

# COM303: Digital Signal Processing

Lecture 18: Multirate signal processing

#### overview

- ▶ ideal and practical sampling and interpolation
- bandpass sampling
- ► multirate signal processing

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$$x(t) \longrightarrow x[n]$$

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ideally in practice

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ideally

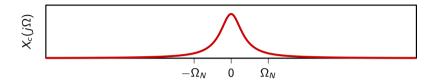
$$x[n] = \langle x(t), \operatorname{sinc}\left(\frac{t - nT_s}{T_s}\right) \rangle$$

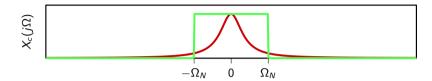
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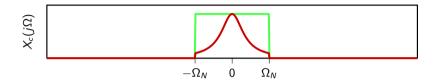
ideally

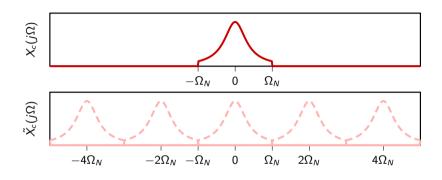
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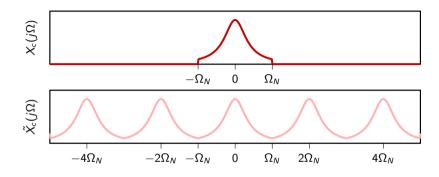
$$X(e^{j\omega}) = X\left(j\Omega_N rac{\omega \mod 2\pi}{\pi}
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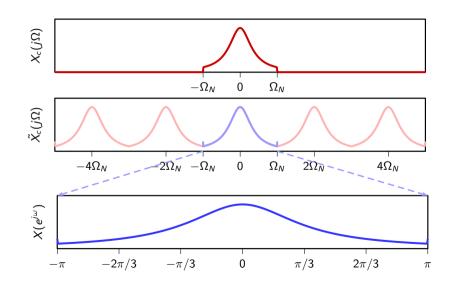












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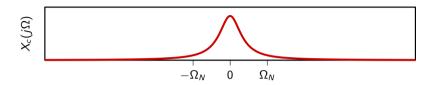
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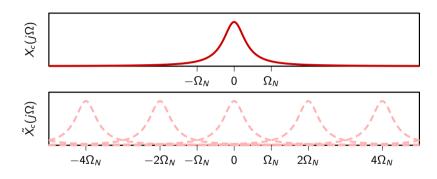
#### in practice

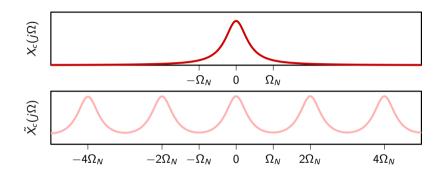
$$x[n] = x(nT_s)$$

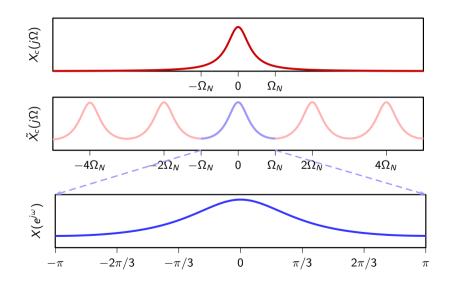
$$X(e^{j\omega}) = \frac{\Omega_N}{\pi} \sum_{k=-\infty}^{\infty} X_c \left( j\Omega_N \frac{\omega}{\pi} - 2jk\Omega_N \right)$$

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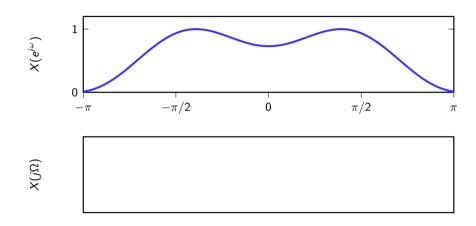
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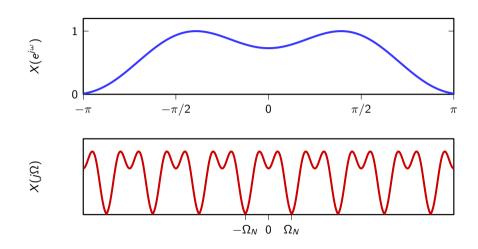
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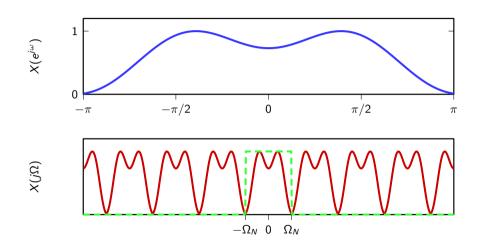
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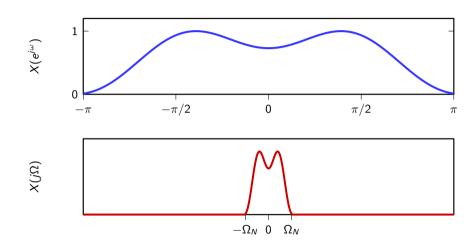
$$x(t) = \sum_{n=-\infty}^{\infty} x[n] \operatorname{sinc}\left(\frac{t - nT_s}{T_s}\right)$$

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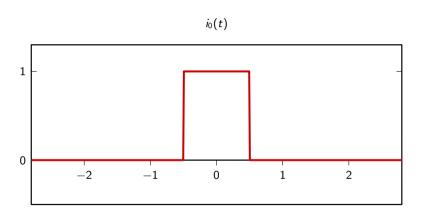
$$X(j\Omega) = ?$$

## Practical interpolation

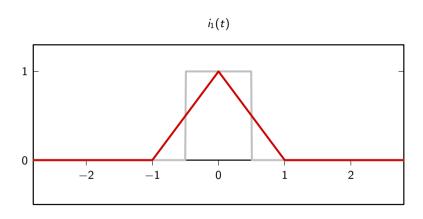
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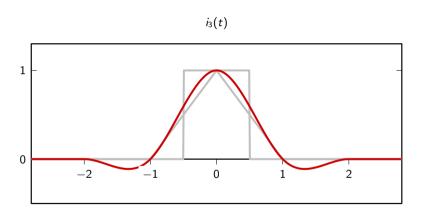
# Local interpolators



