- 1\*\* A particle of mass m is moving horizontally in a straight line. Its motion is opposed by a force of magnitude  $mk(v+v^3)$  Newtons, its speed is v ms $^{-1}$  and k is a positive constant. At time t seconds the particle has displacement x metres from a fixed point 0 on the line. Prove  $x = -\frac{1}{k} \int \frac{1}{1+v^2} dv$
- A body is moving in a horizontal straight line. At time t seconds, its displacement is x metres from a fixed point 0 on the line, and its acceleration is  $-\frac{1}{10}\sqrt{v}(1+\sqrt{v})$  where  $v\geq 0$  is its velocity. The body is initially at 0 with velocity V>0.

Show that 
$$t = 20 \log_e \left( \frac{1 + \sqrt{V}}{1 + \sqrt{v}} \right)$$

**MEDIUM** 

- A high speed train of mass m starts from rest and moves along a straight track. At time t hours, the distance travelled by the train from its starting point is x km, and its velocity is v km/h. The train is driven by a constant force F in the forward direction. The resistive force in the opposite direction is  $Kv^2$ , where K is a positive constant. The terminal velocity of the train is 300 km/h.
  - i Show that the equation of motion for the train is  $m\ddot{x} = F\left(1 \left(\frac{v}{300}\right)^2\right)$
  - ii Find, in terms of F and m, the time it takes the train to reach a velocity of 200 km/h.
- A 20 kg trolley is pushed with a force of 100 N. Friction causes a resistive force which is proportional to the square of the trolley's velocity.
  - i Show that  $\ddot{x} = 5 \frac{kv^2}{20}$  where k is a positive constant.
  - **ii** If the trolley is initially stationary at the origin, show that the distance travelled when its speed *V* is given by

$$x = \frac{10}{k} \ln \left( \frac{100}{100 - kV^2} \right)$$

- 5\*\* A landing aeroplane of mass m kg is brought to rest by the action of two retarding forces: a force of 4m Newtons due to the reverse thrust of the engines; and a force due to the brakes of  $\frac{mv^2}{40\,000}$  Newtons.
  - i Show that the aeroplane's equation of motion for its speed v at time t seconds after landing is

$$\dot{v} = -\frac{v^2 + 400^2}{40\,000}$$

- ii Assuming the aeroplane lands at a speed of U m/s, find an expression for the time it takes to come to rest.
- **iii** Show that, given a sufficiently long runway, no matter how fast its landing speed, it will always come to rest within approximately 2.6 minutes of landing.

<sup>\*\*</sup> Resultant force is given as a function of mass which makes our calculations easier but is not reflective of real life, as resistance is unrelated to mass.

A car, starting from rest, moves along a straight horizontal road. The car's engine produces a constant horizontal force of magnitude 4000 Newtons. At time t seconds, the speed of the car is v ms<sup>-1</sup> and a resistance force of magnitude 40v Newtons acts upon the car. The mass of the car is 1600 kg.

i Show that 
$$\frac{dv}{dt} = \frac{100 - v}{40}$$

ii Find the velocity of the car at time t.

- A supercar has a mass of 1000 kilograms and its engine generates a force of 1125 N. Its motion is opposed by a resistive force of  $\frac{v^2}{20}$  N.
  - a What is the maximum possible speed (terminal velocity) of the car on flat ground?
  - **b** If the car starts from rest, prove that the time taken to reach a speed of v, where v < 150, is given by  $t = \frac{200}{3} \ln \left( \frac{150 + v}{150 v} \right)$
  - **c** How does this formula help support the idea that the car can never reach the terminal velocity?

