

# DIVIDE & CONQUER TRANSFORMATION

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# Problem Specification

$$S(f) \triangleq [\forall x. R(x, f(x))]$$

$S \subseteq \mathcal{U} \rightarrow \mathcal{U}$  — specification for  $f$  —  $S$  is 2<sup>nd</sup>-order  
 $R \subseteq \mathcal{U} \times \mathcal{U}$  — input/output relation

example:  $R(x, y) \triangleq [\varphi(x) \Rightarrow \psi(x, y)]$  —  $\varphi$  pre-condition,  $\psi$  post-condition

this form of  $S$  captures requirements on single runs of  $f$ ;  
richer forms can capture requirements on multiple runs (hyperproperties, e.g. noninterference)

generalizes to  $n$  inputs and  $m$  outputs:

$$S(f) \triangleq [\forall \vec{x}. R(\vec{x}, f(\vec{x}))] \quad S \subseteq \mathcal{U}^n \rightarrow \mathcal{U}^m \quad R \subseteq \mathcal{U}^n \times \mathcal{U}^m$$

this is more general than divide & conquer; it could be moved to separate notes

# Representative Schema

$$DC(a, b, c, d)(x) \triangleq \text{if } a(x) \text{ then } b(x) \text{ else let } (x_1, x_2) = d(x) \text{ in } c(DC(a, b, c, d)(x_1), DC(a, b, c, d)(x_2))$$

- $a \subseteq U$  — atomic (i.e. non-decomposable) problems
- $b: U \rightarrow U$  — base case, i.e. direct solution for atomic problems
- $c: U \times U \rightarrow U$  — compose solutions to sub-problems
- $d: U \rightarrow U \times U$  — decompose problems into sub-problems
- $DC(a, b, c, d): U \rightarrow U$  — solve all problems via divide & conquer
- $\mu: U \rightarrow U$  — measure of DC (variable, schematic)
- $< \subseteq U \times U$  — well-founded relation of DC (variable, schematic)
- $\rho \subseteq U \times U$  — input/output relation (i.e. definition of solutions to problems)

**WFF**  $\emptyset \subset U \subseteq U \Rightarrow \exists m \in U. \forall u \in U - \{m\}. u \neq m$

**$\tau$**   $\neg a(x) \wedge d(x) = (x_1, x_2) \Rightarrow \mu(x_1) < \mu(x) \wedge \mu(x_2) < \mu(x)$

**BASE**  $a(x) \Rightarrow \rho(x, b(x))$

**STEP**  $\neg a(x) \wedge d(x) = (x_1, x_2) \wedge \rho(x_1, y_1) \wedge \rho(x_2, y_2) \Rightarrow \rho(x, c(y_1, y_2))$

**ALL**  $\rho(x, DC(a, b, c, d)(x))$

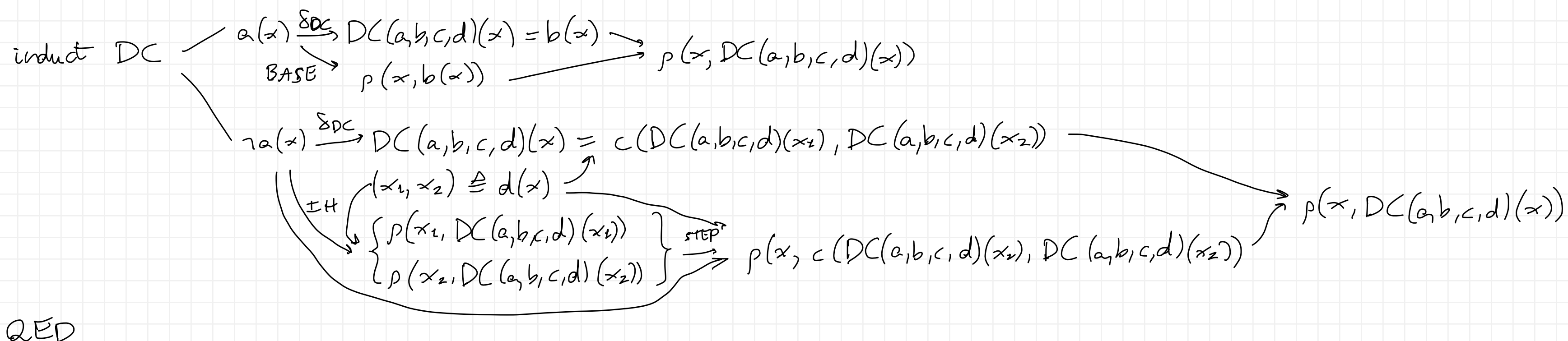
—  $<$  well-founded

— DC terminates

—  $b$  solves atomic case

—  $c$  composes sub-solutions into solutions

**COR**  $\vdash \text{BASE} \wedge \text{STEP} \Rightarrow \text{ALL}$  — correctness theorem



# List Fold Schema and Its Application

$\text{fold}(g, h)(x) \triangleq \text{if } \text{atom}(x) \text{ then } g(x) \text{ else } h(\text{car}(x), \text{fold}(g, h)(\text{cdr}(x)))$

$M_{\text{fold}}(x) \triangleq \text{len}(x) \quad \boxed{\tau_{\text{fold}}} \vdash \neg \text{atom}(x) \Rightarrow \text{len}(\text{cdr}(x)) < \text{len}(x)$

**BASE**  $\text{atom}(x) \Rightarrow \rho(x, g(x))$

**STEP**  $\text{cons}(x) \wedge \rho(\text{cdr}(x), y) \Rightarrow \rho(x, h(\text{car}(x), y))$

**ALL**  $\rho(x, \text{fold}(g, h)(x))$

**COR**  $\vdash \boxed{\text{BASE}} \wedge \boxed{\text{STEP}} \Rightarrow \boxed{\text{ALL}}$

induct  $x$    
 $\text{atom}(x) \xrightarrow{\delta_{\text{fold}}} \text{fold}(g, h)(x) = g(x) \xrightarrow{\text{BASE}} \rho(x, g(x)) \rightarrow \rho(x, \text{fold}(g, h)(x))$    
 $\text{cons}(x) \xrightarrow{\delta_{\text{fold}}} \text{fold}(g, h)(x) = h(\text{car}(x), \text{fold}(g, h)(\text{cdr}(x))) \xrightarrow{\text{IH}} \rho(\text{cdr}(x), \text{fold}(g, h)(\text{cdr}(x))) \xrightarrow{\text{STEP}} \rho(x, h(\text{car}(x), \text{fold}(g, h)(\text{cdr}(x)))) \rightarrow \rho(x, \text{fold}(g, h)(x))$    
 QED

$S(f) \triangleq [\forall x. R(x, f(x))]$  - old specification

$S'(f, g, h) \triangleq [f = \text{fold}(g, h) \wedge S_g(g) \wedge S_h(h)]$

$S_g(g) \triangleq [\forall x. \text{atom}(x) \Rightarrow R(x, g(x))]$

$S_h(h) \triangleq [\forall x, y. \text{cons}(x) \wedge R(\text{cdr}(x), y) \Rightarrow R(x, h(\text{car}(x), y))]$

- new specifications

**SS'**  $\vdash S'(f, g, h) \Rightarrow S(f)$

$S'(f, g, h) \xrightarrow{\delta_{S'}} \begin{matrix} f = \text{fold}(g, h) \\ S_g(g) \\ S_h(h) \end{matrix} \xrightarrow[\rho := R]{\text{COR}} \forall x. R(x, \text{fold}(g, h)(x)) \xrightarrow{\delta_S} [\forall x. R(x, f(x))] = S(f)$    
 QED