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# Spectral representation (I)

$$X(j\Omega) = \int_{-\infty}^{\infty} x(t) e^{-j\Omega t} dt$$

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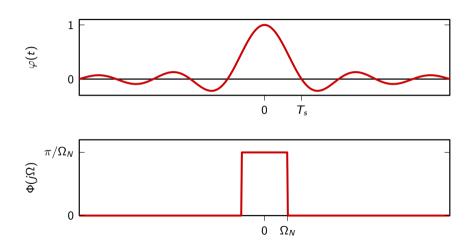
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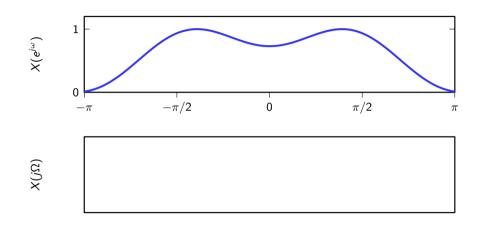
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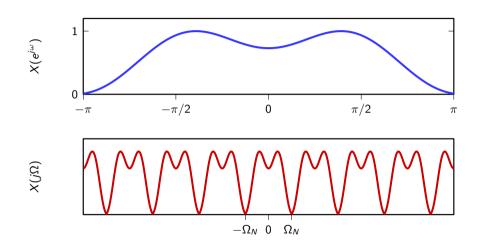
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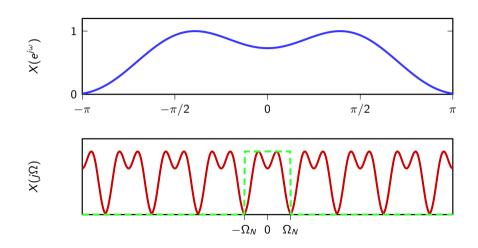
$$egin{aligned} i(t) &= \operatorname{sinc}(t) \ I(j\Omega) &= \operatorname{rect}\left(rac{\Omega}{2\pi}
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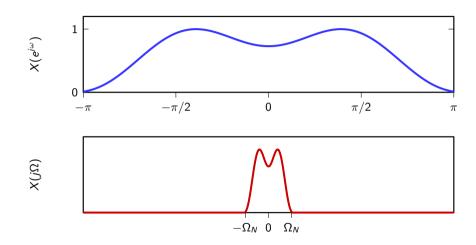
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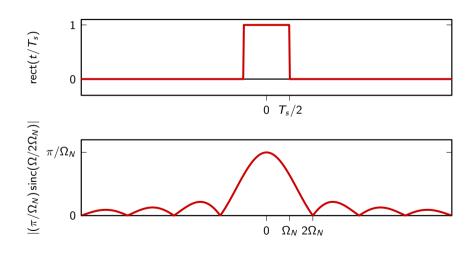


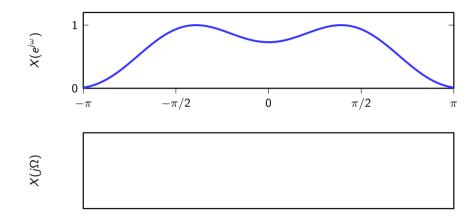


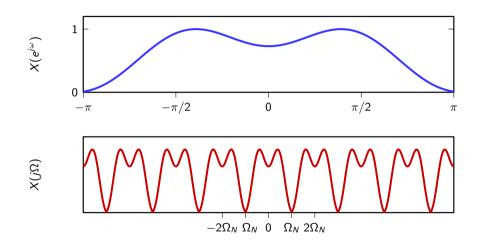


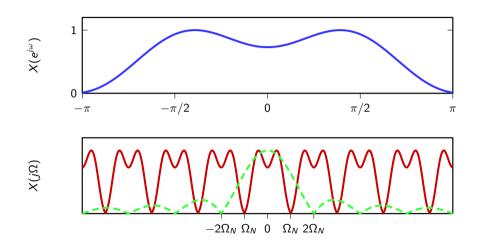


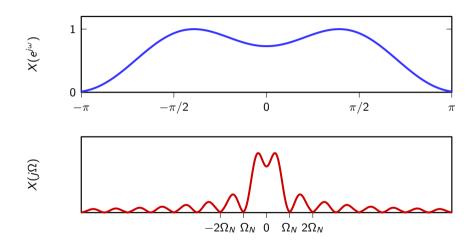
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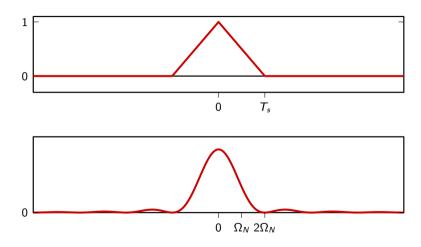


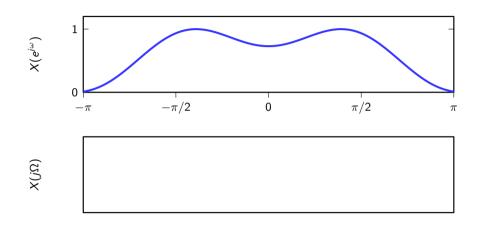


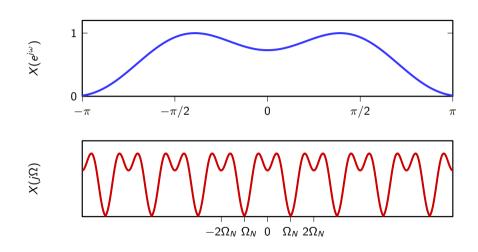


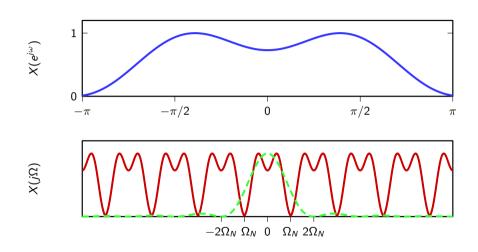


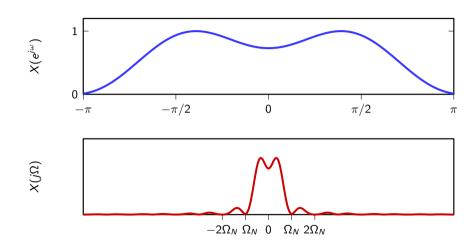












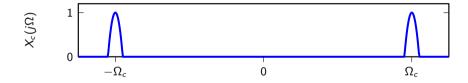


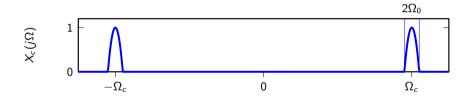
### sampling theorem gives a *sufficient* condition

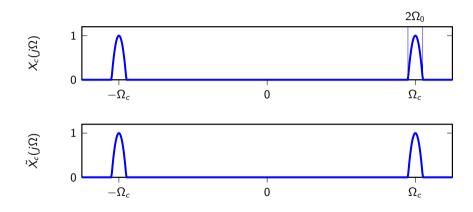
- ▶ in theory,  $\Omega_N > \Omega_{\text{max}}$
- ▶ what if signal is bandpass?

