Single-Variable Calculus

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Preface

Before Newton ever formulated a description of universal gravitation or his famous laws of motion that changed physics forever, he did something arguably more important; changing mathematics forever too. I am talking, of course, about infinitesimal calculus.

Much like ourselves, Isaac Newton had to live through a deadly pandemic – the Bubonic plague. Much like today, universities were closed, students were sent home, and people were told to self-isolate. It was sometime around 1665, while he was in quarantine at his home in London, that he figured out a way to analyse the motion of objects using infinitesimals – that taking smaller and smaller increments of time give a more and more accurate calculation for an object's speed at a particular instant. He was thinking in terms of distance and speed at the time, but these same ideas would later be generalised to apply to all sorts of functions in mathematics and physics – what we now call differential calculus.

Incredibly, at around exactly the same time, a German mathematician, Gottfried Wilhelm Leibniz, was also thinking about and developing a different branch of calculus, and would soon arrive at the same fundamentals of calculus as Newton, completely independently!

Leibniz, working at Leipzig University (my own alma mater), was thinking about the area under an arbitrary curve, and how it can be approximated using smaller and smaller shapes. He was deriving what we now call integral calculus, and much of the notation we use comes directly from him.

Newton and Leibniz would later have many disputes over who came up with calculus first; both claiming one copied the other. It is somewhat surprising and hard to believe at first that two people would come up with such a novel idea at exactly the same time in history, but all retrospective analysis shows that this was indeed a coincidence. The invention (or discovery?) of this magical branch of mathematics was inevitable – and the world was ready for it in 1665.

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Not long after, the ideas of calculus would lead to the mathematical descriptions of gravity by Newton, and of electromagnetism by James Clerk Maxwell. These ideas sparked the first industrial revolution in England. They gave us the manufacturing capabilities to wage world wars. Electricity dramatically increased the quality of life for billions of people. A few centuries later, calculus put the first human being on the Moon and helps epidemiologists fight off the pandemics that plague us today.

Part I Differentiation

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Chapter 1

Derivatives

1.1 Geometric Interpretation

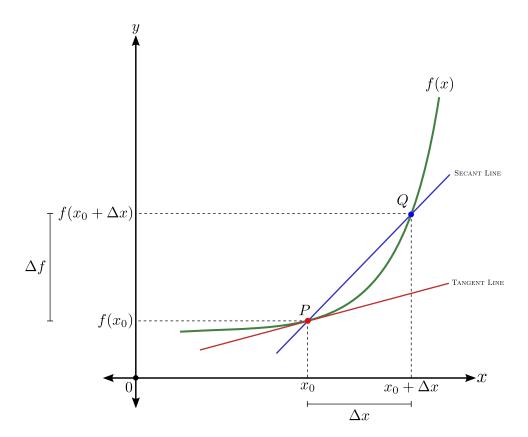


Figure 1.1: A function with secant and tangent lines

This is the graph of a function, f(x), and P and Q are points on that curve.

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Geometrically, the line \overline{PQ} is known as the *secant* line — a line that passes through at least two points on a curve. We can see that the slope of \overline{PQ} is $\frac{\Delta f}{\Delta x}$ and it is different than the slope (m) of the *tangent* line.

Definition 1.1. The derivative of f at the point x_0 , denoted $f'(x_0)$, is the slope of the tangent line to y = f(x) at the point P.

Although that is a pretty solid definition of a derivative, we need to be careful about how we think about the tangent line. It is not just any line that passes through P; it is the *limit* of the secant line as the distance between P and Q goes to 0.

Similarly, the slope of \overline{PQ} approaches the slope of the tangent line as $Q \to P$. We can imagine this by dragging Q along the path of the curve down to P and think about how that would change the slope of \overline{PQ} . In the *limiting* case, Q would be right next to P and the slope of \overline{PQ} would be identical to the slope of the tangent line. This idea of limits is mathematically denoted in the following way:

$$f'(x_0) = \lim_{\Delta x \to 0} \frac{\Delta f}{\Delta x} = \lim_{\Delta x \to 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x} = m$$
 (1.1)

Example 1.1. $f(x) = x^2$

We need to find the general equation of the slope of the tangent line at any point x on the curve of $y = x^2$ in terms of x.

From Equation 1.1, we have:

$$f'(x) = \lim_{\Delta x \to 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}$$

By plugging in the given function, we get:

$$f'(x) = \lim_{\Delta x \to 0} \frac{(x + \Delta x)^2 - x^2}{\Delta x}$$

$$= \lim_{\Delta x \to 0} \frac{x^2 + 2x\Delta x + (\Delta x)^2 - x^2}{\Delta x}$$

$$= \lim_{\Delta x \to 0} \frac{\Delta x (2x + \Delta x)}{\Delta x}$$

$$= \lim_{\Delta x \to 0} (2x + \Delta x)$$

$$= 2x$$

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Notations

Calculus, rather like English or any other language, was developed by several people. As a result, just as there are many ways to express the same thing in English, there are many notations for the derivative.

