# Simulations on "Bayesian Hierarchical weighting adjustment and survey inference" by Trangucci et al.

Fall 2018

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# MODEL DESCRIPTION

# 1.1 Trangucci et al. model0

We describe the model given in (?, Sec. 2).

- Population made of H strata  $U_1, ..., U_J$ .
- Stratum *j* size:  $N_j$ , Total size:  $N = \sum_i N_i$
- Sample size in stratum j:  $n_j$
- $\bullet$  *I* vector: sample indicator
- *y* vector: study variable
- $\theta_j$ : average of y in stratum j.  $\theta_j = \sum_{i \in U_j} y_i$ . In the paper there is an ambiguity: First,  $\theta$  is called the "population estimand of interest[...] the overall or domain mean". Ambiguity comes from the term "mean". Is  $\theta = N^{-1} \sum_i y_i$  or Is  $\theta = N^{-1} \sum_k E[y_i]$ ?
- X: Design variables. In the paper  $X^1, ..., X^J$  are badly defined. The idea is that X variables are Q categorical variables. The strata correspond to the cells obtained from these categorical variables.

- denote by  $1, ... K_q$  the categories for variable  $X_q$ .
- denote by j[i] the stratim of unit i
- Denote by k[q, j] the category for variable  $X_q$  in stratum j

Consider the following hierarchical model:

$$y_i \sim \mathcal{N}\left(\theta_{j[i]}^{\star}, \sigma_y^2\right) \tag{1.1}$$

$$\theta_{j}^{\star} = \alpha_{0} + \sum_{\ell=1}^{Q} \left( \sum_{q_{1} < \dots < q_{\ell} \in \{1, \dots, Q\}} \alpha_{j}^{(q_{1}, \dots, q_{\ell})} \right)$$
(1.2)

$$\forall \ell \in \{1, ..., Q\}, \ \forall q_1, ..., q_\ell \in \{1, ..., Q\}, \ \forall j \in \{1, ..., H\} : \alpha_j^{(q_1, ..., q_\ell)} \sim \mathcal{N}(0, (\lambda_j^{(q_1, ..., q_\ell)} \sigma)^2)$$
 (1.3)

$$\forall \ell \in \{1, \dots, Q\}, \ \forall q_1, \dots, q_\ell \in \{1, \dots, Q\}, \ \forall j \in \{1, \dots, H\} : \lambda_j^{(q_1, \dots, q_\ell)} = \delta^{(\ell)} \prod_{l=1}^{\ell} \gamma_{k[q_l, j]}^{(q_l)}$$

$$(1.4)$$

$$\sigma \sim \text{Cauchy}_{+}(0,1) \tag{1.5}$$

$$\forall q \in \{1, \dots, Q\}, \ k \in \{1, \dots, K_q\} : \gamma_k^{(q)} \sim \mathcal{N}_+(0, 1)$$
(1.6)

$$\delta^{(\ell)} \sim \mathcal{N}_{+}(0,1) \tag{1.7}$$

$$\sigma_v \sim \text{Cauchy}_+(0,5)$$
 (1.8)

$$\alpha_0 \sim \mathcal{N}(0, 10) \tag{1.9}$$

Note I made up the prior on  $\alpha_0$  as I did not find in the paper.

## 1.2 Competing model

We describe a competing model.

Consider the following hierarchical model:

$$y_i \sim \mathcal{N}\left(\theta_{i[i]}^{\mathcal{Q}}, \sigma_y^2\right)$$
 (1.10)

$$(\theta_j^{\mathcal{Q}})_{j=1}^Q \sim \mathcal{N}(0, \Sigma)$$
 (1.11)

$$\Sigma_{i_1, i_2} = \sigma^2 D_{\alpha}(j_1, j_2) \tag{1.12}$$

$$D_{\alpha}(j_1, j_2) = \sigma_y^2 \left( \exp\left( -\sum_{q=1}^{Q} \alpha_q(k[q, j_1] \neq k[q, j_2]) \right) \right)$$
 (1.13)

$$\sigma_{y} \sim \text{Cauchy}_{+}(0,5) \tag{1.14}$$

$$\alpha_q \sim \text{Cauchy}_+(0,1)$$
 (1.15)

