

Exam:

- written exam Tuesday July 3 from 8:15-11:15
- sample exams of previous years online
- miniproject counts 33 percent towards final grade

For written exam:

- bring 1 sheet A5 (double-sided) of own notes/summary
- HANDWRITTEN!
- no calculator, no textbook

LEARNING OUTCOMES

- Solve linear one-dimensional differential equations
- Analyze two-dimensional models in the phase plane
- Develop a simplified model by separation of time scales
- Analyze connected networks in the mean-field limit
- Formulate stochastic models of biological phenomena
- Formalize biological facts into mathematical models
- Prove stability and convergence
- Predict outcome of dynamics
- Describe neuronal phenomena
- Apply model concepts in simulations

Transversal skills

- Plan and carry out activities in a way which makes optimal use of available time and other resources.
- Collect data.
- Write a scientific or technical report.

Look at samples of
past exams

Use a textbook,
or video lectures.
Don't use slides as
only resources

miniproject

Your Questions for Exam?

LEARNING OUTCOMES (in red: repeated today)

- Solve linear one-dimensional differential equations
- Analyze two-dimensional models in the phase plane
- Develop a simplified model by separation of time scales
- Analyze connected networks in the mean-field limit
- Formulate stochastic models of biological phenomena
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Transversal skills

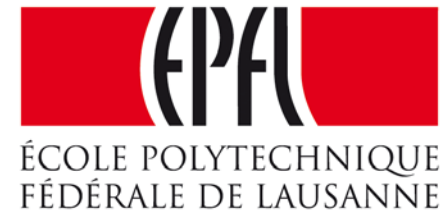
- Plan and carry out activities in a way which makes optimal use of available time and other resources.
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past exams

Use a textbook,
(Use video lectures)
don't use slides (only)

miniproject

Biological Modeling of Neural Networks



Week XX

Optimizing Neuron Models For Coding and Decoding

Wulfram Gerstner

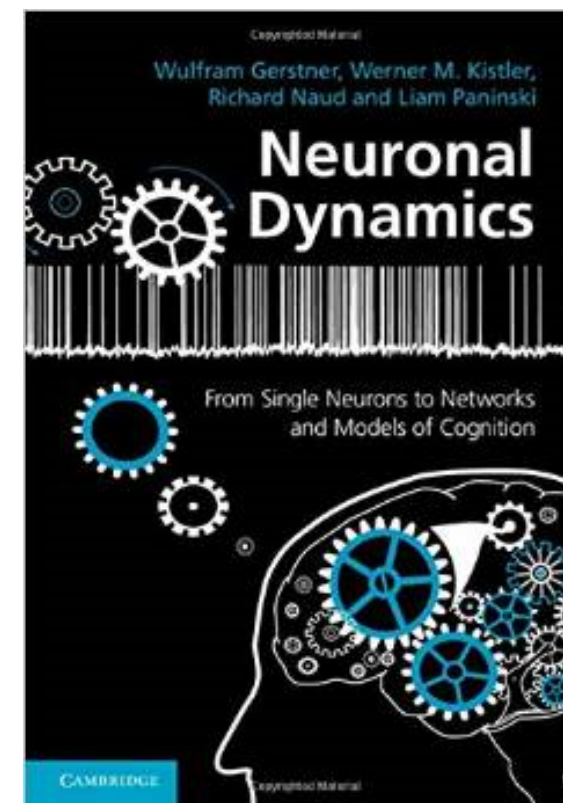
EPFL, Lausanne, Switzerland

Reading for this week:

NEURONAL DYNAMICS

- Ch. 4.6, 6.1, 6.2, 6.4, 9.2
- Ch. 10.2.3, 11.1, 11.3.3

Cambridge Univ. Press



9.1 What is a good neuron model?

- Models and data

9.2 AdEx model

- Firing patterns and adaptation

9.3 Spike Response Model (SRM)

- Integral formulation

9.4 Generalized Linear Model

- Adding noise to the SRM
- Likelihood of a spike train

(9.5 Parameter Estimation)

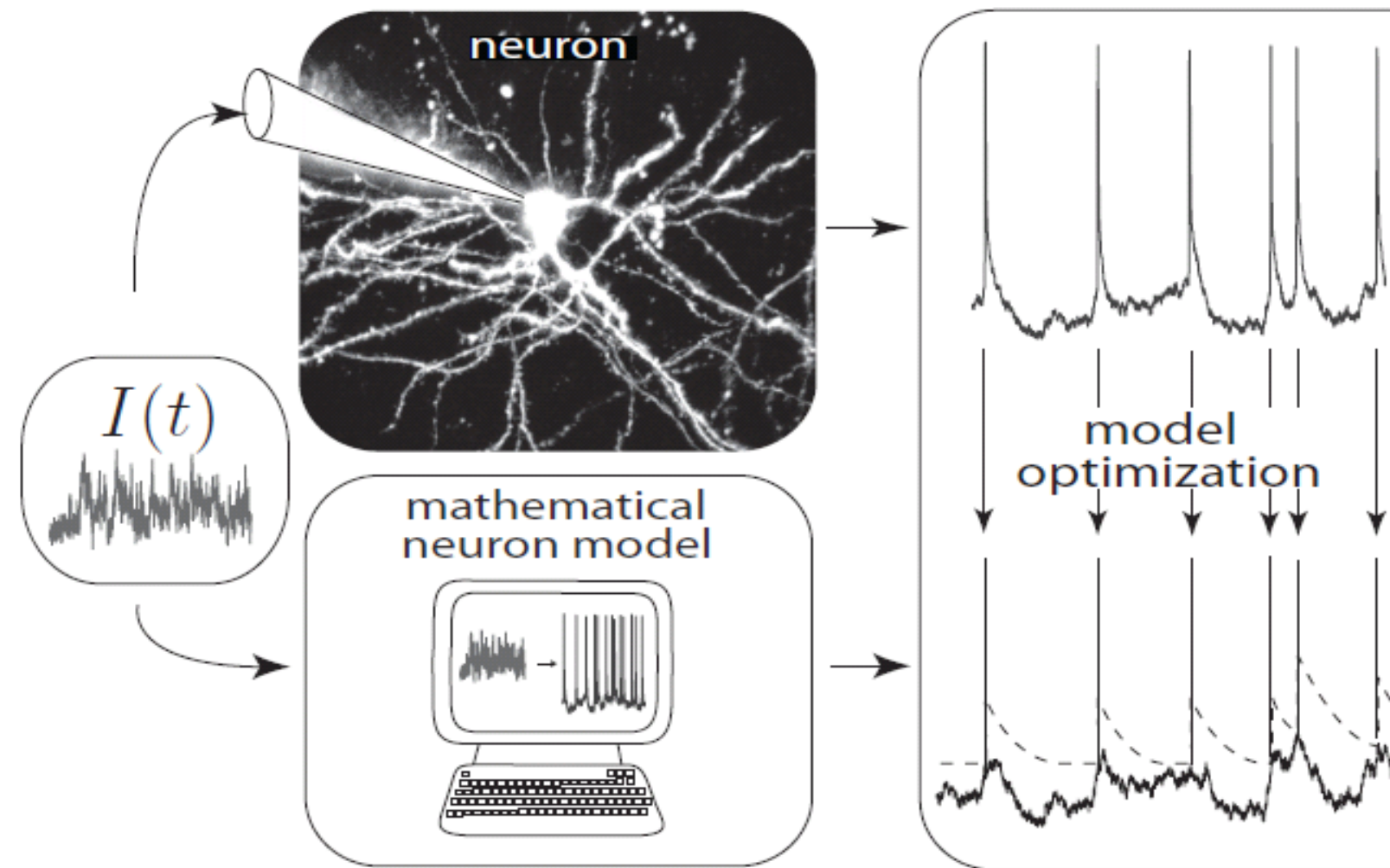
- (- Quadratic and convex optimization)

9.6. Modeling in vitro data

- how long lasts the effect of a spike?

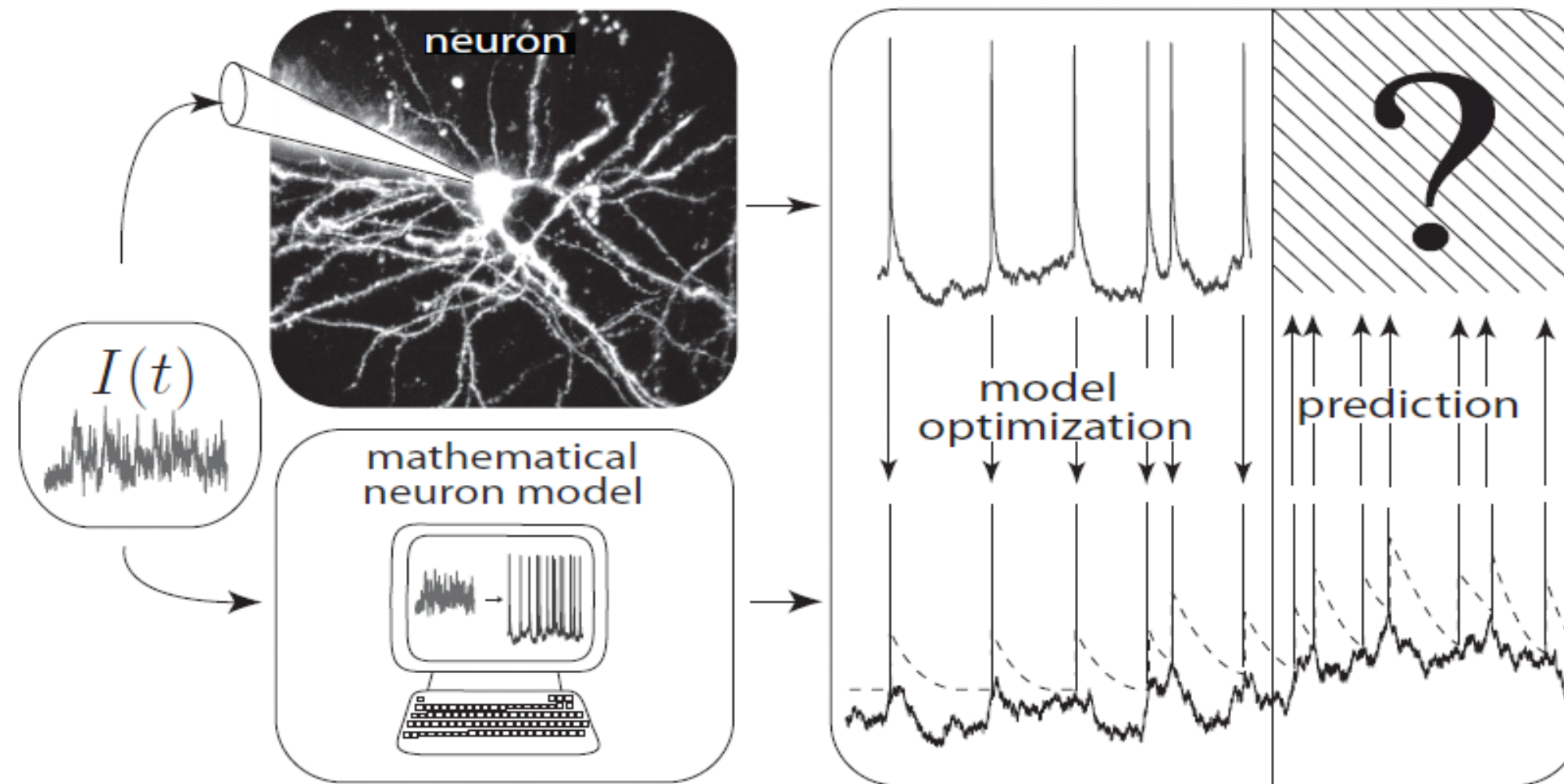
9.7. Helping humans – in vivo data

Neuronal Dynamics – 9.1 Neuron Models and Data



- What is a good neuron model?
- Estimate parameters of models?

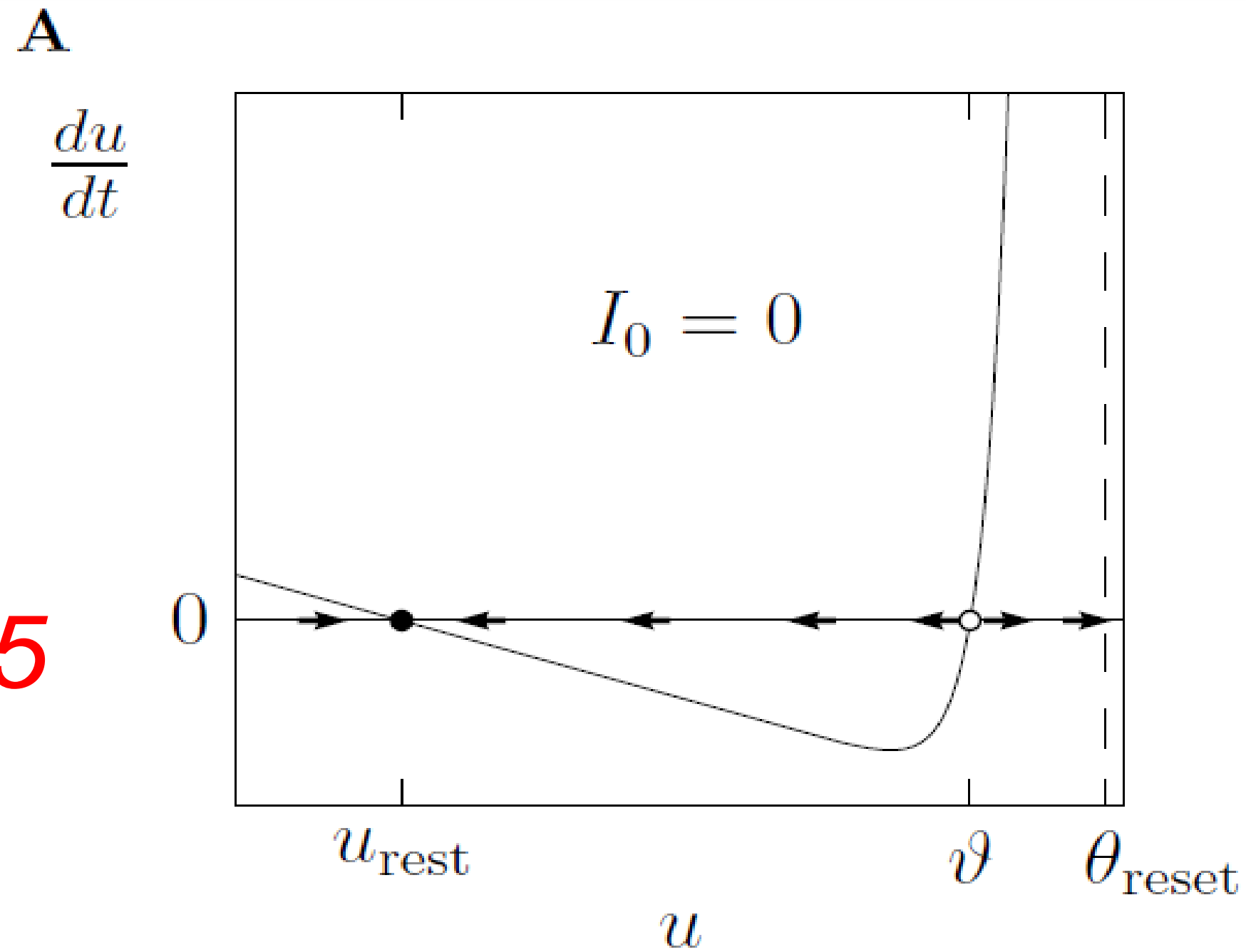
Neuronal Dynamics – 9.1 What is a good neuron model?



- A) Predict spike times
- B) Predict subthreshold voltage
- C) Easy to interpret (not a 'black box')
- D) Flexible enough to account for a variety of phenomena
- E) Systematic procedure to 'optimize' parameters

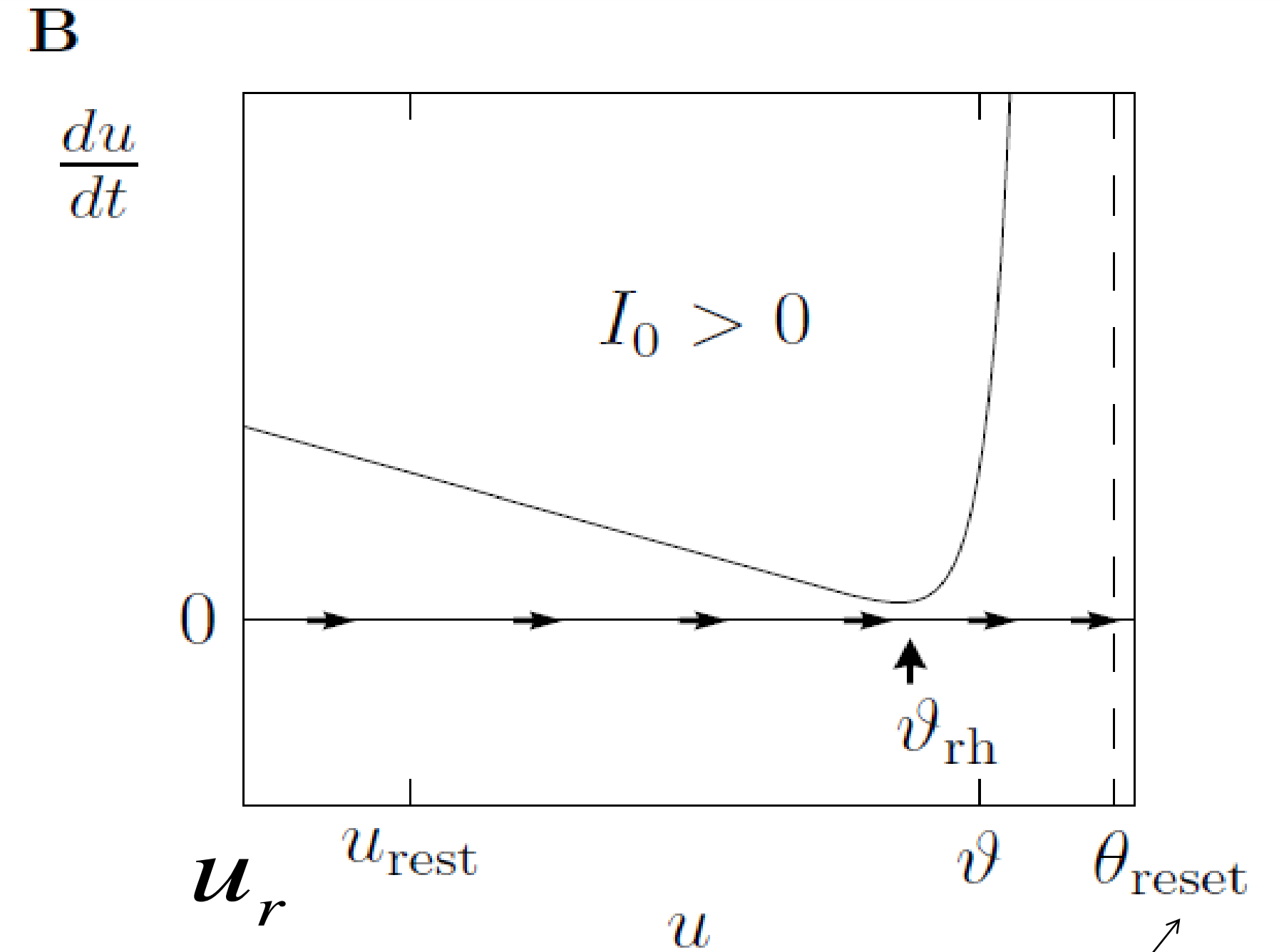
Neuronal Dynamics – Review: Nonlinear Integrate-and-fire

See:
week 1,
lecture 1.5



$$\tau \frac{du}{dt} = f(u) + RI(t)$$

What is a good choice of **f** ?



If $u = \theta_{\text{reset}}$

then reset to

$$u = u_r$$

Neuronal Dynamics – Review: Nonlinear Integrate-and-fire

$$(1) \quad \tau \frac{du}{dt} = f(u) + RI(t)$$

(2) *If $u = \theta_{reset}$ then reset to $u = u_r$*

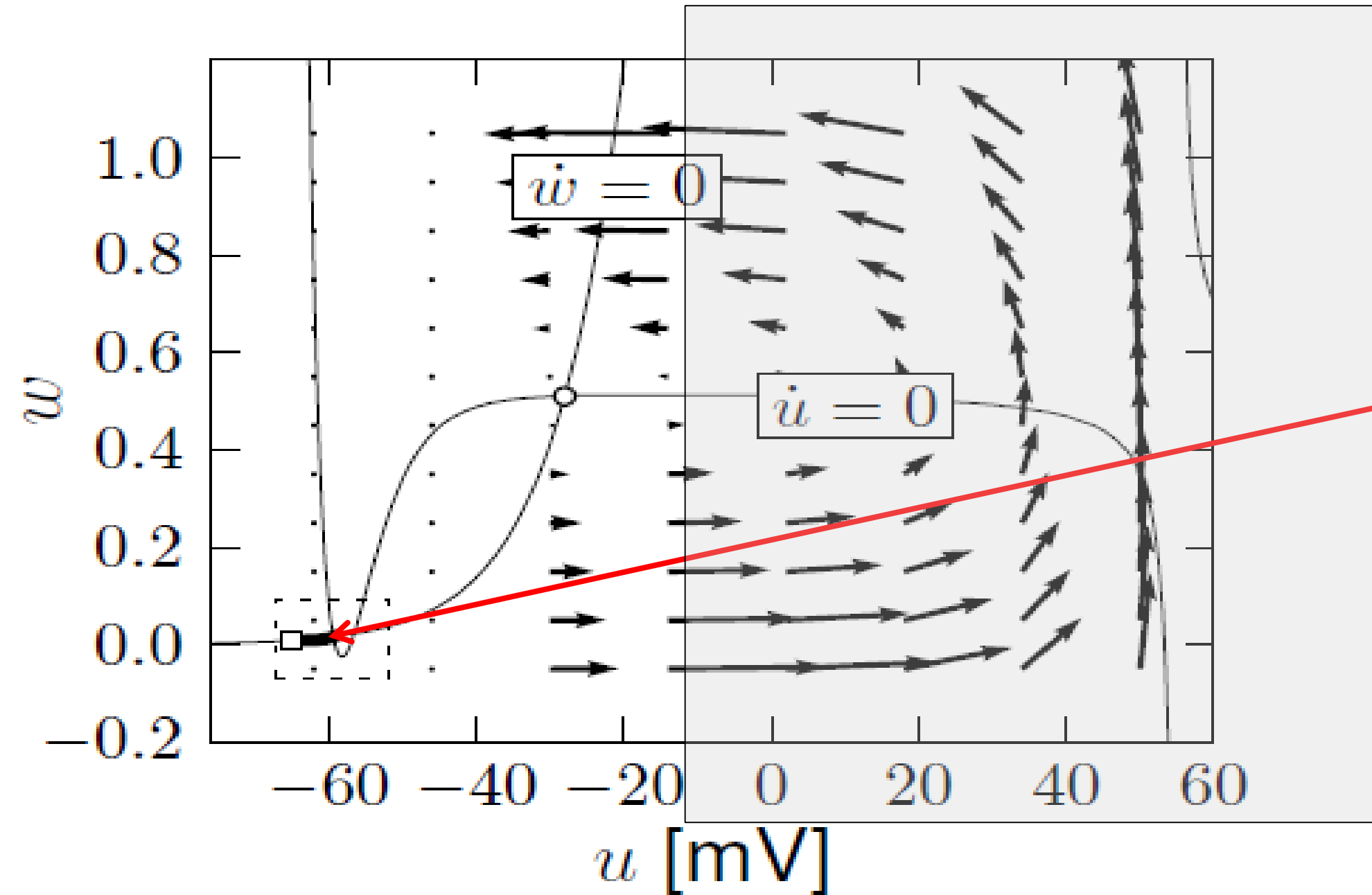
What is a good choice of ***f*** ?

- (i) Extract *f* from more complex models
- (ii) Extract *f* from data

Neuronal Dynamics – Review: 2-dim neuron models

(i) Extract f from more complex models

$$\tau \frac{du}{dt} = f(u) + RI(t)$$



A. detect spike and reset
resting state

Separation of time scales:
Arrows are nearly horizontal

Spike initiation, from rest

$$\tau \frac{du}{dt} = F(u, w) + RI(t)$$

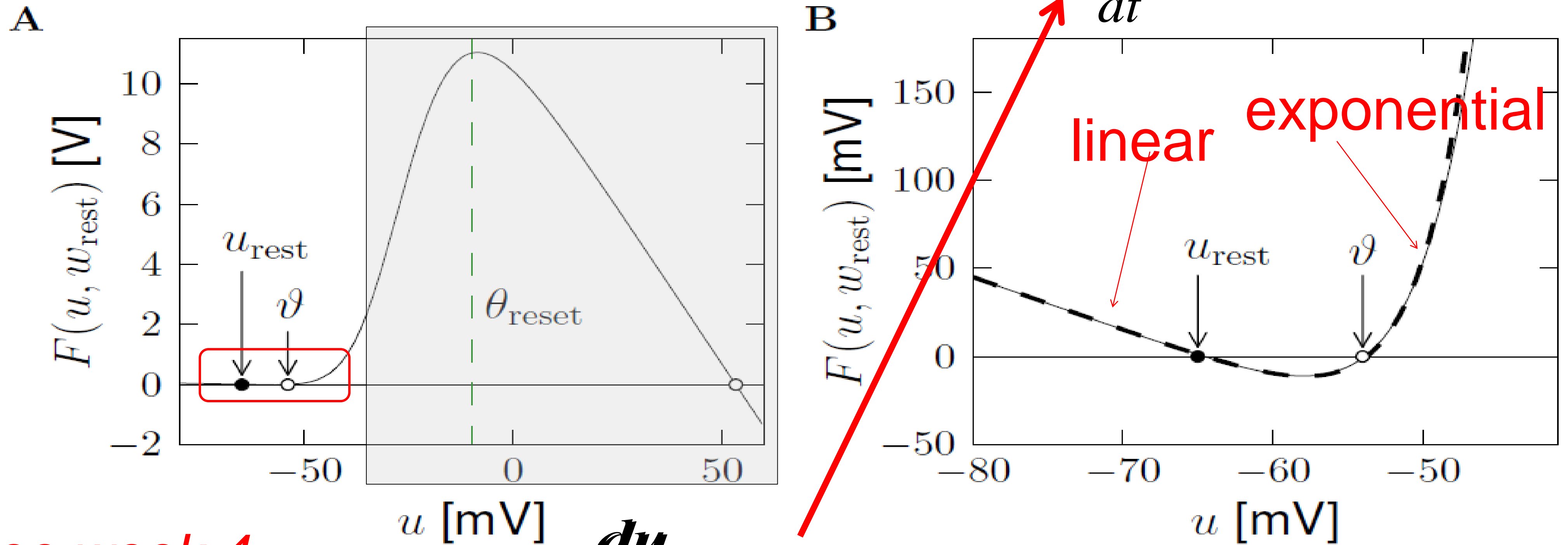
$$w \approx w_{rest}$$

$$\tau_w \frac{dw}{dt} = G(u, w)$$

B. Assume $w = w_{rest}$

Neuronal Dynamics – Review: Nonlinear Integrate-and-fire

(i) Extract f from more complex models $\tau \frac{du}{dt} = f(u) + RI(t)$



See week 4:
2dim version of
Hodgkin-Huxley

$$\tau \frac{du}{dt} = F(u, w_{rest}) + RI(t)$$

Separation of time scales

$$\tau_w \frac{dw}{dt} = G(u, w) \longrightarrow w \approx w_{rest}$$

Neuronal Dynamics – Review: Nonlinear Integrate-and-fire

(ii) Extract f from data *Badel et al. (2008)*

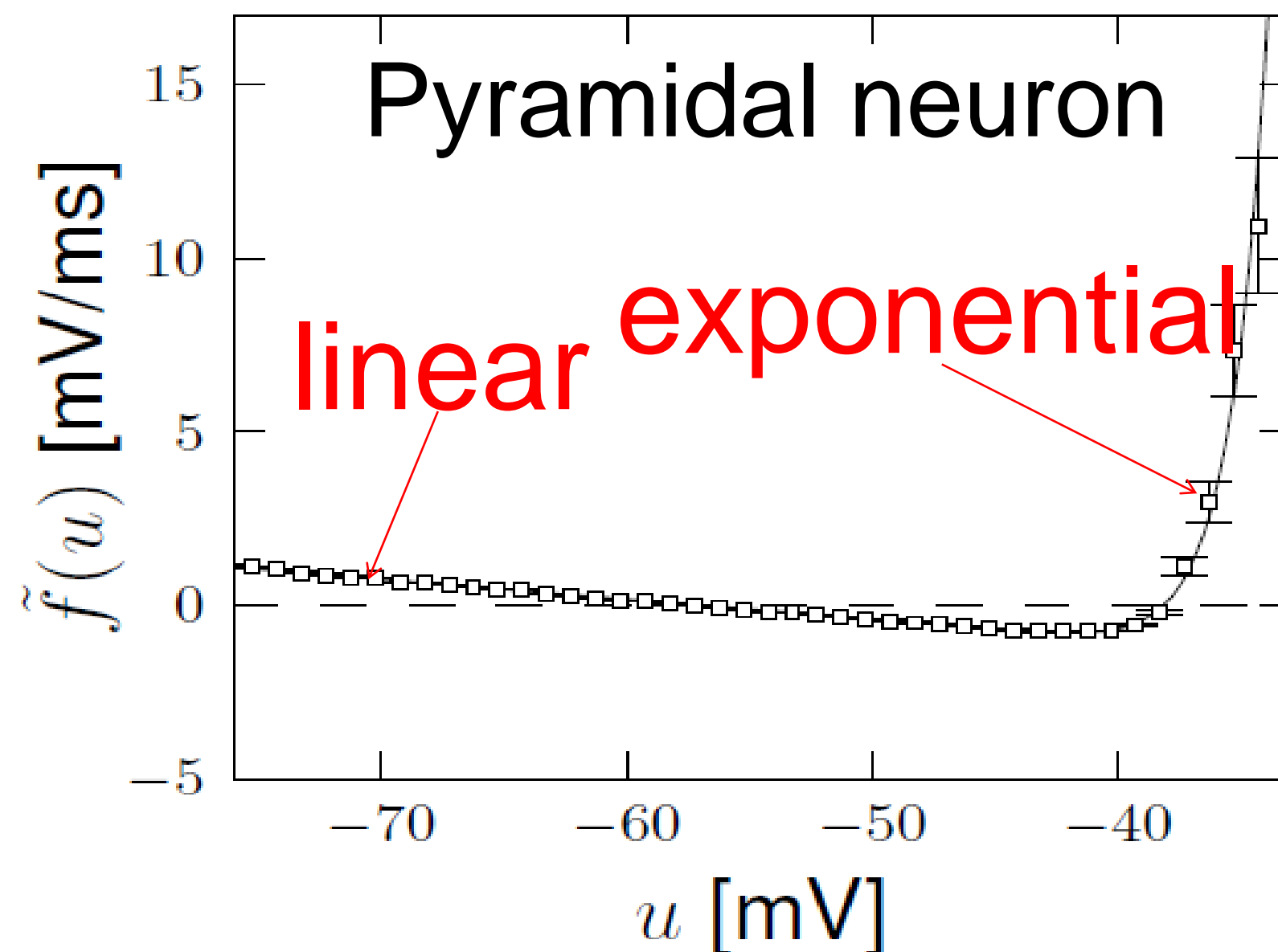
$$\tau \frac{du}{dt} = f(u) + RI(t)$$

$$\tilde{f}(u) = \frac{f(u)}{\tau}$$

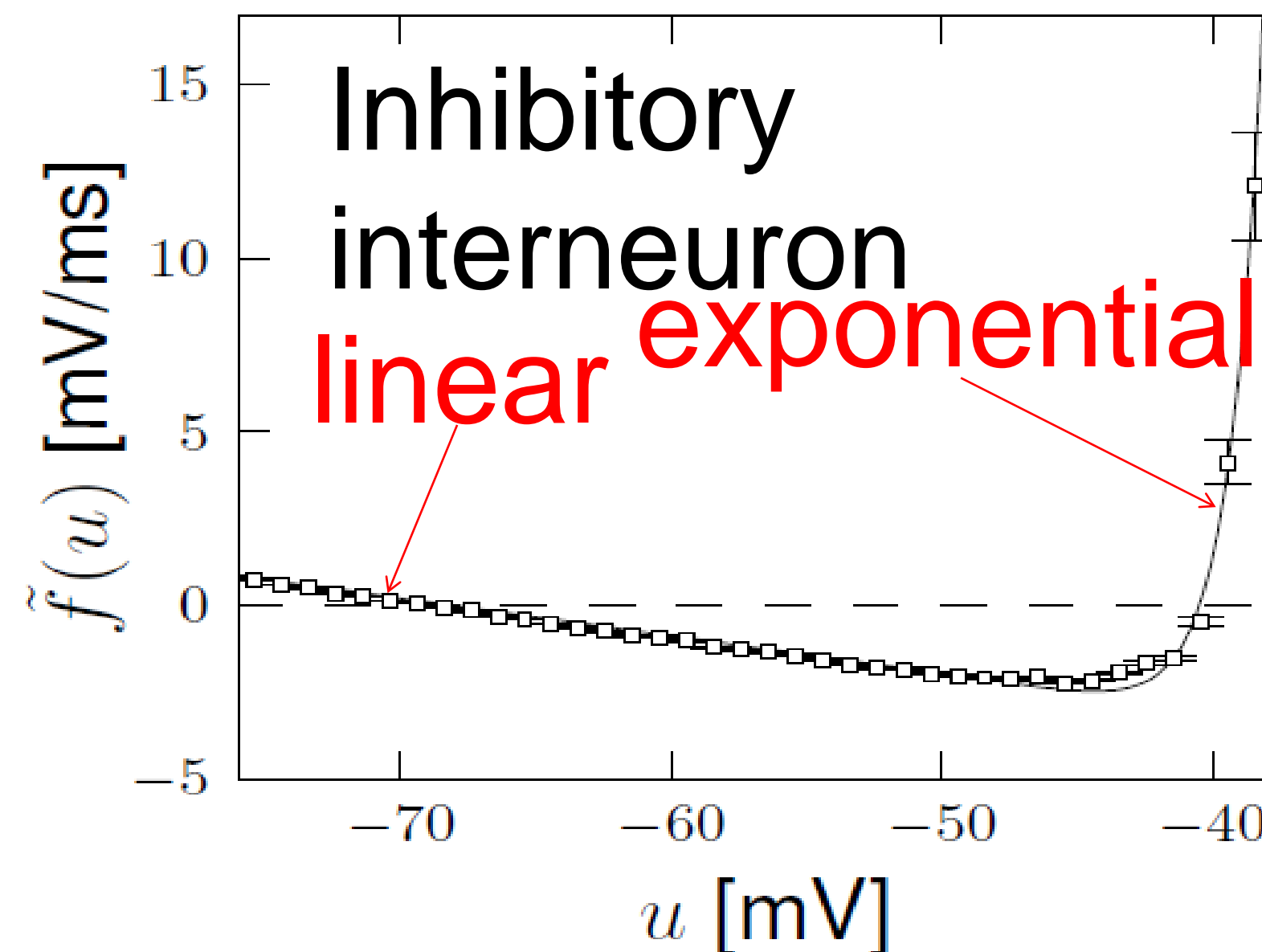
$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \mathcal{V}}{\Delta}\right)$$

Exp. Integrate-and-Fire, *Fourcaud et al. 2003*

A



B



*Badel et al.
(2008)*

Neuronal Dynamics – Review: Nonlinear Integrate-and-fire

$$(1) \quad \tau \frac{du}{dt} = f(u) + RI(t)$$

$$(2) \quad \text{If } u = \theta_{reset} \text{ then reset to } u = u_r$$

Best choice of f : linear + exponential

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \mathcal{I}}{\Delta}\right)$$

BUT: Limitations – need to add

- Adaptation on slower time scales
- Possibility for a diversity of firing patterns
- Increased threshold \mathcal{I} after each spike
- Noise

Week 9 – part 2 : Adaptive Exponential Integrate-and-Fire Model



Biological Modeling of Neural Networks:

Week 9 – Optimizing Neuron Models For Coding and Decoding

Wulfram Gerstner

EPFL, Lausanne, Switzerland

✓ 9.1 What is a good neuron model?

