Simulations on "Bayesian Hierarchical weighting adjustment and survey inference" by Trangucci et al.

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1

MODEL DESCRIPTION

1.1 Trangucci et al. model0

We describe the model given in (?, Sec. 2).

- Population made of H strata $U_1, ..., U_J$.
- Stratum *j* size: N_j , Total size: $N = \sum_i N_i$
- Sample size in stratum j: n_j
- \bullet *I* vector: sample indicator
- *y* vector: study variable
- θ_j : average of y in stratum j. $\theta_j = \sum_{i \in U_j} y_i$. In the paper there is an ambiguity: First, θ is called the "population estimand of interest[...] the overall or domain mean". Ambiguity comes from the term "mean". Is $\theta = N^{-1} \sum_i y_i$ or Is $\theta = N^{-1} \sum_k E[y_i]$?
- X: Design variables. In the paper $X^1, ..., X^J$ are badly defined. The idea is that X variables are Q categorical variables. The strata correspond to the cells obtained from these categorical variables.

- denote by $1, ... K_q$ the categories for variable X_q .
- denote by j[i] the stratim of unit i
- Denote by k[q, j] the category for variable X_q in stratum j

Consider the following hierarchical model:

$$y_i \sim \mathcal{N}\left(\theta_{j[i]}^{\star}, \sigma_y^2\right) \tag{1.1}$$

$$\theta_{j}^{\star} = \alpha_{0} + \sum_{\ell=1}^{Q} \left(\sum_{q_{1} < \dots < q_{\ell} \in \{1, \dots, Q\}} \alpha_{j}^{(q_{1}, \dots, q_{\ell})} \right)$$
(1.2)

$$\forall \ell \in \{1, ..., Q\}, \ \forall q_1, ..., q_\ell \in \{1, ..., Q\}, \ \forall j \in \{1, ..., H\} : \alpha_j^{(q_1, ..., q_\ell)} \sim \mathcal{N}(0, (\lambda_j^{(q_1, ..., q_\ell)} \sigma)^2)$$
 (1.3)

$$\forall \ell \in \{1, \dots, Q\}, \ \forall q_1, \dots, q_\ell \in \{1, \dots, Q\}, \ \forall j \in \{1, \dots, H\} : \lambda_j^{(q_1, \dots, q_\ell)} = \delta^{(\ell)} \prod_{l=1}^{\ell} \gamma_{k[q_l, j]}^{(q_l)}$$

$$(1.4)$$

$$\sigma \sim \text{Cauchy}_{+}(0,1) \tag{1.5}$$

$$\forall q \in \{1, \dots, Q\}, \ k \in \{1, \dots, K_q\} : \gamma_k^{(q)} \sim \mathcal{N}_+(0, 1)$$
(1.6)

$$\delta^{(\ell)} \sim \mathcal{N}_{+}(0,1) \tag{1.7}$$

$$\sigma_v \sim \text{Cauchy}_+(0,5)$$
 (1.8)

$$\alpha_0 \sim \mathcal{N}(0, 10) \tag{1.9}$$

Note I made up the prior on α_0 as I did not find in the paper.

1.2 Competing model

We describe a competing model.

Consider the following hierarchical model:

$$y_i \sim \mathcal{N}\left(\theta_{i[i]}^{\mathcal{Q}}, \sigma_y^2\right)$$
 (1.10)

$$(\theta_j^{\mathcal{Q}})_{j=1}^Q \sim \mathcal{N}(0, \Sigma)$$
 (1.11)

$$\Sigma_{i_1, i_2} = \sigma^2 D_{\alpha}(j_1, j_2) \tag{1.12}$$

$$D_{\alpha}(j_1, j_2) = \sigma_y^2 \left(\exp\left(-\sum_{q=1}^{Q} \alpha_q(k[q, j_1] \neq k[q, j_2]) \right) \right)$$
 (1.13)

$$\sigma_{y} \sim \text{Cauchy}_{+}(0,5) \tag{1.14}$$

$$\alpha_q \sim \text{Cauchy}_+(0,1)$$
 (1.15)

1.3 Competing model 2 (Joseph)

The MRP should work for any dataset, but it shouldn't be totally unrealistic, relative to the prior. I have written cell mean j in primitive notation for a two-way layout Let i = 1...I denote the rows, j = 1...J the column. Then $\theta_{i,j} = \eta + \alpha_i + \beta_j + \gamma_{ij}$.

