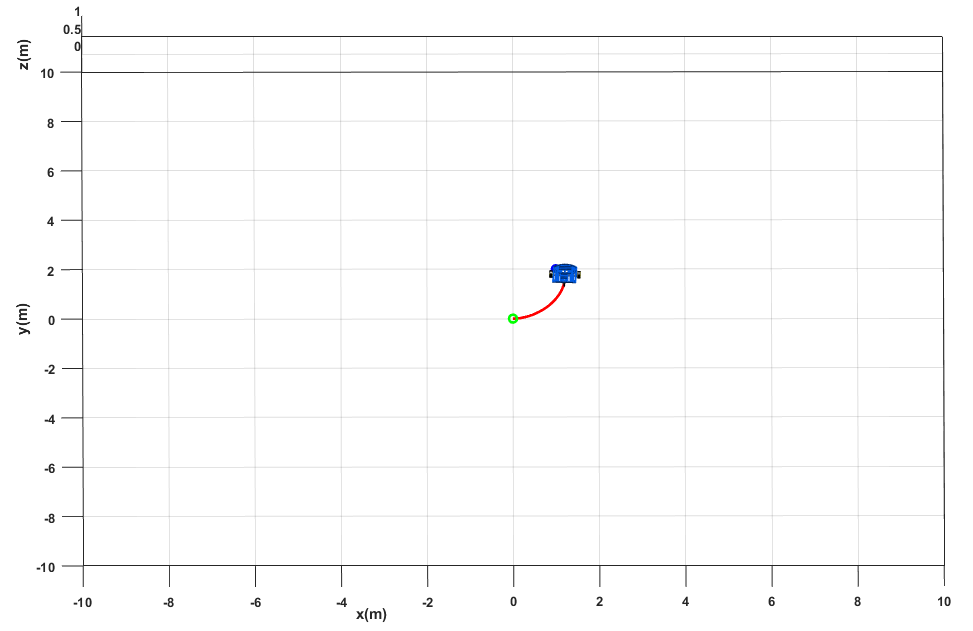
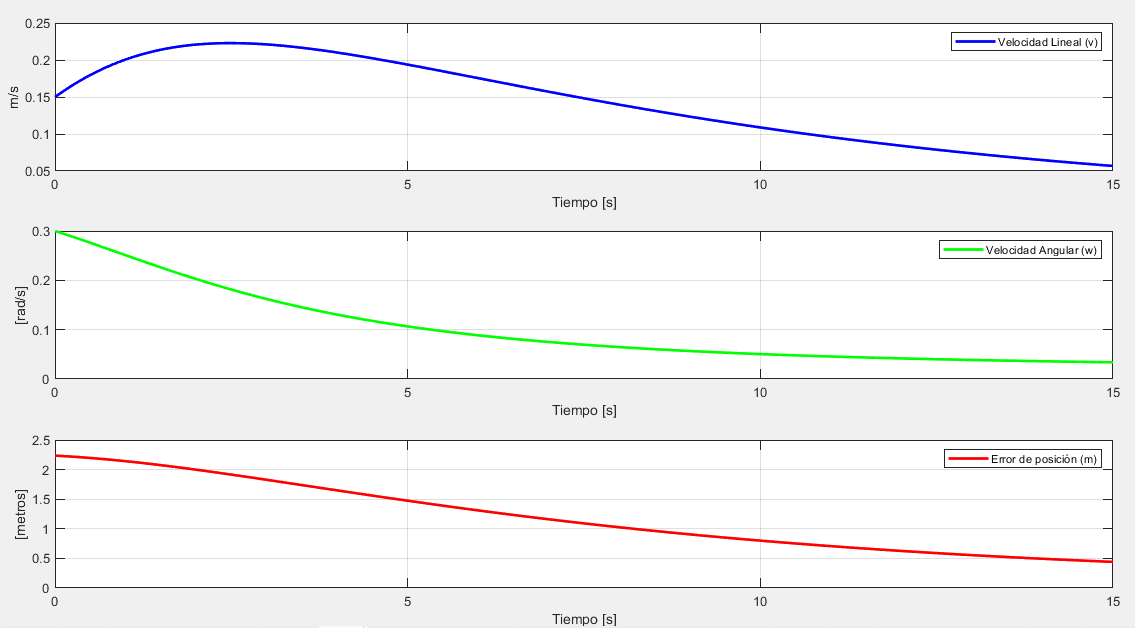
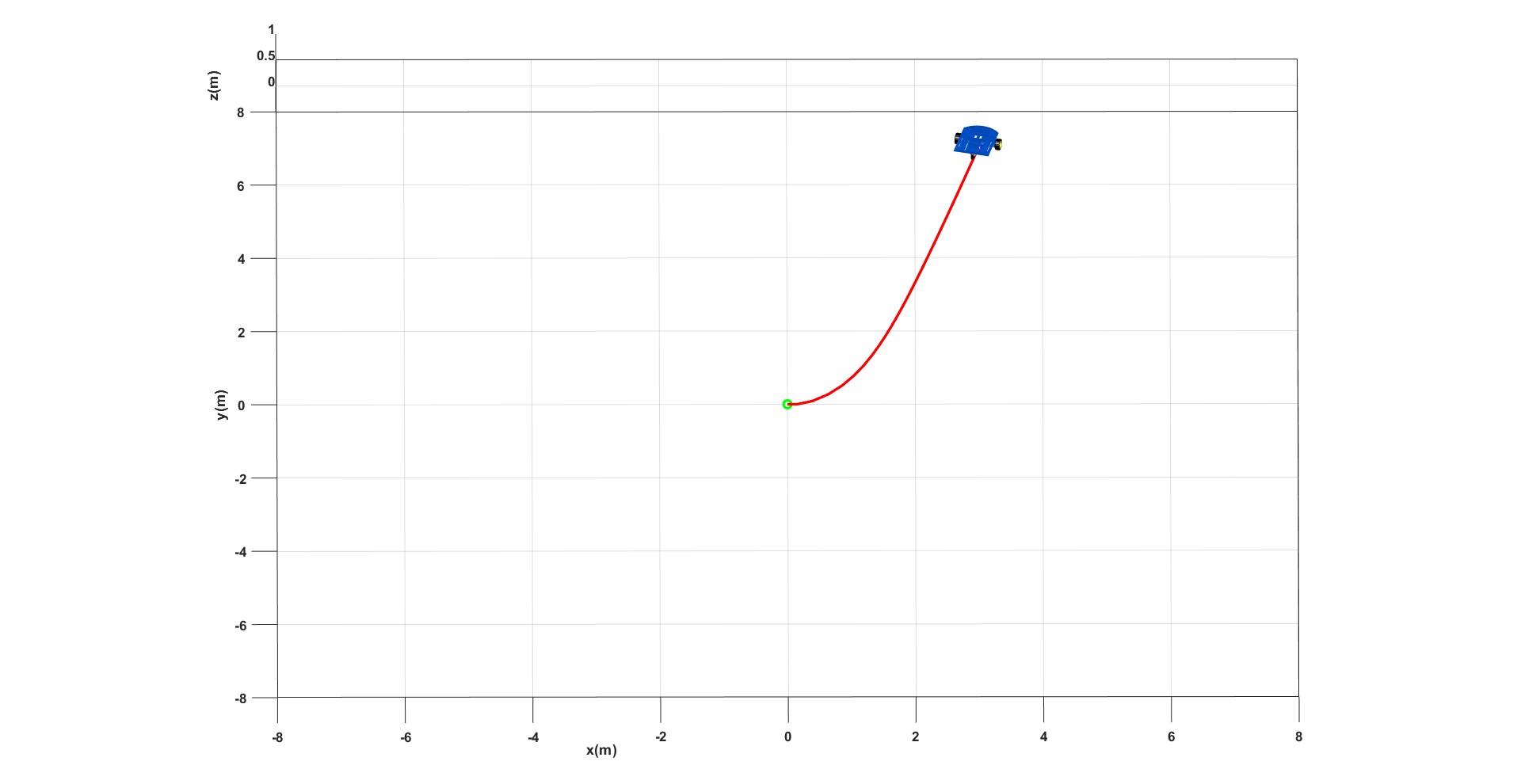
Consideramos los valores de .5, .1 y .15 para ver las diferencias en el recorrido al alterar los valores de ganancia en la simulación