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# **DATA GENERATION**

### Step 1

Create procedures that can

- 1. generate a population of size N and with Q random categorical variables  $X_1, ..., X_Q$ .  $X_q$  is generated by drawing with replacement in  $\{1, ..., K_q\}$  where  $K_q > 1$ ,  $K_q$  can be generated by drawing from  $\mathcal{U}_{1,...,p}$ .
- 2. compute the corresponding stratum j = 1,...,J and the correspondances  $(k[q,j])_{j=1,...,J,q=1,...,Q}$ .
- 3. generate, for such a population, the hyper parameters  $\sigma_v$ ,  $\alpha_0$ ,  $(\delta^\ell)_{\ell=1,\dots,Q}$ ,  $\lambda_k^l$ ,  $\sigma$ .
- 4. compute the  $\lambda_{k_1,\ldots,k_\ell}^{(q_1,\ldots,q_\ell)}$ , for possible values of  $k_1,\ldots,k_\ell^{(q_1,\ldots,q_\ell)}$ .
- 5. generate the  $\alpha_{j,(k_1,\ldots,k_\ell)}^{(q_1,\ldots,q_\ell)}$
- 6. compute  $\theta^*$ .
- 7. generate a number r of realisations of y for such hyperparameters and such strata.
- 8. Set seed.
- 9. Create a population with N = 10000, Q = 2, p = 5. Display  $J, N_j, \theta^*$ .
- 1. To generate the population and stratification variables we use the function SimuTrangucci::Gen\_design\_variables:

```
?SimuTrangucci::Gen_design_variables
XX=SimuTrangucci::Gen_design_variables()
```

- 2.
- 3.
- 4.

5.

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9. 9. This are tables we obtained with different seeds.

Table 2.1:

	$X_1$	$X_2$	Stratum (j)	$N_{j}$	θ*
S1	1	1	S1	113	-5.151
S2	1	2	S2	111	-3.938
S3	1	3	S3	119	-2.698
S4	2	1	S4	101	-0.163
S5	2	2	S5	106	-4.607
S6	2	3	S6	105	-1.853
S7	3	1	S7	140	0.434
S8	3	2	S8	104	-1.733
S9	3	3	S9	101	-6.088

Table 2.2:

	$X_1$	$X_2$	Stratum (j)	$N_j$	$\theta^{\star}$
S1	1	1	S1	91	3.215
S2	1	2	S2	73	0.055
S3	1	3	S3	83	2.687
S4	1	4	S4	86	2.681
S5	2	1	S5	91	-5.146
S6	2	2	S6	82	-10.338
S7	2	3	S7	80	3.576
S8	2	4	S8	78	0.260
S9	3	1	S9	95	6.074
S10	3	2	S10	80	0.900
S11	3	3	S11	91	2.567
<u>S12</u>	3	4	S12	70	-4.289

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# **BAYESIAN COMPUTATIONS**

### Step 1

Using Jags,

- 1. Draw posterior distribution of  $\theta_j^*$  for the largest value of  $\theta_j^*$ , obtained from the observation of  $v^{(1)}$  only. Add real value of  $\theta_1$  and prediction to the plot.
- 2. Draw distribution of predictions of  $\theta_i^*$ . Add real value of  $\theta_j$  to the plot.
- 3. Draw real values of all  $\theta_i^*$  vs r = 30 predictions.

Some functions to generate the jags model file:

```
library(SimuTrangucci)
library(R2jags)
library(ggplot2)
library(plyr)
GG<-Generate_all(N=1000,Q=2,p=5)
x<-model.text(GG);x</pre>
```

```
model{
for(i in 1:N){y[i]~dnorm(thetastar[j_i[i]],1/sqrt(sigma_y^2));}
for (j in 1:J){thetastar[j]=alpha0+alpha.X1[j]+alpha.X2[j]+alpha.X1.X2[j];}
for (j in 1:J){alpha.X1[j]~dnorm(0,1/sqrt(lambda.X1[j]*sigma^2));}
for (j in 1:J){alpha.X2[j]~dnorm(0,1/sqrt(lambda.X2[j]*sigma^2));}
for (j in 1:J){alpha.X1.X2[j]~dnorm(0,1/sqrt(lambda.X1.X2[j]*sigma^2));}
for (j in 1:J){lambda.X1[j]=delta[1]*lambda0.X1[k_qj[1,j]];}
for (j in 1:J){lambda.X2[j]=delta[1]*lambda0.X2[k_qj[2,j]];}
for (j in 1:J){lambda.X1.X2[j]=delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]];}
for(k in 1:K_q[1]){lambda0.X1[k]~dnorm(0,1)}
for(k in 1:K_q[2]){lambda0.X2[k]~dnorm(0,1)}
for(l in 1:0){delta[1]~dnorm(0,1)}
sigma=abs(sigmarel)
sigma_y=abs(sigma_yrel)
sigma_yrel~dt(0,1/sqrt(5),1)
```

