Visualizaciones estáticas

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```
import pandas as pd
import numpy as np
import pydicom
from pydicom.pixel_data_handlers.util import apply_voi_lut
import os
import matplotlib.pyplot as plt
import matplotlib.animation as animation
from scipy import ndimage
import torch
import torch.nn as nn
import torchvision.transforms as transforms
import torchvision.models as models
from torch.utils.data import DataLoader, TensorDataset
import torch.optim as optim
import cv2
from PIL import Image
from zipfile import ZipFile
from torchvision import transforms
import torch.optim as optim
from torch.utils.tensorboard import SummaryWriter
import torch
import torch.nn as nn
from efficientnet_pytorch import EfficientNet
from tqdm import tqdm
import torch.nn.functional as F
from sklearn.decomposition import PCA
from sklearn.model_selection import train_test_split
from sklearn.metrics import precision_score, f1_score
```

```
import torch.nn as nn
import torch.optim as optim
import torchvision
import torchvision.transforms as transforms
import numpy as np
import pandas as pd
import os
from sklearn.metrics import precision_score, f1_score
```

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```
import matplotlib.pyplot as plt
from sklearn.model_selection import train_test_split
from torch.utils.tensorboard import SummaryWriter
from tqdm import tqdm
import seaborn as sns
```

```
from sklearn.metrics import confusion_matrix
from sklearn.metrics import multilabel_confusion_matrix
```

```
if torch.cuda.is_available():
    print('GPU está disponible')
else:
    print('No se encontró GPU, usando CPU')
```

GPU está disponible

```
def get_metrics(matrix):
    precision = []
    recall = []
    f1 = []
    tp = matrix[0][0]
    fp = matrix[1][0]
    fn = matrix[1][0]
    tn = matrix[1][1]
    precision = tp / (tp + fp)
    recall = tp / (tp + fn)
    f1 = 2 * (precision * recall) / (precision + recall)
    accuracy = (tp + tn) / (tp + tn + fp + fn)
    return accuracy, recall, f1
```

3D CNN

```
class Simple3DCNN(nn.Module):
    def __init__(self, num_classes):
        super(Simple3DCNN, self).__init__()

# Capa 3D Conv1

self.conv1 = nn.Conv3d(in_channels=1, out_channels=32, kernel_size=3, padding=1)
    self.relu1 = nn.ReLU()
    self.pool1 = nn.MaxPool3d(kernel_size=2, stride=2)

# Capa 3D Conv2

self.conv2 = nn.Conv3d(in_channels=32, out_channels=64, kernel_size=3, padding=1)
    self.relu2 = nn.ReLU()
    self.pool2 = nn.MaxPool3d(kernel_size=2, stride=2)

#Forzar dimensionalidad
```

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```
self.fce = nn.Linear(4800, 2400) # (64 * 75, 64*75/2)
    self.relue1 = nn.ReLU()
    self.fce2 = nn.Linear(2400, 240)
    self.relue2 = nn.ReLU()
    self.fce3 = nn.Linear(240, 128)
    self.relue3 = nn.ReLU()
    self.fce4 = nn.Linear(128, 1)
    # Capa completamente conectada
    self.fc1 = nn.Linear(64 * 4 * 4 * 4, 128)
    self.relu3 = nn.ReLU()
    self.fc2 = nn.Linear(128, 7)
    self.softmax = nn.Softmax(dim=1)
def forward(self, x):
   x = self.conv1(x)
    x = self.relu1(x)
   x = self.pool1(x)
   x = self.conv2(x)
   x = self.relu2(x)
    x = self.pool2(x)
    # forzar dimensionalidad
    x = x.view(-1, 64 * 75)
   x = self.fce(x)
   x = self.relue1(x)
   x = self.fce2(x)
   x = self.relue2(x)
   x = self.fce3(x)
   x = self.relue3(x)
    x = self.fce4(x)
   x = x.view(-1, 64 * 4 * 4 * 4)
   x = self.fc1(x)
    x = self.relu3(x)
   x = self.fc2(x)
    x = self.softmax(x)
    return x
```

