



Faculty of Engineering and Technology
Electrical and Computer Engineering Department
Computer Design Lab – ENCS4110
Experiment No. 3 Report
ARM's Flow Control Instructions

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Abstract

In this experiment we aim to understand ARM assembly language and its instructions using Keil uVision5 program, and we learn ARM branch instructions and their implementation, as well as we understand the importance of condition flags and how we can manipulate them to use branches, and finally we learn to investigate how to use strings in Keil uVision5.

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Theory

ARM Register Set

There are basically two types of registers - general purpose registers and special purpose registers. General purpose registers hold data or addresses.

The letter r is placed before the registration number to identify them.

For example, the label r4 is assigned to register 4. This figure shows the active registers available in user mode, which is a protected state commonly used to run programmers. There are seven different modes the processor can operate in, which we'll run through in a moment.

The registers in this example are all 32 bits in size.

There is up to 18 active registers are available:

16 data registers and 2 processor status registers.

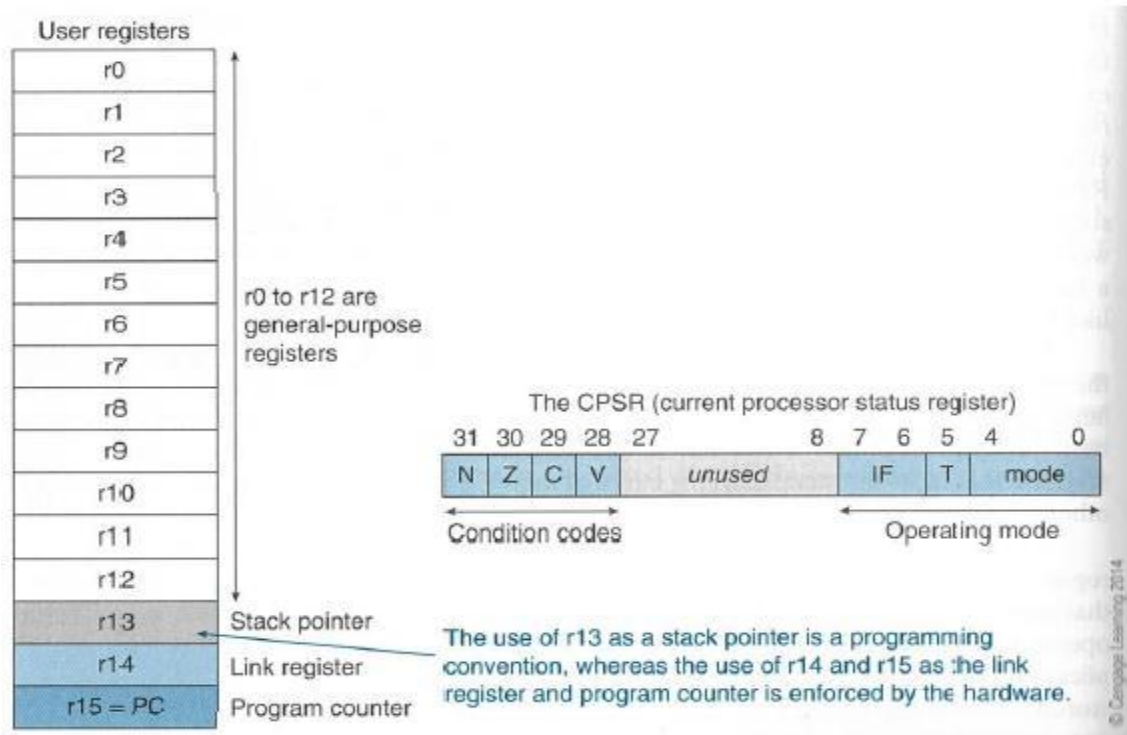


Figure 1 ARM register set

The data registers are labeled by the programmer from r0 to r15.

