

1.1

$$\begin{aligned} P(x, y|z) &= \frac{P(x, y, z)}{P(z)} = \frac{P(x|y, z) P(y, z)}{P(z)} \\ &= \frac{P(x|y, z) P(y|z) \cancel{P(z)}}{\cancel{P(z)}} \\ &= P(x|y, z) P(y|z) \end{aligned}$$

Recall  $P(x, y|z) = P(x|z) P(y|z)$  ①

We get  $P(x|y, z) = P(x|z)$  //

Similarly,

$$\begin{aligned} P(x, y|z) &= \frac{P(x, y, z)}{P(z)} = \frac{P(y|x, z) P(x, z)}{P(z)} \\ &= \frac{P(y|x, z) P(x|z) \cancel{P(z)}}{\cancel{P(z)}} \\ &= P(y|x, z) P(x|z) \end{aligned}$$

From ①, we get  $P(y|z) = P(y|x, z)$  //

1.2

$$\begin{cases} P(z_t = \text{clean} | x_t = \text{dirty}) = 0.2 \\ P(z_t = \text{clean} | x_t = \text{clean}) = 0.6 \end{cases}$$

$$\begin{cases} P(x_{t+1} = \text{clean} | u_{t+1} = \text{act}, x_t = \text{dirty}) = 0.6 \\ P(x_{t+1} = \text{dirty} | u_{t+1} = \text{act}, x_t = \text{dirty}) = 0.4 \\ P(x_{t+1} = \text{clean} | u_{t+1} = \text{act}, x_t = \text{clean}) = 1 \\ P(x_{t+1} = \text{dirty} | u_{t+1} = \text{act}, x_t = \text{clean}) = 0 \end{cases}$$

$$P(x_t = \text{clean}) = c, \quad P(x_t = \text{dirty}) = 1 - c$$

Take action  $u_{t+1} = \text{act}$ .

$$\overline{\text{bel}}(x_{t+1} = \text{clean})$$

$$= P(x_{t+1} = \text{clean} | u_{t+1} = \text{act}, x_t = \text{clean}) \text{bel}(x_t = \text{clean}) \\ + P(x_{t+1} = \text{clean} | u_{t+1} = \text{act}, x_t = \text{dirty}) \text{bel}(x_t = \text{dirty})$$

$$= c + 0.6(1 - c) = 0.4c + 0.6$$

$$\overline{\text{bel}}(x_{t+1} = \text{dirty})$$

$$= P(x_{t+1} = \text{dirty} | u_{t+1} = \text{act}, x_t = \text{clean}) \text{bel}(x_t = \text{clean}) \\ + P(x_{t+1} = \text{dirty} | u_{t+1} = \text{act}, x_t = \text{dirty}) \text{bel}(x_t = \text{dirty})$$

$$= 0 + 0.4(1 - c) = 0.4(1 - c)$$

Incorporating the measurements:

$$\text{bel}(x_{t+1} = \text{clean})$$

$$= \eta P(z_{t+1} = \text{clean} | x_{t+1} = \text{clean}) \overline{\text{bel}}(x_{t+1} = \text{clean})$$