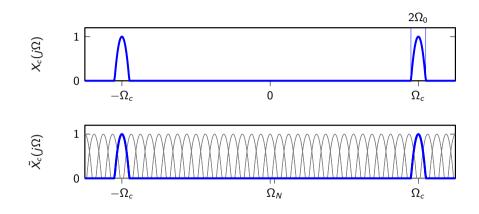
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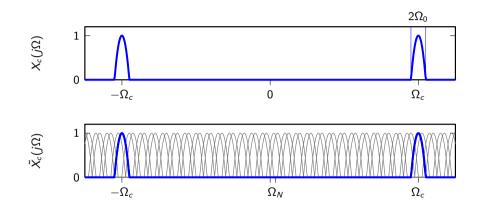
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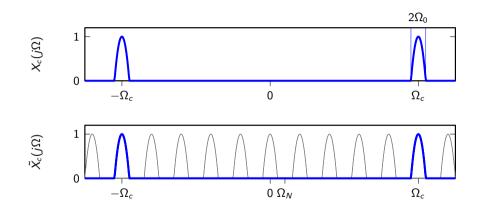


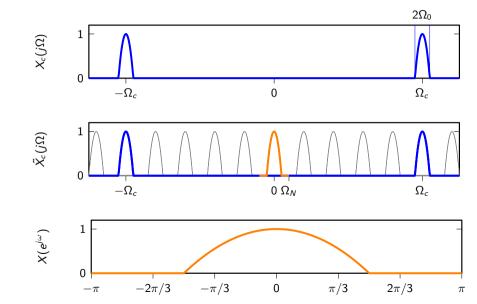












- ▶ bandpass signal:  $X(j\Omega) = 0$  for  $|\Omega \Omega_c| > \Omega_0$
- $lackbox{ }$  no alias requires at least:  $\Omega_N \geq \Omega_0$
- **b** baseband condition:  $\Omega_N = \Omega_c/k$  for some  $k \in \mathbb{N}$
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- ightharpoonup channel width is 9kHZ, i.e.  $f_0 = 4.5$ KHz
- ightharpoonup take a channel at  $f_c = 1.5 \text{MHz}$
- ▶ in theory:  $F_s \ge 2 * 1,504,500$ Hz,  $T_s < 10^{-6}$  seconds!
- ▶ antialias:  $F_s \ge 2f_0 \Rightarrow F_s \ge 9$ KHz
- ▶ baseband:  $kF_s/2 = 1500$ kHz
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- upsampling
- downsampling
- applications

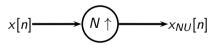
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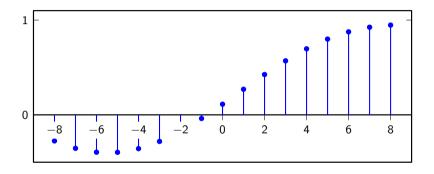
- ▶ why multirate?
- upsampling
- downsampling
- applications

### **Upsampling**

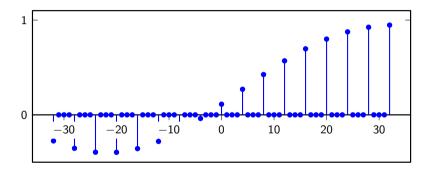
$$x_{NU}[n] = \left\{ egin{array}{ll} x[k] & ext{for } n=kN, & k \in \mathbb{Z} \\ 0 & ext{otherwise.} \end{array} 
ight.$$



# Example: upsampling by 4



### Example: upsampling by 4



$$X_{NU}(z) = \sum_{k=-\infty}^{\infty} x_{NU}[k]z^{-k}$$
$$= \sum_{k=-\infty}^{\infty} x[k]z^{-Nk}$$
$$= X(z^{N})$$

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$$= \sum_{k=-\infty}^{\infty} x[k]z^{-Nk}$$
$$= X(z^{N})$$

$$X_{NU}(e^{j\omega}) = X(e^{j\omega N})$$

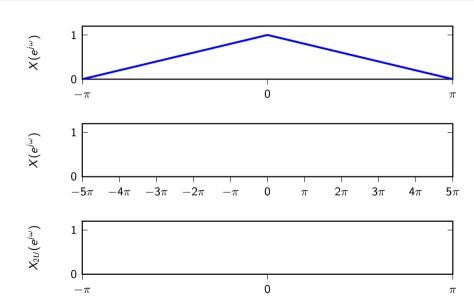
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$$= X(z^{N})$$

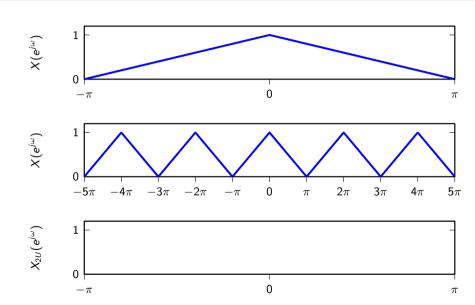
$$X_{NU}(e^{j\omega}) = X(e^{j\omega N})$$

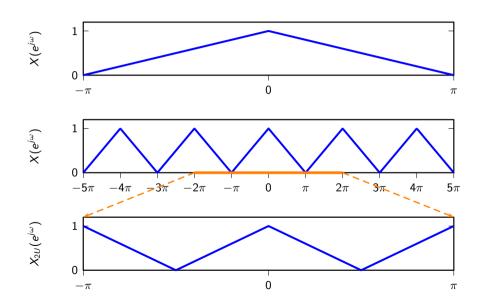
$$X_{NU}(z) = \sum_{k=-\infty}^{\infty} x_{NU}[k]z^{-k}$$

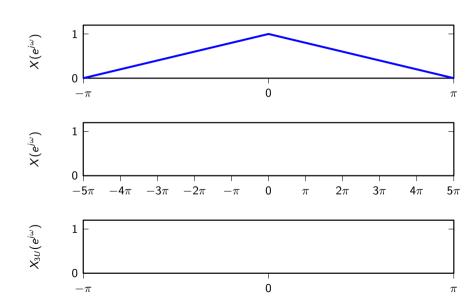
$$= \sum_{k=-\infty}^{\infty} x[k]z^{-Nk}$$

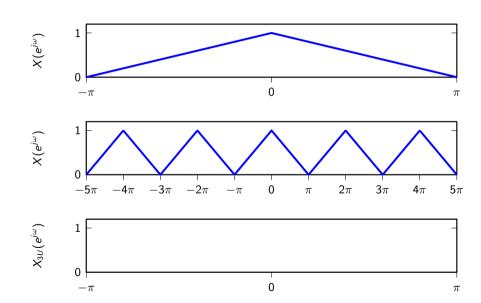
$$= X(z^{N})$$
 $X_{NU}(e^{j\omega}) = X(e^{j\omega N})$ 