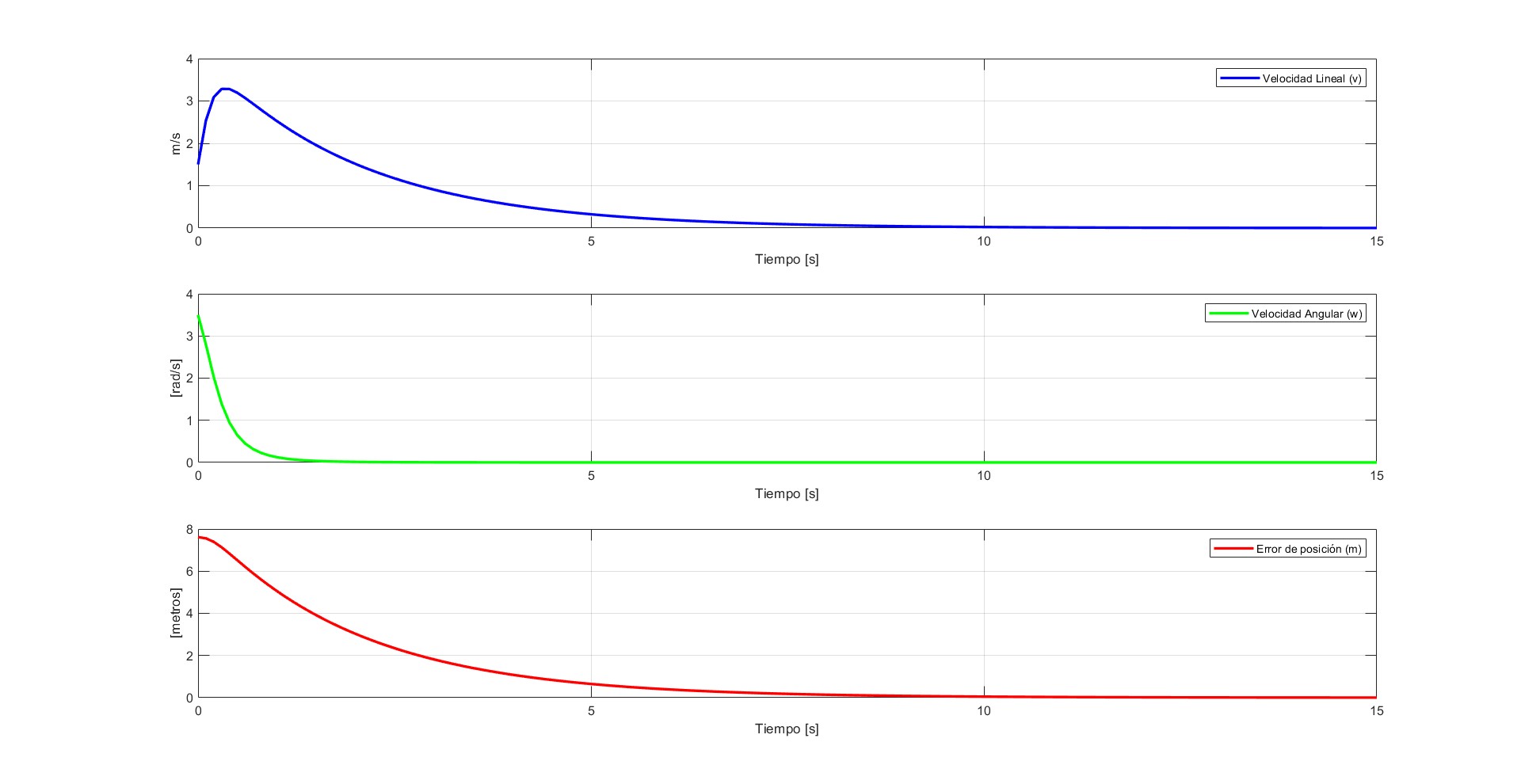
**a) (1, 2) .15**

****

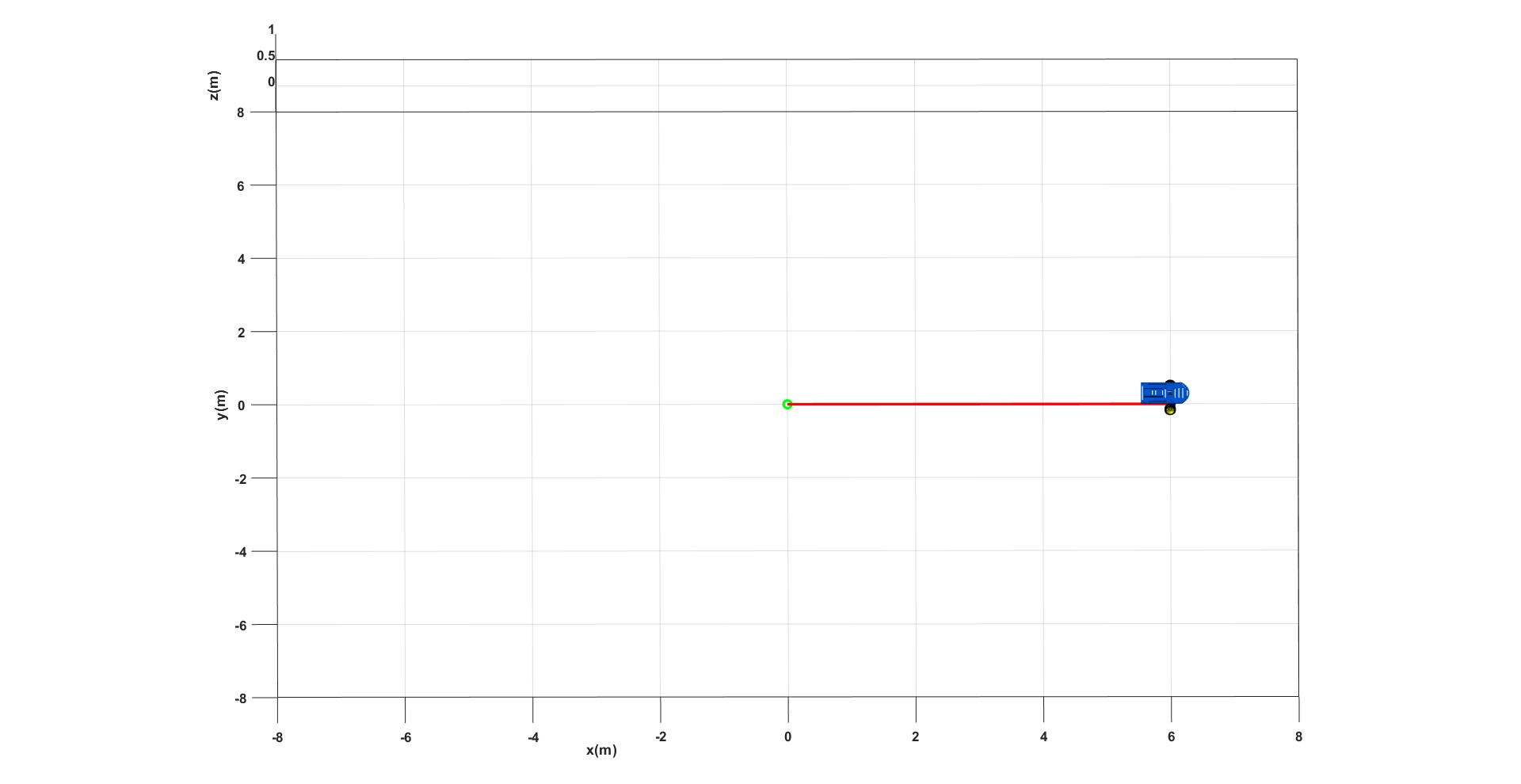
****

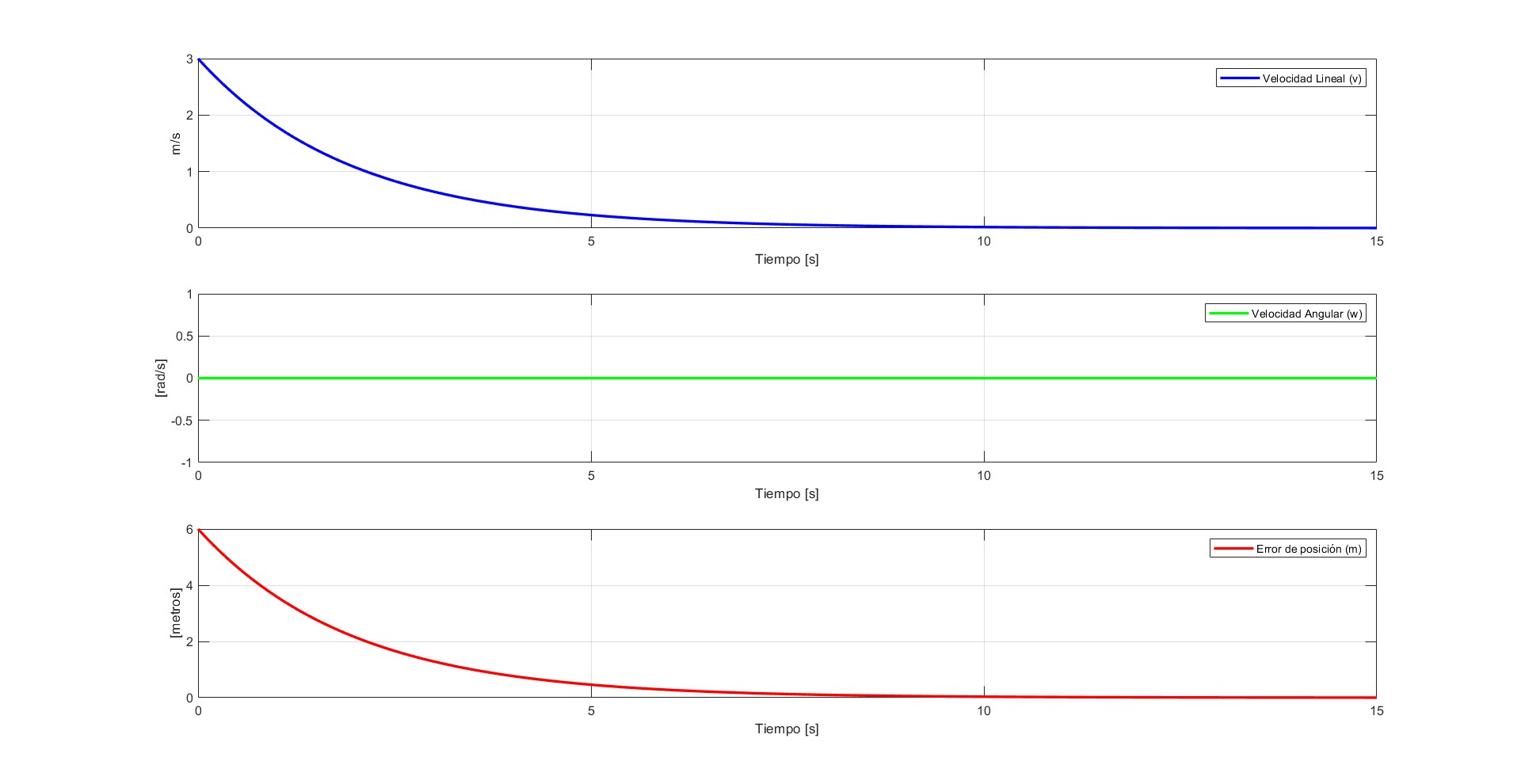
**b) (3, 7) .5**

****

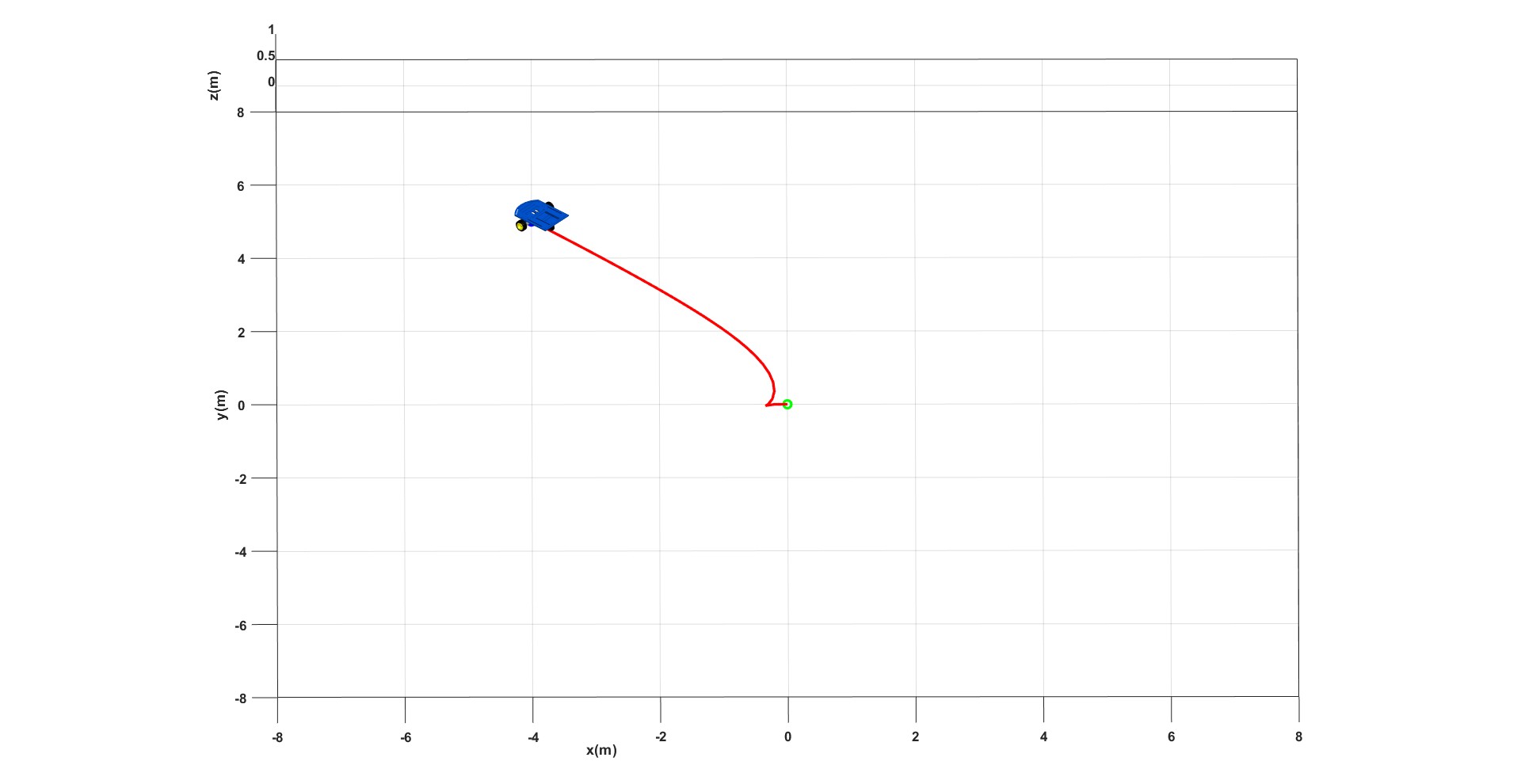
****

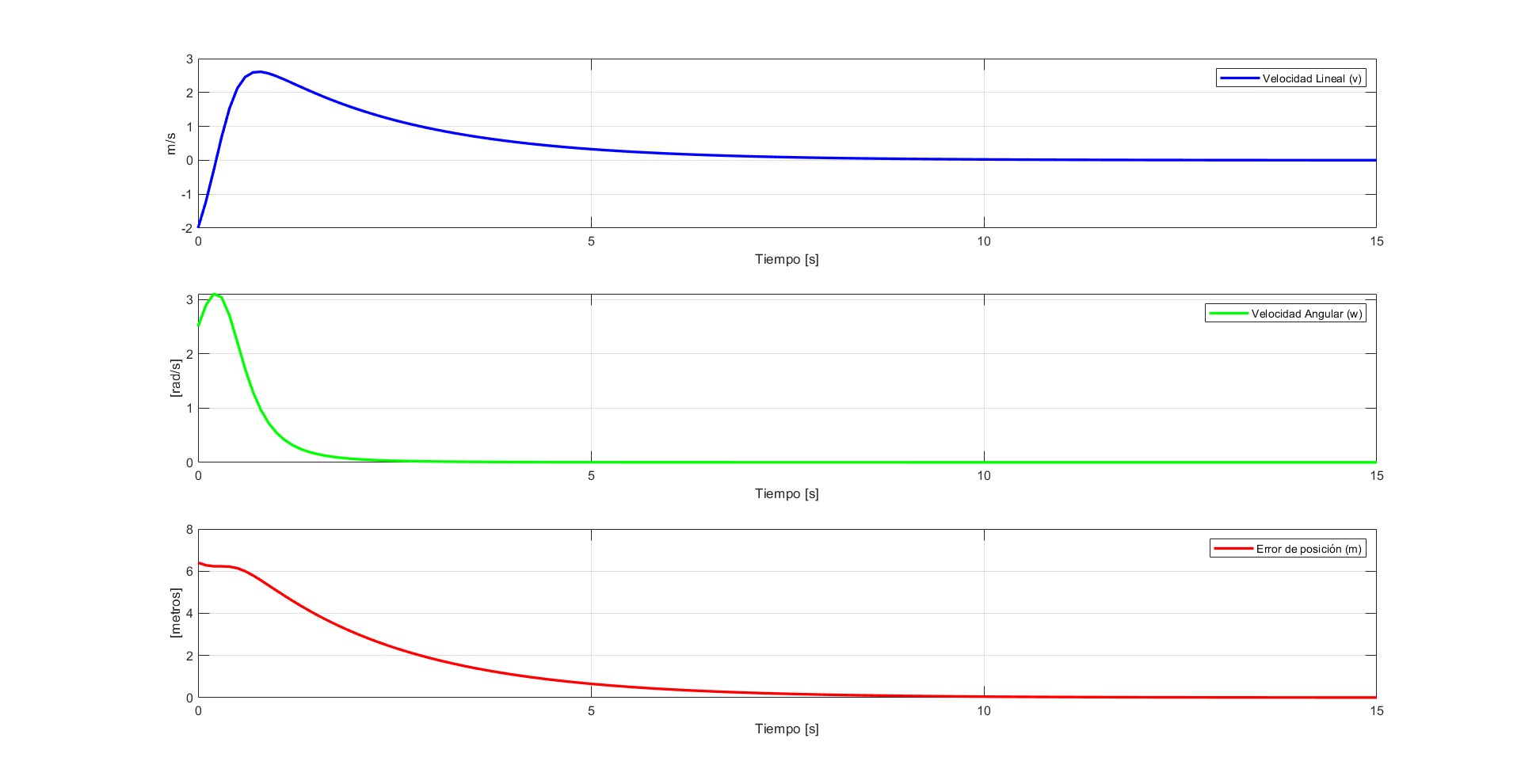
**c) (6, 0) .5**

****

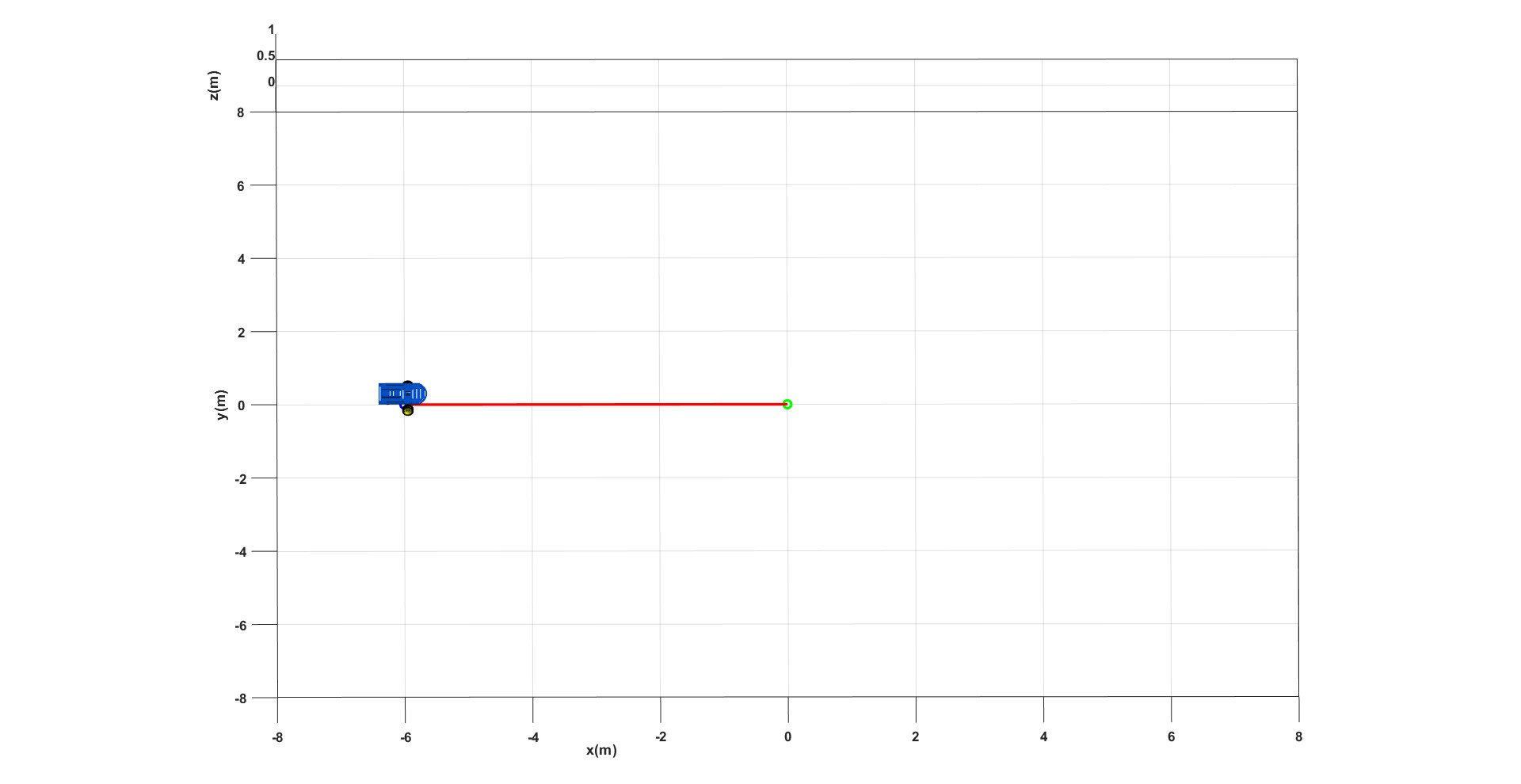