$$= \eta 0.6(0.4c + 0.6) = \eta(0.24c + 0.36)$$

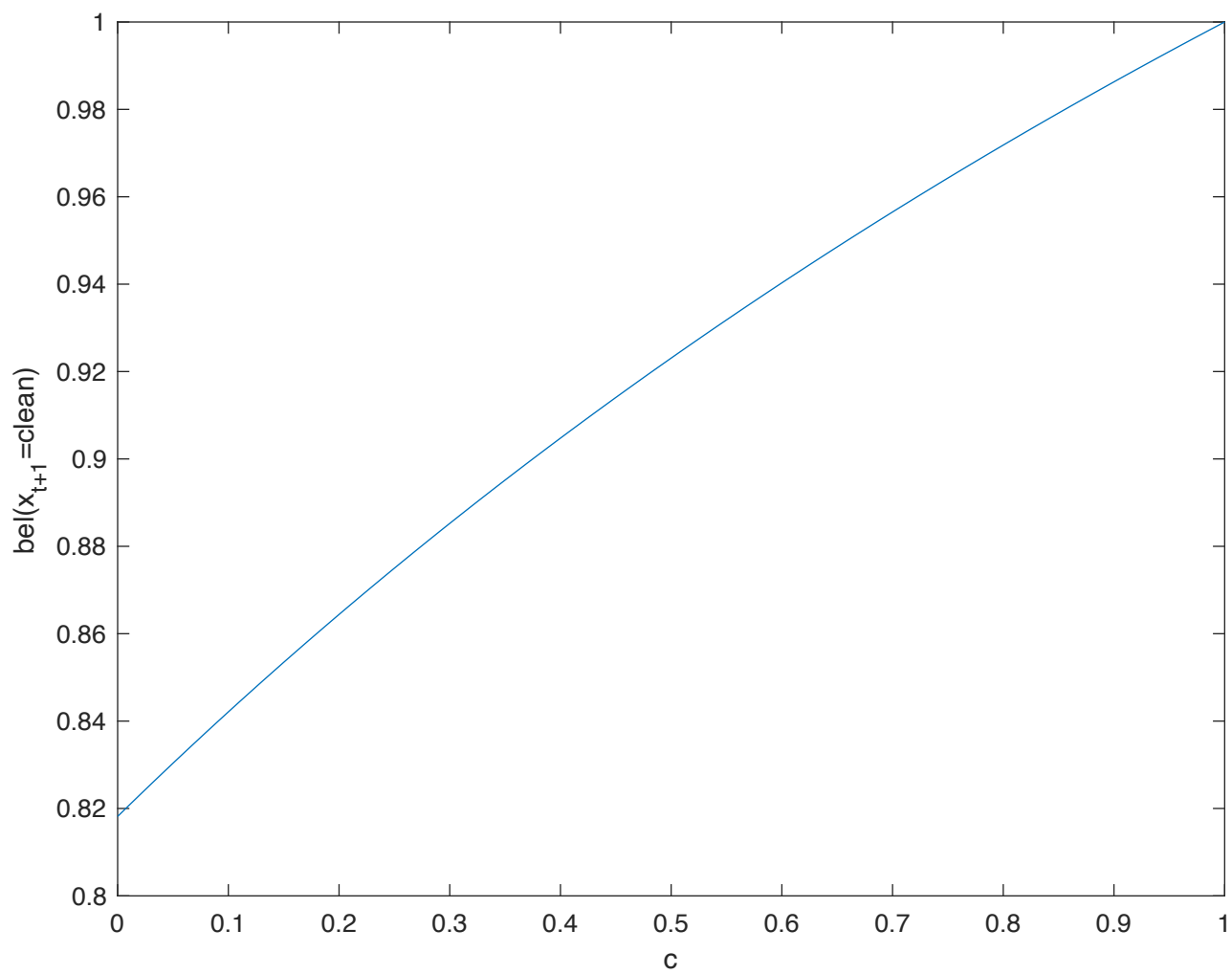
$$\text{bel}(x_{t+1} = \text{dirty})$$

$$= \eta P(z_{t+1} = \text{clean} | x_{t+1} = \text{dirty}) \overline{\text{bel}}(x_{t+1} = \text{dirty})$$

$$= \eta 0.2 \times 0.4(1 - c) = \eta 0.08(1 - c)$$

$$\eta = \frac{1}{0.08(1 - c) + 0.24c + 0.36} = \frac{1}{0.16c + 0.44}$$

$$P(x_{t+1} = \text{clean} | z_{t+1} = \text{clean}) = \frac{0.24c + 0.36}{0.16c + 0.44}$$



1.3.

$$p(x, y) = p(x|y) p(y)$$

$$p(x|y) = \frac{p(x, y)}{p(y)} = \frac{\frac{1}{2\lambda\sqrt{|\Sigma|}} \exp\left\{-\frac{1}{2} \begin{bmatrix} x-\mu_x \\ y-\mu_y \end{bmatrix}^T \Sigma^{-1} \begin{bmatrix} x-\mu_x \\ y-\mu_y \end{bmatrix}\right\}}{\frac{1}{\sqrt{2\pi}} \sigma_y \exp\left(-\frac{(y-\mu_y)^2}{2\sigma_y^2}\right)}$$

$$\text{since } p(y) = \mathcal{N}(\mu_y, \sigma_y^2)$$

Looking at the terms before the exponential functions:

$$\frac{\frac{1}{2\lambda\sqrt{|\Sigma|}}}{\frac{1}{\sqrt{2\pi}} \sigma_y} = \frac{\frac{1}{2\lambda\sqrt{\sigma_x^2 \sigma_y^2 - \sigma_{xy}^4}}}{\frac{1}{\sqrt{2\pi}} \sigma_y} = \frac{1}{\sqrt{2\pi} \sqrt{\sigma_x^2 - \frac{\sigma_{xy}^4}{\sigma_y^2}}} = \frac{1}{\sqrt{2\pi} \sigma_{x|y}}$$

