# Exercise 6: 9<sup>th</sup> and 16<sup>th</sup> of April 2019 CS-526 Learning Theory

Most of the following exercises are extracted from the books "Pattern Recognition and Machine Learning" by Bishop and "Bayesian Reasoning and Machine Learning" by Barber.

#### Problem 1

Suppose we have some data  $(x_i, y_i), i = 1, ..., m$  where  $x_i, y_i \in \mathbb{R}$  and we want to find a regression function y = f(x). We use a fully Bayesian model:

$$y = \sum_{a=1}^{p} w_a x^a + \xi,$$

where the inputs  $x \sim P_0$  are iid and generated according to a prior  $P_0$  and  $\xi \sim \mathcal{N}(0, \sigma^2)$  iid. The  $w_a \in \mathbb{R}$  are regression parameters. We take for  $w_a$  the prior  $\sim e^{-\alpha w_a^2}$  where  $\alpha$ . The parameters  $\alpha$  and  $\sigma^2$  are supposed to be known. So our model for the data generating process is

$$\mathcal{D}(y \mid x, w)\mathcal{D}(x) = (2\pi\sigma^2)^{-1/2} e^{-\frac{1}{2\sigma^2}(y - \sum_{a=1}^p w_a x^a)^2} P_0(x)$$

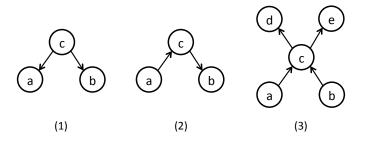
- 1) Write down the joint distribution for  $(y_1, \ldots, y_m, x_1, \ldots, x_m, w_1, \ldots, w_p)$ .
- 2) Draw a Belief Network (directed acyclic graph) corresponding to this probabilistic model.
- 3) Remark 1: Show that the maximum likelihood principle (take  $\alpha = 0$  or equivalently no prior on  $w_a$ 's) is equivalent to empirical risk minimisation in the hypothesis class of functions  $\mathcal{H} \ni f(x) = \sum_{a=1}^{p} w_a x^a$ .
- 4) Remark 2: Consider the MAP principle for estimating  $w_a$ 's and show that it is equivalent to an empirical risk minimization with additional penalty term proportional to  $\alpha \sum_{a=1}^{p} w_a^2$  (this is called ridge regression).
- 5) Remark 3: The ML or MAP estimates of  $w_a$ 's are to viewed in general as summarized versions of a more detailled object, namely the complete posterior distribution  $P(w_1, \ldots, w_p \mid (x_i, y_i)_{i=1}^m)$ . Show that the optimal regression function in a fully Bayesian approach is

$$f(x) = \sum_{a=1}^{p} \mathbb{E}_{w|data}[w_a]x^a$$

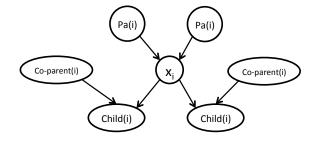
where  $\mathbb{E}_{w|data}$  is the expectation with respect to the posterior distribution  $P(w_1, \ldots, w_p \mid (x_i, y_i)_{i=1}^m)$ .

#### Problem 2

For each case below, is  $a \perp \!\!\! \perp b$  true? And is  $a \perp \!\!\! \perp b | c$  true? If yes, prove your answer.



# Problem 3



Consider a generic belief network (also called Bayesian network). Let  $MB(i) = \{pa(i), child(i), co-parent(i)\}\$  be the Markov blanket of  $x_i$ . Show that

$$p(x_i|\{x_i\}_{i\neq i}) = p(x_i|\{x_v\}_{v\in MB(i)}).$$

## Problem 4 (Bishop, p.371 & 419, Exercise 8.7)



The linear-Gaussian models for the above graph consists of three random variables  $x_1, x_2, x_3$ . The model has the structure equations

$$x_i = \sum_{j \in pa(i)} w_{ij} x_j + b_i + \sqrt{v_i} \epsilon_i, \quad i = 1, 2, 3$$

where pa(i) is the set of parent nodes of node i ( $pa(1) = \emptyset$ ,  $pa(2) = \{1\}$ ,  $pa(3) = \{2\}$ ).

Show that the mean and covariance of the joint distribution for the above graph are given by (hint: use a recursive calculation)

$$\mu = (b_1, b_2 + w_{21}b_1, b_3 + w_{32}b_2 + w_{32}w_{21}b_1)^{\top}$$

$$\Sigma = \begin{pmatrix} v_1 & w_{21}v_1 & w_{32}w_{21}v_1 \\ w_{21}v_1 & v_2 + w_{21}^2v_1 & w_{32}(v_2 + w_{21}^2v_1) \\ w_{32}w_{21}v_1 & w_{32}(v_2 + w_{21}^2v_1) & v_3 + w_{32}^2(v_2 + w_{21}^2v_1) \end{pmatrix}$$

# Problem 5 (Barber, p.75, Exercise 4.4)

The restricted Boltzmann machine (RBM) is a constrained Boltzmann machine on a bipartite graph, consisting of a layer of visible variables  $\mathbf{v} = (v_1, \dots, v_V)^{\top}$  and hidden variables  $\mathbf{h} = (h_1, \dots, h_H)^{\top}$ :

$$p(\mathbf{v}, \mathbf{h}) = \frac{1}{Z(\mathbf{W}, \mathbf{a}, \mathbf{b})} \exp\left(\mathbf{v}^{\top} \mathbf{W} \mathbf{h} + \mathbf{a}^{\top} \mathbf{v} + \mathbf{b}^{\top} \mathbf{h}\right)$$

All variables are binary taking value 0 or 1. Here **W** is an  $V \times H$  matrix of weight  $W_{ji}$ .

1) Show that the distribution of hidden units conditional on the visible unit is factorized as

$$p(\mathbf{h}|\mathbf{v}) = \prod_{i} p(h_i|\mathbf{v}), \quad \text{with } p(h_i = 1|\mathbf{v}) = \sigma(b_i + \sum_{j} W_{ji}v_j)$$

where  $\sigma(x) = e^x/(1+e^x)$ .

- 2) By symmetry arguments, write down the form of the conditional  $p(\mathbf{v}|\mathbf{h})$ .
- 3) Is  $p(\mathbf{h}) = \prod_i p(h_i)$ ?
- 4) Can the partition function  $Z(\mathbf{W}, \mathbf{a}, \mathbf{b})$  be computed efficiently for the RBM?

# Problem 6 (Barber, p.77, Exercise 4.14)

Consider a pairwise binary Markov network defined on variables  $x_i \in \{0, 1\}, i = 1, ..., N$ , with  $p(\mathbf{x}) = \frac{1}{Z} \prod_{ij \in \mathcal{E}} \phi_{ij}(x_i, x_j)$  where  $\mathcal{E}$  is a given edge set and the factors  $\phi_{ij}$  are arbitrary (here edges are non necessarily maximal cliques). Explain how to translate such a Markov network into a Boltzmann machine.

## Problem 7

Let G = (V, E) an undirected graph whose vertices  $V = \{1, ..., n\}$  are associated to random variables, and edges are given by the set of pairs E. For simplicity the random variables are assumed to be discrete. Denote C the set of maximal cliques of G and consider a probability distribution  $p(\mathbf{x})$  which factorizes as

$$p(\mathbf{x}) = \frac{1}{Z} \prod_{C \in \mathcal{C}} \psi_C(\mathbf{x}_C),$$

where  $Z = \sum_x \prod_{C \in \mathcal{C}} \psi_C(\mathbf{x}_C)$  and  $\forall C \in \mathcal{C}, \forall \mathbf{x}_C : \psi_C(\mathbf{x}_C) > 0$ . Remember that – for a Markov Random Field – the Markov blanket  $\partial S$  of a subset  $S \subseteq V$  is the set of all vertices that are directly connected to a vertex in S and are not in S. Show that the following conditional independence properties is satisfied:

$$\forall S \subseteq V : p(\mathbf{x}_S | \mathbf{x}_{V \setminus S}) = p(\mathbf{x}_S | \mathbf{x}_{\partial S}).$$

# Problem 8 (Barber, p.99, Exercise 5.4)

Consider the hidden Markov model (HMM)

$$p(\mathbf{v}, \mathbf{h}) = p(h_1)p(v_1|h_1) \prod_{t=2}^{T} p(v_t|h_t)p(h_t|h_{t-1})$$

in which  $dom(h_t) = \{1, \dots, H\}$  and  $dom(h_t) = \{1, \dots, V\}$  for all  $t = 1, \dots, T$ .

- 1) Draw a belief network representation of the above distribution.
- 2) Show that the belief network for  $p(h_1, \ldots, h_T)$  is a simple linear chain. Draw the belief network corresponding to  $p(v_1, \ldots, v_T)$  (this is called a fully connected cascade belief network).
- 3) Draw a factor graph representation of the above distribution.
- 4) Use the factor graph to derive a Sum-Product algorithm to compute marginals  $p(h_t|v_1, \ldots, v_T)$ . Explain the sequence order of messages passed on your factor graph.
- 5) Explain how to compute  $p(h_t, h_{t+1}|v_1, \dots, v_T)$ .

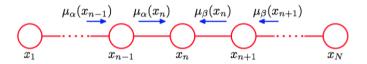
## Problem 9 (Barber, p.98, Exercise 5.1)

Given a pairwise tree Markov network of the form

$$p(x) = \frac{1}{Z} \prod_{i \sim j} \phi(x_i, x_j),$$

explain how to efficiently compute the normalization factor (also called the partition function) Z as a function of the potentials  $\phi$ .

## Problem 10 (Bishop, p.397 & 421, Exercise 8.16 & 8.17)



The joint distribution for the above graph takes the form

$$p(\mathbf{x}) = \frac{1}{Z}\phi_{1,2}(x_1, x_2)\phi_{2,3}(x_2, x_3)\cdots\phi_{N-1,N}(x_{N-1}, x_N).$$

The marginal probability  $p(x_n) = \sum_{i \in \{1,\dots,N\} \setminus n} p(\mathbf{x})$  can be written as

$$p(x_n) = \frac{1}{Z_n} \mu_{\alpha}(x_n) \mu_{\beta}(x_n)$$
 with  $Z_n = \sum_{x_n} \mu_{\alpha}(x_n) \mu_{\beta}(x_n)$ 

where  $\mu_{\alpha}(x_n)$  is the message passing forward from node n-1 to node n, and  $\mu_{\beta}(x_n)$  is the message passing backward from node n+1 to node n. The computation of  $\mu_{\alpha}(x_n)$  and  $\mu_{\beta}(x_n)$  can be done recursively by the following message passing equations:

$$\mu_{\alpha}(x_2) = \sum_{x_1} \phi_{1,2}(x_1, x_2)$$

$$\mu_{\beta}(x_{N-1}) = \sum_{x_N} \phi_{N-1,N}(x_{N-1}, x_N)$$

$$\mu_{\alpha}(x_n) = \sum_{x_{n-1}} \phi_{n-1,n}(x_{n-1}, x_n) \mu_{\alpha}(x_{n-1})$$

$$\mu_{\beta}(x_n) = \sum_{x_{n+1}} \phi_{n,n+1}(x_n, x_{n+1}) \mu_{\beta}(x_{n+1})$$

- 1) Discuss how to modify the above message passing algorithm in order to compute  $p(x_n|x_N)$  efficiently.
- 2) Suppose N = 5, and nodes  $x_3, x_5$  are observed. Show that if the message passing algorithm is applied to the evaluation of  $p(x_2|x_3, x_5)$ , the result will be independent of the value of  $x_5$ .