## **CHALLENGING**

- A fishing boat drifts with a current in a straight line across a fishing ground. The boat's velocity v, at time t after the start of this drift is given by  $v = b (b v_0)e^{-\alpha t}$ , where  $v_0$ ,  $\alpha$  and b are positive constants, and  $v_0 < b$ .
  - i Show that  $\frac{dv}{dt} = \alpha(b-v)$
  - ii The physical significance of  $v_0$  is that it represents the initial velocity of the boat. What is the physical significance of b?
  - iii Let x be the distance travelled by the boat from the start of the drift. Find x as a function of t. Hence show that

$$x = \frac{b}{\alpha} \log_{e} \left( \frac{b - v_0}{b - v} \right) + \frac{v^0 - v}{\alpha}$$

**iv** The initial velocity of the boat is  $\frac{b}{10}$ . How far has the boat drifted when  $v = \frac{b}{2}$ ?

- A particle of unit mass moves in a straight line against a resistance numerically equal to  $v+v^3$ , where v is its velocity. Initially the particle is at the origin and is traveling with velocity Q, where Q>0.
  - i Explain why  $\ddot{x} = -(v + v^3)$
  - ii Show that v is related to the displacement x by the formula  $x = \tan^{-1}\left[\frac{Q-v}{1+Qv}\right]$
  - iii Show that the time t which has elapsed when the particle is traveling with velocity V is given by  $t = \frac{1}{2}\log_e\left[\frac{Q^2(1+V^2)}{V^2(1+O^2)}\right]$

iv Find  $V^2$  as a function of t.

- A particle of mass one kg is moving in a straight line. It is initially at the origin and is travelling with velocity  $\sqrt{3}$  ms<sup>-1</sup>. The particle is moving against a resisting force  $v + v^3$ , where v is the velocity.
  - i Briefly explain why the acceleration of the particle is given by  $\frac{dv}{dt} = -(v + v^3)$
  - ii Show that the displacement x of the particle from the origin is given by  $x = \tan^{-1}\left(\frac{\sqrt{3} v}{1 + v\sqrt{3}}\right)$
  - iii Show that the time t which has elapsed when the particle is travelling with velocity V is given by  $t = \frac{1}{2} \log_e \left[ \frac{3(1+V^2)}{4V^2} \right]$
  - iv Find  $V^2$  as a function of t.
  - **v** Hence find the limiting position of the particle as  $t \to \infty$ .

1 
$$mv \frac{dv}{dx} = -mk(v + v^3)$$
$$\frac{dv}{dx} = -k(1 + v^2)$$
$$\frac{dx}{dv} = -\frac{1}{k} \times \frac{1}{1 + v^2}$$
$$x = -\frac{1}{k} \int \frac{1}{1 + v^2} dv$$

$$\frac{dv}{dt} = -\frac{1}{10}\sqrt{v}(1+\sqrt{v})$$

$$\frac{dt}{dv} = -\frac{10}{\sqrt{v}(1+\sqrt{v})}$$

$$t = -\int_{v}^{v} \frac{10}{\sqrt{v}(1+\sqrt{v})} dv$$

$$= 20 \int_{v}^{v} \frac{\frac{1}{2}v^{-\frac{1}{2}}}{1+\sqrt{v}} dv$$

$$= 20 \left[\ln(1+\sqrt{v})\right]_{v}^{v}$$

$$= 20 (\ln(1+\sqrt{v}) - \ln(1+\sqrt{v}))$$

$$= 20 \ln\left(\frac{1+\sqrt{v}}{1+\sqrt{v}}\right)$$

 $20\ddot{x} = 100 - kv^2$ 

3 The equation of motion is given by  $m\ddot{x} = F - kv^2$ At terminal velocity of 300 km/h  $\ddot{x} = 0$  $\therefore 0 = F - k \times 300^2$ The equation of motion is:  $m\ddot{x} = F - \frac{F}{300^2}v^2$ 

$$m\ddot{x} = F - \frac{F}{300^2}v^2$$
$$= F\left[1 - \left(\frac{v}{300}\right)^2\right]$$