```
#Cargar datos

class ImageDataGenerator3D:
    def __init__(self, volumes_ruta, csv, max_UID):
        self.volumes_ruta = volumes_ruta
        self.max_UID = max_UID
```

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```
self.current UID = 0
    self.names = []
    self.df = csv
    self.read volumes path()
def read_volumes_path(self):
    ruta_carpeta = self.volumes_ruta
    if os.path.exists(ruta_carpeta) and os.path.isdir(ruta_carpeta):
        objetos = os.listdir(ruta carpeta)
        for objeto in objetos:
            objeto_ruta = os.path.join(ruta_carpeta, objeto)
            self.names.append(objeto ruta)
def reset_idx(self):
    self.current_UID = 0
def get next ruta(self):
    next_name = 'volumes/' + self.df.iloc[self.current_UID]['StudyInstanceUID'] + '.npy'
    return next_name
def __iter__(self):
    return self
def next (self):
    if self.current UID >= self.max UID:
        # print("No hay mas datos")
        self.current_UID = 0
        raise StopIteration()
    else:
        # Cargar el volumen
        name = self.get_next_ruta()
        volume = np.load(name)
        #volume.resize((256, 256, 256))
        #label = [float(value) for value in self.df.iloc[self.current_UID][['C1', 'C2', 'C3',
        label = self.df.iloc[self.current_UID][['C1', 'C2', 'C3', 'C4', 'C5', 'C6', 'C7']].tol
        # Incrementar el UID
        self.current UID += 1
        # Devolver el volumen
        return volume, label
def len (self):
    # Devuelve la longitud total del generador
    return self.max UID
```

```
num_classes = 7
```

```
model3D = Simple3DCNN(num_classes)
model3D.load_state_dict(torch.load('modelo_entrenado3D.pth'))
```

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<all keys matched successfully>

```
model3D.to('cuda')
Simple3DCNN(
  (conv1): Conv3d(1, 32, kernel_size=(3, 3, 3), stride=(1, 1, 1), padding=(1, 1, 1))
  (relu1): ReLU()
  (pool1): MaxPool3d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
  (conv2): Conv3d(32, 64, kernel_size=(3, 3, 3), stride=(1, 1, 1), padding=(1, 1, 1))
  (relu2): ReLU()
  (pool2): MaxPool3d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
  (fce): Linear(in_features=4800, out_features=2400, bias=True)
  (relue1): ReLU()
  (fce2): Linear(in_features=2400, out_features=240, bias=True)
  (relue2): ReLU()
  (fce3): Linear(in_features=240, out_features=128, bias=True)
  (relue3): ReLU()
  (fce4): Linear(in_features=128, out_features=1, bias=True)
  (fc1): Linear(in_features=4096, out_features=128, bias=True)
  (relu3): ReLU()
  (fc2): Linear(in_features=128, out_features=7, bias=True)
  (softmax): Softmax(dim=1)
)
data = pd.read_csv('train_filtrado_volumes.csv')
data = data.iloc[0:600]
train_data, test_data = train_test_split(data, test_size=0.2, random_state=42)
data_gen = ImageDataGenerator3D('volumes', train_data, len(train_data))
test data gen = ImageDataGenerator3D('volumes', test data, len(test data))
accumulated cm = np.zeros((7,2,2), dtype=int)
def calculate_matrix(predic_labels, labels):
    for i in range(len(labels)):
         if predic_labels[i] == 1 and labels[i] == 1:
             accumulated_cm[i][0][0] += 1
         elif predic_labels[i] == 1 and labels[i] == 0:
             accumulated_cm[i][0][1] += 1
         elif predic labels[i] == 0 and labels[i] == 1:
             accumulated_cm[i][1][0] += 1
         elif predic labels[i] == 0 and labels[i] == 0:
            accumulated_cm[i][1][1] += 1
```

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```
model3D.eval()
accuracy_iter = 0
test_accuracy = []
accuracy total = 0
confusion_matrices = []
with torch.no grad():
    for i, (volume, label) in tqdm(enumerate(test_data_gen), total=len(test_data_gen)):
        image tensor = torch.from numpy(volume).unsqueeze(0).float().to('cuda')
        label tensor = torch.tensor(label).unsqueeze(0).float().to('cuda')
        predictions = model3D(image_tensor)
        threshold = 0.5
        predicted_labels = (predictions > threshold).float() # 1 si es mayor al umbral, 0 de lo
        predicted labels np = predicted labels.cpu().numpy()[0]
        labels_np = label_tensor.cpu().numpy()[0]
        # confusion matrices.append(multilabel confusion matrix(label, predicted labels np))
        accuracy per class = (predicted labels np == label).mean(axis=0)
        calculate_matrix(predicted_labels_np, labels_np)
        # Calcular la precisión global (promedio de la precisión por clase)
        number of 1 = np.count nonzero(label)
        intersection = np.logical and(predicted labels np, label)
        intersection_1 = np.count_nonzero(intersection)
        accuracy iter = 0
        if number_of_1 == 0:
            if intersection_1 > number_of_1:
                accuracy_iter = 0
            elif intersection_1 == 0:
                accuracy_iter = 1
        else:
            accuracy_iter = intersection_1 / number_of_1
        accuracy_total += accuracy_iter
        test_accuracy.append(accuracy_iter)
```

100%| 1.16s/it]

