

Markov Chain Monte Carlo Diagnostics

Michael Betancourt

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In this short note I will preview the new suite of Markov chain Monte Carlo analysis tools that I will be introducing more formally in upcoming writing. These tools largely focus on

diagnostics but there are also a few that cover Markov chain Monte Carlo estimation assuming a central limit theorem.

We'll start with diagnostics specific to Hamiltonian Monte Carlo then consider more generic diagnostics that consider each expectand of interest one at a time. Finally we'll look at a way to visualize one-dimensional pushforward distributions using Markov chain Monte Carlo to estimate bin probabilities.

Before any of that, however, we need to set up our graphics.

```
par(family="serif", las=1, bty="l", cex.axis=1, cex.lab=1, cex.main=1,
    xaxs="i", yaxs="i", mar = c(5, 5, 3, 5))

c_light <- c("#DCBCBC")
c_light_highlight <- c("#C79999")
c_mid <- c("#B97C7C")
c_mid_highlight <- c("#A25050")
c_dark <- c("#8F2727")
c_dark_highlight <- c("#7C0000")

c_light_teal <- c("#6B8E8E")
c_mid_teal <- c("#487575")
c_dark_teal <- c("#1D4F4F")
```

1 Extraction

The `extract` function in `RStan` parses the Markov chain output within a `StanFit` object into a usable format. Due to some unfortunate choices in early development, however, the function behaves a bit awkwardly.

By default it permutes the Markov chain iterations and then aggregates them together. This permutation strips the iterations of their autocorrelations, making it impossible to recover accurate estimates of the Markov chain Monte Carlo estimator error.

There is an optional argument that deactivates the permutation, but that also completely changes the output format. In particular it strips the expectands of their names, requiring that users access each expectand by the order in which they appear in the original Stan program.

Finally the `extract` function also ignores all of the Hamiltonian Monte Carlo diagnostic information emitted at each transition. Instead the `get_sampler_params` function recovers this information, albeit it yet another output format.

To facilitate the analysis of Stan output I've included my own custom extract functions that format the Markov chain Monte Carlo output into named lists, with one named element for each expectand or Hamiltonian Monte Carlo diagnostic. The elements themselves are two-dimensional arrays with the first index denoting the individual Markov chains and the second index denoting the iterations within an individual Markov chain.

```
# Extract unpermuted expectand values from a StanFit object and format
# them for convenient access. Removes the auxiliary `lp__` variable.
# @param stan_fit A StanFit object
# @return A named list of two-dimensional arrays for each expectand in
#         the StanFit object. The first dimension of each element
#         indexes the Markov chains and the second dimension indexes the
#         sequential states within each Markov chain.
extract_expectands <- function(stan_fit) {
  nom_params <- rstan::extract(fit, permuted=FALSE)
  N <- dim(nom_params)[3] - 1
  params <- lapply(1:N, function(n) t(nom_params[, ,n]))
  names(params) <- names(fit)[1:N]
  (params)

# Extract Hamiltonian Monte Carlo diagnostics values from a StanFit
# object and format them for convenient access.
# @param stan_fit A StanFit object
# @return A named list of two-dimensional arrays for each expectand in
#         the StanFit object. The first dimension of each element
#         indexes the Markov chains and the second dimension indexes the
#         sequential states within each Markov chain.
extract_hmc_diagnostics <- function(stan_fit) {
  diagnostic_names <- c('divergent__', 'treedepth__', 'n_leapfrog__',
                        'stepsize__', 'energy__', 'accept_stat__')

  nom_params <- get_sampler_params(fit, inc_warmup=FALSE)
  C <- length(nom_params)
  params <- lapply(diagnostic_names,
                    function(name) t(sapply(1:C, function(c)
                                             nom_params[c][[1]][,name])))
  names(params) <- diagnostic_names
  (params)
```

If users are able to modify these functions to accept the output from other interfaces to Stan and return the same output format then all of the following functions will be immediately

available. That is all except for the `plot_inv_metric` function which does require a separate RStan-specific function for extracting adaptation information.

2 Hamiltonian Monte Carlo Diagnostics

Hamiltonian Monte Carlo introduces a suite of powerful diagnostics that can identify obstructions to Markov chain Monte Carlo central limit theorems. These diagnostics are not only extremely sensitive but also probe the behavior of the entire Markov chain state instead of the projections of that state through single expectands.

2.1 Check Hamiltonian Monte Carlo Diagnostics

All of our diagnostics are assembled in this single `check_all_hmc_diagnostics` function.

The first diagnostic looks for unstable numerical Hamiltonian trajectories, or divergences. These unstable trajectories are known to obstruct typical central limit theorem conditions. Divergences arise when the target distribution is compressed into a narrow region; this forces the Hamiltonian dynamics to accelerate which makes them more difficult to accurately simulate.

Increasing `adapt_delta` will on average result in a less aggressive step size optimization that in some cases may improve the stability of the numerical integration but at the cost of longer, and hence more expensive, numerical Hamiltonian trajectories. In most cases, however, the only productive way to avoid divergences is to reparameterize the ambient space to decompress these pinches in the target distribution.

Stan's Hamiltonian Monte Carlo sampler expands the length of the numerical Hamiltonian trajectories dynamically to maximize the efficiency of the exploration. That length, however, is capped at $2^{\text{max_treedepth}}$ steps to prevent trajectories from growing without bound.

When numerical Hamiltonian trajectories are long but finite this truncation will limit the computational efficiency. Increasing `max_treedepth` allow the trajectories to expand further. While the resulting trajectories will be more expensive that added cost will be more than made up for by increased computational efficiency.

The energy fraction of missing information, or E-FMI, quantifies how well the Hamiltonian dynamics are able to explore the target distribution. If the E-FMI is too small then even the exact Hamiltonian trajectories will be limited to confined regions of the ambient space and full exploration will be possible only with the momenta resampling between trajectories. In this case the Markov chain exploration devolves into less efficient, diffusive behavior where Markov chain Monte Carlo estimation is fragile at best.

This confinement is caused by certain geometries in the target distribution, most commonly a funnel geometry where some subset of parameters shrink together as another parameter ranges

across its typical values. The only way to avoid these problems is to identify the problematic geometry and then find a reparameterization of the ambient space that transforms the geometry into something more pleasant.

Finally the average proxy accept statistic is a summary for Stan's step size adaptation. During warmup the integrator step size is dynamically tuned until this statistic achieves the target value which defaults to 0.801. Because this adaptation is stochastic the realized average during the main sampling phase can often vary between 0.75 and 0.85.

So long as the target distribution is sufficiently well-behaved then the adaptation should always converge to that target, at least for long enough warmup periods. Small averages indicate some obstruction to the adaptation, for example discontinuities in the target distribution or inaccurate gradient evaluations.

```
# Check all Hamiltonian Monte Carlo Diagnostics
# for an ensemble of Markov chains
# @param diagnostics A named list of two-dimensional arrays for
#                   each expectand. The first dimension of each
#                   element indexes the Markov chains and the
#                   second dimension indexes the sequential
#                   states within each Markov chain.
# @param adapt_target Target acceptance proxy statistic for step size
#                   adaptation.
# @param max_treedepth The maximum numerical trajectory treedepth
# @param max_width Maximum line width for printing
check_all_hmc_diagnostics <- function(diagnostics,
                                     adapt_target=0.801,
                                     max_treedepth=10,
                                     max_width=72) {
  if (!is.vector(diagnostics)) {
    cat('Input variable `diagnostics` is not a named list!')
    return
  }
}
```

2.2 Integrator Inverse Metric Elements

Diagnostic failures indicate the presence of problems but only hint at the nature of those problems. In order to resolve the underlying problems we need to investigate them beyond these hints. Fortunately Hamiltonian Monte Carlo provides a wealth of additional information that can assist.

First we can look at the inverse metric adaptation in each of the Markov chains. Inconsistencies in the adapted inverse metric elements across the Markov chains are due to the individual chains encountering different behaviors during warmup.

```

# Plot outcome of inverse metric adaptation
# @params stan_fit A StanFit object
# @params B The number of bins for the inverse metric element histograms.
plot_inv_metric <- function(stan_fit, B=25) {
  adaptation_info <- rstan::get_adaptation_info(stan_fit)
  C <- length(adaptation_info)

  inv_metric_elems <- list()
  for (c in 1:C) {
    raw_info <- adaptation_info[[c]]
    clean1 <- sub("# Adaptation terminated\n# Step size = [0-9.]*\n#",
      "", raw_info)
    clean2 <- sub(" [a-zA-Z ]*:\n# ", "", clean1)
    clean3 <- sub("\n$", "", clean2)
    inv_metric_elems[[c]] <- as.numeric(strsplit(clean3, ',')[[1]])
  }
}

```

Note that the adaptation information may be accessed differently in other Stan interfaces, in which case this function would have to be modified accordingly.

2.3 Integrator Step Sizes

The other product of Stan's adaptation is the step size of the numerical integrator used to build the numerical Hamiltonian trajectories. As with the inverse metric elements heterogeneity in the adapted values across the Markov chains indicates that the Markov chains encountered substantially different behavior during warmup.

```

# @param diagnostics A named list of two-dimensional arrays for
#                     each expectand. The first dimension of each
#                     element indexes the Markov chains and the
#                     second dimension indexes the sequential
#                     states within each Markov chain.
display_stepsizes <- function(diagnostics) {
  if (!is.vector(diagnostics)) {
    cat('Input variable `diagnostics` is not a named list!')
    return
  }
}

```

2.4 Numerical Trajectory Lengths

We can see the consequence of the adapted step sizes by looking at the numerical trajectories generated for each Hamiltonian Markov transition. The longer these trajectories the more degenerate the target distribution, and the more expensive it is to explore.

```
# @param diagnostics A named list of two-dimensional arrays for
#                     each expectand. The first dimension of each
#                     element indexes the Markov chains and the
#                     second dimension indexes the sequential
#                     states within each Markov chain.
plot_num_leapfrogs <- function(diagnostics) {
  if (!is.vector(diagnostics)) {
    cat('Input variable `diagnostics` is not a named list!')
    return
  }

# @param diagnostics A named list of two-dimensional arrays for
#                     each expectand. The first dimension of each
#                     element indexes the Markov chains and the
#                     second dimension indexes the sequential
#                     states within each Markov chain.
plot_num_leapfrogs_by_chain <- function(diagnostics) {
  if (!is.vector(diagnostics)) {
    cat('Input variable `diagnostics` is not a named list!')
    return
  }
}
```

2.5 Average Proxy Acceptance Statistic

When the different adaptation outcomes are due to problematic behaviors encountered during warmup then the average proxy acceptance statistics should also vary across the Markov chains.

```
# each Markov chain
# @param diagnostics A named list of two-dimensional arrays for
#                     each expectand. The first dimension of each
#                     element indexes the Markov chains and the
#                     second dimension indexes the sequential
#                     states within each Markov chain.
```

```

display_ave_accept_proxy <- function(fit) {
  if (!is.vector(diagnostics)) {
    cat('Input variable `diagnostics` is not a named list!')
    return
  }
}

```

2.6 Divergence-Labeled Pairs Plot

One of the most powerful features of divergent transitions is that they not only indicate problematic geometry but also provide some spatial information on the source of that problematic geometry. In particular the states generated from unstable numerical Hamiltonian trajectories will tend to be closer to the problematic geometry than those from stable trajectories.