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```
sigmarel^{\sim}dt(0,1,1)
alpha0^{\sim}dnorm(0,.1)
   GG<-Generate_all(N=1000,Q=5,p=5)
   x < - model.text(GG);x
model{
for(i in 1:N){y[i]~dnorm(thetastar[j_i[i]],1/sqrt(sigma_y^2));}
for \ (j \ in \ 1:J) \{thetastar[j]=alpha0+alpha.X1[j]+alpha.X2[j]+alpha.X3[j]+alpha.X4[j]+alpha.X5[j]+alpha.X4[j]+alpha.X5[j]+alpha.X4[j]+alpha.X5[j]+alpha.X4[j]+alpha.X5[j]+alpha.X4[j]+alpha.X5[j]+alpha.X4[j]+alpha.X4[j]+alpha.X5[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X5[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j]+alpha.X4[j
for (j in 1:J){alpha.X1[j]~dnorm(0,1/sqrt(lambda.X1[j]*sigma^2));}
for (j in 1:J){alpha.X2[j]~dnorm(0,1/sqrt(lambda.X2[j]*sigma^2));}
for (j in 1:J){alpha.X3[j]~dnorm(0,1/sqrt(lambda.X3[j]*sigma^2));}
for (j in 1:J){alpha.X4[j]~dnorm(0,1/sqrt(lambda.X4[j]*sigma^2));}
for (j in 1:J){alpha.X5[j]~dnorm(0,1/sqrt(lambda.X5[j]*sigma^2));}
for (j in 1:J){alpha.X1.X2[j]~dnorm(0,1/sqrt(lambda.X1.X2[j]*sigma^2));}
for (j in 1:J){alpha.X1.X3[j]~dnorm(0,1/sqrt(lambda.X1.X3[j]*sigma^2));}
for (j in 1:J){alpha.X1.X4[j]~dnorm(0,1/sqrt(lambda.X1.X4[j]*sigma^2));}
for (j in 1:J){alpha.X1.X5[j]~dnorm(0,1/sqrt(lambda.X1.X5[j]*sigma^2));}
for (j in 1:J){alpha.X2.X3[j]~dnorm(0,1/sqrt(lambda.X2.X3[j]*sigma^2));}
for (j in 1:J){alpha.X2.X4[j]~dnorm(0,1/sqrt(lambda.X2.X4[j]*sigma^2));}
for (j in 1:J){alpha.X2.X5[j]~dnorm(0,1/sqrt(lambda.X2.X5[j]*sigma^2));}
for (j in 1:J){alpha.X3.X4[j]~dnorm(0,1/sqrt(lambda.X3.X4[j]*sigma^2));}
for (j in 1:J){alpha.X3.X5[j]~dnorm(0,1/sqrt(lambda.X3.X5[j]*sigma^2));}
for (j in 1:J){alpha.X4.X5[j]~dnorm(0,1/sqrt(lambda.X4.X5[j]*sigma^2));}
for (j in 1:J){alpha.X1.X2.X3[j]~dnorm(0,1/sqrt(lambda.X1.X2.X3[j]*sigma^2));}
for (j in 1:J){alpha.X1.X2.X4[j]~dnorm(0,1/sqrt(lambda.X1.X2.X4[j]*sigma^2));}