ARM processors contain three registers:

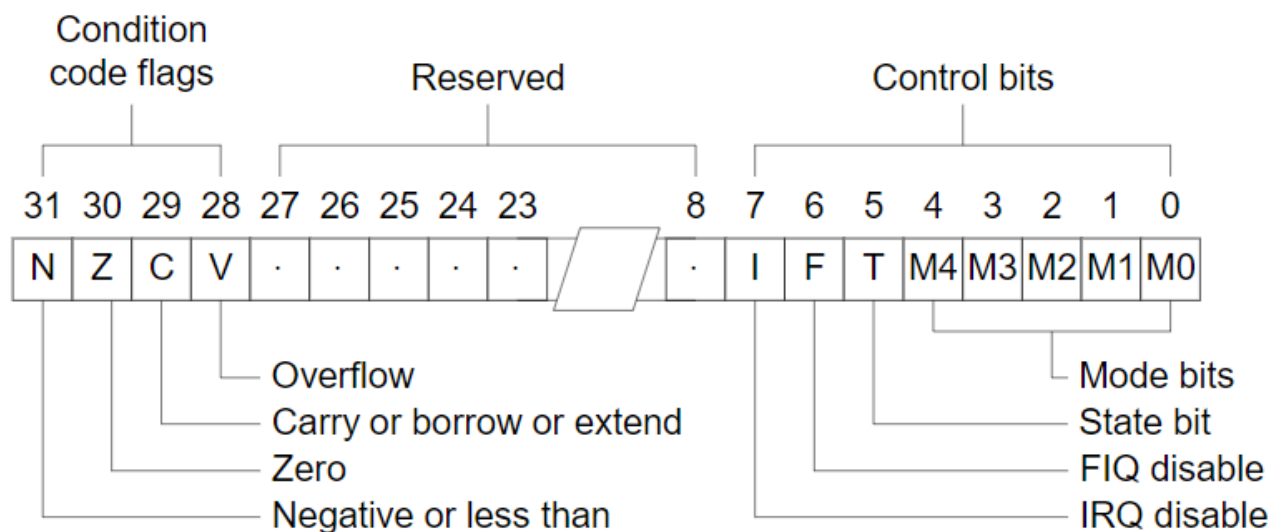
r13, r14 and r15, each assigned to a specific task or unique function. To distinguish them from other registers, they are usually assigned separate labels. The color register indicates which special register has been assigned.

Register 13 is used as a stack pointer (SP) and stores the top of the stack in the current processor mode.

The r14 register is called the link register (LR) and is where the kernel sets the return address each time it calls a subroutine. Register 15 is the program counter (PC) and contains the address of the next instruction to be fetched by the processor.

Current Program Status Register

CPSR is used by the ARM core to monitor and control internal functions. The vacant area has been set aside for future development as well its used in flags, status, extension, and control are the four fields of the CPSR, each of which is 8 bits wide.



N: Negative

The N flag is set by an instruction if the result is negative. In fact, N is set to the two's complement sign bit (bit 31).

Z: Zero

The Z flag is set if the result of the instruction set the flag to zero.

C: Carry (or Unsigned Overflow)

The C flag is set if the result of the unsigned operation exceeds the 32-bit result register. For instance, this bit can be used to implement 64-bit unsigned arithmetic.

V: (Signed) Overflow

The V flag works like the C flag, but for signed operations. For example, 0x7fffffff is the largest two's complement positive integer that can be represented in 32 bits, so 0x7fffffff + 0x7fffffff triggers a signed overflow, but not an unsigned (or carry) overflow:

the result, 0xffffffff, is true if interpreted as an unsigned quantity, but represents a negative value (-2) if interpreted as a signed quantity.

Conditional Execution

An important element of any computer is the ability of the program to modify what it does based on different conditions. Most computers provide conditional branch instructions, which move execution to another part of the program based on different conditional flags. For example, consider the code `if (x == 0) { do_something }`. Compiled into assembly code, this first checks the value of variable `x` and sets the flag Zero if `x` is 0. Then a conditional branch instruction jumps through the `do_something` code if the Zero flag is undefined. ARM processors go much further than others:

each statement becomes a conditional statement. Each statement consists of one of 16 conditions and the statement is executed only if the condition is true; otherwise, the instruction is ignored. (This is also known as predication.) The motive is to avoid unnecessary code jumps.