****

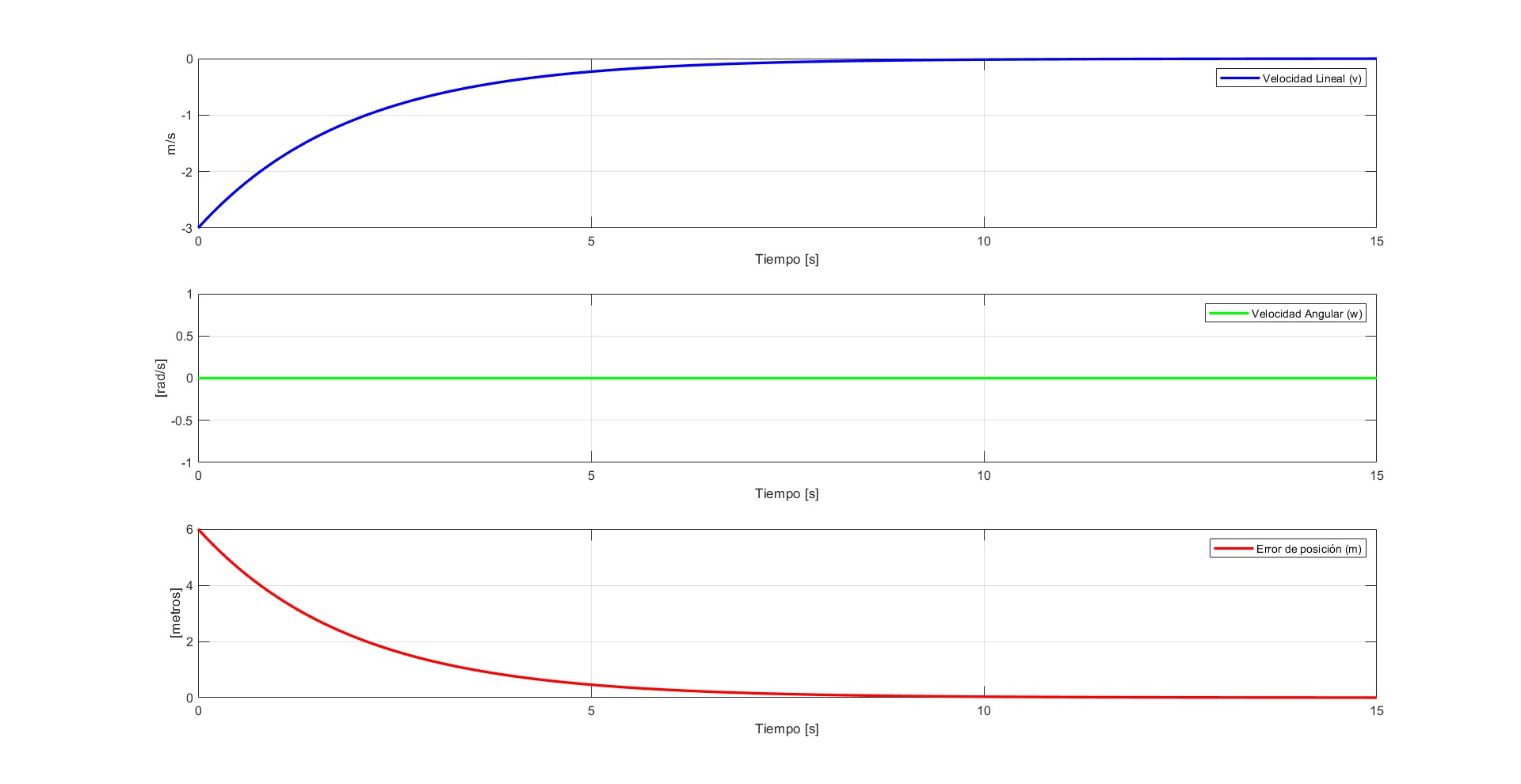
**d) (-4, 5) .5**

****

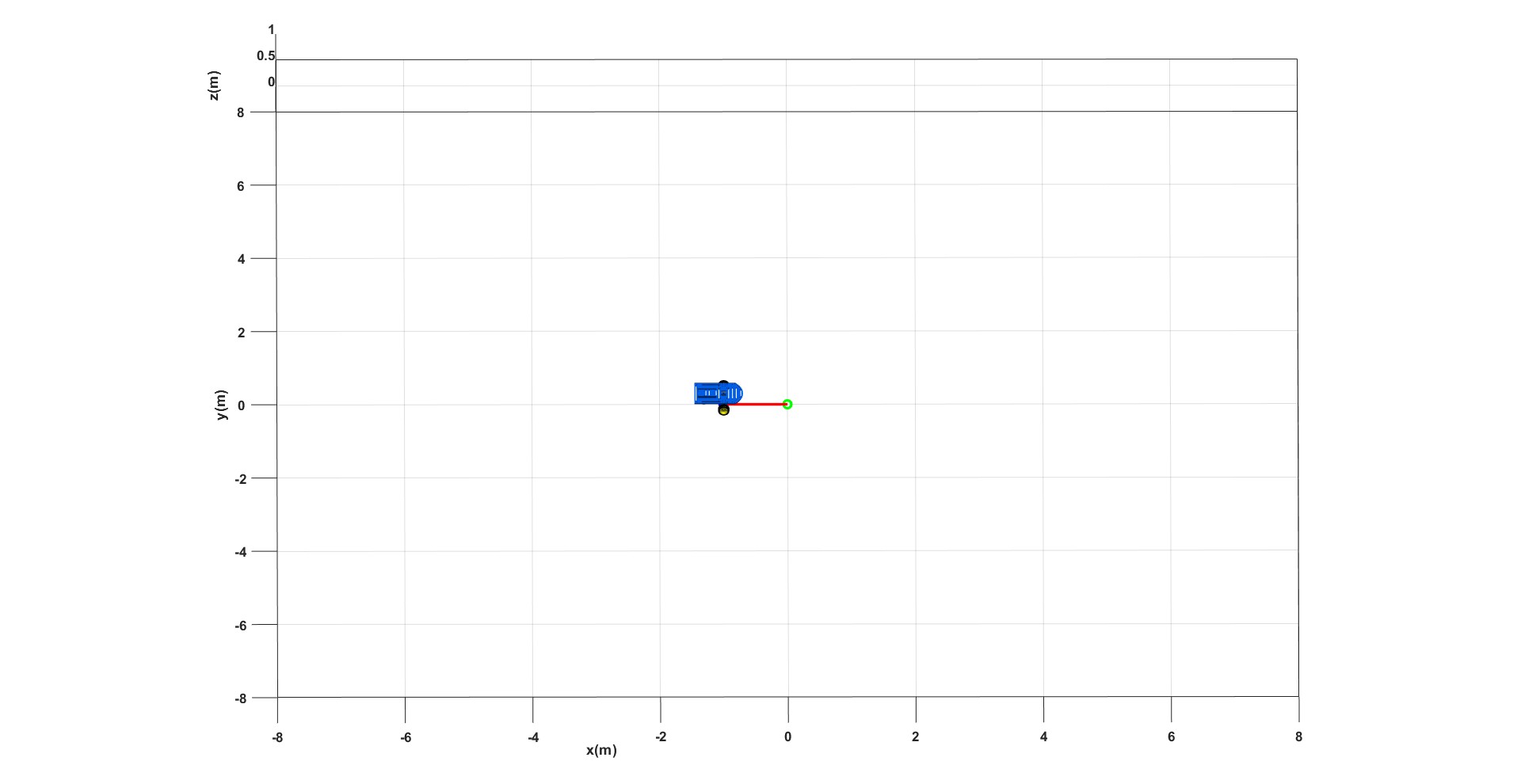
****

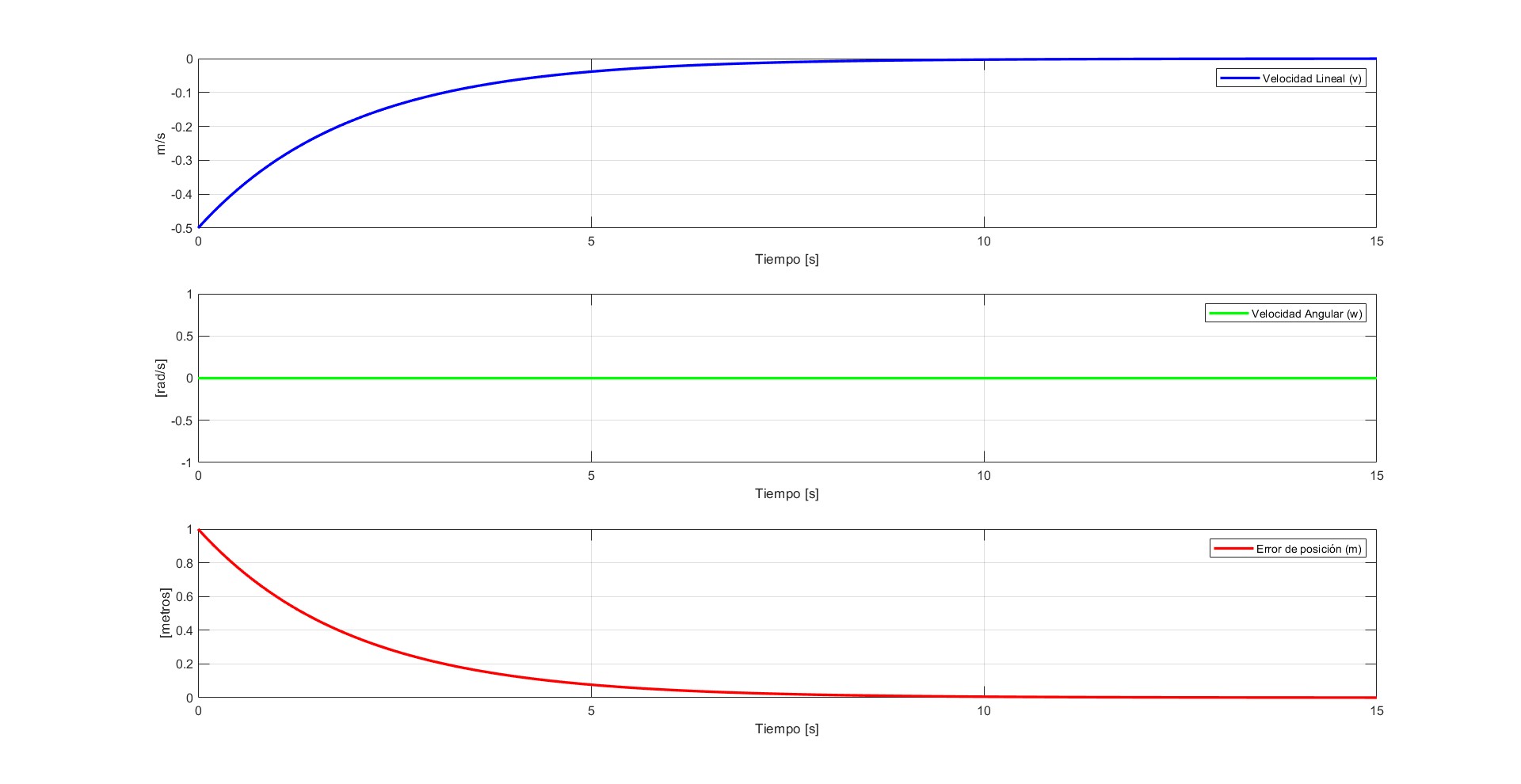
**e) (-6, 0) .5**

****

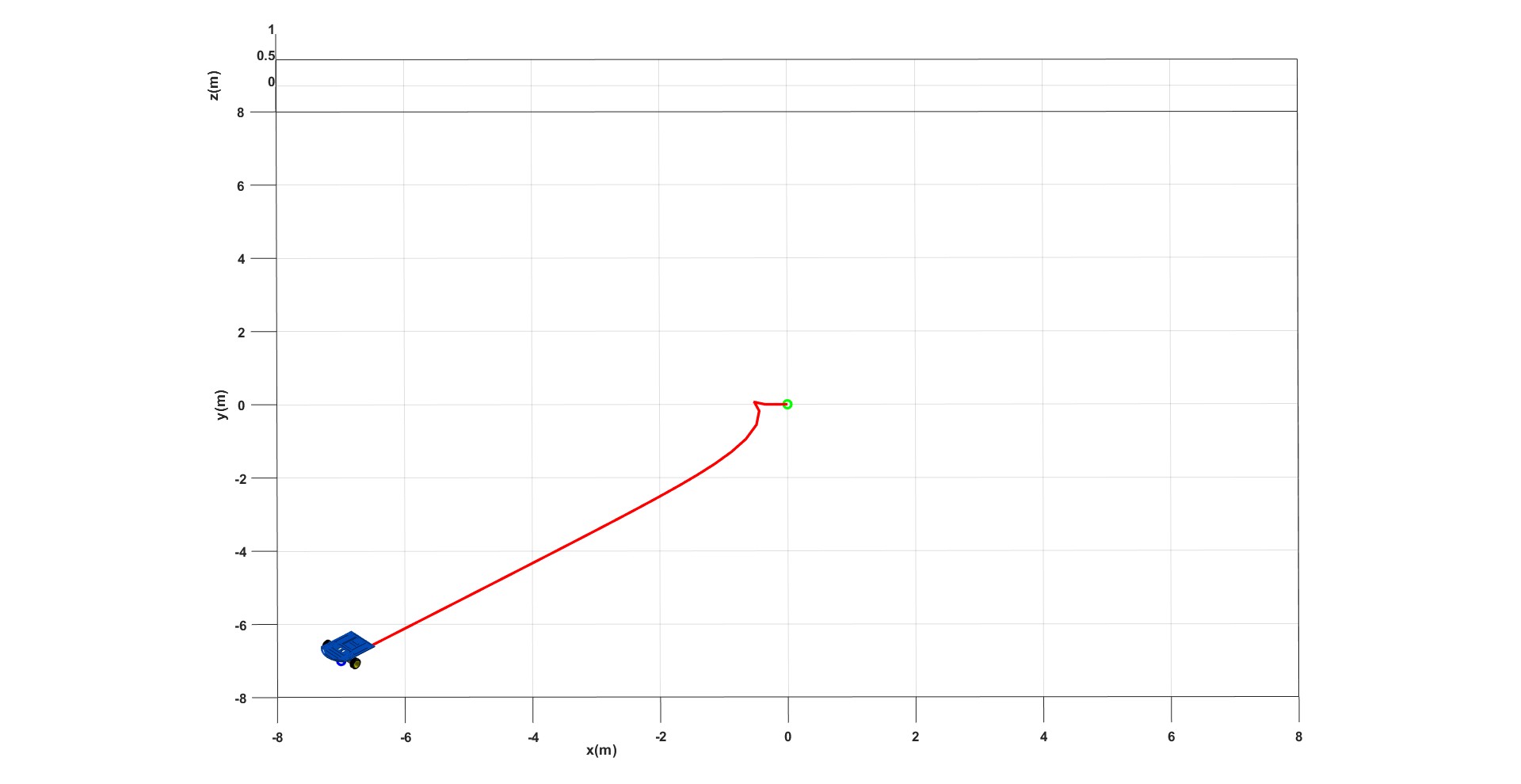
****

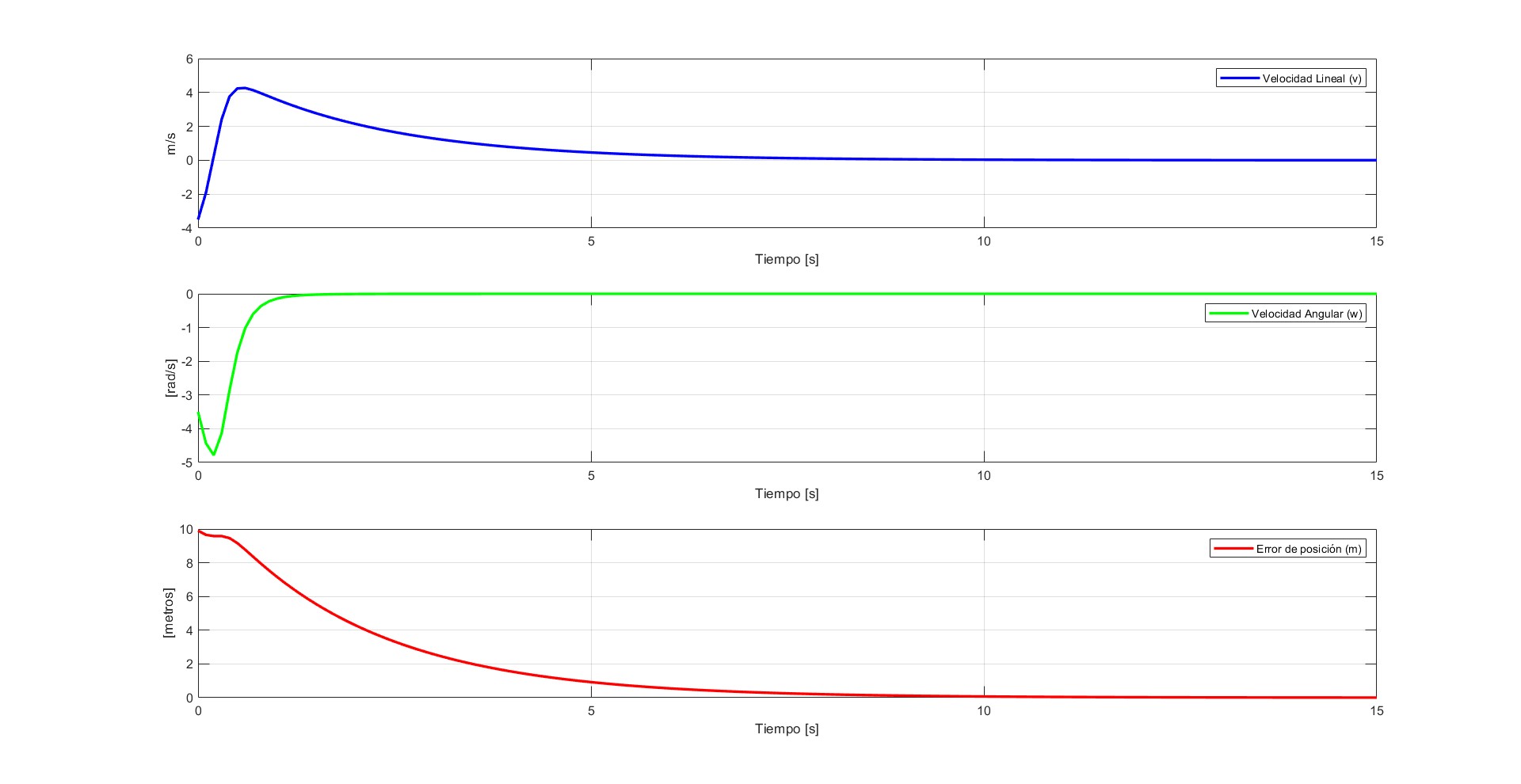
