

Problem 3 – Mathematics of Element Formulations showing analytical calculations

Part A) Derivation of Shape Functions for N_i where $i = 1, 2, 3, 4$

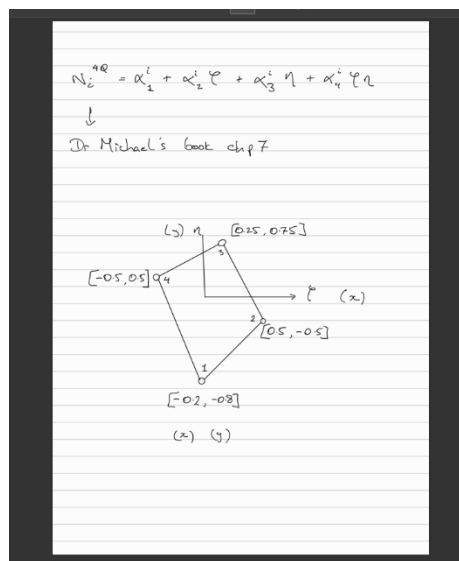


Figure 3.01: Derivation of Shape functions (page 1 of 9)

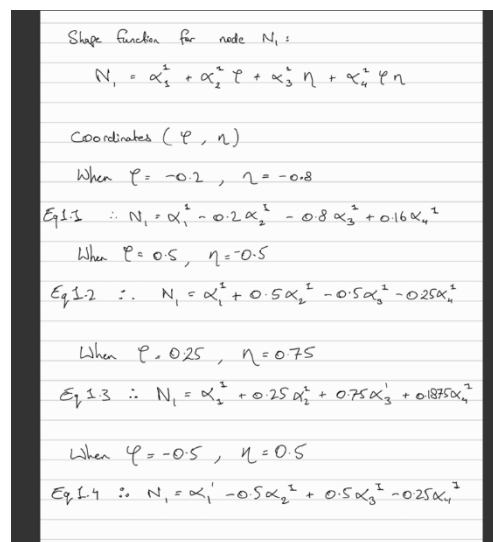


Figure 3.02: Derivation of Shape functions (page 2 of 9)

Eq 1.1 $1 = \alpha_1^1 - 0.2\alpha_2^1 - 0.8\alpha_3^1 + 0.16\alpha_4^1$

Eq 1.2 $0 = \alpha_1^1 + 0.5\alpha_2^1 - 0.5\alpha_3^1 - 0.25\alpha_4^1$

Eq 1.3 $0 = \alpha_1^1 + 0.25\alpha_2^1 + 0.75\alpha_3^1 + 0.1875\alpha_4^1$

Eq 1.4 $0 = \alpha_1^1 - 0.5\alpha_2^1 + 0.5\alpha_3^1 - 0.25\alpha_4^1$

Solved Simultaneously w/ Calculator

@ Node 1, $N_1 = 1$

Node 1 = 0 @ Nodes (2, 3, 4)

$\alpha_1^1 = 0.294985$, $\alpha_2^1 = -0.5162242$

$\alpha_3^1 = -0.5162242$, $\alpha_4^1 = 1.179941$

Figure 3.03: Derivation of Shape Functions (page 3 of 9)

Shape function for Node N_2

$N_2 = \alpha_1^2 + \alpha_2^2 \xi + \alpha_3^2 \eta + \alpha_4^2 \xi \eta$

When $\xi = -0.2$, $\eta = -0.8$

Eq 2.1 $\therefore N_2 = \alpha_1^2 - 0.2\alpha_2^2 - 0.8\alpha_3^2 + 0.16\alpha_4^2$

When $\xi = 0.5$, $\eta = -0.5$

Eq 2.2 $\therefore N_2 = \alpha_1^2 + 0.5\alpha_2^2 - 0.5\alpha_3^2 - 0.25\alpha_4^2$