- Models and data

9.2 AdEx model

- Firing patterns and adaptation

9.3 Spike Response Model (SRM)

- Integral formulation

9.4 Generalized Linear Model

- Adding noise to the SRM

9.5 Parameter Estimation

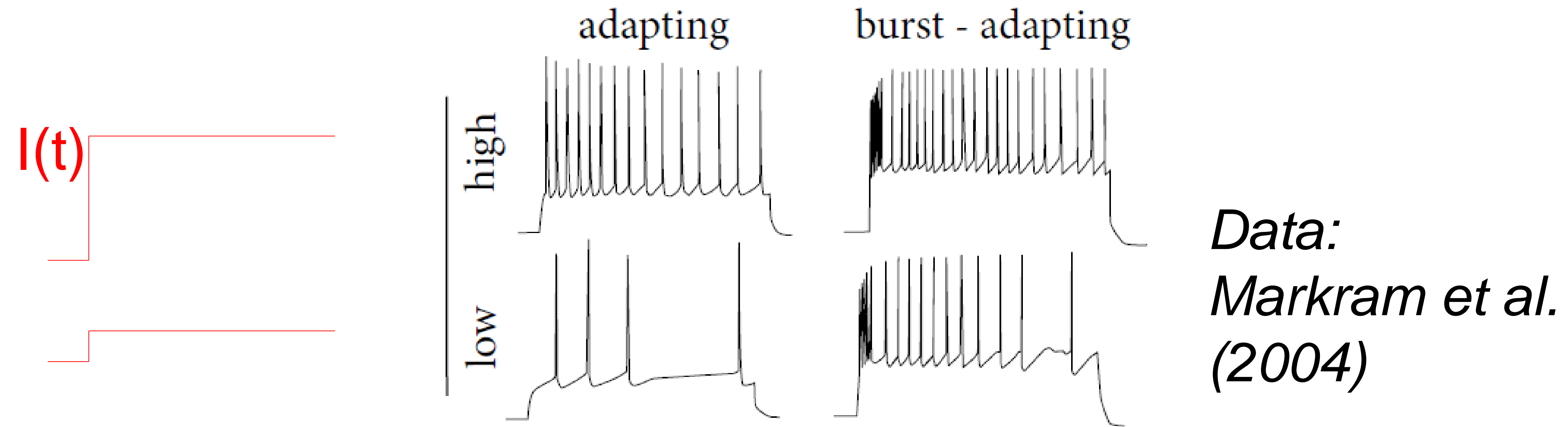
- Quadratic and convex optimization

9.6. Modeling in vitro data

- how long lasts the effect of a spike?

Neuronal Dynamics – 9.2 Adaptation

Step current input – neurons show adaptation



1-dimensional (nonlinear) integrate-and-fire model cannot do this!

Neuronal Dynamics – 9.2 Adaptive Exponential I&F

Add adaptation variables:

Blackboard !

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \vartheta}{\Delta}\right) - R \sum_k w_k$$

$$\tau_k \frac{dw_k}{dt} = a_k (u - u_{rest}) - w_k + b_k \tau_k \sum_f \delta(t - t^f)$$

**Exponential I&F
+ 1 adaptation var.
= AdEx**

**SPIKE AND
RESET**

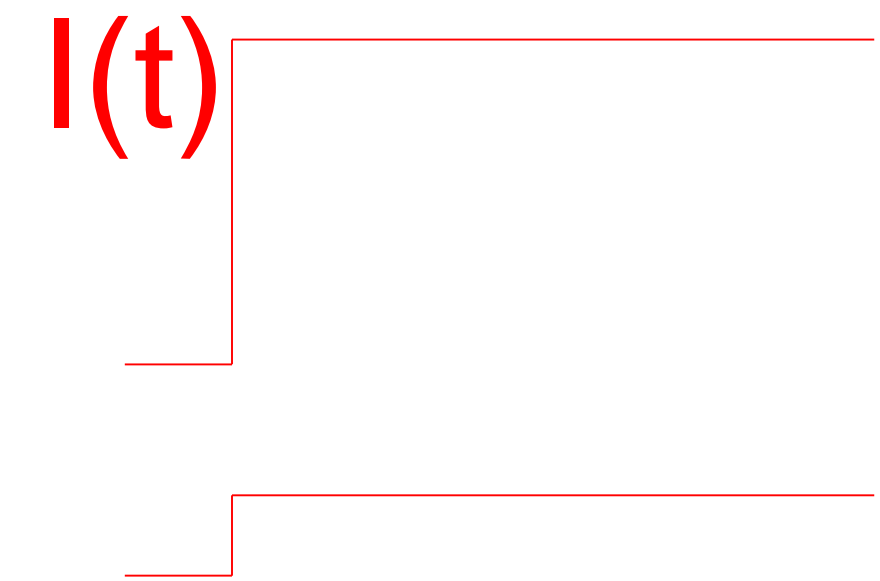
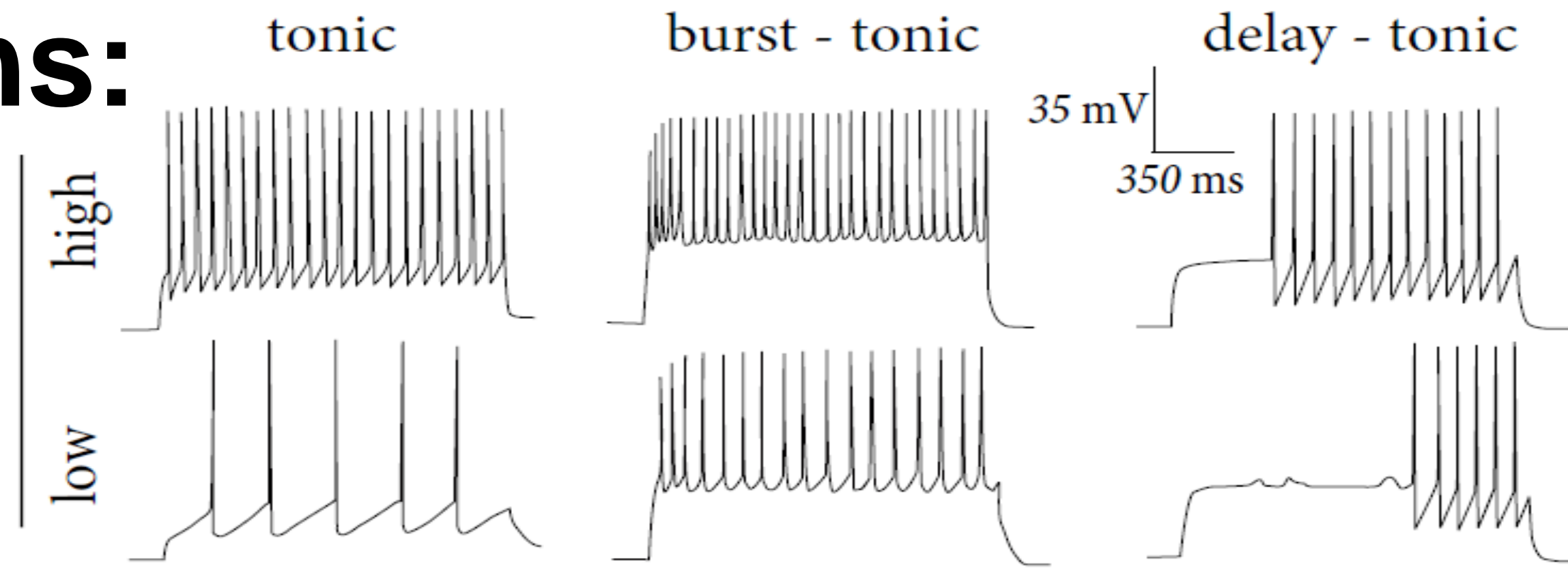
after each spike w_k
jumps by an amount b_k

If $u = \theta_{reset}$ then reset to $u = u_r$

*AdEx model,
Brette & Gerstner (2005):*

Firing patterns:

Response to
Step currents,
Exper. Data,
Markram et al.
(2004)



Firing patterns:

Response to
Step currents,
AdEx Model,
Naud&Gerstner

ERN

tonic

high

low

tonic

intial burst

delay

INITIATION PATTERN

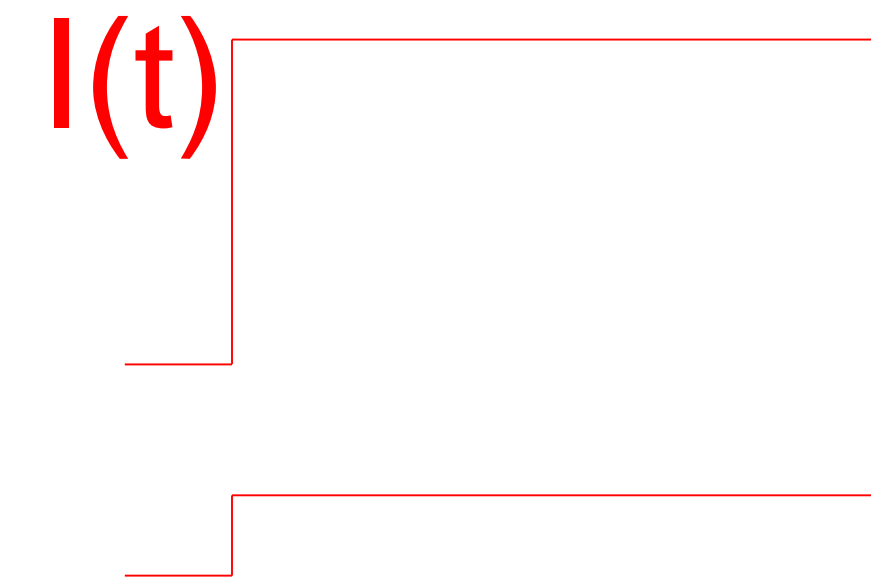


Image:
Neuronal Dynamics,
Gerstner et al.
Cambridge (2002)

Neuronal Dynamics – 9.2 Adaptive Exponential I&F

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \vartheta}{\Delta}\right) - R w + R I(t)$$

$$\tau_w \frac{dw}{dt} = a (u - u_{rest}) - w + b \tau_w \sum_f \delta(t - t^f)$$

AdEx model

Phase plane analysis!

Can we understand the different firing patterns?

Neuronal Dynamics – Quiz 9.1. Nullclines of AdEx

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \vartheta}{\Delta}\right) - R w + R I(t)$$

$$\tau_w \frac{dw}{dt} = a (u - u_{rest}) - w$$

A - What is the qualitative shape of the w-nullcline?

- ☐ constant
- ☐ linear, slope a
- ☐ linear, slope 1
- ☐ linear + quadratic
- ☐ linear + exponential

B - What is the qualitative shape of the u-nullcline?

- ☐ linear, slope 1
- ☐ linear, slope 1/R
- ☐ linear + quadratic
- ☐ linear w. slope 1/R + exponential

3 minutes

Restart at 9:40

Week 9 – part 2b : Firing Patterns



Biological Modeling of Neural Networks:

Week 9 – Optimizing Neuron Models For Coding and Decoding

Wulfram Gerstner

EPFL, Lausanne, Switzerland

9.1 What is a good neuron model?

- Models and data

9.2 AdEx model

- Firing patterns and adaptation

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- Integral formulation

9.4 Generalized Linear Model

- Adding noise to the SRM

9.5 Parameter Estimation

- Quadratic and convex optimization

9.6. Modeling in vitro data

- how long lasts the effect of a spike?

AdEx model

after each spike
 u is reset to u_r

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \mathcal{V}}{\Delta}\right) - R w + RI(t)$$

$$\tau_w \frac{dw}{dt} = a (u - u_{rest}) - w + b \tau_w \sum_f \delta(t - t^f)$$

after each spike
 w jumps by an amount b

parameter a – slope of w -nullcline

Can we understand the different firing patterns?

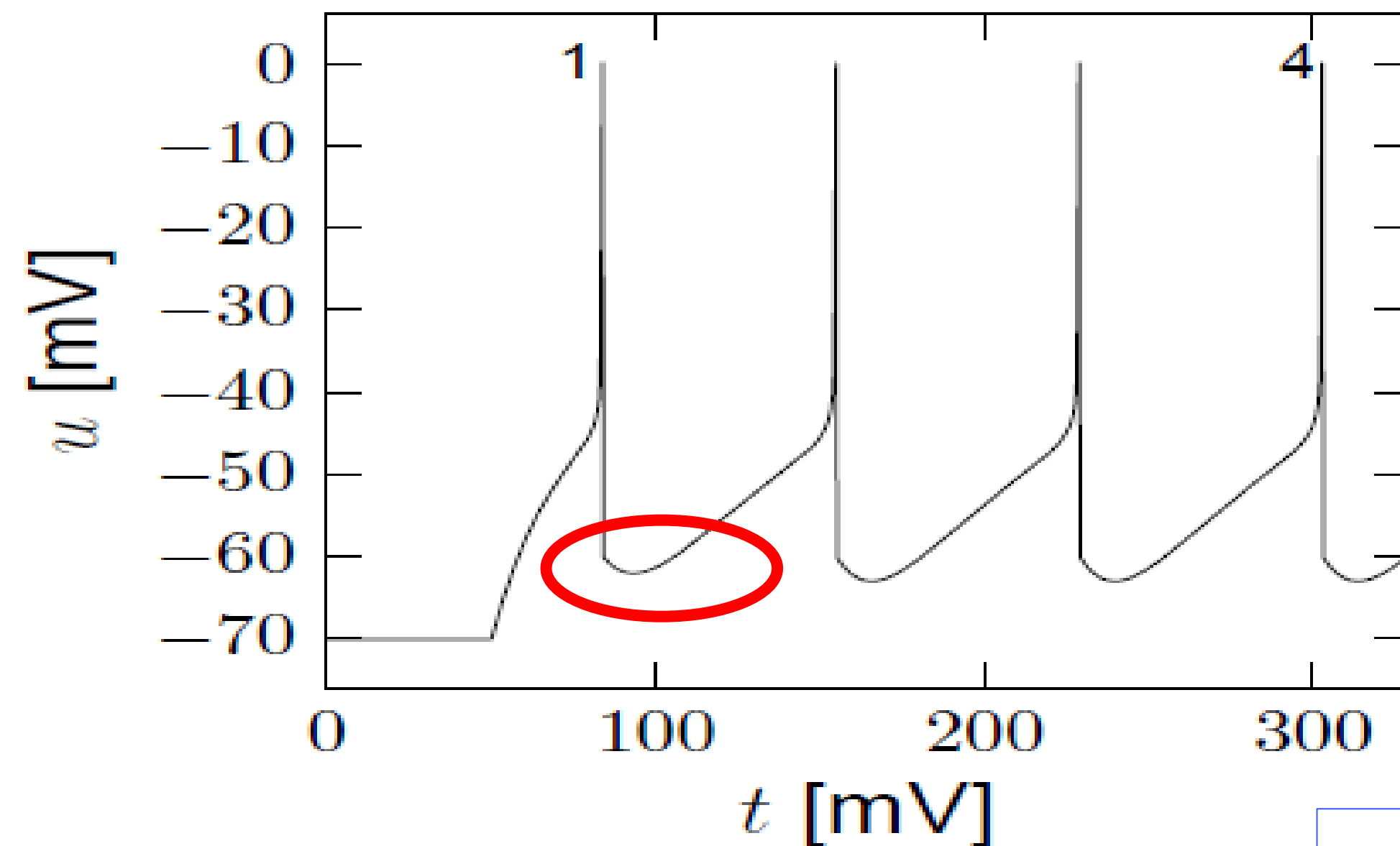
AdEx model – phase plane analysis: **large b**

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \vartheta}{\Delta}\right) + w + RI(t)$$

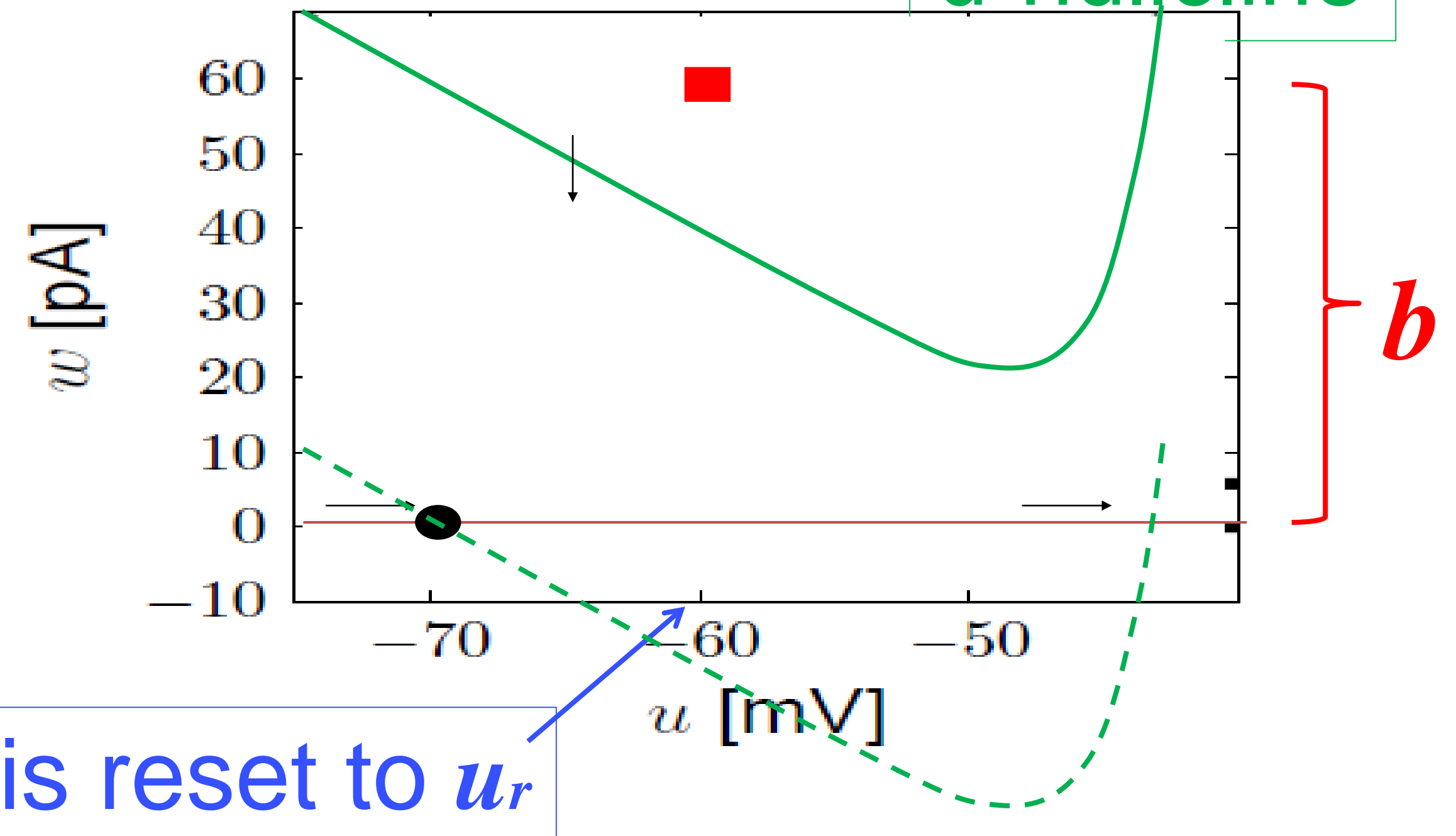
$$\tau_w \frac{dw}{dt} = \cancel{a(u - u_{rest})} - w + b \tau_w \sum_f \delta(t - t^f)$$

$a=0$

A



B



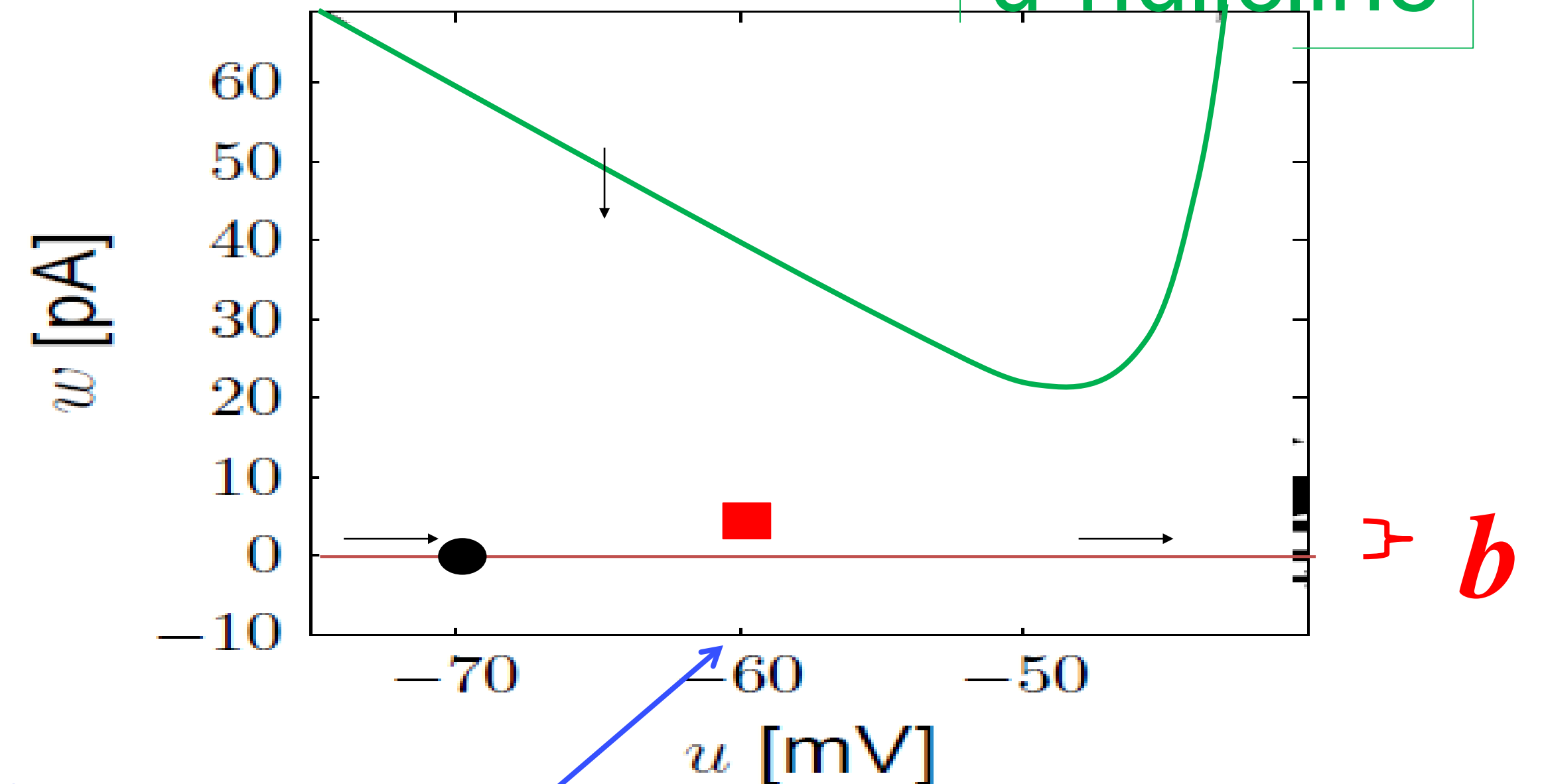
AdEx model – phase plane analysis: **small b**

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \mathcal{V}}{\Delta}\right) + w + RI(t)$$

$$\tau_w \frac{dw}{dt} = a (u - u_{rest}) - w + b \tau_w \sum_f \delta(t - t^f)$$

adaptation

D



u is reset to u_r

Quiz 9.2: AdEx model – phase plane analysis

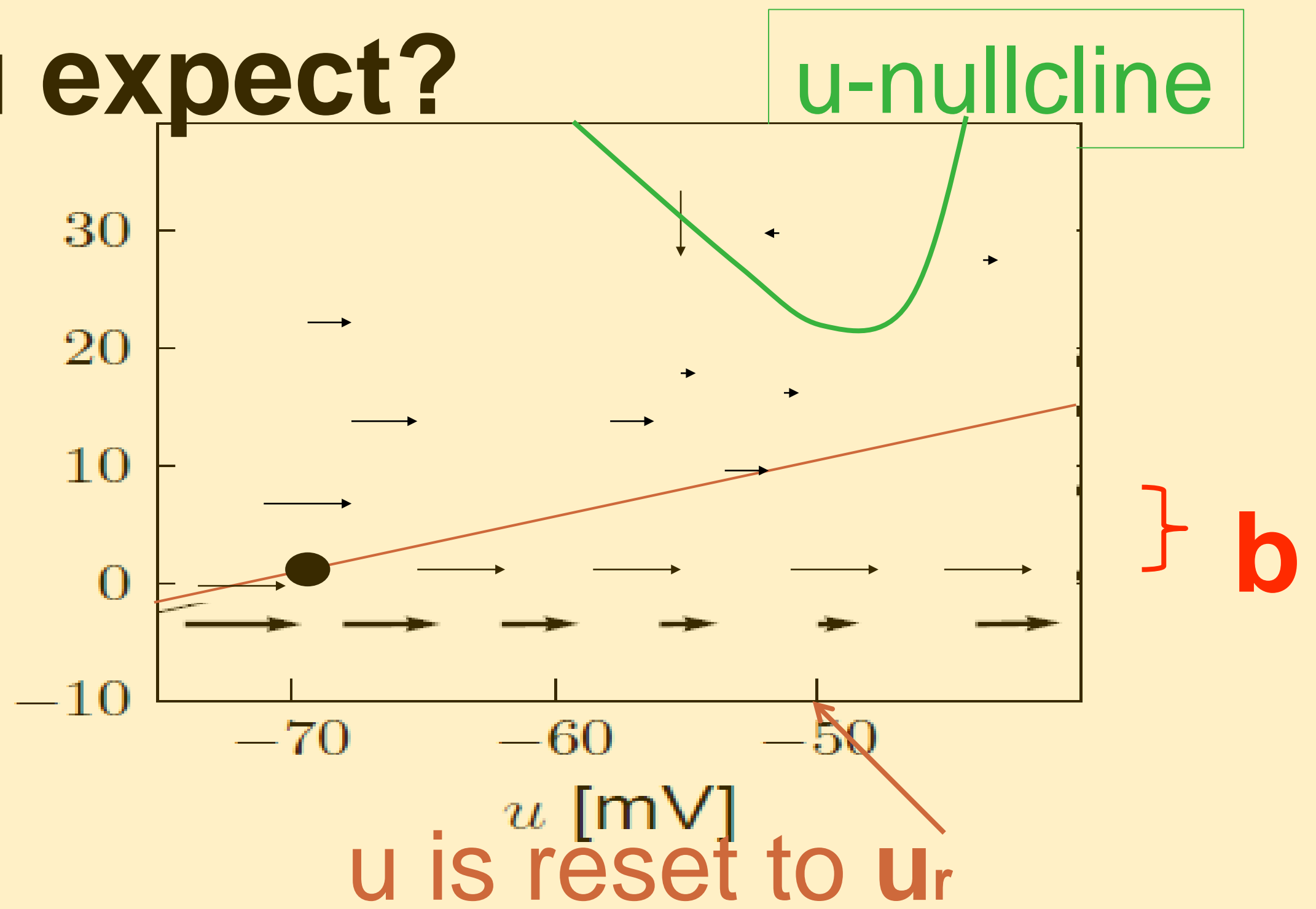
$$\tau_w \gg \tau$$

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \mathcal{G}}{\Delta}\right) + w + RI(t)$$

$$\tau_w \frac{dw}{dt} = a(u - u_{rest}) + b \tau_w \sum_f \delta(t - t^f)$$

What firing pattern do you expect?