**f) (-1, 0) .5**

****

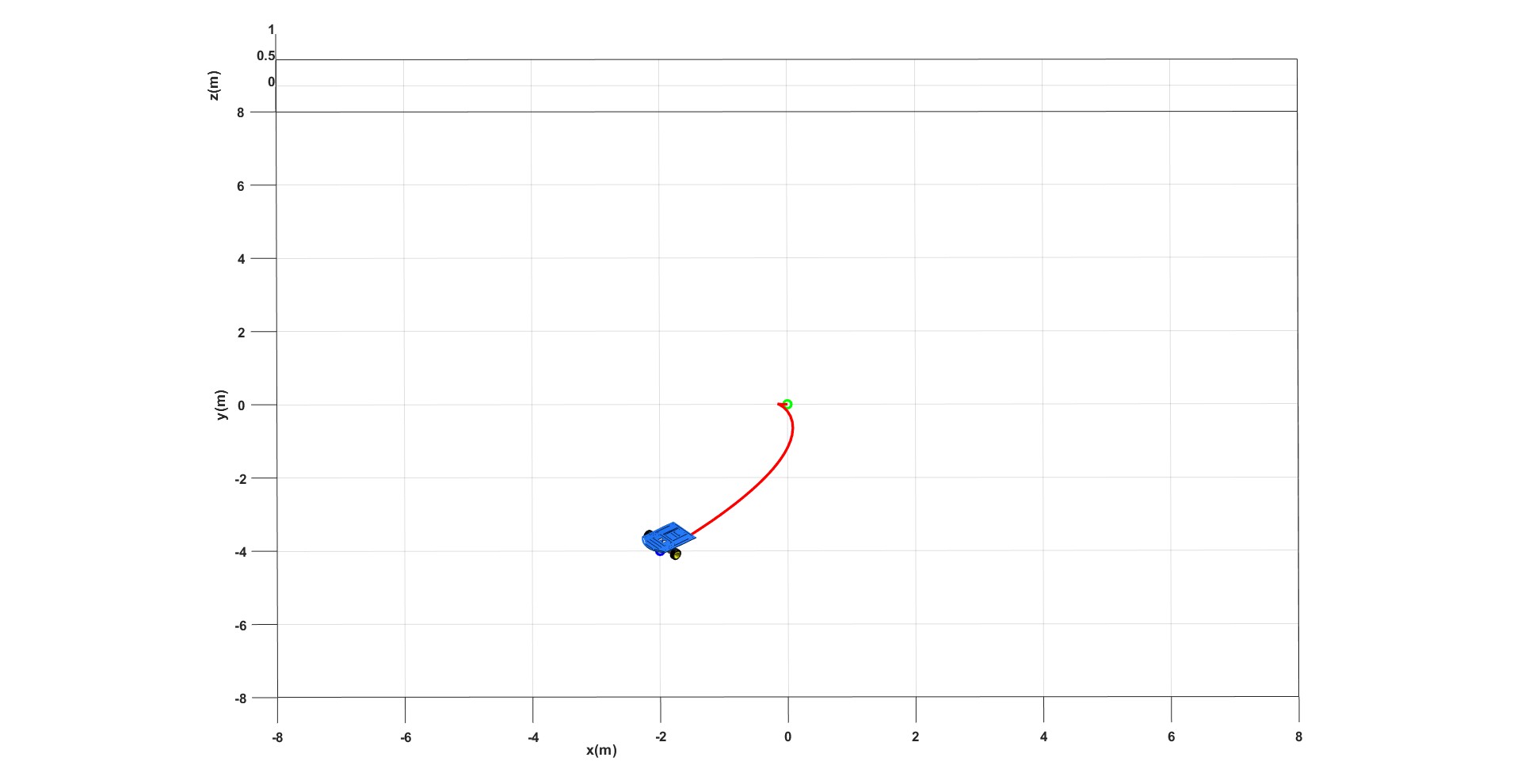
****

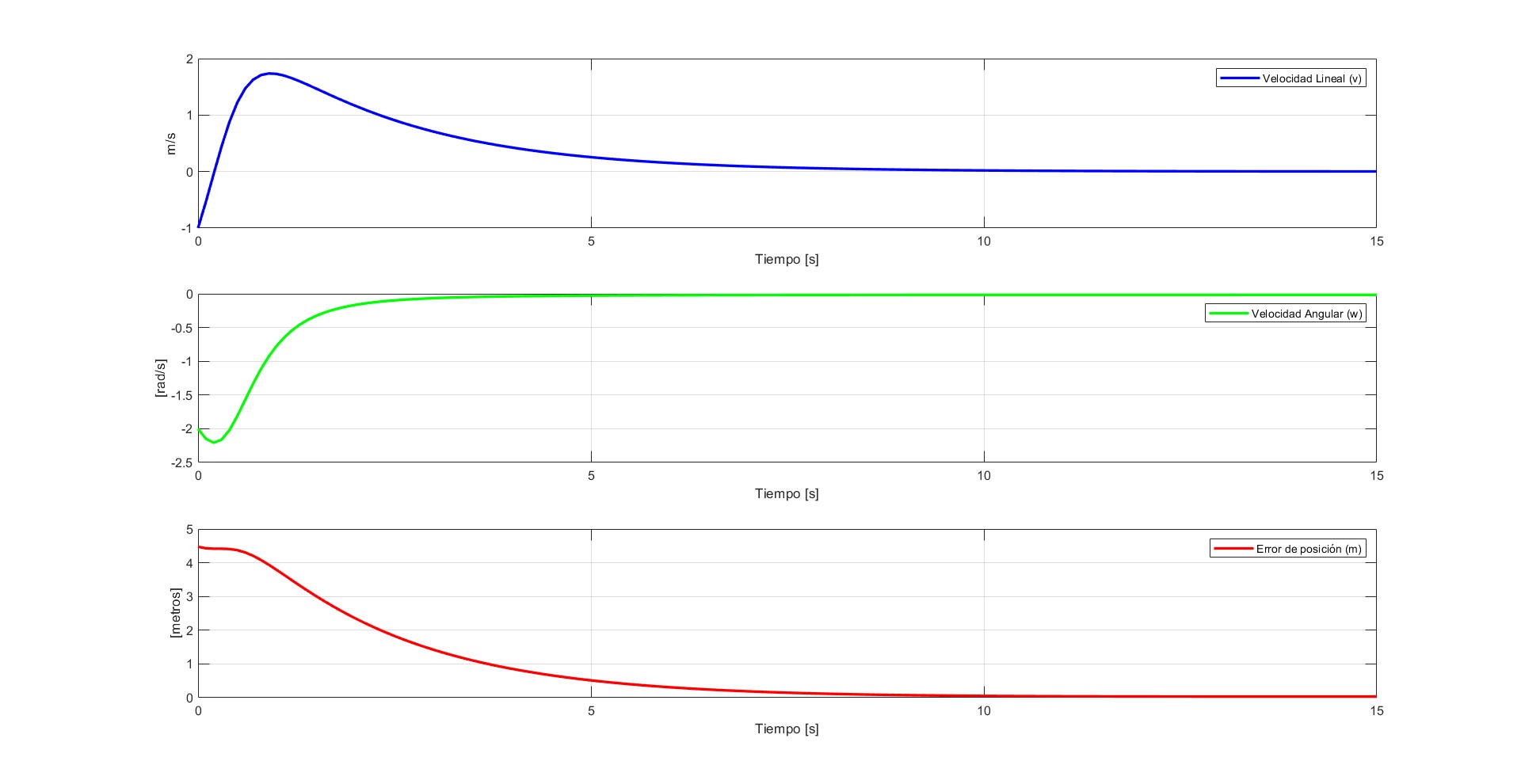
**g) (-7, -7) .5**

****

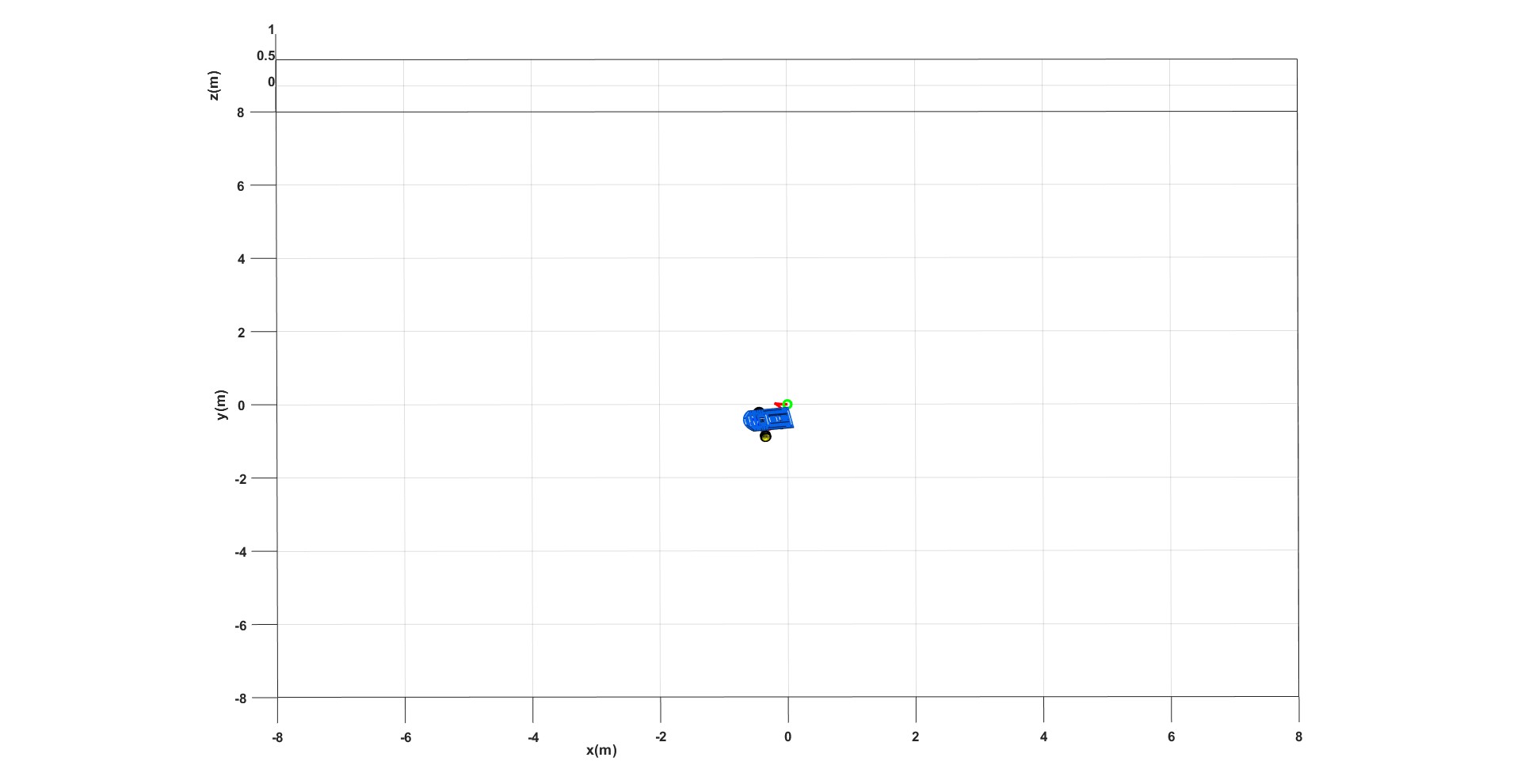
****

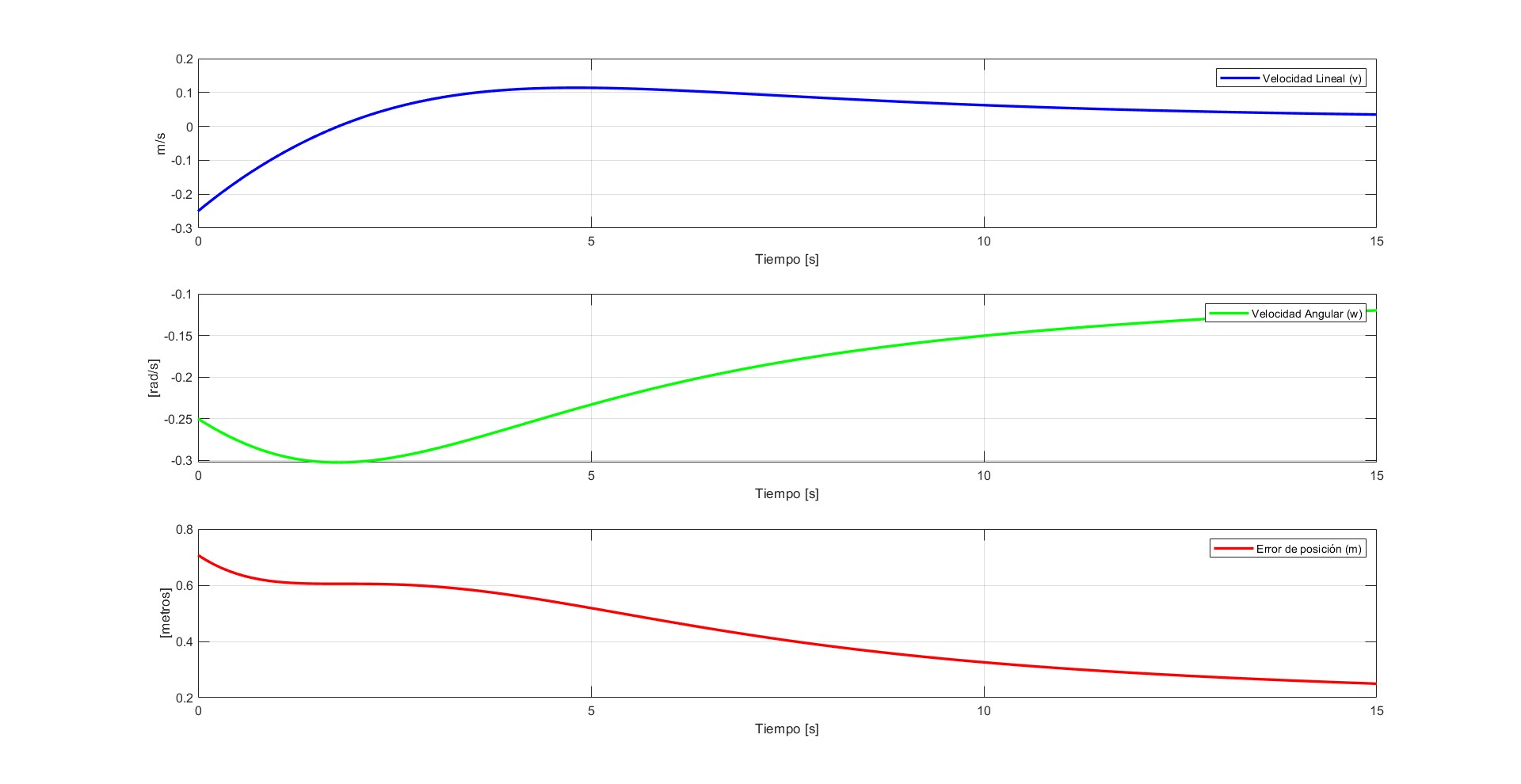
**h) (-2, -4) .5**

****

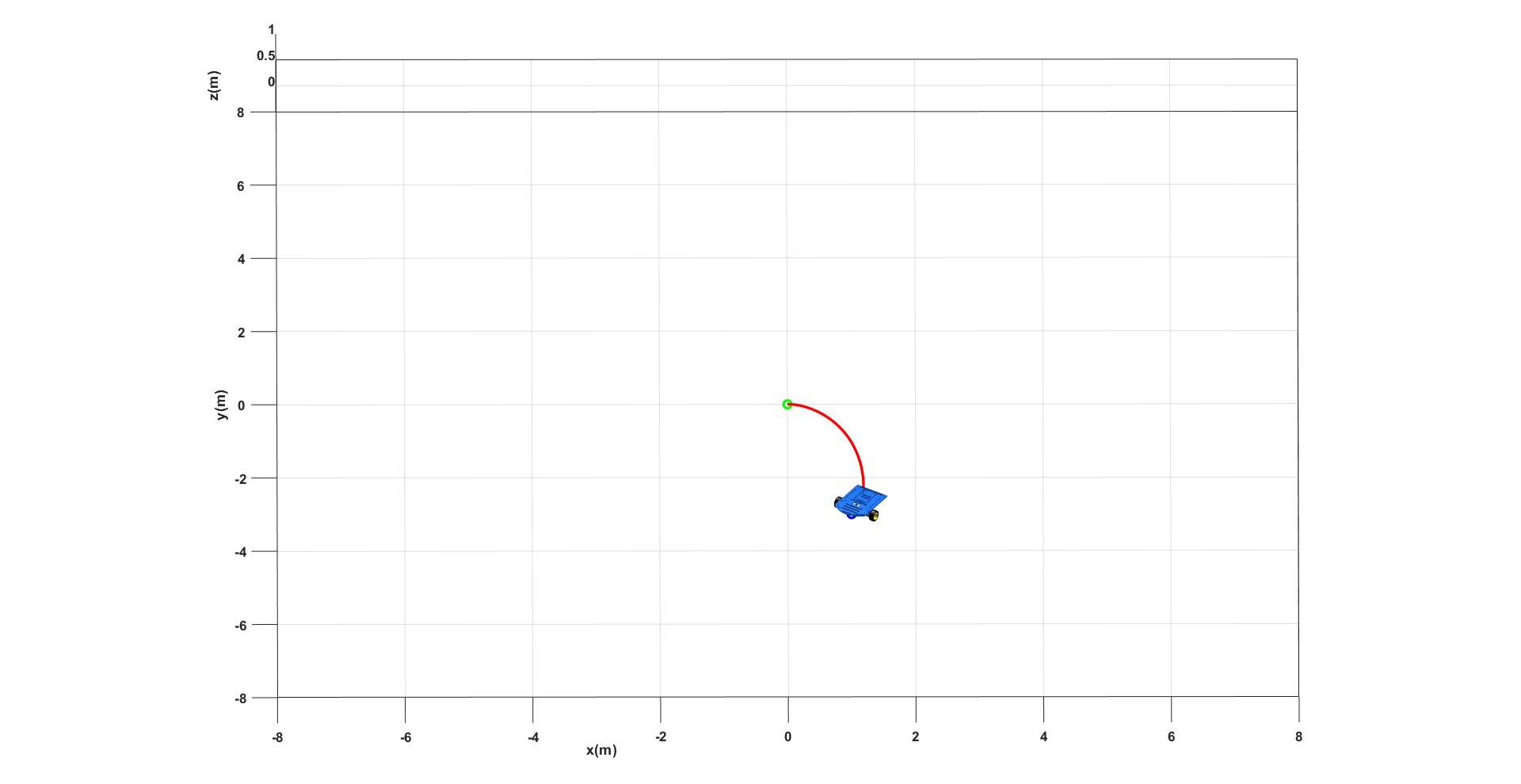
