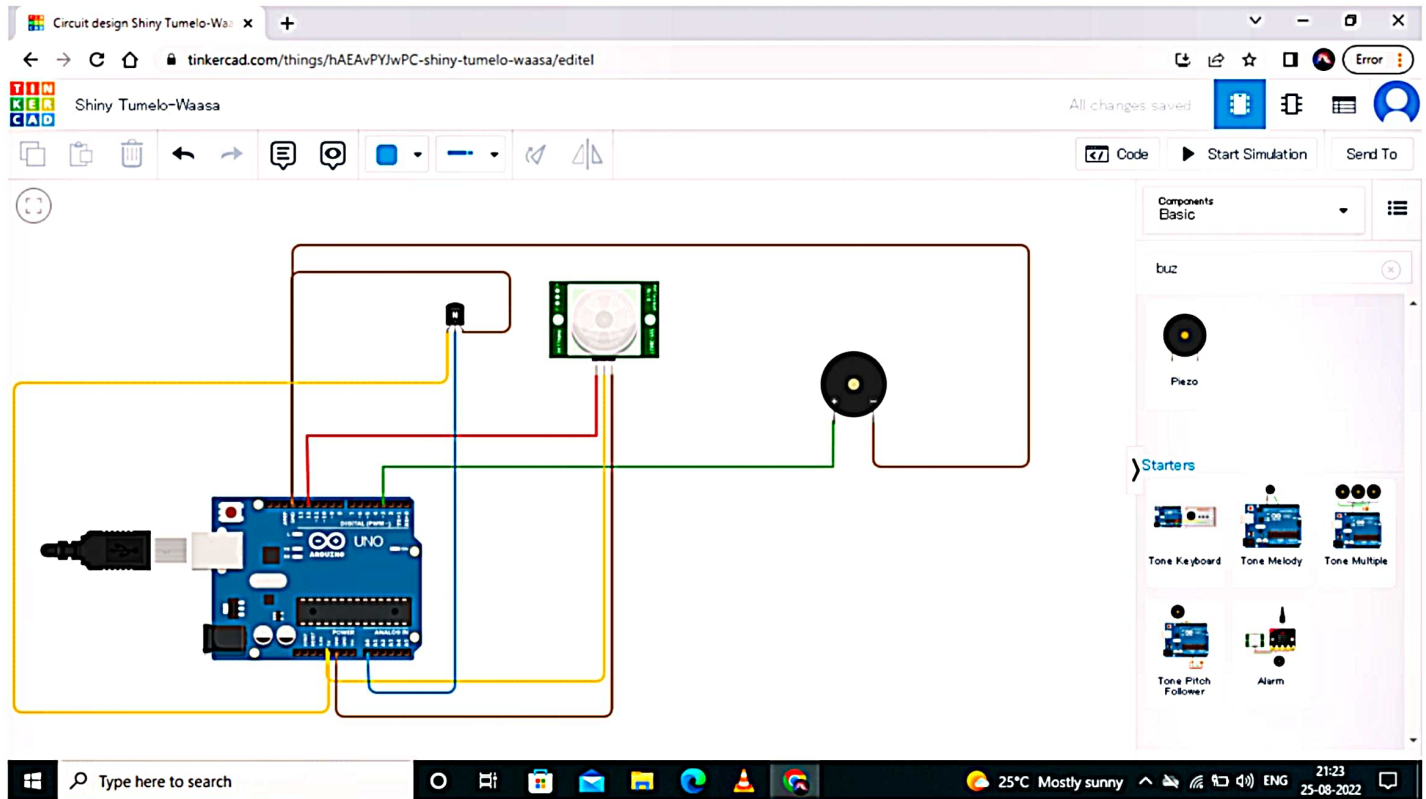
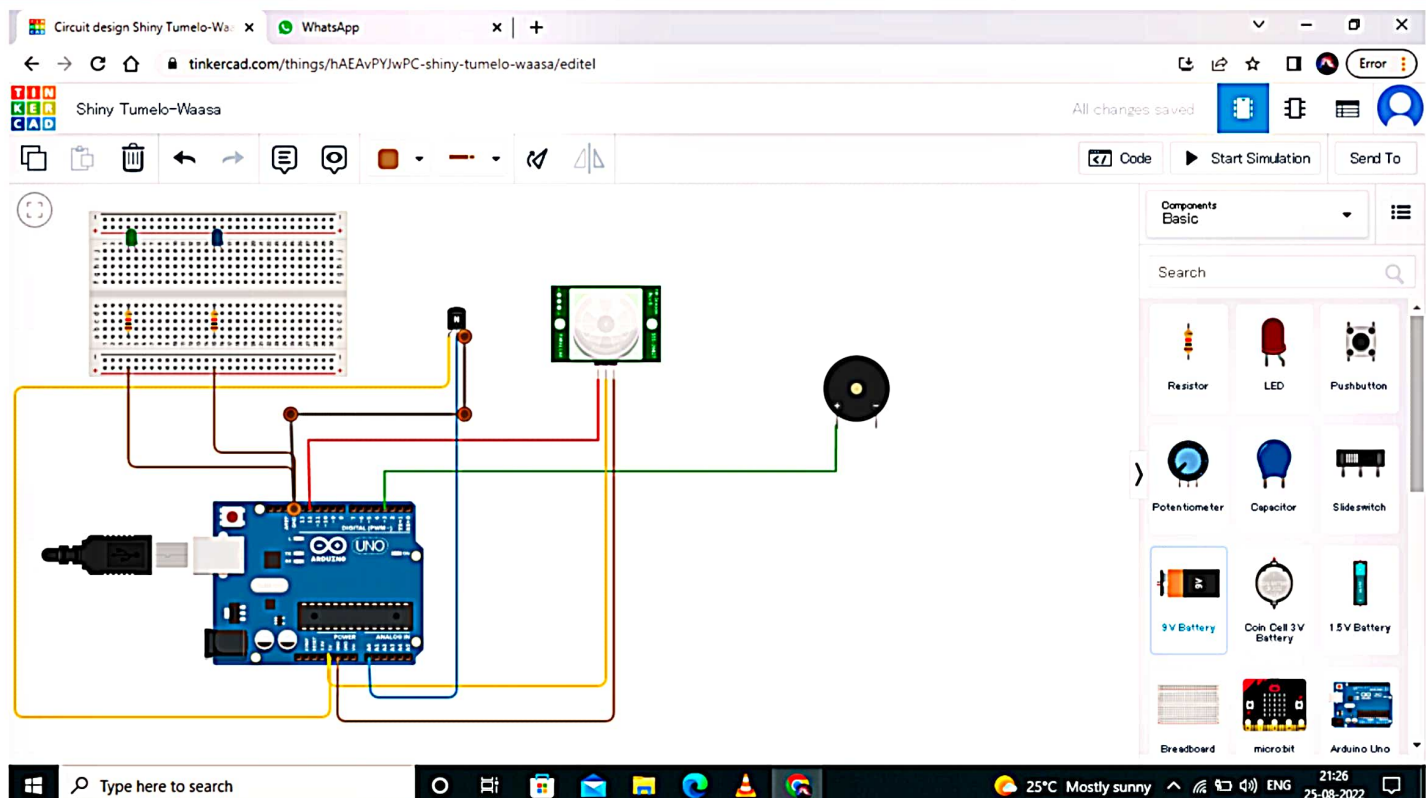