```
# for i, confusion_matrix in enumerate(confusion_matrices):
# print(f"Matriz de Confusión para Clase {i}:")
# print(confusion_matrix)
for index,matriz in enumerate(accumulated_cm):
    accuracy, recall, f1 = get_metrics(matriz)
    print("Accuracy:", accuracy)
    print("Recall:", recall)
    print("F1:", f1)
    plt.figure(figsize=(5,5))
    blue_palette = sns.color_palette("Blues")
```

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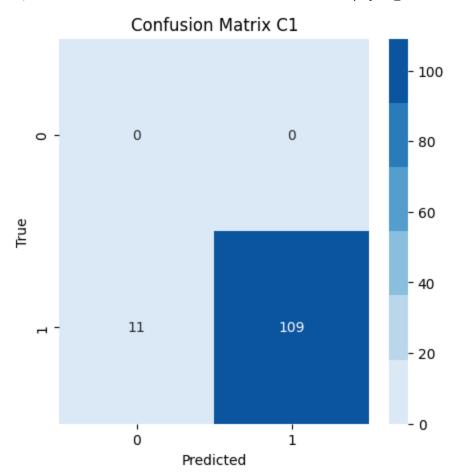
plt.xlabel('Predicted')
plt.ylabel('True')

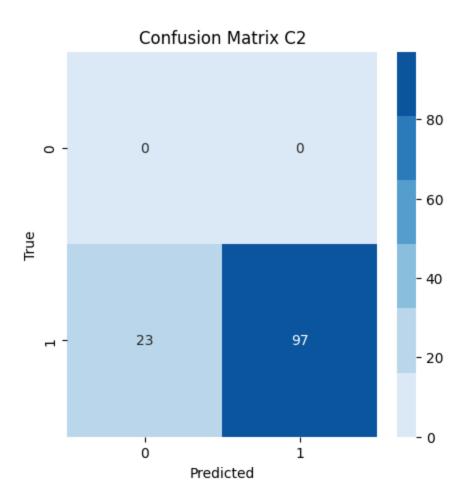
F1: 0.28776978417266186

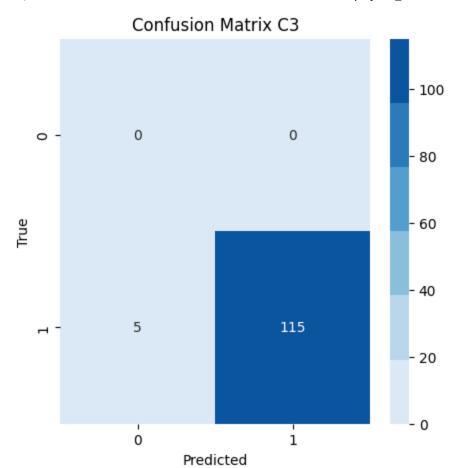
sns.heatmap(matriz,cmap=blue palette, annot=True, fmt="d")

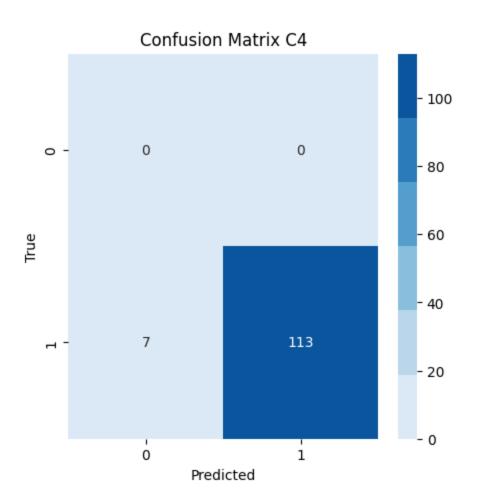
```
plt.title(f'Confusion Matrix C{index+1}')
 plt.show()
 print(accumulated_cm)
C:\Users\Daniel\AppData\Local\Temp\ipykernel_28148\2099467119.py:9: RuntimeWarning: invalid value
encountered in scalar divide
  precision = tp / (tp + fp)
C:\Users\Daniel\AppData\Local\Temp\ipykernel_28148\2099467119.py:9: RuntimeWarning: invalid value
encountered in scalar divide
  precision = tp / (tp + fp)
C:\Users\Daniel\AppData\Local\Temp\ipykernel_28148\2099467119.py:9: RuntimeWarning: invalid value