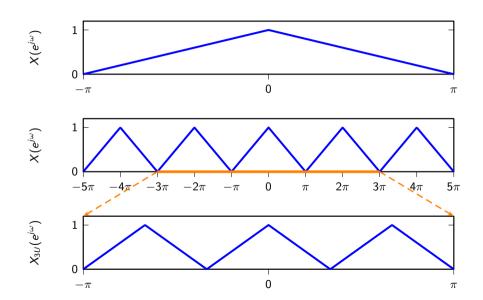


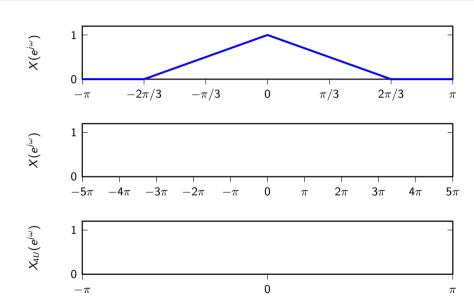


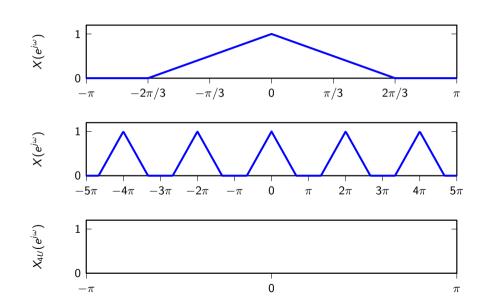


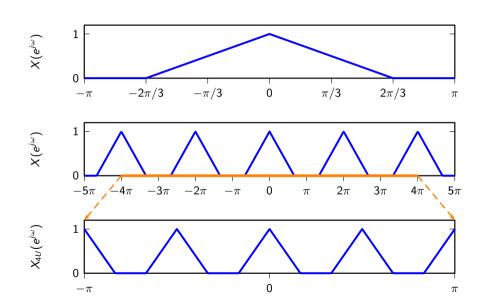












### Upsampling: what we don't like

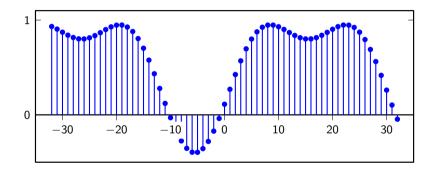
- ▶ in the time domain: zeros between nonzero samples are not "natural"
- ▶ in the frequency domain: extra replicas of the spectrum; can we get rid of them?

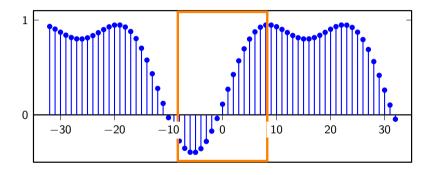
the two problems are the same!

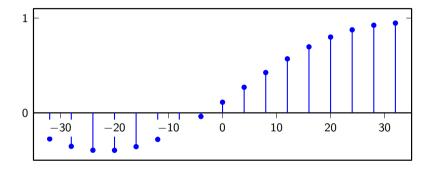
### Upsampling: what we don't like

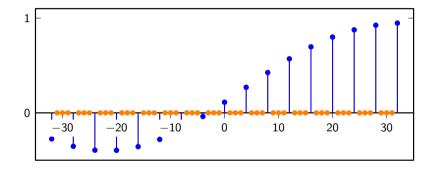
- ▶ in the time domain: zeros between nonzero samples are not "natural"
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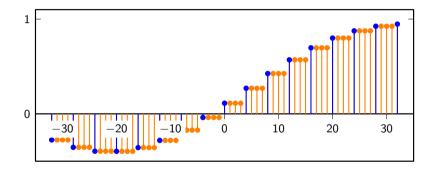
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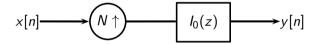






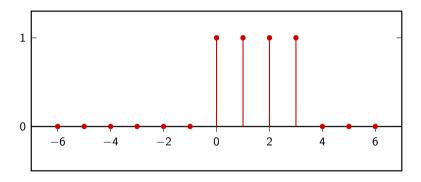


#### Zero-order interpolator



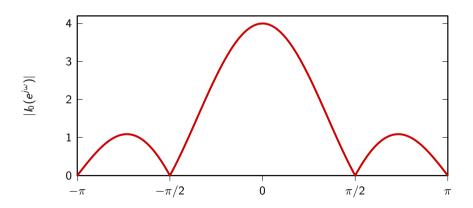
#### Zero-order interpolator for 4-upsampling

$$i_0[n] = u[n] - u[n-4]$$

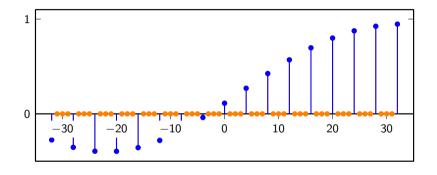


#### Zero-order interpolator for 4-upsampling

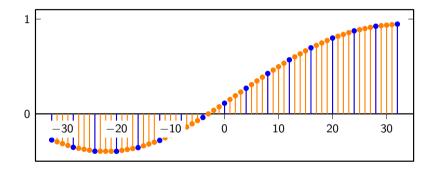
$$|I_0(e^{j\omega})| = \left| \frac{\sin\left(\frac{\omega}{2}N\right)}{\sin\left(\frac{\omega}{2}\right)} \right| \qquad N = 4$$



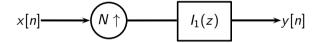
## Upsampling in the time domain, revisited



## Upsampling in the time domain, revisited

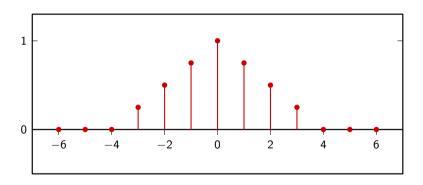


#### first-order interpolator

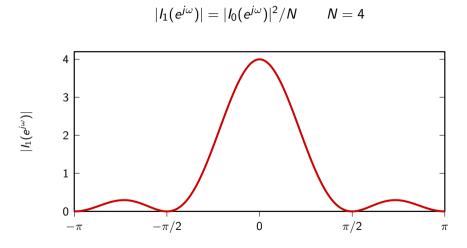


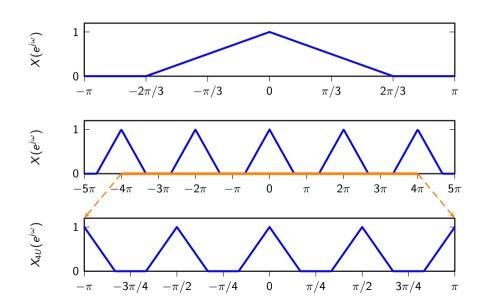
#### first-order interpolator for 4-upsampling