When $\xi = 0.25$, $\eta = 0.75$

Eq 2.3 $\therefore N_2 = \alpha_1^2 + 0.25\alpha_2^2 + 0.75\alpha_3^2 + 0.1875\alpha_4^2$

When $\xi = -0.5$, $\eta = 0.5$

Eq 2.4 $\therefore N_2 = \alpha_1^2 - 0.5\alpha_2^2 + 0.5\alpha_3^2 - 0.25\alpha_4^2$

Figure 3.04: Derivation of Shape Functions (page 4 of 9)

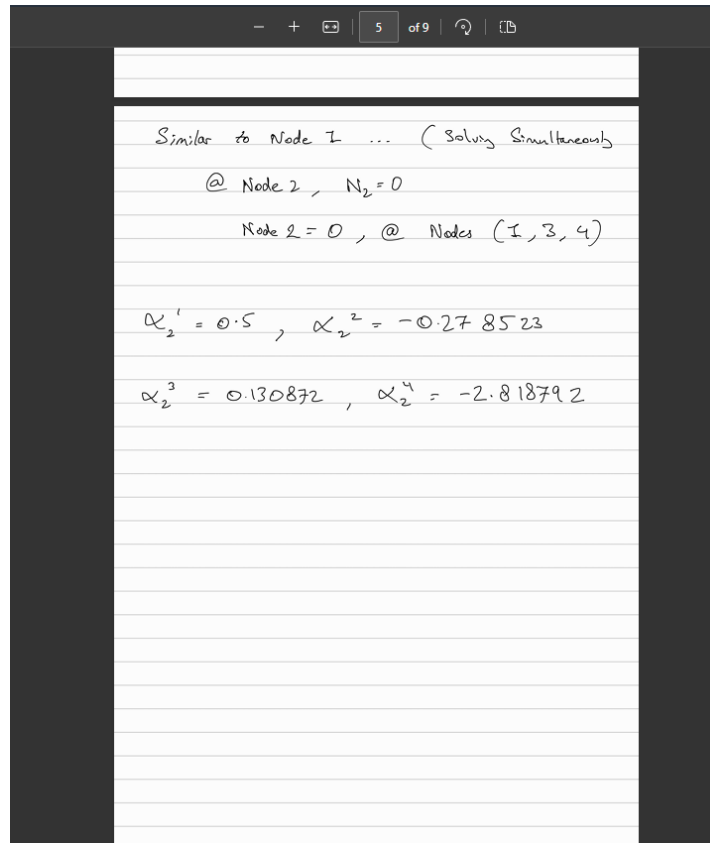


Figure 3.05: Derivation of Shape Functions (page 5 of 9)