Consequently if we plot the states from divergent and non-divergent transitions separately then we should see the divergent states concentrate towards the problematic behavior. The high-dimensional states themselves can be visualized with pairs plots.

```

# named samples and flatten the output. Transformation defaults to
# identity if name is not included in `transforms` dictionary. A
# ValueError is thrown if samples are not properly constrained.
# @param name Expectand name.
# @param samples A named list of two-dimensional arrays for
#               each expectand. The first dimension of each element
#               indexes the Markov chains and the second dimension
#               indexes the sequential states within each Markov chain.
# @param transforms A named list of transformation flags for each
#                  expectand.
# @return The transformed expectand name and a one-dimensional array of
#         flattened transformation outputs.
apply_transform <- function(name, samples, transforms) {
  t <- transforms[[name]]
  if (is.null(t)) t <- 0

  transformed_name <- ""
  transformed_samples <- 0

  if (t == 0) {
    transformed_name <- name
    transformed_samples <- c(t(samples[[name]]), recursive=TRUE)
  } else if (t == 1) {

```



```

# transitions separated by color
# @param x_names A list of expectand names to be plotted on the x axis.
# @param y_names A list of expectand names to be plotted on the y axis.
# @param expectand_samples A named list of two-dimensional arrays for
#                           each expectand. The first dimension of each
#                           element indexes the Markov chains and the
#                           second dimension indexes the sequential
#                           states within each Markov chain.
# @param diagnostics A named list of two-dimensional arrays for
#                     each expectand. The first dimension of each
#                     element indexes the Markov chains and the
#                     second dimension indexes the sequential
#                     states within each Markov chain.
# @params transforms A named list of flags configurating which if any
#                    transformation to apply to each named expectand:
#                    0: identity
#                    1: log
#                    2: logit
# @param xlim        Optional global x-axis bounds for all pair plots.
#                     Defaults to dynamic bounds for each pair plot.
# @param ylim        Optional global y-axis bounds for all pair plots.
#                     Defaults to dynamic bounds for each pair plot.
# @params plot_mode Plotting style configuration:
#                   0: Non-divergent transitions are plotted in
#                       transparent red while divergent transitions are
#                       plotted in transparent green.
#                   1: Non-divergent transitions are plotted in gray
#                       while divergent transitions are plotted in
#                       different shades of teal depending on the
#                       trajectory length. Transitions from shorter
#                       trajectories should cluster somewhat closer to
#                       the neighborhoods with problematic geometries.
# @param max_width Maximum line width for printing
plot_div_pairs <- function(x_names, y_names,
                           expectand_samples, diagnostics,
                           transforms=list(), xlim=NULL, ylim=NULL,
                           plot_mode=0, max_width=72) {
  if (!is.vector(x_names)) {
    cat('Input variable `x_names` is not a list!')
    return
  }
}

```

3 Expectand Diagnostic Functions

The Hamiltonian Monte Carlo diagnostics exploited the particular structure of the Hamiltonian Markov transition. For a general Markov transition we don't have any particular structure to exploit, and hence limited diagnostic options. In this general setting we have to investigate the behavior of not the entire state but instead particular expectands of interest.

3.1 xihat

A Markov chain Monte Carlo central limit theorem cannot exist for the expectand $f : X \rightarrow \mathbb{R}$ unless both $\mathbb{E}_\pi[f]$ and $\mathbb{E}_\pi[f^2]$ are finite, in which case we say that the expectand is sufficiently integrable. Moreover the smaller the following moments the faster the central limit theorem will kick in.

$\hat{\xi}$ uses the tail behavior of a realized Markov chain to estimate the integrability of an expectand. More specifically $\hat{\xi}$ estimates the shape of a general Pareto density function from non-central values of the expectand.

If the tail behavior were exactly general Pareto then the larger the shape parameter ξ the fewer moments of the distribution will be well-defined. Formally the m th-order moment is well-defined only if

$$m < \frac{1}{\xi}.$$

For example with $\xi = 0.9$ the expectation $\mathbb{E}_\pi[f]$ is finite but $\mathbb{E}_\pi[f^2]$ is not. Similarly for $\xi = 0.4$ the expectations $\mathbb{E}_\pi[f]$ and $\mathbb{E}_\pi[f^2]$ are finite but the third-order moment $\mathbb{E}_\pi[f^3]$ is not.

The estimator $\hat{\xi}$ is constructed from the smallest and largest values of an expectand evaluated across a realized Markov chain, where the smallest and largest values are separated from the central values using a heuristic. Because $\hat{\xi}$ only estimates the tail shape I require a conservative threshold of $\hat{\xi} \geq 0.25$ for the diagnostic warning to be triggered.

If the expectand output is bounded then the lower and upper tail might consist of the same value. In this case the $\hat{\xi}$ estimator is poorly-behaved, but the boundedness also guarantees that moments of all orders exist. To make this diagnostic as robust as possible $\hat{\xi}$ will return -2 in these cases to avoid the diagnostic threshold.

```
# distribution from a sample of positive values using the method
# introduced in "A New and Efficient Estimation Method for the
# Generalized Pareto Distribution" by Zhang and Stephens
# https://doi.org/10.1198/tech.2009.08017.
#
# Within the generalized Pareto distribution family all moments up to
# the mth order are finite if and only if
```

```

# xi < 1 / m.
#
# @params fs A one-dimensional array of positive values.
# @return Shape parameter estimate.
compute_xi_hat <- function(fs) {
  N <- length(fs)
  sorted_fs <- sort(fs)

  # Return erroneous result if all input values are the same
  if (sorted_fs[1] == sorted_fs[N]) {
    return (NaN)
  }

# for an arbitrary sample of expectand values, ignoring any
# autocorrelation between the values.
# @param fs A one-dimensional array of expectand values.
# @return Left and right shape estimators.
compute_tail_xi_hats <- function(fs) {
  f_center <- median(fs)

  # Isolate lower and upper tails which can be adequately modeled by a
  # generalized Pareto shape for sufficiently well-behaved distributions
  fs_left <- abs(fs[fs < f_center] - f_center)
  N <- length(fs_left)
  M <- min(0.2 * N, 3 * sqrt(N))
  fs_left <- fs_left[M:N]

  fs_right <- fs[fs > f_center] - f_center
  N <- length(fs_right)
  M <- min(0.2 * N, 3 * sqrt(N))
  fs_right <- fs_right[M:N]

  # Default to NaN if left tail is ill-defined
  xi_hat_left <- NaN
  if (length(fs_left) > 40)
    xi_hat_left <- compute_xi_hat(fs_left)

  # Default to NaN if right tail is ill-defined
  xi_hat_right <- NaN
  if (length(fs_right) > 40)
    xi_hat_right <- compute_xi_hat(fs_right)

```

```

    c(xi_hat_left, xi_hat_right)
  }

# ensemble.
# @param samples A two-dimensional array of scalar Markov chain states
#               with the first dimension indexing the Markov chains and
#               the second dimension indexing the sequential states
#               within each Markov chain.
# @param max_width Maximum line width for printing
check_tail_xi_hats <- function(samples, max_width=72) {
  if (length(dim(samples)) != 2) {
    cat('Input variable `samples` has the wrong dimension')
    return
  }
}

```

3.2 Frozen Chains

Another sign of problems is when all evaluations of an expectand are constant. This could be due to the Markov chain being stuck at a single state or just that the pushforward distribution of the expectand concentrates on a single value. We can't distinguish between these possibilities without more information, but we can signal a constant expectand by looking at its empirical variance.

Here we'll use a Welford accumulator to compute the empirical variance of the expectand values in a single sweep.

```

# pass using Welford accumulators.
# @params A one-dimensional array of expectand values.
# @return The empirical mean and variance.
welford_summary <- function(fs) {
  mean <- 0
  var <- 0

  N <- length(fs)
  for (n in 1:N) {
    delta <- fs[n] - mean
    mean <- mean + delta / n
    var <- var + delta * (fs[n] - mean)
  }
}

```

```

# @param samples A two-dimensional array of scalar Markov chain states
#               with the first dimension indexing the Markov chains and
#               the second dimension indexing the sequential states
#               within each Markov chain.
# @param max_width Maximum line width for printing
check_variances <- function(samples, max_width=72) {
  if (length(dim(samples)) != 2) {
    cat('Input variable `samples` has the wrong dimension')
    return
  }
}

```

3.3 Split Rhat

One of the key features of Markov chain equilibrium is that the distribution of Markov chain realizations is independent of the initialization. In particular the expectand evaluations from any equilibrated Markov chain should be statistically equivalent to any other. Even more the evaluations across any subset of Markov chain states should be equivalent.

The split \hat{R} statistic quantifies the heterogeneity in the expectand evaluations across an ensemble of Markov chains, each of which has been split in half. Mathematically split \hat{R} is similar to analysis of variance in that compares the empirical variance of the average expectand values in each chain half to the average of the empirical variances in each chain half; the key difference is that split \hat{R} transforms this ratio so that in equilibrium the statistic decays towards 1 from above.

When split \hat{R} is much larger than 1 the expectand evaluations across each Markov chain halves are not consistent with each other. This could be because the Markov chains have not converged to the same typical set or because they have not yet expanded into that typical set.

```

# terminal Markov chains
# @params chain A sequence of expectand values derived from a single
#             Markov chain.
# @return Two subsequences of expectand values.
split_chain <- function(chain) {
  N <- length(chain)
  M <- N %% 2
  list(chain1 <- chain[1:M], chain2 <- chain[(M + 1):N])
}

```

```

# ensemble.
# @param samples A two-dimensional array of scalar Markov chain states
#               with the first dimension indexing the Markov chains and
#               the second dimension indexing the sequential states
#               within each Markov chain.
# @return Split Rhat estimate.
compute_split_rhat <- function(samples) {
  if (length(dim(samples)) != 2) {
    cat('Input variable `samples` has the wrong dimension')
    return
  }

  # @param expectand_samples A named list of two-dimensional arrays for
  #                           each expectand. The first dimension of each
  #                           element indexes the Markov chains and the
  #                           second dimension indexes the sequential
  #                           states within each Markov chain.
  compute_split_rhats <- function(expectand_samples) {
    if (!is.vector(expectand_samples)) {
      cat('Input variable `expectand_samples` is not a named list!')
      return
    }

    # @param samples A two-dimensional array of scalar Markov chain states
    #                 with the first dimension indexing the Markov chains and
    #                 the second dimension indexing the sequential states
    #                 within each Markov chain.
    # @param max_width Maximum line width for printing
    check_rhat <- function(samples, max_width=72) {
      if (length(dim(samples)) != 2) {
        cat('Input variable `samples` has the wrong dimension')
        return
      }
    }
  }
}

```

3.4 Integrated Autocorrelation Time

The information about the target distribution encoded within a Markov chain, and hence the potential precision of Markov chain Monte Carlo estimators, is limited by the autocorrelation of the internal states. Assuming equilibrium we can estimate the stationary autocorrelations

between the outputs of a given expectand from the realized Markov chain and then combine them into an estimate of the integrated autocorrelation time $\tau[f]$ which moderates the asymptotic variance of well-behaved Markov chain Monte Carlo estimators.

