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Illuminant maps analysis for image splicing detection

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Introduction

Digital images are easy to manipulate thanks to the availability of the **powerful editing software** and **sophisticated digital cameras**.

The development of methods for verifying **image authenticity** is a real need in forensics.

Purpose: to detect image splicing aimed at *deceiving* the viewer.



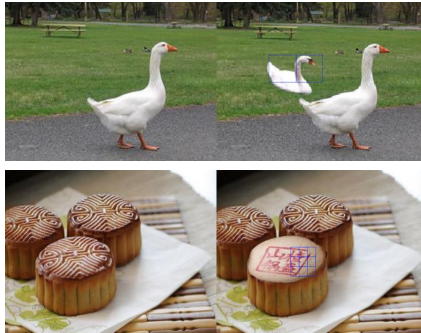
Forgery detection

Image splicing detection techniques are based on *inconsistencies*:

1. **Image resampling, copy-paste:** deduced from image metadata.
2. **Compression-based inconsistencies:** JPEG compression introduces blocking artifacts. Manufacturers of digital cameras and image processing software typically use different JPEG quantization tables.
3. **Neighboring pixels relationship inconsistencies:** when an image is spliced some artifacts can be created.
4. **Intrinsic image properties inconsistencies:** e.g. scene lights, shadows or perspective.

Lighting-based inconsistencies

Methods based on **lighting inconsistencies** are particularly *robust*: a perfect illumination adjustment in a image composition is very hard to achieve.



Lighting-based inconsistencies

These methods can be divided into two types of approaches:

1. **Object light source inconsistencies:** detected using *shadows*, *face geometry*, *generic object surfaces*.
2. **Illuminant colors inconsistencies:** assuming that a scene is lit by the same light source, all objects must have the same illuminant colors.

2.1 Specular dichromatic reflectance models

2.2 Illuminant Maps (IMs)



Illuminant Maps estimation

For the Illuminant Maps estimation, two different techniques are used:

1. A *statistical-based* approach using **Generalized Grayworld Estimate (GGE)** algorithm.
2. A *physics-based* approach using **Inverse-Intensity Chromaticity (IIC)** method.



Image



Illuminant map



Distance map

Generalized Greyworld Estimate (GGE)

Generalized Greyworld Estimate is proposed in [2] as a combination of the *Grey-World* and *Grey-Edge methods* aimed to evaluate **color constancy**.

The main premise behind it is that in a normal well color balanced photo, the **average** of all the colors is a neutral gray. Therefore, it assumes that the *Minkowski norm* of the derivative of the reflectance in a scene is **achromatic**.

$$ke^{n,p,\sigma} = \left(\int \left| \frac{\vartheta^n \mathbf{f}^\sigma(\mathbf{x})}{\vartheta \mathbf{x}^n} \right|^p d\mathbf{x} \right)^{\frac{1}{p}} \quad (1)$$

where \mathbf{x} denotes a pixel coordinate, k is a scale factor, $|\cdot|$ is the absolute value operator, ϑ the partial differential operator, \mathbf{f}^σ is the observed intensities at position \mathbf{x} , smoothed by a Gaussian kernel σ , p is the *Minkowski norm*, and n is the derivative order.

Generalized Greyworld Estimate (GGE)

The illuminant estimation of (1) is a framework for low-level based illuminant estimation based on three variables:

1. The order n of the image structure.
2. The Minkowski norm p which determines the relative weights of the multiple measurements from which the final illuminant color is estimated.
3. The scale of the local measurements as denoted by σ .

Advantages:

- the Minkowski norm of RGB values or derivatives can be computed *extremely fast*
- the method does not require an image database taken under a **known light source**

Inverse-Intensity Chromaticity (IIC)

Extension of the **dichromatic reflectance model**, which states that *the amount of light reflected from a point, \mathbf{x} , of a dielectric, non-uniform material is a linear combination of diffuse reflection and specular reflection.*

Given an image taken with a **RGB camera**, the response $I_c(\mathbf{x})$ for each color filter $c \in \{R, G, B\}$ is

$$I_c(\mathbf{x}) = m_d(\mathbf{x})B_c(\mathbf{x}) + m_s(\mathbf{x})G_c(\mathbf{x})$$

where m_d and m_s are geometric parameters of **diffuse and specular reflection**.

