# Mechanized Operational Semantics

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(Lecture 2: An Operational Semantics)

## Java Virtual Machine

We have a precise mathematical model of the Java Virtual Machine, called M6 (Model 6)

It is too complicated to present here (160 pages).

We will look at a simpler model, M1 (3 pages).

## **M1**

An M1 state consists of:

- program counter (pc)
- local variables (locals)
- push down stack (stack)
- program to run (program)

PUSH 23  $\Leftarrow pc$ LOAD 1
ADD
STORE 1

0 [17 12] pc locals

stack

program

PUSH 23 LOAD 1  $\Leftarrow pc$  ADD STORE 1 .... 1 [17 12] 23 pc locals stack program

PUSH 23 LOAD 1 ADD  $\Leftarrow pc$  STORE 1 ... 2 [17 12] 23 pc locals stack program

PUSH 23 LOAD 1 ADD STORE 1  $\Leftarrow pc$  .... 3 [17 12] 35 pc locals stack program

PUSH 23
LOAD 1
ADD
STORE 1
...  $\Leftarrow pc$ 4 [17 35] pc locals stack program

```
PUSH 23
LOAD 1
ADD
STORE 1
```

• • •

$$\begin{bmatrix} 4 & [17 \ 35] \end{bmatrix}$$
  $pc \quad locals \quad stack \quad program$ 

If locals[1] is the variable a, then this is the compiled code for "a = 23+a;"

# Recall g

```
(defun g (n a)
  (if (zp n)
          a
          (g (- n 1) (* n a))))
```

# The M1 Program

We use locals[0] to hold n and locals[1] to hold a.

```
; loop
    (LOAD 0)
    (IFLE 10)    ; if n<=0 go end
    (LOAD 0)
    (LOAD 1)
    (MUL)
    (STORE 1)    ; a := n*a</pre>
```

```
(LOAD 0)
  (PUSH 1)
  (SUB)
  (STORE 0) ; n := n-1
  (GOTO -10) ; go loop
; end
  (LOAD 1)
  (RETURN)))
```

## M1 versus JVM

% cat Fact.java
% javac Fact.java
% javap -c Fact

#### The Plan

Formalize M1 states and other basic utilities

Formalize the semantics of each instruction

Formalize the "fetch-execute" cycle

# Formalizing M1

## Formalizing M1

```
(defun make-state (pc locals stack program)
  (list pc locals stack program))
```

## Formalizing M1

```
(defun opcode (inst) (car inst))
(defun arg1 (inst) (nth 1 inst))
(defun arg2 (inst) (nth 2 inst))

(opcode '(PUSH 23)) \Rightarrow PUSH
(arg1 '(PUSH 23)) \Rightarrow 23
```

```
(defun push (x stk) (cons x stk))
(defun top (stk) (car stk))
(defun pop (stk) (cdr stk))

(push 3 '(2 1)) \Rightarrow (3 2 1)
(top '(3 2 1)) \Rightarrow 3
(pop '(3 2 1)) \Rightarrow (2 1)
```

```
(defun do-inst (inst s)
 (if (equal (opcode inst) 'PUSH)
      (execute-PUSH inst s)
   (if (equal (opcode inst) 'LOAD)
        (execute-LOAD inst s)
      (if (equal (opcode inst) 'STORE)
          (execute-STORE inst s)
        (if (equal (opcode inst) 'ADD)
            (execute-ADD inst s)
```

```
(defun do-inst (inst s)
 (if (equal (opcode inst) 'PUSH)
      (execute-PUSH inst s)
   (if (equal (opcode inst) 'LOAD)
        (execute-LOAD inst s)
      (if (equal (opcode inst) 'STORE)
          (execute-STORE inst s)
        (if (equal (opcode inst) 'ADD)
            (execute-ADD inst s)
```

## Aside: HOL

If we had a higher order logic:

- instruction: state → state
- do-inst: apply

```
(defun do-inst (inst s)
 (if (equal (opcode inst) 'PUSH)
      (execute-PUSH inst s)
   (if (equal (opcode inst) 'LOAD)
        (execute-LOAD inst s)
      (if (equal (opcode inst) 'STORE)
          (execute-STORE inst s)
        (if (equal (opcode inst) 'ADD)
            (execute-ADD inst s)
```

```
(defun next-inst (s)
     (nth (pc s) (program s)))
(defun step (s)
     (do-inst (next-inst s) s))
```

```
(defun run (sched s)
  (if (endp sched)
    s
    (run (cdr sched) (step s))))
```

Sched is a "schedule" telling us how many steps to take.

