

# Lecture 7: Spatio-temporal models

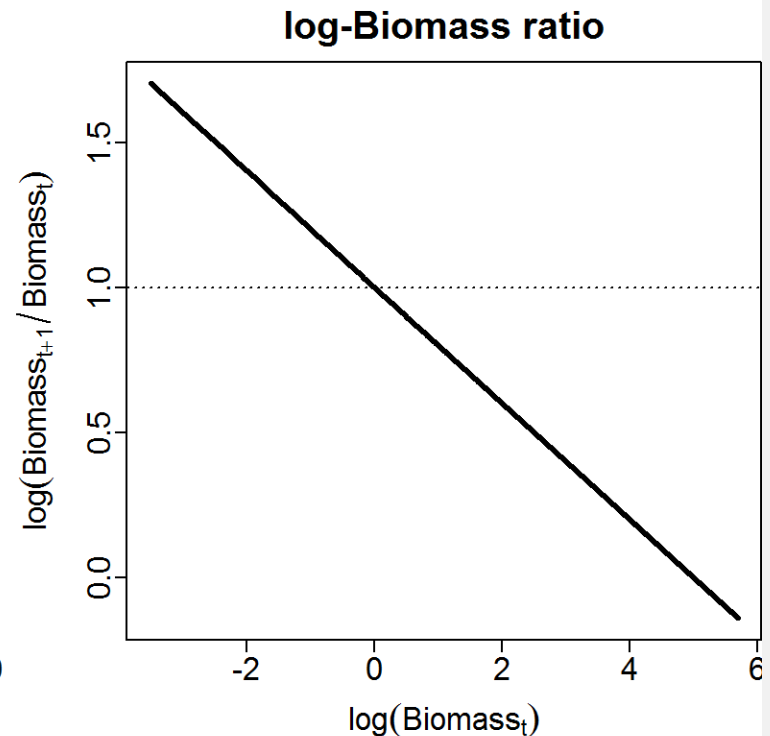
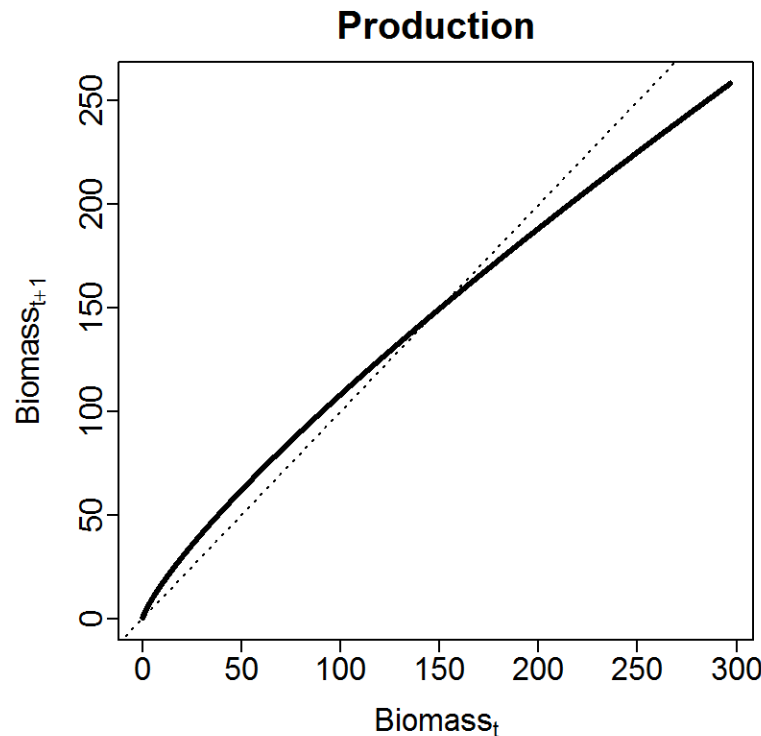
May 12, 2016

# Gompertz model

$$d_{t+1} = d_t \times \exp(\alpha) \times \exp(-\beta \log(d_t)) \times \exp(\varepsilon_t)$$

$$\varepsilon_t \sim \text{Normal}(0, \sigma_\varepsilon^2)$$

$$\log(b_t) \sim \text{Normal}(\log(d_t), \sigma_b^2)$$



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$$\log(b_t) \sim \text{Normal}(\log(d_t), \sigma_b^2)$$

- Fits to an index of abundance, **b**
- $\beta$  is the strength of density dependence
  - Linear impact of  $\log(d_t)$  on per-capita productivity
- $\varepsilon_t$  is a lognormally distributed process error
- $\sigma_\varepsilon^2$  is the variance of log-process errors
- $\sigma_b^2$  is the variance of log-observation errors