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C:\Users\Daniel\AppData\Local\Temp\ipykernel_28148\2099467119.py:9: RuntimeWarning: invalid value
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C:\Users\Daniel\AppData\Local\Temp\ipykernel_28148\2099467119.py:9: RuntimeWarning: invalid value
encountered in scalar divide
  precision = tp / (tp + fp)
C:\Users\Daniel\AppData\Local\Temp\ipykernel_28148\2099467119.py:9: RuntimeWarning: invalid value
encountered in scalar divide
  precision = tp / (tp + fp)
Accuracy: 0.9083333333333333
Recall: 0.0
F1: nan
Accuracy: 0.8083333333333333
Recall: 0.0
F1: nan
Accuracy: 0.9583333333333334
Recall: 0.0
F1: nan
Accuracy: 0.9416666666666667
Recall: 0.0
F1: nan
Accuracy: 0.93333333333333333
Recall: 0.0
F1: nan
Accuracy: 0.88333333333333333
Recall: 0.0
F1: nan
Accuracy: 0.175
Recall: 1.0
```

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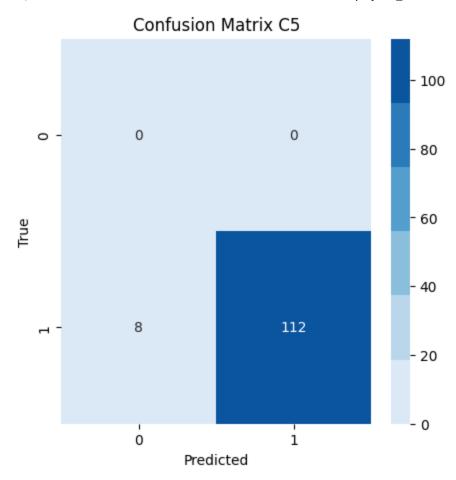


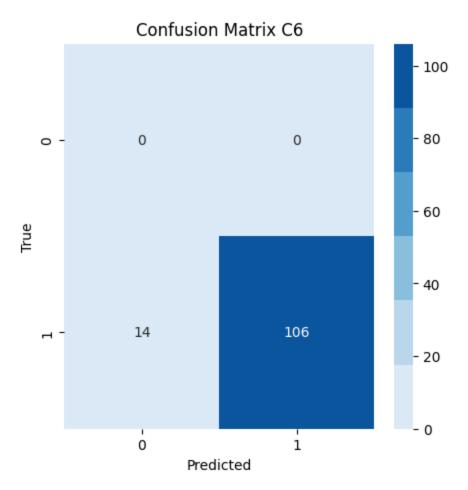




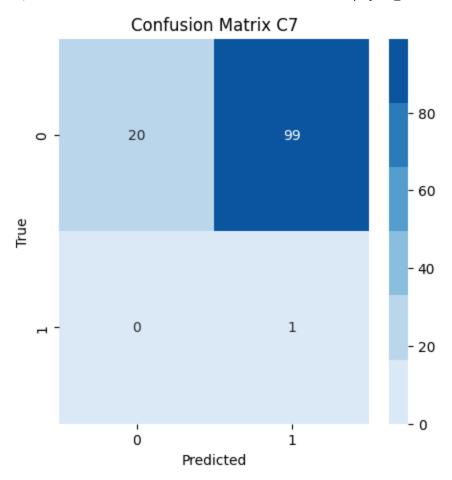


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```
[ 11 109]]
[[ 0 0]
[ 23 97]]
[[ 0 0]
[ 5 115]]
```

