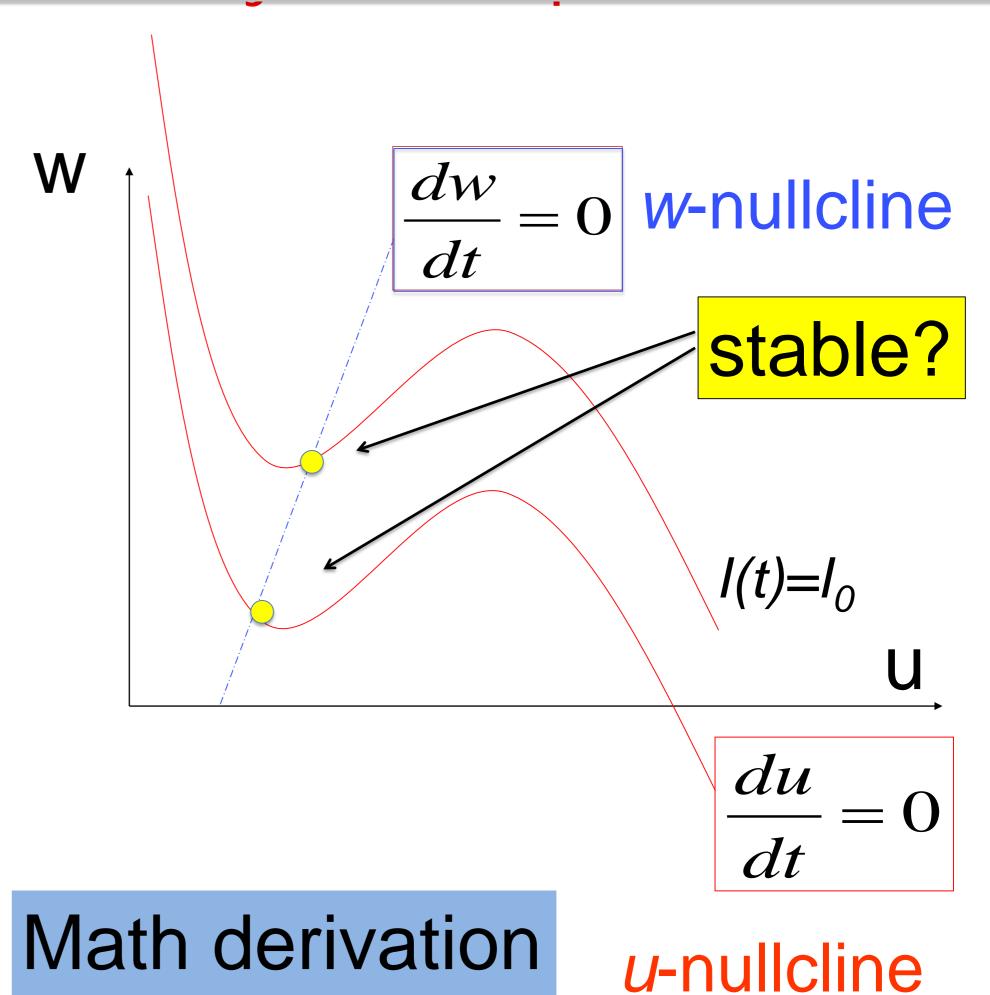
Discussion of Exercise 2: Detour. Stability of fixed points

$$\tau \frac{du}{dt} = F(u, w) + RI_0$$

$$\tau_w \frac{dw}{dt} = G(u, w)$$

zoom in:





now

3.3. Neuron models and Stability of fixed points

Now Back:

Application to our neuron model

2-dimensional equation

$$\tau \frac{du}{dt} = F(u, w) + RI_0$$

$$\tau_w \frac{dw}{dt} = G(u, w)$$

Stability characterized by Eigenvalues of linearized equations

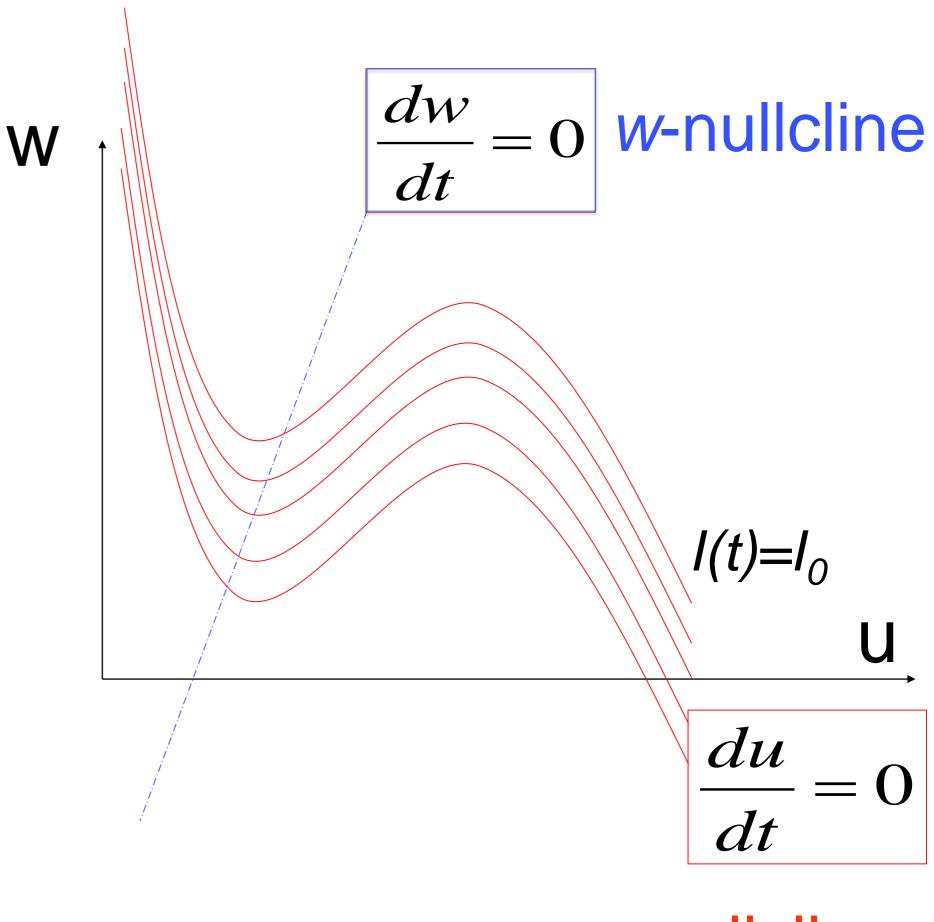
$$\frac{\mathrm{d}}{\mathrm{d}t}\boldsymbol{x} = \begin{pmatrix} F_u & F_w \\ G_u & G_w \end{pmatrix} \boldsymbol{x}$$

$$\tau \frac{du}{dt} = F(u, w) + RI_0$$
$$= u - \frac{1}{3}u^3 - w + RI_0$$

$$\tau_w \frac{dw}{dt} = G(u, w) = b_0 + b_1 u - w$$

Intersection point (fixed point)