Let $\Delta_c(\mathbf{x})$ and $\Gamma_c(\mathbf{x})$ be the diffuse and **specular chromaticity**:

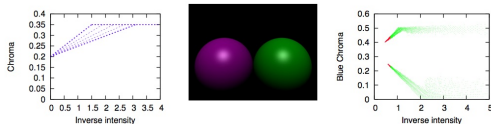
$$\Delta_c(\mathbf{x}) = \frac{B_c(\mathbf{x})}{\sum_{i \in \{R, G, B\}} B_i(\mathbf{x})} \text{ and } \Gamma_c(\mathbf{x}) = \frac{G_c(\mathbf{x})}{\sum_{i \in \{R, G, B\}} G_i(\mathbf{x})}$$

Inverse-Intensity Chromaticity (IIC)

In this model, the intensity $I_c(\mathbf{x})$ and the chromaticity $\sigma_c(\mathbf{x})$ of a color channel $c \in \{R, G, B\}$ at pixel position \mathbf{x} are related by

$$\sigma_c(\mathbf{x}) = p_c(\mathbf{x}) \frac{1}{\sum_{i \in \{R, G, B\}} I_i(\mathbf{x})} + \Gamma_c(\mathbf{x}) \quad (2)$$

where $p_c(\mathbf{x}) = w_d(\mathbf{x}) \sum_i B_i(\mathbf{x})(\Delta_c(\mathbf{x}) - \Gamma_c(\mathbf{x}))$

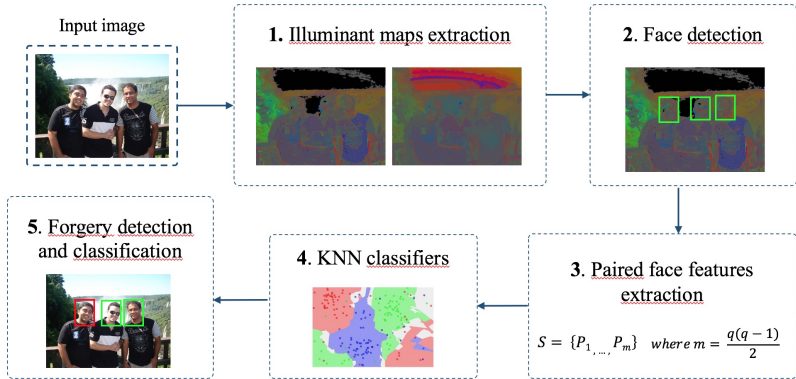


The *domain* of the line is determined by $\frac{1}{\sum_i I_i(\mathbf{x})}$ and the *range* is given by $0 \leq \sigma_c \leq 1$. Domain and range together form the **inverse-intensity chromaticity (IIC) space**.

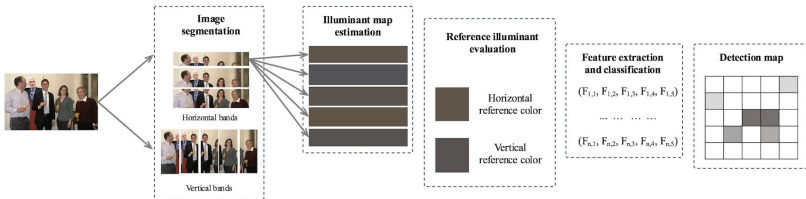
Proposed approach

- **Face forgery detection module:** specifically for detecting forgeries involving people. Based on the work presented by Carvalho et al. [1].
- **Regional forgery detection module:** image content independent. Based on the work presented by Fan et al. [2]

Face forgery detection module



Region forgery detection module



Experimental results - 1

Test case	Train	Test	Accuracy	AUC	F-Score
Test 1	DSO-1	DSO-1	0.84	0.90	0.78
Test 2	DSI-1	DSI-1	0.89	0.92	0.89
Test 3	DSO-1	DSI-1	0.59	0.58	0.64
Test 4	DSI-1	DSO-1	0.63	0.60	0.54

Tabella : Performance of face forgery detection module over paired faces using non-uniform weights.

Experimental results - 1

Test case	Train	RC	ACC	AUC	F-Score
Test 1	-	Median	0.49	0.32	0.25
Test 2	-	Global	0.52	0.40	0.27
Test 3	SplicedCC	Median	0.54	0.53	0.26
Test 4	SplicedCC	Global	0.57	0.57	0.31
Test 5	SplicedDSO	Median	0.53	0.50	0.27
Test 6	SplicedDSO	Global	0.61	0.63	0.33

Tabella : Performance of region forgery detection module.

Conclusions

- Two different approaches for forgery detection are presented: a face forgery detection module and a generic region forgery detection module.
- *Illuminant maps* are used to entail the interaction between the light source and the objects contained in a scene.
- Face module achieved most promising results, but it needs some *a priori* knowledge about the content of the image.
- **Future developments:** given that our method compares skin material, it is feasible to use additional body parts, such as arms and legs, to increase the detection and confidence of the method.
- Further improvements can be achieved when more advanced illuminant color estimators become available.

References

- [1] T. Carvalho, et al. *Illuminant-Based Transformed Spaces for Image Forensics*. IEEE Transactions on Information Forensics and Security 11.4 (2016): 720-733.
- [2] Y. Fan, P. Carrè, and C. Fernandez Maloigne. Image splicing detection with local illumination estimation. In Image Processing ICIP, 2015.
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- [4] C. Riess and E. Angelopoulou. 2010. *Scene illumination as an indicator of image manipulation*. In *Proceedings of the 12th international conference on Information hiding*, Berlin, Heidelberg, 66-80.