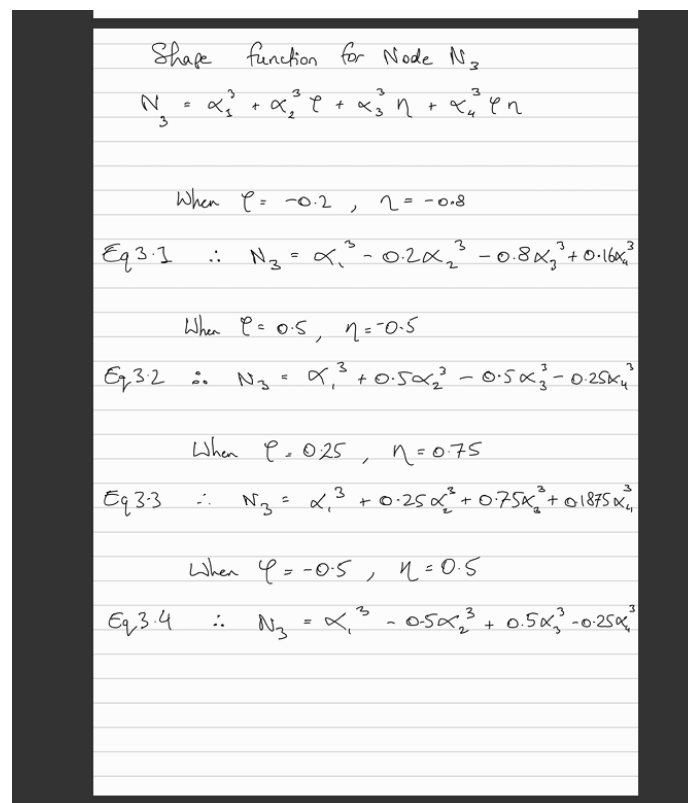


Figure 3.06: Derivation of Shape Functions (page 6 of 9)

Solving the 4 equations simultaneously
w/ Node N_3 being 1 @ node 3
and zero everywhere else

$$\alpha_1^3 = -1.016949, \quad \alpha_2^3 = 2.779661$$

$$\alpha_3^3 = 2.779661, \quad \alpha_4^3 = -4.067797$$

Figure 3.07: Derivation of Shape Functions (page 7 of 9)

Shape function for Node N_4

$$N_4 = \alpha_1^4 + \alpha_2^4 \xi + \alpha_3^4 \eta + \alpha_4^4 \xi \eta$$

Eq 4.1 $\therefore N_4 = \alpha_1^4 - 0.2\alpha_2^4 - 0.8\alpha_3^4 + 0.16\alpha_4^4$

Eq 4.2 $\therefore N_4 = \alpha_1^4 + 0.5\alpha_2^4 - 0.5\alpha_3^4 - 0.25\alpha_4^4$

Eq 4.3 $\therefore N_4 = \alpha_1^4 + 0.25\alpha_2^4 + 0.75\alpha_3^4 + 0.1875\alpha_4^4$

Eq 4.4 $\therefore N_4 = \alpha_1^4 - 0.5\alpha_2^4 + 0.5\alpha_3^4 - 0.25\alpha_4^4$

Solving the 4 equations simultaneously
w/ Node N_4 being 1 @ node 4
and zero everywhere else

$$\alpha_1^4 = 0.21976, \quad \alpha_2^4 = -0.759587$$

$$\alpha_3^4 = 0.240413, \quad \alpha_4^4 = -1.120944$$

Figure 3.08: Derivation of Shape Functions (page 8 of 9)

The final equations (shape functions)

$$N_i^{4Q} = \alpha_1^i + \alpha_2^i \xi + \alpha_3^i \eta + \alpha_4^i \xi \eta$$

$$N_1 = 0.295 - 0.516 \xi - 0.516 \eta + 1.180 \xi \eta$$

$$N_2 = 0.5 - 0.279 \xi + 0.131 \eta - 2.819 \xi \eta$$

$$N_3 = -1.017 + 2.780 \xi + 2.780 \eta - 4.068 \xi \eta$$

$$N_4 = 0.220 - 0.760 \xi + 0.240 \eta - 1.121 \xi \eta$$

Figure 3.09: Derivation of Shape functions (page 9 of 9)

Figures 3.01 to 3.09 show the step-by-step derivation of the shape functions.

Part B) Shape function plot

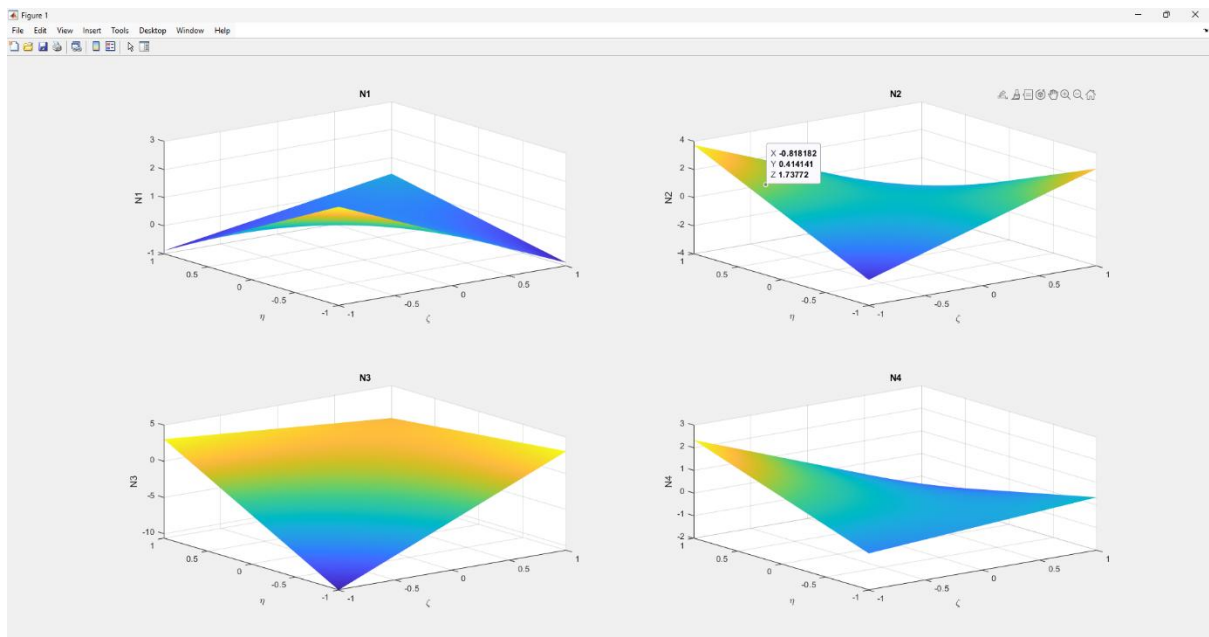


Figure 3.10: Shape Function plots

Part C) Derivation of Resulting Strain-Displacement Matrix, **B**

Strain-Displacement, B^e Matrix

$$\epsilon^e = \begin{bmatrix} \frac{\partial u^e}{\partial \xi} \\ \frac{\partial u^e}{\partial \eta} \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} \frac{\partial N_1^e}{\partial \xi} u_1^e + \frac{\partial N_2^e}{\partial \xi} u_2^e + \frac{\partial N_3^e}{\partial \xi} u_3^e + \frac{\partial N_4^e}{\partial \xi} u_4^e \\ \frac{\partial N_1^e}{\partial \eta} u_1^e + \frac{\partial N_2^e}{\partial \eta} u_2^e + \frac{\partial N_3^e}{\partial \eta} u_3^e + \frac{\partial N_4^e}{\partial \eta} u_4^e \end{bmatrix}$$

$$\Rightarrow \epsilon^e = \begin{bmatrix} \frac{\partial N_1^e}{\partial \xi} & \frac{\partial N_2^e}{\partial \xi} & \frac{\partial N_3^e}{\partial \xi} & \frac{\partial N_4^e}{\partial \xi} \\ \frac{\partial N_1^e}{\partial \eta} & \frac{\partial N_2^e}{\partial \eta} & \frac{\partial N_3^e}{\partial \eta} & \frac{\partial N_4^e}{\partial \eta} \end{bmatrix} \begin{bmatrix} u_1^e \\ u_2^e \\ u_3^e \\ u_4^e \end{bmatrix}$$

Figure 3.11: Derivation of B Matrix (page 1 of 4)

$$\begin{bmatrix} \frac{\partial N_1^e}{\partial \xi} & \frac{\partial N_2^e}{\partial \xi} & \frac{\partial N_3^e}{\partial \xi} & \frac{\partial N_4^e}{\partial \xi} \\ \frac{\partial N_1^e}{\partial \eta} & \frac{\partial N_2^e}{\partial \eta} & \frac{\partial N_3^e}{\partial \eta} & \frac{\partial N_4^e}{\partial \eta} \end{bmatrix} \begin{bmatrix} u_1^e \\ u_2^e \\ u_3^e \\ u_4^e \end{bmatrix}$$

