



# CS 3200 Introduction to Scientific Computing

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**Topic: Solving Nonlinear Equations** 

#### Nonlinear Equations f(x) = 0

- Find a root **x** of **f** where both **x** and **f(x)** are n-vectors
- There may be one, none or multiple solutions (roots)!
- The notation f(x) is short-hand for the vector function

$$\begin{bmatrix} f_1(x_1, x_2, \dots, x_n) \\ f_2(x_1, x_2, \dots, x_n) \\ \vdots \\ f_n(x_1, x_2, \dots, x_n) \end{bmatrix} = 0$$
 We consider only a scalar case  $f(x) = 0$ 

#### **Bisection Method**

- The **Bisection method** is one of the simplest methods to find a zero of a nonlinear function f(x) = 0.
- Start with an initial interval that is known to contain a zero of the function.
- Reduce the interval by dividing it into two equal parts, perform a simple test and based on the result of the test, half of the interval is thrown away.
- The procedure is repeated until the interval size is small enough for accuracy purposes.

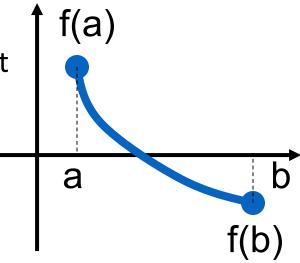
## Intermediate Value Theorem

• Let f(x) be defined on the interval [a,b].

#### • Intermediate value theorem:

if a function is <u>continuous</u> and f(a) and f(b) have <u>different signs</u> then the function has at least one zero in the interval [a,b].

Hence we can sub-divide the interval and apply the process recursively.



Note each iteration narrows down the interval containing the root by a factor of 2

After n iterations the interval is

$$\frac{(b-a)}{2^n}$$

# **Bisection Algorithm**

#### Loop

- 1. Compute the mid point c=(a+b)/2
- 2. Evaluate f(c)
- 3. If f(a) f(c) < 0 then new interval [a, c] If f(a) f(c) > 0 then new interval [c, b]

#### **End loop**

$$if \frac{(b-a)}{2^n} < tol$$

then

$$n > \log_2(\frac{(b-a)}{tol}),$$

$$e.g.\log_2(10^9) \approx 30$$

After n steps subdivide Interval by 2<sup>n</sup> How big does n have to be?

# Bisection Summary

- Bisection is foolproof
- Bisection is slow

# Newton (1671) -Raphson (1690) Method for a Single Equation

Raphson's method is closer to the one we use today.

Suppose we are at the m th iteration of solving f(x)=0

- 1. For each guess of x,  $x^{(m)}$ , define  $\Delta x^{(m)} = x x^{(m)}$
- 2. Represent f(x) by a Taylor series about  $f(x^{(m)})$

$$f(x) = f(x^{(m)}) + \frac{df(x^{(m)})}{dx} \Delta x^{(m)} + \frac{1}{2} \frac{d^2 f(x^{(m)})}{dx^2} \left(\Delta x^{(m)}\right)^2 + h.o.t.$$

# Newton-Raphson Method,

3. Approximate f(x) by neglecting higher order terms (h.o.t.)

$$f(x) = 0 \approx f(x^{(m)}) + \frac{df(x^{(m)})}{dx} \Delta x^{(m)}$$

4. Use this approximation to solve for  $\Delta x^{(m)}$ 

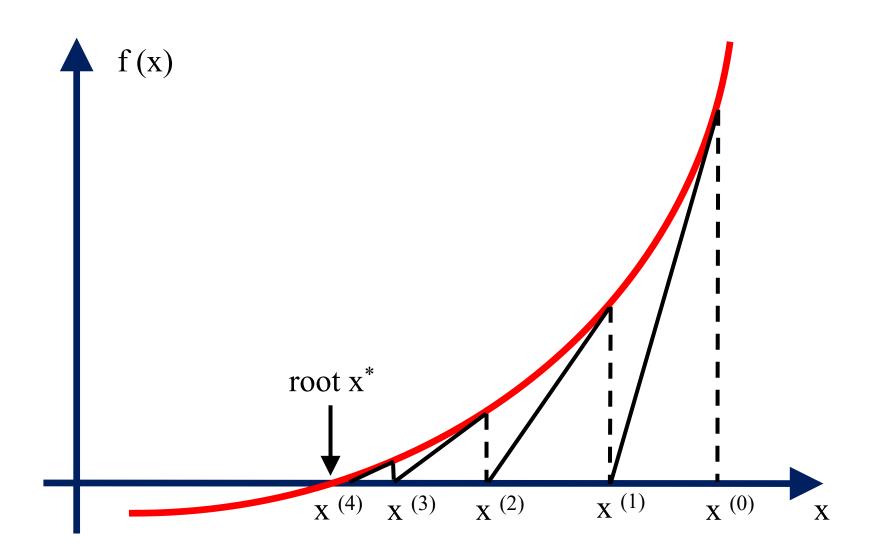
$$\Delta x^{(m)} = -\left[\frac{df(x^{(m)})}{dx}\right]^{-1} f(x^{(m)})$$