For a simple example take the I = 3 J = 2 and think of constant local effect within level "1" s.e the paper's notation:

$$\begin{array}{lll} \theta_{1,1} &=& \eta + \alpha + \beta \\ \theta_{1,2} &=& \eta + \alpha_i + \beta_j + d_1 \\ \theta_{2,1} &=& \eta + \alpha + \beta \\ \theta_{2,2} &=& \eta + \alpha + \beta + d_2 \\ \theta_{3,1} &=& \eta + \alpha + \beta \\ \theta_{3,2} &=& \eta + \alpha + \beta + d_3 \end{array}$$

and perhaps $Y_{ij} \equiv \theta_{ij}$

2

DATA GENERATION

Step 1

Create procedures that can

- 1. generate a population of size N and with Q random categorical variables X_1, \ldots, X_Q . X_q is generated by drawing with replacement in $\{1, \ldots, K_q\}$ where $K_q > 1$, K_q can be generated by drawing from $\mathcal{U}_{1,\ldots,p}$.
- 2. compute the corresponding stratum j = 1,...,J and the correspondances $(k[q,j])_{j=1,...,J,q=1,...,Q}$.
- 3. generate, for such a population, the hyper parameters σ_y , α_0 , $(\delta^\ell)_{\ell=1,\dots,Q}$, λ_k^l , σ .
- 4. compute the $\lambda_{k_1,\ldots,k_\ell}^{(q_1,\ldots,q_\ell)}$, for possible values of $k_1,\ldots,k_\ell^{(q_1,\ldots,q_\ell)}$.
- 5. generate the $\alpha_{j,(k_1,\ldots,k_\ell)}^{(q_1,\ldots,q_\ell)}$.

- 6. compute θ^* .
- 7. generate a number r of realisations of y for such hyperparameters and such strata.
- 8. Set seed.
- 9. Create a population with N = 10000, Q = 2, p = 5. Display J, N_j, θ^* .
- 1. To generate the population and stratification variables we use the function SimuTrangucci::Gen_design_variables:

?SimuTrangucci::Gen_design_variables
XX=SimuTrangucci::Gen_design_variables()

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9. 9. This are tables we obtained with different seeds.

Table 2.1:

	X_1	X_2	Stratum (j)	N_{j}	$ heta^{\star}$
S1	1	1	S1	113	-5.151
S2	1	2	S2	111	-3.938
S3	1	3	S3	119	-2.698
S4	2	1	S4	101	-0.163
S5	2	2	S5	106	-4.607
S6	2	3	S6	105	-1.853
S7	3	1	S7	140	0.434
S8	3	2	S8	104	-1.733
S9	3	3	S9	101	-6.088

Table 2.2:

	X_1	X_2	Stratum (j)	N_{j}	$ heta^{\star}$
S1	1	1	S1	91	3.215
S2	1	2	S2	73	0.055
S3	1	3	S3	83	2.687
S4	1	4	S4	86	2.681
S5	2	1	S5	91	-5.146
S6	2	2	S6	82	-10.338
S7	2	3	S7	80	3.576
S8	2	4	S8	78	0.260
S9	3	1	S9	95	6.074
S10	3	2	S10	80	0.900
S11	3	3	S11	91	2.567
S12	3	4	S12	70	-4.289

3

BAYESIAN COMPUTATIONS

Step 1

Using Jags,

1. Draw posterior distribution of θ_j^{\star} for the largest value of θ_j^{\star} , obtained from the observation of

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y^{(1)} only. Add real value of \theta_1 and prediction to the plot.
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- 2. Draw distribution of predictions of θ_i^* . Add real value of θ_i to the plot.
- 3. Draw real values of all θ_i^* vs r = 30 predictions.