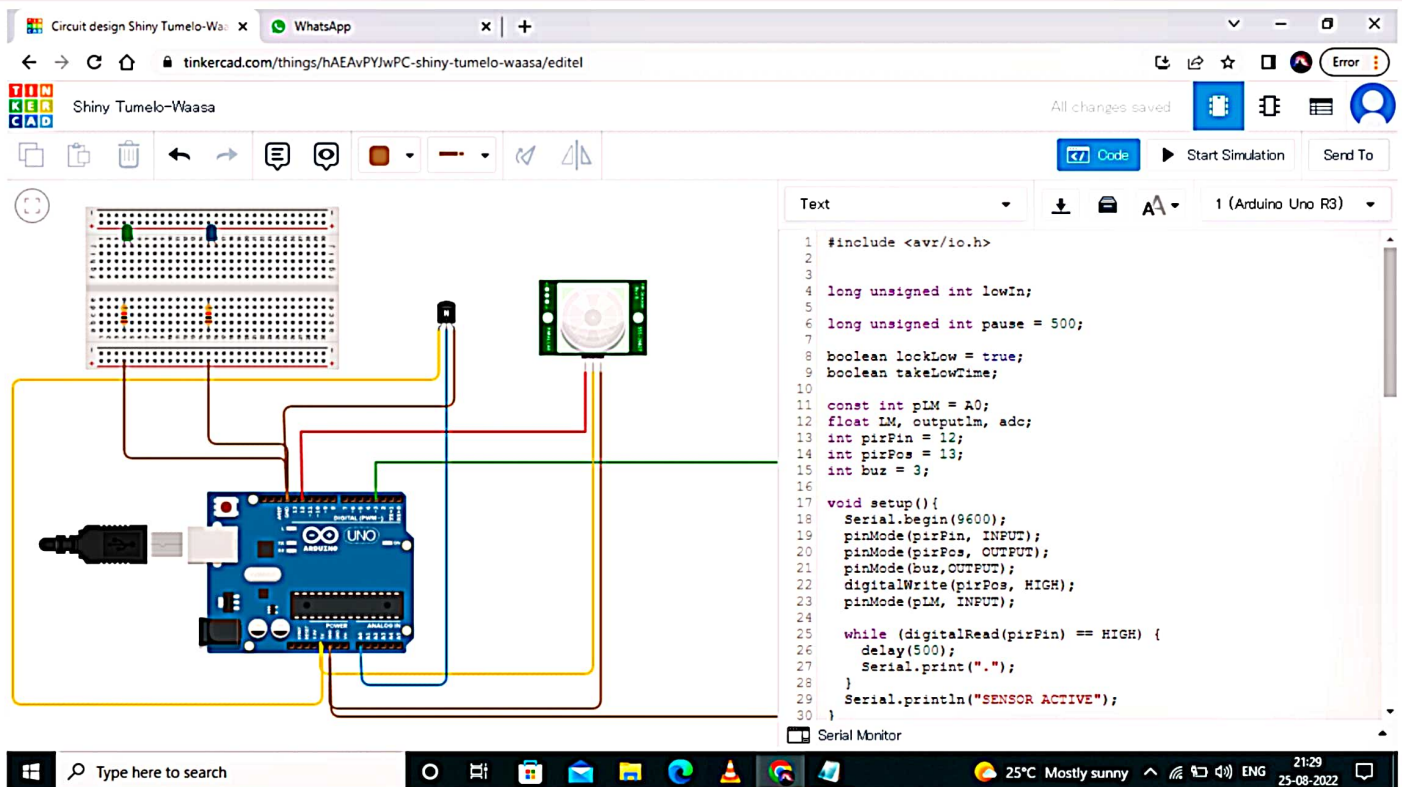
# Assignment 1: Make a smart home tinkercad, using 2 sensor, led, buzzer in simulate in a single code