- -moves
- -changes Stability



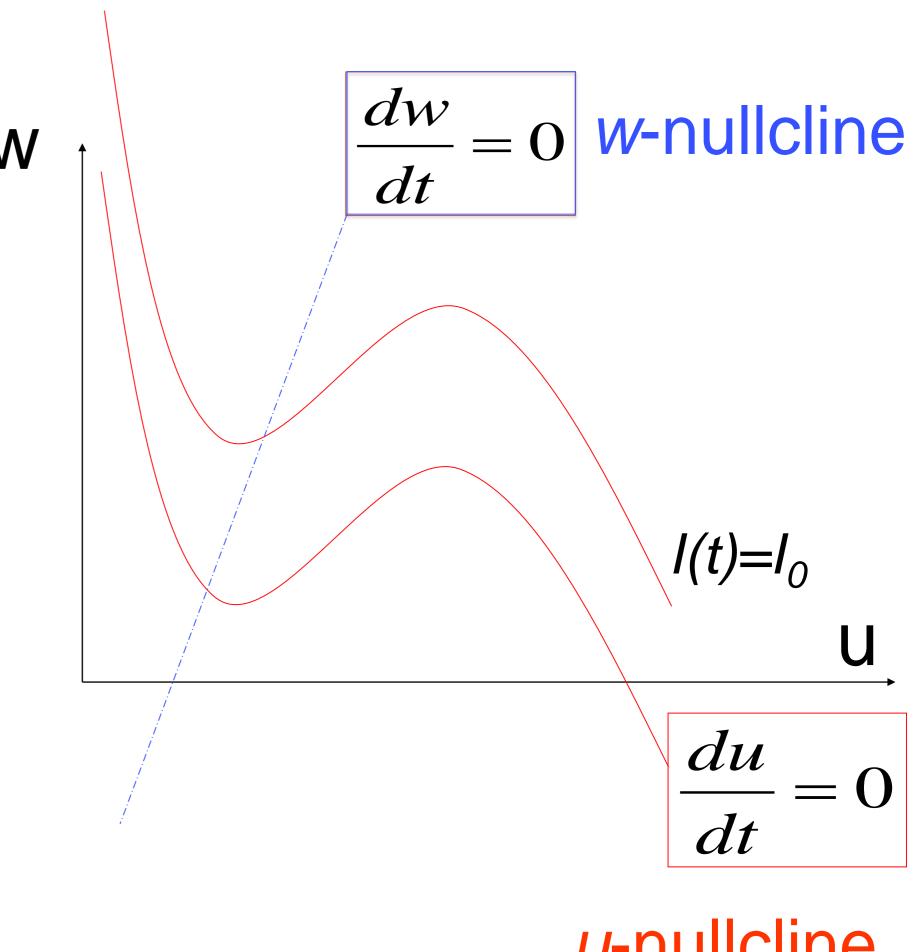
u-nullcline

$$\tau \frac{du}{dt} = F(u, w) + RI_0$$
$$= u - \frac{1}{3}u^3 - w + RI_0$$

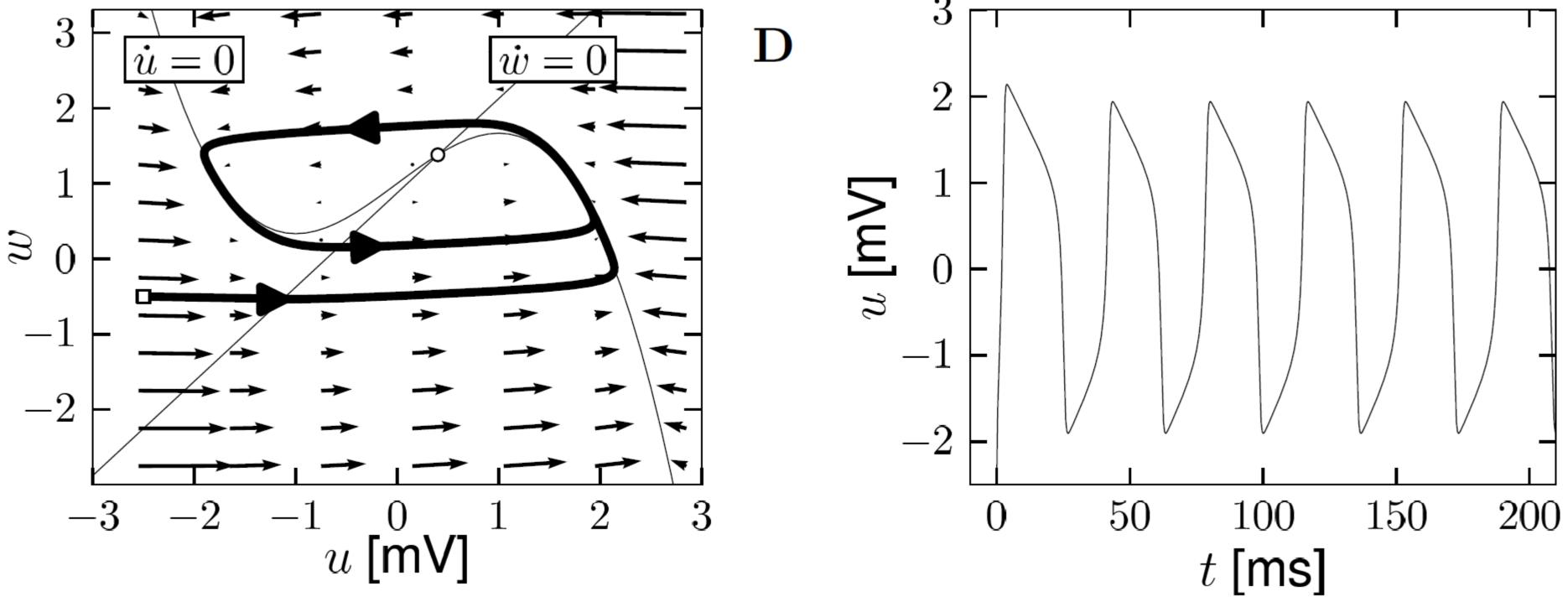
$$\tau_w \frac{dw}{dt} = G(u, w) = b_0 + b_1 u - w$$

Intersection point (fixed point)

- -moves
- -changes Stability



u-nullcline



FN model with $b_0 = 0.9; b_1 = 1.0; RI_0 = 2$ constant input: u-nullcline moves limit cycle

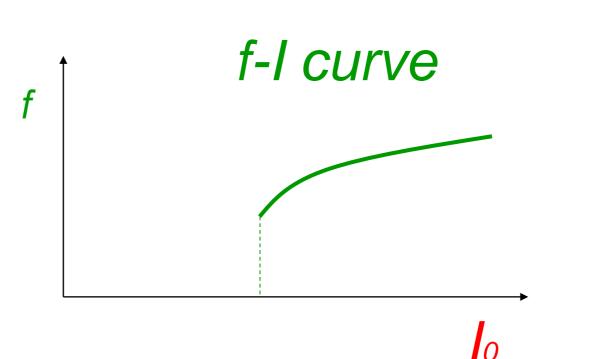


Image:
Neuronal Dynamics,
Gerstner et al.,
Cambridge (2014)

Neuronal Dynamics - Quiz 3.5.

- A. Short current pulses. In a 2-dimensional neuron model, the effect of a delta current pulse can be analyzed
 [] By moving the u-nullcline vertically upward
 [] By moving the w-nullcline vertically upward
 [] As a potential change in the stability or number of the fixed point(s)
 [] As a new initial condition
 [] By following the flow of arrows in the appropriate phase plane diagram
- **B. Constant current.** In a 2-dimensional neuron model, the effect of a constant current can be analyzed
- [] By moving the u-nullcline vertically upward
- [] By moving the w-nullcline vertically upward
- [] As a potential change in the stability or number of the fixed point(s)
- [] By following the flow of arrows in the appropriate phase plane diagram