Some functions to generate the jags model file:

```
library(SimuTrangucci)
  library(R2jags)
  library(ggplot2)
  library(plyr)
  GG \leftarrow Generate\_all(N=1000, Q=2, p=5)
  x < - model.text(GG);x
model{
for(i in 1:N){y[i]~dnorm(thetastar[j_i[i]],1/sqrt(sigma_y^2));}
for (j in 1:J){thetastar[j]=alpha0+alpha.X1[j]+alpha.X2[j]+alpha.X1.X2[j];}
for (j in 1:J){alpha.X1[j]~dnorm(0,1/sqrt((lambda.X1[j]*sigma)^2));}
for (j in 1:J){alpha.X2[j]~dnorm(0,1/sqrt((lambda.X2[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2[j]~dnorm(0,1/sqrt((lambda.X1.X2[j]*sigma)^2));}
for (j in 1:J){\{lambda.X1[j]=delta[1]*lambda0.X1[k_qj[1,j]];\}}
for (j in 1:J){lambda.X2[j]=delta[1]*lambda0.X2[k_qj[2,j]];}
for (j in 1:J){lambda.X1.X2[j]=delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]];}
for (k \text{ in } 1:K_q[1])\{lambda0.X1[k]^adnorm(0,1)\}
for (k \text{ in } 1:K_q[2]) \{lambda 0.X2[k]^d norm(0,1)\}
for(1 in 1:Q){delta[1]~dnorm(0,1)}
sigma=abs(sigmarel)
sigma_y=abs(sigma_yrel)
sigma_yrel~dt(0,1/sqrt(5),1)
sigmarel^{\sim}dt(0,1,1)
alpha0~dnorm(0,.1)
  GG \leftarrow Generate\_all(N=1000,Q=5,p=5)
  x < - model.text(GG);x
model{
for(i in 1:N){y[i]~dnorm(thetastar[j_i[i]],1/sqrt(sigma_y^2));}
for (j in 1:J){thetastar[j]=alpha0+alpha.X1[j]+alpha.X2[j]+alpha.X3[j]+alpha.X4[j]+alpha.X5[
for (j in 1:J){alpha.X1[j]~dnorm(0,1/sqrt((lambda.X1[j]*sigma)^2));}
for (j in 1:J){alpha.X2[j]~dnorm(0,1/sqrt((lambda.X2[j]*sigma)^2));}
for (j in 1:J){alpha.X3[j]~dnorm(0,1/sqrt((lambda.X3[j]*sigma)^2));}
for (j in 1:J){alpha.X4[j]~dnorm(0,1/sqrt((lambda.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X5[j]~dnorm(0,1/sqrt((lambda.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2[j]~dnorm(0,1/sqrt((lambda.X1.X2[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X3[j]~dnorm(0,1/sqrt((lambda.X1.X3[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X4[j]~dnorm(0,1/sqrt((lambda.X1.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X5[j]~dnorm(0,1/sqrt((lambda.X1.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X3[j]~dnorm(0,1/sqrt((lambda.X2.X3[j]*sigma)^2));}
```