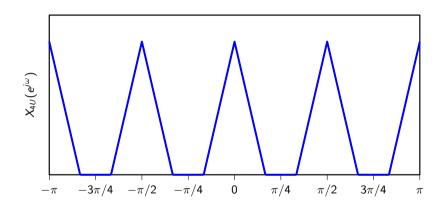
$$i_1[n] = (i_0[n] * i_0[n])/N$$

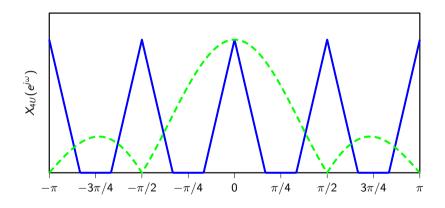


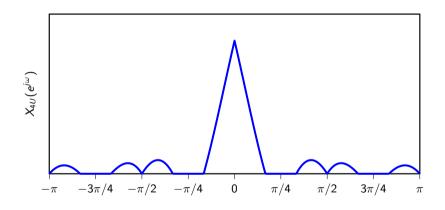
#### first-order interpolator for 4-upsampling

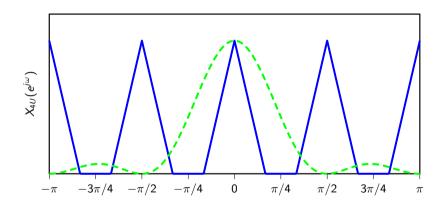


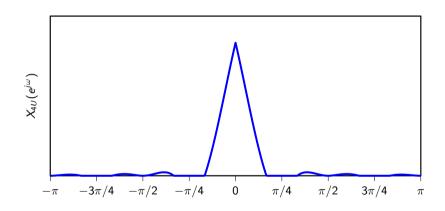


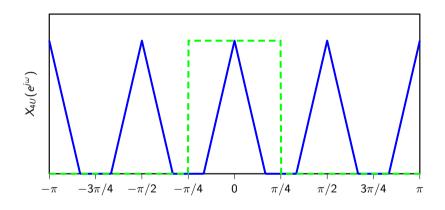


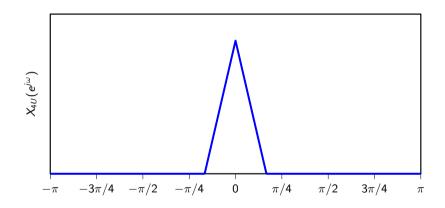




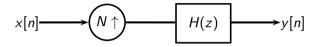






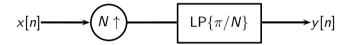


#### ideal digital interpolator



$$H(e^{j\omega}) = \operatorname{rect}(\omega N/2\pi)$$
  
 $h[n] = (1/N)\operatorname{sinc}(n/N)$ 

#### ideal digital interpolator

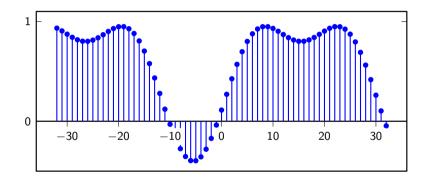


## Downsampling

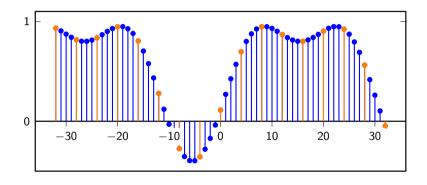
$$x_{ND}[n] = x[nN]$$



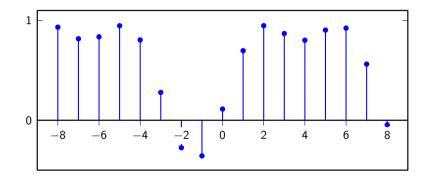
## Example: downsampling by 4



#### Example: downsampling by 4



#### Example: downsampling by 4



$$X_{ND}(z) = \sum_{k=-\infty}^{\infty} x[kN]z^{-k} = ?$$

if we can compute

$$A(z) = \sum_{k=-\infty}^{\infty} x[kN]z^{-kN}$$

then

$$X_{ND}(z) = A(z^{1/N})$$

$$X_{ND}(z) = \sum_{k=-\infty}^{\infty} x[kN]z^{-k} = ?$$

if we can compute

$$A(z) = \sum_{k=-\infty}^{\infty} x[kN]z^{-kN}$$

then

$$X_{ND}(z) = A(z^{1/N})$$

$$A(z) = \sum_{k=-\infty}^{\infty} x[kN]z^{-kN}$$
$$= \sum_{k=-\infty}^{\infty} \xi[k]x[k]z^{-k}$$

$$\xi[n] = egin{cases} 1 & ext{for } n = k N \\ 0 & ext{otherwise} \end{cases}$$

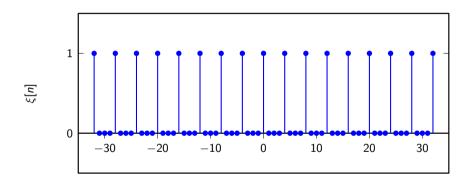
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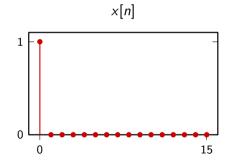
$$\xi[n] = \begin{cases} 1 & \text{for } n = kN \\ 0 & \text{otherwise} \end{cases}$$

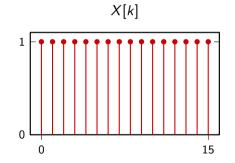
# $\xi[n]$ for N=4



# Blast from the past: DFT of $x[n] = \delta[n], \quad x[n] \in \mathbb{C}^N$

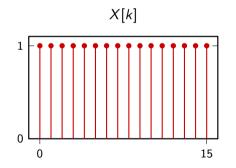
$$X[k] = \sum_{n=0}^{N-1} \delta[n] e^{-j\frac{2\pi}{N}nk} = 1$$

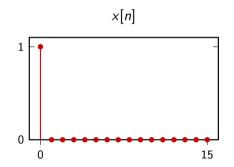




#### From the other side:

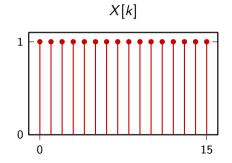
$$\mathsf{IDFT}\left\{1\right\} = \frac{1}{N} \sum_{m=0}^{N-1} e^{j\frac{2\pi}{N}mn} = \delta[\mathit{n}]$$

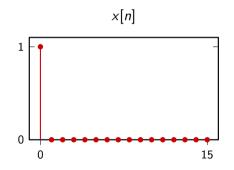




#### From the other side:

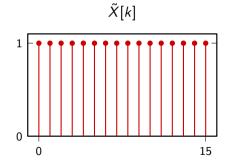
$$\mathsf{IDFT}\left\{1\right\} = \frac{1}{N} \sum_{m=0}^{N-1} e^{j\frac{2\pi}{N}mn} = \begin{cases} 1 & \mathsf{for} \ n=0 \\ 0 & \mathsf{otherwise} \end{cases} \qquad n = 0, \dots, N-1$$