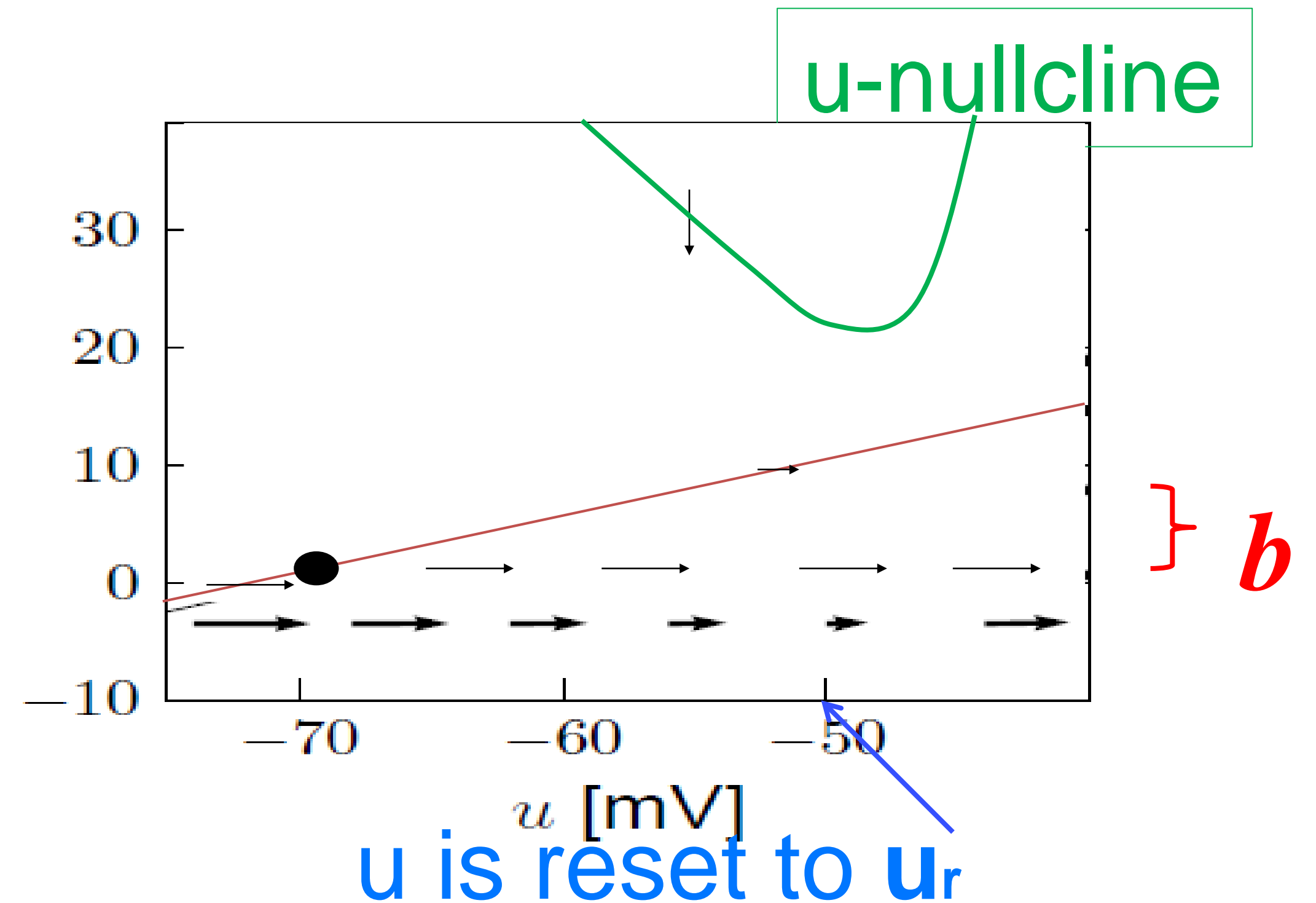
- (i) Adapting
- (ii) Bursting
- (iii) Initial burst
- (iv) Non-adapting



AdEx model – phase plane analysis: **a>0**

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \mathcal{V}}{\Delta}\right) + w + RI(t)$$

$$\tau_w \frac{dw}{dt} = a (u - u_{rest}) - w + b \tau_w \sum_f \delta(t - t^f)$$



Neuronal Dynamics – 9.2 AdEx model and firing patterns

after each spike u is reset to u_r

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \mathcal{U}}{\Delta}\right) - R w + R I(t)$$

$$\tau_w \frac{dw}{dt} = a (u - u_{rest}) - w + b \tau_w \sum_f \delta(t - t^f)$$

after each spike

w jumps by an amount b

Blackboard:
Copy equations

parameter a – slope of w nullcline

Firing patterns arise from different parameters!

See Naud et al. (2008), see also Izhikhevich (2003)

Neuronal Dynamics – Review: Nonlinear Integrate-and-fire

$$(1) \quad \tau \frac{du}{dt} = f(u) + RI(t)$$

(2) *If $u = \theta_{reset}$ then reset to $u = u_r$*

Best choice of f : linear + exponential

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \mathcal{I}}{\Delta}\right)$$

BUT: Limitations – need to add

- ✓ -Adaptation on slower time scales
- ✓ -Possibility for a diversity of firing patterns
- Increased threshold \mathcal{I} after each spike
- Noise

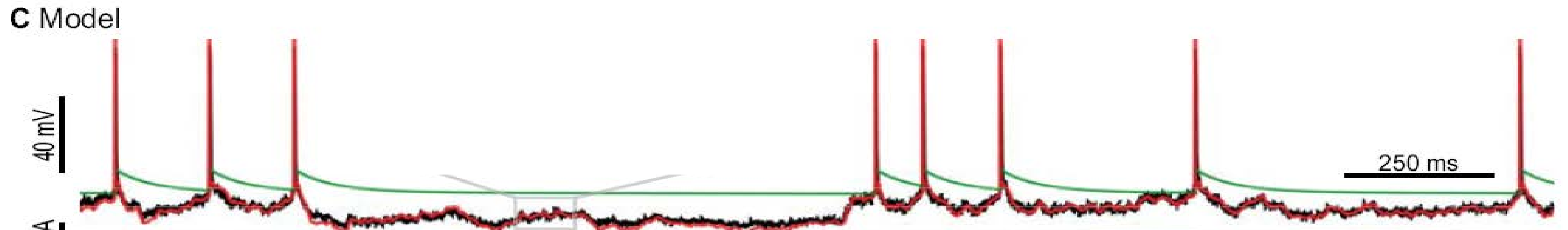
Neuronal Dynamics – 9.2 AdEx with dynamic threshold

Add dynamic threshold:

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \mathcal{G}}{\Delta}\right) - R \sum_k w_k + RI(t)$$

Threshold increases after each spike

$$\mathcal{G} = \theta_0 + \sum_f \theta_1 (t - t^f)$$



Neuronal Dynamics – 9.2 Generalized Integrate-and-fire

$$\tau \frac{du}{dt} = f(u) + RI(t)$$

If $u = \theta_{reset}$ then reset to $u = u_r$

add

- ✓ -Adaptation variables
- ✓ -Possibility for firing patterns
- ✓ -Dynamic threshold \mathcal{I}
- Noise



Use 'escape noise'
(see earlier lecture)

Week 9 – part 3: Spike Response Model (SRM)



Biological Modeling of Neural Networks:

Week 9 – Optimizing Neuron Models For Coding and Decoding

Wulfram Gerstner

EPFL, Lausanne, Switzerland

✓ 9.1 What is a good neuron model?

- Models and data

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- Firing patterns and adaptation

9.3 Spike Response Model (SRM)

- Integral formulation

9.4 Generalized Linear Model

- Adding noise to the SRM

9.5 Parameter Estimation

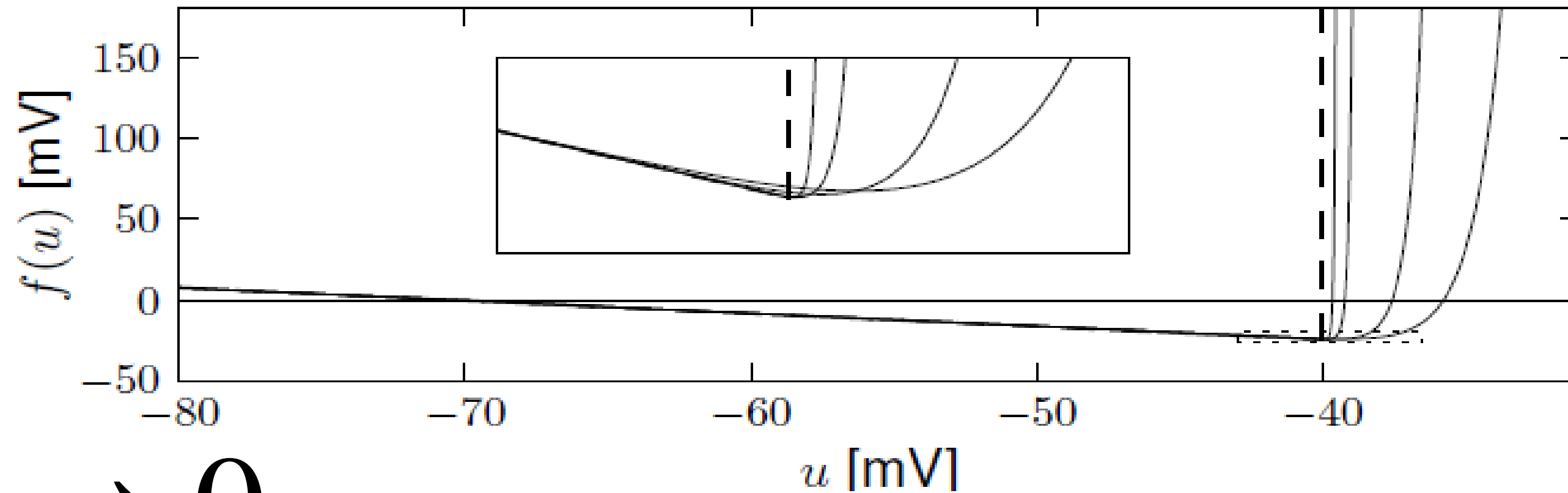
- Quadratic and convex optimization

9.6. Modeling in vitro data

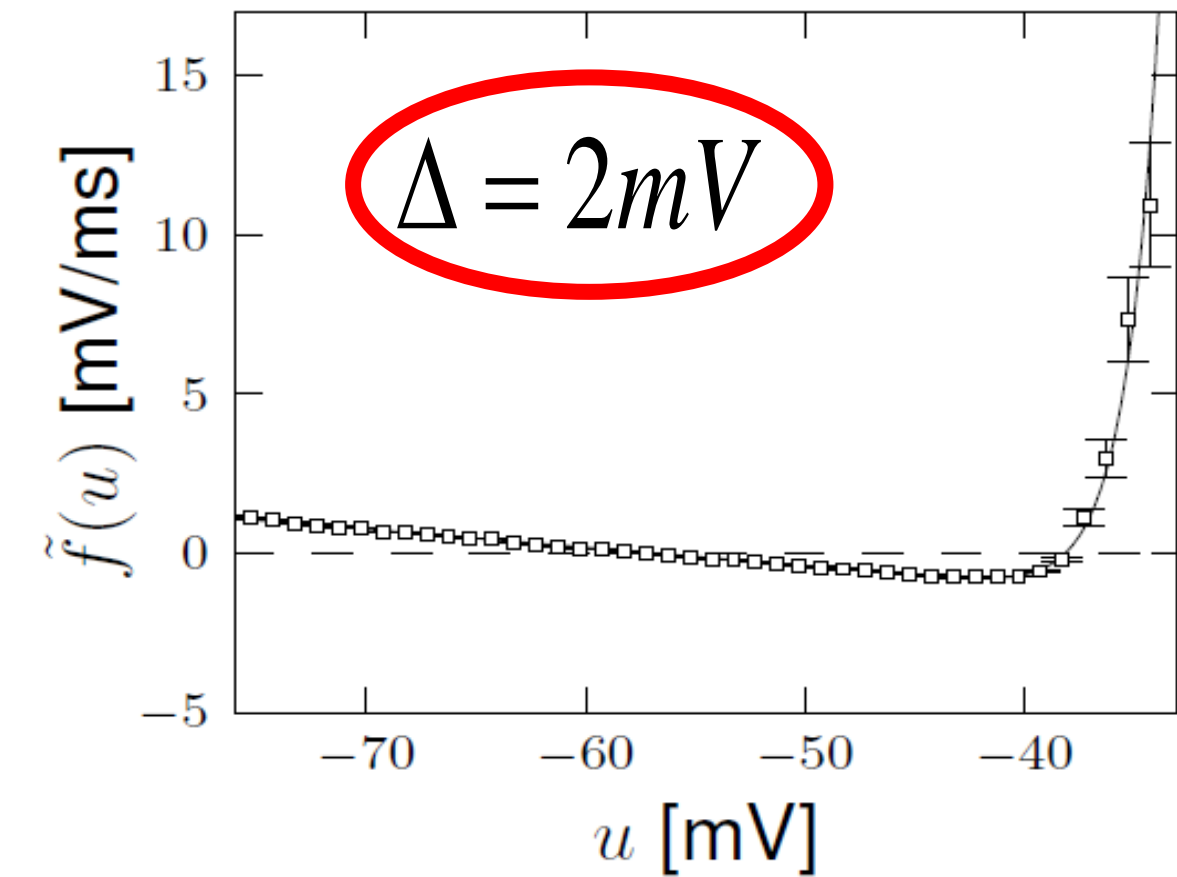
- how long lasts the effect of a spike?

Exponential versus Leaky Integrate-and-Fire

$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \mathcal{V}}{\Delta}\right) + RI(t)$$



Badel et al (2008)
A



$\Delta \rightarrow 0$

$$\tau \frac{du}{dt} = -(u - u_{rest}) + RI(t)$$

Reset if $u = \mathcal{V}$

Leaky Integrate-and-Fire

Neuronal Dynamics – 9.3 Adaptive leaky integrate-and-fire

$$\tau \frac{du}{dt} = -(u - u_{rest}) - R \sum_k w_k + RI(t)$$

$$\tau_k \frac{dw_k}{dt} = a_k (u - u_{rest}) - w_k + b_k \tau_k \sum_f \delta(t - t^f)$$

SPIKE AND
RESET

after each spike

w_k jumps by an amount b_k

If $u = \vartheta(t)$ then reset to $u = u_r$

Dynamic threshold

Exercise 1: from adaptive IF to SRM

$$\tau \frac{du}{dt} = -(u - u_{rest}) - R \alpha w + RI(t), \quad \alpha = \{0, 1\}$$

If $u = \mathcal{I}$ then reset to $u = u_r$

$$\tau_w \frac{dw}{dt} = -w + b \tau_w \sum_f \delta(t - t^f)$$

Start before break
Next lecture at 10:20

Integrate the above system of two differential equations so as to rewrite the equations as

potential $u(t) = \int_0^\infty \underline{\eta(s)} S(t-s) ds + \int_0^\infty \underline{\varepsilon(s)} I(t-s) ds + u_{rest}$

Hint: voltage reset equivalent to short current pulse

A – what is $\underline{\eta(s)}$? (i) $x(s) = \frac{R}{\tau} \exp(-\frac{s}{\tau})$ (ii) $x(s) = \frac{R}{\tau_w} \exp(-\frac{s}{\tau_w})$

B – what is $\underline{\varepsilon(s)}$? (iii) $x(s) = C[\exp(-\frac{s}{\tau}) - \exp(-\frac{s}{\tau_w})]$ (iv) **Combi of (i) + (iii)**

Neuronal Dynamics – 9.3 Adaptive leaky I&F and SRM

$$\tau \frac{du}{dt} = -(u - u_{rest}) - R \sum_k w_k + RI(t)$$
$$\tau_k \frac{dw_k}{dt} = a_k (u - u_{rest}) - w_k + b_k \tau_k \sum_f \delta(t - t^f)$$

Adaptive
leaky I&F

Linear equation → can be integrated!

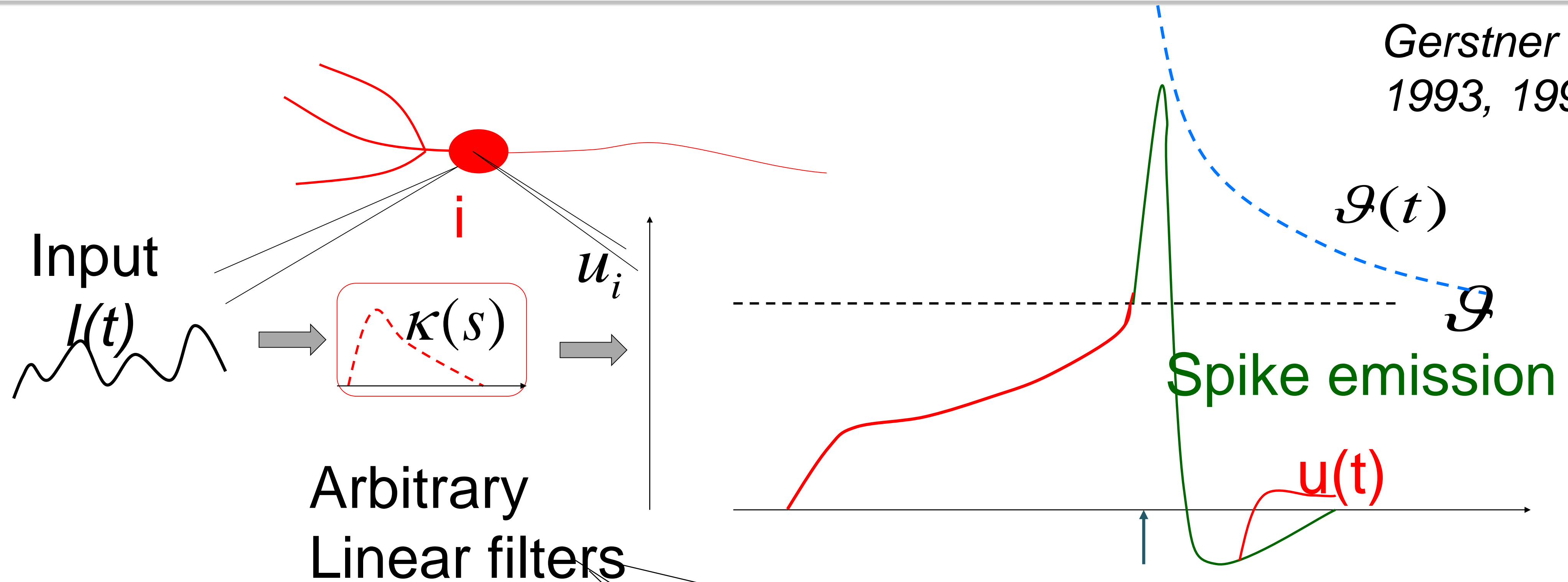
$$u(t) = \sum_f \eta (t - t^f) + \int_0^\infty ds \kappa(s) I(t - s)$$

$$\mathcal{I}(t) = \theta_0 + \sum_f \theta_1 (t - t^f)$$

Spike Response Model (SRM)
Gerstner et al. (1996)

Neuronal Dynamics – 9.3 Spike Response Model (SRM)

*Gerstner et al.,
1993, 1996*



potential

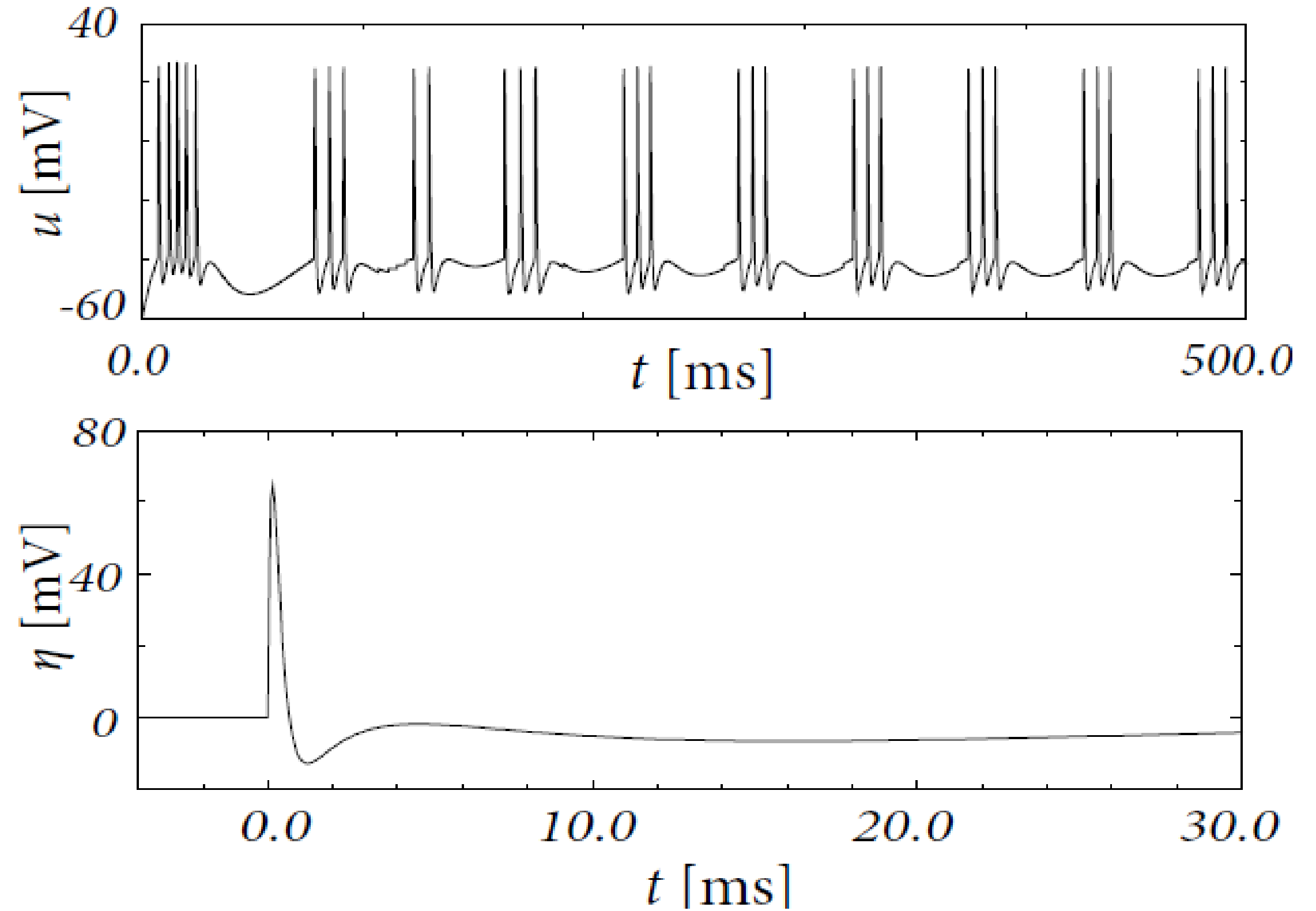
$$u(t) = \sum_{t'} \eta(t - t') + \int_0^\infty \kappa(s) I(t - s) ds + u_{rest}$$

threshold

$$\mathcal{G}(t) = \theta_0 + \sum_{t'} \theta_1(t - t')$$

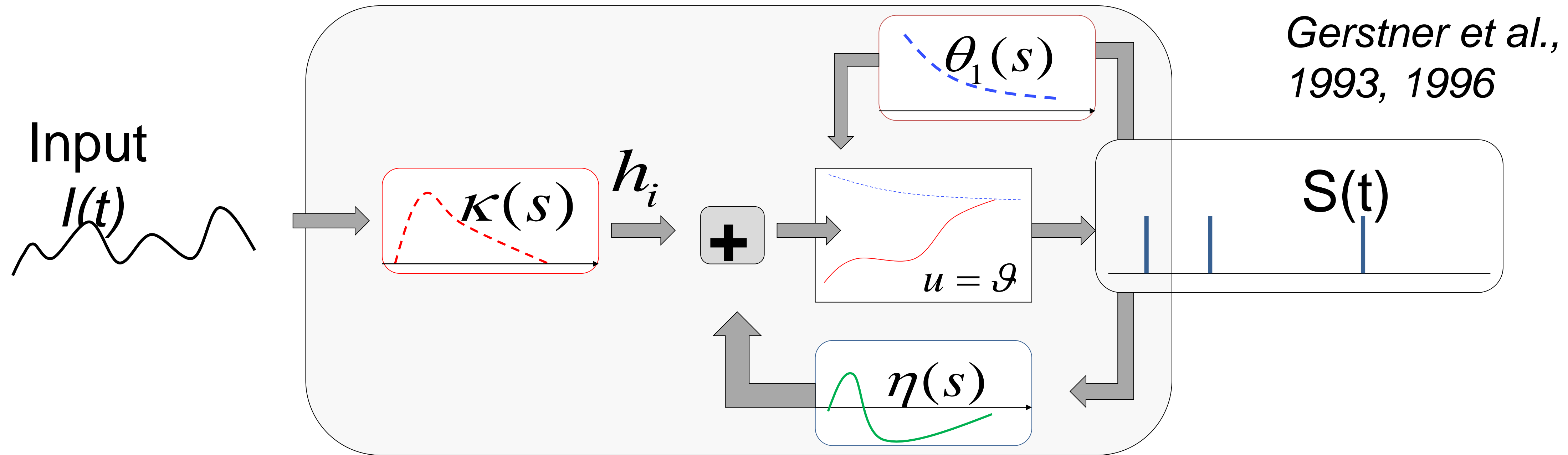
Neuronal Dynamics – 9.3 Bursting in the SRM

**SRM with appropriate η
leads to bursting**



$$u(t) = \sum_f \eta(t - t^f) + \int_{-\infty}^{\infty} ds \kappa(s) I(t - s) + u_{rest}$$
$$u(t) = \int_0^{\infty} ds \eta(s) S(t - s) + \int_0^{\infty} ds \kappa(s) I(t - s) + u_{rest}$$

Neuronal Dynamics – 9.3 Spike Response Model (SRM)



potential

$$u(t) = \sum_{t'} \underline{\eta(t - t')} + \int_0^\infty \underline{\kappa(s)} I(t - s) ds + u_{rest}$$

threshold

$$\mathcal{G}(t) = \theta_0 + \sum_{t'} \underline{\theta_1(t - t')}$$

firing if

$$u(t) = \mathcal{G}(t)$$

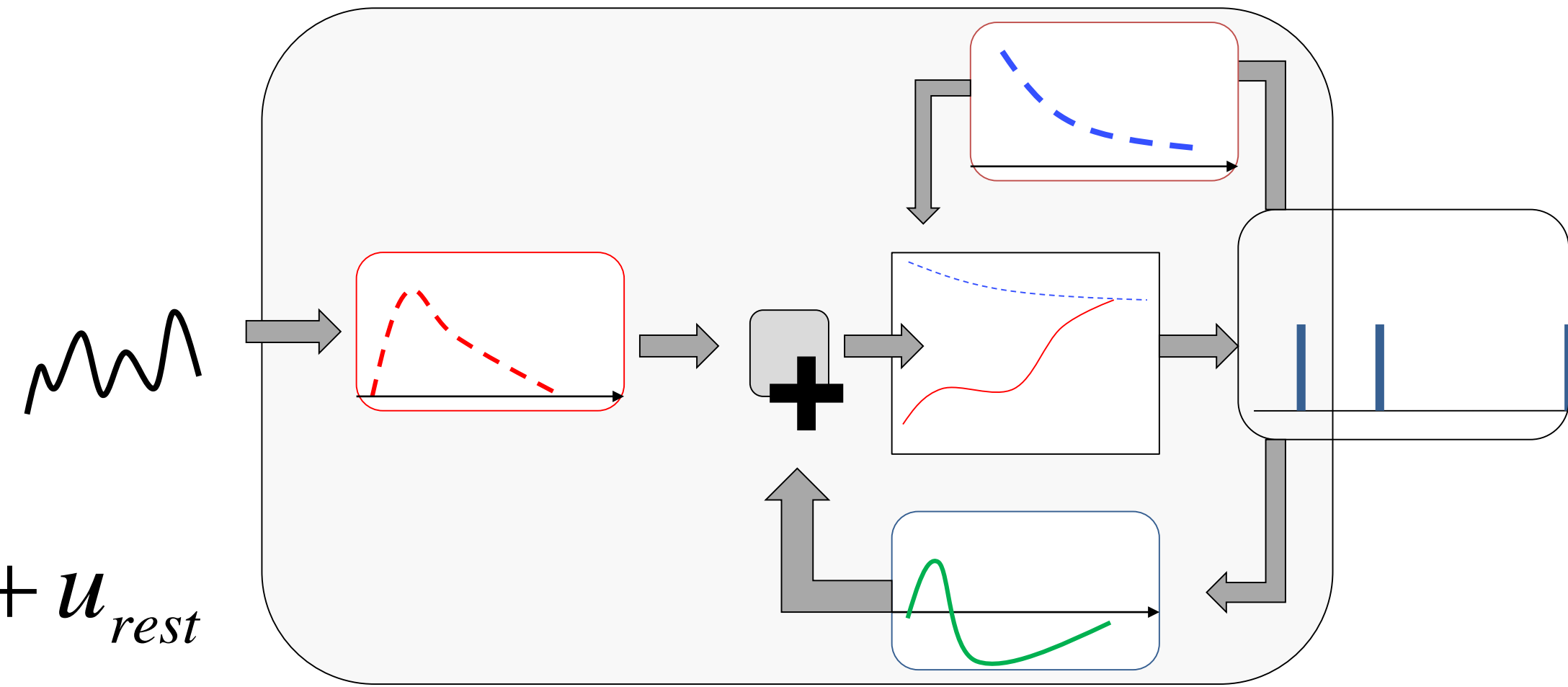
Neuronal Dynamics – 9.3 Spike Response Model (SRM)

potential

$$u(t) = \sum_{t'} \underline{\eta(t-t')} + \int_0^\infty \underline{\kappa(s)} I(t-s) ds + u_{rest}$$

threshold

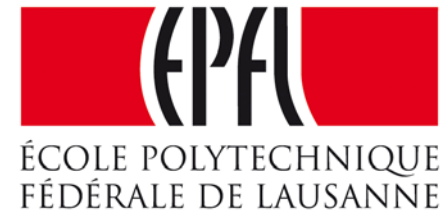
$$\mathcal{G}(t) = \theta_0 + \sum_{t'} \underline{\theta_1(t-t')}$$



Linear filters for

- input
- threshold
- refractoriness

Biological Modeling of Neural Networks:



Week 9 – Optimizing Neuron Models For Coding and Decoding

Wulfram Gerstner

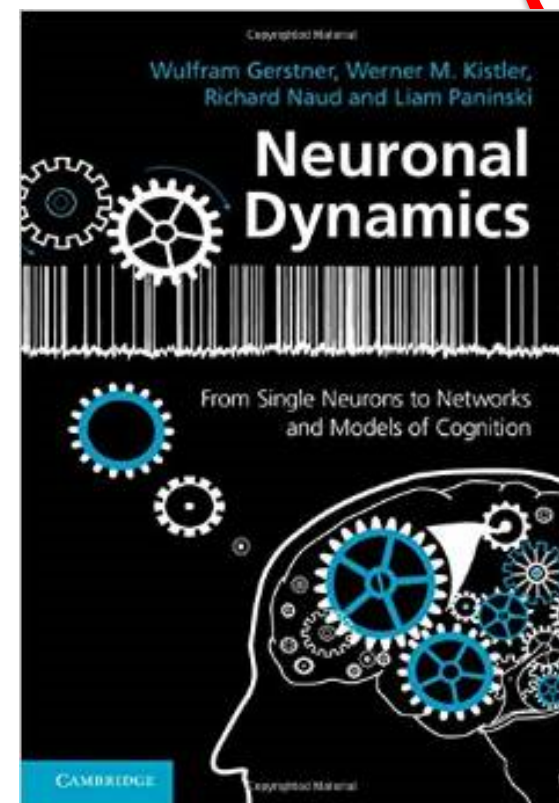
EPFL, Lausanne, Switzerland

Reading for this week:

NEURONAL DYNAMICS

- Ch. 4.6, 6.1, 6.2, 6.4, 9.2
- Ch. 10.2.3, 11.1, 11.3.3

Cambridge Univ. Press



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9.4 Generalized Linear Model

- Adding noise to the SRM
- Likelihood of a spike train

9.5 Parameter Estimation

- Quadratic and convex optimization

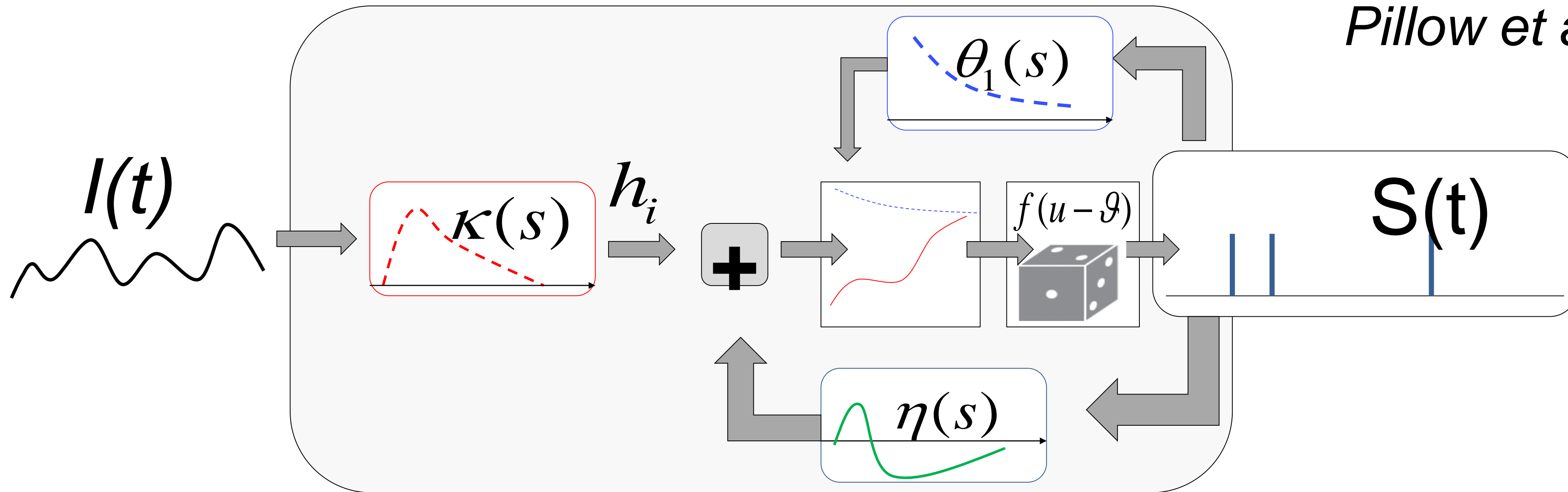
9.6. Modeling in vitro data

- how long lasts the effect of a spike?