In practice it's often easier to interpret the effective sample size,

$$\text{ESS}[f] = \frac{N}{\tau[f]},$$

or in practice the empirical effective sample size that we estimate from the realized Markov chains,

$$\text{ESS}\hat{S}[f] = \frac{N}{\hat{\tau}[f]}.$$

The effective sample size can be interpreted as how large of an ensemble of exact samples we would need to achieve the same estimator error for the particular expectand of interest.

```
# of expectand values, known here as \hat{\tau}.
# @param fs A one-dimensional array of expectand values.
# @return Left and right shape estimators.
compute_tau_hat <- function(fs) {
  # Compute empirical autocorrelations
  N <- length(fs)
  zs <- fs - mean(fs)

  if (var(fs) < 1e-10)
    return(Inf)

  B <- 2**ceiling(log2(N)) # Next power of 2 after N
  zs_buff <- c(zs, rep(0, B - N))

  Fs <- fft(zs_buff)
  Ss <- Fs * Conj(Fs)
  Rs <- fft(Ss, inverse=TRUE)

  acov_buff <- Re(Rs)
  rhos <- head(acov_buff, N) / acov_buff[1]

  # Drop last lag if (L + 1) is odd so that the lag pairs are complete
  L <- N
  if ((L + 1) %% 2 == 1)
    L <- L - 1

  # Number of lag pairs
  P <- (L + 1) / 2
```

```

# Construct asymptotic correlation from initial monotone sequence
old_pair_sum <- rhos[1] + rhos[2]
for (p in 2:P) {
  current_pair_sum <- rhos[2 * p - 1] + rhos[2 * p]

  if (current_pair_sum < 0) {
    rho_sum <- sum(rhos[2:(2 * p)])

    if (rho_sum <= -0.25)
      rho_sum <- -0.25

    asymp_corr <- 1.0 + 2 * rho_sum
    return (asymp_corr)
  }

# Markov chains for the given expectands
# @param expectand_samples A named list of two-dimensional arrays for
#                           each expectand. The first dimension of each
#                           element indexes the Markov chains and the
#                           second dimension indexes the sequential
#                           states within each Markov chain.
compute_min_eesss <- function(expectand_samples) {
  if (!is.vector(expectand_samples)) {
    cat('Input variable `expectand_samples` is not a named list!')
    return
  }
}

```

Assuming stationarity we can use the empirical effective sample size to estimate the Markov chain Monte Carlo standard error for any well-behaved expectand estimator

$$\hat{f} \approx \mathbb{E}_{\pi}[f].$$

The necessary effective sample size depends on the precision required for a given Markov chain Monte Carlo estimator. This can vary not only from analysis to analysis but also between multiple expectands within a single analysis. That said an effective sample size of 100 is sufficient for most applications and provides a useful rule of thumb.

When Markov chains have not equilibrated the empirical effective sample size will have no relation to the error of Markov chain Monte Carlo estimators. To avoid any confusion we should interpret an empirical effective sample size simply as a quantification of the autocorrelations of a particular expectand within a realized Markov chain. In particular an empirical effective sample size below 100 indicates strong autocorrelation that will complicate Markov chain Monte Carlo estimation in the worst case and reduce estimator precision in the best case.


```

# expectand output ensemble.
# @param samples A two-dimensional array of scalar Markov chain states
#               with the first dimension indexing the Markov chains and
#               the second dimension indexing the sequential states
#               within each Markov chain.
# @param min_eess_per_chain The minimum empirical effective sample size
#               before a warning message is passed.
# @param max_width Maximum line width for printing
check_eess <- function(samples,
                        min_eess_per_chain=100,
                        max_width=72) {
  if (length(dim(samples)) != 2) {
    cat('Input variable `samples` has the wrong dimension')
    return
  }
}

```

For example empirical effective sample sizes can provide a useful way to distinguish if some diagnostic failures are due to Markov chains that are just too short or more persistent problems.

3.5 All Expectand Diagnostics

In practice we have no reason not to check all of these diagnostics at once for each expectand of interest.

```

# @param expectand_samples A named list of two-dimensional arrays for
#                           each expectand. The first dimension of each
#                           element indexes the Markov chains and the
#                           second dimension indexes the sequential
#                           states within each Markov chain.
# @param min_eess_per_chain The minimum empirical effective sample size
#                           before a warning message is passed.
# @param exclude_zvar Binary variable to exclude all expectands with
#                           vanishing empirical variance from other diagnostic
#                           checks.
# @param max_width Maximum line width for printing
check_all_expectand_diagnostics <- function(expectand_samples,
                                             min_eess_per_chain=100,
                                             exclude_zvar=FALSE,
                                             max_width=72) {

  if (!is.vector(expectand_samples)) {

```

```

    cat('Input variable `expectand_samples` is not a named list!')
  return
}

```

That said for particularly problematic fits the output from checking all of the expectands can be overwhelming. In cases where that may be a risk we can summarize the output more compactly.

```

# @param expectand_samples A named list of two-dimensional arrays for
#                           each expectand. The first dimension of each
#                           element indexes the Markov chains and the
#                           second dimension indexes the sequential
#                           states within each Markov chain.
# @param min_eess_per_chain The minimum empirical effective sample size
#                           before a warning message is passed.
# @param exclude_zvar Binary variable to exclude all expectands with
#                       vanishing empirical variance from other diagnostic
#                       checks.
# @param max_width Maximum line width for printing
summarize_expectand_diagnostics <- function(expectand_samples,
                                           min_eess_per_chain=100,
                                           exclude_zvar=FALSE,
                                           max_width=72) {

  if (!is.vector(expectand_samples)) {
    cat('Input variable `expectand_samples` is not a named list!')
    return
  }
}

```

3.6 Empirical Autocorrelation Visualization

If we encounter large empirical integrated autocorrelation times, or small estimated effective sample sizes, then we may want to follow up with the empirical autocorrelations themselves. An empirical correlogram provides a useful visualization of these estimates.

```

# @param fs A one-dimensional array of sequential expectand values.
# @return A one-dimensional array of empirical autocorrelations at each
#         lag up to the length of the sequence.
compute_rhos <- function(fs) {
  # Compute empirical autocorrelations
  N <- length(fs)
}

```

```

zs <- fs - mean(fs)

if (var(fs) < 1e-10)
  return(rep(1, N))

B <- 2**ceiling(log2(N)) # Next power of 2 after N
zs_buff <- c(zs, rep(0, B - N))

Fs <- fft(zs_buff)
Ss <- Fs * Conj(Fs)
Rs <- fft(Ss, inverse=TRUE)

acov_buff <- Re(Rs)
rhos <- head(acov_buff, N) / acov_buff[1]

# Drop last lag if (L + 1) is odd so that the
# lag pairs are complete
L <- N
if ((L + 1) %% 2 == 1)
  L <- L - 1

# Number of lag pairs
P <- (L + 1) / 2

# Construct asymptotic correlation from initial monotone sequence
old_pair_sum <- rhos[1] + rhos[2]
max_L <- N

for (p in 2:P) {
  current_pair_sum <- rhos[2 * p - 1] + rhos[2 * p]

  if (current_pair_sum < 0) {
    max_L <- 2 * p
    rhos[(max_L + 1):N] <- 0
    break
  }
}

# chain ensemble.
# @param fs A two-dimensional array of scalar Markov chain states
#           with the first dimension indexing the Markov chains and
#           the second dimension indexing the sequential states

```

```

#           within each Markov chain.
# @param max_L Maximum autocorrelation lag
# @param rho_lim Plotting range of autocorrelation values
# @display_name Name of expectand
plot_empirical_correlogram <- function(fs,
                                     max_L,
                                     rho_lim=c(-0.2, 1.1),
                                     display_name="") {
  if (length(dim(fs)) != 2) {
    cat('Input variable `fs` has the wrong dimensions!')
  }
}

```

3.7 Chain-Separated Pairs Plot

We can also visualize strong autocorrelations by coloring the states of each Markov chain in a continuous gradient. When neighboring states are strongly correlated these colors will appear to vary smoothly across the ambient space. More productive Markov transitions result in a more chaotic spray of colors.

```

# expectands as a pairs plot. Point colors darken along each Markov
# chain to visualize the autocorrelation.
# @param f1s A two-dimensional array of expectand values with the first
#           dimension indexing the Markov chains and the second
#           dimension indexing the sequential states within each
#           Markov chain.
# @params display_name1 Name of first expectand
# @param f2s A two-dimensional array of expectand values with the first
#           dimension indexing the Markov chains and the second
#           dimension indexing the sequential states within each
#           Markov chain.
# @params display_name2 Name of second expectand
plot_pairs_by_chain <- function(f1s, display_name1,
                               f2s, display_name2) {
  if (length(dim(f1s)) != 2) {
    cat('Input variable `f1s` has the wrong dimensions!')
    return
  }
}

```

4 Markov Chain Monte Carlo Estimation

If none of the diagnostics indicate an obstruction to a Markov chain Monte Carlo central limit theorem then we can construct expectation value estimates and their standard errors.

```
# @param samples A two-dimensional array of scalar Markov chain states
#               with the first dimension indexing the Markov chains and
#               the second dimension indexing the sequential states
#               within each Markov chain.
# @param expectand Scalar function to be applied to the Markov chain
#               states.
# @return A two-dimensional array of expectand values with the
#         first dimension indexing the Markov chains and the
#         second dimension indexing the sequential states within
#         each Markov chain.
pushforward_chains <- function(samples, expectand) {
  apply(samples, 2, expectand)
}

# @param fs A one-dimensional array of sequential expectand values.
# @return The Markov chain Monte Carlo estimate, its estimated standard
#         error, and empirical effective sample size.
mcmc_est <- function(fs) {
  S <- length(fs)
  if (S == 1) {
    return(c(fs[1], 0, NaN))
  }

  # @param samples A two-dimensional array of expectand values with the
  #               first dimension indexing the Markov chains and the
  #               second dimension indexing the sequential states within
  #               each Markov chain.
  # @return The ensemble Markov chain Monte Carlo estimate, its estimated
  #         standard error, and empirical effective sample size.
  ensemble_mcmc_est <- function(samples) {
    if (length(dim(samples)) != 2) {
      cat('Input variable `samples` has the wrong dimension')
      return (c(NaN, NaN, NaN))
    }
  }
}
```

In addition to examining the single expectation value of an expectand we can also visualize the entire pushforward distribution of the expectand by estimating the target probabilities in histogram bins.

```
# histogram, using Markov chain Monte Carlo estimators to estimate the
# output bin probabilities. Bin probability estimator error is shown
# in gray.
# @param samples A two-dimensional array of expectand values with the
#               first dimension indexing the Markov chains and the
#               second dimension indexing the sequential states within
#               each Markov chain.
# @param B The number of histogram bins
# @param display_name Expectand name
# @param flim Optional histogram range
# @param baseline Optional baseline value for visual comparison
plot_expectand_pushforward <- function(samples, B, display_name="f",
                                       flim=NULL, baseline=NULL) {
  if (length(dim(samples)) != 2) {
    cat('Input variable `samples` has the wrong dimension')
    return
  }
}
```

5 Demonstration

Now let's put all of these analysis tools to use with an `rstan` fit object.

First we setup our local R environment.

```
library(rstan)
rstan_options(auto_write = TRUE) # Cache compiled Stan programs
options(mc.cores = parallel::detectCores()) # Parallelize chains
parallel::setDefaultClusterOptions(setup_strategy = "sequential")
```

Next we source all of these diagnostics into a local environment to avoid any conflicts with other functions.

```
util <- new.env()
source('stan_utility_rstan.R', local=util)
```

Then we can simulate some binary data from a logistic regression model.

```

simu <- stan(file="stan_programs/simu_logistic_reg.stan",
             iter=1, warmup=0, chains=1,
             seed=4838282, algorithm="Fixed_param")

```

```

SAMPLING FOR MODEL 'simu_logistic_reg' NOW (CHAIN 1).
Chain 1: Iteration: 1 / 1 [100%] (Sampling)
Chain 1:
Chain 1: Elapsed Time: 0 seconds (Warm-up)
Chain 1:           0.001723 seconds (Sampling)
Chain 1:           0.001723 seconds (Total)
Chain 1:

```

```

X <- extract(simu)$X[1,,]
y <- extract(simu)$y[1,]

data <- list("M" = 3, "N" = 1000, "x0" = c(-1, 0, 1), "X" = X, "y" = y)

```

We'll try to fit this model not with a constraint-respecting logistic regression model but rather a constraint blaspheming linear probability model. Importantly the resulting posterior density function is discontinuous with configurations $\alpha + \delta X * \beta > 0$ resulting in finite `bernoulli_lpmf` outputs and those with $\alpha + \delta X * \beta \leq 0$ resulting in minus infinite outputs.