[[[0 0]]

[7 113]] [[0 0]

[8 112]] [[0 0]

[14 106]]

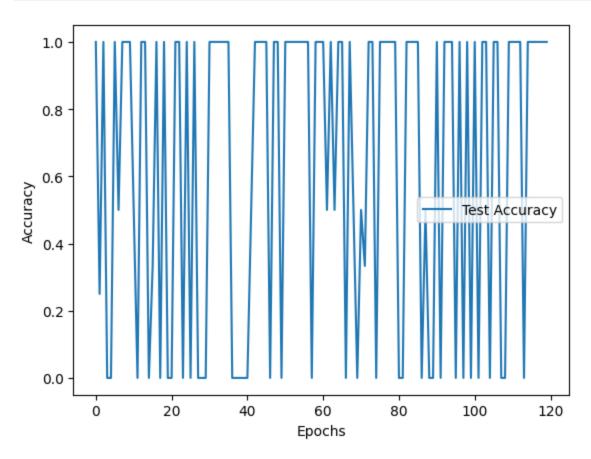
[[20 99] [0 1]]]

print(accuracy_total)

76.91666666666667

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```
plt.plot(test_accuracy, label='Test Accuracy')
plt.xlabel('Epochs')
plt.ylabel('Accuracy')
plt.legend()
plt.show()
```



EfficientNet - GRU

```
class ImageDataGenerator:
    def __init__(self, df, ct_folder, max_samples, cervical, vertebrae_info, batch_size=32):
```

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```
self.df = df
    self.ct_folder = ct_folder
    self.batch_size = batch_size
    self.num samples = len(df)
    self.current idx = 0
    self.cervical = cervical
    self.vertebrae_info = vertebrae_info
    self.max_samples = max_samples
def __iter__(self):
    return self
def next (self):
    # batch_images = []
    # batch_labels = []
    batch_images = torch.zeros((self.batch_size, self.max_samples, 3, 224, 224))
    batch labels = torch.zeros((self.batch size, 1))
    max_length = self.max_samples
    for i in range(self.batch_size):
        if self.current_idx >= self.num_samples:
            self.current idx = 0
            raise StopIteration
        ct_name = self.df.iloc[self.current_idx]['StudyInstanceUID']
        labels = [float(self.df.iloc[self.current idx]['C' + str(self.cervical)])]
        filas_seleccionadas = self.vertebrae_info.loc[(self.vertebrae_info['StudyInstanceUID'
        # labels = self.df.iloc[self.current_idx][['C1', 'C2', 'C3', 'C4', 'C5', 'C6', 'C7']]
        if not filas_seleccionadas.empty:
            slice_numbers = filas_seleccionadas['Slice'].tolist()
            with ZipFile(os.path.join(self.ct_folder, ct_name + '.zip'), 'r') as zip_ref:
                image_files = zip_ref.namelist()
                # Read and process each image
                ct_images = []
                counter = 0
                for image_file in image_files:
                    slice_number = int(image_file.split('.jpg')[0].split('/')[-1])
                    if slice number in slice numbers:
                        with zip_ref.open(image_file) as img_file:
                            image = Image.open(img_file) # Load the image
                            image = preprocess_image_for_combined_model(image)
                            # ct_images.append(image)
                            batch images[i, counter] = image
                        counter += 1
                        if counter == max_length:
                            break
                # ct_images = apply_PCA(torch.stack(ct_images))
                # print(ct_images.shape)
                while counter < max length:</pre>
                    # ct_images.append(torch.zeros(3, 224, 224))
                    batch_images[i, counter] = torch.zeros(3, 224, 224)
```

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```
counter += 1
    # Append images and labels to the batch=
    # batch_images.append(ct_images)

# batch_labels.append(labels)
batch_labels[i] = torch.tensor(labels)
self.current_idx += 1

# for el in batch_images:
# for el2 in el:
# print(type(el2))
# batch_images = np.array(batch_images)
# batch_labels = np.array(batch_labels)
return batch_images, batch_labels

def __len__(self):
# Devuelve La Longitud total del generador
return self.num_samples
```