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## Gompertz model (Version #2)

$$\log(d_{t+1}) = \alpha + \rho \log(d_t) + \varepsilon_t$$

$$\varepsilon_t \sim \text{Normal}(0, \sigma_\varepsilon^2)$$

$$\log(b_t) \sim \text{Normal}(d_t, \sigma_b^2)$$

- Log-density follows an autoregressive process over time
- $\rho = 1 - \beta$  is “density dependence”
  - $\rho = 0$  means each year fluctuates independently
  - $\rho = 1$  means the population follows a random-walk with no equilibrium

## Gompertz model (version #3)

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$$\mathbf{d} = \alpha + \boldsymbol{\varepsilon}$$

$$\boldsymbol{\varepsilon} \sim \text{MVN}(\mathbf{0}, \sigma_{\varepsilon}^2 \mathbf{R})$$

$$\log(\mathbf{b}) \sim \text{MVN}(\mathbf{d}, \sigma_b^2 \mathbf{I})$$

- Where  $\mathbf{R}$  is the correlation matrix for an AR1 process

$$\mathbf{R} = \frac{1}{1-\rho^2} \begin{bmatrix} 1 & \rho & \rho^2 & \dots & \rho^{T-1} \\ \rho & 1 & \rho & \dots & \rho^{T-2} \\ \rho^2 & \rho & 1 & \dots & \rho^{T-3} \\ \dots & \dots & \dots & \dots & \dots \\ \rho^{T-1} & \rho^{T-2} & \rho^{T-3} & \dots & 1 \end{bmatrix}$$

## REVIEW: Four ways to code

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1. Stochastic process

$$\varepsilon_{s+1} \sim \text{Normal}(\rho\varepsilon_s, \sigma_\varepsilon^2)$$

2. Via precision matrix  $\mathbf{Q}$

$$\Pr(\boldsymbol{\varepsilon}|\boldsymbol{\Sigma}) \propto \sqrt{\det(\mathbf{Q})} \exp(-0.5\boldsymbol{\varepsilon}^T \mathbf{Q} \boldsymbol{\varepsilon})$$

3. Via multivariate normal density function in TMB

$$\boldsymbol{\varepsilon} \sim \text{MVN}(0, \boldsymbol{\Sigma})$$

4. Via autoregressive function in TMB

$$\boldsymbol{\varepsilon} \sim f(\rho, \sigma_\varepsilon^2)$$

## Spatial Gompertz model

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$$\log(d_{t+1}(s)) = \alpha + \omega(s) + \rho \log(d_t(s)) + \varepsilon_t(s)$$

$$\boldsymbol{\omega} \sim \text{MVN}(0, \sigma_{\omega}^2 \mathbf{C}_{\omega})$$

$$\boldsymbol{\varepsilon}_{t+1} \sim \text{MVN}(\rho \boldsymbol{\varepsilon}_t, \sigma_{\varepsilon}^2 \mathbf{C}_{\varepsilon})$$

$$c_i \sim \text{Poisson}(d_{t_i}(s_i))$$

- Very similar to standard Gompertz model
- Fits to spatially referenced count data

## Implications

- Expectation:

$$\mathbb{E}(\log(\mathbf{d})) = \frac{\alpha}{1 - \rho}$$

$$\mathbb{E}(\log(d(s))) = \frac{\alpha + \omega(s)}{1 - \rho}$$

## Variance

$$\mathbb{V}(\log(d(s))) = \sigma_{\omega}^2 + \frac{\sigma_{\varepsilon}^2}{1 - \rho^2}$$

## Spatial Gompertz model:

- Can use same trick as “Gompertz model version #3”

$$c_i \sim \text{Poisson}(\exp(d_{t_i}(s_i)))$$

$$\mathbf{d} = \alpha + \boldsymbol{\omega} + \boldsymbol{\varepsilon}_t$$

$$\boldsymbol{\omega} \sim \text{MVN}(\mathbf{0}, \frac{\sigma_{\omega}^2}{1 - \rho} \mathbf{C}_{\omega})$$

$$\text{vec}(\mathbf{E}) \sim \text{MVN}(\mathbf{0}, \sigma_{\varepsilon}^2 \mathbf{C}_{\varepsilon} \otimes \mathbf{R})$$

Where  $\mathbf{R}$  is the correlation matrix for 1<sup>st</sup> order autocorrelation

$$\mathbf{R} = \begin{bmatrix} 1 & \rho & \rho^2 & \dots & \rho^{T-1} \\ \rho & 1 & \rho & \dots & \rho^{T-2} \\ \rho^2 & \rho & 1 & \dots & \rho^{T-3} \\ \dots & \dots & \dots & \dots & \dots \\ \rho^{T-1} & \rho^{T-2} & \rho^{T-3} & \dots & 1 \end{bmatrix}$$