 $m\ddot{x} = F \left[ 1 - \left( \frac{v}{300} \right)^2 \right]$  $\frac{dv}{dt} = \frac{F}{m} \left[ \frac{300^2 - v^2}{300^2} \right]$  $\frac{dt}{dv} = \frac{m}{F} \left( \frac{300^2}{300^2 - v^2} \right)$  $t = \frac{m}{F} \int_0^{200} \frac{300}{300^2 - v^2} dv$  $= \frac{300^2 m}{600 F} \int_0^{200} \left( \frac{1}{300 + v} + \frac{1}{300 - v} \right) dv$  $= \frac{150m}{F} \left[ \ln(300 + v) - \ln(300 - v) \right]^{200}$  $= \frac{150m}{F} \left[ \ln \frac{300 + v}{300 - v} \right]_{0}^{200}$  $=\frac{150m}{F}\left(\ln\frac{500}{100}-\ln\frac{300}{300}\right)$  $=\frac{150m}{F}\ln 5$  hours

$$\ddot{x} = 5 - \frac{kv^2}{20}$$

$$ii$$

$$v \frac{dv}{dx} = 5 - \frac{kv^2}{20}$$

$$\frac{dv}{dx} = \frac{100 - kv^2}{20v}$$

$$\frac{dx}{dv} = \frac{20v}{100 - kv^2}$$

$$x = \int_0^V \frac{20v}{100 - kv^2} dv$$

$$= -\frac{10}{k} \left[ \ln(100 - kv^2) \right]_0^V$$

$$= -\frac{10}{k} \left( \ln(100 - kV^2) - \ln 100 \right)$$

$$= \frac{10}{k} \ln\left(\frac{100}{100 - kV^2}\right)$$

i  

$$m\dot{v} = -\frac{mv^2}{40\ 000} - 4m$$

$$\dot{v} = -\frac{v^2 + 160\ 000}{40\ 000}$$

$$= -\frac{v^2 + 400^2}{40\ 000}$$

$$\begin{aligned} & \frac{\mathbf{ii}}{dv} \\ & \frac{dv}{dt} = -\frac{v^2 + 400^2}{40\,000} \\ & \frac{dt}{dv} = -\frac{40\,000}{v^2 + 400^2} \\ & t = -\int_{U}^{0} \frac{40\,000}{v^2 + 400^2} dv \\ & = 40\,000 \left[ \frac{1}{400} \tan^{-1} \frac{v}{400} \right]_{0}^{U} \\ & = 100 \left( \tan^{-1} \frac{U}{400} - 0 \right) \\ & = 100 \tan^{-1} \frac{U}{400} \, \mathrm{s} \end{aligned}$$

6

$$1600 \frac{dv}{dt} = 4000 - 40v$$
$$\frac{dv}{dt} = \frac{100 - v}{40} \text{ ms}^{-2}$$

$$\begin{aligned} \overline{dv} - \overline{100 - v} \\ t &= \int_0^v \frac{40}{100 - v} dv \\ &= -40 \left[ \ln(100 - v) \right]_0^v \\ -\frac{t}{40} &= \ln(100 - v) - \ln 100 \\ \ln 100 - \frac{t}{40} &= \ln(100 - v) \\ 100e^{-\frac{t}{40}} &= 100 - v \\ v &= 100 \left( 1 - e^{-\frac{t}{40}} \right) \, \text{ms}^{-1} \end{aligned}$$

## iii

As 
$$U \to \infty$$
  $\tan^{-1} \frac{U}{400} \to \frac{\pi}{2}$ 

 $\therefore t \to 100 \times \frac{\pi}{2} \approx 157 \text{ s} \approx 2.618 \text{ minutes}$ 

: The plane lands within approximately 2.6 minutes of landing regardless of speed.