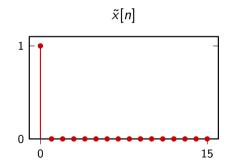




#### From the other side:

$$rac{1}{N}\sum_{m=0}^{N-1}e^{jrac{2\pi}{N}mn}=egin{cases} 1 & ext{for } n \mod N=0 \ 0 & ext{otherwise} \end{cases}$$





$$\xi[n] = \frac{1}{N} \sum_{m=0}^{N-1} e^{j\frac{2\pi}{N}mn}$$

$$A(z) = \sum_{k=-\infty}^{\infty} \xi[k] x[k] z^{-k}$$

$$= \frac{1}{N} \sum_{m=0}^{N-1} \sum_{k=-\infty}^{\infty} x[k] e^{j\frac{2\pi}{N}mk} z^{-k}$$

$$= \frac{1}{N} \sum_{m=0}^{N-1} X(e^{-j\frac{2\pi}{N}m} z)$$

$$\xi[n] = \frac{1}{N} \sum_{m=0}^{N-1} e^{j\frac{2\pi}{N}mn}$$

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$$= \frac{1}{N} \sum_{m=0}^{N-1} X(e^{-j\frac{2\pi}{N}m} z)$$

#### Spectral representation

$$A(e^{j\omega}) = \frac{1}{N} \sum_{m=0}^{N-1} X(e^{j(\omega - \frac{2\pi}{N}m)})$$

#### Spectral representation

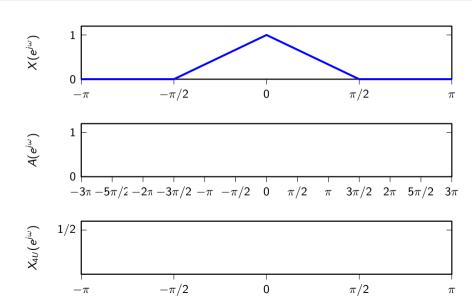
$$X_{ND}(z) = A(z^{1/N}) = \frac{1}{N} \sum_{m=0}^{N-1} X(e^{-j\frac{2\pi}{N}m} z^{\frac{1}{N}})$$

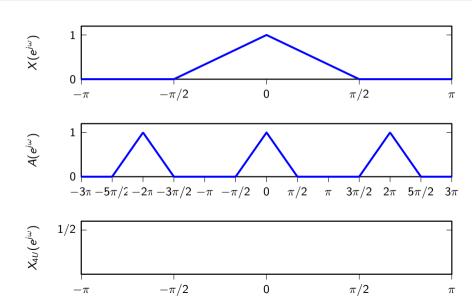
$$X_{ND}(e^{j\omega}) = \frac{1}{N} \sum_{m=0}^{N-1} X(e^{j(\frac{\omega - 2\pi m}{N})})$$

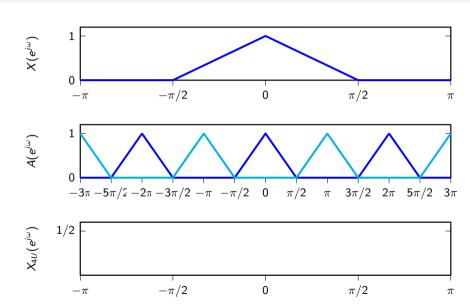
#### Spectral representation

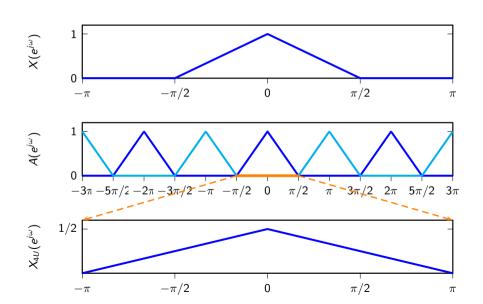
$$X_{ND}(z) = A(z^{1/N}) = \frac{1}{N} \sum_{m=0}^{N-1} X(e^{-j\frac{2\pi}{N}m} z^{\frac{1}{N}})$$

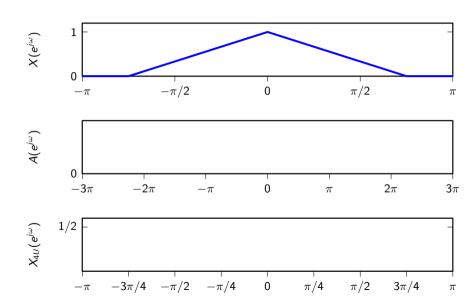
$$X_{ND}(e^{j\omega}) = \frac{1}{N} \sum_{m=0}^{N-1} X(e^{j(\frac{\omega-2\pi m}{N})})$$