5. Solve for a new estimate of x

$$x^{(m+1)} = x^{(m)} + \Delta x^{(m)}$$

6. Continue until convergence

# Newton's Method for a Single Equation



## Newton-Raphson Example

Solve 
$$f(x) = x^2 - 2 = 0$$

The equation we use to update our estimate is

$$\Delta x^{(m)} = -\left[\frac{df(x^{(m)})}{dx}\right]^{-1} f(x^{(m)})$$

$$\Delta x^{(m)} = -\left[\frac{1}{2x^{(m)}}\right] ((x^{(m)})^2 - 2)$$

$$x^{(m+1)} = x^{(m)} + \Delta x^{(m)}$$

$$x^{(m+1)} = x^{(m)} - \left[\frac{1}{2x^{(m)}}\right] ((x^{(m)})^2 - 2)$$

# Newton-Raphson Example

$$x^{(m+1)} = x^{(m)} - \left[\frac{1}{2x^{(m)}}\right]((x^{(m)})^2 - 2)$$

Guess  $x^{(0)} = 1$ . The iteration gives

m 
$$x^{(m)}$$
  $f(x^{(m)})$   $\Delta x^{(m)}$   
0 1 -1 0.5  
1 1.5 0.25 -0.08333  
2 1.41667 6.953×10<sup>-3</sup> -2.454×10<sup>-3</sup>  
3 1.41422 6.024×10<sup>-6</sup>

# Example 2

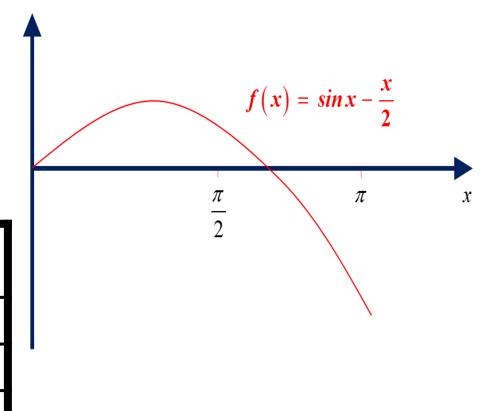
• Find the positive root of  $\sin x - 0.5x = 0$  using Newton's method starting  $x^{(0)} = \pi/2$ 

$$x^{(1)} = x^{(0)} - \frac{f(x^{(0)})}{f'(x^{(0)})}$$

$$= 1.57079 - \frac{1.0 - 0.78539}{0 - 0.5}$$

= 2.00001

iteration number m	
2	1.90100
3	1.89551
4	1.89549



# Newton's Method may

Converge

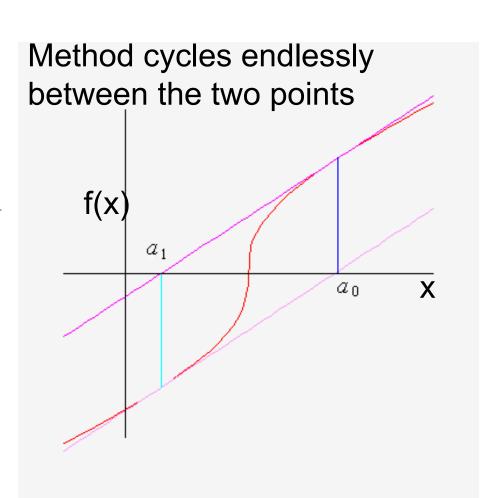
Or converge to the wrong root

Diverge

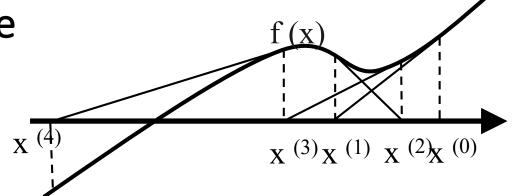
Or get stuck

Convergence only if we start "close enough"