Only its length matters.

#### **Aside**

In more sophisticated models, sched is a list of "thread identifiers" and tells us which thread to step next.

# **Terminating Computations**

When is a state halted?

```
(defun haltedp (s)
  (equal s (step s)))
```

## Recall Program g

```
(defconst *g*
 '((PUSH 1); 0
   (STORE 1); 1 a := 1
   (LOAD 0) ; 2 loop
   (IFLE 10); 3 if n<=0 go end
   (LOAD 0) ; 4
   (LOAD 1) ; 5
   (MUL) ; 6
   (STORE 1); 7 a := n*a
   (LOAD 0) ; 8
   ...))
```

How long does it take to run g?

Let's construct a schedule for g.

More precisely, let's write a function that takes g's input n and returns a schedule to run g on n.

```
'((PUSH 1); 0
 (STORE 1) ; 1 a := 1
 (LOAD 0) ; 2 loop
 (IFLE 10); 3 if n<=0 go end
 (LOAD 0) ; 4
 (LOAD 1)
           ; 5
 (MUL)
           ; 6
 (STORE 1); 7 a := n*a
 (LOAD 0) ; 8
 (PUSH 1) ; 9
 (SUB) ; 10
 (STORE 0); 11 n := n-1
 (GOTO -10); 12 go loop
 (LOAD 1) ; 13 end
 (RETURN))); 14 return a
```

```
'((PUSH 1); 0
 (STORE 1); 1 a := 1
 (LOAD 0) ; 2 loop
 (IFLE 10); 3 if n \le 0 go end
 (LOAD 0) ; 4
 (LOAD 1) ; 5
 (MUL) ; 6
 (STORE 1); 7 a := n*a
 (LOAD 0) ; 8
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 (SUB) ; 10
 (STORE 0); 11 n := n-1
 (GOTO -10); 12 go loop
 (LOAD 1) ; 13 end
 (RETURN))); 14 return a
```

## A Schedule for g

```
(defun g-sched (n)
  (append (repeat 0 2)
          (g-sched-loop n)))
(defun g-sched-loop (n)
  (if (zp n)
      (repeat 0 4)
    (append (repeat 0 11)
            (g-sched-loop (- n 1)))))
```

## Running g

### Demo 1

M1 inherits a lot of power from ACL2.

We're executing about 360,000 instructions/sec on this laptop.

But how does M1 compare to the JVM?

### **Operation**

Load int from local variable

Format (2 bytes)

ILOAD index

### **Form**

21 (0x15)

## **Operand Stack**

### **Description**

The *index* is an unsigned byte that must be an index into the local variable array of the current frame. The local variable at *index* must contain an int. The value of the local variable at *index* is pushed onto the operand stack.

### **Operation**

Load int from local variable

Format (2 bytes)

ILOAD index

#### **Form**

21 (0×15)

## **Operand Stack**

```
ILOAD
```

typed!

## **Operation**

Load int from local variable

Format (2 bytes)

ILOAD index

### **Form**

21 (0×15)

## **Operand Stack**

 $\dots \Rightarrow \dots$ , value

**Operation** 

32-bit arithmetic!

Load int from local variable

Format (2 bytes)

ILOAD index

**Form** 

21 (0×15)

**Operand Stack** 

## **Operation**

Load int from local variable

Format (2 bytes) instruction stream

ILOAD index is unparsed bytes

#### **Form**

21 (0x15)

## **Operand Stack**

## Description threads and method calls!

The index is an unsigned byte that must be an index into the local variable array of the current frame. The local variable at index must contain an int. The value of the local variable at index is pushed onto the operand stack.

## Comparison with the JVM

- specification style is very similar
- functionality is similar

It is possible to "grow" M1 into a complete JVM.

## A High Level Language

It is easy to write a compiler from a simple language of while and assignments to M1 code.

## Demo 2

To see the implementation of the compiler, read the preliminary material prepared for this Summer School.

### **Conclusion**

Two advantages of operational semantics:

- easy to relate to implementation or an informal specification
- executable

ACL2 "customers" *really like* the ability to run their models.

### **Next Time**

But can we prove anything about a model like this?