```
import torch.nn.functional as F
class CombinedModel(nn.Module):
    def __init__(self, efficientnet_output_size, gru_hidden_size, gru_num_layers, num_classes):
        super(CombinedModel, self).__init__()
        # Cargar EfficientNet preentrenado
        self.efficientnet = models.efficientnet_b0(pretrained=True)
        # Eliminar la capa Fully Connected
        self.features = nn.Sequential(*list(self.efficientnet.children())[:-1])
        # Pooling Global Promedio
        self.global_avg_pool = nn.AdaptiveAvgPool2d(1)
        # GRU Layer
        self.gru = nn.GRU(input_size=efficientnet_output_size, hidden_size=gru_hidden_size, batch]
        # Fully Connected Layer
        self.fc = nn.Linear(gru_hidden_size, 1)
        self.dropout = nn.Dropout(0.5)
        # Softmax
        # self.softmax = nn.Softmax(dim=1)
        self.sigmoid = nn.Sigmoid()
   def forward(self, x):
        batch_size, timesteps, C, H, W = x.size()
        x = x.view(batch_size * timesteps, C, H, W)
        # Pasar imágenes por EfficientNet
        x = self.features(x)
```

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```
# Pooling Global Promedio
x = self.global_avg_pool(x).squeeze(-1).squeeze(-1)

x = x.view(batch_size, timesteps, -1)
# print(x.shape)
# Pasar La secuencia de feature maps por La GRU
out, _ = self.gru(x)
# Usar solo La última salida de La secuencia
out = out[:, -1, :]
# Pasar por La capa Fully Connected
out = self.dropout(self.fc(out))
# Softmax
out = self.sigmoid(out)

return out
```

```
sample = 600
```

```
data_VGG = pd.read_csv('train_filtrado_images.csv')
data_VGG = data_VGG.sample(n=sample, random_state=42)
```

```
# Parámetros del modelo
vgg_output_size = 1280  # Tamaño de la salida de la VGG16
gru_hidden_size = 128  # Tamaño del estado oculto de la GRU
gru_num_layers = 2  # Número de capas en la GRU
num_classes = 7  # Reemplaza con el número de clases en tu problema
```

```
data_vertebrae = pd.read_csv('meta_train_with_vertebrae.csv')
```

```
train_data, test_data = train_test_split(data_VGG, test_size=0.2, random_state=42)
```

```
batch_size = 1
```

```
def get_matrix(vertebrae):
    # Cargar el modelo entrenado
    combined_model = CombinedModel(vgg_output_size, gru_hidden_size, gru_num_layers, num_classes)
    combined_model.load_state_dict(torch.load(f'modelo_entrenadoC{vertebrae}.pth'))
    combined_model.to('cuda')

data_generator = ImageDataGenerator(train_data, 'imagenes_train', 75, vertebrae, data_vertebrae, data_generator_test = ImageDataGenerator(test_data, 'imagenes_train', 75, vertebrae, data_vertebrae, da
```

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```
test_accuracy = []
accuracy_total = 0
confusion_matrices = []
confusion total = np.zeros((2, 2))
with torch.no_grad():
    for i, (images tensor, labels tensor) in tqdm(enumerate(data generator test), total=len(data)
        image_tensor = images_tensor.to('cuda')
        label_tensor = labels_tensor.to('cuda')
        predictions = combined_model(image_tensor)
        threshold = 0.5
        predicted_labels = (predictions > threshold).float() # 1 si es mayor al umbral, 0 de
        predicted_labels_np = predicted_labels.cpu().numpy()
        true_labels = label_tensor.cpu().numpy()
        confusion batch = confusion matrix(true labels, predicted labels np)
        # Acumula la matriz de confusión en la matriz total
        confusion_total += confusion_batch
accuracy, recall, f1 = get_metrics(confusion_total.copy())
print("Accuracy:", accuracy)
print("Recall:", recall)
print("F1:", f1)
plt.figure(figsize=(5,5))
blue_palette = sns.color_palette("Blues")
sns.heatmap(confusion_total,cmap=blue_palette, annot=True, fmt=".0f")
plt.xlabel('Predicted')
plt.ylabel('True')
plt.title(f'Confusion Matrix C{vertebrae}')
plt.show()
```

```
vertebrae = [1, 2, 3, 4, 5, 6, 7]