Since y = f(x), it is natural to write:

$$\Delta y = \Delta f = f(x) - f(x_0) = f(x_0 + \Delta x) - f(x_0)$$

If we divide both sides by Δx , we get two expressions for the difference quotient:

$$\frac{\Delta y}{\Delta x} = \frac{\Delta f}{\Delta x}$$

As $\Delta x \to 0$:

$$\frac{\Delta y}{\Delta x} \to \frac{dy}{dx} \Big|_{x=x_0}$$
 (Leibniz' Notation)
$$\frac{\Delta f}{\Delta x} \to f'(x_0)$$
 (Newton's Notation)

Other, equally valid notations for the derivative of a function f include:

$$f'(x) = f' = Df = \frac{df}{dx} = \frac{dy}{dx} = \frac{d}{dx}y = \frac{d}{dx}f(x)$$

The $dot\ notation$ (also introduced by Newton) is another convention used to denote derivatives with respect to t:

$$\frac{dy}{dt} = \dot{y}$$

As we have seen from Example 1.1, at any point x, the slope of the parabola, x^2 , is 2x. We can show that this can be generalised to the following formula:

$$\frac{d}{dx}(x^n) = nx^{n-1} \tag{1.2}$$

Example 1.2.

$$\frac{d}{dx}(x^3 + 3x^{10}) = (3)x^{3-1} + 3(10)x^{10-1}$$
$$= 3x^2 + 30x^9$$

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1.2 Physical Interpretation

When something is changing with respect some other thing, it can be useful to know fast it's changing at a particular instant.

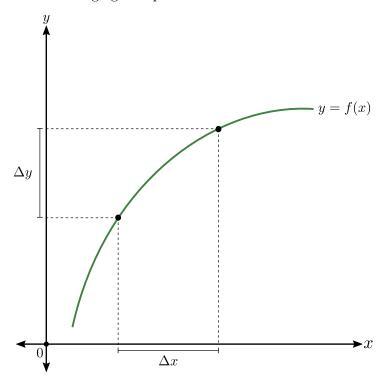


Figure 1.2: Graph of a function with Δx and Δy labelled

Speed is a perfect example of this. When you are moving, the distance (s) you travel changes with time (t). The rate of change of distance with respect to time (what we usually call speed), is a measure of how fast you're moving. Sometimes, it is useful to know what your average speed (\bar{v}) was over the whole journey, which is given by:

$$\bar{v} = \frac{\Delta s}{\Delta t}$$

Other times, your speed at a particular instant is more important – this is what is known as your *instantaneous* speed (v). You don't get a speeding ticket for having a high average speed over the whole journey; you get one for having a high speed at the *instant* you crossed a detection point. Similarly, the speed shown on a car's speedometer is not your average speed for the whole trip, it is your instantaneous speed at that particular instant. Derivates do a great job at finding these instantaneous rates of change:

$$v = \frac{ds}{dt}$$

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Example 1.3. The distance (s) travelled by any free-falling object over time (t) is, approximately:

$$s = 5t^2$$

In other words, after falling for one second, free-falling objects usually travel five meters. After two seconds, twenty meters, and so on.

If we drop a ball from top of a five-hundred-meter tall building, we know it will take about ten seconds to fall:

$$500 = 5t^2$$

$$\therefore t = 10 \,\mathrm{s}$$

Since we know $\Delta s = 500$ and $\Delta t = 10$, we can find the average speed of the ball over its entire fall:

$$\bar{v} = \frac{\Delta s}{\Delta t}$$
$$= \frac{500}{10}$$
$$= 50 \,\mathrm{m \, s}^{-1}$$

However, using differentiation, we can also find its instantaneous speed at any instant during its ten-second fall. We just need the derivative of s with respect to t:

$$v = \frac{ds}{dt}$$
$$= \frac{d}{dt} (5t^2)$$
$$= 10t$$

All we need to do now is plug in any value of t we want, and this derivative will tell us the speed of the ball at that particular instant in time. After, say, six seconds of falling $(t = 6 \,\mathrm{s})$, we know the ball was travelling at $v = 60 \,\mathrm{m \, s^{-1}}$.

Part II

Applications of Differentiation

Part III

Integration

Part IV

Techniques of Integration

Acknowledgments

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