## Using Tinkercad connecting the circuit



# Code inserting:



## Program code:

```
#include <avr/io.h>
```

```
long unsigned int lowIn;
```

```
long unsigned int pause = 500;
```

```
boolean lockLow = true;
boolean takeLowTime;
```

```
const int pLM = A0;
float LM, outputlm, adc;
int pirPin = 12;
int pirPos = 13;
int buz = 3;
```

```
void setup(){  
Serial.begin(9600);  
pinMode(pirPin, INPUT);  
pinMode(pirPos, OUTPUT);  
pinMode(buz,OUTPUT);  
digitalWrite(pirPos, HIGH);  
pinMode(pLM, INPUT);  
  
while (digitalRead(pirPin) ==  
HIGH) {  
delay(500);  
Serial.print(".");  
}  
Serial.println("SENSOR  
ACTIVE");  
}  
void lm35(){  
adc = analogRead(pLM);  
LM = adc / 2.0479;  
outputlm=adc*4.883;  
if (LM >= 10)  
{  
analogWrite(buz,50);  
  
Serial.println("Kecepatan=50");  
}  
if (LM >= 60)  
{  
analogWrite(buz,100);  
  
Serial.println("Kecepatan=100");  
}
```

```

}
void loop(){
if(digitalRead(pirPin) == HIGH){
  lm35();
  if(lockLow){

    lockLow = false;
    Serial.println("---");
    Serial.print("motion detected at ");
    Serial.print(millis()/1000);
    Serial.println(" sec");
    delay(50);
  }
  takeLowTime = true;
}

if(digitalRead(pirPin) == LOW){
  digitalWrite(buz,LOW);
  if(takeLowTime){
    lowIn = millis();
    takeLowTime = false;
  }

  if(!lockLow && millis() - lowIn >
  pause){

    lockLow = true;
    Serial.print("motion ended at ");
    Serial.print((millis() -
    pause)/1000);
    Serial.println(" sec");
    delay(50);
  }
  delay(1000);
  Serial.print(", LM: ");
  Serial.print(LM);
  Serial.println();
  delay(1000);
  Serial.print(", ADC: ");
  Serial.print(adc);
  Serial.println();
  delay(1000);
}

```

# Output:

