## Week 7 Spatiotemporal models

- Monitoring network such as LTERs
- General modeling

$$Y(s,t) = \mu(s,t) + \epsilon(s,t)$$
 
$$\mu(s,t) = x(s,t)\beta(s,t)$$
 
$$\epsilon = w(s,t) + e(s,t)$$
 Spatiotemporal process White noise 
$$Y|\mu w \sim Normal(\mu+w,e)$$

model 1:

Additive 
$$e(s,t) = \alpha(t) + w(s) + \epsilon(s,t)$$

model 2:

Temporal evolution at s 
$$e(s,t) = \alpha_s(t) + \epsilon(s,t)$$

model 3:

structure at t

Spatial 
$$e(s,t) = w_t(s) + \epsilon(s,t)$$

## To illustrate a specific problem...

Environ Ecol Stat (2008) 15:59–70 DOI 10.1007/s10651-007-0040-1

## A hierarchical Bayesian non-linear spatio-temporal model for the spread of invasive species with application to the Eurasian Collared-Dove

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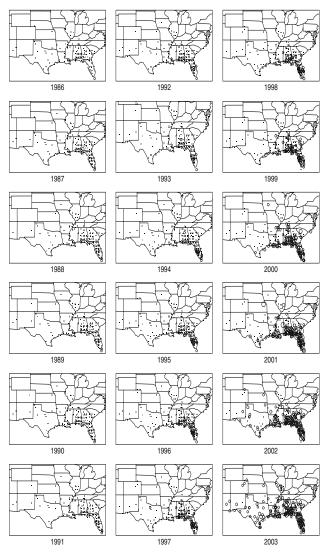


Fig. 1 Spread of ECD throughout the United States from 1986 through 2003 (points represent zero counts at sampled location, while circle size corresponds to non-zero count magnitude)

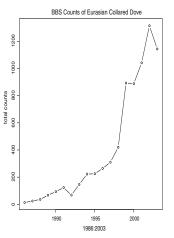


Fig. 2 Population growth of ECD in the United States from 1986 through 2003 (total counts over time)

Data model  $n_{i,t}|\lambda_{i,t} \sim Pois(\lambda_{i,t}), \quad i = 1, ..., m \quad t = 1, ..., T.$ 

Model

Process Model  $\log(\lambda_t) = \mathbf{K}_t \mathbf{u}_t + \boldsymbol{\varepsilon}_t, \quad \boldsymbol{\varepsilon}_t \sim N(\mathbf{0}, \sigma_{\varepsilon}^2 \mathbf{I}), \quad t = 1, \dots, T.$ 

reaction-diffusion equation 
$$\frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left( \delta(x, y) \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left( \delta(x, y) \frac{\partial u}{\partial y} \right) + \gamma_0 u \left( 1 - \frac{u}{\gamma_1} \right),$$

Parameter model  $\delta = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\xi}, \quad \boldsymbol{\xi} \sim N(\mathbf{0}, \sigma_{\delta}^2 \mathbf{R}(\theta)). \quad R(\theta, d) = exp(-\theta||d||).$ 

## Results

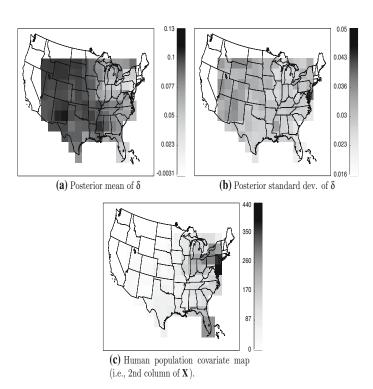


Fig. 4 Posterior summary of  $\delta$  and covariate. (a) Posterior mean of  $\delta$ . (b) Posterior standard dev. of  $\delta$ . (c) Human population covariate map (i.e., 2nd column of X)

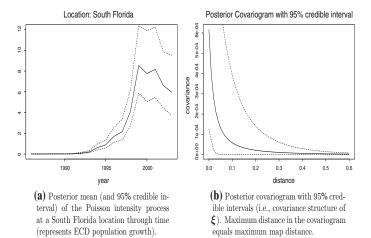
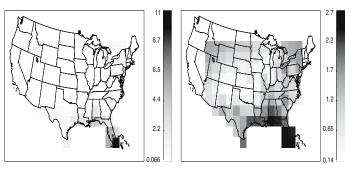


Fig. 5 Posterior summary of  $\lambda$  and  $\xi$ . (a) Posterior mean (and 95% credible interval) of the Poisson intensity process at a South Florida location through time (represents ECD population growth). (b) Posterior covariogram with 95% credible intervals (i.e., covariance structure of  $\xi$ ). Maximum distance in the covariogram equals maximum map distance



(a) Posterior mean for Poisson intensity prediction.

**(b)** Posterior standard deviation for Poisson intensity prediction.

Fig. 7 Posterior prediction of  $\lambda$  for 2004. (a) Posterior mean for Poisson intensity prediction. (b) Posterior standard deviation for Poisson intensity prediction