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for (j in 1:J){alpha.X2.X4[j]~dnorm(0,1/sqrt((lambda.X2.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X5[j]~dnorm(0,1/sqrt((lambda.X2.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X3.X4[j]~dnorm(0,1/sqrt((lambda.X3.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X3.X5[j]~dnorm(0,1/sqrt((lambda.X3.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X4.X5[j]~dnorm(0,1/sqrt((lambda.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X3[j]~dnorm(0,1/sqrt((lambda.X1.X2.X3[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X4[j]~dnorm(0,1/sqrt((lambda.X1.X2.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X5[j]~dnorm(0,1/sqrt((lambda.X1.X2.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X3.X4[j]~dnorm(0,1/sqrt((lambda.X1.X3.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X3.X5[j]~dnorm(0,1/sqrt((lambda.X1.X3.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X4.X5[j]~dnorm(0,1/sqrt((lambda.X1.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X3.X4[j]~dnorm(0,1/sqrt((lambda.X2.X3.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X3.X5[j]~dnorm(0,1/sqrt((lambda.X2.X3.X5[j]*sigma)^2));}
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for (j in 1:J){alpha.X3.X4.X5[j]~dnorm(0,1/sqrt((lambda.X3.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X3.X4[j]~dnorm(0,1/sqrt((lambda.X1.X2.X3.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X3.X5[j]~dnorm(0,1/sqrt((lambda.X1.X2.X3.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X4.X5[j]~dnorm(0,1/sqrt((lambda.X1.X2.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X3.X4.X5[j]~dnorm(0,1/sqrt((lambda.X1.X3.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X3.X4.X5[j]~dnorm(0,1/sqrt((lambda.X2.X3.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X3.X4.X5[j]~dnorm(0,1/sqrt((lambda.X1.X2.X3.X4.X5[j]*sigma)^2));}
for (j in 1:J){lambda.X1[j]=delta[1]*lambda0.X1[k_qj[1,j]];}
for (j in 1:J){lambda.X2[j]=delta[1]*lambda0.X2[k_qj[2,j]];}
for (j in 1:J){lambda.X3[j]=delta[1]*lambda0.X3[k_qj[3,j]];}
for (j \text{ in } 1:J)\{lambda.X4[j]=delta[1]*lambda0.X4[k_qj[4,j]];\}
for (j in 1:J){lambda.X5[j]=delta[1]*lambda0.X5[k_qj[5,j]];}
for \ (j \ in \ 1:J) \{lambda.X1.X2[j] = delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]; \}
for (j in 1:J){lambda.X1.X3[j]=delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]];}
for \ (j \ in \ 1:J) \{lambda.X1.X4[j] = delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X4[k_qj[4,j]]; \}
for (j in 1:J){lambda.X1.X5[j]=delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X5[k_qj[5,j]];}
for (j in 1:J){lambda.X2.X3[j]=delta[2]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]];}
for \ (j \ in \ 1:J) \{lambda.X2.X4[j] = delta[2]*lambda0.X2[k_qj[2,j]]*lambda0.X4[k_qj[4,j]]; \}
for \ (j \ in \ 1:J) \{lambda.X2.X5[j] = delta[2] * lambda0.X2[k_qj[2,j]] * lambda0.X5[k_qj[5,j]]; \} \} 
for (j in 1:J){\{1ambda.X3.X4[j]=delta[2]*lambda0.X3[k_qj[3,j]]*lambda0.X4[k_qj[4,j]];\}}
for \ (j \ in \ 1:J) \{lambda.X3.X5[j] = delta[2] * lambda0.X3[k_qj[3,j]] * lambda0.X5[k_qj[5,j]]; \}
for (j in 1:J){lambda.X4.X5[j]=delta[2]*lambda0.X4[k_qj[4,j]]*lambda0.X5[k_qj[5,j]];}
for (j in 1:J){1ambda.X1.X2.X3[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]
for (j in 1:J){\{1ambda.X1.X2.X4[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]
for (j in 1:J){1ambda.X1.X2.X5[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]
for \ (j \ in \ 1:J) \{lambda.X1.X3.X4[j] = delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k
for (j in 1:J){1ambda.X1.X3.X5[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]
for (j in 1:J){\{1ambda.X1.X4.X5[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]
for (j in 1:J){1ambda.X2.X3.X4[j]=delta[3]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]
for (j in 1:J){1ambda.X2.X3.X5[j]=delta[3]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]
for (j in 1:J){1ambda.X2.X4.X5[j]=delta[3]*lambda0.X2[k_qj[2,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]
for (j in 1:J){\{1ambda.X3.X4.X5[j]=delta[3]*lambda0.X3[k_qj[3,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]
for (j in 1:J){lambda.X1.X2.X3.X4[j]=delta[4]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,j]]*lambda0.X1[k_qj[2,
for \ (j \ in \ 1:J) \{lambda.X1.X2.X3.X5[j] = delta[4] * lambda0.X1[k_qj[1,j]] * lambda0.X2[k_qj[2,j]] * lambda0.X2[k_qj[2,j]] * lambda0.X1[k_qj[1,j]] * lambda0.X1[k_qj[1,j
for (j in 1:J){\{lambda.X1.X2.X4.X5[j]=delta[4]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1
```

```
for (j in 1:J)\{lambda.X1.X3.X4.X5[j]=delta[4]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,
for (j in 1:J){lambda.X2.X3.X4.X5[j]=delta[4]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]]*la
for (j in 1:J){lambda.X1.X2.X3.X4.X5[j]=delta[5]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]
for (k \text{ in } 1:K_q[1]) \{lambda 0.X1[k]^a dnorm(0,1)\}
for (k \text{ in } 1:K_q[2])\{lambda0.X2[k]^adnorm(0,1)\}
for (k in 1:K_q[3]) \{lambda0.X3[k]^dnorm(0,1)\}
for (k in 1: K_q[4]) \{lambda 0. X4[k]^d norm(0,1)\}
for (k \text{ in } 1:K_q[5])\{lambda0.X5[k]^adnorm(0,1)\}
for(1 in 1:Q){delta[1]~dnorm(0,1)}
sigma=abs(sigmarel)
sigma_y=abs(sigma_yrel)
sigma_yrel~dt(0,1/sqrt(5),1)
sigmarel^{\sim}dt(0,1,1)
alpha0~dnorm(0,.1)
}
```

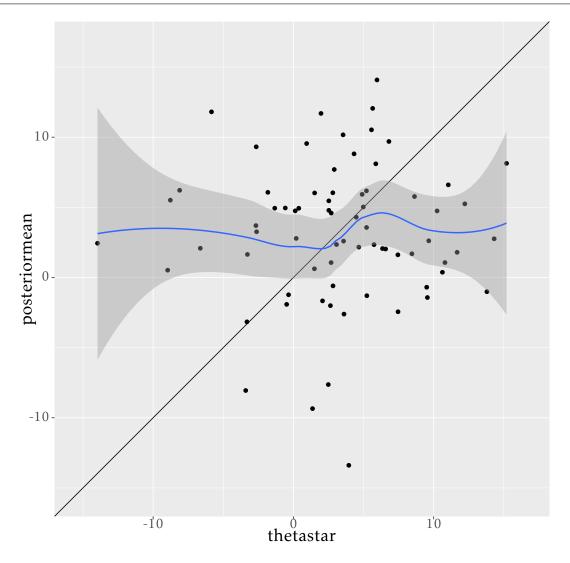
What it does:

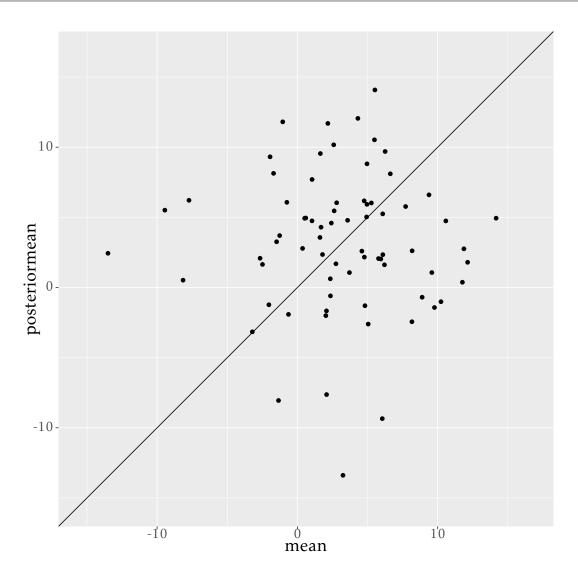
```
set.seed(2)
GG \leftarrow Generate\_all(N=1000,Q=4,p=5)
GG$XX$K_q
gibbs.samples<-Trangucci.fit(GG)
```

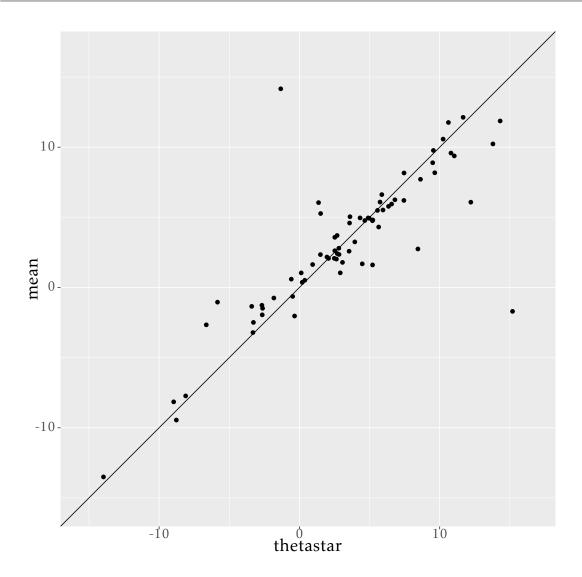
[1] 3 2 3 4

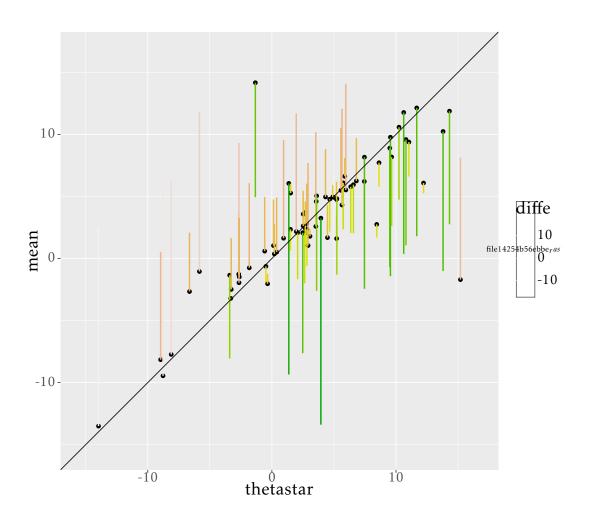
```
X = data.frame(j=1:GG$XX$J,thetastar=GG$thetastar,t(gibbs.samples[[1]]$BUGSoutput$sims.
     list$thetastar[sample(nrow(gibbs.samples[[1]]$BUGSoutput$sims.list$thetastar),100)
names(X[3:ncol(X)])<-paste0("rep",1:(ncol(X)-2))</pre>
XX<-reshape2::melt(X,id.vars=c("j","thetastar"),value.name="sample")
graph1<-ggplot(XX,aes(x=thetastar,y=sample))+geom_point()+geom_abline(slope=1,intercept
   geom_point(aes(x=thetastar,y=thetastar,colour="red"))
XXX < -plyr::ddply(cbind(GG$XX$Xd,y=GG$y[,1]), ~Strata, function(d){data.frame(mean=mean(d)}
YYY<-data.frame(thetastar=GG$thetastar,posteriormean=as.vector(gibbs.samples[[2]]$
   BUGSoutput $mean $thetastar), GG$XX$Strata)
ZZZ<-merge(XXX,YYY,by="Strata")</pre>
ZZZ<-ZZZ[order(ZZZ$thetastar),]
ZZZ$ j <- 1: nrow(ZZZ)
ZZZ$diffe<-ZZZ$posteriormean-ZZZ$mean
graph5<-ggplot(ZZZ,aes(x=thetastar,</pre>
                                          y=mean))+geom_point()+geom_segment(aes(x =
   thetastar, y = mean , xend = thetastar, yend = posteriormean,colour=diffe),linejoin="
   mitre", size=1) + geom_abline(slope=1, intercept=0) +
   scale_colour_gradientn(colours = terrain.colors(10))
r<-ggplot_build(graph5)$layout$panel_params[[1]]$x.range
s<-ggplot_build(graph5)$layout$panel_params[[1]]$y.range
t < -c(min(r[1], s[1]), max(r[2], s[2]))
graph5<-graph5+coord_equal(xlim=t,ylim=t)</pre>
graph4<-ggplot(ZZZ,aes(x=thetastar,</pre>
                                          y=mean))+geom_point()+geom_abline(slope=1,
   intercept=0)+coord_equal(xlim=t,ylim=t)
graph2 < - ggplot(ZZZ, aes(x=thetastar, y=posteriormean)) + geom_point() + geom_abline(slope=1,</pre>
   intercept=0)+coord_equal(xlim=t,ylim=t)+geom_smooth()
graph3<-ggplot(ZZZ,aes(x=mean,</pre>
                                    y=posteriormean))+geom_point()+geom_abline(slope=1,
   intercept=0)+coord_equal(xlim=t,ylim=t)
```