Spike Response Model (SRM)

Generalized Linear Model GLM

*Gerstner et al.,
1992, 2000
Truccolo et al., 2005
Pillow et al. 2008*



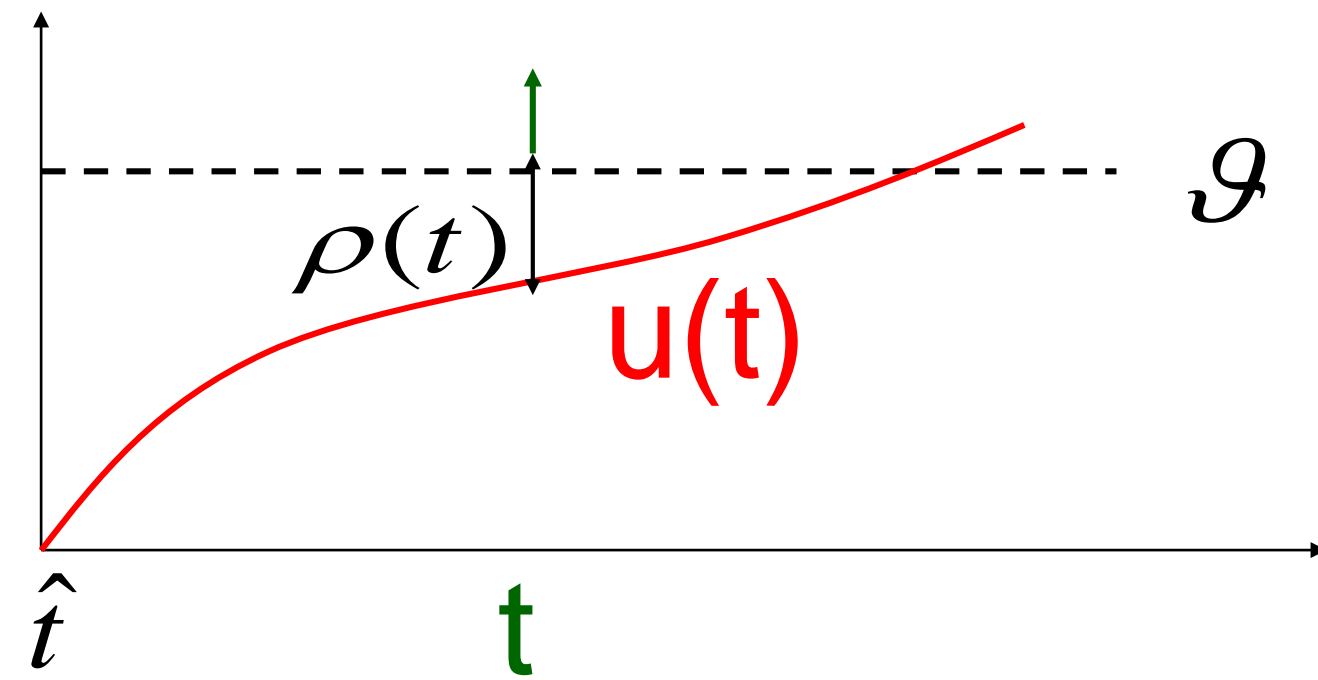
potential $u(t) = \int \underline{\eta(s)} S(t-s) ds + \int_0^\infty \underline{\kappa(s)} I(t-s) ds + u_{rest}$

threshold $\vartheta(t) = \theta_0 + \int \underline{\theta_1(s)} S(t-s) ds$

firing intensity $\rho(t) = f(u(t) - \vartheta(t))$

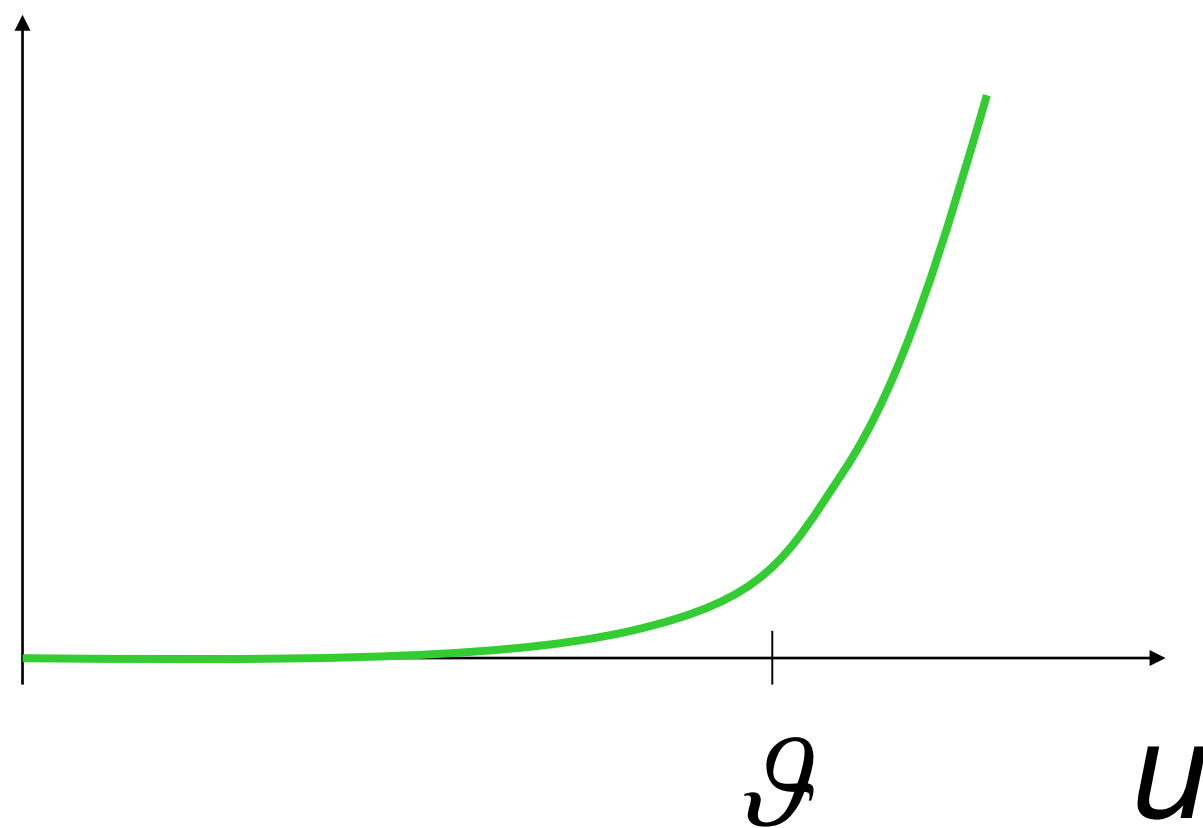
Neuronal Dynamics – review: Escape noise

escape process



escape rate

$$\rho(t) = f(u(t) - \mathcal{G})$$



escape rate

$$\rho(t) = \rho_0 \exp\left(\frac{u(t) - \mathcal{G}}{\Delta}\right)$$

Example: leaky integrate-and-fire model

$$\tau \cdot \frac{d}{dt} u = -(u - u_{rest}) + RI(t)$$

$$\text{if spike at } t^f \Rightarrow u(t^f + \delta) = u_r$$

Exerc. 2.1: Non-leaky IF with escape rates

$$\frac{du}{dt} = \frac{R}{\tau} I(t) = \frac{1}{C} I(t) \quad \text{nonleaky}$$

reset to $u_r = 0$

$$\tau \frac{du}{dt} = -(u - u_{rest}) + RI(t)$$

reset to $u_{rest} = u_r = 0$

Integrate for constant input (repetitive firing)

12 minutes,
Next lecture
at 10:55

Calculate

- potential

$$u(t - \hat{t})$$

- hazard

$$\rho(t - \hat{t}) = \beta \cdot [u(t - \hat{t}) - \mathcal{V}]_+$$

- survivor function

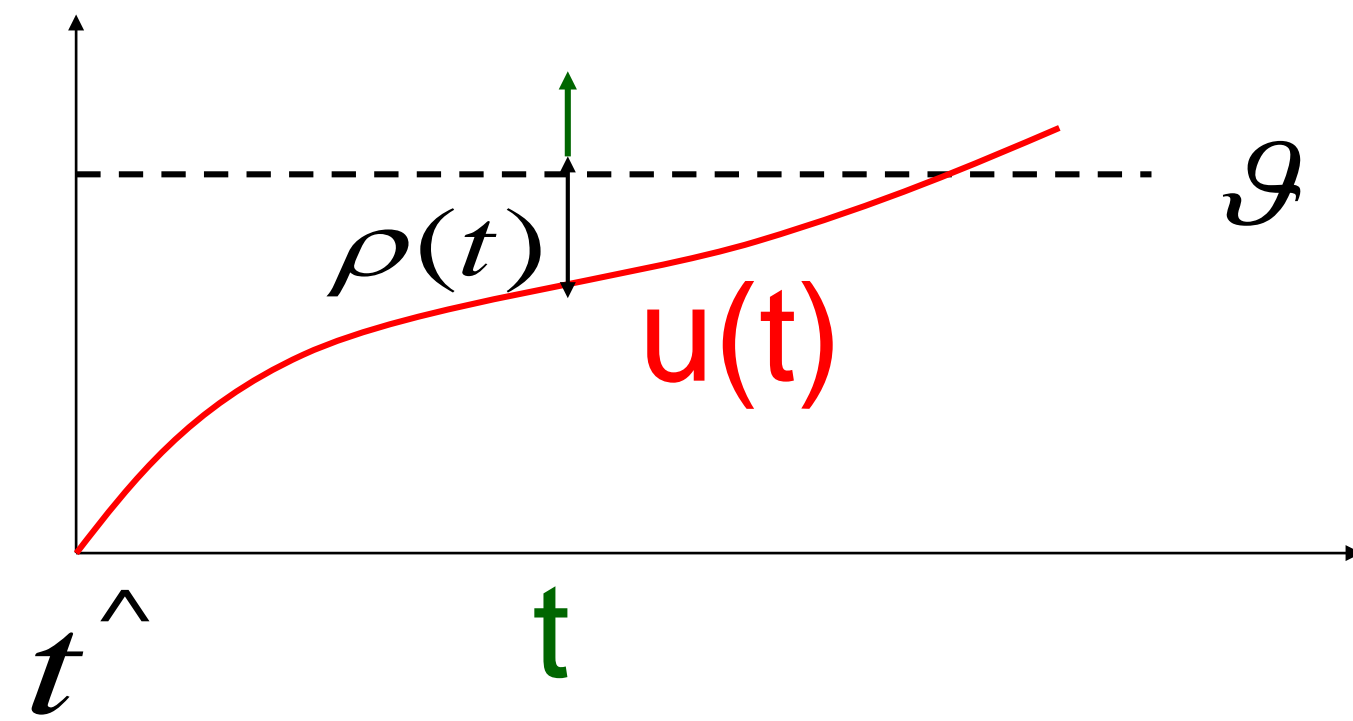
$$S(t - \hat{t})$$

- interval distrib.

$$P_0(t - \hat{t})$$

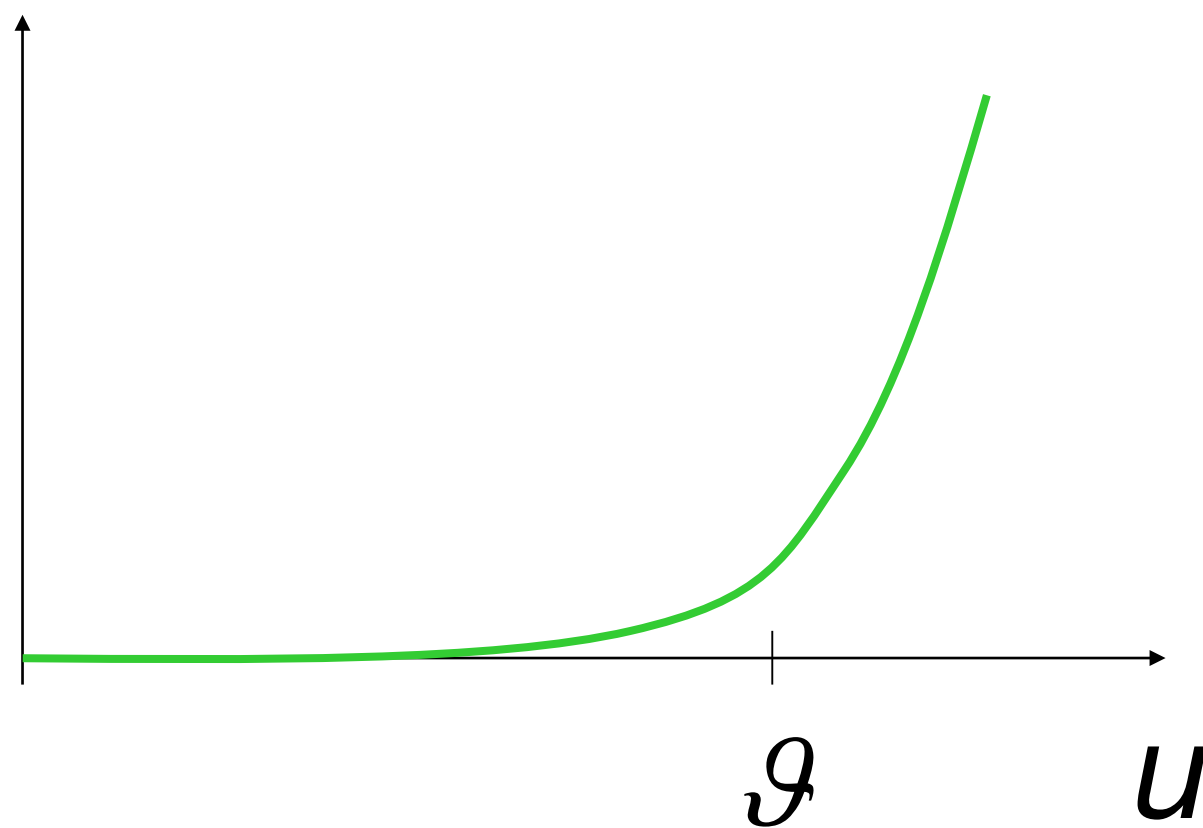
Neuronal Dynamics – review: Escape noise

escape process



escape rate

$$\rho(t) = f(u(t) - \mathcal{G}(t))$$



Survivor function

$$\frac{d}{dt} S_I(t|\hat{t}) = -\rho(t) S_I(t|\hat{t})$$

$$S_I(t|\hat{t}) = \exp\left(-\int_{\hat{t}}^t \rho(t') dt'\right)$$

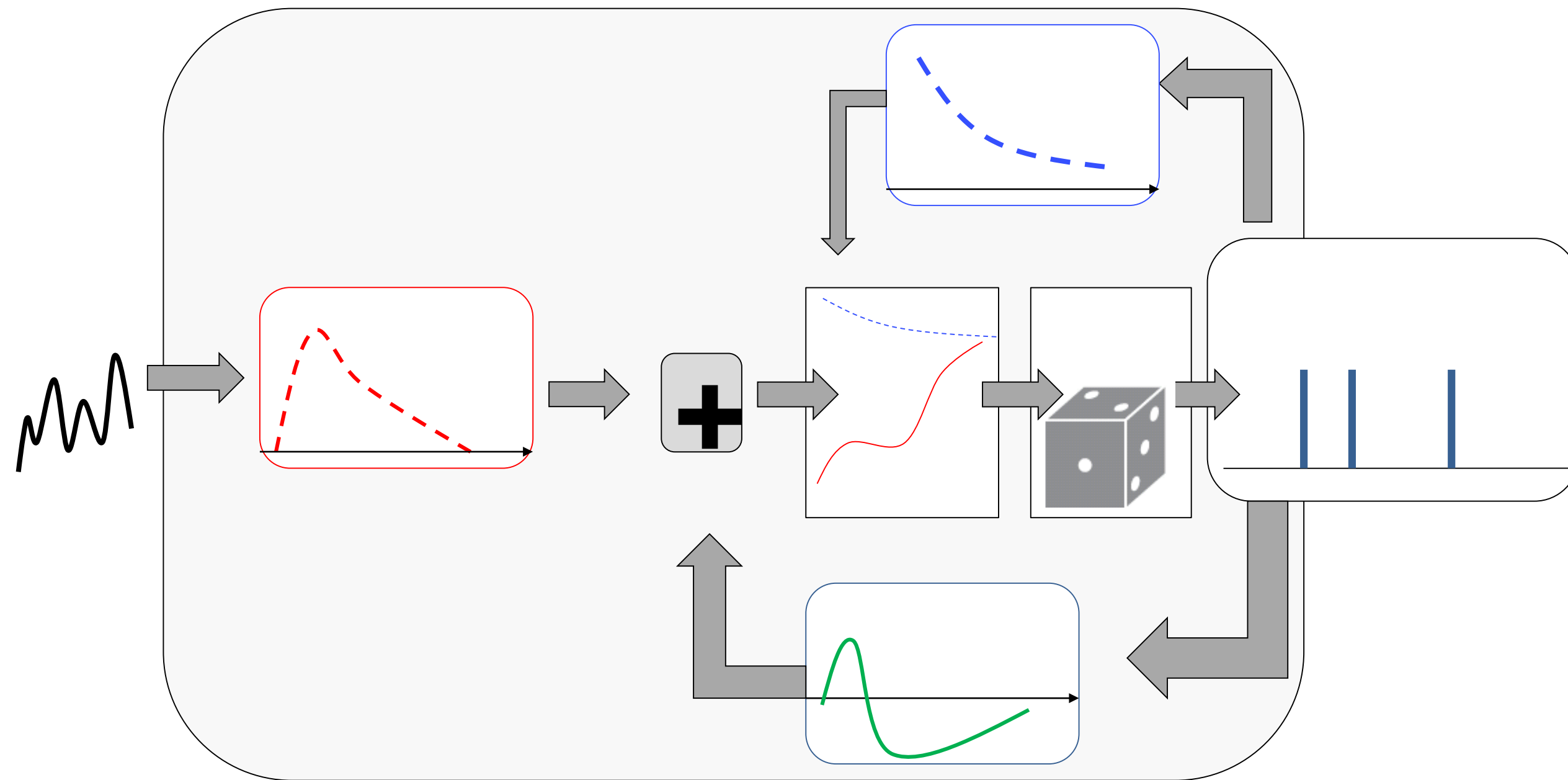
Interval distribution

$$P_I(t|\hat{t}) = \underbrace{\rho(t)}_{\text{escape rate}} \cdot \underbrace{\exp\left(-\int_{\hat{t}}^t \rho(t') dt'\right)}_{\text{Survivor function}}$$

Good choice


$$\rho(t) = f(u(t) - \mathcal{G}(t)) = \rho_0 \exp\left[\frac{u(t) - \mathcal{G}(t)}{\Delta u}\right]$$

Neuronal Dynamics – Likelihood of spike train



-linear filters
-escape rate
→ likelihood of observed
spike train

Neuronal Dynamics – 9.4 Likelihood of a spike train in GLMs

$$S(t) = \sum_f \delta(t - t^f)$$


→ Blackboard

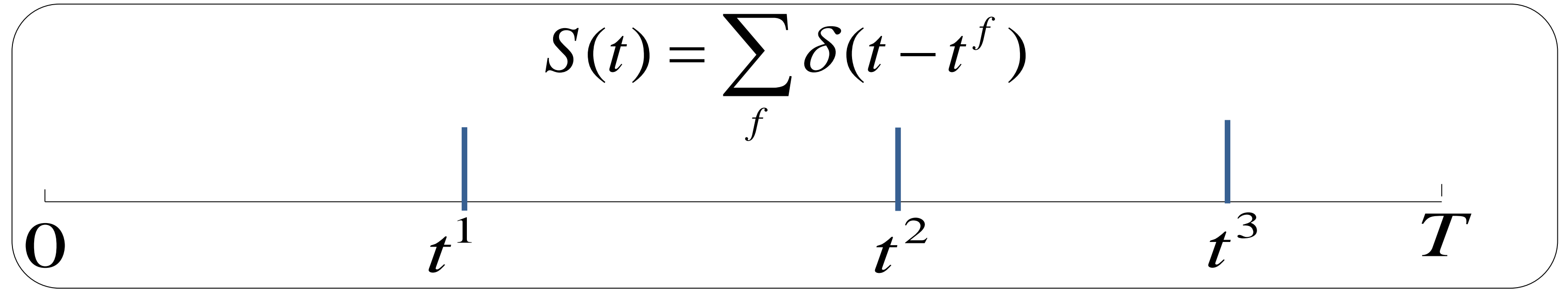
t^1, t^2, \dots, t^N

Measured spike train with spike times

Likelihood L that this spike train
could have been generated by model?

$$L(t^1, \dots, t^N) = \exp\left(-\int_0^{t^1} \rho(t') dt'\right) \rho(t^1) \cdot \exp\left(-\int_{t^1}^{t^2} \rho(t') dt'\right) \dots$$

Neuronal Dynamics – 9.4 Likelihood of a spike train

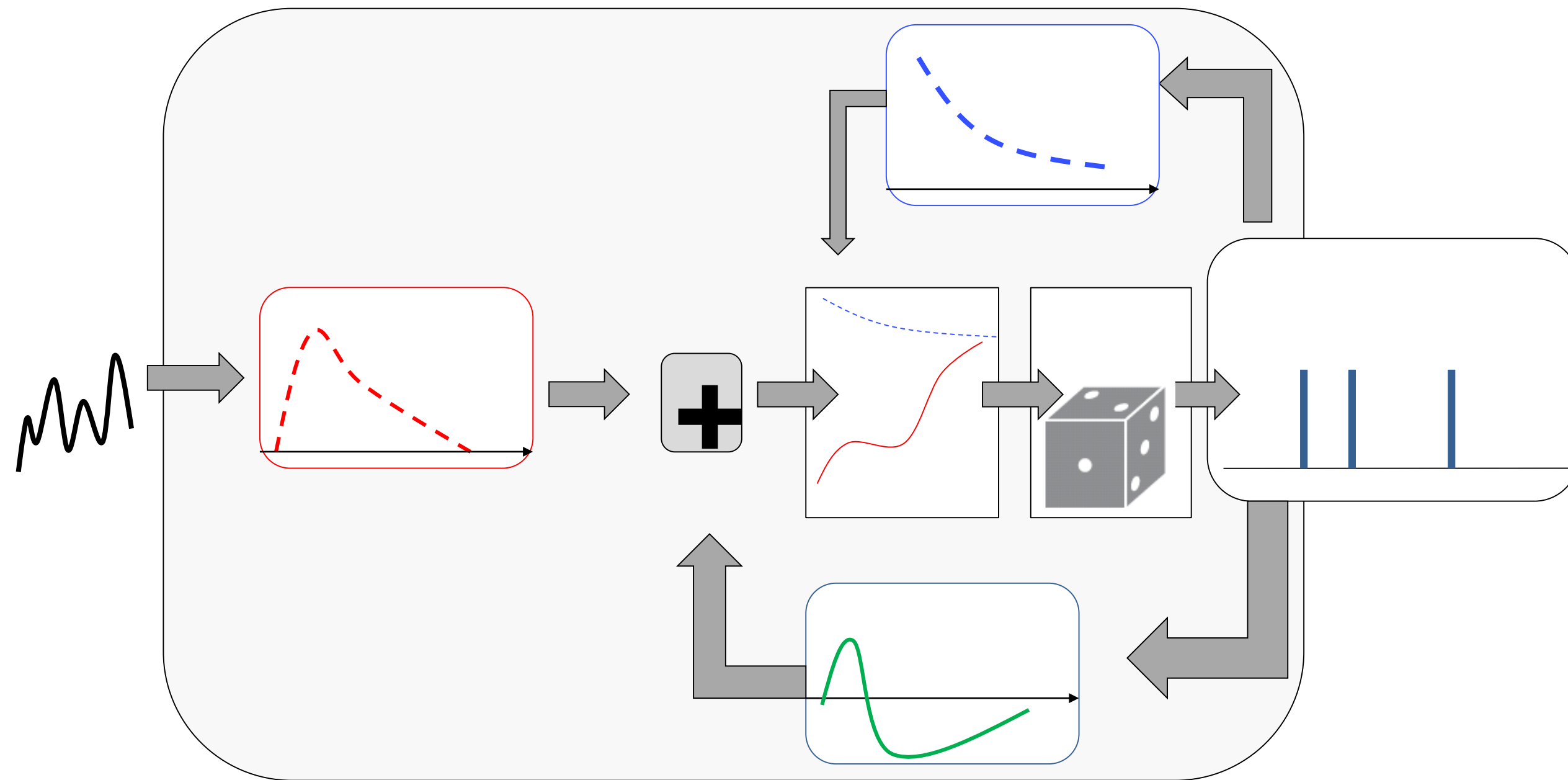


$$L(t^1, \dots, t^N) = \exp\left(-\int_0^{t^1} \rho(t') dt'\right) \rho(t^1) \cdot \exp\left(-\int_{t^1}^{t^2} \rho(t') dt'\right) \rho(t^2) \dots \exp\left(-\int_{t^N}^T \rho(t') dt'\right)$$

$$L(t^1, \dots, t^N) = \exp\left(-\int_0^T \rho(t') dt'\right) \prod_f \rho(t^f)$$

$$\log L(t^1, \dots, t^N) = -\int_0^T \rho(t') dt' + \sum_f \log \rho(t^f)$$

Neuronal Dynamics – 9.4 SRM with escape noise = GLM



-linear filters
-escape rate
→likelihood of observed
spike train

→parameter optimization
of neuron model

Week 9 – part 5: Parameter Estimation



Biological Modeling of Neural Networks:

Week 9 – Optimizing Neuron Models For Coding and Decoding

Wulfram Gerstner

EPFL, Lausanne, Switzerland

✓ 9.1 What is a good neuron model?

- Models and data

✓ 9.2 AdEx model

- Firing patterns and adaptation

✓ 9.3 Spike Response Model (SRM)

- Integral formulation

✓ 9.4 Generalized Linear Model

- Adding noise to the SRM

(9.5 Parameter Estimation)

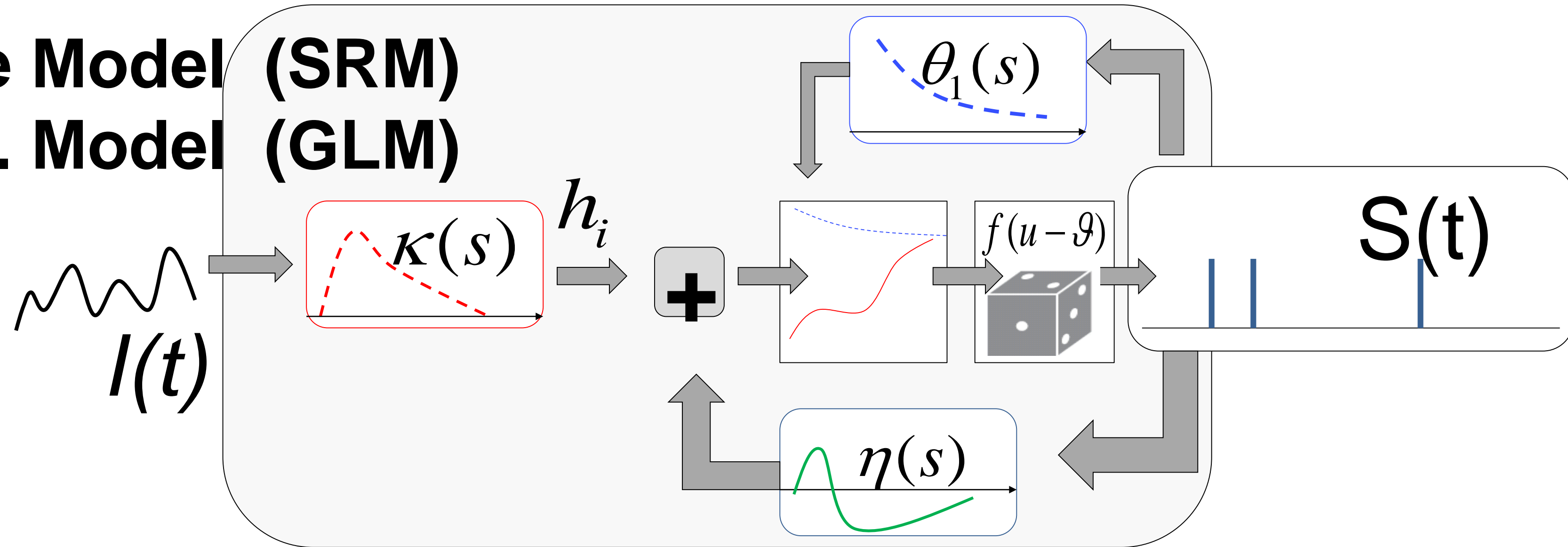
- Quadratic and convex optimization

9.6. Modeling in vitro data

- how long lasts the effect of a spike?

Neuronal Dynamics – 9.5 Parameter estimation: voltage

Spike Response Model (SRM) Generalized Lin. Model (GLM)



Subthreshold
potential

$$u(t) = \int \underbrace{\eta(s)}_{\text{known spike train}} S(t-s) ds + \int_0^\infty \underbrace{\kappa(s)}_{\text{known input}} I(t-s) ds + u_{rest}$$

known spike train

known input

Linear filters/linear in parameters

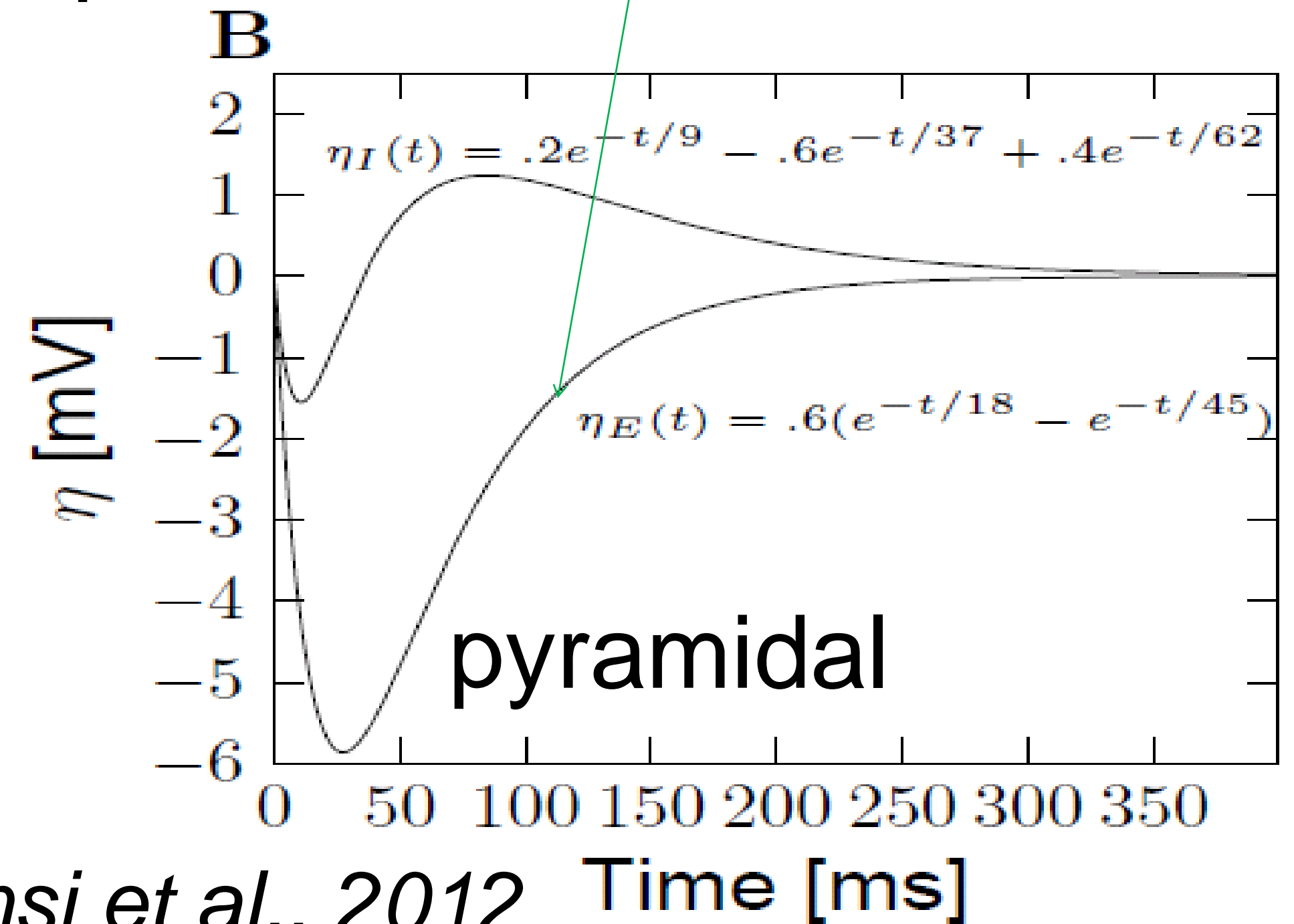
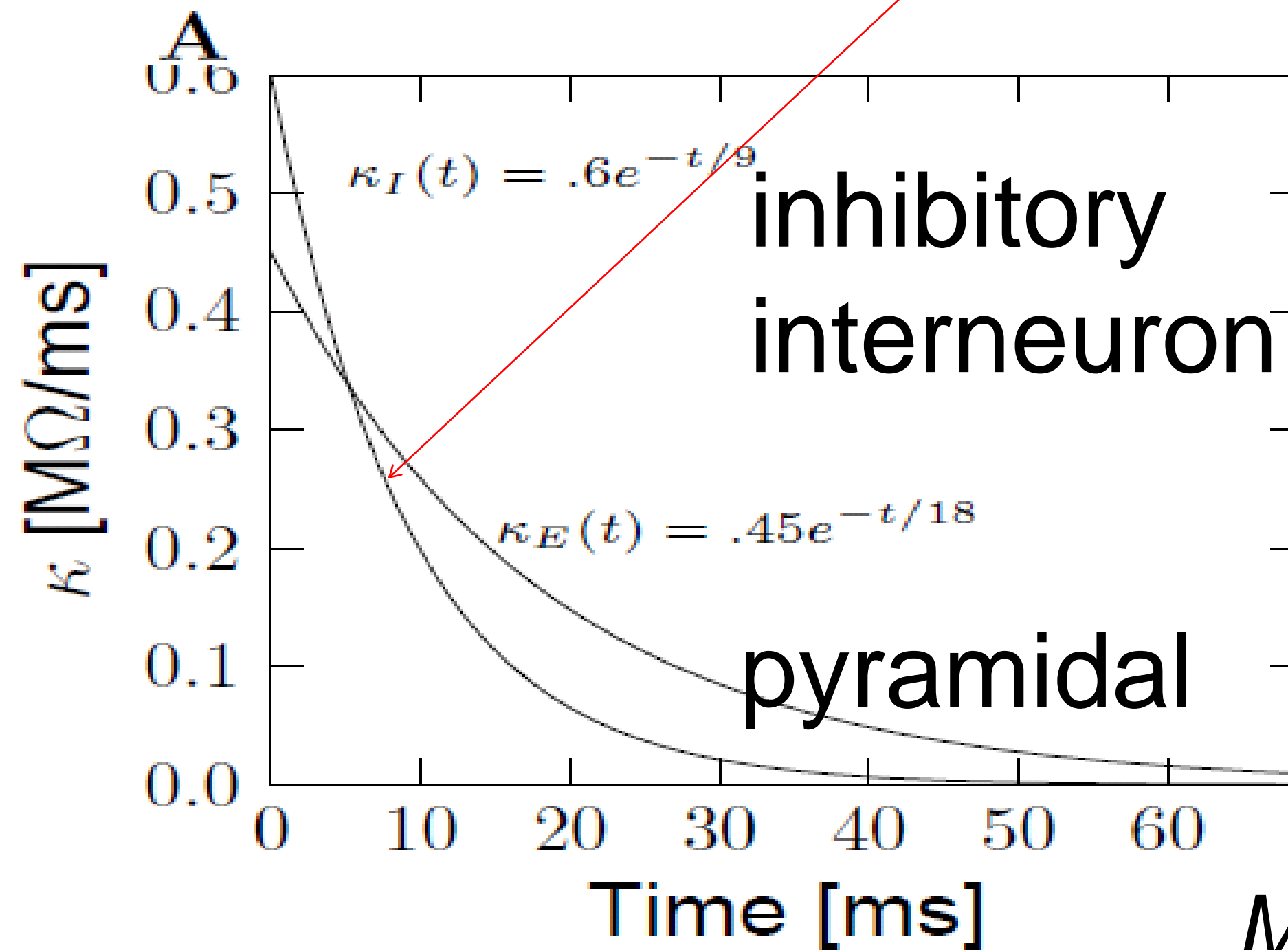
Neuronal Dynamics – 9.5 Extracted parameters: voltage

Subthreshold
potential

$$u(t) = \int_0^\infty \underbrace{\kappa(s)}_{\text{known input}} I(t-s) ds + u_{rest} + \int \underbrace{\eta(s)}_{\text{known spike train}} S(t-s) ds$$

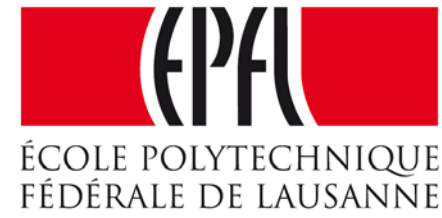
known input

known spike train



Mensi et al., 2012

Week 9 – part 5b: Quadratic and Convex Optimization



Biological Modeling of Neural Networks:

Week 9 – Optimizing Neuron Models For Coding and Decoding

Wulfram Gerstner

EPFL, Lausanne, Switzerland

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✓ 9.4 Generalized Linear Model

- Adding noise to the SRM

9.5 Parameter Estimation

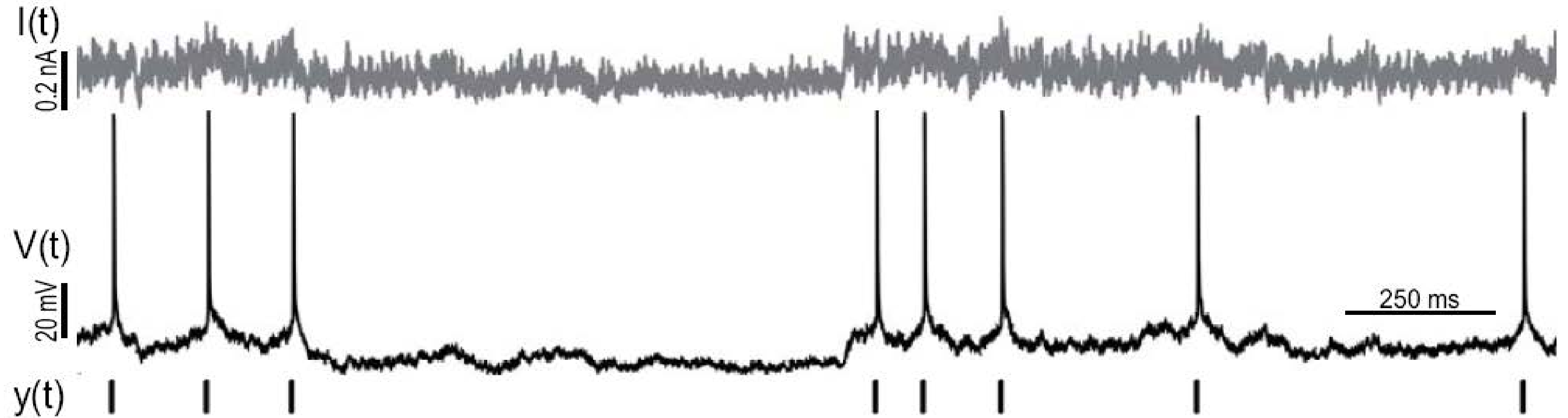
- Quadratic and convex optimization

9.6. Modeling in vitro data

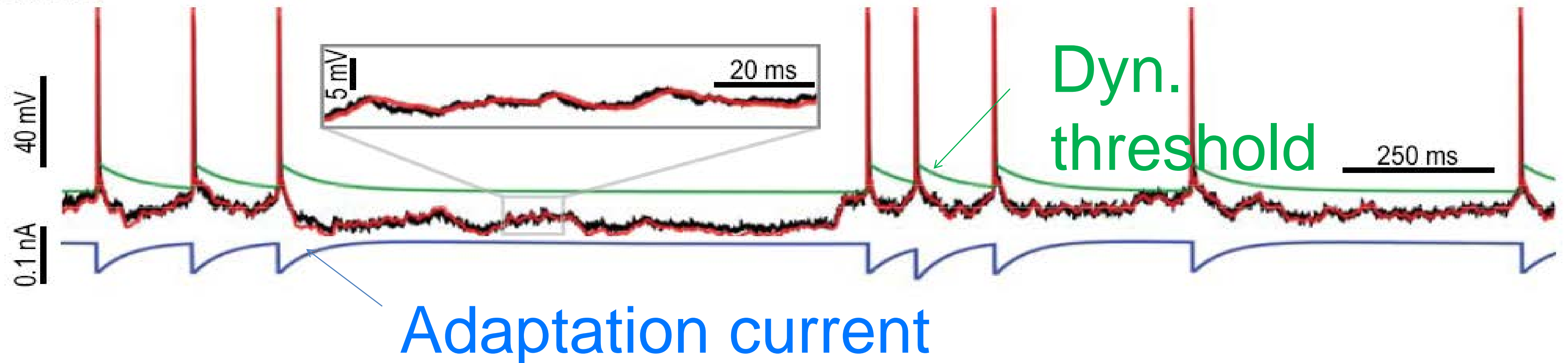
- how long lasts the effect of a spike?

Fitting models to data: so far 'subthreshold'

A Experimental data set



C Model

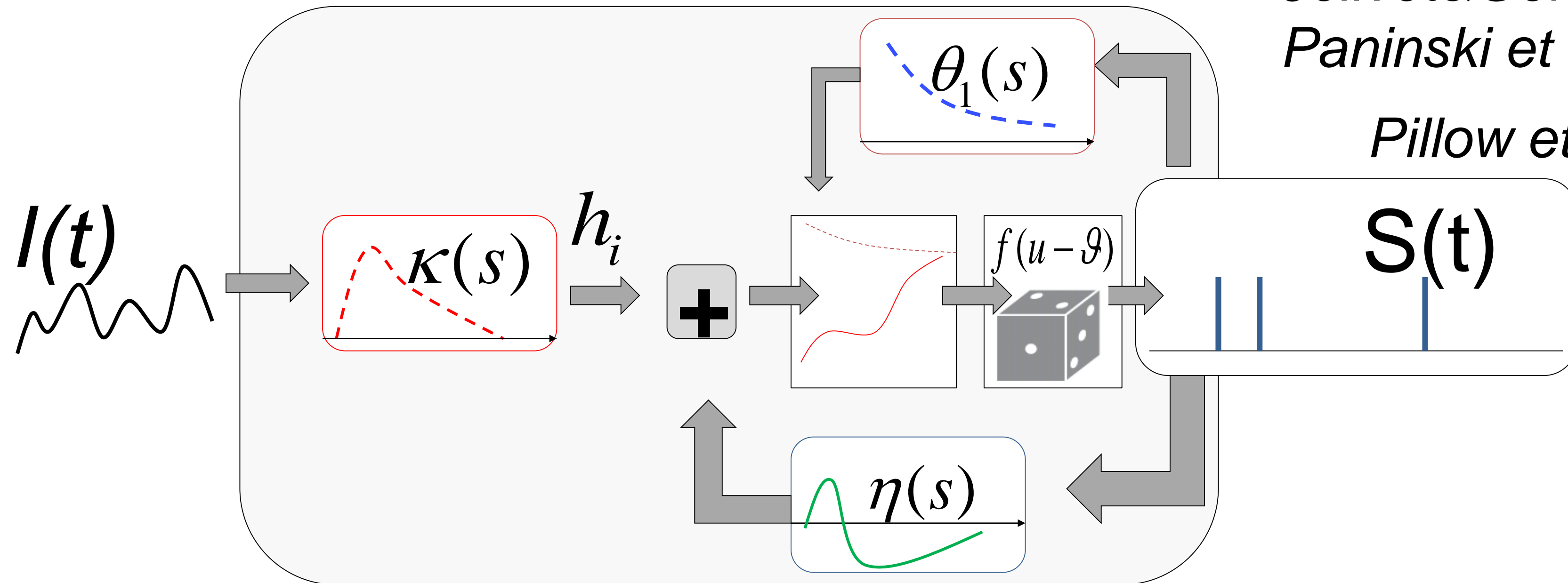


Neuronal Dynamics – 9.5 Threshold: Predicting spike times

Jolivet & Gerstner, 2005

Paninski et al., 2004

Pillow et al. 2008



potential $u(t) = \int \underline{\eta(s)} S(t-s) ds + \int_0^\infty \underline{\kappa(s)} I(t-s) ds + u_{rest}$

threshold $\vartheta(t) = \theta_0 + \int \underline{\theta_1(s)} S(t-s) ds$

firing intensity $\rho(t) = f(u(t) - \vartheta(t))$

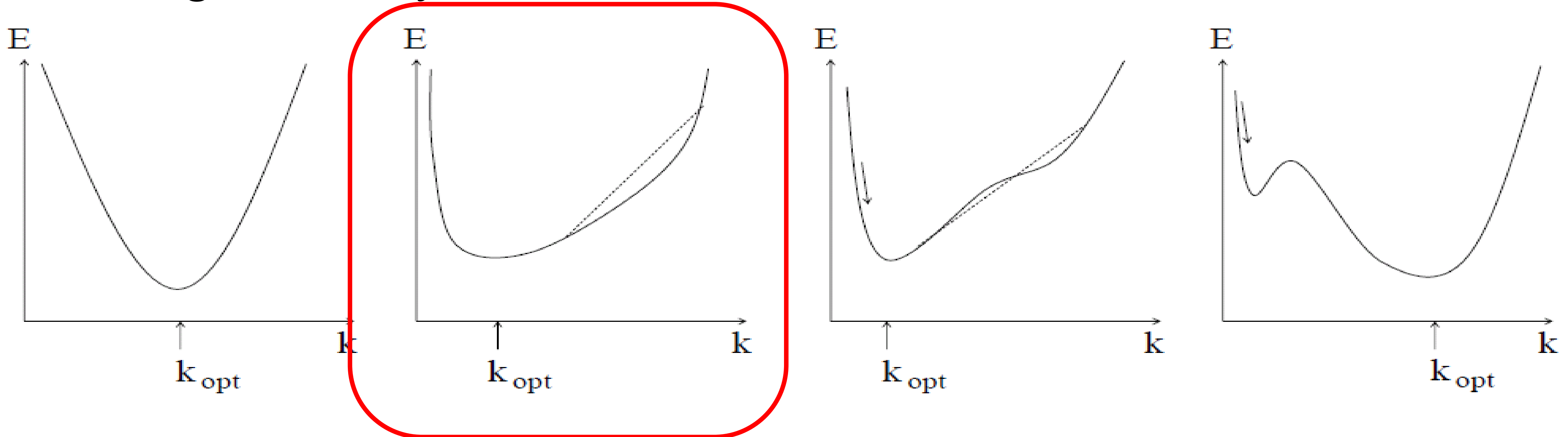
Neuronal Dynamics – 9.5 Generalized Linear Model (GLM)

$$\log L(t^1, \dots, t^N) = -\int_0^T \rho(t') dt' + \sum_f \log \rho(t^f) = -E$$

potential $u(t) = \int \underline{\eta(s)} S(t-s) ds + \int_0^\infty \underline{\kappa(s)} I(t-s) ds + u_{rest}$

threshold $\mathcal{G}(t) = \theta_0 + \int \underline{\theta_1(s)} S(t-s) ds$

firing intensity $\rho(t) = f(u(t) - \mathcal{G}(t))$



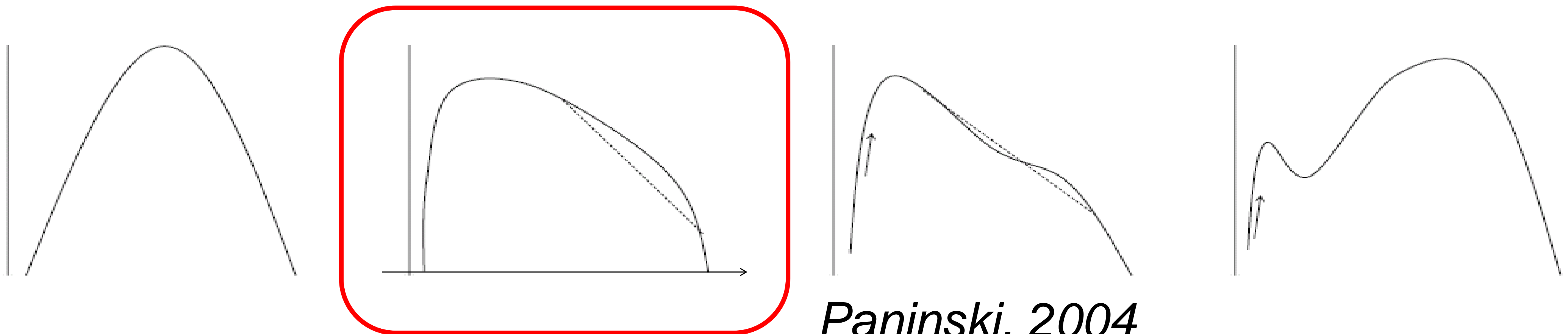
Neuronal Dynamics – 9.5 GLM: concave error function

potential $u(t) = \int \underline{\eta(s)} S(t-s) ds + \int_0^\infty \underline{\kappa(s)} I(t-s) ds + u_{rest}$

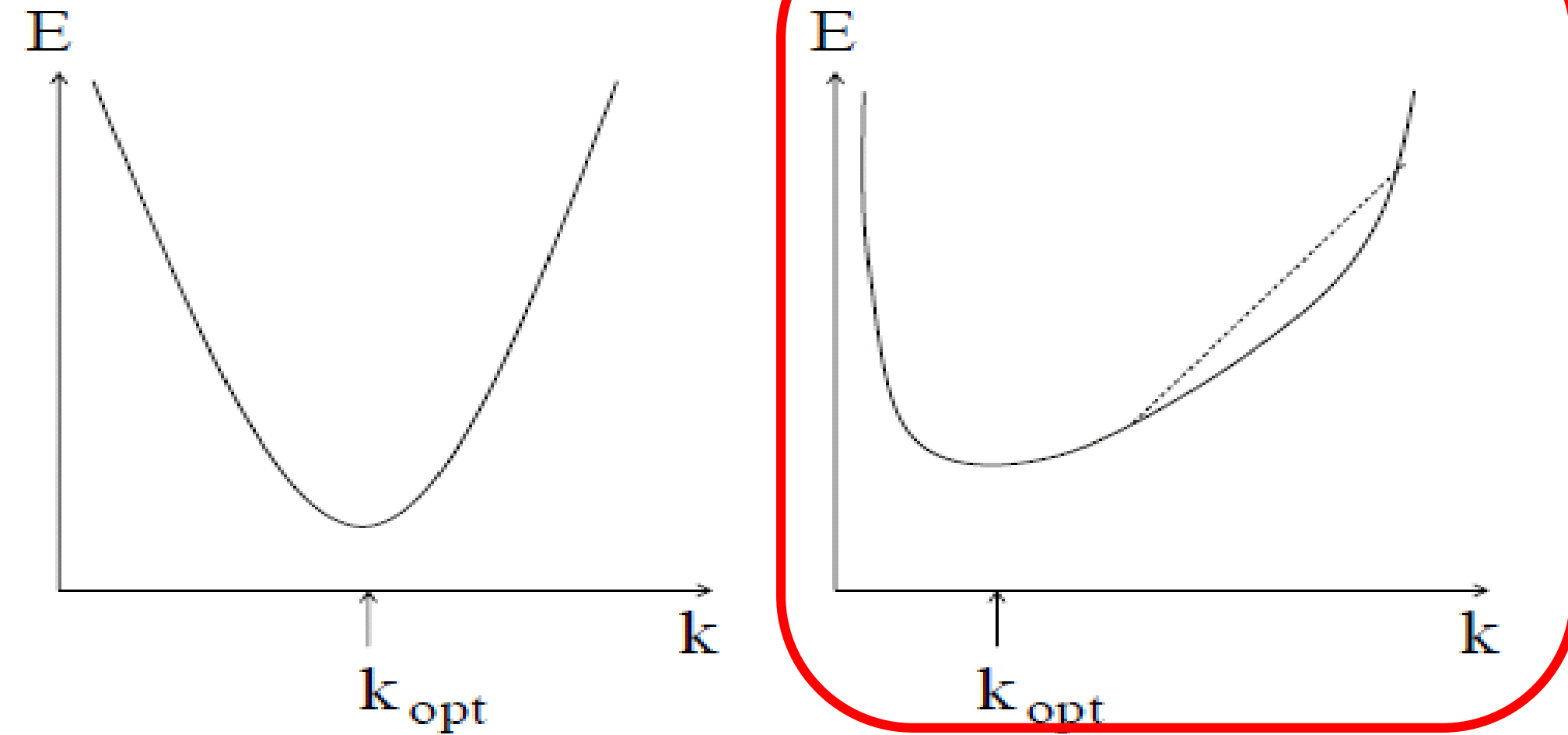
threshold $\mathcal{G}(t) = \theta_0 + \int \underline{\theta_1(s)} S(t-s) ds$

firing intensity $\rho(t) = f(u(t) - \mathcal{G}(t))$

$$\log L(t^1, \dots, t^N) = -\int_0^T \rho(t') dt' + \sum_f \log \rho(t^f)$$



Neuronal Dynamics – 9.5 quadratic and convex/concave optimization



Voltage/subthreshold

- linear in parameters
→ quadratic error function

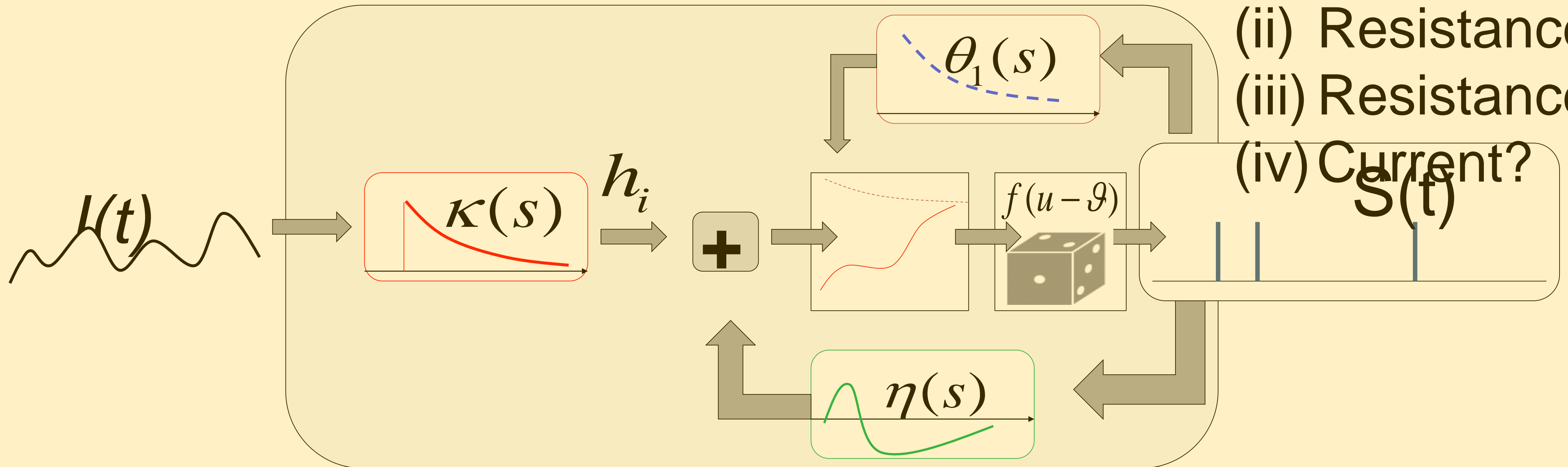
Spike times

- nonlinear, but GLM
→ convex error function

Quiz NOW :

What are the units of $\eta(s)$?

- (i) Voltage?
- (ii) Resistance?
- (iii) Resistance/s?
- (iv) Current?



potential

$$u(t) = \int \eta(s) S(t-s) ds + \int_0^\infty \kappa(s) I(t-s) ds + u_{rest}$$

threshold

$$\mathcal{G}(t) = \theta_0 + \int \theta_1(s) S(t-s) ds$$

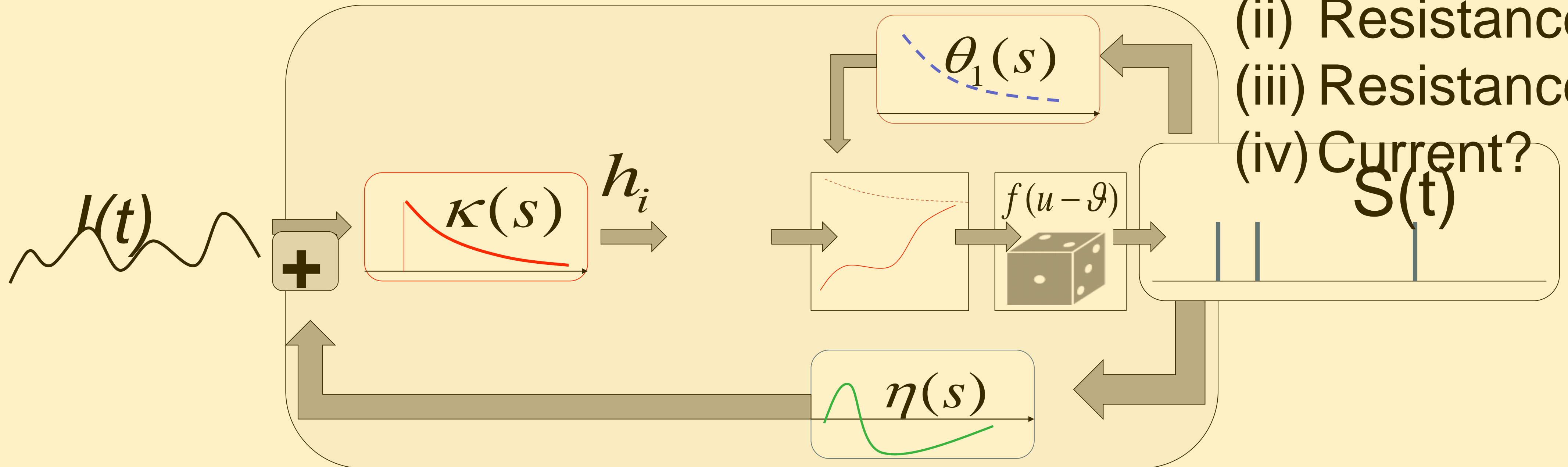
firing intensity

$$\rho(t) = f(u(t) - \mathcal{G}(t))$$

Quiz NOW:

What are the units of $\eta(s)$?

- (i) Voltage?
- (ii) Resistance?
- (iii) Resistance/s
- (iv) Current?

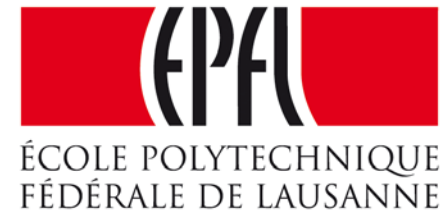


potential $C \frac{d}{dt} u(t) = -\frac{(u - u_{rest})}{R} + \int \underline{\eta(s)} S(t - s) ds + \underline{I(t - s)}$

threshold $\vartheta(t) = \theta_0 + \int \theta_1(s) \underline{S(t - s)} ds$

firing intensity $\rho(t) = f(u(t) - \vartheta(t))$

Week 9 – part 6: Modeling in vitro data



Biological Modeling of Neural Networks:

Week 9 – Optimizing Neuron Models For Coding and Decoding

Wulfram Gerstner

EPFL, Lausanne, Switzerland

✓ 9.1 What is a good neuron model?