Because of this awkward constraint we have to carefully initialize our Markov chains to satisfy the $\alpha + \delta X * \beta > 0$ constraint.

```

set.seed(48383499)

interval_inits <- list()

for (c in 1:4) {
  beta <- c(0, 0, 0)
  alpha <- rnorm(1, 0.5, 0.1)
  interval_inits[[c]] <- list("alpha" = alpha, "beta" = beta)
}

fit <- stan(file="stan_programs/bernoulli_linear.stan",
            data=data, seed=8438338,
            warmup=1000, iter=2024, refresh=0,
            init=interval_inits)

```

Stan is able to run to completion, but just how useful are the Markov chains that it generates?

Let's start with the Hamiltonian Monte Carlo diagnostics.

```
diagnostics <- util$extract_hmc_diagnostics(fit)
util$check_all_hmc_diagnostics(diagnostics)
```

Chain 1: 1022 of 1024 transitions (99.8%) diverged.

Chain 2: 1014 of 1024 transitions (99.0%) diverged.

Chain 3: 1015 of 1024 transitions (99.1%) diverged.

Chain 4: 1013 of 1024 transitions (98.9%) diverged.

Chain 4: Average proxy acceptance statistic (0.629) is
smaller than 90% of the target (0.801).

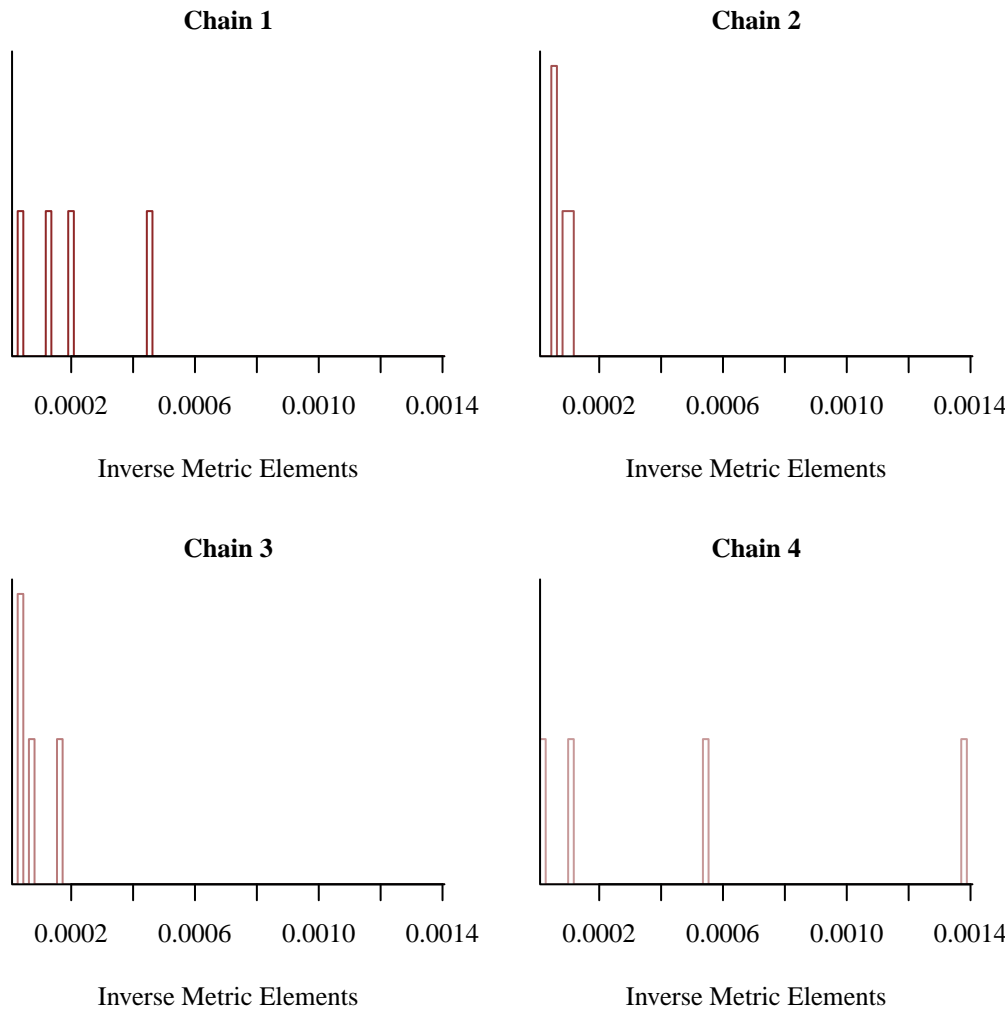
Divergent Hamiltonian transitions result from unstable numerical trajectories. These instabilities are often due to degenerate target geometry, especially "pinches". If there are only a small number of divergences then running with `adapt_delta` larger than 0.801 may reduce the instabilities at the cost of more expensive Hamiltonian transitions.

A small average proxy acceptance statistic indicates that the adaptation of the numerical integrator step size failed to converge. This is often due to discontinuous or imprecise gradients.

Almost every transition across the four Markov chains resulted in a divergence. This is due to the discontinuity in the linear probability model as the sudden jump from a finite to a negative infinite target density results in unstable numerical trajectories.

We also see the one of the Markov chains wasn't able to hit the step size adaptation target. To see why let's dig into the adapted configuration of the Hamiltonian Markov transition.

```
util$plot_inv_metric(fit, 75)
```

The problematic Markov chain also exhibits the most variation in its inverse metric elements, which in this case is probably an artifact of its warmup phase spending too much time close to a constraint boundary. Artificially variable inverse metric elements frustrate numerical integration which can then frustrate the integrator step size adaptation.

Interestingly the adapted step sizes are nearly the same for all four Markov chains. The lower average proxy acceptance statistic seen in the fourth Markov chain is due entirely to the wonky inverse metric adaptation.

```
util$display_stepsizes(diagnostics)
```

Chain 1: Integrator Step Size = 0.022103

Chain 2: Integrator Step Size = 0.024148

Chain 3: Integrator Step Size = 0.037035
Chain 4: Integrator Step Size = 0.026320

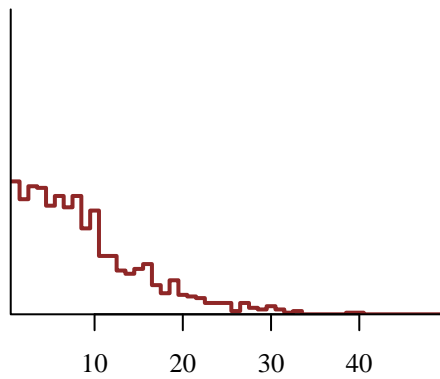
```
util$display_ave_accept_proxy(diagnostics)
```

Chain 1: Average proxy acceptance statistic = 0.766
Chain 2: Average proxy acceptance statistic = 0.814
Chain 3: Average proxy acceptance statistic = 0.729
Chain 4: Average proxy acceptance statistic = 0.629

The different inverse metric results in different Hamiltonian dynamics. In this case the dynamics driving the fourth Markov chain are not able to explore as far as those in the other chains.

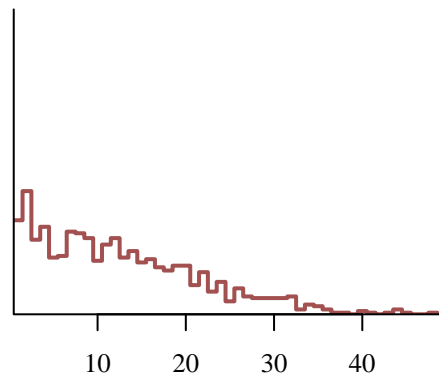
```
util$plot_num_leapfrogs_by_chain(diagnostics)
```

Chain 1 (Stepsize = 0.022)



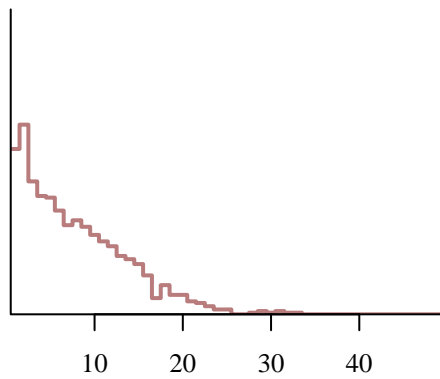
Numerical Trajectory Length

Chain 2 (Stepsize = 0.024)



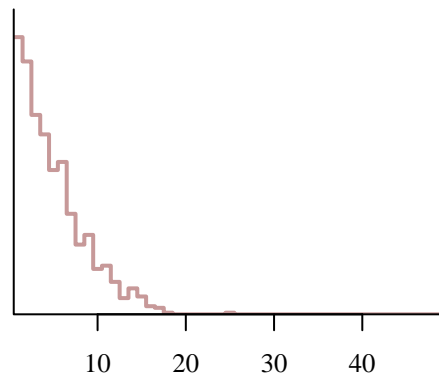
Numerical Trajectory Length

Chain 3 (Stepsize = 0.037)



Numerical Trajectory Length

Chain 4 (Stepsize = 0.026)