```
graph6<-ggplot(reshape2::melt(ZZZ[c("j","thetastar","mean","posteriormean")],id.vars=c("
    j")),aes(x=j,y=value,colour=variable))+geom_line()
graph7<-ggplot(reshape2::melt(ZZZ[c("j","thetastar","posteriormean")],id.vars=c("j")),
    aes(x=j,y=value,colour=variable))+geom_line()
    geom_vline(xintercept=GG$hyper$sigma,colour="red")
    geom_vline(xintercept=GG$hyper$sigma_y,colour="red")
    geom_vline(xintercept=GG$lambda$`3`[1],colour="red")
    geom_vline(xintercept=GG$lambda$`3`[1],colour="red")
    geom_vline(xintercept=GG$hyper$delta[2],colour="red")
    geom_vline(xintercept=GG$hyper$delta[3],colour="red")
ggplot(X,aes(x,y))+geom_point()+geom_abline(intercept=0,slope=1)</pre>
```









Step 2 same thing with Stan

Some functions to generate the jags model file:

 $library (SimuTrangucci) \ library (R2jags) \ library (ggplot2) \ library (plyr) \ GGi-Generate_a ll(N=1000,Q=2,p=5)x < -model.text(GG); x$

```
model{
for(i in 1:N){y[i]~dnorm(thetastar[j_i[i]],1/sqrt(sigma_y^2));}
for (j in 1:J){thetastar[j]=alpha0+alpha.X1[j]+alpha.X2[j]+alpha.X1.X2[j];}
for (j in 1:J){alpha.X1[j]~dnorm(0,1/sqrt((lambda.X1[j]*sigma)^2));}
for (j in 1:J){alpha.X2[j]~dnorm(0,1/sqrt((lambda.X2[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2[j]~dnorm(0,1/sqrt((lambda.X1.X2[j]*sigma)^2));}
for (j in 1:J){lambda.X1[j]=delta[1]*lambda0.X1[k_qj[1,j]];}
for (j in 1:J){lambda.X2[j]=delta[1]*lambda0.X2[k_qj[2,j]];}
for (j in 1:J){lambda.X1.X2[j]=delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]];}
for(k in 1:K_q[1]){lambda0.X1[k]~dnorm(0,1)}
for(k in 1:K_q[2]){lambda0.X2[k]~dnorm(0,1)}
for(l in 1:Q){delta[1]~dnorm(0,1)}
```

p. 13

```
sigma=abs(sigmarel)
sigma_y=abs(sigma_yrel)
sigma_yrel~dt(0,1/sqrt(5),1)
sigmarel^{\sim}dt(0,1,1)
alpha0~dnorm(0,.1)
  GG_i-Generate<sub>a</sub>ll(N = 1000, Q = 5, p = 5)x < -model.text(GG); x
model{
for(i in 1:N){y[i]~dnorm(thetastar[j_i[i]],1/sqrt(sigma_y^2));}
for (j in 1:J){thetastar[j]=alpha0+alpha.X1[j]+alpha.X2[j]+alpha.X3[j]+alpha.X4[j]+alpha.X5[
for (j in 1:J){alpha.X1[j]~dnorm(0,1/sqrt((lambda.X1[j]*sigma)^2));}
for (j in 1:J){alpha.X2[j]~dnorm(0,1/sqrt((lambda.X2[j]*sigma)^2));}
for (j in 1:J){alpha.X3[j]~dnorm(0,1/sqrt((lambda.X3[j]*sigma)^2));}
for (j in 1:J){alpha.X4[j]~dnorm(0,1/sqrt((lambda.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X5[j]~dnorm(0,1/sqrt((lambda.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2[j]~dnorm(0,1/sqrt((lambda.X1.X2[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X3[j]~dnorm(0,1/sqrt((lambda.X1.X3[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X4[j]~dnorm(0,1/sqrt((lambda.X1.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X5[j]~dnorm(0,1/sqrt((lambda.X1.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X3[j]~dnorm(0,1/sqrt((lambda.X2.X3[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X4[j]~dnorm(0,1/sqrt((lambda.X2.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X5[j]~dnorm(0,1/sqrt((lambda.X2.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X3.X4[j]~dnorm(0,1/sqrt((lambda.X3.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X3.X5[j]~dnorm(0,1/sqrt((lambda.X3.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X4.X5[j]~dnorm(0,1/sqrt((lambda.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X3[j]~dnorm(0,1/sqrt((lambda.X1.X2.X3[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X4[j]~dnorm(0,1/sqrt((lambda.X1.X2.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X5[j]~dnorm(0,1/sqrt((lambda.X1.X2.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X3.X4[j]~dnorm(0,1/sqrt((lambda.X1.X3.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X3.X5[j]~dnorm(0,1/sqrt((lambda.X1.X3.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X4.X5[j]~dnorm(0,1/sqrt((lambda.X1.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X3.X4[j]~dnorm(0,1/sqrt((lambda.X2.X3.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X3.X5[j]~dnorm(0,1/sqrt((lambda.X2.X3.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X4.X5[j]~dnorm(0,1/sqrt((lambda.X2.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X3.X4.X5[j]~dnorm(0,1/sqrt((lambda.X3.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X3.X4[j]~dnorm(0,1/sqrt((lambda.X1.X2.X3.X4[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X3.X5[j]~dnorm(0,1/sqrt((lambda.X1.X2.X3.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X4.X5[j]~dnorm(0,1/sqrt((lambda.X1.X2.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X3.X4.X5[j]~dnorm(0,1/sqrt((lambda.X1.X3.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X2.X3.X4.X5[j]~dnorm(0,1/sqrt((lambda.X2.X3.X4.X5[j]*sigma)^2));}
for (j in 1:J){alpha.X1.X2.X3.X4.X5[j]~dnorm(0,1/sqrt((lambda.X1.X2.X3.X4.X5[j]*sigma)^2));}
for (j in 1:J){lambda.X1[j]=delta[1]*lambda0.X1[k_qj[1,j]];}
for (j in 1:J){lambda.X2[j]=delta[1]*lambda0.X2[k_qj[2,j]];}
for (j in 1:J){lambda.X3[j]=delta[1]*lambda0.X3[k_qj[3,j]];}
for (j in 1:J){lambda.X4[j]=delta[1]*lambda0.X4[k_qj[4,j]];}
for (j in 1:J){lambda.X5[j]=delta[1]*lambda0.X5[k_qj[5,j]];}
for (j in 1:J){lambda.X1.X2[j]=delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]];}
for (j in 1:J){\{lambda.X1.X3[j]=delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]];\}}
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for (j in 1:J){lambda.X1.X4[j]=delta[2]*lambda0.X1[k qj[1,j]]*lambda0.X4[k qj[4,j]];}
 for \ (j \ in \ 1:J) \{lambda.X1.X5[j] = delta[2] * lambda0.X1[k_qj[1,j]] * lambda0.X5[k_qj[5,j]]; \}
 for (j in 1:J){lambda.X2.X3[j]=delta[2]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]];}
 for (j in 1:J){lambda.X2.X4[j]=delta[2]*lambda0.X2[k_qj[2,j]]*lambda0.X4[k_qj[4,j]];}
 for (j in 1:J){lambda.X2.X5[j]=delta[2]*lambda0.X2[k_qj[2,j]]*lambda0.X5[k_qj[5,j]];}
 for (j in 1:J){lambda.X3.X4[j]=delta[2]*lambda0.X3[k_qj[3,j]]*lambda0.X4[k_qj[4,j]];}
 for (j in 1:J){lambda.X3.X5[j]=delta[2]*lambda0.X3[k_qj[3,j]]*lambda0.X5[k_qj[5,j]];}
 for (j in 1:J){lambda.X4.X5[j]=delta[2]*lambda0.X4[k_qj[4,j]]*lambda0.X5[k_qj[5,j]];}
 for (j in 1:J){\{lambda.X1.X2.X3[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]
 for (j in 1:J){\{1ambda.X1.X2.X4[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]
 for (j in 1:J){\{1ambda.X1.X2.X5[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]
 for (j in 1:J){1ambda.X1.X3.X4[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]
 for \ (j \ in \ 1:J) \{lambda.X1.X3.X5[j] = delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k
 for (j in 1:J){\{1ambda.X1.X4.X5[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]
 for (j in 1:J){1ambda.X2.X3.X4[j]=delta[3]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]
 for (j in 1:J){1ambda.X2.X3.X5[j]=delta[3]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]
 for (j in 1:J){1ambda.X2.X4.X5[j]=delta[3]*lambda0.X2[k_qj[2,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]
 for (j in 1:J){\{1ambda.X3.X4.X5[j]=delta[3]*lambda0.X3[k_qj[3,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]
 for (j in 1:J){\{lambda.X1.X2.X3.X4[j]=delta[4]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1
 for (j in 1:J){lambda.X1.X2.X3.X5[j]=delta[4]*lambda0.X1[k qj[1,j]]*lambda0.X2[k qj[2,j]]*la
 for \ (j \ in \ 1:J)\{lambda.X1.X2.X4.X5[j]=delta[4]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X2[k\_qj[2,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k\_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k
 for (j in 1:J){lambda.X1.X3.X4.X5[j]=delta[4]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]]*la
 for (j in 1:J){\{1ambda.X2.X3.X4.X5[j]=delta[4]*1ambda0.X2[k_qj[2,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3,j]]*1ambda0.X3[k_qj[3
 for (j in 1:J){lambda.X1.X2.X3.X4.X5[j]=delta[5]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]
 for (k \text{ in } 1:K_q[1])\{lambda0.X1[k]^adnorm(0,1)\}
 for (k \text{ in } 1:K_q[2])\{1 \text{ ambda } 0.X2[k]^d \text{ dnorm } (0,1)\}
 for(k in 1:K_q[3]){lambda0.X3[k]~dnorm(0,1)}
 for (k \text{ in } 1:K_q[4])\{lambda0.X4[k]^dnorm(0,1)\}
 for (k \text{ in } 1:K_q[5]) \{lambda 0.X5[k]^a dnorm(0,1)\}
 for(1 in 1:Q){delta[1]~dnorm(0,1)}
 sigma=abs(sigmarel)
sigma_y=abs(sigma_yrel)
 sigma_yrel~dt(0,1/sqrt(5),1)
 sigmarel^{-}dt(0,1,1)
alpha0~dnorm(0,.1)
                              What it does:
                             \mathsf{set}.\mathsf{seed}(2)\ \mathsf{GG}_{\mathsf{i}}\text{-}\mathsf{Generate}_{a}ll(N=1000,Q=4,p=5)\\ \mathsf{GGXX}\\ K_{a}gibbs.samples < -Transucci.fit(GG)
```

Step 3

- 1. Design a sampling scheme that favors some cells
- 2. Compute Trangucci estimator for θ for the r = 30 realisations.

Step 4

- 1. Use the second model to generate the population, and run the analysis on that model.
- 2. Look at predictions for pop total.
- 1. Assume the following model:

2.

4

BAYESIAN COMPUTATIONS