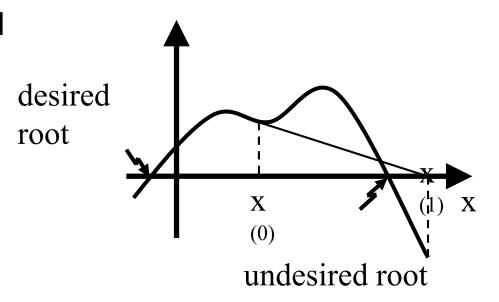
There are globally convergent extensions



# **Oscillatory Convergence**



Convergence to an Unwanted Root



# **Newton Raphson Secant Method**

This is really just using a finite difference approximation to the derivative

$$\frac{df}{dx}(x^{(m)}) \approx \frac{f(x^{(m)}) - f(x^{(m-1)})}{(x^{(m)} - x^{(m-1)})}$$

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As

$$f(x^{(m-1)}) = f(x^{(m)}) - (x^{(m)} - x^{(m-1)}) \frac{df}{dx} \bigg|_{x^{(m)}} + \frac{(x^{(m)} - x^{(m-1)})^2}{2} \frac{d^2 f}{dx^2} \bigg|_{x^{(m)}} + \dots$$

$$f(x^{(m)}) - f(x^{(m-1)}) = (x^{(m)} - x^{(m-1)}) \frac{df}{dx} \bigg|_{x^{(m)}} - \frac{(x^{(m)} - x^{(m-1)})^2}{2} \frac{d^2 f}{dx^2} \bigg|_{x^{(m)}} + \dots$$

then

$$\frac{df}{dx}(x^{(m)}) = \frac{f(x^{(m)}) - f(x^{(m-1)})}{(x^{(m)} - x^{(m-1)})} + \frac{(x^{(m)} - x^{(m-1)})}{2} \frac{d^2f}{dx^2}\Big|_{x^{(m)}} + \dots$$

**Error** 

# **Newton Raphson Secant Method**

$$x^{(m+1)} = x^{(m)} - f(x^{(m)}) \frac{(x^{(m)} - x^{(m-1)})}{(f(x^{(m)}) - f(x^{(m-1)}))}$$

 $X_{-3}$ 

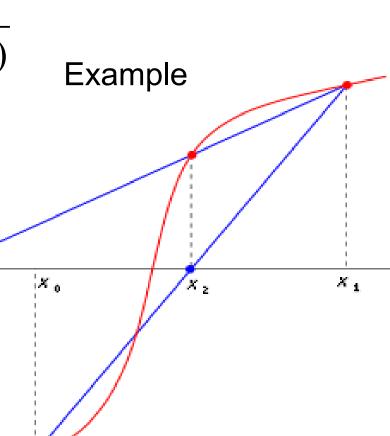
f(x)

$$x^{(2)} = x^{(1)} - f(x^{(1)}) \frac{(x^{(1)} - x^{(0)})}{(f(x^{(1)}) - f(x^{(0)}))}$$

Need to pick two starting values

This is useful when the derivative Is not available?

E.G. f(x) defined by complex code



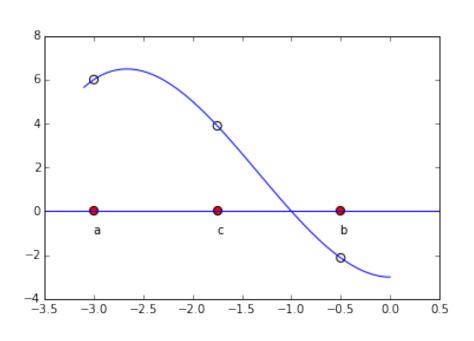
# Fzero – A globally convergent polyalgorithm

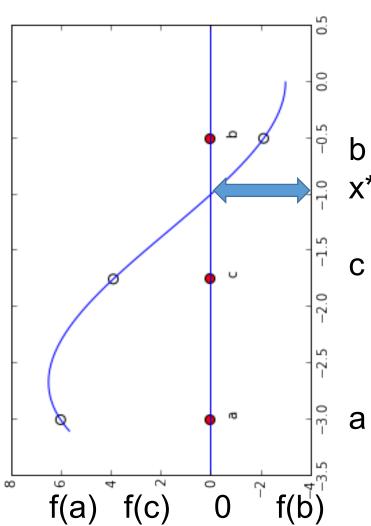
- Fzero uses a combination of three algorithms to get a foolproof method that always finds a root
  - Bisection
  - Newton Secant
  - Inverse Quadratic Interpolation

# Inverse Quadratic Interpolation (IQI)

Use the data points (f(x),x) (f(a),a) (f(b),b) and (f(c),c) To define a quadratic polynomial