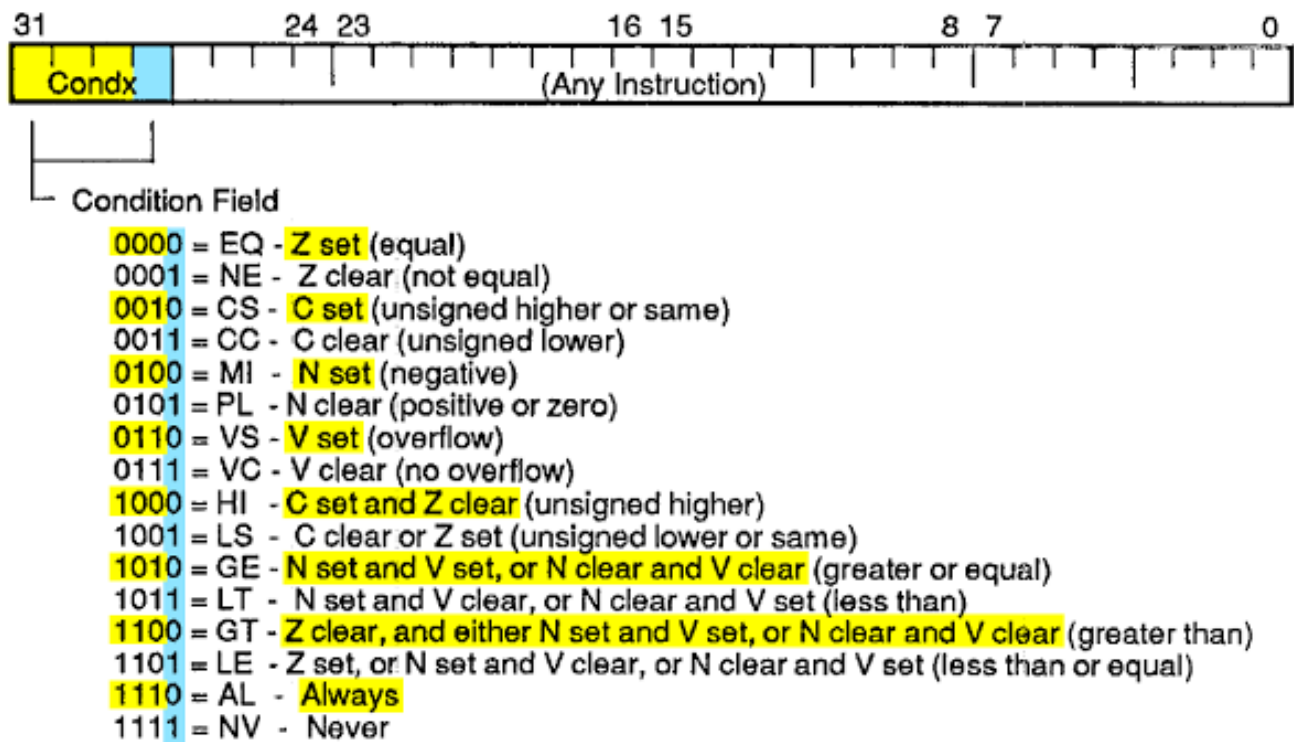


Figure 2 Conditional execution

ARM Instruction Format:

Arm instruction contain 32-bit, The condition field is 4 bits wide and sits between the immediate flag, which signals that operand 2 holds an immediate value, and the condition-set flag, which we can use to update the status register during an operation (more on these later). Notice it's the opcode that determines the operation—such as addition, subtraction, or exclusive OR—that the processor will perform.

