Geometric Algebra (GA)

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1 Documentation

Overview (high-level initial intros on youtube):

- *https://www.thestrangeloop.com*
- *https://www.youtube.com/@sudgylacmoe*
- *https://www.youtube.com/@bivector*

Sources:

- `https://projectivegeometricalgebra.org`
- `https://terathon.com/blog/poor-foundations-ga.html`
- `https://bivector.net`
- `https://www.youtube.com/@bivector`
- `https://www.youtube.com/@sudgylacmoe`
- `https://www.youtube.com/watch?v=ItGlUbFBFfc`
- `https://www.youtube.com/watch?v=v-WGO2ILMXA&t=1476s`

1.1 Introduction

The ga library is intended to make Geometric Algebra more accessible by providing functionality for numerical calculations required for simulation of physical systems.

It implements functionality for two-dimensional $(2d)$ and three-dimensional $(3d)$ spaces with Euclidean geometry. Currently it provides data types and operations for non-projective Euclidean geometry $(ega2d, ega3d)$ and projective Euclidean geometry $(pga2dp, pga3dp)$. The library handles multivectors and their components efficiently. It can be easily extended to provide functionality for handling spacetime algebra (STA) with limited effort.

The main library is a header only library in the ga folder which can be used by including either

```
#include ga/ga_ega.hpp // or
#include ga/ga_pga.hpp
```

and by making the corresponding namespaces accessible for use by stating

```
using namespace hd::ga;      // and either
using namespace hd::ga::ega; // or
using namespace hd::ga::pga;
```

in your application code. For a simple usage example please have a look either at `ga_test/src/ga_ega_test.cpp` or at `ga_test/src/ga_pga_test.cpp`.

All product expressions are generated by the file `ga_prdxpr/ga_prdxpr_main.cpp` and user input provided in the header files of the corresponding algebra. The generated coefficient expressions are used to fill-in the source code for geometric products, wedge and dot products or their regressive counterparts. If certain combinations are not yet implemented in the ga library they can easily be generated within `ga_prdxpr` as needed and then be added to the library.

The complement operation used in this library corresponds to the complement as defined in [Lengyel, 2024]. It is uniquely determined with respect to the outer product (not with respect to the geometric product as commonly used by many autors actively working on geometric algebra). This is helpful to generate consistent signs of expressions, operators, complements and duals. The left complement $\underline{u}$ is defined as $\underline{u} \wedge u = I_n$ and the right complement

$\bar{u}$ as $u \wedge \bar{u} = I_n$ with I_n as the pseudoscalar of the n-dimensional space modeled by the algebra.

The complement operation is used in turn to define a unique dualization operation that works for cases when the metric is non-degenerate as well as for cases where it is degenerate, like in projective geometric algebra. The right dual $A^\star$ is defined as $A^\star = \overline{GA}$, where A is an arbitrary multivector and G the extended metric. There is also a corresponding left dualization operation defined as $A_\star = \underline{GA}$. $\star$ is used as dualization operator (Hodge star). Relations to the geometric product $A^\star = A^\dagger I_n$ and $A_\star = I_n A^\dagger$ also exist with $\dagger$ as the reversion operation.

TODO: *fill in further introductory notes here*

1.2 Basic formulas

The following is provided for Euclidean algebra of two-dimensional space (*ega2d*) using an orthormal basis $\boldsymbol{e}_1$, $\boldsymbol{e}_2$:

$$(\boldsymbol{e}_1)^2 = \boldsymbol{e}_1^2 = +1, \text{ and } (\boldsymbol{e}_2)^2 = \boldsymbol{e}_2^2 = +1 \tag{1a}$$

$$s_{2d} = s\mathbf{1} \tag{1b}$$

$$v_{2d} = v_1\boldsymbol{e}_1 + v_2\boldsymbol{e}_2 \tag{1c}$$

$$ps_{2d} = ps\boldsymbol{e}_{12} = ps\mathbb{1} \tag{1d}$$

equation (1b) is the scalar part s_{2d}, equation (1c) contains the vector part v_{2d}, and equation (1d) contains the pseudoscalar part ps_{2d}. The index $2d$ is typically omitted when clear from context. Using these components the multivector of two-dimensional space M is defined as

$$M = s\mathbf{1} + v_1\boldsymbol{e}_1 + v_2\boldsymbol{e}_2 + ps\boldsymbol{e}_{12} \tag{2}$$

where equation (2) contains three parts: the scalar $s\mathbf{1}$ (basis element is the scalar $\mathbf{1}$; if $\mathbf{1}$ is not shown, it is implicitly assumed for scalar values), the vector v (basis elements $\boldsymbol{e}_1$ and $\boldsymbol{e}_2$) and the pseudoscalar part $ps\boldsymbol{e}_{12} = ps\mathbb{1}$ (basis element is $\boldsymbol{e}_{12}$, which is sometimes written as $\mathbb{1}$ to show its character as pseudoscalar of this space. It is a bivector in $2d$-Euclidean space).

