



## Robot Description & Illustration

## Field of Application

## Exposure to

robotsettings

## Robot Task Specification

## Robot Morphology

a      z      t

appearance

communication

movement

context

a (anthropomorphic),  
z (zoomorphic),  
t (technical)

## Degree of Robot Autonomy

**- +**

information  
acquisition

information  
analyses

decision-  
making

action  
implementation

## Human Role

### Communication Channel

input

## Proximity

temporal

physical

## Team Composition

$$N_H = N_R$$

$$N_H > N_R$$

$$N_H < N_R$$

output