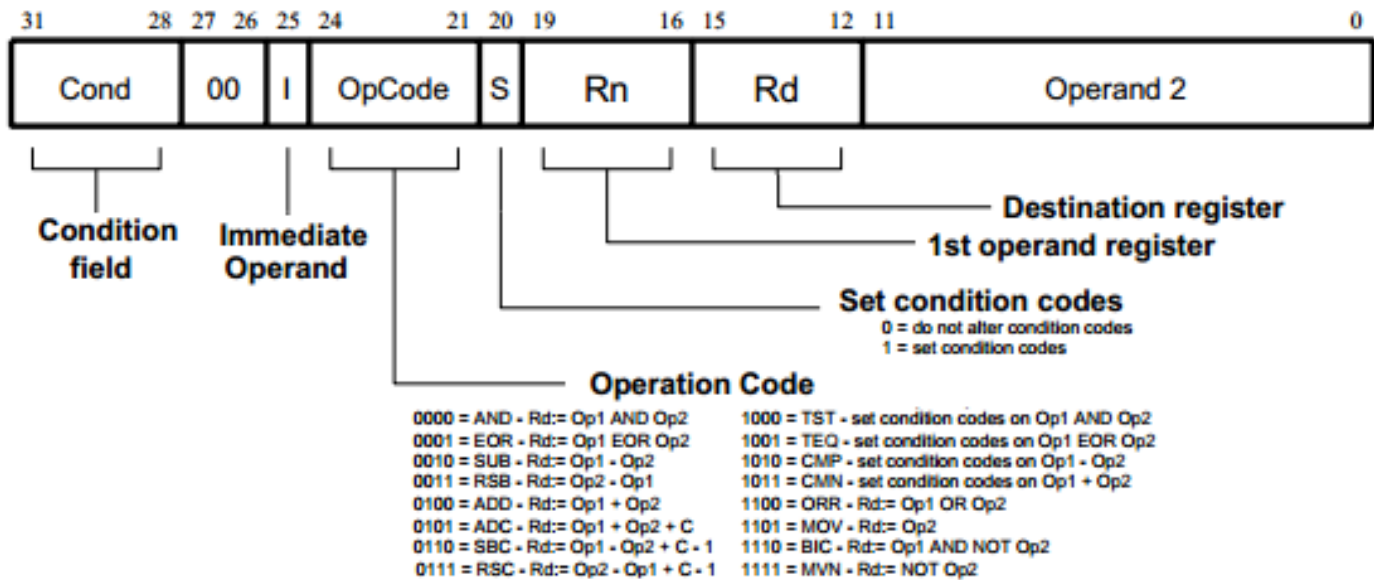


Figure 3 ARM data-processing instruction

Procedure and Lab work

Part 1: Examples of Using Branch Instructions

Example1:

; This program will count the length of a string. Directives

```
PRESERVE8
THUMB
; Vector Table Mapped to Address 0 at Reset
; Linker requires __Vectors to be exported
AREA RESET, DATA, READONLY
EXPORT __Vectors
__Vectors
    DCD 0x20001000 ; stack pointer value when stack is empty
    DCD Reset_Handler ; reset vector
    ALIGN
; *****
; Byte array/character string
; DCB type declares that memory will be reserved for consecutive bytes
; You can list comma separated byte values, or use "quoted" characters.
; The ,0 at the end null terminates the character string. You could also use "\0".
; The zero value of the null allows you to tell when the string ends.
; The DCB directive allocates one or more bytes of memory, and defines the initial
; runtime contents of the memory.
; Example Unlike C strings, ARM assembler strings are not null-terminated.
; You can construct a null-terminated C string using DCB as follows: C_string DCB "C_string",0
; *****
string1
    DCB "Hello world!",0
; The program
; Linker requires Reset_Handler
    AREA MYCODE, CODE, READONLY
    ENTRY
    EXPORT Reset_Handler
Reset_Handler
;*****;;User Code Start from the next line;*****;;
    LDR R0, = string1 ; Load the address of string1 into the register R0
    MOV R1, #0 ; Initialize the counter counting the length of string1
loopCount
    LDRB R2, [R0] ; Load the character from the address R0 contains
    CMP R2, #0
    BEQ countDone
; If it is zero...remember null terminated...
; You are done with the string. The length is in R1.
    ADD R0, #1 ; Otherwise, increment index to the next character
    ADD R1, #1 ; increment the counter for length
    B loopCount
countDone
STOP
    B STOP
    END ; End of the program
```

Which give us the results as this when we build and compile the program:

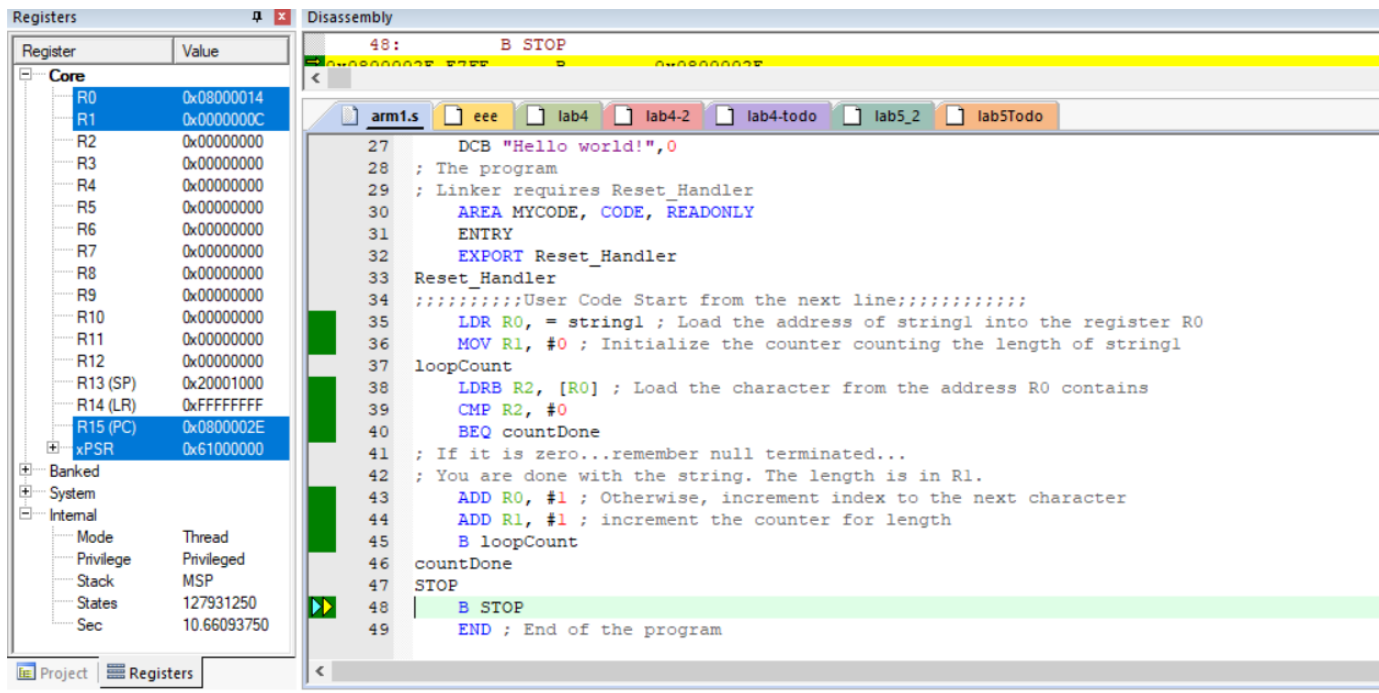


Figure 4 Example1

The code went as following:

The address of the string is loaded into R0, then we get R1 as a counter to count the string's characters, we get into the loop, we load the first letter in the string into R2, and compare it to 0 which is null, since its not null or the end of the string we increment R0 to point into the next character, then we add 1 to R1 as a count as so until it reached the end of the string the branch go to countDone and exit the program, the result of the count is stored in R2 which equal to 0x0C or 12 in decimal.

Example2:

```
;;; Directives
    PRESERVE8
    THUMB
; Vector Table Mapped to Address 0 at Reset
; Linker requires __Vectors to be exported
    AREA RESET, DATA, READONLY
    EXPORT __Vectors
__Vectors
    DCD 0x20001000 ; stack pointer value when stack is empty
    DCD Reset_Handler ; reset vector
    ALIGN
;Your Data section
;AREA DATA
; AREA MYRAM, DATA, READWRITE
SUMP DCD SUM
N DCD 5
    AREA MYRAM, DATA, READWRITE
SUM DCD 0
; The program
; Linker requires Reset_Handler
    AREA MYCODE, CODE, READONLY
    ENTRY
    EXPORT Reset_Handler
Reset_Handler
;;;;;;;;;;User Code Start from the next line;;;;;;;;;;
    LDR R1, N ;Load count into R1
    MOV R0, #0 ;Clear accumulator R0
LOOP
    ADD R0, R0, R1 ;Add number into R08
    SUBS R1, R1, #1 ;Decrement loop counter R1
    BGT LOOP ;Branch back if not done
    LDR R3, SUMP ;Load address of SUM to R3
    STR R0, [R3] ;Store SUM
    LDR R4, [R3]
STOP
    B STOP
END
```

Executing the code above will give us the result as:

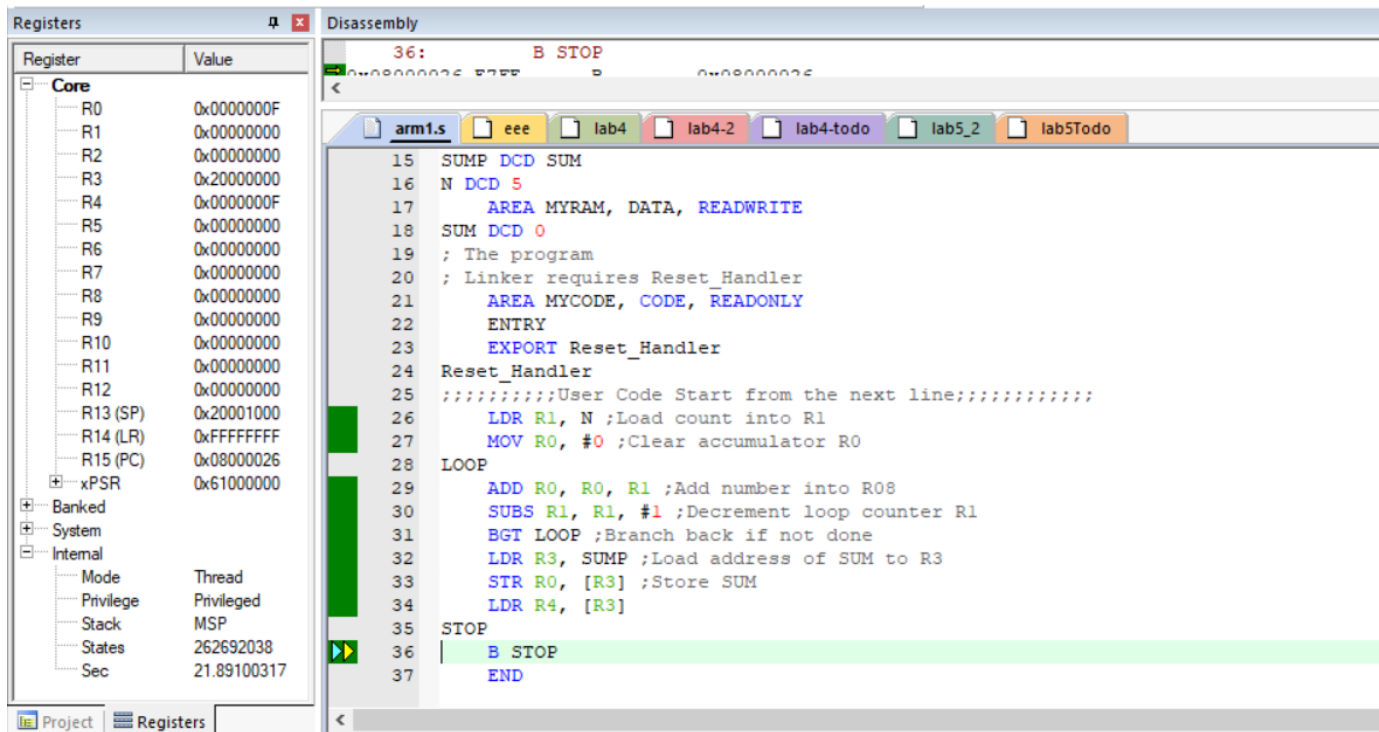


Figure 5 Example2

Noting that: the counter load into R1, and initiate R0 with 0, then we enter the loop, we add R1 into R0, which will be R0 = 0x5 for first loop, then R1 decrement by 1, R1 is greater than 0 we stay in the loop, we load the address SUMP into R3 then we store the value of R0 into R3, and load the value by getting it load to R4 again, the loop goes on until R1 equal to zero which will give us the sum up to 0x0F or 15 in decimal, the answer is right and we see that in the value of R4.

Lab work:

Write an ARM assembly language program CountVowelsOne.s to count how many vowels and how many non-vowels are in the following string. "ARM assembly language is important to learn!",0

```
;;; Directives
    PRESERVE8
    THUMB
; Vector Table Mapped to Address 0 at Reset
; Linker requires __Vectors to be exported
    AREA RESET, DATA, READONLY
    EXPORT __Vectors
__Vectors
    DCD 0x20001000 ; stack pointer value when stack is empty
    DCD Reset_Handler ; reset vector
    ALIGN
;Your Data section
;AREA DATA
; AREA MYRAM, DATA, READWRITE
string1
    DCB "ARM assembly language is important to learn!",0
    AREA MYRAM, DATA, READWRITE
SUM DCD 0
; The program
; Linker requires Reset_Handler
    AREA MYCODE, CODE, READONLY
    ENTRY
    EXPORT Reset_Handler
Reset_Handler
;;;;;;;;;;User Code Start from the next line;;;;;;;;;;
    LDR R1, =string1 ;Load string into R1
    MOV R0, #0 ;Clear accumulator R0
LOOP
    LDRB R2,[R1]
    CMP R2,#0
    BEQ stopcount
    ADD R1,#1
    CMP R2,' ' ; compare it to jump character " we don't want to count it since it not a vowel
    BEQ LOOP
    CMP R2,#90 ; character is uppercase
    BLS returnSmall
    B getVowels
returnSmall
    add R2,R2,#32
```

getVowels

```
CMP R2,'a'  
BEQ addVowel;  
CMP R2,'i'  
BEQ addVowel;  
CMP R2,'o'  
BEQ addVowel;  
CMP R2,'u'  
BEQ addVowel;  
CMP R2,'e'  
BEQ addVowel;  
B LOOP;
```

addVowel ; add to the counter

```
ADD R0,#1  
B LOOP
```

stopcount

STOP

B STOP

END

And it will give us the answer in R0 which is 14 vowel character stored in R0.