Thus we have:

$$\sigma_{x|y}^2 = \sigma_x^2 - \frac{\sigma_{xy}^4}{\sigma_y^2} //$$

Next looking into the exponential functions.

$$\text{We have } \Sigma^{-1} = \frac{1}{\sigma_x^2 \sigma_y^2 - \sigma_{xy}^4} \begin{bmatrix} \sigma_y^2 & -\sigma_{xy}^2 \\ -\sigma_{xy}^2 & \sigma_x^2 \end{bmatrix}$$

$$\exp\left\{-\frac{1}{2} \cdot \frac{1}{\sigma_x^2 \sigma_y^2 - \sigma_{xy}^4} \begin{bmatrix} x-\mu_x \\ y-\mu_y \end{bmatrix}^T \begin{bmatrix} \sigma_y^2 & -\sigma_{xy}^2 \\ -\sigma_{xy}^2 & \sigma_x^2 \end{bmatrix} \begin{bmatrix} x-\mu_x \\ y-\mu_y \end{bmatrix} + \frac{(y-\mu_y)^2}{2\sigma_y^2}\right\}$$

$$= \exp\left\{-\frac{1}{2(\sigma_x^2 - \frac{\sigma_{xy}^4}{\sigma_y^2})} \cdot A\right\} = \exp\left\{-\frac{A}{2\sigma_{x|y}^2}\right\}$$

We'll next evaluate A.

$$\begin{aligned}
A &= \begin{bmatrix} x - \mu_x \\ y - \mu_y \end{bmatrix}^T \begin{bmatrix} 1 & -\frac{\sigma_{xy}^2}{\sigma_y^2} \\ -\frac{\sigma_{xy}^2}{\sigma_y^2} & \frac{\sigma_x^2}{\sigma_y^2} \end{bmatrix} \begin{bmatrix} x - \mu_x \\ y - \mu_y \end{bmatrix} - \left( \frac{\sigma_x^2}{\sigma_y^2} - \frac{\sigma_{xy}^4}{\sigma_y^4} \right) (y - \mu_y)^2 \\
&= \begin{bmatrix} x - \mu_x \\ y - \mu_y \end{bmatrix}^T \begin{bmatrix} 1 & -\frac{\sigma_{xy}^2}{\sigma_y^2} \\ -\frac{\sigma_{xy}^2}{\sigma_y^2} & \frac{\sigma_x^2}{\sigma_y^2} \end{bmatrix} \begin{bmatrix} x - \mu_x \\ y - \mu_y \end{bmatrix} - \begin{bmatrix} x - \mu_x \\ y - \mu_y \end{bmatrix}^T \begin{bmatrix} 0 & 0 \\ 0 & \frac{\sigma_x^2}{\sigma_y^2} - \frac{\sigma_{xy}^4}{\sigma_y^4} \end{bmatrix} \begin{bmatrix} x - \mu_x \\ y - \mu_y \end{bmatrix} \\
&= \begin{bmatrix} x - \mu_x \\ y - \mu_y \end{bmatrix}^T \begin{bmatrix} 1 & -\frac{\sigma_{xy}^2}{\sigma_y^2} \\ -\frac{\sigma_{xy}^2}{\sigma_y^2} & \frac{\sigma_x^2}{\sigma_y^2} \end{bmatrix} \begin{bmatrix} x - \mu_x \\ y - \mu_y \end{bmatrix} \\
&= (x - \mu_x)^2 - 2 \cdot \frac{\sigma_{xy}^2}{\sigma_y^2} (x - \mu_x)(y - \mu_y) + \frac{\sigma_{xy}^4}{\sigma_y^4} (y - \mu_y)^2 \\
&= \left[ (x - \mu_x) - \frac{\sigma_{xy}^2}{\sigma_y^2} (y - \mu_y) \right]^2 \\
&= \left\{ x - \left[ \mu_x + \frac{\sigma_{xy}^2}{\sigma_y^2} (y - \mu_y) \right] \right\}^2
\end{aligned}$$

Thus,  $\mu_{x|y} = \mu_x + \frac{\sigma_{xy}^2}{\sigma_y^2} (y - \mu_y) //$

$p(x|y) = \mathcal{N}(\mu_{x|y}, \sigma_{x|y}^2)$  and

$\mu_{x|y}$  &  $\sigma_{x|y}^2$  are given above.

## 2.2 Gaussian Process Predictions

Plot using the default parameters.