NOW Exercise 2.1: Stability of Fixed Point in 2D

$$\frac{du}{dt} = \alpha u - w$$

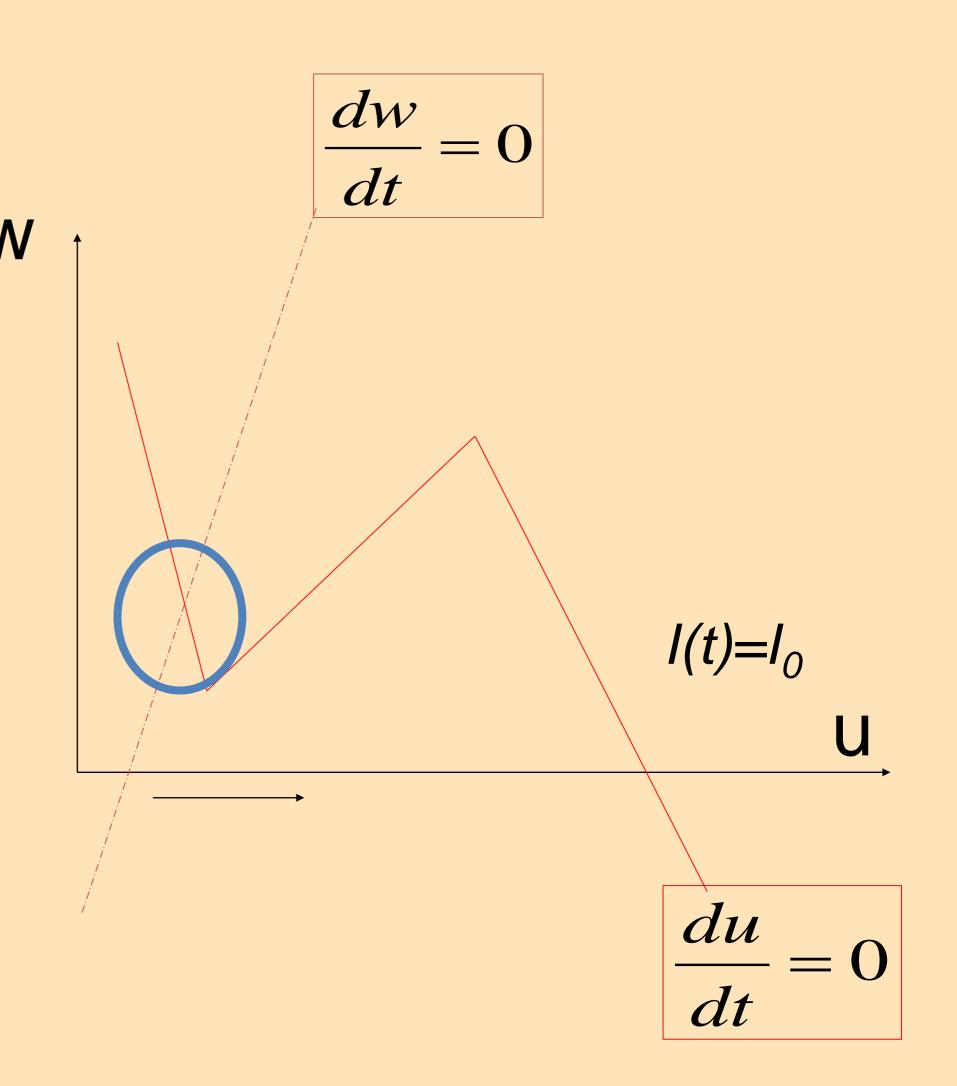
$$\frac{dw}{dt} = \beta u - w$$

Exercises:

- 2.1 now!
- 2.2 homework

- calculate stability
- compare

$$\frac{dx}{dt} = -\frac{x}{\tau}$$

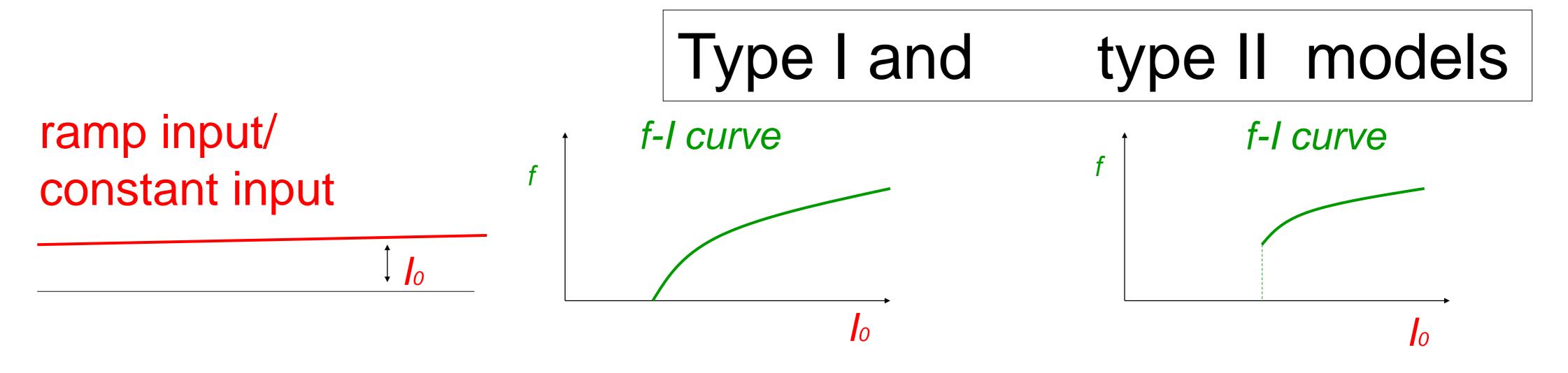


Computer exercise now

Can we understand the dynamics of the 2D model?

The END for today

Now: computer exercises



Discussion of Exercise 2 Detour. Stability of fixed points

$$\tau \frac{du}{dt} = F(u, w) + RI_0$$

$$\tau_w \frac{dw}{dt} = G(u, w)$$

zoom in:

$$x = u - u_0$$

$$y = w - w_0$$

Fixed point at (u_0, w_0)

At fixed point

$$0 = F(u_0, w_0) + RI_0$$

$$0 = G(u_0, w_0)$$

Discussion of Exercise 2 - Detour. Stability of fixed points

$$\tau \frac{du}{dt} = F(u, w) + RI_0$$

$$\tau_w \frac{dw}{dt} = G(u, w)$$

zoom in:

$$x = u - u_0$$

$$y = w - w_0$$

$$\tau \frac{dx}{dt} = F_u x + F_w y$$

$$\tau_w \frac{dy}{dt} = G_u x + G_w y$$

Fixed point at (u_0, w_0)

At fixed point

$$0 = F(u_0, w_0) + RI_0$$

$$0 = G(u_0, w_0)$$

$$\frac{\mathrm{d}}{\mathrm{d}t}\boldsymbol{x} = \begin{pmatrix} F_{\boldsymbol{u}} & F_{\boldsymbol{w}} \\ G_{\boldsymbol{u}} & G_{\boldsymbol{w}} \end{pmatrix} \boldsymbol{x},$$

Discussion of Exercise 2 Detour. Stability of fixed points

Linear matrix equation

$$\frac{\mathrm{d}}{\mathrm{d}t}\boldsymbol{x} = \begin{pmatrix} F_{\boldsymbol{u}} & F_{\boldsymbol{w}} \\ G_{\boldsymbol{u}} & G_{\boldsymbol{w}} \end{pmatrix} \boldsymbol{x},$$

Search for solution

$$x(t) = e \exp(\lambda t)$$

Two solution with Eigenvalues λ_{+}, λ_{-}

$$\lambda_{+} + \lambda_{-} = F_{u} + G_{w}$$

$$\lambda_{+} \lambda_{-} = F_{u} G_{w} - F_{w} G_{u}$$

Discussion of Exercise 2: Detour. Stability of fixed points

Linear matrix equation

$$\frac{\mathrm{d}}{\mathrm{d}t}\boldsymbol{x} = \begin{pmatrix} F_u & F_w \\ G_u & G_w \end{pmatrix} \boldsymbol{x}$$

Search for solution

$$\dot{x}(t) = e \exp(\lambda t)$$

Two solution with Eigenvalues λ_{+}, λ_{-}

$$\lambda_{+} + \lambda_{-} = F_{u} + G_{w}$$

$$\lambda_{+} \lambda_{-} = F_{u} G_{w} - F_{w} G_{u}$$

Stability requires:

$$\lambda_{+} < 0$$
 and $\lambda_{-} < 0$

$$\downarrow$$

$$F_{u} + G_{w} < 0$$
and
$$F_{u}G_{w} - F_{w}G_{u} > 0$$

Discussion of exercise 2: Detour. Stability of fixed points



$$\tau \frac{du}{dt} = au - w + I_0$$

$$\tau_w \frac{dw}{dt} = c u - w$$

$$\lambda_{\scriptscriptstyle +/-} =$$