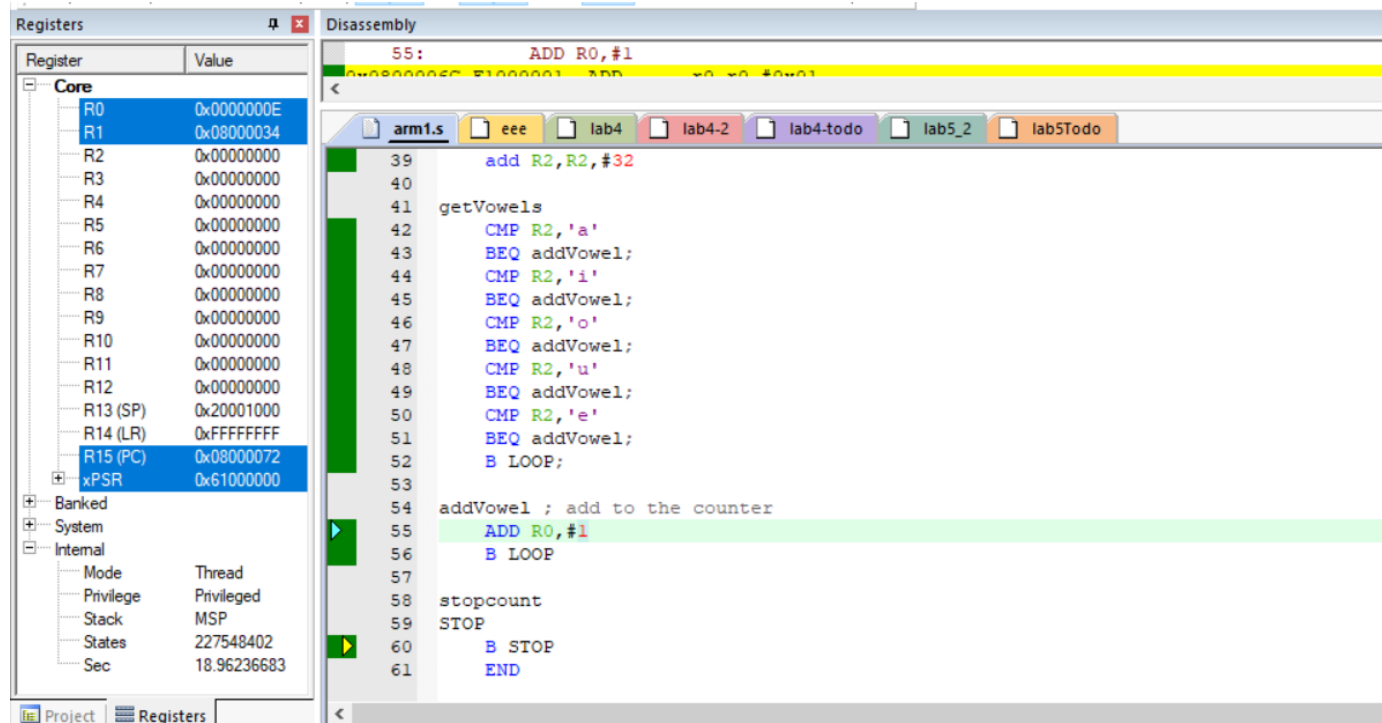


Figure 6 Lab work

To do:

We got asked in class to write a code that will check if the number can mod 8.

;;; Directives

PRESERVE8

THUMB

; Vector Table Mapped to Address 0 at Reset

; Linker requires __Vectors to be exported

AREA RESET, DATA, READONLY

EXPORT __Vectors

__Vectors

DCD 0x20001000 ; stack pointer value when stack is empty

DCD Reset_Handler ; reset vector

ALIGN

;Your Data section

;AREA DATA

; AREA MYRAM, DATA, READWRITE

SUMP DCD SUM

N DCD 5,16,20,8,64,'\$'

AREA MYRAM, DATA, READWRITE

SUM DCD 0

; The program

; Linker requires Reset_Handler

AREA MYCODE, CODE, READONLY

ENTRY

EXPORT Reset_Handler

Reset_Handler

;;;;;;;;;;User Code Start from the next line;;;;;;;;;;

LDR R0, =N ;Load count into R1

MOV R1,#0

LOOP

LDR R2,[R0]

CMP R2,'\$' ;which is the end of the array

BEQ STOP

ADD R0,#4 ; we increment it by 4 since its word and not byte.