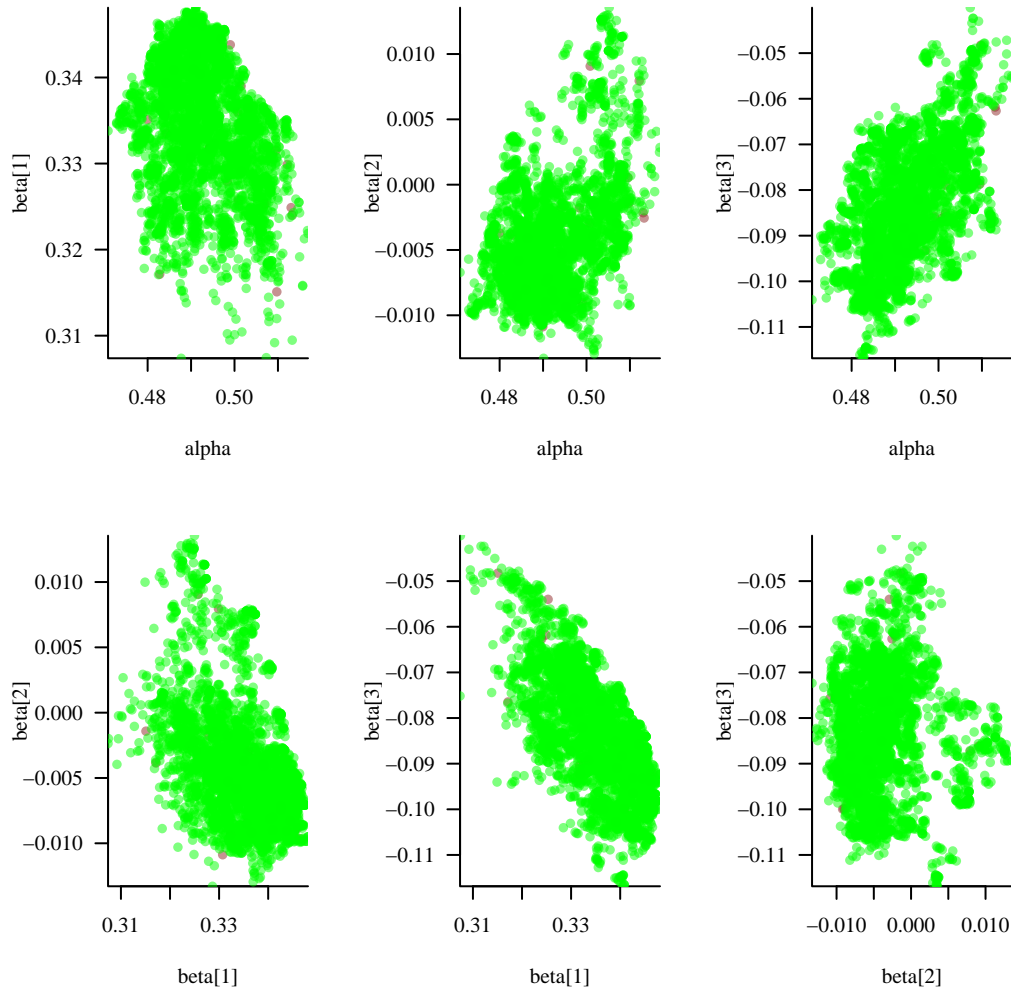


Numerical Trajectory Length

Finally because nearly every transition is divergent we can't extract much information from the divergent-labeled pairs plots.

```
samples <- util$extract_expectands(fit)

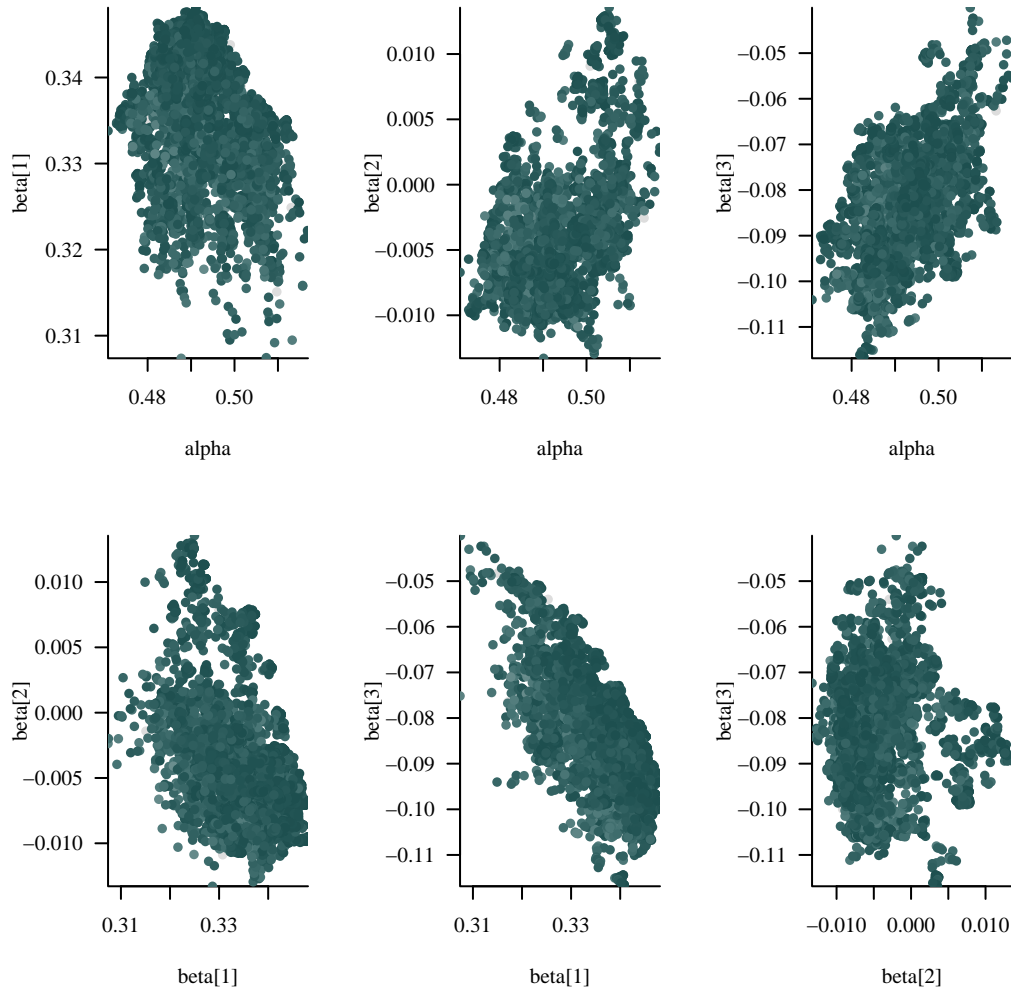
names <- c('alpha',
           sapply(1:data$M, function(m) paste0('beta[', m, ']')))
util$plot_div_pairs(names, names, samples, diagnostics)
```



We can also color the divergent transitions by their numerical trajectory lengths. On average transitions from shorter numerical trajectories should be closer to the problematic behavior than transitions from longer numerical trajectories. Because there are so many divergent transitions here the point colors overlap and it's hard to make too much out, but it does look like there may be a problematic boundary. For example plot of `beta[2]` against `beta[1]` is consistent with a boundary defined by

$$\beta_1 + \beta_2 = \text{constant}.$$

```
util$plot_div_pairs(names, names, samples, diagnostics, plot_mode=1)
```



Having examined the Hamiltonian Monte Carlo diagnostics let's now look through the expectand specific diagnostics. By default we'll look at the parameter projection functions as well as all of the expectands defined in the `generated quantities` block.

Because of the Hamiltonian Monte Carlo diagnostic failures I'm going to limit the output just in case we have many failures for these diagnostics as well.

```
util$summarize_expectand_diagnostics(samples)
```

The expectands `alpha`, `beta[1]`, `beta[2]`, `beta[3]`, `p[1]`, `p[2]`, `p[3]`, `p[4]`, `p[5]`, `p[6]`, `p[7]`, `p[8]`, `p[9]`, `p[10]`, `p[11]`, `p[12]`, `p[13]`, `p[14]`, `p[15]`, `p[16]`, `p[17]`, `p[18]`, `p[19]`, `p[20]`, `p[21]`, `p[22]`, `p[23]`, `p[24]`, `p[25]`, `p[26]`, `p[27]`, `p[28]`, `p[29]`, `p[30]`, `p[31]`, `p[32]`, `p[33]`, `p[34]`,

p[35], p[36], p[37], p[38], p[39], p[40], p[41], p[42], p[43], p[44],
p[45], p[46], p[47], p[48], p[49], p[50], p[51], p[52], p[53], p[54],
p[55], p[56], p[57], p[58], p[59], p[60], p[61], p[62], p[63], p[64],
p[65], p[66], p[67], p[68], p[69], p[70], p[71], p[72], p[73], p[74],
p[75], p[76], p[77], p[78], p[79], p[80], p[81], p[82], p[83], p[84],
p[85], p[86], p[87], p[88], p[89], p[90], p[91], p[92], p[93], p[94],
p[95], p[96], p[97], p[98], p[99], p[100], p[101], p[102], p[103],
p[104], p[105], p[106], p[107], p[108], p[109], p[110], p[111], p[112],
p[113], p[114], p[115], p[116], p[117], p[118], p[119], p[120], p[121],
p[122], p[123], p[124], p[125], p[126], p[127], p[128], p[129], p[130],
p[131], p[132], p[133], p[134], p[135], p[136], p[137], p[138], p[139],
p[140], p[141], p[142], p[143], p[144], p[145], p[146], p[147], p[148],
p[149], p[150], p[151], p[152], p[153], p[154], p[155], p[156], p[157],
p[158], p[159], p[160], p[161], p[162], p[163], p[164], p[165], p[166],
p[167], p[168], p[169], p[170], p[171], p[172], p[173], p[174], p[175],
p[176], p[177], p[178], p[179], p[180], p[181], p[182], p[183], p[184],
p[185], p[186], p[187], p[188], p[189], p[190], p[191], p[192], p[193],
p[194], p[195], p[196], p[197], p[198], p[199], p[200], p[201], p[202],
p[203], p[204], p[205], p[206], p[207], p[208], p[209], p[210], p[211],
p[212], p[213], p[214], p[215], p[216], p[217], p[218], p[219], p[220],
p[221], p[222], p[223], p[224], p[225], p[226], p[227], p[228], p[229],
p[230], p[231], p[232], p[233], p[234], p[235], p[236], p[237], p[238],
p[239], p[240], p[241], p[242], p[243], p[244], p[245], p[246], p[247],
p[248], p[249], p[250], p[251], p[252], p[253], p[254], p[255], p[256],
p[257], p[258], p[259], p[260], p[261], p[262], p[263], p[264], p[265],
p[266], p[267], p[268], p[269], p[270], p[271], p[272], p[273], p[274],
p[275], p[276], p[277], p[278], p[279], p[280], p[281], p[282], p[283],
p[284], p[285], p[286], p[287], p[288], p[289], p[290], p[291], p[292],
p[293], p[294], p[295], p[296], p[297], p[298], p[299], p[300], p[301],
p[302], p[303], p[304], p[305], p[306], p[307], p[308], p[309], p[310],
p[311], p[312], p[313], p[314], p[315], p[316], p[317], p[318], p[319],
p[320], p[321], p[322], p[323], p[324], p[325], p[326], p[327], p[328],
p[329], p[330], p[331], p[332], p[333], p[334], p[335], p[336], p[337],
p[338], p[339], p[340], p[341], p[342], p[343], p[344], p[345], p[346],
p[347], p[348], p[349], p[350], p[351], p[352], p[353], p[354], p[355],
p[356], p[357], p[358], p[359], p[360], p[361], p[362], p[363], p[364],
p[365], p[366], p[367], p[368], p[369], p[370], p[371], p[372], p[373],
p[374], p[375], p[376], p[377], p[378], p[379], p[380], p[381], p[382],
p[383], p[384], p[385], p[386], p[387], p[388], p[389], p[390], p[391],
p[392], p[393], p[394], p[395], p[396], p[397], p[398], p[399], p[400],
p[401], p[402], p[403], p[404], p[405], p[406], p[407], p[408], p[409],
p[410], p[411], p[412], p[413], p[414], p[415], p[416], p[417], p[418],
p[419], p[420], p[421], p[422], p[423], p[424], p[425], p[426], p[427],

p[815], p[816], p[817], p[818], p[819], p[820], p[821], p[822], p[823],
p[824], p[825], p[826], p[827], p[828], p[829], p[830], p[831], p[832],
p[833], p[834], p[835], p[836], p[837], p[838], p[839], p[840], p[841],
p[842], p[843], p[844], p[845], p[846], p[847], p[848], p[849], p[850],
p[851], p[852], p[853], p[854], p[855], p[856], p[857], p[858], p[859],
p[860], p[861], p[862], p[863], p[864], p[865], p[866], p[867], p[868],
p[869], p[870], p[871], p[872], p[873], p[874], p[875], p[876], p[877],
p[878], p[879], p[880], p[881], p[882], p[883], p[884], p[885], p[886],
p[887], p[888], p[889], p[890], p[891], p[892], p[893], p[894], p[895],
p[896], p[897], p[898], p[899], p[900], p[901], p[902], p[903], p[904],
p[905], p[906], p[907], p[908], p[909], p[910], p[911], p[912], p[913],
p[914], p[915], p[916], p[917], p[918], p[919], p[920], p[921], p[922],
p[923], p[924], p[925], p[926], p[927], p[928], p[929], p[930], p[931],
p[932], p[933], p[934], p[935], p[936], p[937], p[938], p[939], p[940],
p[941], p[942], p[943], p[944], p[945], p[946], p[947], p[948], p[949],
p[950], p[951], p[952], p[953], p[954], p[955], p[956], p[957], p[958],
p[959], p[960], p[961], p[962], p[963], p[964], p[965], p[966], p[967],
p[968], p[969], p[970], p[971], p[972], p[973], p[974], p[975], p[976],
p[977], p[978], p[979], p[980], p[981], p[982], p[983], p[984], p[985],
p[986], p[987], p[988], p[989], p[990], p[991], p[992], p[993], p[994],
p[995], p[996], p[997], p[998], p[999], p[1000], y_pred[1], y_pred[2],
y_pred[3], y_pred[4], y_pred[5], y_pred[6], y_pred[7], y_pred[8],
y_pred[9], y_pred[10], y_pred[11], y_pred[12], y_pred[13], y_pred[14],
y_pred[15], y_pred[16], y_pred[17], y_pred[18], y_pred[19], y_pred[20],
y_pred[21], y_pred[22], y_pred[23], y_pred[24], y_pred[25], y_pred[26],
y_pred[27], y_pred[28], y_pred[29], y_pred[30], y_pred[31], y_pred[32],
y_pred[33], y_pred[34], y_pred[35], y_pred[36], y_pred[37], y_pred[38],
y_pred[39], y_pred[40], y_pred[41], y_pred[42], y_pred[43], y_pred[44],
y_pred[45], y_pred[46], y_pred[47], y_pred[48], y_pred[49], y_pred[50],
y_pred[51], y_pred[52], y_pred[53], y_pred[54], y_pred[55], y_pred[56],
y_pred[57], y_pred[58], y_pred[59], y_pred[60], y_pred[61], y_pred[62],
y_pred[63], y_pred[64], y_pred[65], y_pred[66], y_pred[67], y_pred[68],
y_pred[69], y_pred[70], y_pred[71], y_pred[72], y_pred[73], y_pred[74],
y_pred[75], y_pred[76], y_pred[77], y_pred[78], y_pred[79], y_pred[80],
y_pred[81], y_pred[82], y_pred[83], y_pred[84], y_pred[85], y_pred[86],
y_pred[87], y_pred[88], y_pred[89], y_pred[90], y_pred[91], y_pred[92],
y_pred[93], y_pred[94], y_pred[95], y_pred[96], y_pred[97], y_pred[98],
y_pred[99], y_pred[100], y_pred[101], y_pred[102], y_pred[103],
y_pred[104], y_pred[105], y_pred[106], y_pred[107], y_pred[108],
y_pred[109], y_pred[110], y_pred[111], y_pred[112], y_pred[113],
y_pred[114], y_pred[115], y_pred[116], y_pred[117], y_pred[118],
y_pred[119], y_pred[120], y_pred[121], y_pred[122], y_pred[123],
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y_pred[129], y_pred[130], y_pred[131], y_pred[132], y_pred[133],
y_pred[134], y_pred[135], y_pred[136], y_pred[137], y_pred[138],
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y_pred[144], y_pred[145], y_pred[146], y_pred[147], y_pred[148],
y_pred[149], y_pred[150], y_pred[151], y_pred[152], y_pred[153],
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y_pred[989], y_pred[990], y_pred[991], y_pred[992], y_pred[993],
y_pred[994], y_pred[995], y_pred[996], y_pred[997], y_pred[998],
y_pred[999], y_pred[1000] triggered diagnostic warnings.

The expectands alpha, beta[1], beta[2], beta[3], p[1], p[2], p[3],
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 p[987], p[988], p[989], p[991], p[992], p[993], p[994], p[995], p[996],
 p[997], p[998], p[999], p[1000] triggered \hat{R} warnings.

Split Rhat larger than 1.1 suggests that at least one of the Markov chains has not reached an equilibrium.

The expectands alpha, beta[1], beta[2], beta[3], p[1], p[2], p[3],
 p[4], p[5], p[6], p[7], p[8], p[9], p[10], p[11], p[12], p[13], p[14],
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p[815], p[816], p[817], p[818], p[819], p[820], p[821], p[822], p[823],
p[824], p[825], p[826], p[827], p[828], p[829], p[830], p[831], p[832],
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p[878], p[879], p[880], p[881], p[882], p[883], p[884], p[885], p[886],

```
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p[986], p[987], p[988], p[989], p[990], p[991], p[992], p[993], p[994],
p[995], p[996], p[997], p[998], p[999], p[1000] triggered hat{ESS}
warnings.
```

Small empirical effective sample sizes indicate strong empirical autocorrelations in the realized Markov chains. If the empirical effective sample size is too small then Markov chain Monte Carlo estimation may be unreliable even when a central limit theorem holds.

.

```
clip_output <- function(output, head, tail) {
  for(l in 1:head)
    cat(paste0(output[l], "\n"))
  cat("\n")
  cat(".....\n")
  cat(".....\n")
  cat(".....\n")
  cat("\n")
  N <- length(output)
  for(l in (N - tail):N)
    cat(paste0(output[l], "\n"))
}

clip_output(capture.output(util$check_all_expectand_diagnostics(samples)),
            27, 21)
```

alpha:

```
Split hat{R} (1.575) exceeds 1.1!
Chain 1: hat{ESS} (16.304) is smaller than desired (100)!
```

```
Chain 2: hat{ESS} (16.147) is smaller than desired (100)!
Chain 3: hat{ESS} (7.943) is smaller than desired (100)!
Chain 4: hat{ESS} (6.556) is smaller than desired (100)!
```

```
beta[1]:
```

```
Split hat{R} (1.428) exceeds 1.1!
Chain 1: hat{ESS} (6.385) is smaller than desired (100)!
Chain 2: hat{ESS} (10.338) is smaller than desired (100)!
Chain 3: hat{ESS} (11.444) is smaller than desired (100)!
Chain 4: hat{ESS} (12.705) is smaller than desired (100)!
```

```
beta[2]:
```

```
Split hat{R} (1.420) exceeds 1.1!
Chain 1: hat{ESS} (12.499) is smaller than desired (100)!
Chain 2: hat{ESS} (26.170) is smaller than desired (100)!
Chain 3: hat{ESS} (5.394) is smaller than desired (100)!
Chain 4: hat{ESS} (5.913) is smaller than desired (100)!
```

```
beta[3]:
```

```
Split hat{R} (1.679) exceeds 1.1!
Chain 1: hat{ESS} (7.130) is smaller than desired (100)!
Chain 2: hat{ESS} (5.677) is smaller than desired (100)!
Chain 3: hat{ESS} (5.136) is smaller than desired (100)!
Chain 4: hat{ESS} (13.012) is smaller than desired (100)!
```

```
.....
.....
.....
```

```
Chain 3: Both left and right hat{xi}s are NaN!
Chain 4: Both left and right hat{xi}s are NaN!
```

```
y_pred[1000]:
```

```
Chain 1: Both left and right hat{xi}s are NaN!
Chain 2: Both left and right hat{xi}s are NaN!
Chain 3: Both left and right hat{xi}s are NaN!
Chain 4: Both left and right hat{xi}s are NaN!
```

Large tail hat{xi}s suggest that the expectand might not be sufficiently integrable.

Split Rhat larger than 1.1 suggests that at least one of the Markov

chains has not reached an equilibrium.

Small empirical effective sample sizes indicate strong empirical autocorrelations in the realized Markov chains. If the empirical effective sample size is too small then Markov chain Monte Carlo estimation may be unreliable even when a central limit theorem holds.

.

Well that output restriction proved to be prescient as most of the expectands are encountering problems; even this compact summary is overwhelming. To avoid completely overwhelming ourselves let's focus on the four parameter expectands.

```
base_samples <- samples[names]
util$check_all_expectand_diagnostics(samples[1:4])
```

alpha:

```
Split hat{R} (1.575) exceeds 1.1!
Chain 1: hat{ESS} (16.304) is smaller than desired (100)!
Chain 2: hat{ESS} (16.147) is smaller than desired (100)!
Chain 3: hat{ESS} (7.943) is smaller than desired (100)!
Chain 4: hat{ESS} (6.556) is smaller than desired (100)!
```

beta[1]:

```
Split hat{R} (1.428) exceeds 1.1!
Chain 1: hat{ESS} (6.385) is smaller than desired (100)!
Chain 2: hat{ESS} (10.338) is smaller than desired (100)!
Chain 3: hat{ESS} (11.444) is smaller than desired (100)!
Chain 4: hat{ESS} (12.705) is smaller than desired (100)!
```

beta[2]:

```
Split hat{R} (1.420) exceeds 1.1!
Chain 1: hat{ESS} (12.499) is smaller than desired (100)!
Chain 2: hat{ESS} (26.170) is smaller than desired (100)!
Chain 3: hat{ESS} (5.394) is smaller than desired (100)!
Chain 4: hat{ESS} (5.913) is smaller than desired (100)!
```

beta[3]:

```
Split hat{R} (1.679) exceeds 1.1!
Chain 1: hat{ESS} (7.130) is smaller than desired (100)!
Chain 2: hat{ESS} (5.677) is smaller than desired (100)!
```

Chain 3: $\hat{\text{ESS}}$ (5.136) is smaller than desired (100)!
Chain 4: $\hat{\text{ESS}}$ (13.012) is smaller than desired (100)!

Split \hat{R} at larger than 1.1 suggests that at least one of the Markov chains has not reached an equilibrium.