Evaluate at f(x)=0 to get where The root x\* is





# Inverse Quadratic Interpolation (IQI) Code

```
k = 0; while abs(c-b) > eps*abs(c)
x = polyinterp([f(a),f(b),f(c)],[a,b,c],0)
a = b;
b = c;
c = x;
k = k + 1;
end
```

Problem - needs f(a) f(b) and f(c) to be distinct So cannot always be used In other words

$$x = a \frac{(x - f(b))(x - f(c))}{(f(a) - f(b))(f(a) - f(c))}$$

$$+ b \frac{(x - f(a))(x - f(c))}{(f(b) - f(a))(f(b) - f(c))}$$

$$+ c \frac{(x - f(a))(x - f(b))}{(f(c) - f(a))(f(c) - f(b))}$$

Method breaks down if any two of f(a), f(b) and f(c) are identical

Start with a and b so that f(a) and f(b) have opposite signs, perhaps using bisection.

- Use a secant step to give c between a and b.
- Repeat the following steps until  $|b a| < \varepsilon |b|$  or f(b) = 0.
- Arrange a, b, and c so that
  - f(a) and f(b) have opposite signs,
    - $-|f(b)| \le |f(a)|,$
    - c is the previous value of b.
- If c ≠ a, consider an IQI step.
- If c = a, consider a secant step.
- If the IQI or secant step is in the interval [a, b], take it.
- If the step is not in the interval, use bisection.

Fzero Algorithm

## Matlab fzero function

You can use the fzero function to find the zero of a function of a single variable, which is denoted by x. One form of its syntax is

```
fzero('function', x0)
```

where function is a string containing the name of the function, and x0 is a user-supplied guess for the zero.

The fzero function returns a value of x that is near x0. It identifies only points where the function crosses the x-axis, not points where the function just touches the axis.

For example, fzero ('cos', 2) returns the value 1.5708.

#### Using fzero with User-Defined Functions

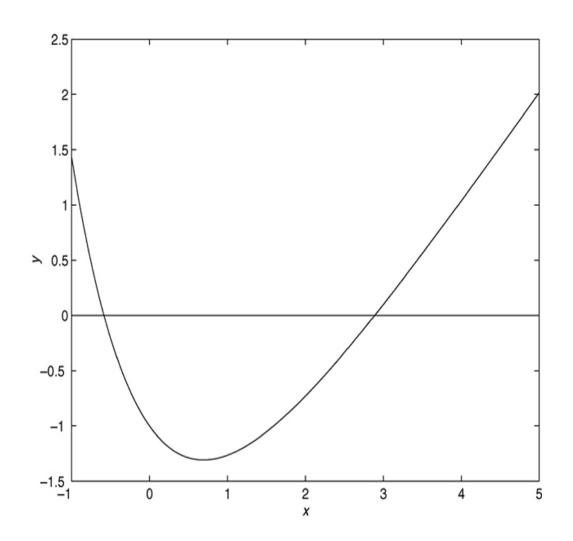
To use the fzero function to find the zeros of more complicated functions, it is more convenient to define the function in a function file.

For example, if  $y = x + 2e^{-x} - 3$ , define the following function file:

function 
$$y = f1(x)$$
  
 $y = x + 2*exp(-x) - 3;$ 

# Plot of the function $y = x + 2e^{-x} - 3$

There is a zero near x = -0.5 and one near x = 3.



#### Multi-Variable Newton-Raphson

Consider the case where  $\mathbf{x}$  is an n-dimension vector, and  $\mathbf{f}(\mathbf{x})$  is an n-dimension function

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \qquad \mathbf{f}(\mathbf{x}) = \begin{bmatrix} f_1(\mathbf{x}) \\ f_2(\mathbf{x}) \\ \vdots \\ f_n(\mathbf{x}) \end{bmatrix}$$

Define the solution  $\hat{\mathbf{x}}$  so  $\mathbf{f}(\hat{\mathbf{x}}) = 0$  and

$$\Delta \mathbf{x} = \hat{\mathbf{x}} - \mathbf{x}$$

Instead of dividing by the derivative we have to solve a system of equations. This will not be covered any further here

#### Matlab Fsolve Routine Later version

- This routine incorporates many features to improve the robustness of Newton's method.
- One of the key ideas is that of a "trust region" in which the next point chosen is only used if the value of the function goes down. This is done by approximating the function f by a simpler function Q(x) which is a quadratic approximation. This provides a different, more robust and more complex search direction than the standard Newton step.
- Alternatives in fsolve are the trust region dogleg and the Levenberg-Marquardt algorithm
- See the fsolve documentation for more details https://www.mathworks.com/help/optim/ug/fsolve.html