****

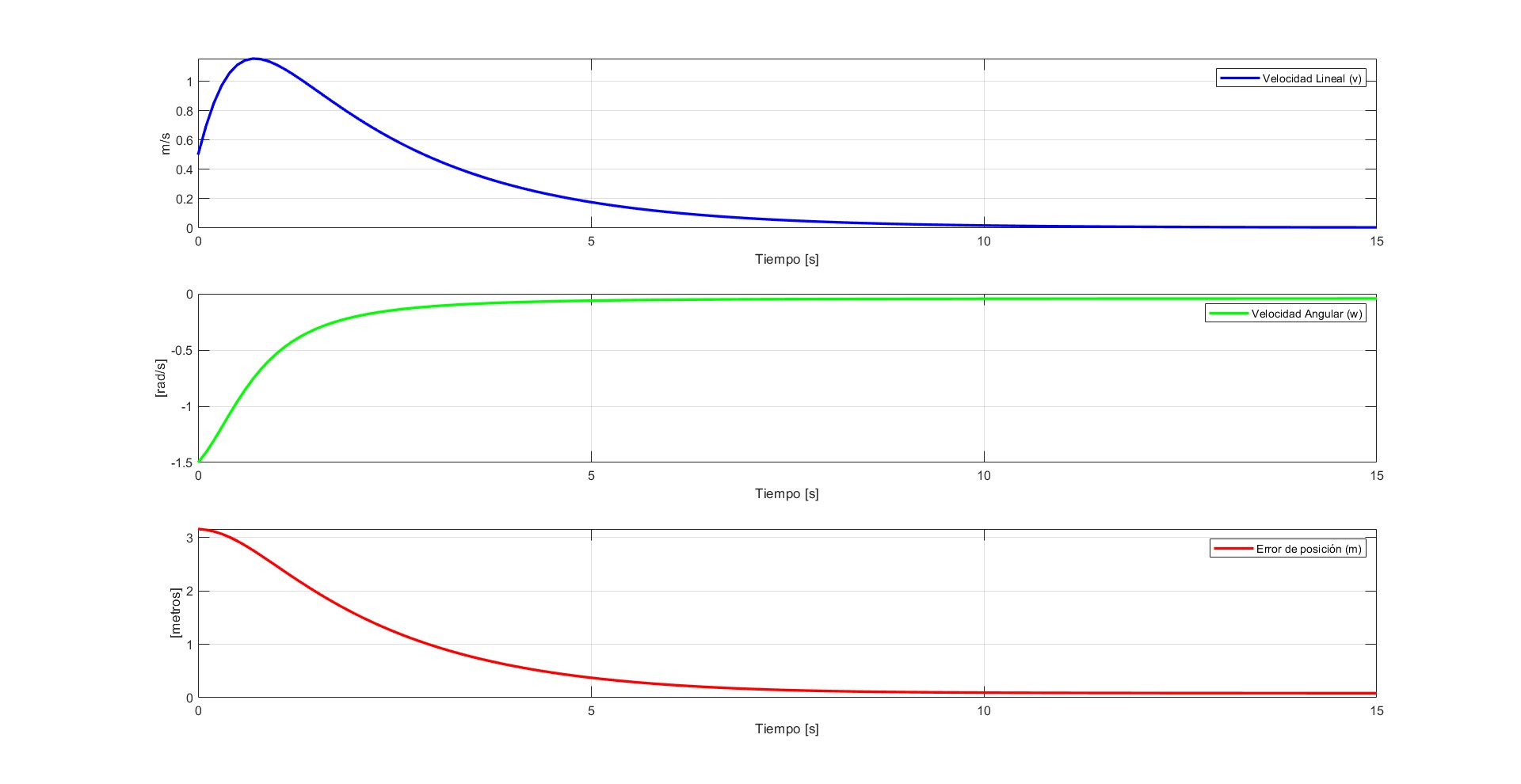
**i) (- 0.5, -0.5) .5**

****

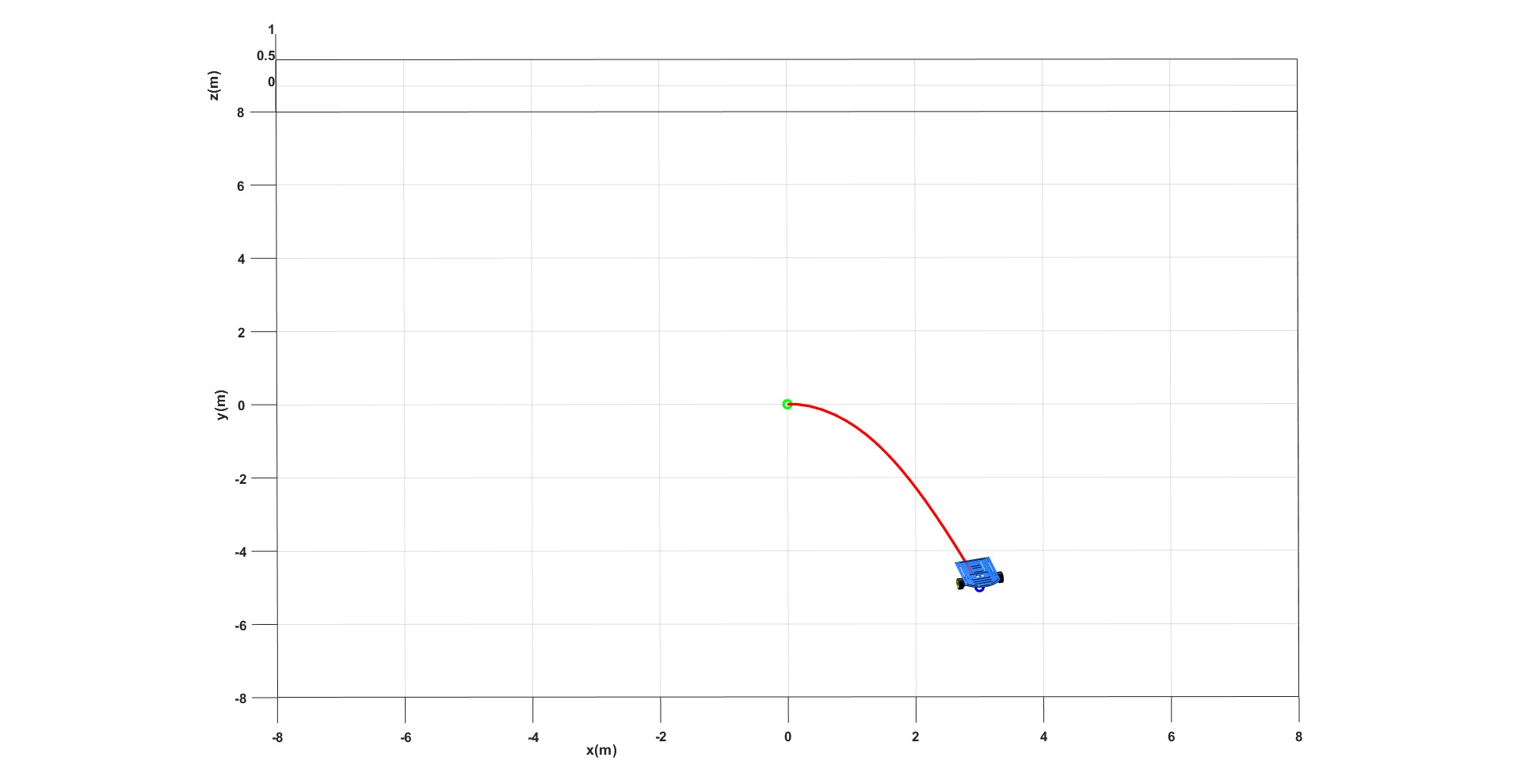
****

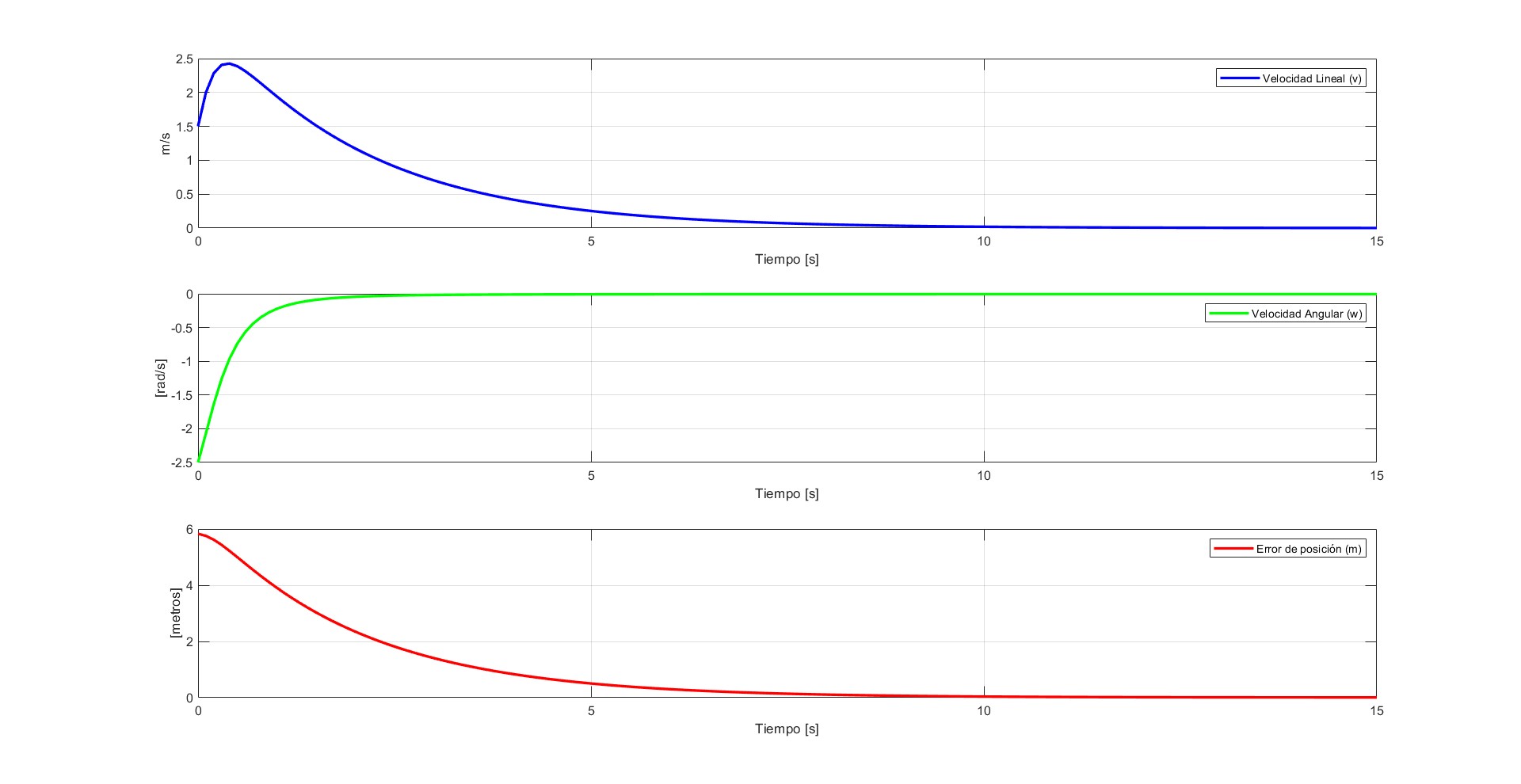
**j) (1, -3) .5**

****

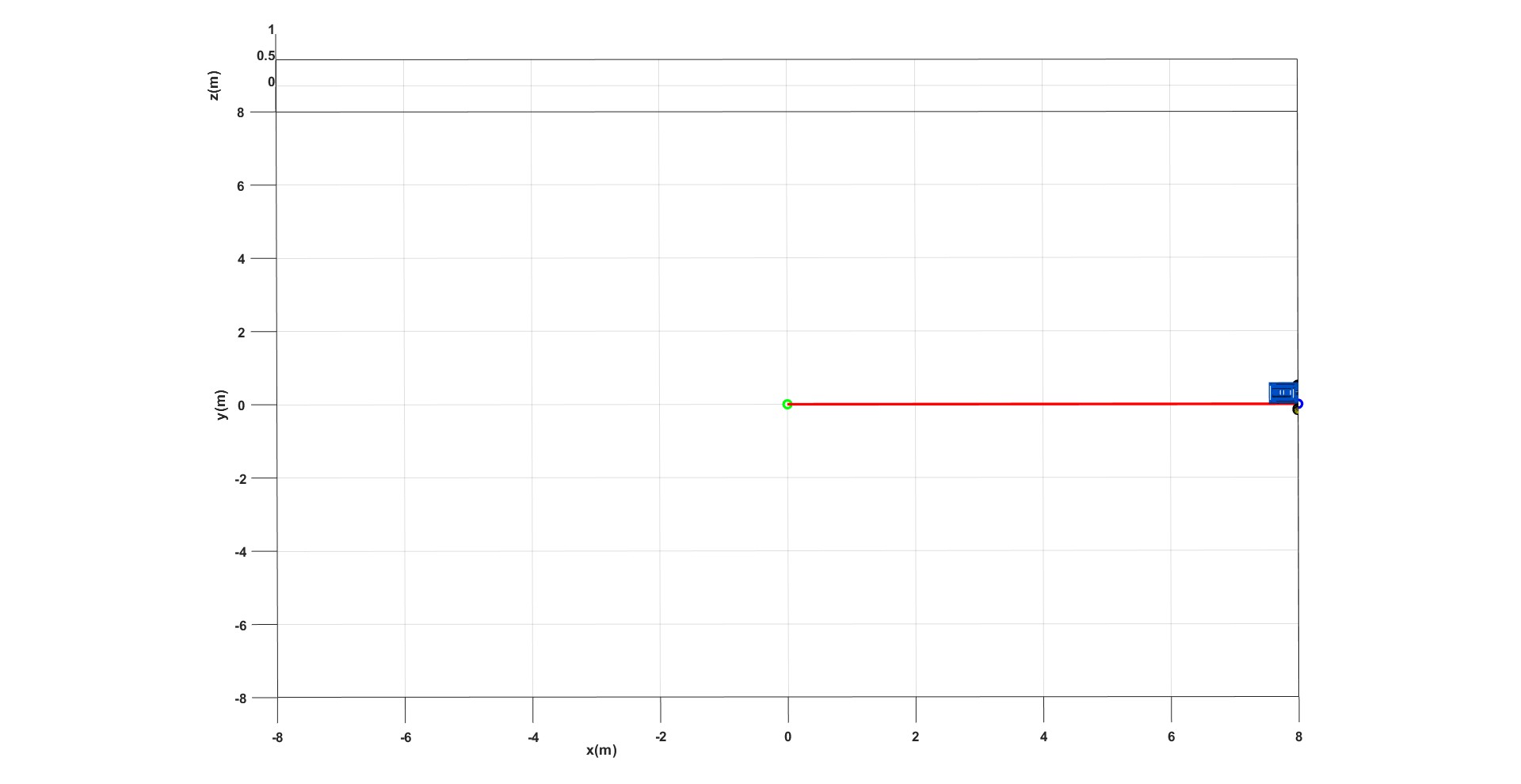
****

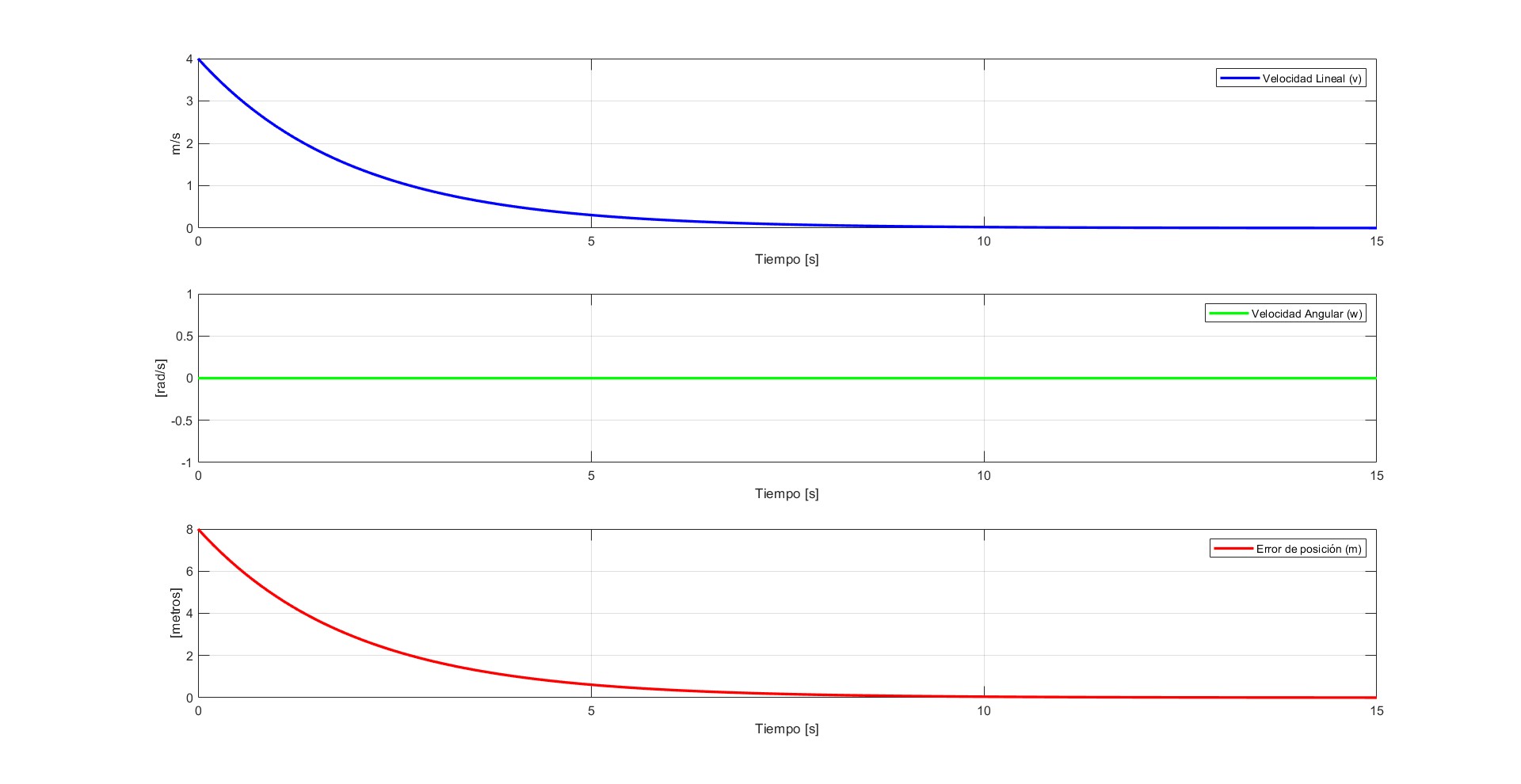
**k) (3, -5) .5**

****

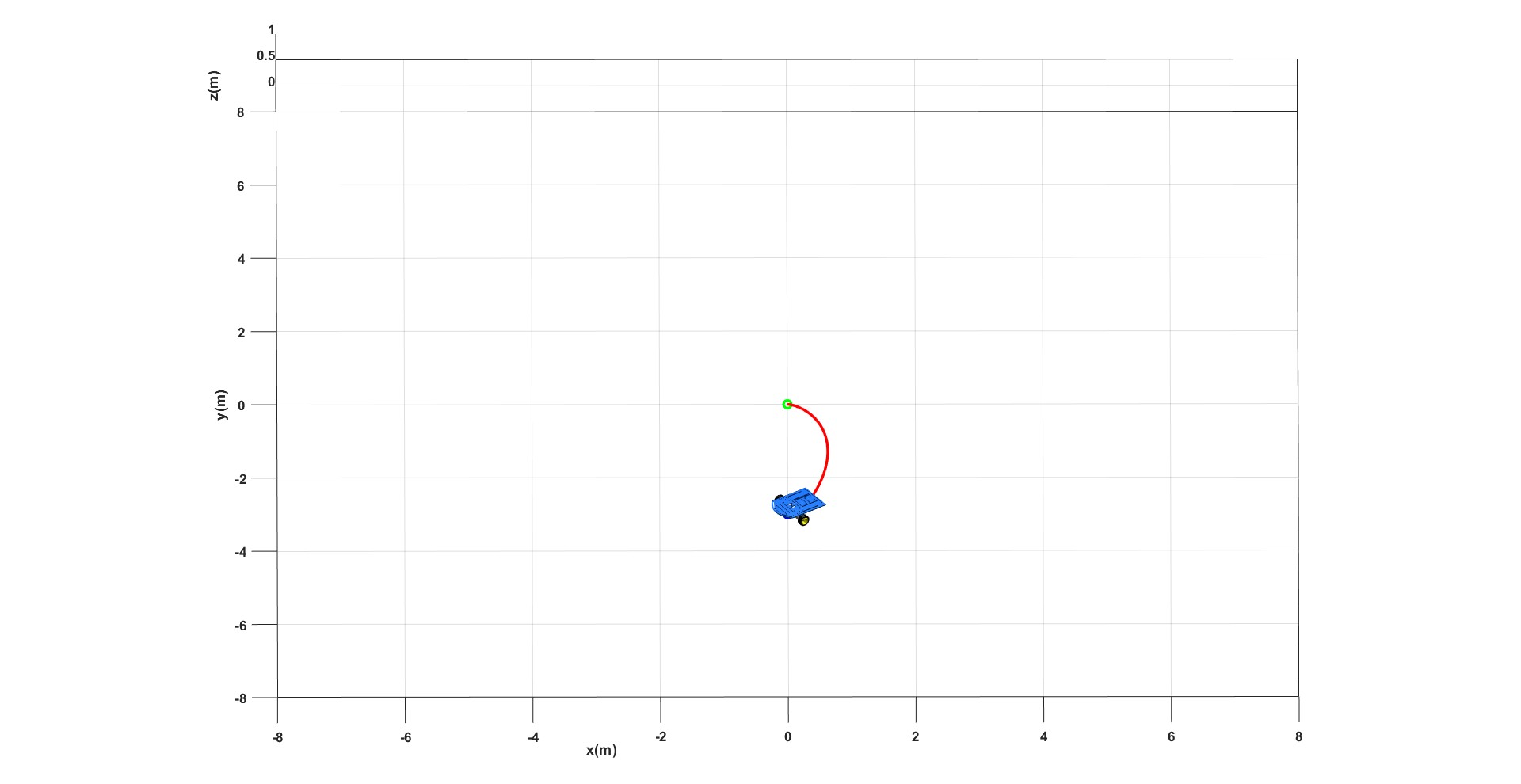
****

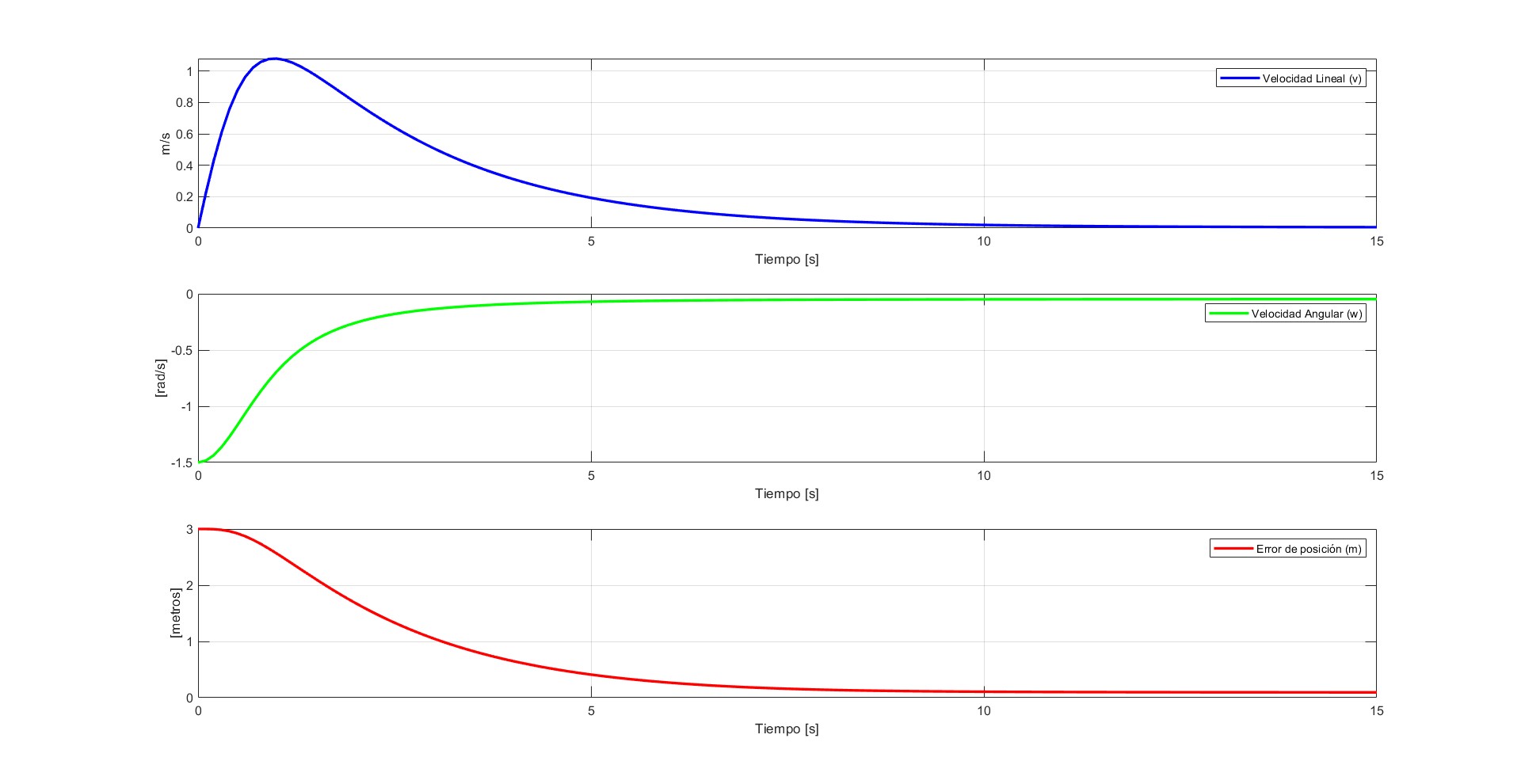
**l) (8, 0) .5**

****

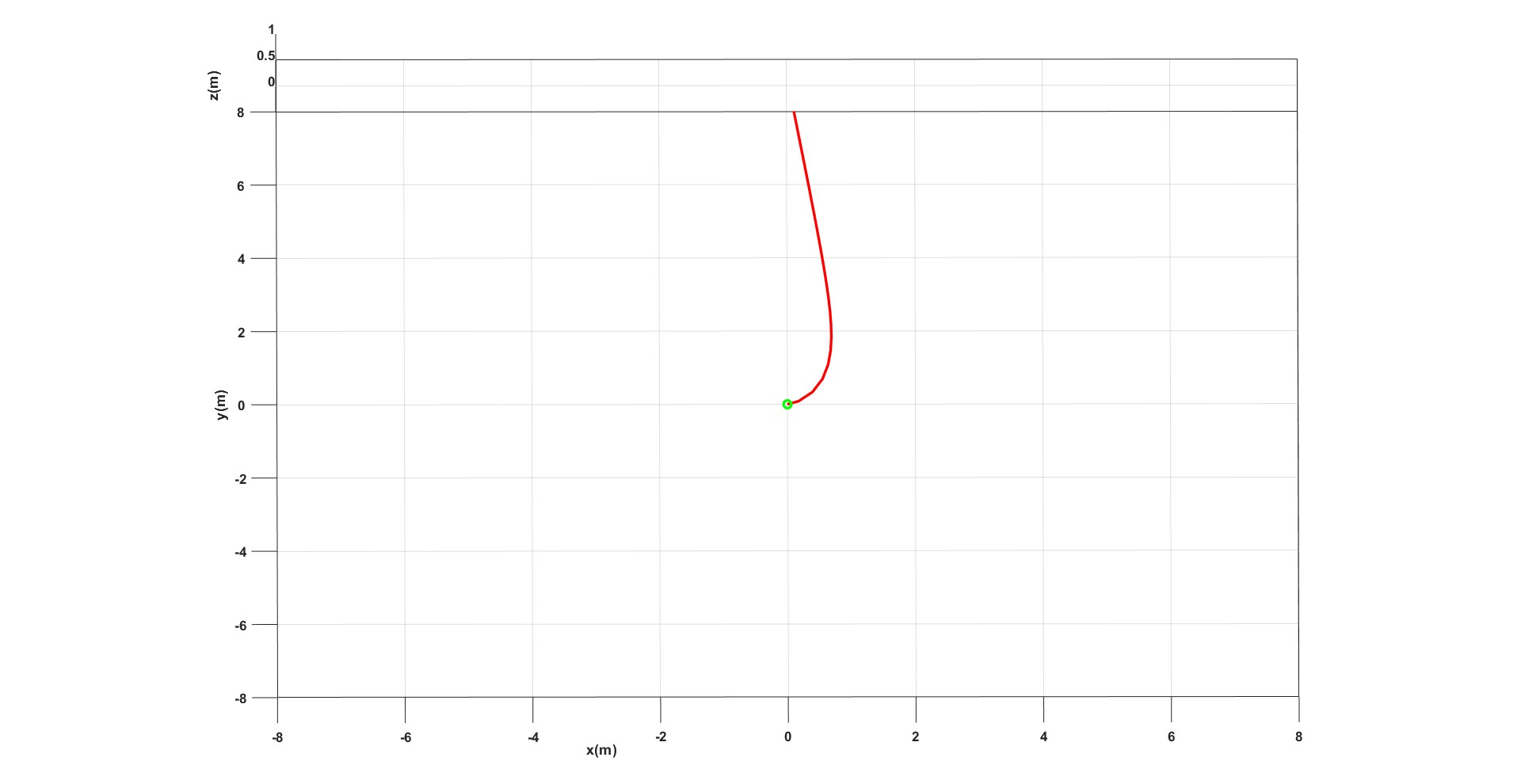
****

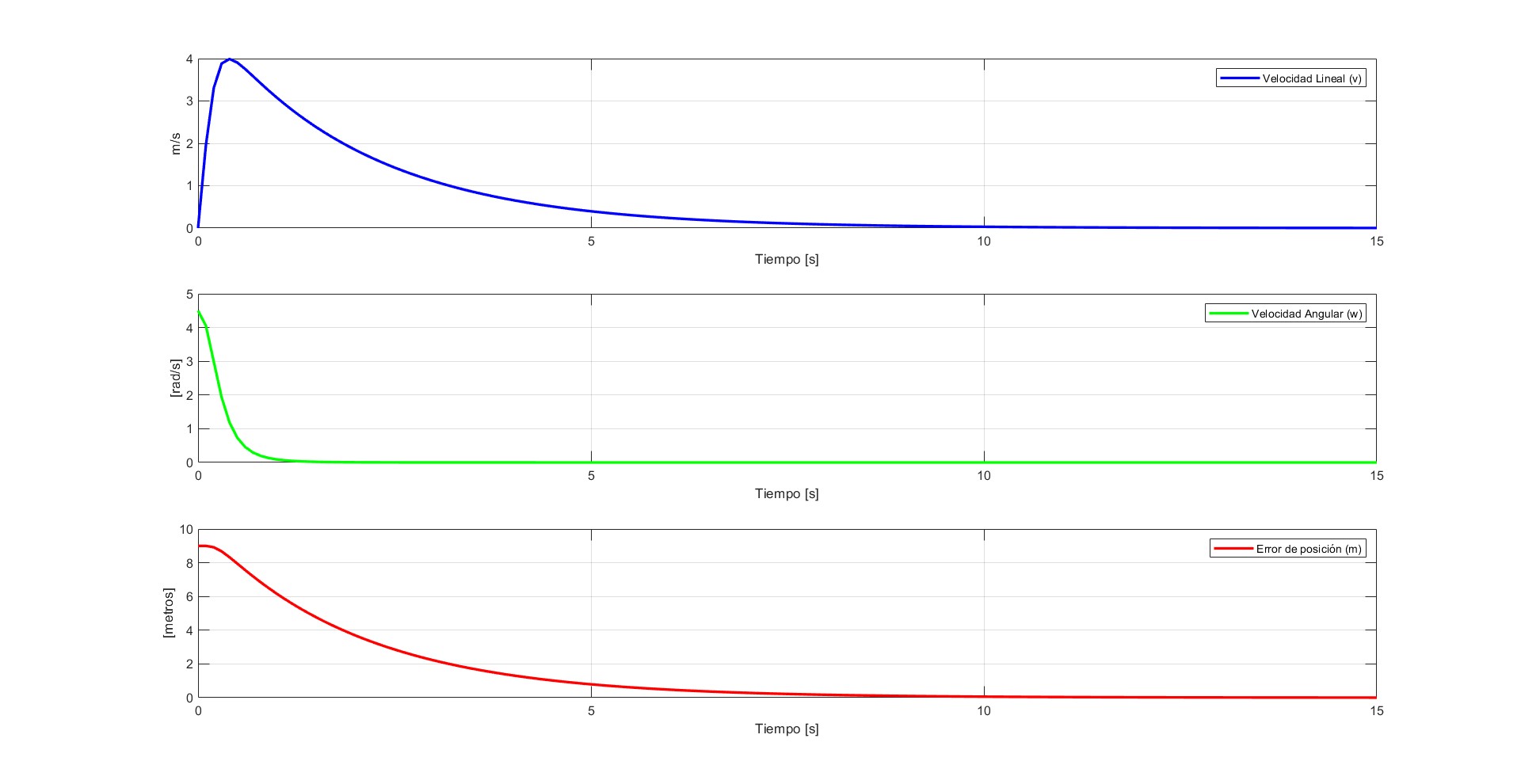
**m) (0, -3) .5**

****

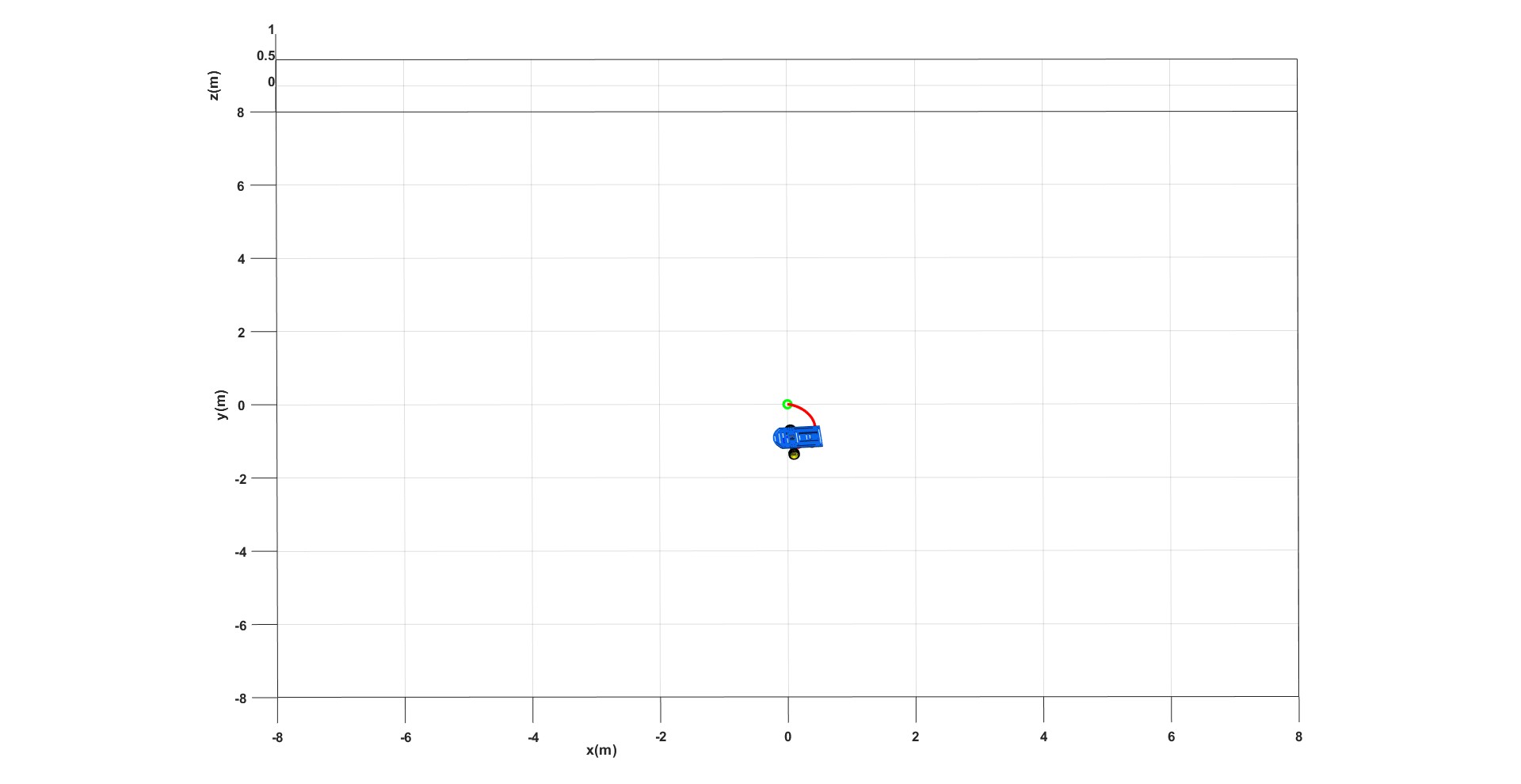
****

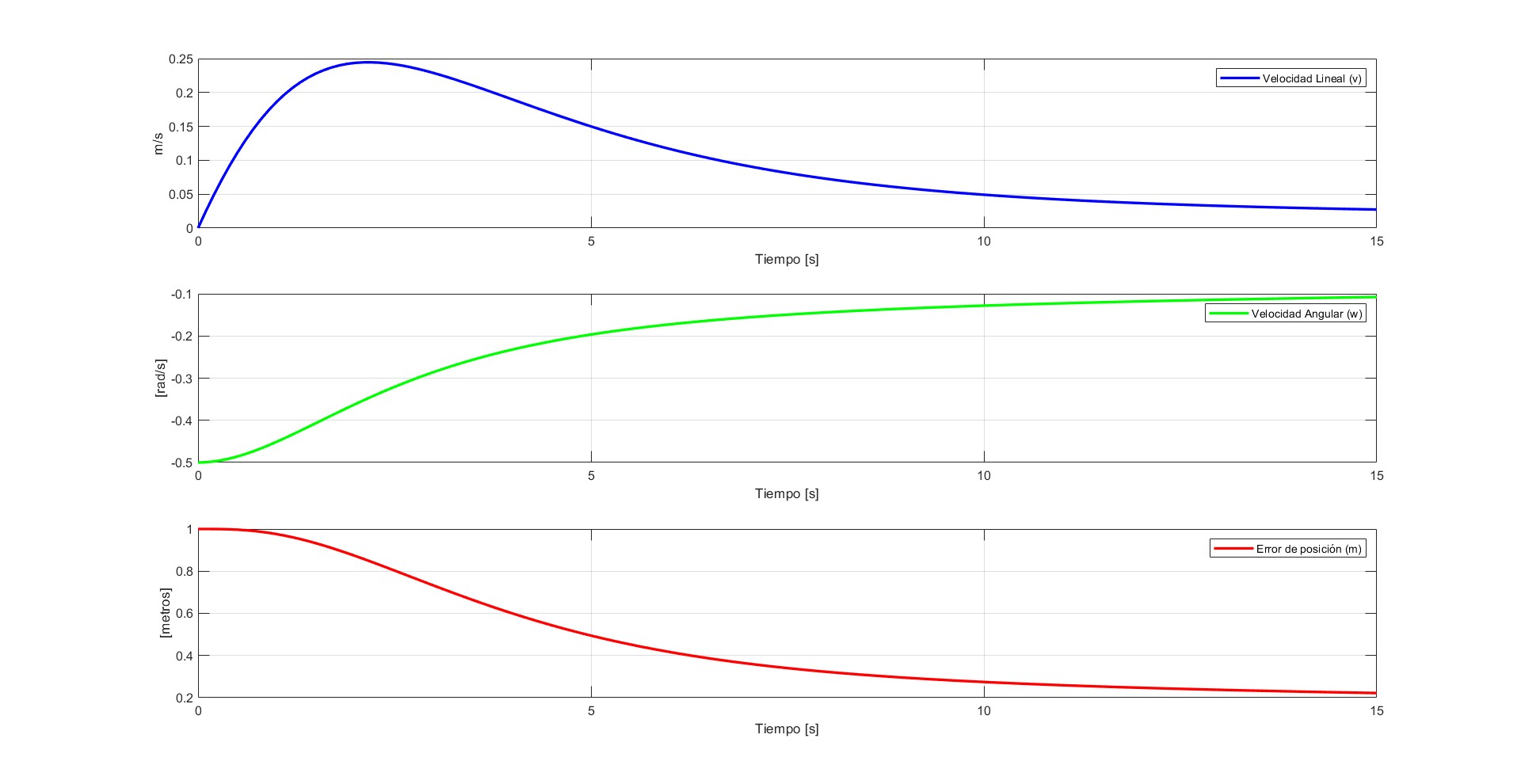
**n) (0, 9) .5**

****

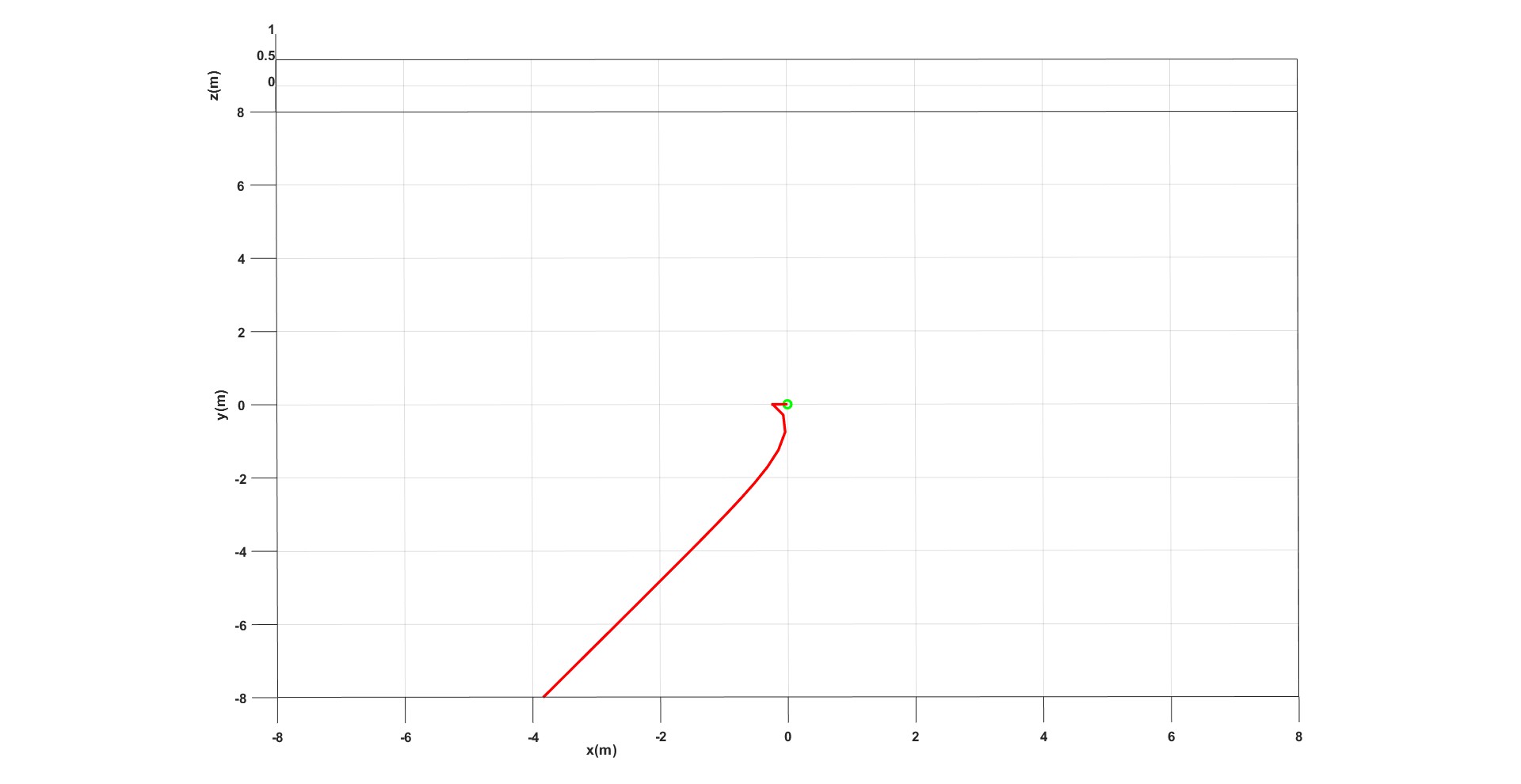
****

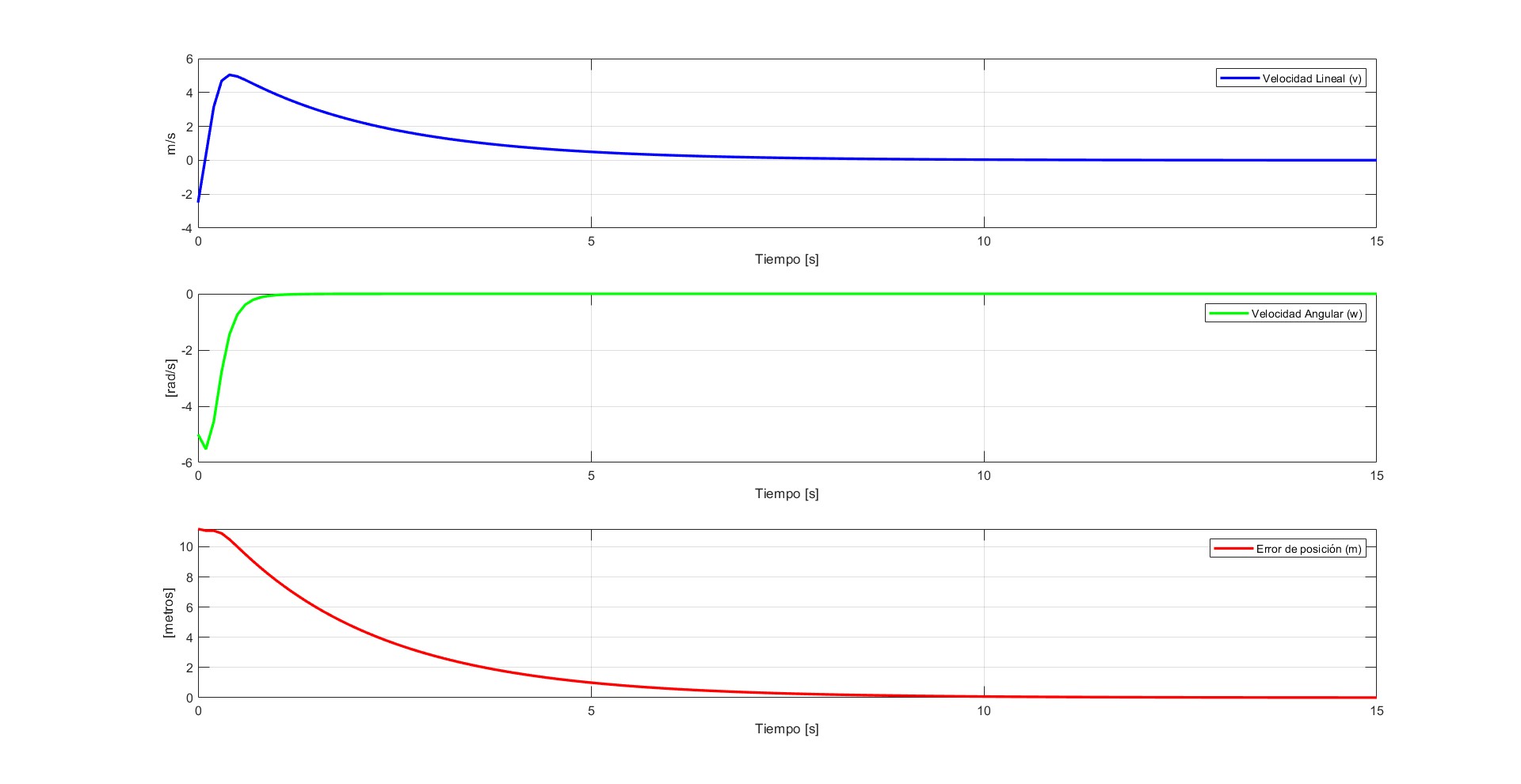
**ñ) (0, -1) .5**

****

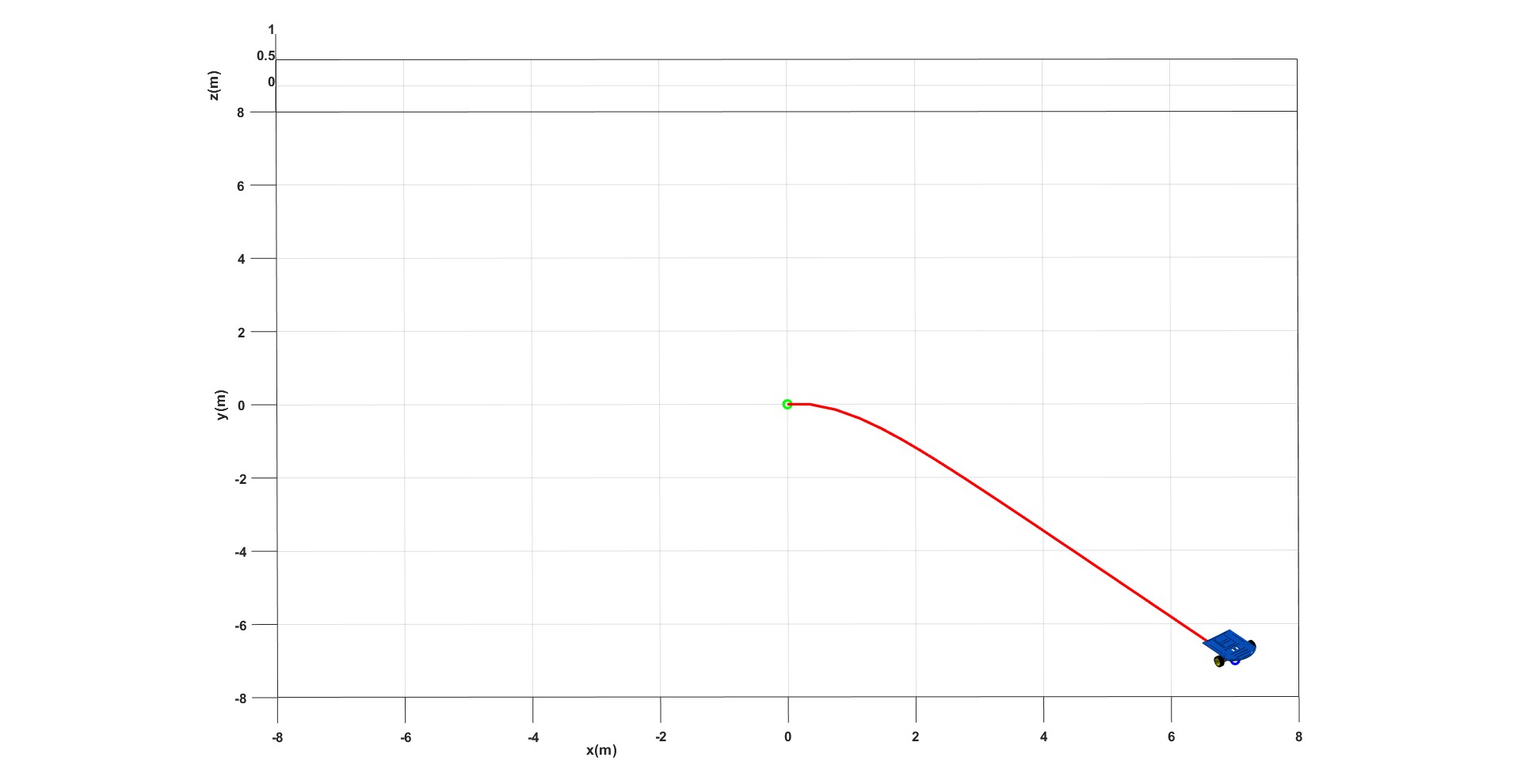
****

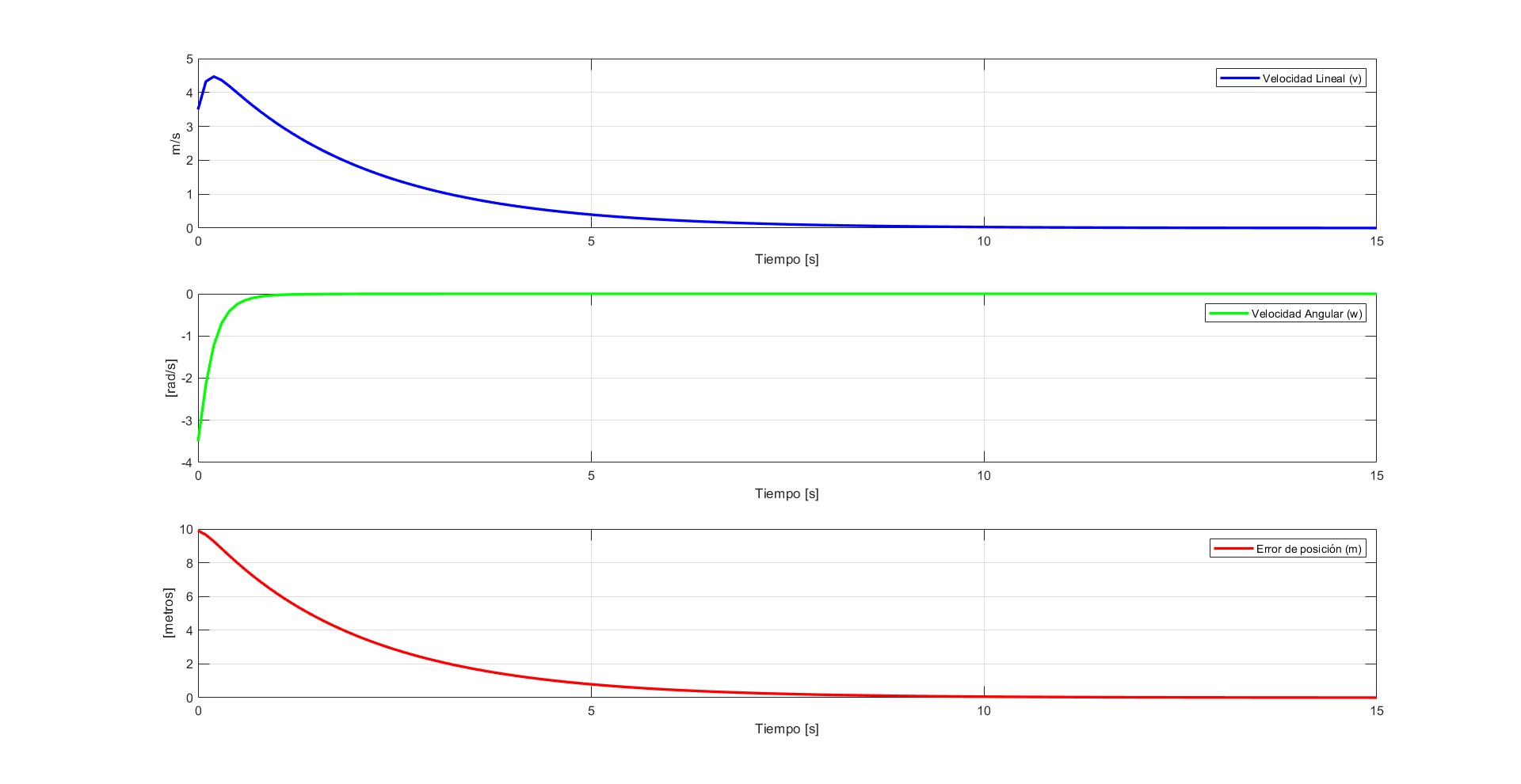
**o) (-5, -10) . 5**

****

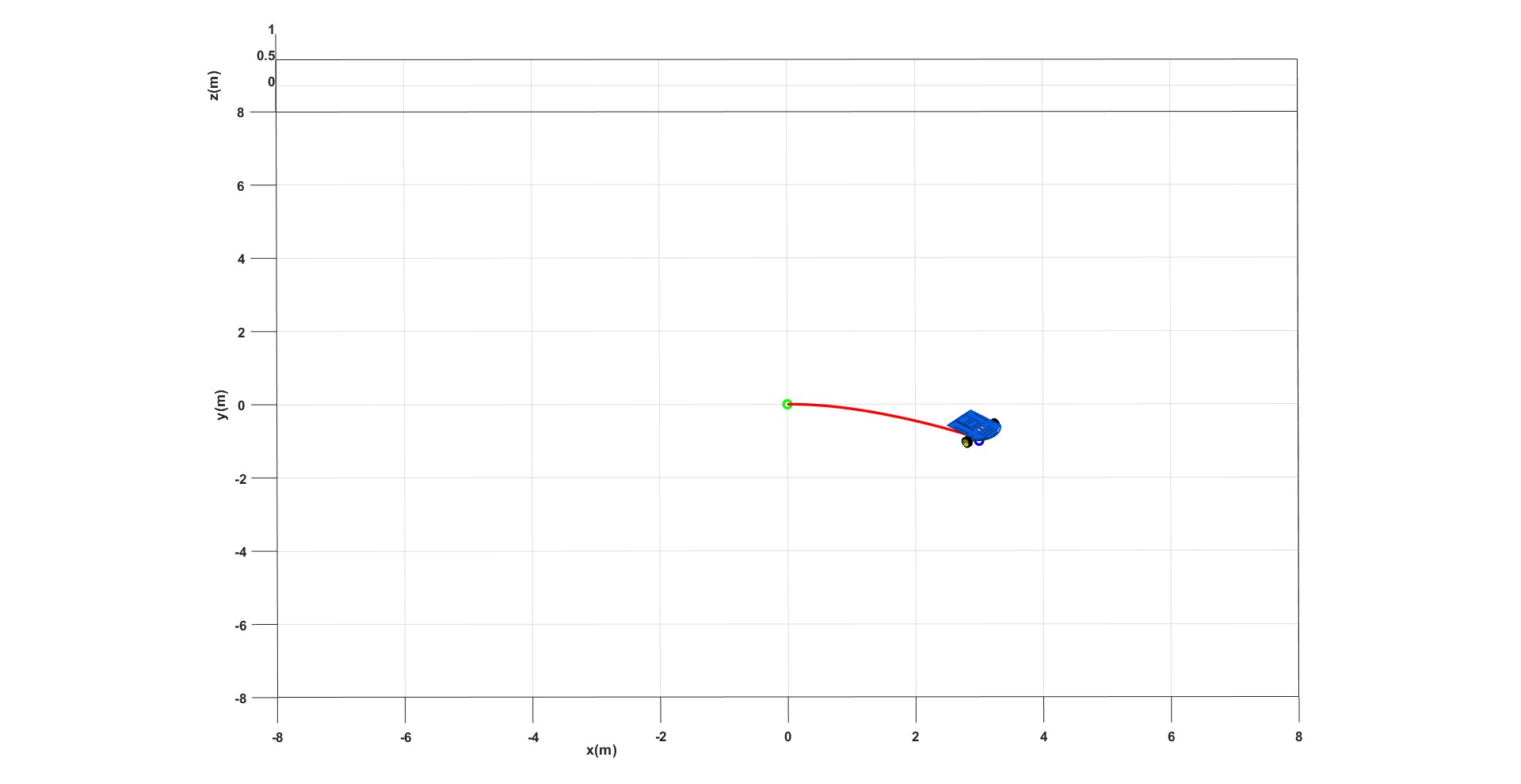
****

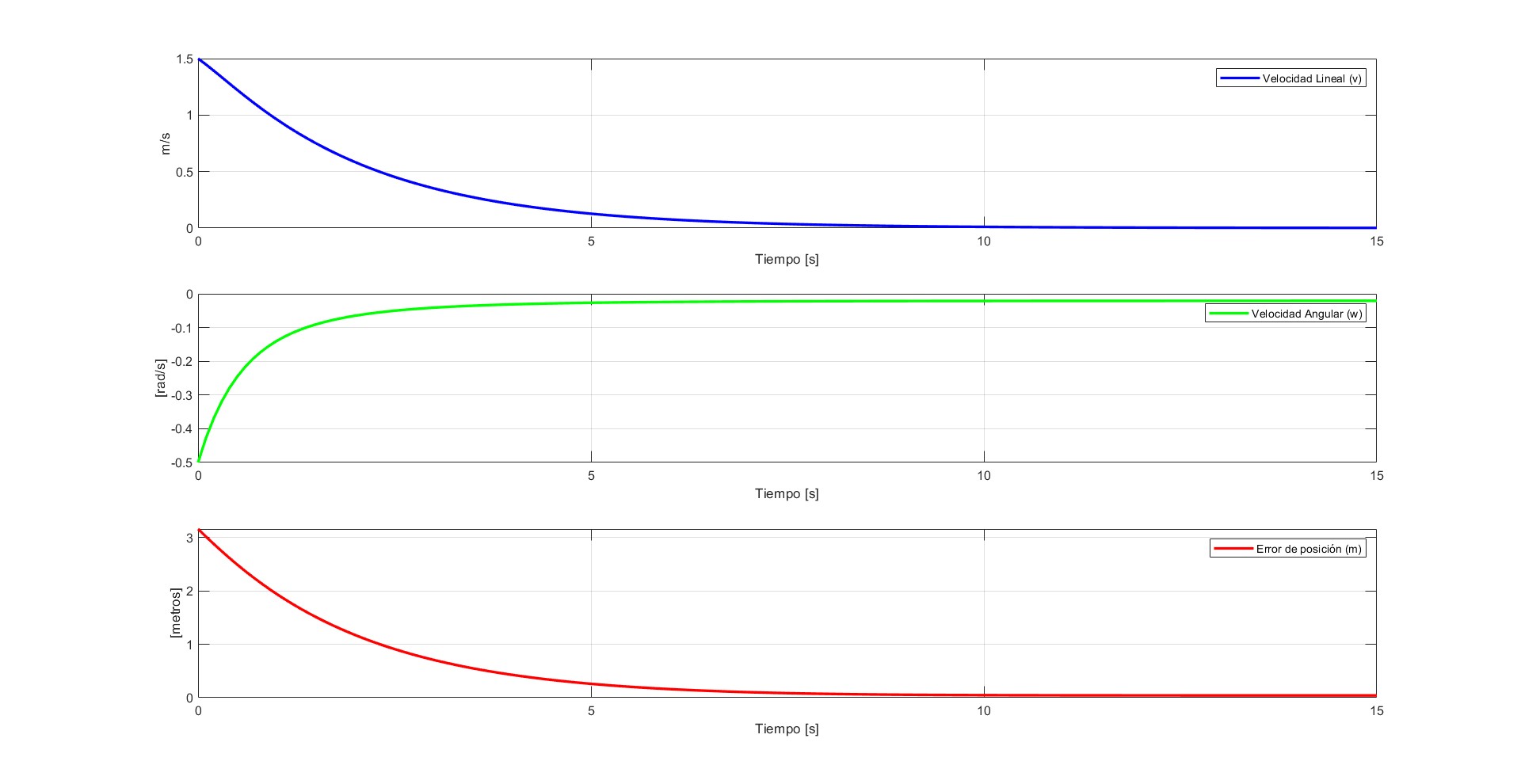
