## ICE503 DSP-Homework#10

1. A causal linear time-invariant system has the system function

$$H(z) = \frac{(1 - 1.5z^{-1} - z^{-2})(1 + 0.9z^{-1})}{(1 - z^{-1})(1 + 0.7jz^{-1})(1 - 0.7jz^{-1})}$$

- (a) Write the difference equation that characterizes the system with x[n] and y[n].
- (b) Plot the pole-zero diagram and indicate the region of convergence for the system function.
- (c) Sketch  $|H(e^{j\omega})|$ .
- 2. Consider a causal linear time-invariant system function H(z) and real impulse response. H(z) evaluated for  $z = e^{j\omega}$  is shown in Figure 1.
  - (a) Carefully sketch a pole-zero plot for H(z) showing all information about the pole and zero locations that can inferred from the figure.
  - (b) Specify whether the system is stable.

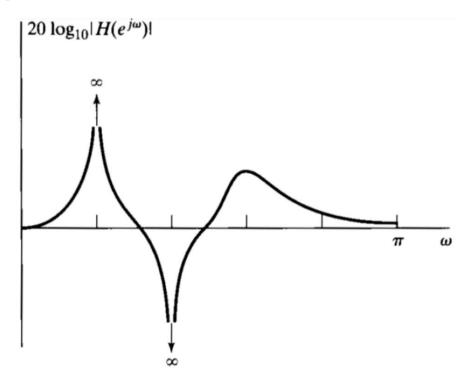


Figure 1. A causal linear time-invariant system function H(z)

## 3. Matlab Simulation

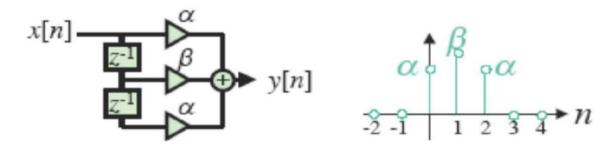
Separate the following information in frequency.

$$x[n] = A\cos(\omega 1n) + B\cos(\omega 2n)$$

with construct  $H(e^{j\omega})$ 

$$H(e^{j\omega}) = \begin{cases} |H(e^{j\omega_1})| \sim 1, \\ |H(e^{j\omega_2})| \sim 0, \end{cases}$$

Where  $\omega_1=0.1$  and  $\omega_2=0.4$ . Consider a 3 pt FIR filters with  $h[n]=\{\alpha \ \beta \ \alpha\}$ . Sketch the frequency response and compare the output signal with input signals.



 $H(z) = \frac{(1-1.5z^{-1}z^{-2})(1+0.9z^{-1})}{(1-z^{-1})(1+0.1jz^{-1})(1-0.1jz^{-1})} = \frac{(-0.6z^{-1}-2.3tz^{-2}-0.9z^{-3})}{(-z^{-1}+0.49z^{-2}-0.49z^{-3})} = \frac{\chi(z)}{\chi(z)}$ ⇒ (1 - ₹ + 0.49 € - 0.49 € 3) Y(E) = (1 - 0.6 € - 1 - 2.3 ₺ € 3 - 0.9 € 3) X(E)  $\Rightarrow$  y[n] - y[n-1] + a49 y[n-2] - a49 y[n-3] = x[n] - 0.6 x[n-1] - 2.35 x[n-2] - 0.9 x[n-3](b)  $H(z) = \frac{(1-1.5z^{-1}z^{-2})(1+0.9z^{-1})}{(1-z^{-1})(1+0.1jz^{-1})(1-0.1jz^{-1})} = \frac{(1-2z^{-1})(1-0.1z^{-1})(1+0.9z^{-1})}{(1-z^{-1})(1+0.1jz^{-1})(1-0.1jz^{-1})}$ , cousal > RD(): |€| > ) poles: 1, ±0.7,j zeros : 2, 0.5, -0.9 (c) ᇴ π