7

$$1000\ddot{x} = 1125 - \frac{v^2}{20}$$

$$\ddot{x} = \frac{22500 - v^2}{20000}$$

Let  $\ddot{x} = 0$ ,  $\therefore 22500 - v_T^2 = 0 \rightarrow v_T = \sqrt{22500} = 150 \text{ ms}^{-1}$ 

h

$$\frac{dv}{dt} = \frac{22500 - v^2}{20000}$$

$$\frac{dt}{dv} = \frac{20000}{22500 - v^2}$$

$$t = \frac{200}{3} \int_0^v \left( \frac{1}{150 - v} + \frac{1}{150 + v} \right) dv$$

$$= \frac{200}{3} \left[ -\ln(150 - v) + \ln(150 + v) \right]_0^v$$

$$= \frac{200}{3} (-\ln(150 - v) + \ln(150 + v))$$

$$= \frac{200}{3} \ln\left( \frac{150 + v}{150 - v} \right)$$

C

The time taken to reach v=150 would be  $t=\frac{200}{3}\ln\left(\frac{150+150}{150-150}\right)=\frac{200}{3}\ln\left(\frac{300}{0}\right)$  which is undefined, which is an indicator that velocity can never reach terminal velocity (slope fields give a better explanation).

$$i \frac{dv}{dt} = \alpha(b - v_0)e^{-\alpha t}$$

$$= \alpha(b - (b - (b - v_0)e^{-\alpha t}))$$

$$= \alpha(b - v)$$

8

ii'b' is the speed of the current – the boat slowly approaches the speed of the current, as a limiting value.

iii
$$v \frac{dv}{dx} = \alpha(b - v)$$

$$\frac{dv}{dx} = \frac{\alpha(b - v)}{v}$$

$$\frac{dx}{dv} = \frac{1}{\alpha} \times \frac{v}{b - v}$$

$$x = \frac{1}{\alpha} \int_{v_0}^{v} \frac{v}{b - v} dv$$

$$= \frac{1}{\alpha} \int_{v_0}^{v} \frac{-(b - v) + b}{b - v} dv$$

$$= \frac{1}{\alpha} \int_{v_0}^{v} \left(-1 + \frac{b}{b - v}\right) dv$$

$$= \frac{1}{\alpha} \left[-v - b \ln(b - v)\right]_{v_0}^{v}$$

$$= \frac{1}{\alpha} \left((-v - b \ln(b - v)) - (-v_0 - b \ln(b - v_0))\right)$$

$$= \frac{1}{\alpha} \left(b \ln\left(\frac{b - v_0}{b - v}\right) + v_0 - v\right)$$

$$= \frac{b}{\alpha} \ln\left(\frac{b - v_0}{b - v}\right) + \frac{v_0 - v}{\alpha}$$

iv
$$x = \frac{b}{\alpha} \ln \left( \frac{b - \frac{b}{10}}{b - \frac{b}{2}} \right) + \frac{\frac{b}{10} - \frac{b}{2}}{\alpha}$$

$$= \frac{b}{\alpha} \ln \left( \frac{9}{\frac{1}{2}} \right) + \frac{b}{\alpha} \left( -\frac{2}{5} \right)$$

$$= \frac{b}{\alpha} \left( \ln \frac{9}{5} - \frac{2}{5} \right)$$

9 i
$$m\ddot{x} = -m(v + v^3)$$

$$\ddot{x} = -(v + v^3)$$

$$v \frac{dv}{dx} = -(v + v^3)$$

$$\frac{dv}{dx} = -(1 + v^2)$$

$$\frac{dx}{dv} = -\frac{1}{1 + v^2}$$

$$x = -\int_{Q}^{v} \frac{1}{1 + v^2} dv$$

$$= \left[ \tan^{-1} v \right]_{v}^{Q}$$

$$= \tan^{-1} Q - \tan^{-1} v$$

$$= \tan^{-1} \left( \frac{\tan(\tan^{-1} Q) - \tan(\tan^{-1} v)}{1 + (\tan(\tan^{-1} Q))(\tan(\tan^{-1} v))} \right]$$