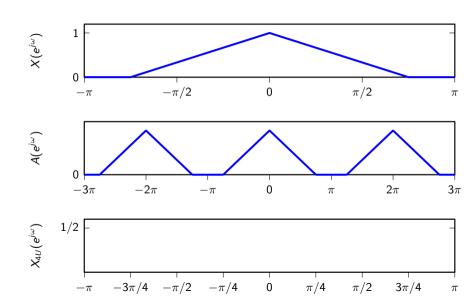


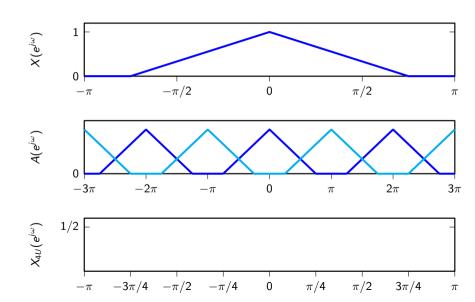


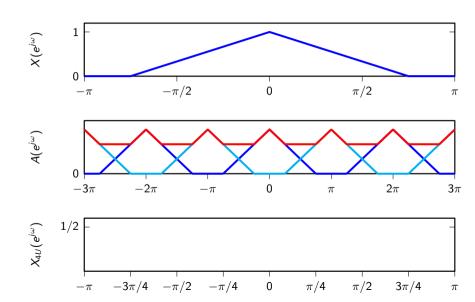


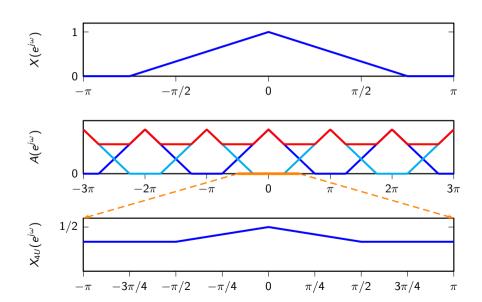


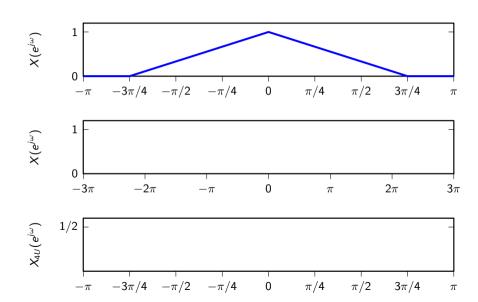


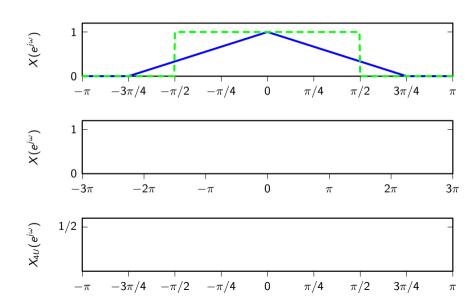


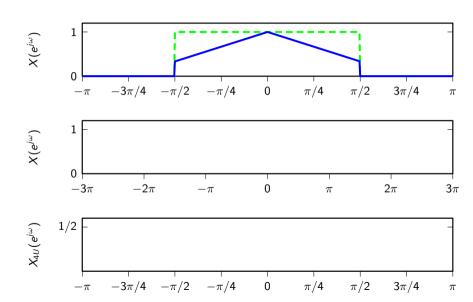


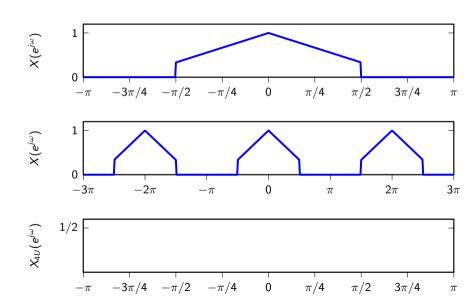


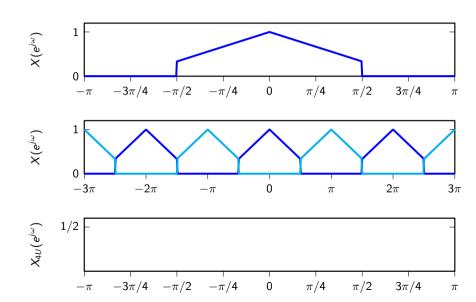


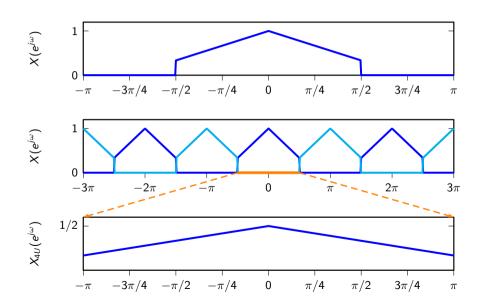




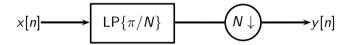


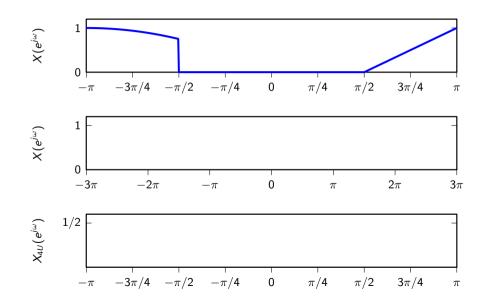


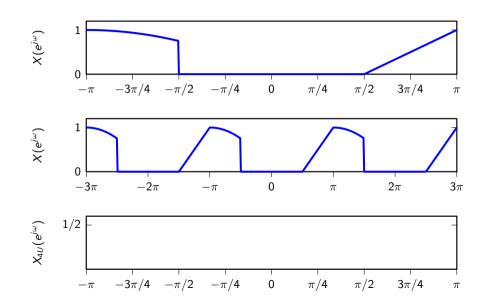


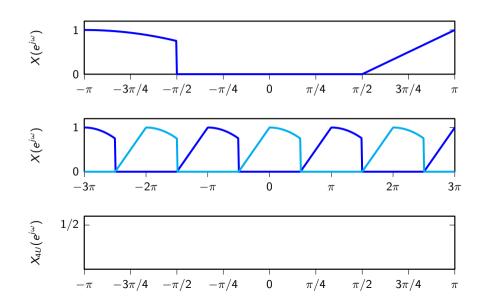


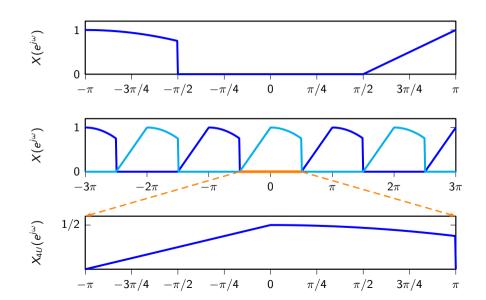
### Downsampling



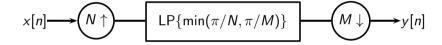








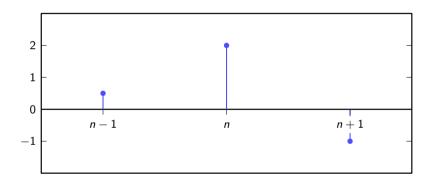
#### Rational Sampling Rate Change

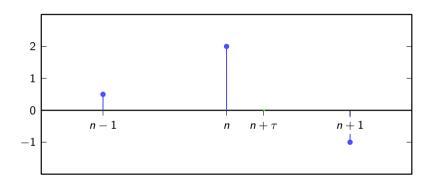


#### Rational Sampling Rate Change

#### Example CD to DVD:

- ► CD:  $F_s = 44100$ Hz
- ▶ DVD:  $F_S = 48000$ Hz
- ▶ in practice, we use time-varying local interpolation





- we want to compute  $x(n+\tau)$ , with  $|\tau| < 1/2$
- ► local Lagrange approximation around *n*

$$x_{L}(n;t) = \sum_{k=-N}^{N} x[n-k] L_{k}^{(N)}(t)$$

$$L_{k}^{(N)}(t) = \prod_{\substack{i=-N\\i\neq n}}^{N} \frac{t-i}{k-i} \qquad k = -N, \dots, N$$

 $\times (n+\tau) \approx x_L(n;\tau)$ 

- we want to compute  $x(n+\tau)$ , with  $|\tau| < 1/2$
- $\triangleright$  local Lagrange approximation around n

$$x_L(n;t) = \sum_{k=-N}^{N} x[n-k] L_k^{(N)}(t)$$

$$L_k^{(N)}(t) = \prod_{\substack{i=-N\\i\neq n}}^{N} \frac{t-i}{k-i} \qquad k = -N, \dots, N$$