B^e u^e

$$N_1 = 0.295 - 0.516 \xi - 0.516 \eta + 1.180 \xi \eta$$

$$N_2 = 0.5 - 0.279 \xi + 0.131 \eta - 2.819 \xi \eta$$

$$N_3 = -1.017 + 2.780 \xi - 2.780 \eta - 4.068 \xi \eta$$

$$N_4 = 0.220 - 0.760 \xi + 0.240 \eta - 1.121 \xi \eta$$

$$\frac{\partial N_1}{\partial \xi} = -0.516 + 1.180 \eta$$

$$\frac{\partial N_2}{\partial \xi} = -0.279 - 2.819 \eta$$

$$\frac{\partial N_3}{\partial \xi} = 2.780 - 4.068 \eta$$

$$\frac{\partial N_4}{\partial \xi} = -0.760 - 1.121 \eta$$

Figure 3.12: Derivation of B Matrix (page 2 of 4)

The image shows a digital notepad interface with a dark top bar containing navigation icons and a page indicator '14 of 15'. The notepad has two visible sections of lined paper. The top section contains four partial derivative equations with respect to φ . The bottom section contains four partial derivative equations with respect to η .

Top section (derivatives w.r.t. φ):

$$\frac{\partial N_1}{\partial \varphi} = -0.516 + 1.180\eta$$

$$\frac{\partial N_2}{\partial \varphi} = -0.279 - 2.819\eta$$

$$\frac{\partial N_3}{\partial \varphi} = 2.780 - 4.068\eta$$

$$\frac{\partial N_4}{\partial \varphi} = 0.760 - 1.121\eta$$

Bottom section (derivatives w.r.t. η):

$$\frac{\partial N_1}{\partial \eta} = -0.516 + 1.180\varphi$$

$$\frac{\partial N_2}{\partial \eta} = 0.131 - 2.819\varphi$$

$$\frac{\partial N_3}{\partial \eta} = 2.780 - 4.068\varphi$$

$$\frac{\partial N_4}{\partial \eta} = 0.240 - 1.121\varphi$$

Figure 3.13: Derivation of B Matrix (page 3 of 4)

$$\begin{bmatrix}
 -0.516 + 1.180\eta & -0.279 - 2.819\eta & 2.780 - 4.068\eta & 0.760 - 1.121\eta \\
 -0.516 + 1.180\psi & 0.131 - 2.819\psi & 2.780 - 4.068\psi & 0.240 - 1.121\psi
 \end{bmatrix}$$

B Matrix

Figure 3.14: Derivation of B Matrix (page 4 of 4)

Part D) Stiffness Matrix, K

Stiffness Matrix

$$K^e \Big|_{\text{Quad}} = \int B^T E B dV$$

$$\Rightarrow K^e \Big|_{\text{Quad}} = B^T E B A^e$$

$$B^T = \begin{bmatrix} -0.516 + 1.180\eta & -0.516 + 1.180\zeta \\ -0.279 - 2.819\eta & 0.131 - 2.819\zeta \\ 2.780 - 4.068\eta & 2.780 - 4.068\zeta \\ 0.760 - 1.121\eta & 0.240 - 1.121\zeta \end{bmatrix}$$

Figure 3.15: derivation of stiffness Matrix
(page 1 of 1)

```
untitled2 *  +
1  syms zeta eta A E real
2
3  E = 210e9
4
5
6  B = [
7      -0.516 + 1.180*eta, -0.279 - 2.819*eta, 2.780 - 4.068*eta, 0.760 - 1.121*eta;
8      -0.516 + 1.180*zeta, 0.131 - 2.819*zeta, 2.780 - 4.068*zeta, 0.240 - 1.121*zeta
9  ];
10
11 K = transpose(B)*E*B*A;
```

Figure 3.16: Matlab formulation of stiffness matrix, K