CMP R2,#8

BLT LOOP

BEQ canDivide8

BGT check

B LOOP

check

MOV R3,#8

SUB R4,R2,R3 ; sub r3 from r2

```

CMP R4,#0
BEQ canDivide8 ; if its zero then the number can divide 8
MOV R2,R4 ; switch the number else
CMP R4,#8 ; if R4 is more than 8 , enter the loop again
BGE check
B LOOP

```

canDivide8

```

ADD R1,#1
B LOOP

```

STOP

```

B STOP
END

```

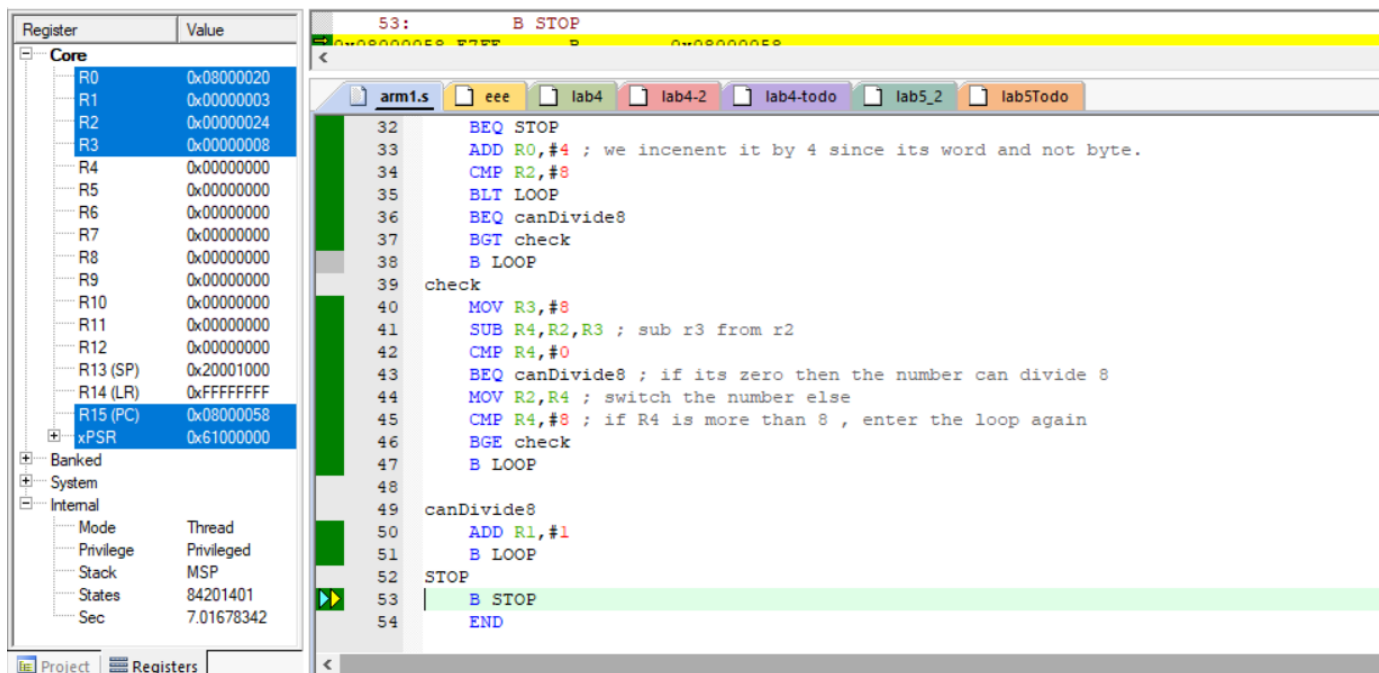


Figure 7 To do

So as we see there's three numbers in the array that can mod 8 which are 16,8 and 64 and we see in the results stored in R1 that 0x03 is the amount of numbers can mod 8, this code is looping to divide by using subtraction and checking again.

Conclusion

In this experiment we learnt how to use strings in assembly language as well as we learnt how to store and load into registers using LDR and LDRB and STR, and how we can use conditions and branches in our code to make it easier to understand and simpler and use less instructions using loops.

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