for vert in vertebrae:
    get_matrix(vert)
```

c:\Users\Daniel\Main\UVG\Semestre_VIII\Data_science\Proyecto2\envi\lib\sitepackages\torchvision\models_utils.py:208: UserWarning: The parameter 'pretrained' is deprecated
since 0.13 and may be removed in the future, please use 'weights' instead.
 warnings.warn(
c:\Users\Daniel\Main\UVG\Semestre_VIII\Data_science\Proyecto2\envi\lib\site-

packages\torchvision\models_utils.py:223: UserWarning: Arguments other than a weight enum or `None` for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent to passing `weights=EfficientNet_B0_Weights.IMAGENET1K_V1`. You can also use `weights=EfficientNet_B0_Weights.DEFAULT` to get the most up-to-date weights.

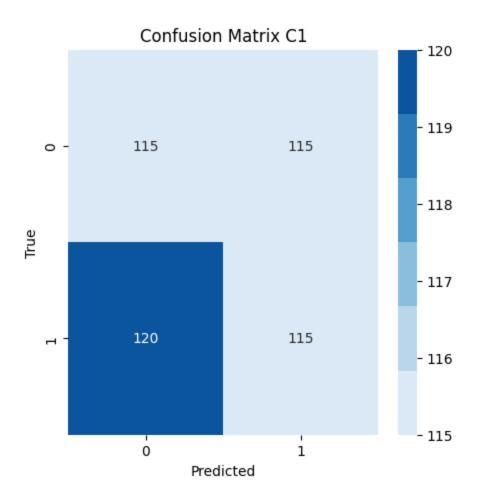
localhost:3390

warnings.warn(msg)

100%| 120/120 [00:29<00:00, 4.05it/s]

Accuracy: 0.4946236559139785 Recall: 0.48936170212765956

F1: 0.4946236559139785



c:\Users\Daniel\Main\UVG\Semestre_VIII\Data_science\Proyecto2\envi\lib\sitepackages\torchvision\models_utils.py:208: UserWarning: The parameter 'pretrained' is deprecated
since 0.13 and may be removed in the future, please use 'weights' instead.

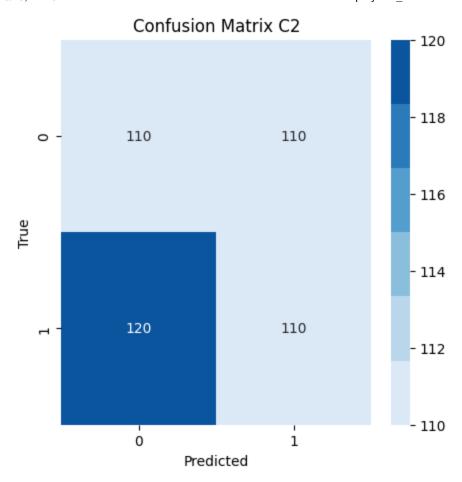
warnings.warn(

c:\Users\Daniel\Main\UVG\Semestre_VIII\Data_science\Proyecto2\envi\lib\sitepackages\torchvision\models_utils.py:223: UserWarning: Arguments other than a weight enum or
`None` for 'weights' are deprecated since 0.13 and may be removed in the future. The current
behavior is equivalent to passing `weights=EfficientNet_B0_Weights.IMAGENET1K_V1`. You can also
use `weights=EfficientNet_B0_Weights.DEFAULT` to get the most up-to-date weights.

warnings.warn(msg)

100%| 120/120 [00:37<00:00, 3.20it/s]

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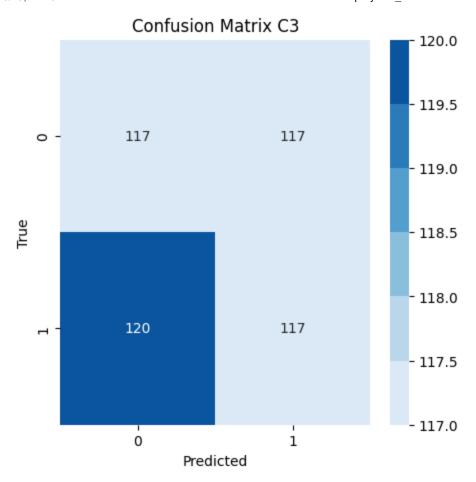
packages\torchvision\models_utils.py:223: UserWarning: Arguments other than a weight enum or `None` for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent to passing `weights=EfficientNet_B0_Weights.IMAGENET1K_V1`. You can also use `weights=EfficientNet_B0_Weights.DEFAULT` to get the most up-to-date weights.

warnings.warn(msg)

100%| 100%| 120/120 [00:29<00:00, 4.04it/s]

Accuracy: 0.4968152866242038
Recall: 0.4936708860759494
F1: 0.4968152866242039

localhost:3390 18/23



