## ICE503 DSP-Homework#5

- 1. The block diagram of a causal LTE system is shown in Figure 1.
  - (a) Write the rational polynomials of the system H(z).
  - (b) Use partial fraction to find the LCCDE h[n] of this system.
  - (c) Write the difference equation that characterizes the system with x[n] and y[n].

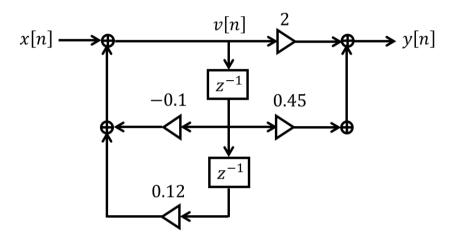


Figure 1: The block diagram of an LTE system

2. When the input to an LTE system is

$$x[n] = \left(\frac{1}{3}\right)^n \mu[n] + 3^n \mu[-n-1]$$

the output is

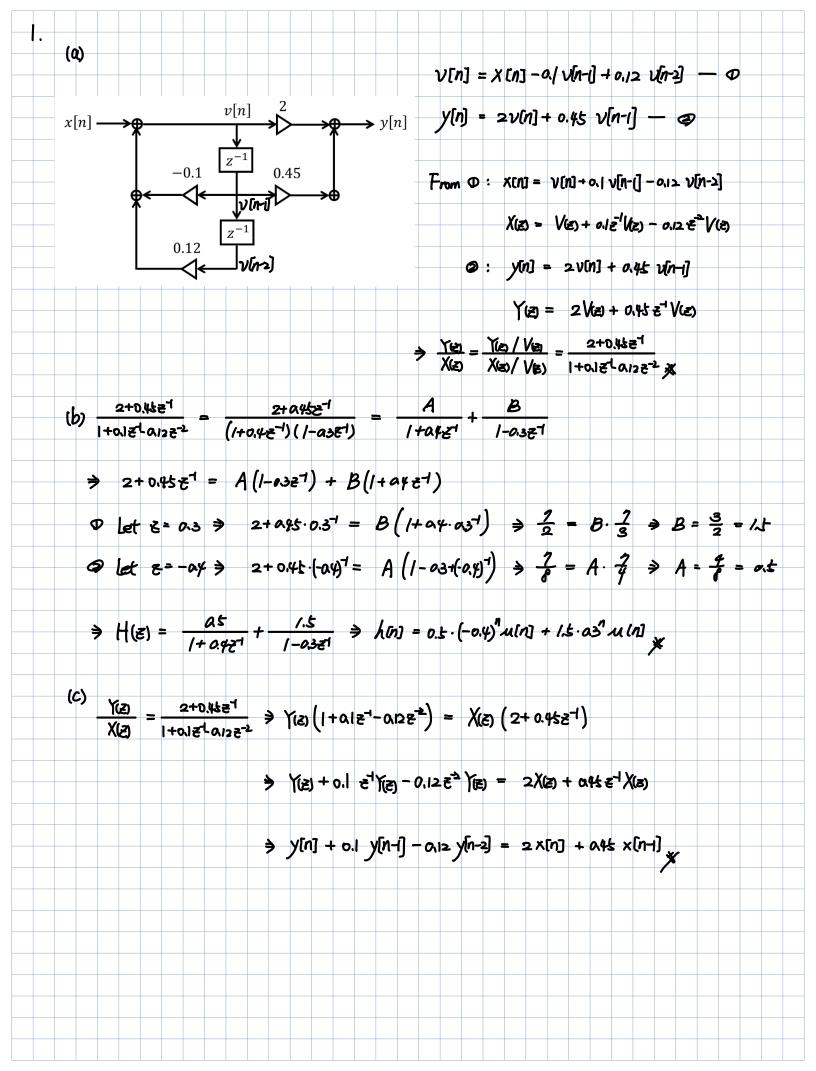
$$y[n] = 5\left(\frac{1}{3}\right)^n \mu[n] - 5\left(\frac{3}{4}\right)^n \mu[n]$$

- (a) Find the ZT of x[n] and y[n], and indicate their ROC.
- (b) Find the rational polynomials of the system H(z), plot the pole(s) and zeros(s) and indicate the ROC.
- (c) Determine whether the system is causal and stable.
- (d) Find the impulse response h[n] of the system.
- (e) Write the difference equation that characterizes the system.

## 3. MATLAB simulation:

In the question 2(b), you might have sketched the pole(s) and zeros(s) of the system H(z), and you might have found the difference equation in the question 2(e)

- (a) Use zplane function to plot the pole(s) and zeros(s) of the system H(z)(The result should be the same as your answer in question 2(b).)
- (b) Use freqz function to calculate a 100-point frequency response vector and the corresponding angular frequency vector, then plot the magnitude and phase response of the frequency response vector.



2. (a) 
$$\times [n] = \frac{1}{5} \frac{1}{5} A[n] + \frac{3}{5} A[n$$