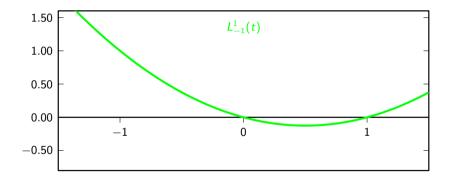
 $\times$   $(n+\tau) \approx x_L(n;\tau)$ 

- we want to compute  $x(n+\tau)$ , with  $|\tau| < 1/2$
- $\triangleright$  local Lagrange approximation around n

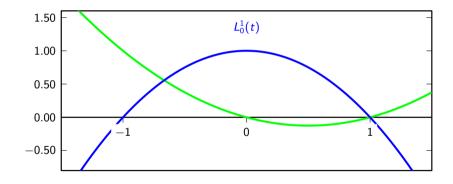
$$x_L(n;t) = \sum_{k=-N}^{N} x[n-k] L_k^{(N)}(t)$$

$$L_k^{(N)}(t) = \prod_{\substack{i=-N\\i\neq n}}^{N} \frac{t-i}{k-i} \qquad k = -N, \dots, N$$

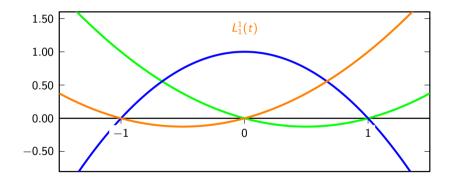
# 2nd-order Lagrange interpolation polynomials (N=1)



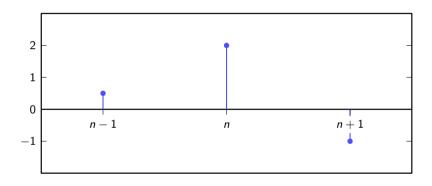
# 2nd-order Lagrange interpolation polynomials (N=1)



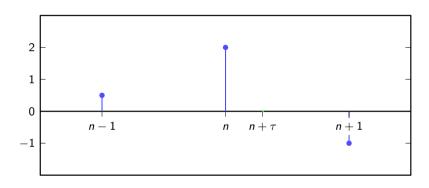
# 2nd-order Lagrange interpolation polynomials (N=1)



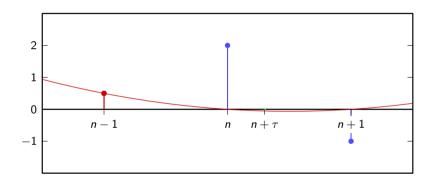
# Lagrange interpolation (N=1)

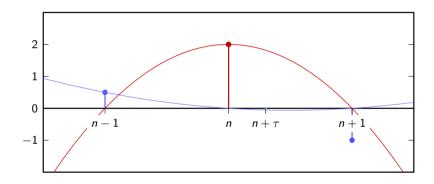


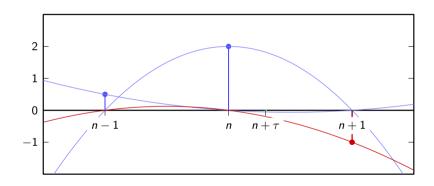
# Lagrange interpolation (N = 1)

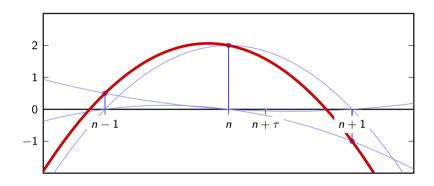


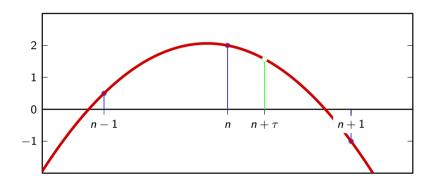
# Lagrange interpolation (N = 1)











- define  $d_{\tau}[k] = L_k^{(N)}(\tau)$ ,  $k = -N, \dots, N$

- ▶  $d_{\tau}[k]$  is a (2N+1)-tap FIR (dependent on  $\tau$ )

- $ightharpoonup x(n+\tau) \approx x_L(n;\tau)$
- define  $d_{\tau}[k] = L_k^{(N)}(\tau), k = -N, \dots, N$

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## Example (N = 1, second order approximation)

$$L_{-1}^{(1)}(t) = t \frac{t-1}{2}$$
 $L_{0}^{(1)}(t) = (1-t)(1+t)$ 
 $L_{1}^{(1)}(t) = t \frac{t+1}{2}$ 

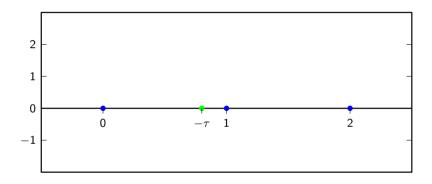
## Example (N = 1, second order approximation)

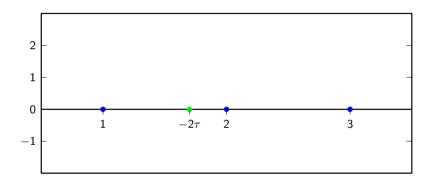
$$d_{0.2}[n] = egin{cases} -0.08 & n = -1 \ 0.96 & n = 0 \ 0.12 & n = 1 \ 0 & ext{otherwise} \end{cases}$$

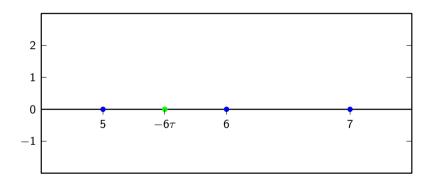
for every 147 CD samples, generate 160 DVD samples

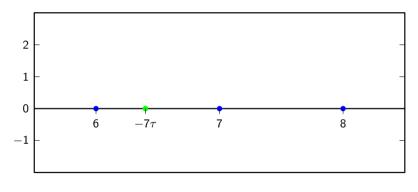


## CD to DVD, revisited, $\tau[1] = 0.06875$



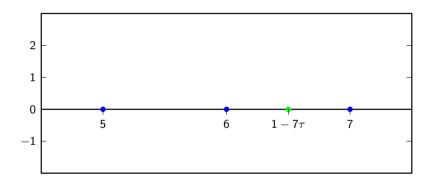


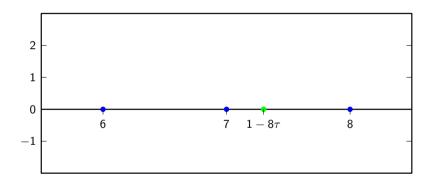




but  $-7\tau<-0.5$ 

## CD to DVD, revisited: repeat a sample





efficient local interpolation with 160 3-tap filters, used in sequence