$$= \tan^{-1} \left( \frac{Q - v}{1 + Qv} \right)$$

$$\begin{aligned} & \frac{dv}{dt} = -(v + v^3) \\ & \frac{dt}{dv} = -\frac{1}{v + v^3} \\ & t = -\int_Q^V \frac{1}{v + v^3} dv \\ & = \int_V^Q \left(\frac{1}{v} - \frac{v}{1 + v^2}\right) dv \\ & = \left[\ln v - \frac{1}{2}\ln(1 + v^2)\right]_V^Q \\ & = \left(\ln Q - \frac{1}{2}\ln(1 + Q^2)\right) \\ & - \left(\ln V - \frac{1}{2}\ln(1 + V^2)\right) \\ & = \left(\frac{1}{2}\ln Q^2 - \frac{1}{2}\ln(1 + Q^2)\right) \\ & - \left(\frac{1}{2}\ln V^2 - \frac{1}{2}\ln(1 + V^2)\right) \\ & = \frac{1}{2}\ln \frac{Q^2}{1 + Q^2} - \frac{1}{2}\ln \frac{V^2}{1 + V^2} \\ & = \frac{1}{2}\ln \left(\frac{Q^2(1 + V^2)}{V^2(1 + Q^2)}\right) \end{aligned}$$

iν

$$e^{2t} = \frac{Q^2(1+V^2)}{V^2(1+Q^2)}$$

$$V^2e^{2t}(1+Q^2) = Q^2 + Q^2V^2$$

$$V^2(e^{2t}(1+Q^2) - Q^2) = Q^2$$

$$V^2 = \frac{Q^2}{e^{2t} + e^{2t}Q^2 - Q^2}$$

10 i
$$m\ddot{x} = -(v + v^{3})$$

$$\ddot{x} = -(v + v^{3})$$

ii  

$$v \frac{dv}{dx} = -(v + v^3)$$

$$\frac{dv}{dx} = -(1 + v^2)$$

$$\frac{dx}{dv} = -\frac{1}{1 + v^2}$$

$$x = -\int_{\sqrt{3}}^{v} \frac{1}{1 + v^2} dv$$

$$= \left[ \tan^{-1} v \right]_{v}^{\sqrt{3}}$$

$$= \tan^{-1} \sqrt{3} - \tan^{-1} v$$

$$= \tan^{-1} \left( \tan(\tan^{-1} \sqrt{3}) - \tan(\tan^{-1} v) \right)$$

$$= \tan^{-1} \left( \frac{\tan(\tan^{-1} \sqrt{3}) + \tan(\tan^{-1} v)}{1 + \tan(\tan^{-1} \sqrt{3}) + \tan(\tan^{-1} v)} \right)$$

$$= \tan^{-1} \left( \frac{\sqrt{3} - v}{1 + \sqrt{3}v} \right)$$

$$\begin{split} & \frac{dv}{dt} = -(v + v^3) \\ & \frac{dt}{dv} = -\frac{1}{v + v^3} \\ & t = -\int_{\sqrt{3}}^{V} \frac{1}{v + v^3} dv \\ & = \int_{V}^{\sqrt{3}} \left(\frac{1}{v} - \frac{v}{1 + v^2}\right) dv \\ & = \left[\ln v - \frac{1}{2}\ln(1 + v^2)\right]_{V}^{\sqrt{3}} \\ & = \ln \sqrt{3} - \frac{1}{2}\ln 4 - \ln V + \frac{1}{2}\ln(1 + V^2) \\ & = \frac{1}{2}\ln 3 + \frac{1}{2}\ln(1 + V^2) - \frac{1}{2}\ln 4 - \frac{1}{2}\ln V^2 \\ & = \frac{1}{2}\ln\left(\frac{3(1 + V^2)}{4V^2}\right) \end{split}$$

iv 
$$e^{2t} = \frac{3(1+V^2)}{4V^2}$$
$$4V^2e^{2t} = 3+3V^2$$
$$V^2(4e^{2t}-3) = 3$$
$$V^2 = \frac{3}{4e^{2t}-3}$$

**v** as 
$$t \to \infty$$
  $e^{2t} \to \infty$   $\therefore V^2 \to 0$   $\therefore V \to 0$   $\therefore x \to \tan^{-1}\left(\frac{\sqrt{3}}{1}\right) = \frac{\pi}{3}$