For Euclidean algebra of three-dimensional space (*ega3d*) using an orthonormal basis $\boldsymbol{e}_1$, $\boldsymbol{e}_2$, $\boldsymbol{e}_3$ there are:

$$(\boldsymbol{e}_1)^2 = \boldsymbol{e}_1^2 = +1, (\boldsymbol{e}_2)^2 = \boldsymbol{e}_2^2 = +1, \text{ and } (\boldsymbol{e}_3)^2 = \boldsymbol{e}_3^2 = +1 \tag{3a}$$

$$s_{3d} = s\mathbf{1} \tag{3b}$$

$$v_{3d} = v_1\boldsymbol{e}_1 + v_2\boldsymbol{e}_2 + v_3\boldsymbol{e}_3 \tag{3c}$$

$$b_{3d} = b_1\boldsymbol{e}_{23} + b_2\boldsymbol{e}_{31} + b_3\boldsymbol{e}_{12} \tag{3d}$$

$$ps_{3d} = ps\boldsymbol{e}_{123} = ps\mathbb{1} \tag{3e}$$

equation (3b) is the scalar part s_{3d}, equation (3c) is the vector part v_{3d}, equation (3d) is the bivector part b_{3d}, and equation (3e) is the pseudoscalar part ps_{3d}. The index $3d$ is typically omitted when clear from context. Comparing to the $2d$-case it becomes obvious, that all parts depend on context, specifically on the dimensionality of the modeled space, and thus need to be defined and treated accordingly (*hint*: since C++ is a statically typed language those types need to be well-defined and distinguishable from each other). Using these components the multivector of three-dimensional space M is defined as

$$M = s\mathbf{1} + v_1\boldsymbol{e}_1 + v_2\boldsymbol{e}_2 + v_3\boldsymbol{e}_3 + b_1\boldsymbol{e}_{23} + b_2\boldsymbol{e}_{31} + b_3\boldsymbol{e}_{12} + ps\boldsymbol{e}_{123} \tag{4}$$

where equation (4) contains four parts: the scalar part $s\mathbf{1}$ (basis element is the scalar $\mathbf{1}$, the vector v (basis elements $\boldsymbol{e}_1$, $\boldsymbol{e}_2$ and $\boldsymbol{e}_3$), the bivector b (basis elements $\boldsymbol{e}_{23}$, $\boldsymbol{e}_{31}$ and $\boldsymbol{e}_{12}$) and the pseudoscalar part $ps\boldsymbol{e}_{123} = ps\mathbb{1}$ (basis element is $\boldsymbol{e}_{123}$, which is sometimes written as $\mathbb{1}$ to show its character as pseudoscalar of this space. It is a trivector in $3d$-Euclidean space).

TODO: *fill in basic product definitions of ega2d and ega3d here*

TODO: *fill in pga2d and pga3d definitions here*

The inner product between multivectors A and B is defined as

$$A \bullet B = A^T G B \tag{5}$$

with G as the extended metric and matrix multiplication on the right hand side. It satisfies the identity

$$A \bullet B = \langle A \mathbin{\text{⟑}} \tilde{B} \rangle_0 = \langle B \mathbin{\text{⟑}} \tilde{A} \rangle_0 \tag{6}$$

where ⟑ within the grade projection operator $\langle\rangle_k$ for grade k stands for the geometric product. The norm of a multivector A is defined as

$$\|A\| = \sqrt{A \bullet A} \tag{7}$$

with a positive argument under the square root due to the definition of the inner product.

The contraction is explicitly defined as

$$A \rfloor B = A_\star \vee B \tag{8a}$$
$$A \lfloor B = A \vee B^\star \tag{8b}$$

with $\star$ denoting the Hodge dual with is formed by the respective complement operation (in spaces of even dimension the left or right complement respectively, and in spaces of uneven dimension the complement function regardless of the side of the operand). For blades A and B, they satisfy

$$A \rfloor B = \langle B \tilde{A} \rangle_{gr(B)-gr(A)} \tag{9a}$$
$$A \lfloor B = \langle \tilde{B} A \rangle_{gr(A)-gr(B)} \tag{9b}$$

and fulfill the requirement that $A \rfloor B = A \lfloor B = A \bullet B$ whenever A and B have the same grade. In this case the contractions reduce to the inner product.

The geometric product between and vector v and a blade B is defined in terms of the interior and exterior products, i.e. the right contraction $\lfloor$, the left contraction $\rfloor$ and wedge product $\wedge$ as follows:

$$a \curlywedge B = B \lfloor a + a \wedge B \tag{10a}$$

$$B \curlywedge a = a \rfloor B + B \wedge a \tag{10b}$$

$a = a_\parallel + a_\perp$ can be decomposed into parts $a_\parallel$ parallel to the k-blade B and $a_\perp$ perpendicular to B. For equation (10a): $B \lfloor a$ is a $(k-1)$-blade. If $a_\parallel \neq 0$ then $B \lfloor a$ represents a subspace of B. $a \wedge B$ is a $(k+1)$-blade. If $a_\perp \neq 0$ then $a \wedge B$ represents $\mathrm{span}(a, B)$.
For arguments of equal grade the contractions reduce to the dot product $\cdot$, so that one can write specifically for two vectors a and b:

$$a \curlywedge b = a \cdot b + a \wedge b \tag{11}$$

Text with a norm $\|x\|$ and an indexed norm as $\|u\|_\bullet$ and $\|u\|_\circ$.

$\boldsymbol{e}_1$, $\boldsymbol{e}_1$, $\boldsymbol{e}_{123}$

TODO: *fill in further basic formulas here*

1.3 Literature

References

[Lengyel, 2024] Lengyel, E. (2024). *Projective Geometric Algebra Illuminated.* Terathon Software LLC.