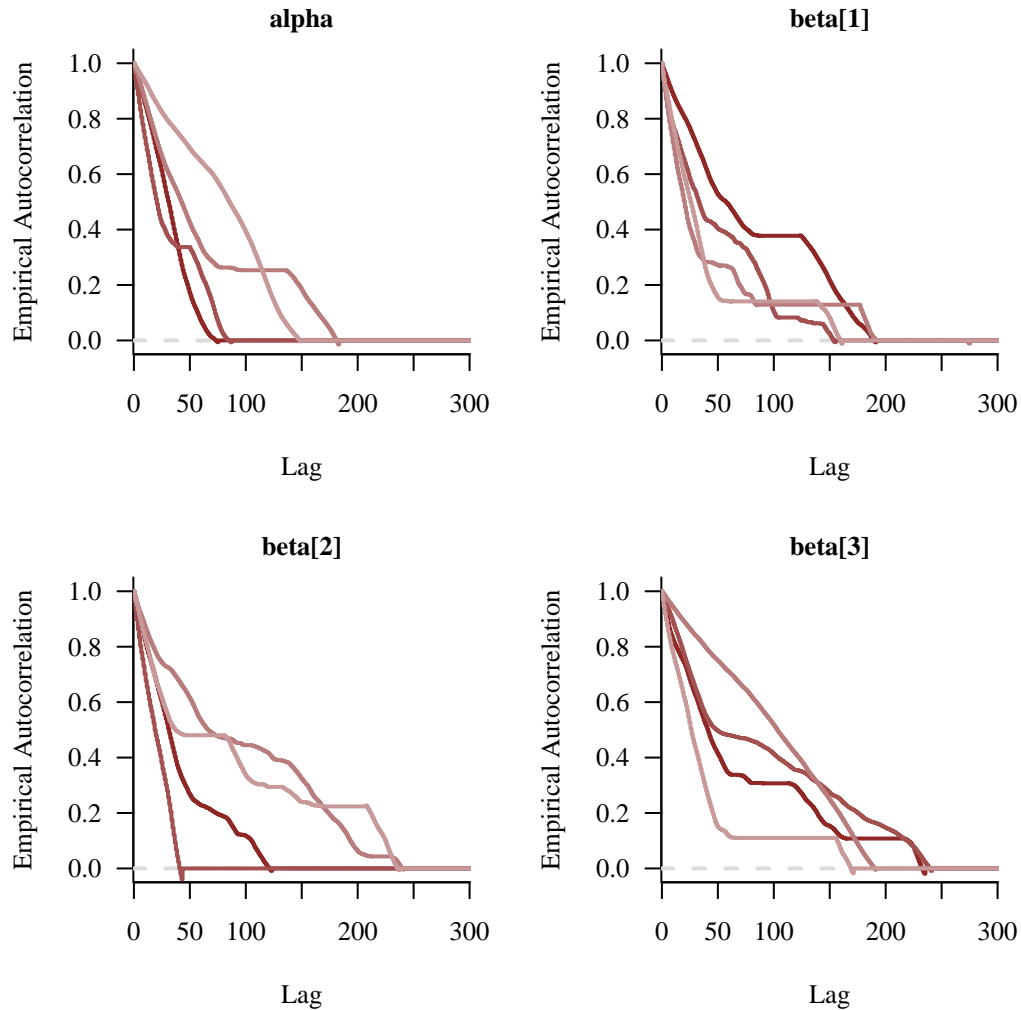
Small empirical effective sample sizes indicate strong empirical autocorrelations in the realized Markov chains. If the empirical effective sample size is too small then Markov chain Monte Carlo estimation may be unreliable even when a central limit theorem holds.

.

All four parameter expectands exhibit split \hat{R} warnings and low empirical effective sample size warnings. The question is whether or not the split \hat{R} warnings indicate quasistationarity or just insufficient exploration.

Motivated by the small effective sample size estimates let's look at the empirical correlograms for each parameter expectand.

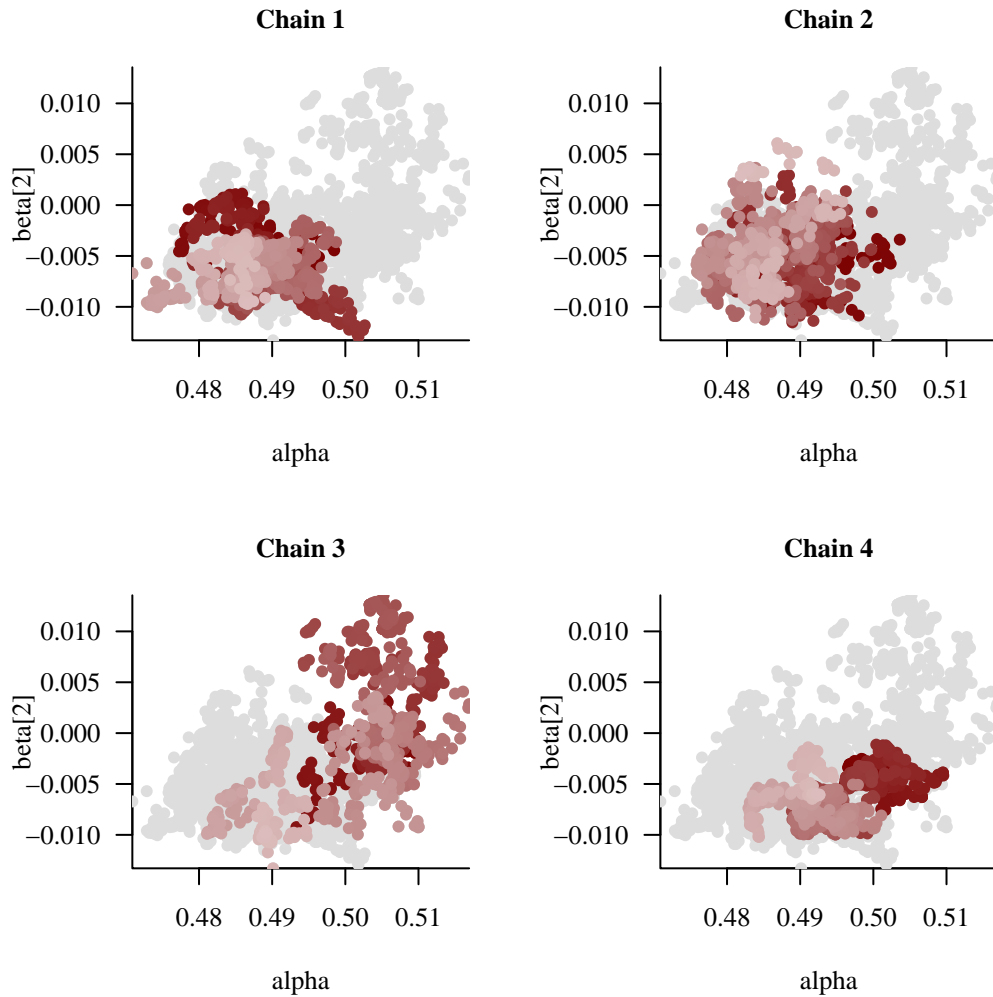
```
par(mfrow=c(2, 2), mar = c(5, 5, 2, 1))
util$plot_empirical_correlogram(samples[["alpha"]], 300,
                                rho_lim=c(-0.05, 1.05), "alpha")
util$plot_empirical_correlogram(samples[["beta[1]"]], 300,
                                rho_lim=c(-0.05, 1.05), "beta[1]")
util$plot_empirical_correlogram(samples[["beta[2]"]], 300,
                                rho_lim=c(-0.05, 1.05), "beta[2]")
util$plot_empirical_correlogram(samples[["beta[3]"]], 300,
                                rho_lim=c(-0.05, 1.05), "beta[3]")
```



Regardless of whether or not these Markov chains are stationary they are extremely autocorrelated. Assuming stationarity we don't start to forget the beginning of each Markov chain until we've worked through almost all of the total length, leaving the equivalent of only one independent sample across each chain.

This is consistent with the constraint violations breaking the coherent, gradient-driven exploration of Hamiltonian Monte Carlo so that the Markov chains devolve into diffuse random walks. Indeed looking at the chain-separated pairs plots we see the spatial color continuity characteristic of a random walk.

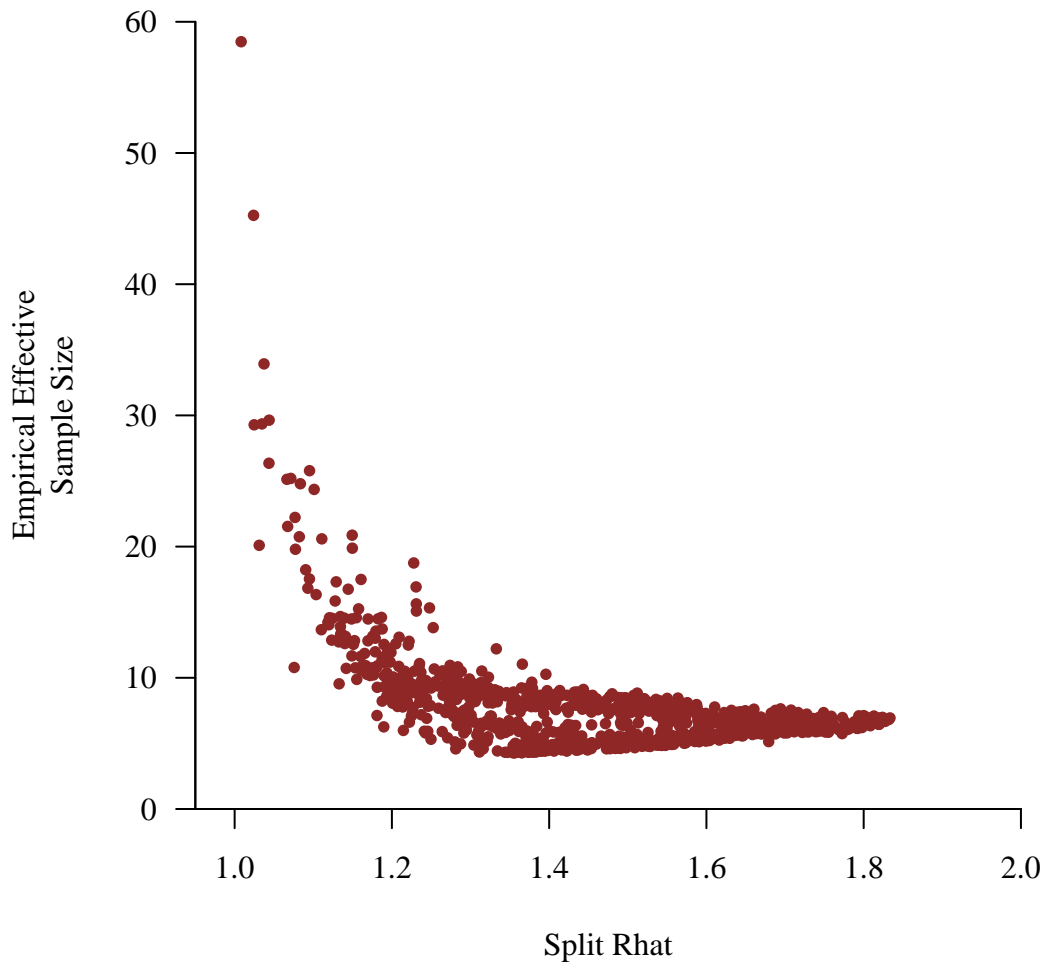
```
util$plot_pairs_by_chain(samples[["alpha"]], "alpha",
                        samples[["beta[2]"]], "beta[2]")
```



To more quantitatively blame the large split \hat{R} s on these strong autocorrelations we can plot the split \hat{R} from each expectand against the corresponding empirical effective sample size. Specifically for each expectand we plot split \hat{R} against the smallest empirical effective sample size amongst the four Markov chains.

```
rhats <- util$compute_split_rhats(samples)
min_eesss <- util$compute_min_eesss(samples)

par(mfrow=c(1, 1), mar = c(5, 5, 2, 1))
plot(rhats, min_eesss,
     col=c_dark, pch=16, cex=0.8,
     xlab="Split Rhat", xlim=c(0.95, 2),
     ylab="Empirical Effective\nSample Size", ylim=c(0, 60))
```



Every expectand with a large split \hat{R} s also exhibits a particularly small minimum empirical effective sample size, confirming that the latter are likely due to our Markov chains not containing enough information.

If we are sloppy, ignore these diagnostics, and assume that all of our Markov chain Monte Carlo estimators are accurate then we are quickly misled about the actual behavior of the posterior distribution. One way to guard against this sloppiness is to always accompany a Markov chain Monte Carlo estimator with an estimated error. Even if that error is inaccurate it can sometimes communicate underlying problems.

For example let's look at a pushforward histogram for each parameter with light gray bands visualizing the standard error around the bin probability estimates in dark red.