## Spatial Gompertz model:

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Innovations parameterization

$$\log(d_{t+1}(s)) = \alpha + \omega(s) + \rho \log(d_t(s)) + \varepsilon_t(s)$$

$$\boldsymbol{\omega} \sim \text{MVN}(\mathbf{0}, \sigma_{\omega}^2 \mathbf{C}_{\omega})$$

$$\boldsymbol{\varepsilon}_t \sim \text{MVN}(\mathbf{0}, \sigma_{\varepsilon}^2 \mathbf{C}_{\varepsilon})$$

State-space parameterization

$$\log(d_{t+1}^*(s)) = \alpha + \omega(s) + \rho \log(d_t(s))$$

$$\log(\mathbf{d}_t) \sim \begin{cases} \text{MVN}\left(\frac{\alpha + \boldsymbol{\omega}}{1 - \rho}, \sigma_{\varepsilon}^2 \mathbf{C}_{\varepsilon}\right) & \text{if } t = 1 \\ \text{MVN}(\log(\mathbf{d}_{t-1}^*), \sigma_{\varepsilon}^2 \mathbf{C}_{\varepsilon}) & \text{if } t > 1 \end{cases}$$

$$\boldsymbol{\omega} \sim \text{MVN}(\alpha \mathbf{1}, \sigma_{\omega}^2 \mathbf{C}_{\omega})$$

... where both use the same measurement model

$$c_i \sim \text{Poisson}(d_{t_i}(s_i))$$

## REVIEW: Four ways to code

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### 1. **Stochastic process**

$$\boldsymbol{\varepsilon}_{s+1} \sim \text{Normal}(\boldsymbol{\rho}\boldsymbol{\varepsilon}_s, \boldsymbol{\sigma}_{\boldsymbol{\varepsilon}}^2)$$

### 2. Via precision matrix $\mathbf{Q}$

$$\Pr(\boldsymbol{\varepsilon}|\boldsymbol{\Sigma}) \propto \sqrt{\det(\mathbf{Q})} \exp(-0.5\boldsymbol{\varepsilon}^T \mathbf{Q} \boldsymbol{\varepsilon})$$

### 3. Via multivariate normal density function in TMB

$$\boldsymbol{\varepsilon} \sim \text{MVN}(\mathbf{0}, \boldsymbol{\Sigma})$$

### 4. **Via autoregressive function in TMB**

$$\boldsymbol{\varepsilon} \sim \boldsymbol{f}(\boldsymbol{\rho}, \boldsymbol{\sigma}_{\boldsymbol{\varepsilon}}^2)$$

# Without spatial

		Temporal effect		
Spatio-temporal effect		None	Independent	Smoothed
	None	$\text{gam}(c \sim 1)$	$\text{gam}(c \sim 1 + \text{factor}(t))$	$\text{gam}(c \sim 1 + s(t))$
	Independent	$\text{gam}(c \sim 1)$	$\text{gam}(c \sim 1 + \text{factor}(t))$	$\text{gam}(c \sim 1 + s(t))$
	Smoothed	$\text{gam}(c \sim 1 + s(x, y, t))$	$\text{gam}(c \sim 1 + \text{factor}(t))$	$\text{gam}(c \sim 1 + s(t) + s(x, y, t))$

# With spatial

		Temporal effect		
Spatio-temporal effect		None	Independent	Smoothed
	None	$\text{gam}(c \sim 1 + s(x, y))$	$\text{gam}(c \sim 1 + s(x, y))$	$\text{gam}(c \sim 1 + s(x, y) + s(t))$
	Independent	$\text{gam}(c \sim 1 + s(x, y))$	$\text{gam}(c \sim 1 + \text{factor}(t))$	$\text{gam}(c \sim 1 + s(x, y) + s(t))$
	Smoothed	$\text{gam}(c \sim 1 + s(x, y))$	$\text{gam}(c \sim 1 + s(x, y))$	$\text{gam}(c \sim 1 + s(x, y) + s(t))$

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## What to do if you have 1000s of unique locations?

### 1. Get a bigger computer

- TMB allows parallelization

### 2. Decrease spatial resolution

- Define number of “knots”
- Run k-means algorithm to identify placement of knots
  - Minimize distance between locations and nearest knot
- Associate each sample with the nearest knot
- Assumes that density is constant at finer scales than the distance between knots

### 3. Run in batches

- Run model on smaller scales
- Run “meta-analysis” model on results from each small-scale model

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## In-class exercise:

Convert to using a different production function

Hint:

- Gompertz production function

$$\log(d_{t+1}) = \alpha + (1 - \beta)\log(d_t)$$

In other words...

$$d_{t+1} = d_t \times \exp(\alpha - \beta \log(d_t))$$

- Moran-Ricker production function

$$d_{t+1} = d_t \times \exp(\alpha - \beta d_t)$$