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- Integral formulation

✓ 9.4 Generalized Linear Model

- Adding noise to the SRM

✓ 9.5 Parameter Estimation

- Quadratic and convex optimization

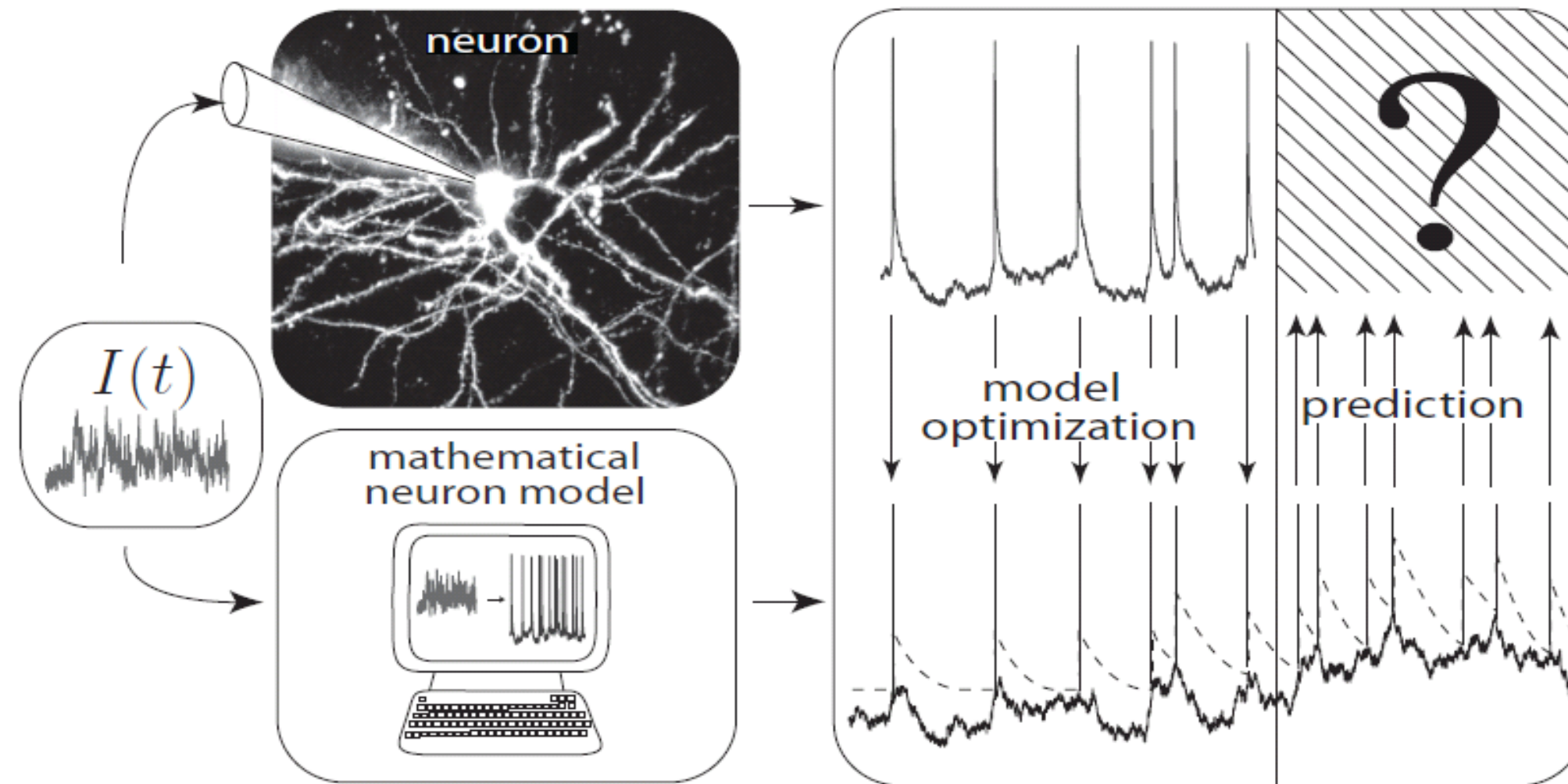
9.6. Modeling in vitro data

- how long lasts the effect of a spike?

9.7. Helping Humans

Neuronal Dynamics – 9.6 Models and Data

comparison model-data



Predict

-Subthreshold voltage

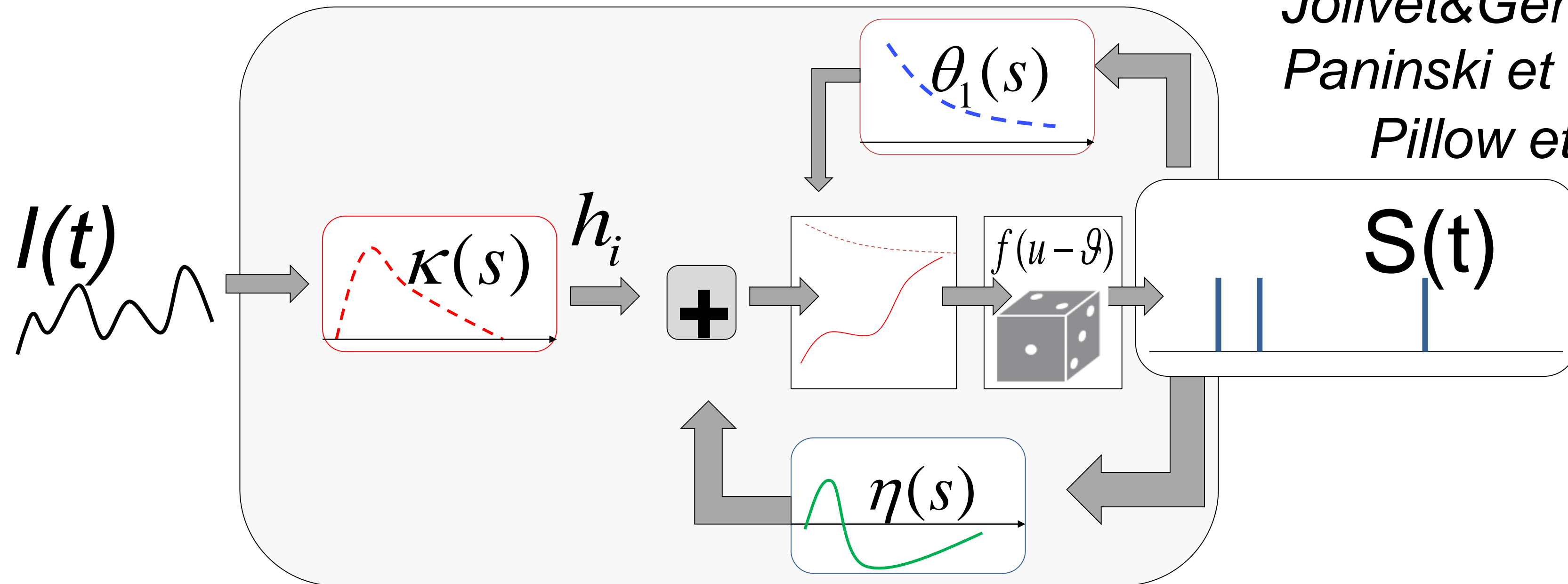
-Spike times

Neuronal Dynamics – 9.6 GLM/SRM with escape noise

Jolivet & Gerstner, 2005

Paninski et al., 2004

Pillow et al. 2008

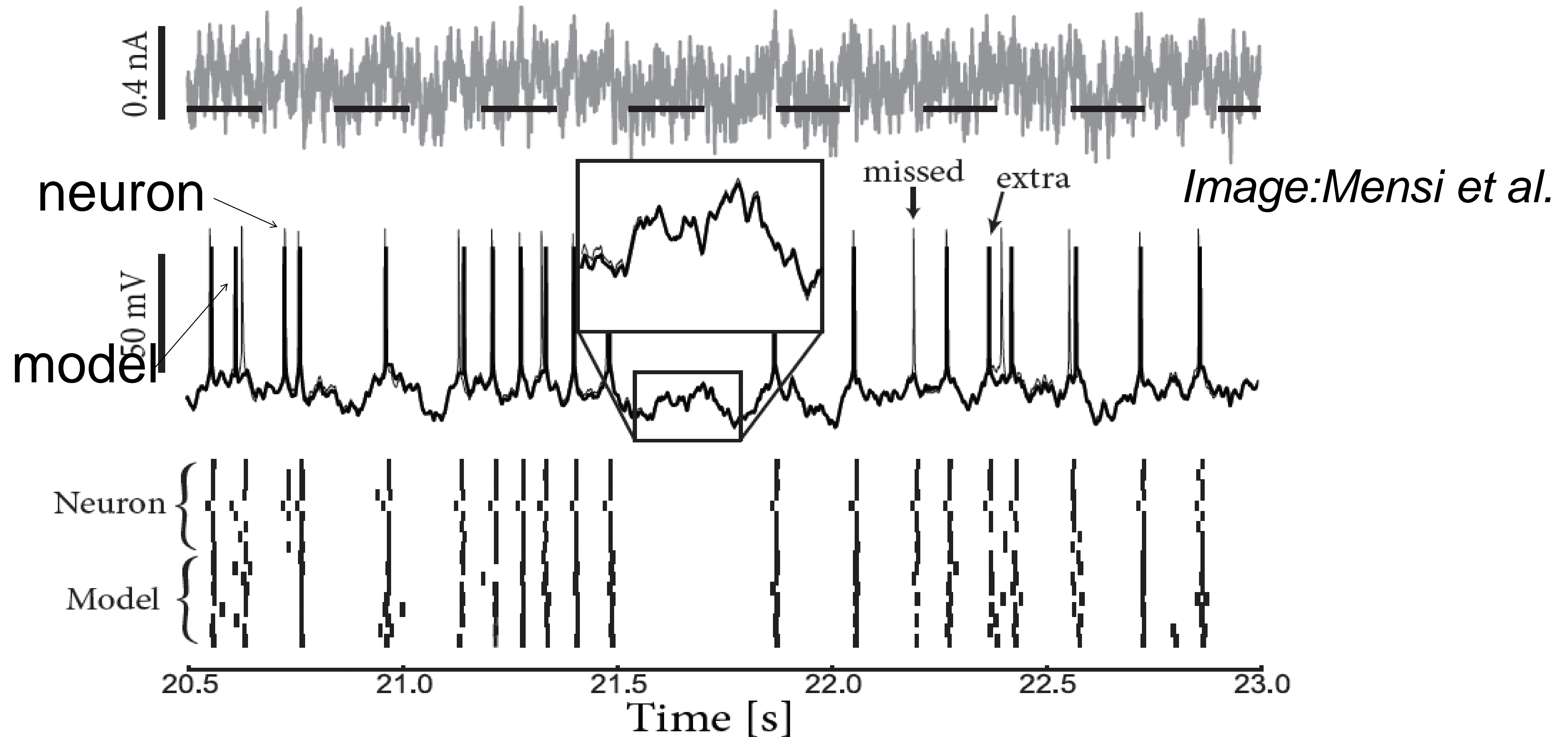


potential $u(t) = \int \underline{\eta(s)} S(t-s) ds + \int_0^\infty \underline{\kappa(s)} I(t-s) ds + u_{rest}$

threshold $\vartheta(t) = \theta_0 + \int \underline{\theta_1(s)} S(t-s) ds$

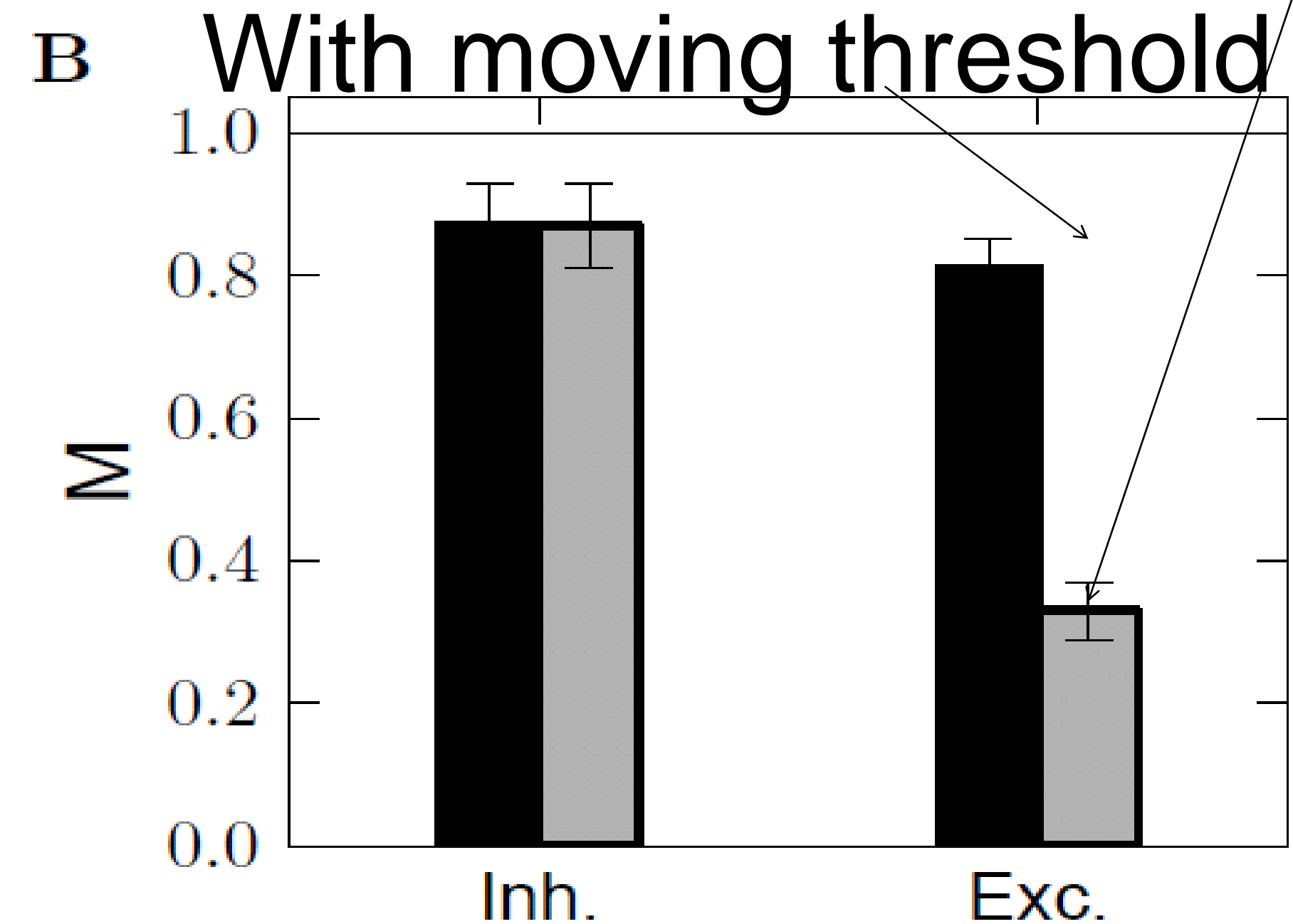
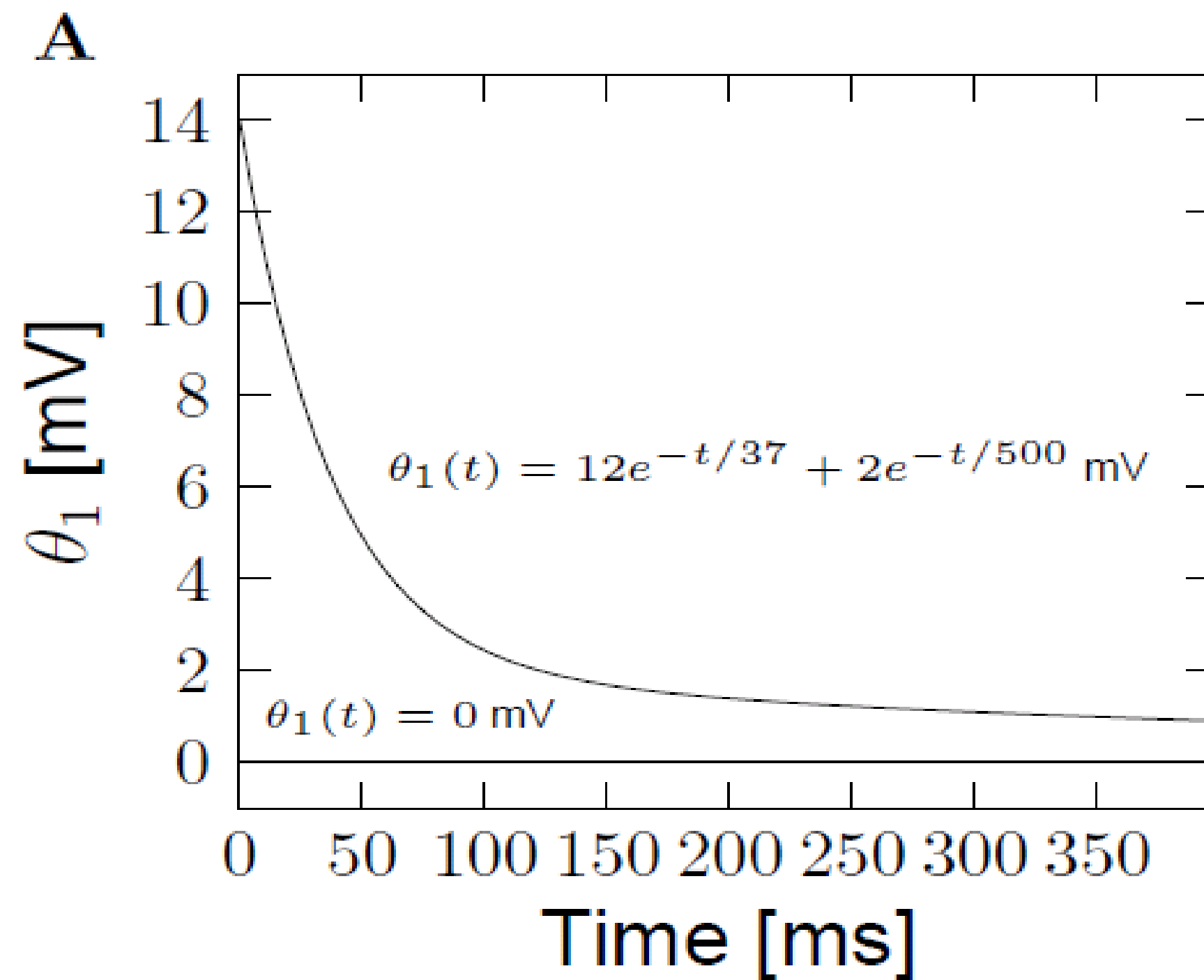
firing intensity $\rho(t) = f(u(t) - \vartheta(t))$

Neuronal Dynamics – 9.6 GLM/SRM predict subthreshold voltage



Role of moving threshold

No moving threshold



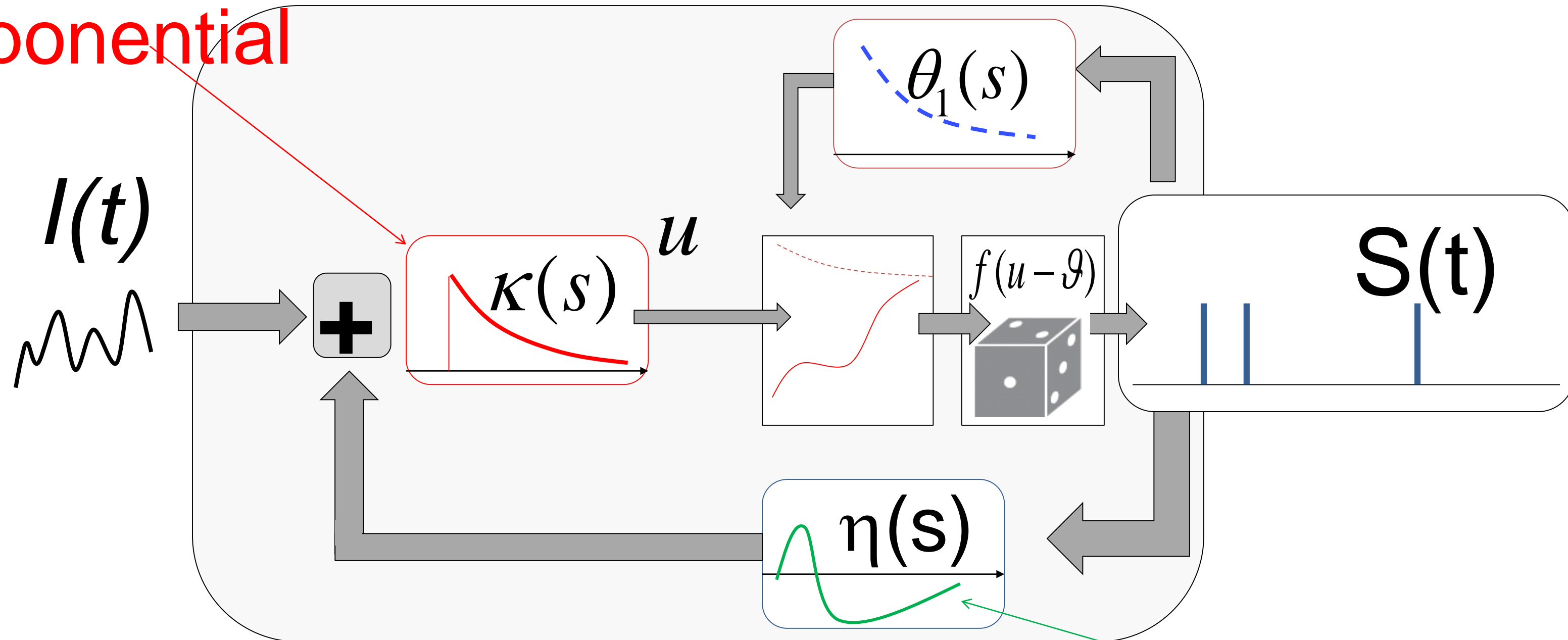
Mensi et al., 2012

Change in model formulation:

What are the units of ?

‘soft-threshold
adaptive IF model’

exponential



potential

$$C \frac{d}{dt} u(t) = \int \eta(s) S(t-s) ds + I(t)$$

threshold

$$\mathcal{G}(t) = \theta_0 + \int \theta_1(s) S(t-s) ds$$

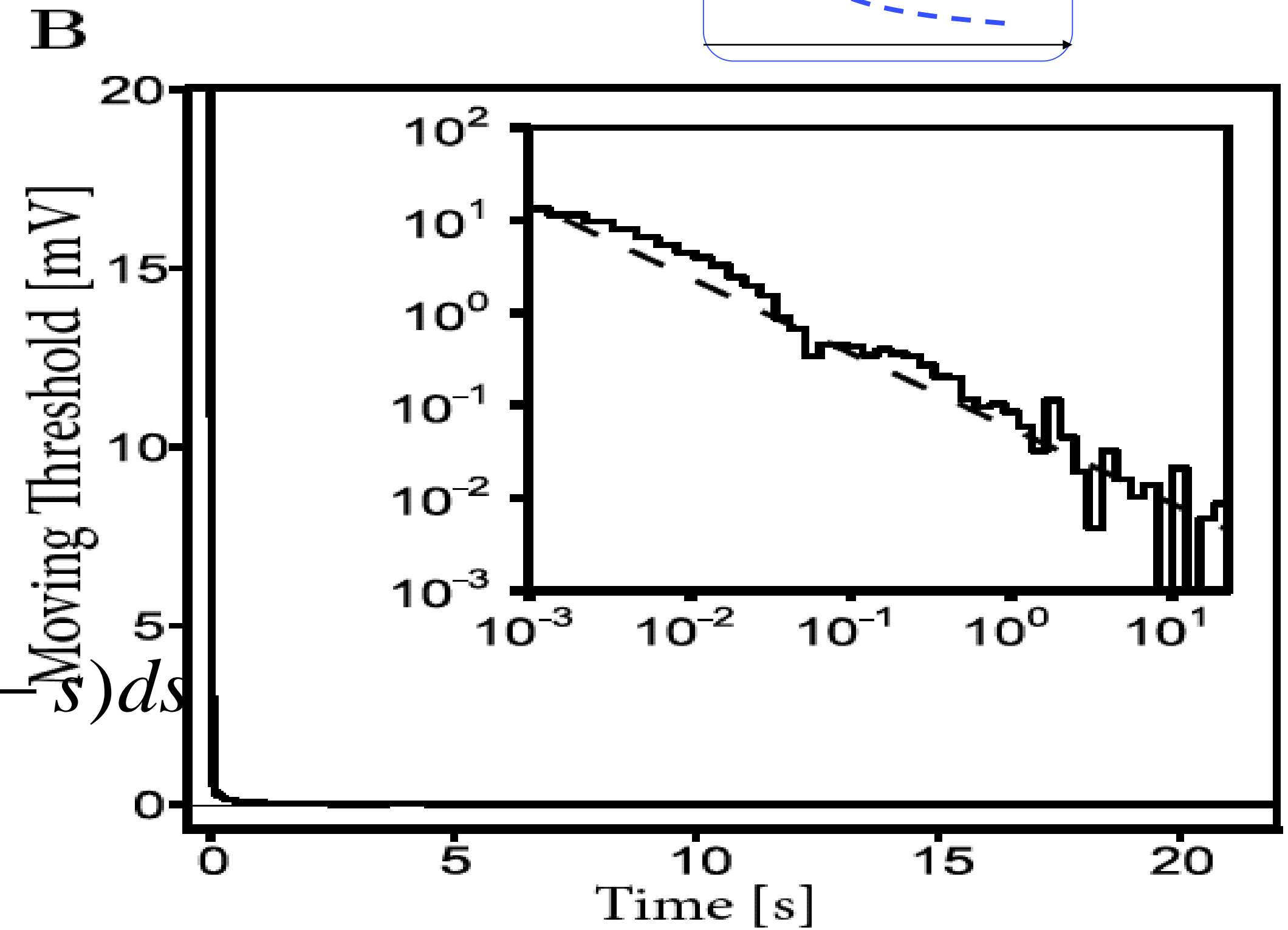
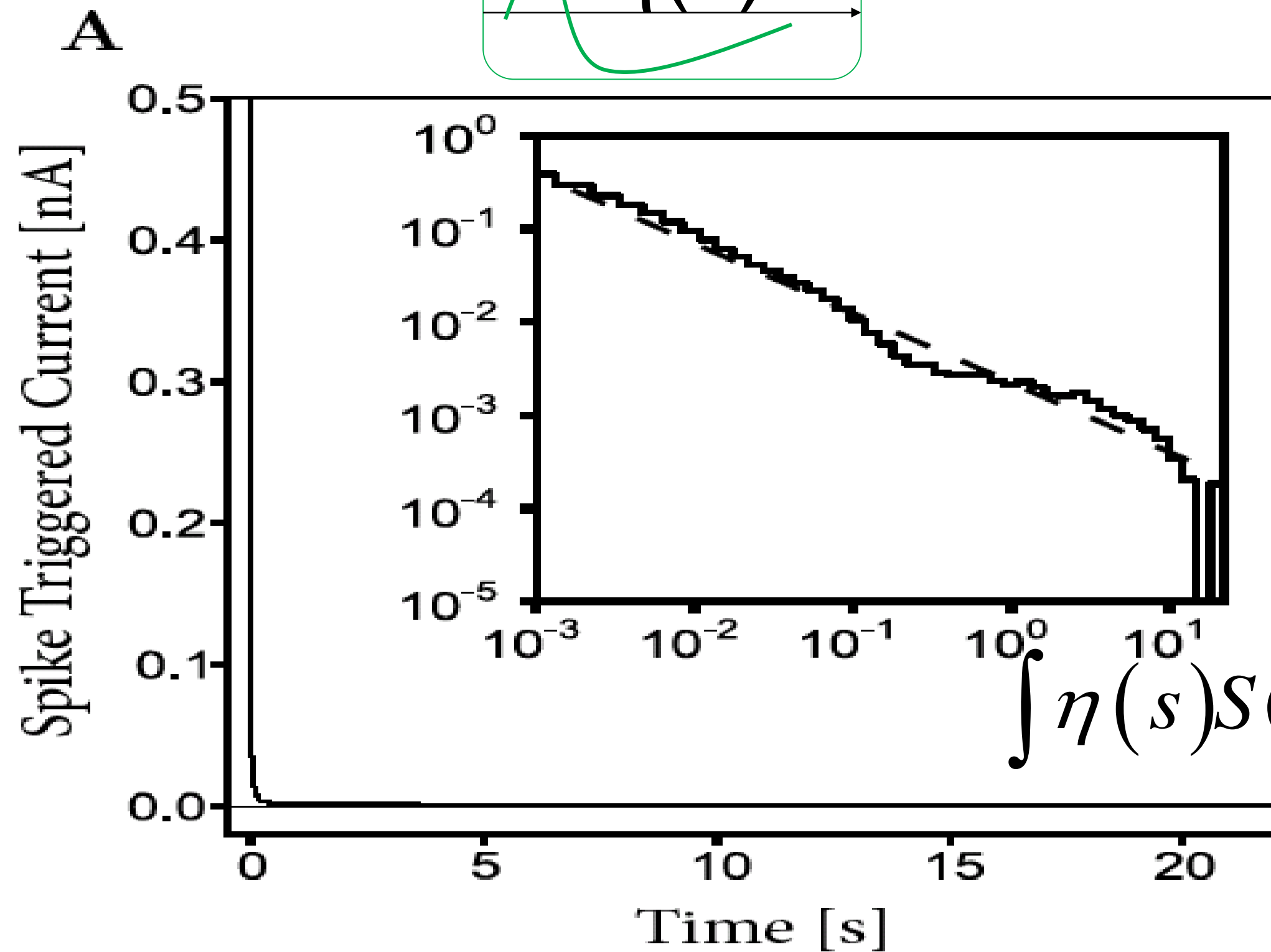
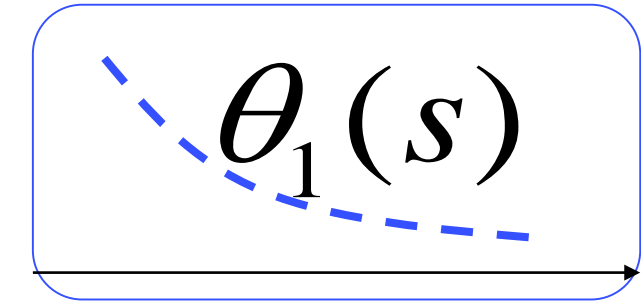
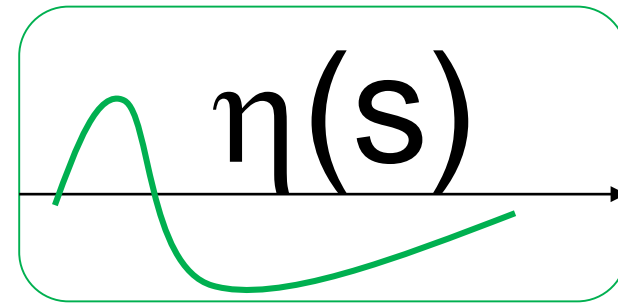
firing intensity $\rho(t) = f(u(t) - \mathcal{G}(t))$

adaptation
current

Neuronal Dynamics – 9.6 How long does the effect of a spike last?

Time scale of filters?

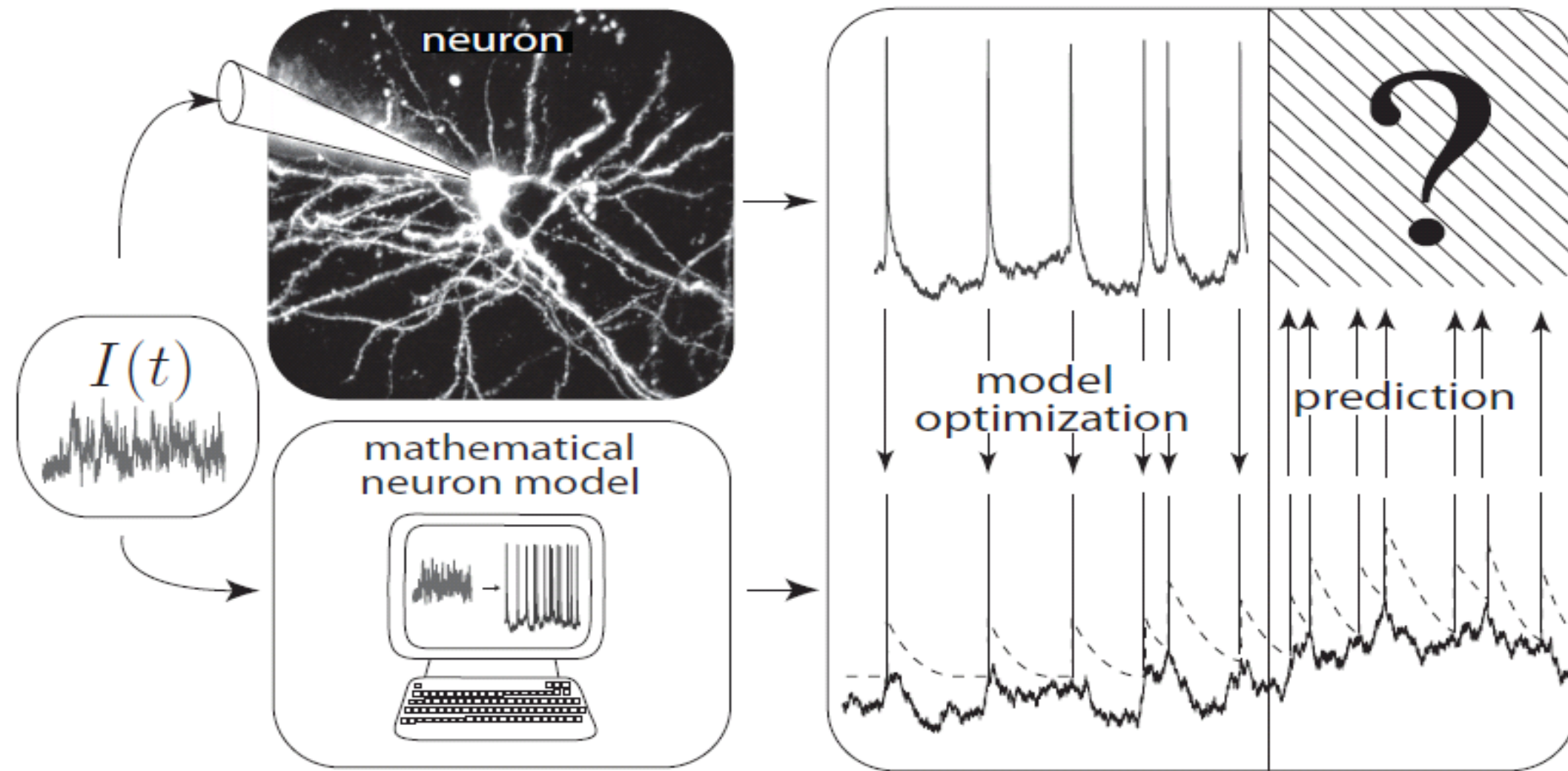
→ **Power law**



A single spike has a measurable effect more than 10 seconds later!