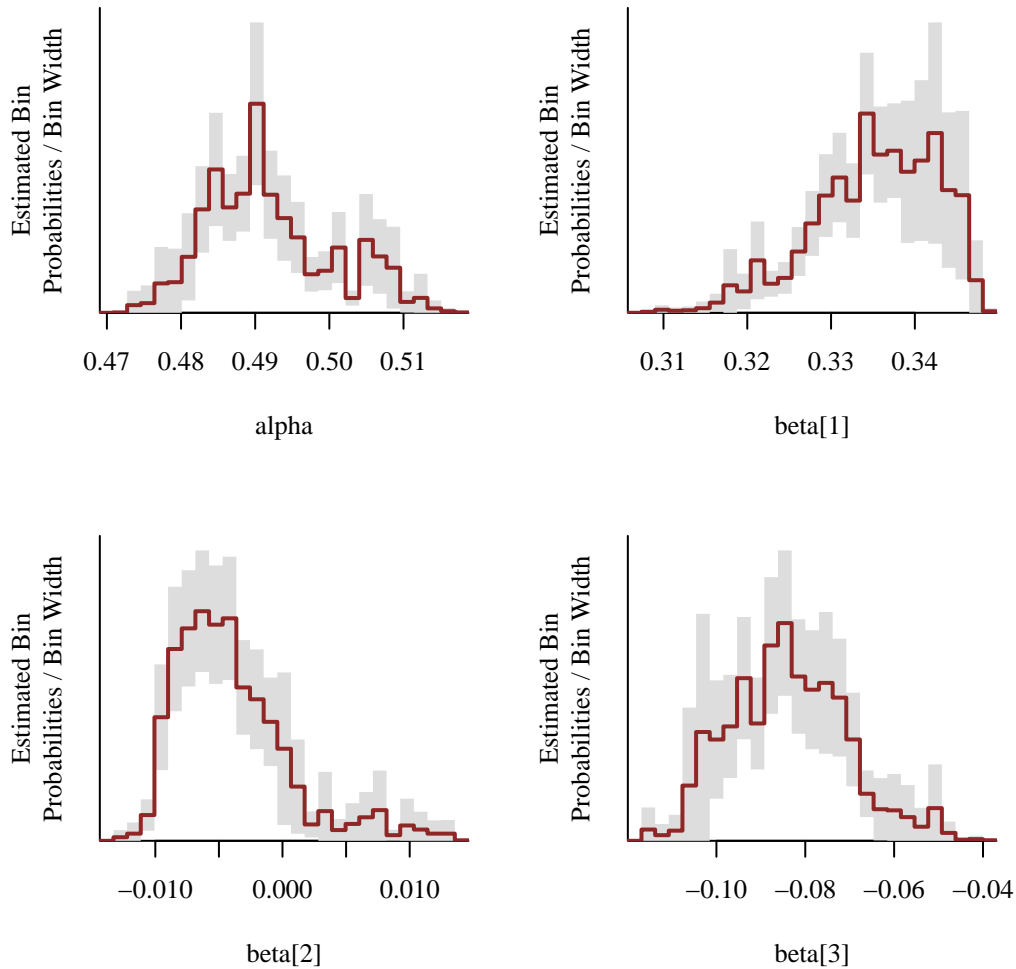
```
par(mfrow=c(2, 2), mar = c(5, 4, 2, 1))
util$plot_expectand_pushforward(samples[["alpha"]], 25,
```



```

                                display_name="alpha")
util$plot_expectand_pushforward(samples[["beta[1]"]], 25,
                                display_name="beta[1]")
util$plot_expectand_pushforward(samples[["beta[2]"]], 25,
                                display_name="beta[2]")
util$plot_expectand_pushforward(samples[["beta[3]"]], 25,
                                display_name="beta[3]")

```

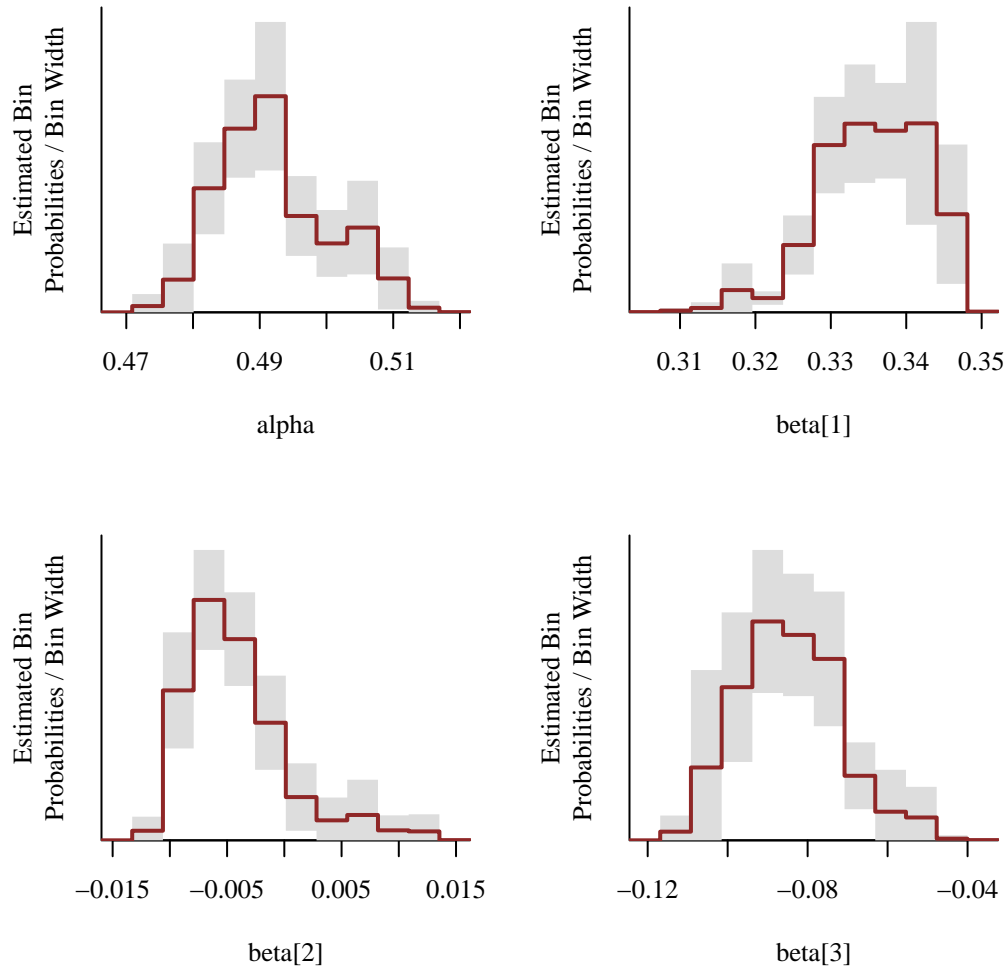


If we look at the central estimates alone we might convince ourselves of all kinds of interesting structure. For example potential multi-modality in **alpha** and **beta[2]** and platykurticity in **beta[1]** and **beta[3]**. These structures, however, are all within the scope of the relatively large standard error bands which suggests that they are all consistent with estimator noise.

Reducing the number of bins decreases the relative standard errors but at the same time many

of the visual artifacts recede.

```
par(mfrow=c(2, 2), mar = c(5, 4, 2, 1))
util$plot_expectand_pushforward(samples[["alpha"]], 10,
                                display_name="alpha")
util$plot_expectand_pushforward(samples[["beta[1]"]], 10,
                                display_name="beta[1]")
util$plot_expectand_pushforward(samples[["beta[2]"]], 10,
                                display_name="beta[2]")
util$plot_expectand_pushforward(samples[["beta[3]"]], 10,
                                display_name="beta[3]")
```



When the bin indicator functions enjoy Markov chain Monte Carlo central limit theorems these standard error bands allow us to discriminate between meaningful structure and accidental

artifacts regardless of the histogram binning. Even if central limit theorems don't hold the error bands provide one more way that we can potentially diagnose untrustworthy computation.

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Original Computing Environment

```
writeLines(readLines(file.path(Sys.getenv("HOME"), ".R/Makevars")))
```

```
CC=clang
```

```
CXXFLAGS=-O3 -mtune=native -march=native -Wno-unused-variable -Wno-unused-function -Wno-macro-redefined  
CXX=clang++ -arch x86_64 -ftemplate-depth-256
```

```
CXX14FLAGS=-O3 -mtune=native -march=native -Wno-unused-variable -Wno-unused-function -Wno-macro-redefined  
CXX14=clang++ -arch x86_64 -ftemplate-depth-256
```

```
sessionInfo()
```

```
R version 4.0.2 (2020-06-22)  
Platform: x86_64-apple-darwin17.0 (64-bit)  
Running under: macOS Catalina 10.15.7
```

```
Matrix products: default  
BLAS:   /Library/Frameworks/R.framework/Versions/4.0/Resources/lib/libRblas.dylib  
LAPACK: /Library/Frameworks/R.framework/Versions/4.0/Resources/lib/libRlapack.dylib
```

```
locale:
```

```
[1] en_US.UTF-8/en_US.UTF-8/en_US.UTF-8/C/en_US.UTF-8/en_US.UTF-8
```

attached base packages:

```
[1] stats      graphics  grDevices  utils      datasets  methods   base
```

other attached packages:

```
[1] colormap_0.1.4      rstan_2.19.3        ggplot2_3.3.1
[4] StanHeaders_2.21.0-3
```

loaded via a namespace (and not attached):

```
[1] Rcpp_1.0.4.6      pillar_1.4.4      compiler_4.0.2    prettyunits_1.1.1
[5] tools_4.0.2       digest_0.6.25     pkgbuild_1.0.8    jsonlite_1.6.1
[9] evaluate_0.17     lifecycle_0.2.0   tibble_3.0.1      gtable_0.3.0
[13] pkgconfig_2.0.3   rlang_0.4.6       cli_2.0.2         curl_4.3
[17] parallel_4.0.2    yaml_2.2.1        xfun_0.33         loo_2.2.0
[21] gridExtra_2.3     withr_2.2.0       stringr_1.4.0     dplyr_1.0.0
[25] knitr_1.40        generics_0.0.2    vctrs_0.3.0       stats4_4.0.2
[29] grid_4.0.2        tidyselect_1.1.0  glue_1.4.1        inline_0.3.15
[33] R6_2.4.1          processx_3.4.2    fansi_0.4.1       rmarkdown_2.2
[37] callr_3.4.3       purrr_0.3.4       magrittr_1.5      codetools_0.2-16
[41] matrixStats_0.56.0 ps_1.3.3          scales_1.1.1      ellipsis_0.3.1
[45] htmltools_0.4.0   assertthat_0.2.1  colorspace_1.4-1  V8_3.2.0
[49] stringi_1.4.6     munsell_0.5.0     crayon_1.3.4
```

Stan Program 2 bernoulli_linear.stan

```
data {
  int<lower=0> M; // Number of covariates
  int<lower=0> N; // Number of observations

  vector[M] x0; // Covariate baselines
  matrix[N, M] X; // Covariate design matrix

  int<lower=0, upper=1> y[N]; // Variates
}

transformed data {
  matrix[N, M] deltaX;
  for (n in 1:N) {
    deltaX[n,] = X[n] - x0';
  }
}

parameters {
  real alpha; // Intercept
  vector[M] beta; // Linear slopes
}

model {
  // Prior model
  alpha ~ normal(0, 1);
  beta ~ normal(0, 1);

  // Vectorized observation model
  y ~ bernoulli(alpha + deltaX * beta);
}

// Simulate a full observation from the current value of the parameters
generated quantities {
  vector[N] p = alpha + deltaX * beta;
  int y_pred[N] = bernoulli_rng(p);
}
```