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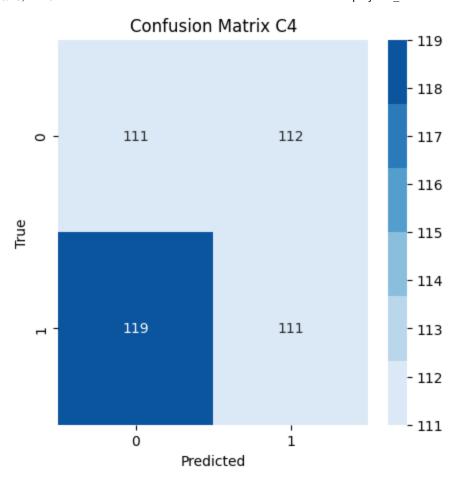
packages\torchvision\models_utils.py:223: UserWarning: Arguments other than a weight enum or `None` for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent to passing `weights=EfficientNet_B0_Weights.IMAGENET1K_V1`. You can also use `weights=EfficientNet_B0_Weights.DEFAULT` to get the most up-to-date weights.

warnings.warn(msg)

100%| 120/120 [00:29<00:00, 4.01it/s]

Accuracy: 0.4900662251655629 Recall: 0.4826086956521739 F1: 0.49006622516556286

localhost:3390 19/23



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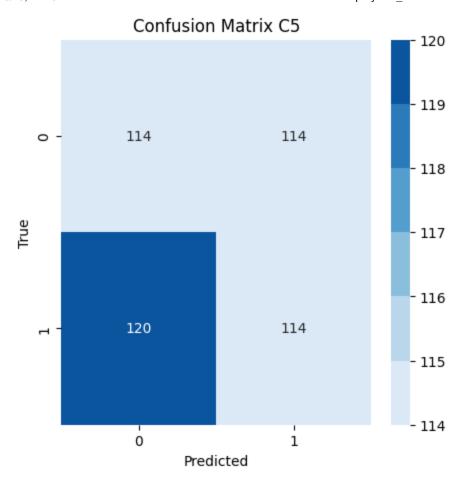
packages\torchvision\models_utils.py:223: UserWarning: Arguments other than a weight enum or `None` for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent to passing `weights=EfficientNet_B0_Weights.IMAGENET1K_V1`. You can also use `weights=EfficientNet_B0_Weights.DEFAULT` to get the most up-to-date weights.

warnings.warn(msg)

100%| 120/120 [00:30<00:00, 3.93it/s]

Accuracy: 0.4935064935064935 Recall: 0.48717948717948717 F1: 0.49350649350649345

localhost:3390 20/23



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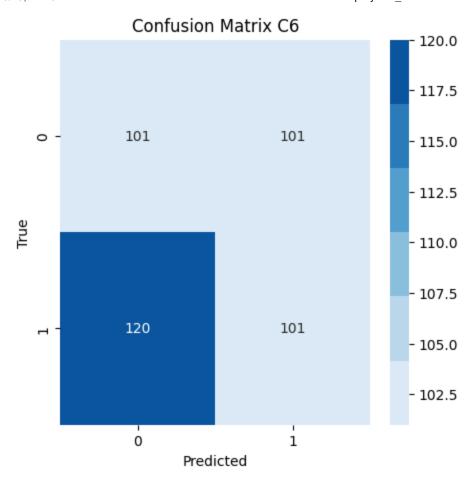
packages\torchvision\models_utils.py:223: UserWarning: Arguments other than a weight enum or `None` for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent to passing `weights=EfficientNet_B0_Weights.IMAGENET1K_V1`. You can also use `weights=EfficientNet_B0_Weights.DEFAULT` to get the most up-to-date weights.

warnings.warn(msg)

100%| 120/120 [00:29<00:00, 4.05it/s]

Accuracy: 0.47754137115839246 Recall: 0.45701357466063347 F1: 0.47754137115839246

localhost:3390 21/23



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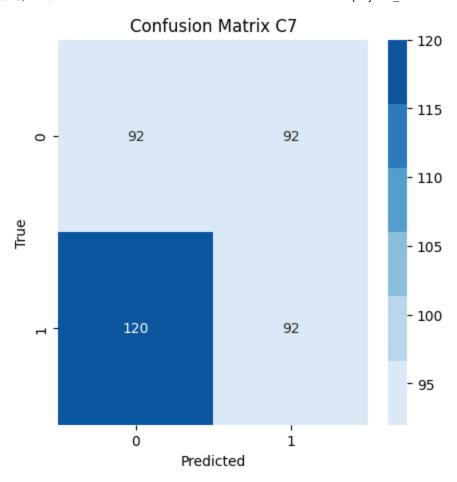
packages\torchvision\models_utils.py:223: UserWarning: Arguments other than a weight enum or `None` for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent to passing `weights=EfficientNet_B0_Weights.IMAGENET1K_V1`. You can also use `weights=EfficientNet_B0_Weights.DEFAULT` to get the most up-to-date weights.

warnings.warn(msg)

100%| 120/120 [00:31<00:00, 3.87it/s]

Accuracy: 0.46464646464646464 Recall: 0.4339622641509434 F1: 0.46464646464646464

localhost:3390 22/23



localhost:3390 23/23