Pozzorini et al. 2013

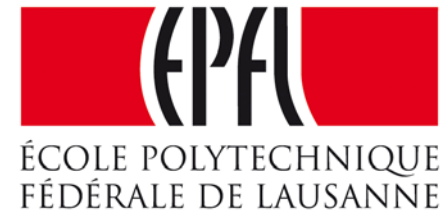
Neuronal Dynamics – 9.6 Models and Data



- Predict spike times
- Predict subthreshold voltage
- Easy to interpret (not a 'black box')
- Variety of phenomena
- Systematic: 'optimize' parameters

BUT so far limited to in vitro

Week 9 – part 6: Modeling in vitro data



Biological Modeling of Neural Networks:

Week 9 – Optimizing Neuron Models For Coding and Decoding

Wulfram Gerstner

EPFL, Lausanne, Switzerland

✓ 9.1 What is a good neuron model?

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✓ 9.4 Generalized Linear Model

- Adding noise to the SRM

✓ 9.5 Parameter Estimation

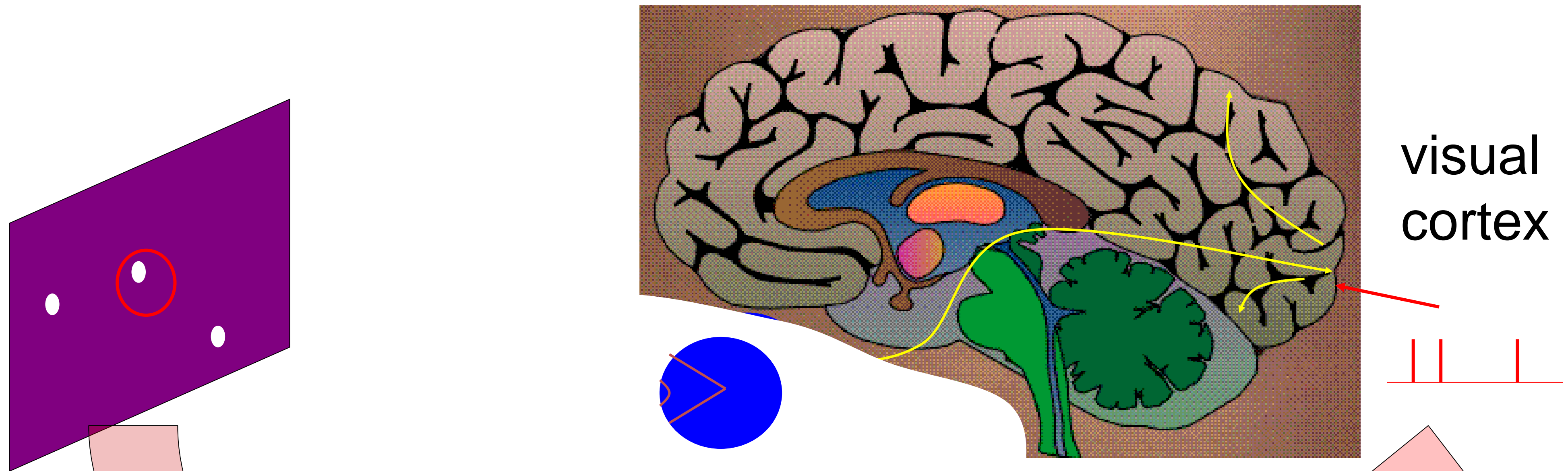
- Quadratic and convex optimization

✓ 9.6. Modeling in vitro data

- how long lasts the effect of a spike?

9.7. Helping Humans: in vivo data

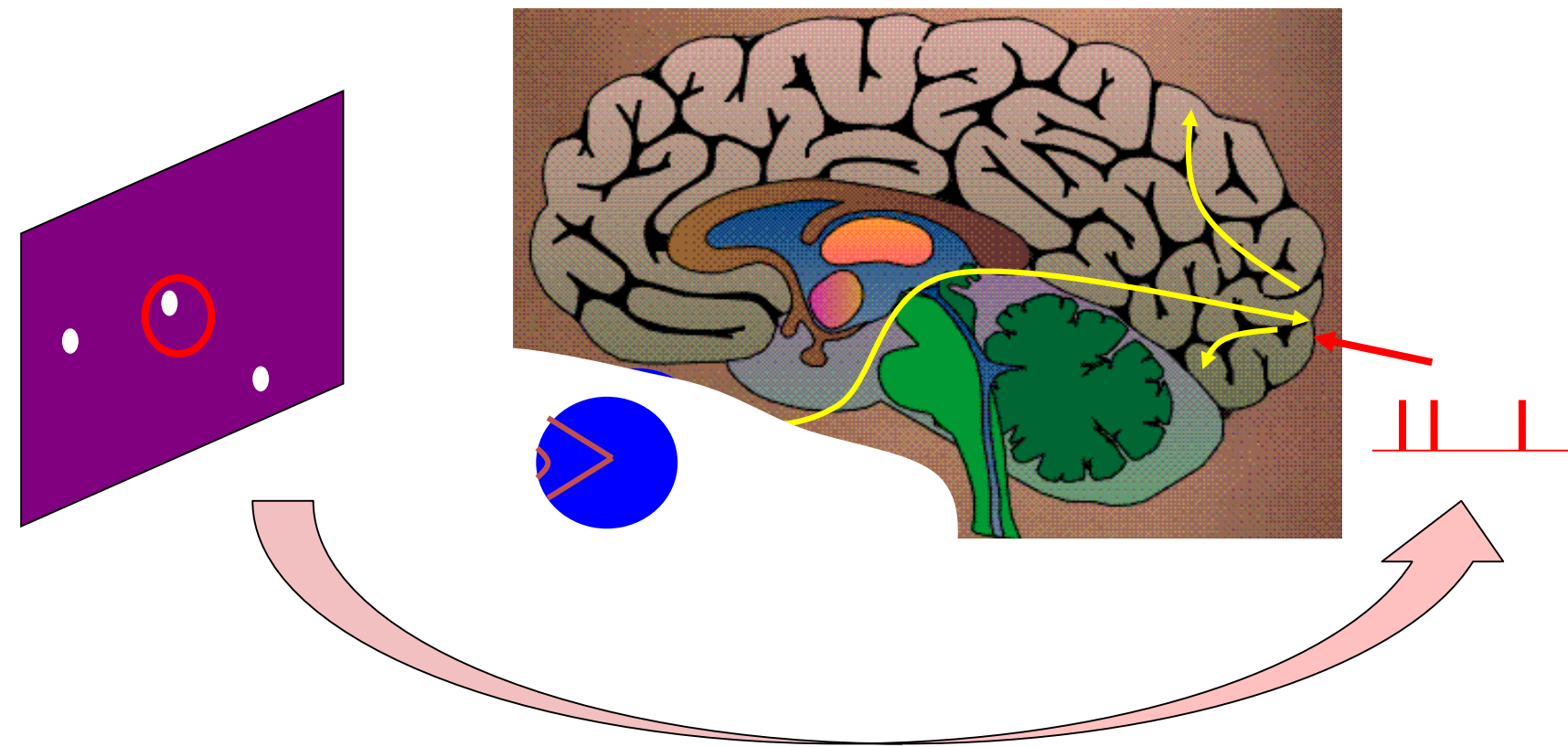
Neuronal Dynamics – 9.7 Model of ENCODING



- A) Predict spike times, given stimulus
- ~~B) Predict subthreshold voltage~~
- C) Easy to interpret (not a 'black box')
- D) Flexible enough to account for a variety of phenomena
- E) Systematic procedure to 'optimize' parameters

Model of 'Encoding'

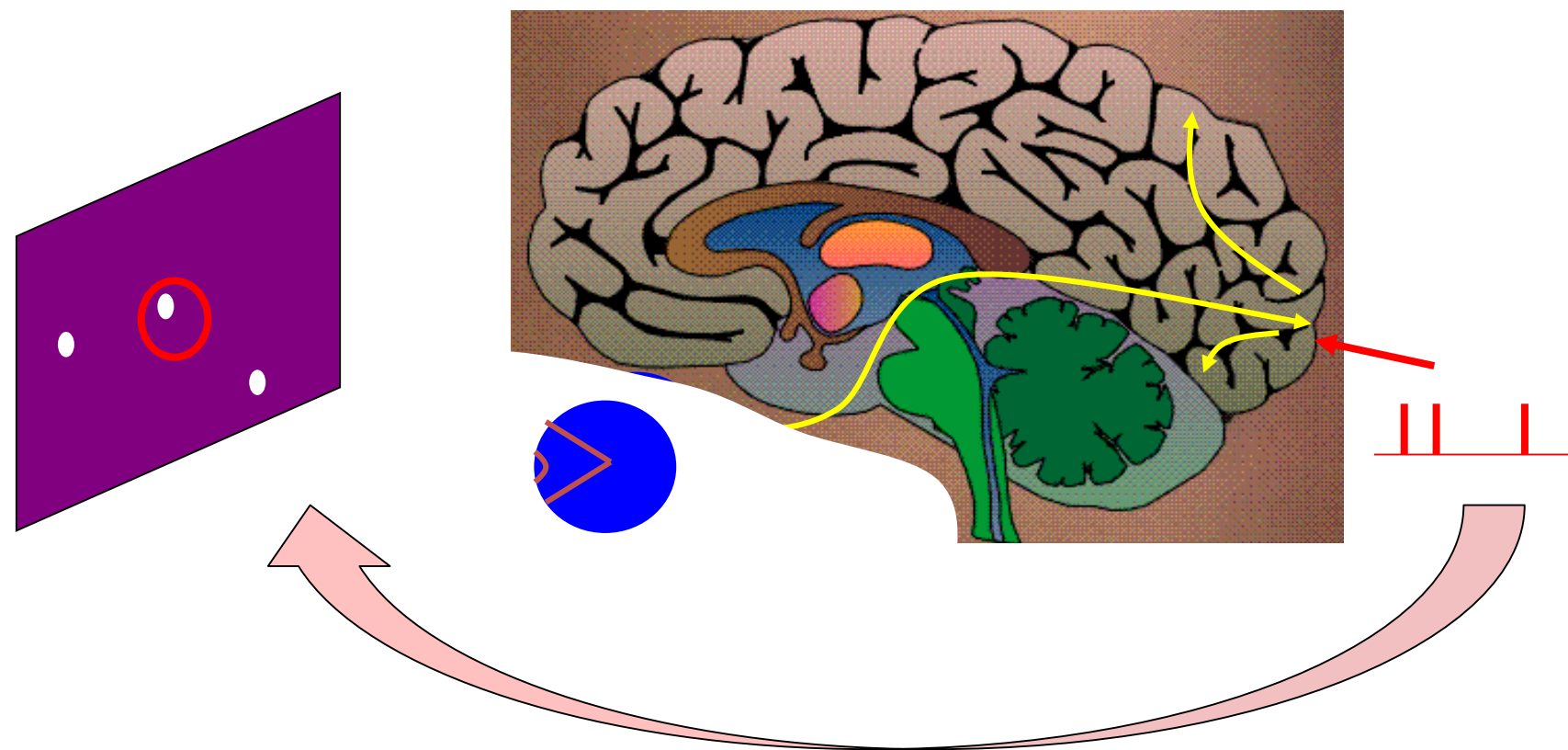
Neuronal Dynamics – 9.7 ENCODING and Decoding



Model of ‘Encoding’

Generalized Linear Model (GLM)

- flexible model
- systematic optimization of parameters



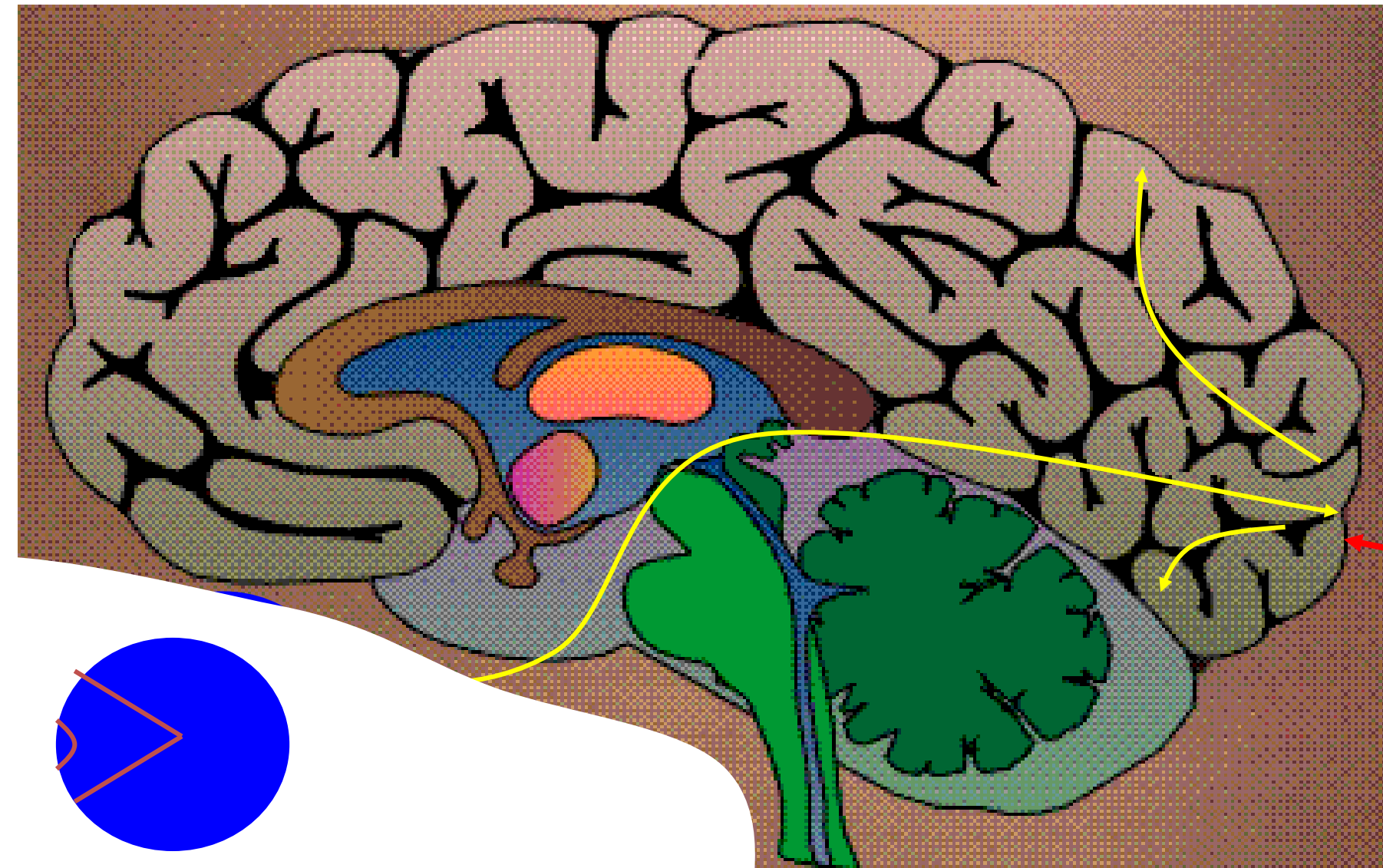
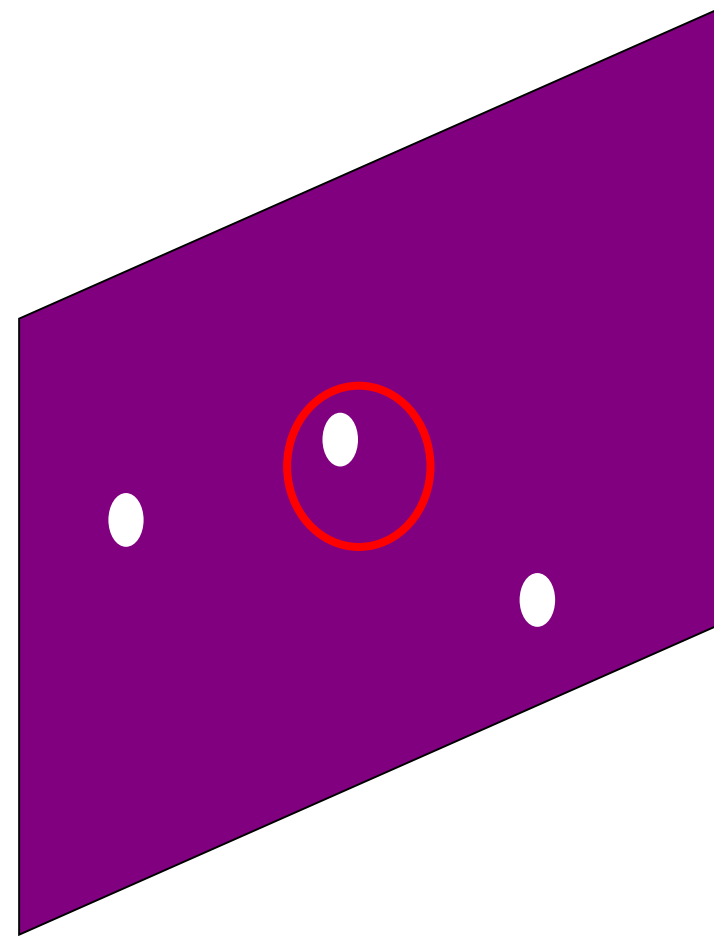
Model of ‘Decoding’

The same GLM works!

- flexible model
- systematic optimization of parameters

Neuronal Dynamics – 9.7 Model of DECODING

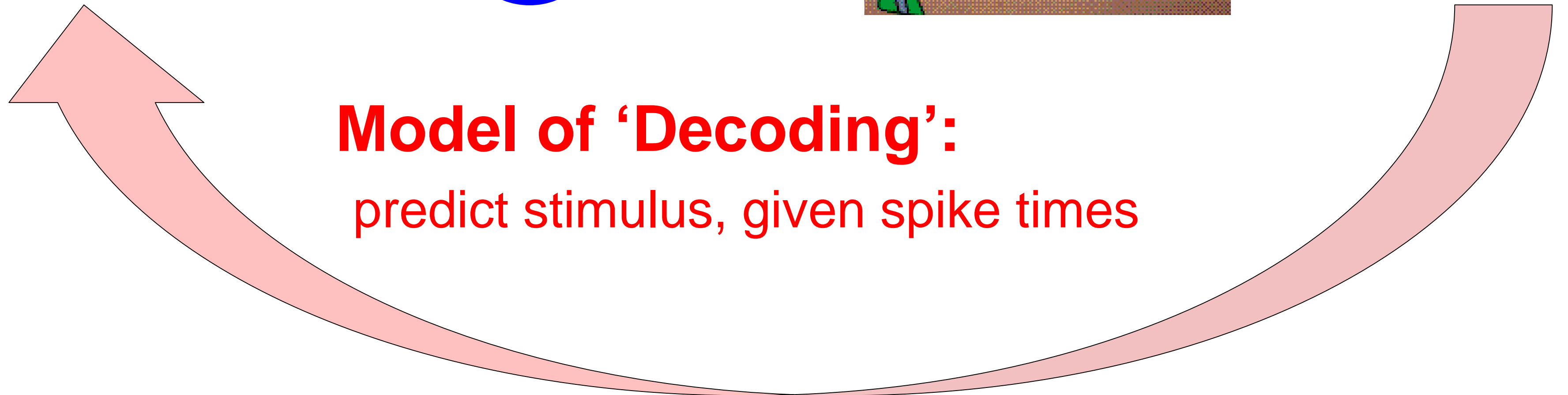
Predict stimulus!



visual
cortex

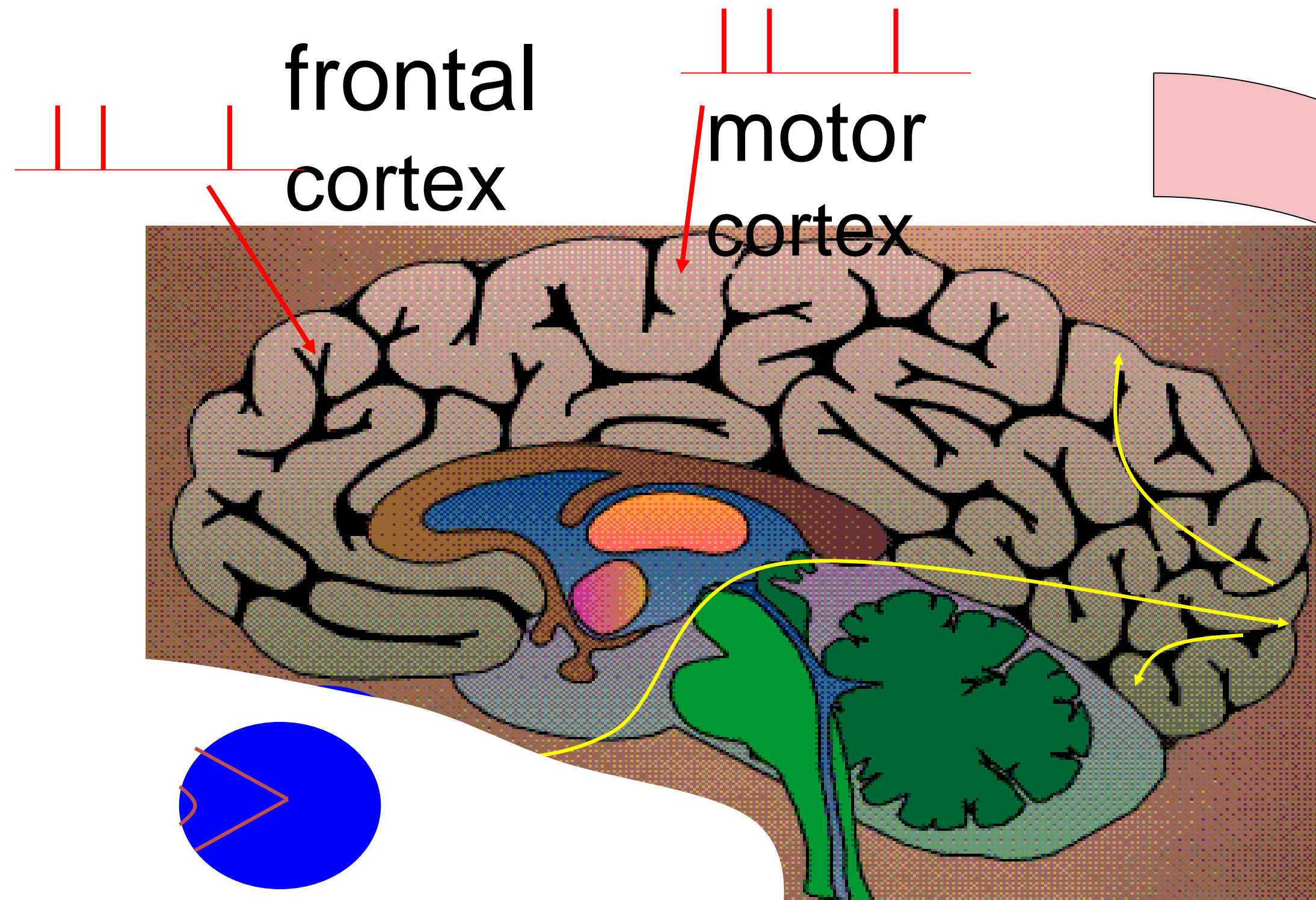


Model of 'Decoding':
predict stimulus, given spike times



Neuronal Dynamics – 9.7 Helping Humans

Application: Neuroprosthetics



Many groups
world wide
work on this
problem!

**Model of
'Decoding'**

**Predict intended arm movement,
given Spike Times**

Application: Neuroprosthetics

Decode the intended arm movement

Hand velocity

*Figure:
Neuronal Dynamics,
Cambridge Univ. Press;
See Truccolo et al. 2005*

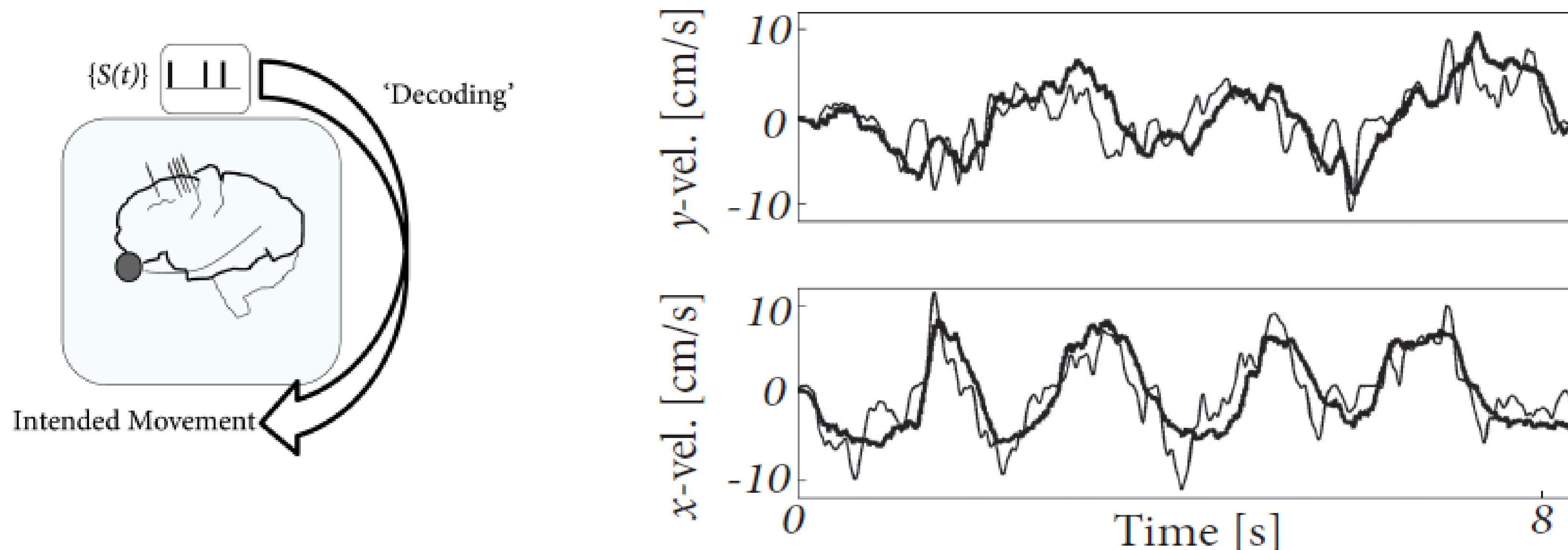


Fig. 11.12: Decoding hand velocity from spiking activity in area MI of cortex. The real hand velocity (thin black line) is compared to the decoded velocity (thick black line) for the x - (top) and the y -components (bottom). Modified from Truccolo et al. (2005).

Neuronal Dynamics **week 7– Suggested Reading/selected references**

Reading: W. Gerstner, W.M. Kistler, R. Naud and L. Paninski,
Neuronal Dynamics: from single neurons to networks and models of cognition. Ch. 6,10,11: Cambridge, 2014

Nonlinear and adaptive IF

Fourcaud-Trocme, N., Hansel, D., van Vreeswijk, C., and Brunel, N. (2003). How spike *J. Neuroscience*, 23:11628-11640.
Badel, L., et al. (2008a). Extracting nonlinear integrate-and-fire, *Biol. Cybernetics*, 99:361-370.
Brette, R. and Gerstner, W. (2005). Adaptive exponential integrate-and-fire *J. Neurophysiol.*, 94:3637- 3642.
Izhikevich, E. M. (2003). Simple model of spiking neurons. *IEEE Trans Neural Netw*, 14:1569-1572.
Gerstner, W. (2008). Spike-response model. *Scholarpedia*, 3(12):1343.

Optimization methods for neuron models, max likelihood, and GLM

-Brillinger, D. R. (1988). Maximum likelihood analysis of spike trains of interacting nerve cells. *Biol. Cybern.*, 59:189-200.
-Truccolo, et al. (2005). A point process framework for relating neural spiking activity to spiking history, neural ensemble, and extrinsic covariate effects. *Journal of Neurophysiology*, 93:1074-1089.
- Paninski, L. (2004). Maximum likelihood estimation of ... *Network: Computation in Neural Systems*, 15:243-262.
- Paninski, L., Pillow, J., and Lewi, J. (2007). Statistical models for neural encoding, decoding, and optimal stimulus design. In Cisek, P., et al. , *Comput. Neuroscience: Theoretical Insights into Brain Function*. Elsevier Science.
Pillow, J., ET AL.(2008). Spatio-temporal correlations and visual signalling... . *Nature*, 454:995-999.

Encoding and Decoding

Rieke, F., Warland, D., de Ruyter van Steveninck, R., and Bialek, W. (1997). *Spikes - Exploring the neural code*. MIT Press,
Keat, J., Reinagel, P., Reid, R., and Meister, M. (2001). Predicting every spike ... *Neuron*, 30:803-817.
Mensi, S., et al. (2012). Parameter extraction and classification *J. Neurophys.*,107:1756-1775.
Pozzorini, C., Naud, R., Mensi, S., and Gerstner, W. (2013). Temporal whitening by . *Nat. Neuroscience*,
Georgopoulos, A. P., Schwartz, A., Kettner, R. E. (1986). Neuronal population coding of movement direction. *Science*, 233:1416-1419.
Donoghue, J. (2002). Connecting cortex to machines: recent advances in brain interfaces. *Nat. Neurosci.*, 5:1085-1088.

**Next year a similar class will be taught.
What should be improved?**

*‘Exercises and Miniprojects take a lot of time,
more than other subjects at 4 ECTS.’*

- workload for a 4 credit course (=6 h p. week, for 18 weeks)
In addition to class 9-12: 2h or less, 3h, 4h or more
[1 credit = 27 hours work total = 1.5 h p. week, for 18 weeks]

Projects: Next year a similar class will be taught. What should be improved?

‘We learn nothing while doing the projects’

‘We just connect the dots’

agree – not sure - disagree

‘The instructions of the graded exercises could be more precise’

agree – not sure - disagree

*‘we spend more time coding than learning things
which is not the goal of the course’*

agree – not sure - disagree

**Next year a similar class will be taught.
What should be improved?**

Keep 3 projects?

Reduce to 1 project, but code 'from scratch'?

More freedom in the projects?

Less freedom (clearer instructions) in the project?

**Next year a similar class will be taught.
What should be improved?**

‘I am more efficient in lectures than in MOOCs’

agree – not sure - disagree

‘2 hours of video needs 4 hours to watch and understand,

‘The inverted classroom is not efficient’

agree – not sure - disagree

- Keep video lectures as an available tool
- Offer at least 10 out of 13

**Next year a similar class will be taught.
What should be improved?**

‘The slides should be redesigned’

‘The slides are too dull (almost without any text)’

agree – not sure - disagree

Quick feedback on course:

“*What can I do better and differently next year?*”

- support: link to book chapter, video, slides
not sufficient, sufficient, good, excellent
- integrated exercises?
repeat next year, do not repeat next year
- workload for a 4 credit course (=6 h p. week, for 18 weeks)
In addition to class 9-12: 2h or less, 3h, 4h or more
- difficulty?
easier than other theory classes,
same, harder than other theory classes
- other points?