**p) (7, -7) .5**

****

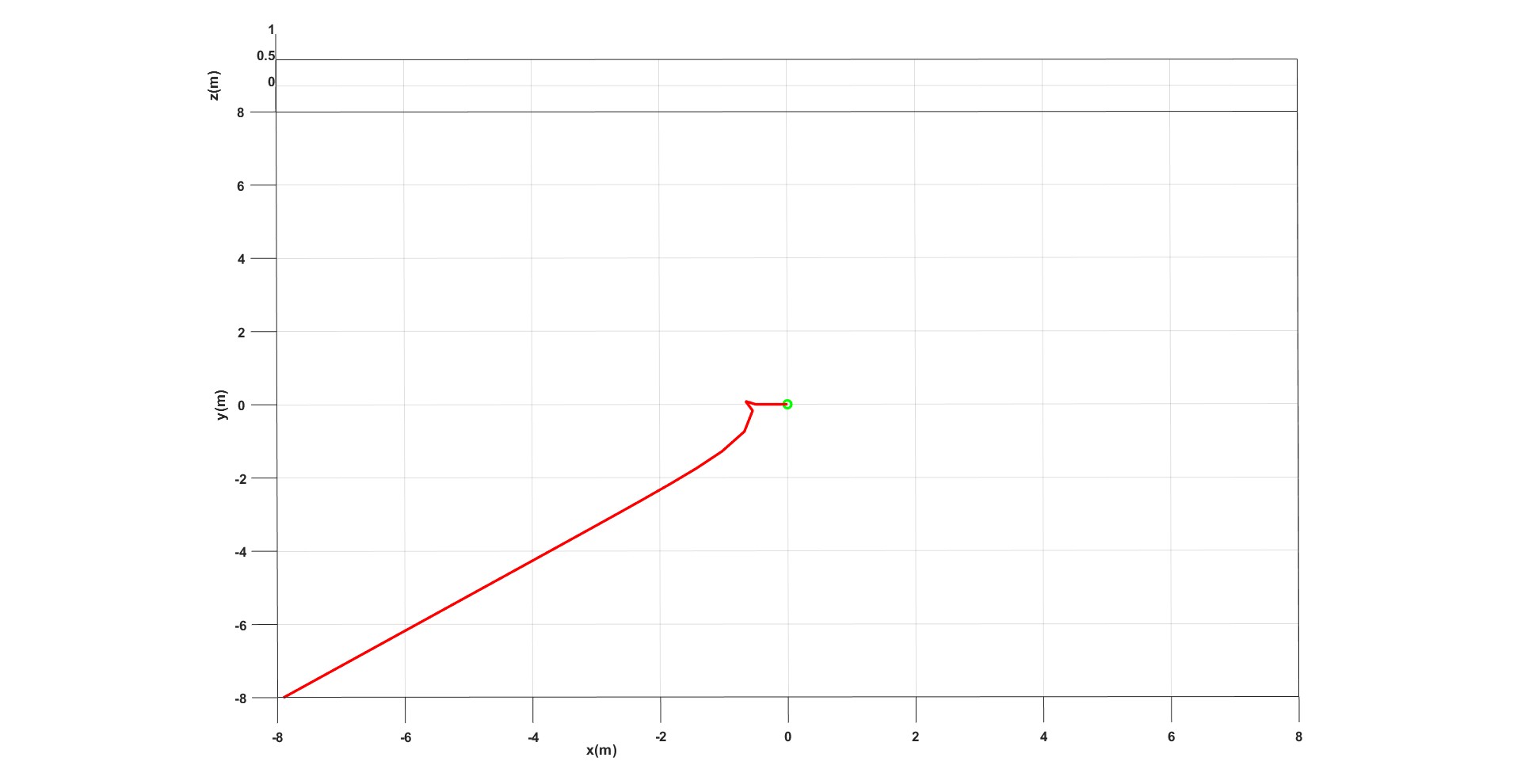
****

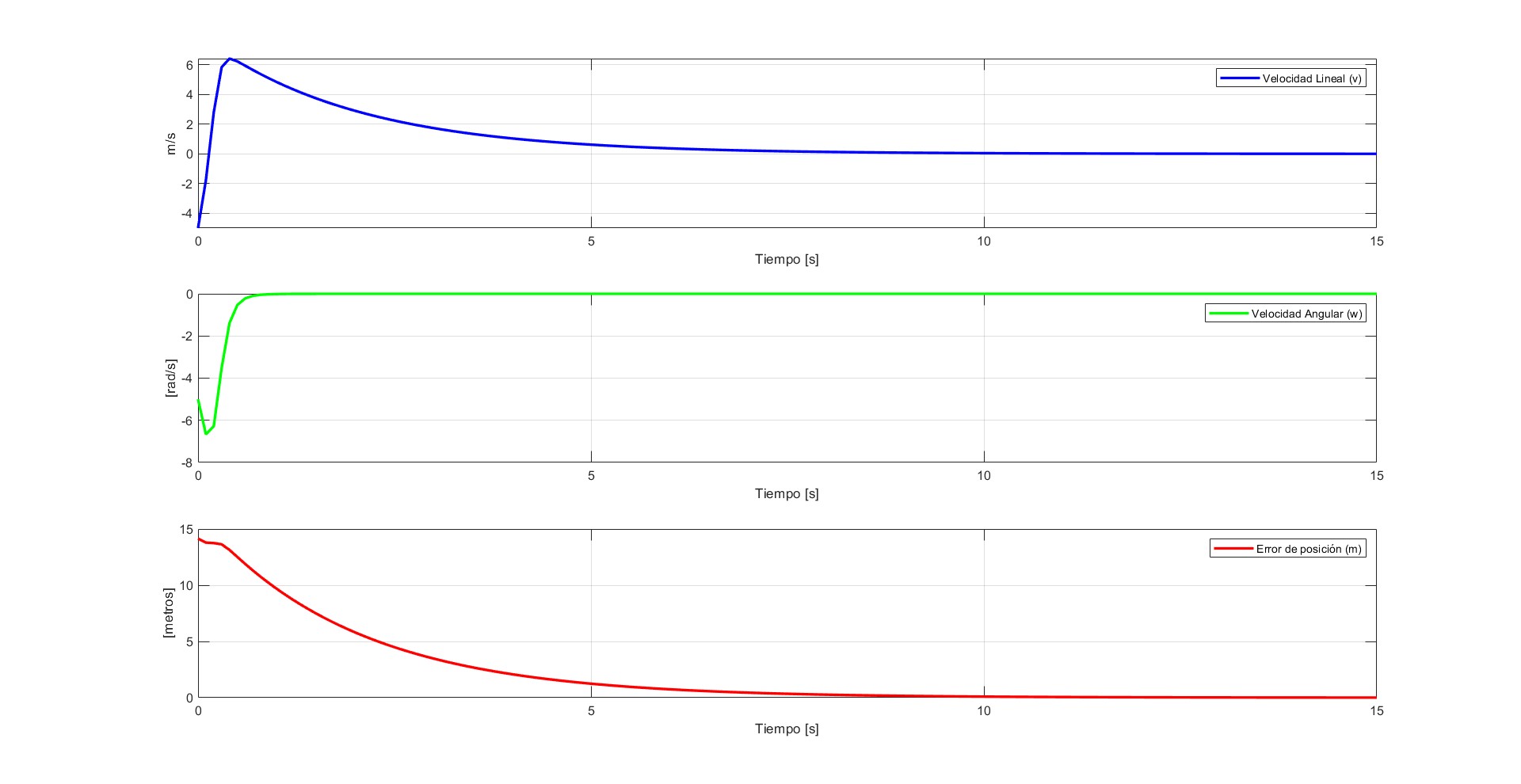
**q) (3, -1) .5**

****

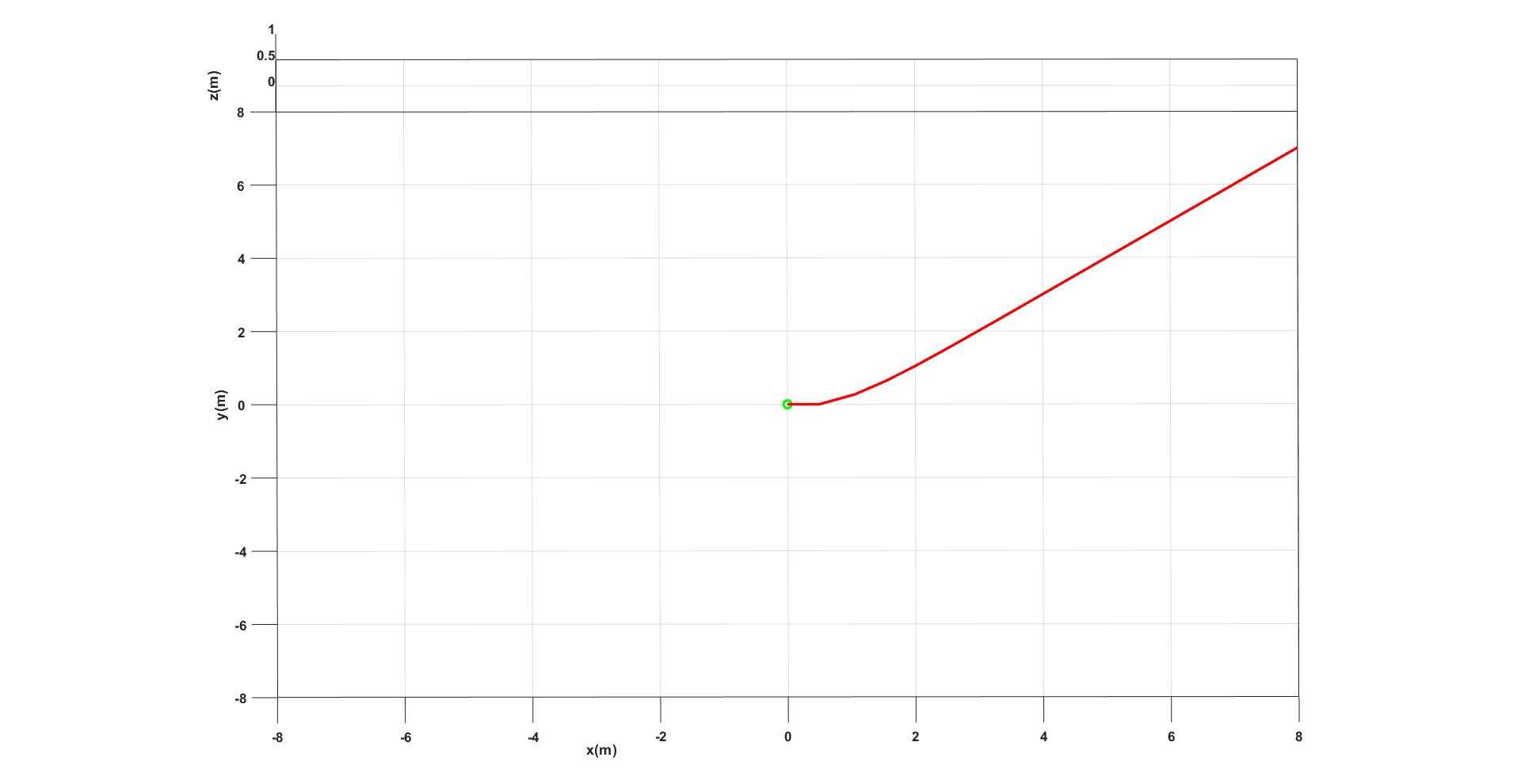
****

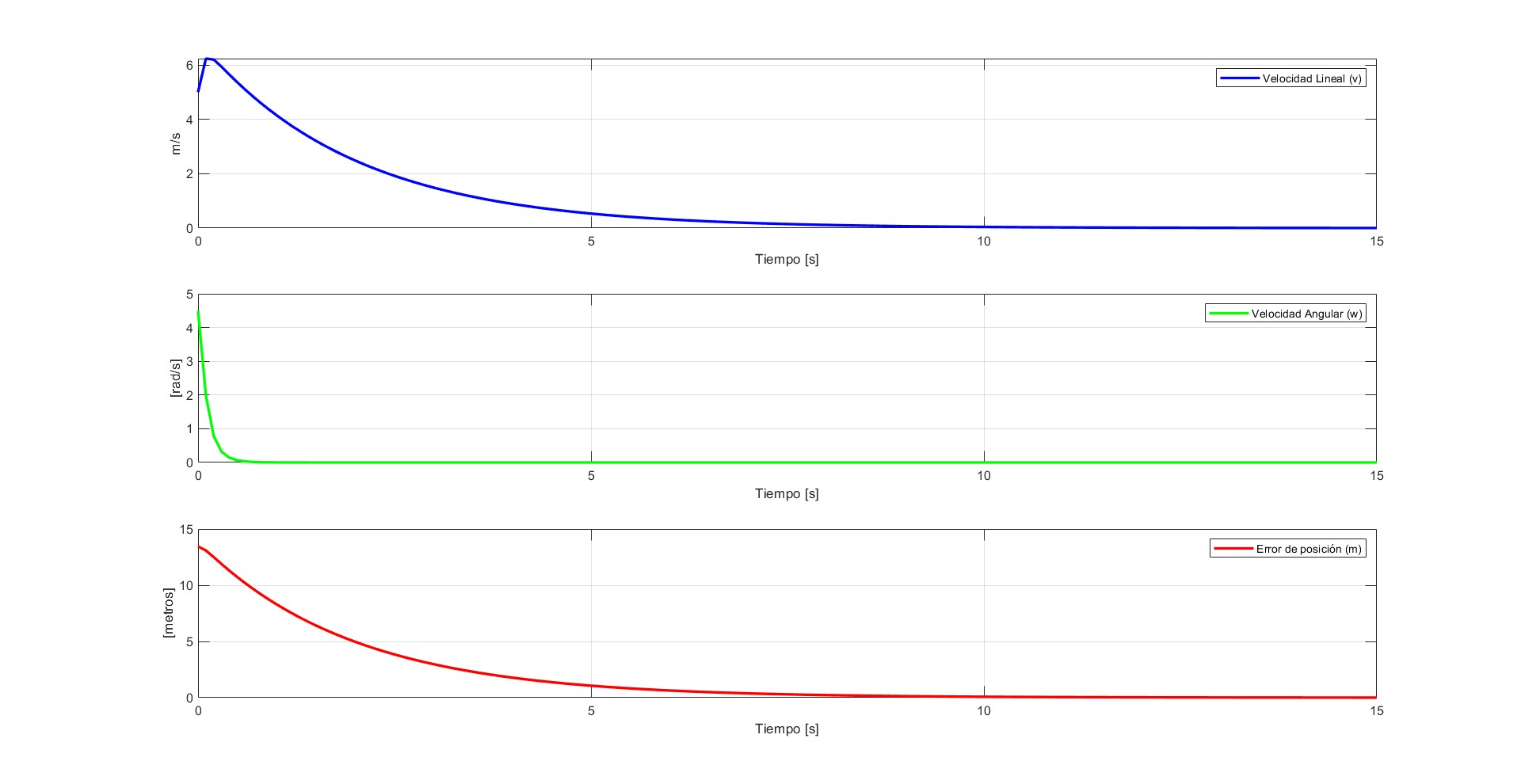
**r) (- 10, -10) .5**

****

****

**s) (10, 9) .5**

****

****