The END

Neuronal Dynamics – Quiz 9.2. Nullclines for constant input

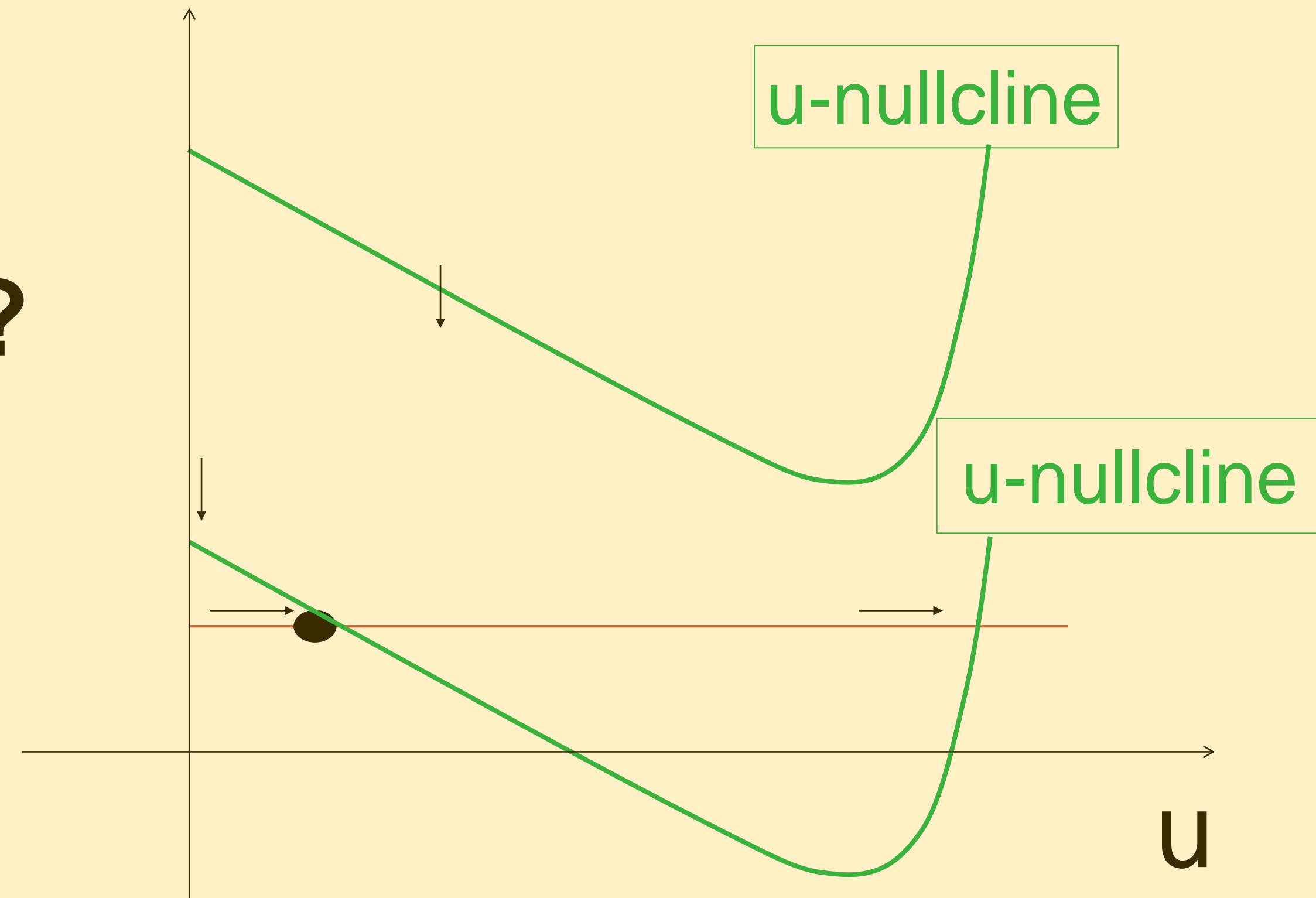
$$\tau \frac{du}{dt} = -(u - u_{rest}) + \Delta \exp\left(\frac{u - \vartheta}{\Delta}\right) + w + RI(t)$$

$$\tau_w \frac{dw}{dt} = a(u - u_{rest}) - w + b \tau_w \sum_f \delta(t - t^f)$$

~~$a=0$~~ Only during reset

What happens if input switches from $I=0$ to $I>0$?

- ☐ u-nullcline moves horizontally
- ☐ u-nullcline moves vertically
- ☐ w-nullcline moves horizontally
- ☐ w-nullcline moves vertically

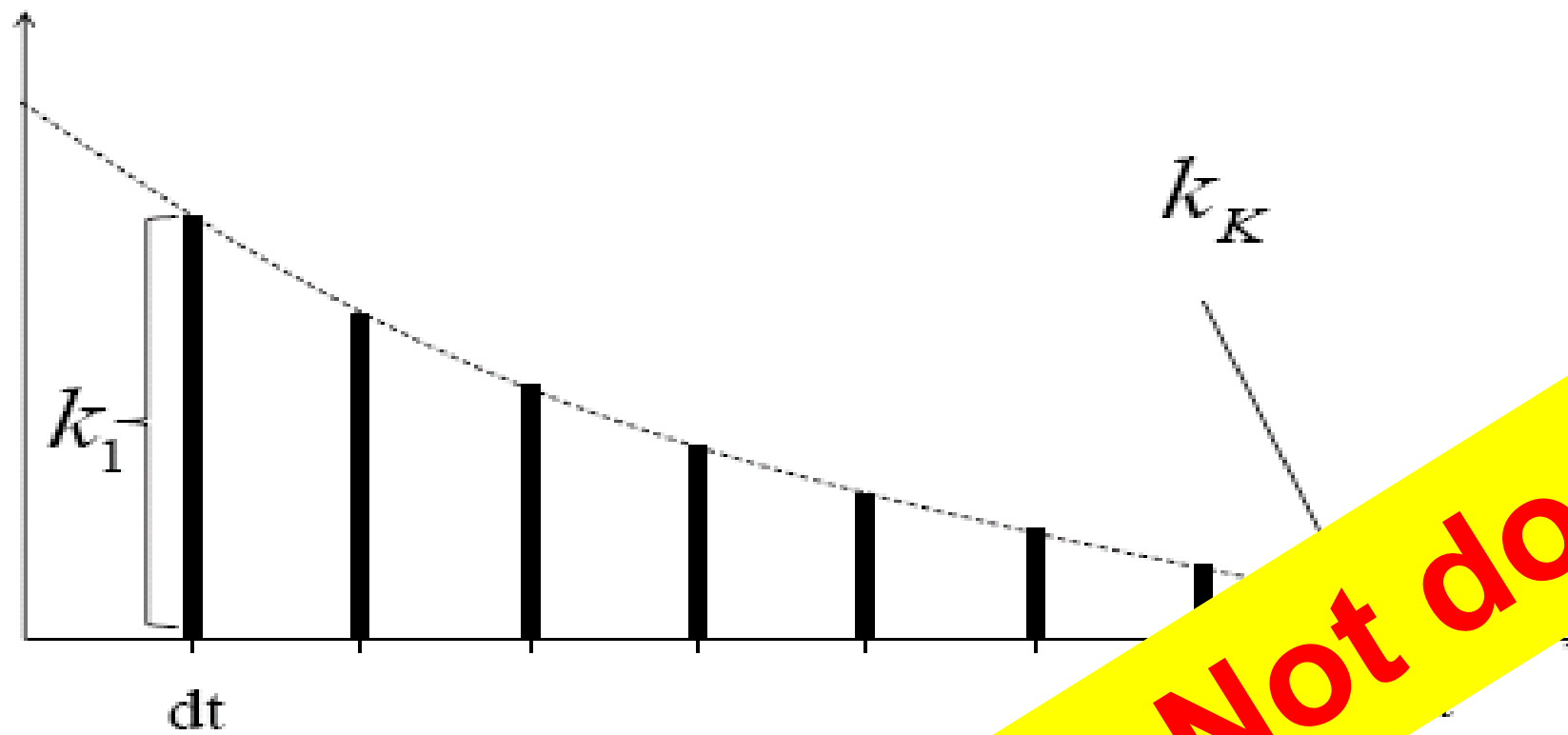


Neuronal Dynamics – 9.5 Parameter estimation: voltage

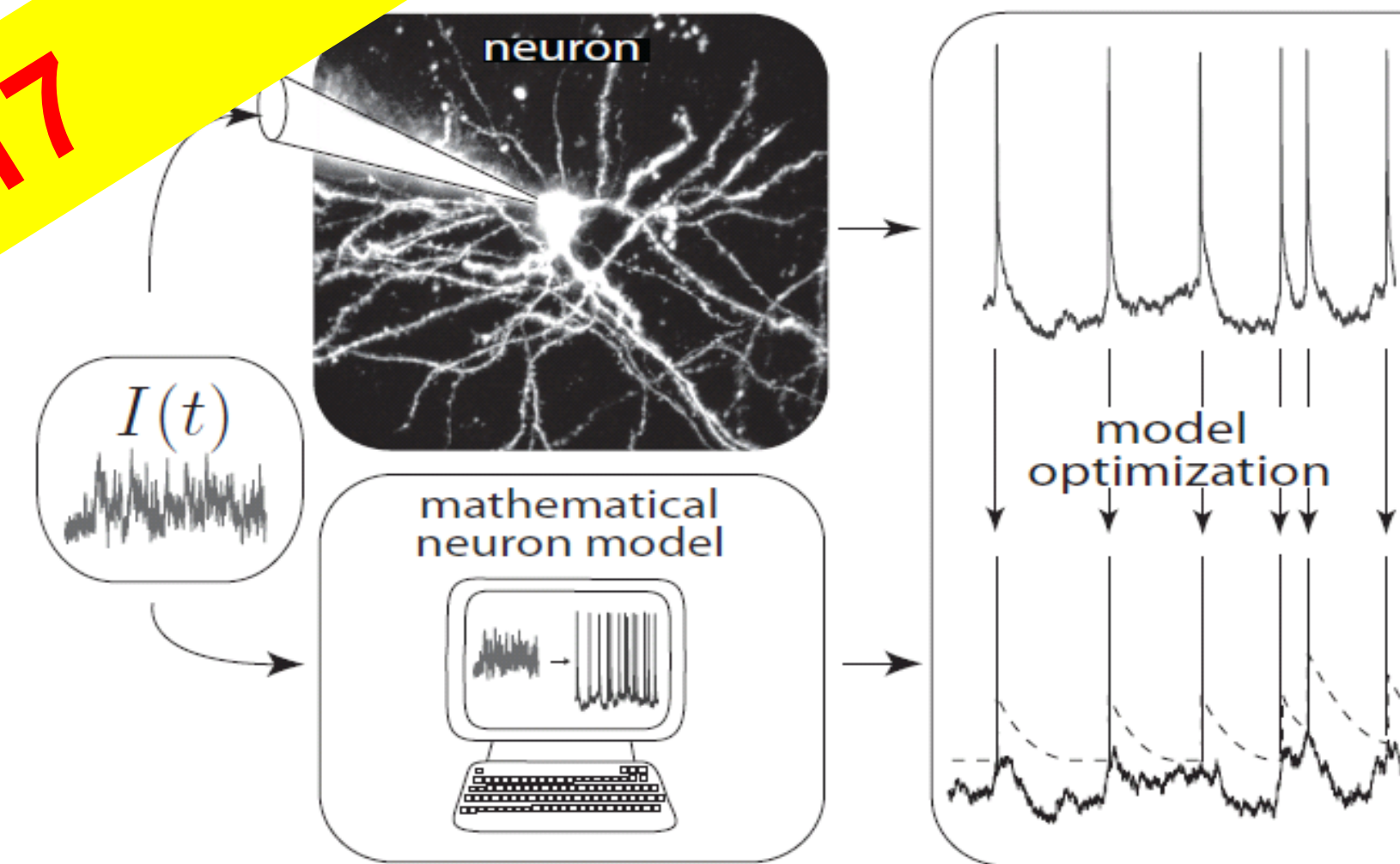
Linear in parameters = linear fit = quadratic problem

$$u(t) = \int_0^\infty \kappa(s) I(t-s) ds + u_{rest}$$

$$u(t_n) = \sum k_k I_{n-k} + u_{rest}$$



comparison model-data



Not done in 2017

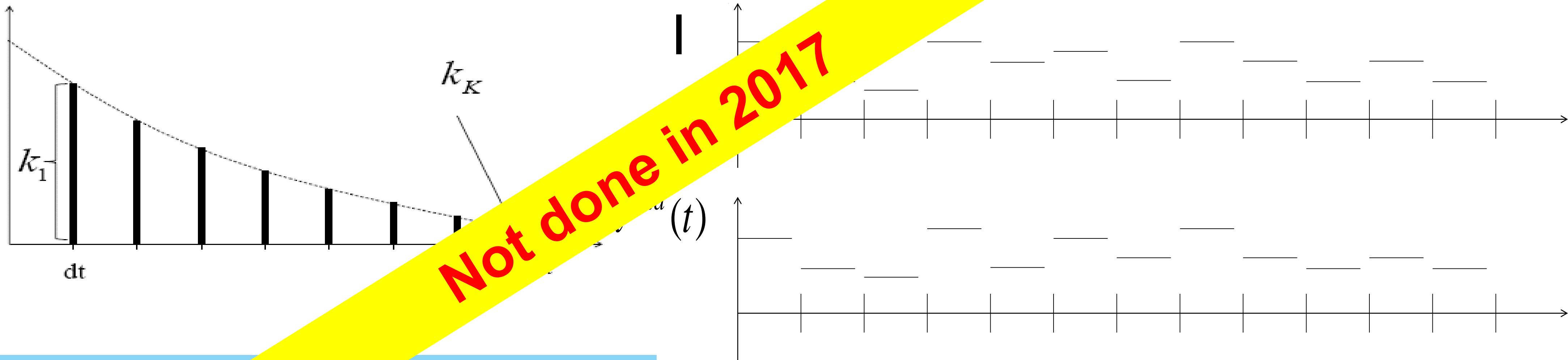
Blackboard: Riemann-sum

Neuronal Dynamics – 9.5 Parameter estimation: voltage

Linear in parameters = linear fit

$$u(t) = \int_0^\infty \kappa(s) I(t-s) ds + u_{rest}$$

$$u(t_n) = \sum k_k I_{n-k} + u_{rest}$$



Blackboard error function

$$E = \sum_n \left[u^{data}(t_n) - \sum_{k=1}^K k_k I_{n-k} - u_{rest} \right]^2$$

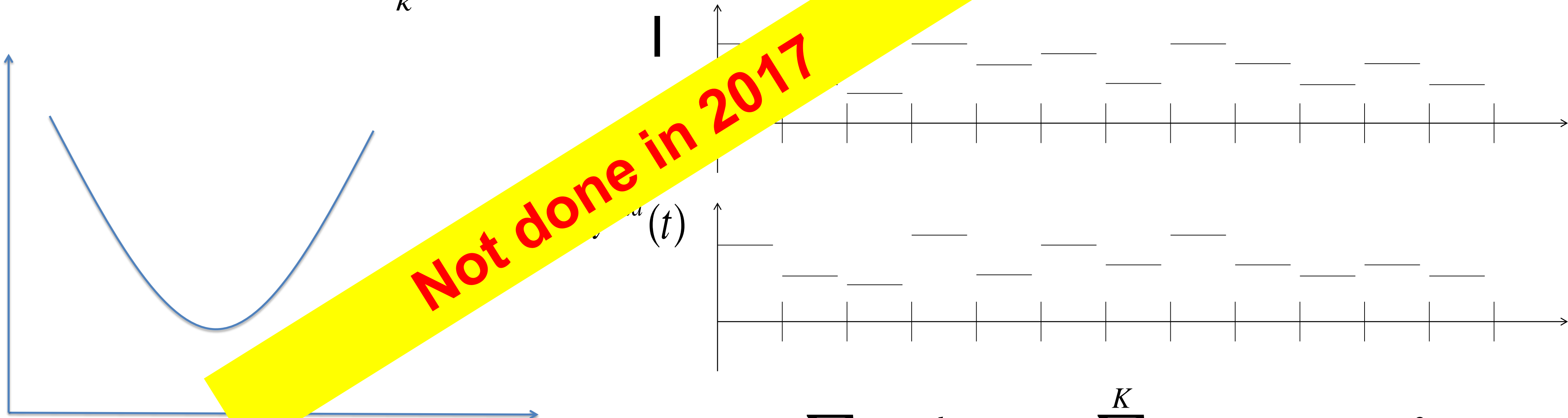
Neuronal Dynamics – 9.5 Parameter estimation: voltage

Linear in parameters = linear fit = quadratic optimization

Model

$$u(t) = \int_0^\infty \kappa(s) I(t-s) ds + u_{rest}$$

$$u(t_n) = \sum_k k_k I_{n-k} + u_{rest}$$



$$E = \sum_n \left[u^{data}(t_n) - \sum_{k=1}^K k_k I_{n-k} - u_{rest} \right]^2$$

Exercise 3 NOW: optimize 1 free parameter

Model

$$u_n = RI_n$$

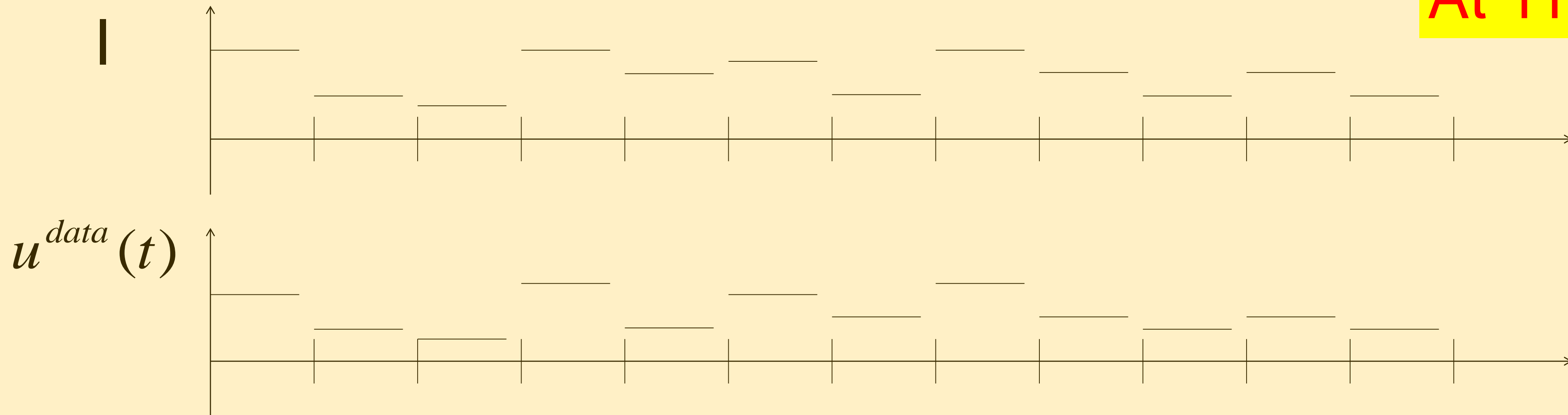
Data

$$u^{data}(t_n)$$

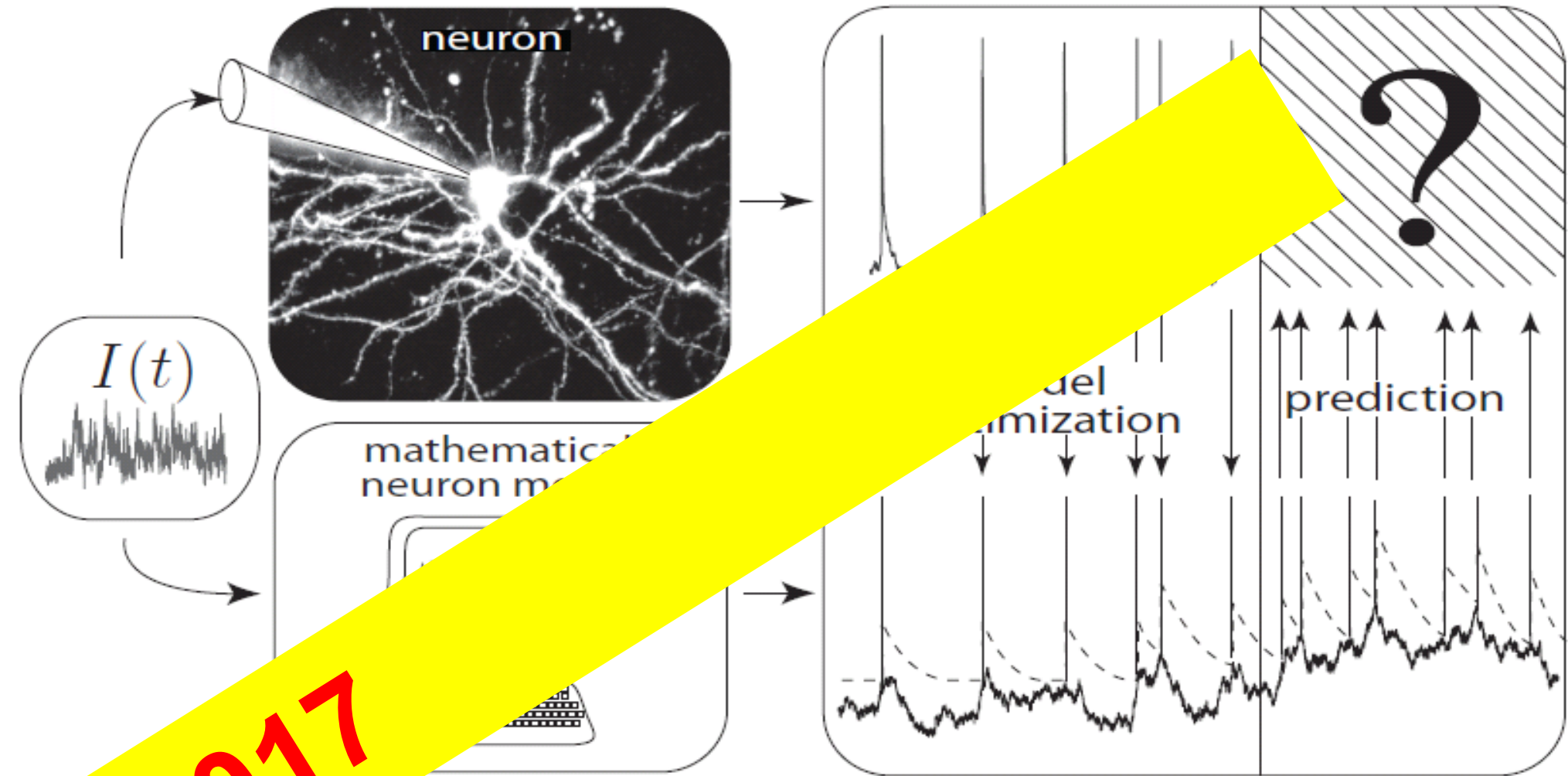
Optimize parameter R, so as to have a minimal error

$$E = \sum_n [u^{data}(t_n) - RI_n]^2$$

Next lecture
At 11h40



Neuronal Dynamics – What is a good neuron model?



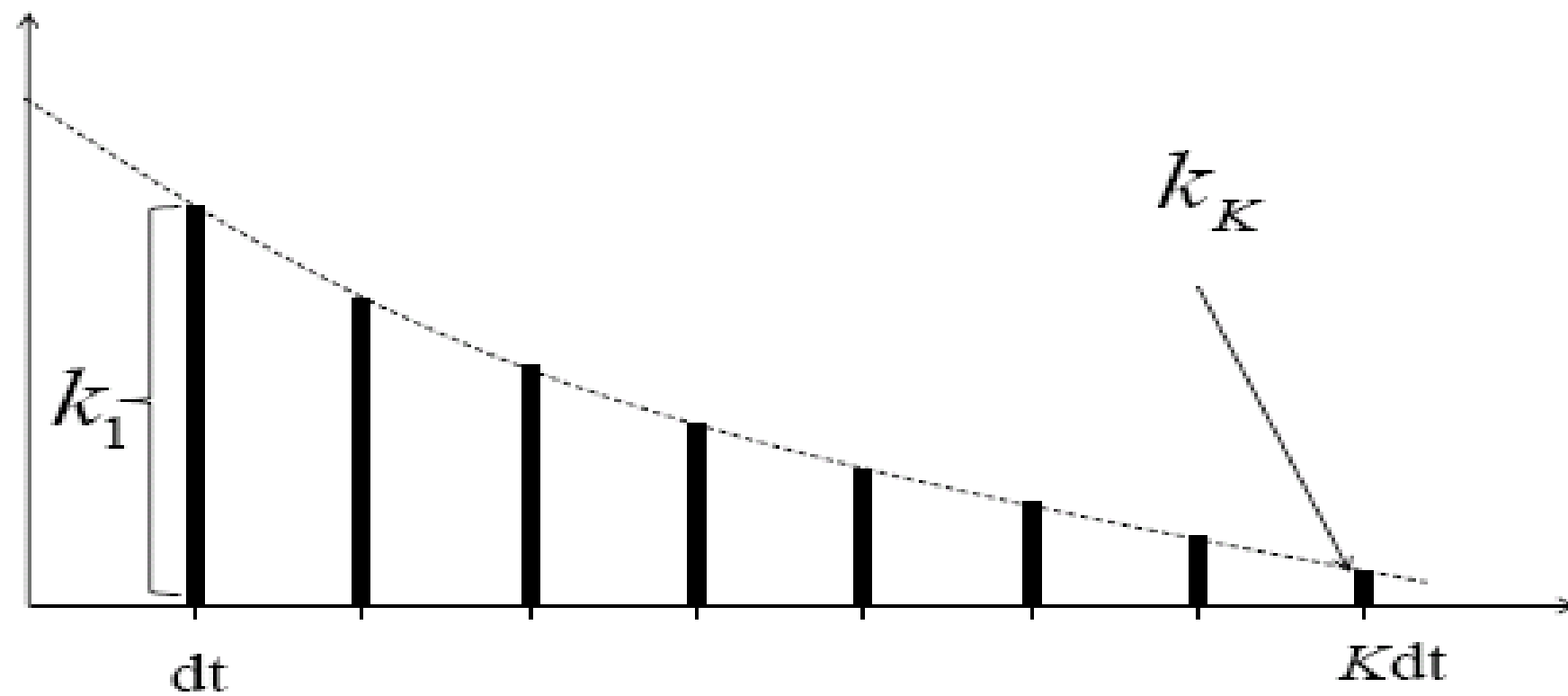
Not done in 2017

- A) Predict spike times
- B) Predict subthreshold voltage
- C) Easy to interpret (not a 'black box')
- D) Flexible
- E) Systematic: 'optimize' parameters

Neuronal Dynamics – 9.5 Parameter estimation: voltage

Vector notation

$$u(t_n) = \sum_k k_k I_{n-k} + u_{rest}$$



$$u(t_n) = \mathbf{k} \cdot \mathbf{x}_n$$

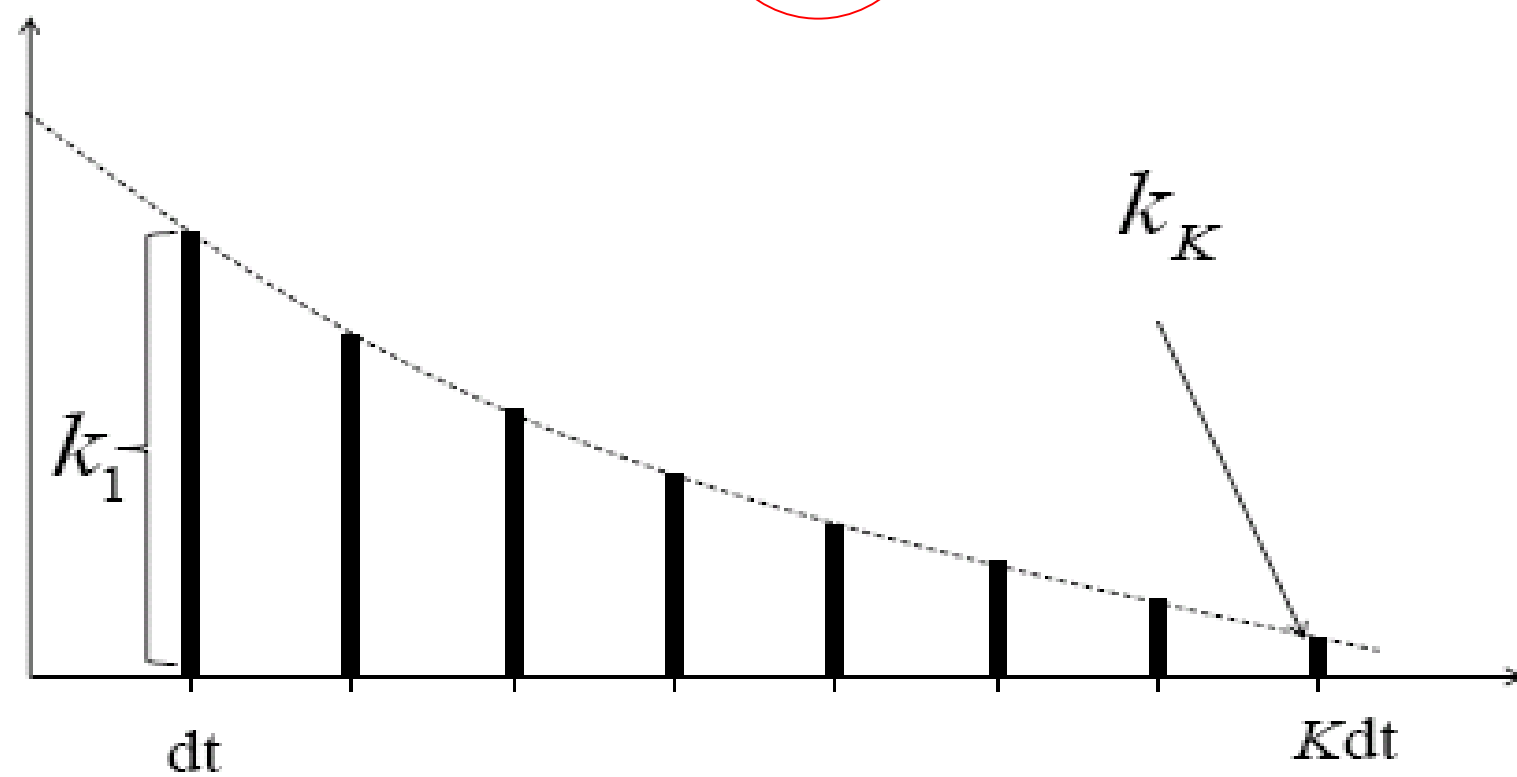
$$E = \sum_n \left[u^{data}(t_n) - \sum_{k=1}^K k_k I_{n-k} - u_{rest} \right]^2$$

Neuronal Dynamics – 9.5 Parameter estimation: voltage

Linear in parameters = linear fit = quadratic problem

$$u(t) = \int_0^\infty \kappa(s) I(t-s) ds + u_{rest} + \int_0^\infty \eta(s) S(t-s) ds$$

$$u(t_n) = \sum k_k I_{n-k} + u_{rest}$$



$$u(t_n) = \vec{k} \cdot \vec{x}_n$$

time \ input	\vec{x}				
	x_1	x_2	x_3	...	x_K
$t=K+1$	I_K	I_{K-1}	I_{K-2}	...	I_1
$t=K+2$	I_{K+1}	I_K	I_{K-1}	...	I_2
$t=K+3$	I_{K+2}	I_{K+1}	I_K	...	I_3
...					
...					
...					
$t=T$	I_T	I_{T-1}	I_{T-2}	...	I_{T-K+1}

$$E = \sum_n \left[u^{data}(t_n) - \sum_{k=1}^K k_k I_{n-k} - u_{rest} \right]^2$$