for (j in 1:J){alpha.X1.X2.X5[j]~dnorm(0,1/sqrt(lambda.X1.X2.X5[j]*sigma^2));}
for (j in 1:J){alpha.X1.X3.X4[j]~dnorm(0,1/sqrt(lambda.X1.X3.X4[j]*sigma^2));}
for (j in 1:J){alpha.X1.X3.X5[j]~dnorm(0,1/sqrt(lambda.X1.X3.X5[j]*sigma^2));}
for (j in 1:J){alpha.X1.X4.X5[j]~dnorm(0,1/sqrt(lambda.X1.X4.X5[j]*sigma^2));}
for (j in 1:J){alpha.X2.X3.X4[j]~dnorm(0,1/sqrt(lambda.X2.X3.X4[j]*sigma^2));}
for (j in 1:J){alpha.X2.X3.X5[j]~dnorm(0,1/sqrt(lambda.X2.X3.X5[j]*sigma^2));}
for (j in 1:J){alpha.X2.X4.X5[j]~dnorm(0,1/sqrt(lambda.X2.X4.X5[j]*sigma^2));}
for (j in 1:J){alpha.X3.X4.X5[j]~dnorm(0,1/sqrt(lambda.X3.X4.X5[j]*sigma^2));}
for (j in 1:J){alpha.X1.X2.X3.X4[j]~dnorm(0,1/sqrt(lambda.X1.X2.X3.X4[j]*sigma^2));}
for (j in 1:J){alpha.X1.X2.X3.X5[j]~dnorm(0,1/sqrt(lambda.X1.X2.X3.X5[j]*sigma^2));}
for (j in 1:J){alpha.X1.X2.X4.X5[j]~dnorm(0,1/sqrt(lambda.X1.X2.X4.X5[j]*sigma^2));}
for (j in 1:J){alpha.X1.X3.X4.X5[j]~dnorm(0,1/sqrt(lambda.X1.X3.X4.X5[j]*sigma^2));}
for (j in 1:J){alpha.X2.X3.X4.X5[j]~dnorm(0,1/sqrt(lambda.X2.X3.X4.X5[j]*sigma^2));}
for (j in 1:J){alpha.X1.X2.X3.X4.X5[j]~dnorm(0,1/sqrt(lambda.X1.X2.X3.X4.X5[j]*sigma^2));}
for (j in 1:J){lambda.X1[j]=delta[1]*lambda0.X1[k_qj[1,j]];}
for (j in 1:J){lambda.X2[j]=delta[1]*lambda0.X2[k_qj[2,j]];}
for (j in 1:J){lambda.X3[j]=delta[1]*lambda0.X3[k_qj[3,j]];}
for (j in 1:J){lambda.X4[j]=delta[1]*lambda0.X4[k_qj[4,j]];}
for (j in 1:J){lambda.X5[j]=delta[1]*lambda0.X5[k_qj[5,j]];}
for (j in 1:J){lambda.X1.X2[j]=delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]];}
for \ (j \ in \ 1:J) \{lambda.X1.X3[j] = delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]]; \}
for (j in 1:J){\{lambda.X1.X4[j]=delta[2]*lambda0.X1[k_qj[1,j]]*lambda0.X4[k_qj[4,j]];\}}
```

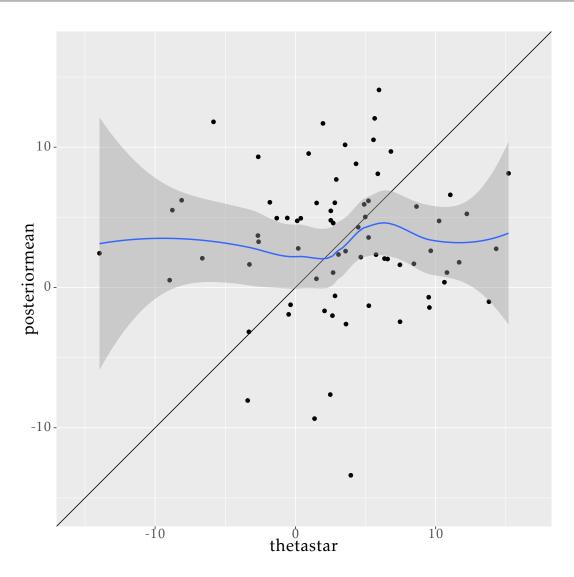
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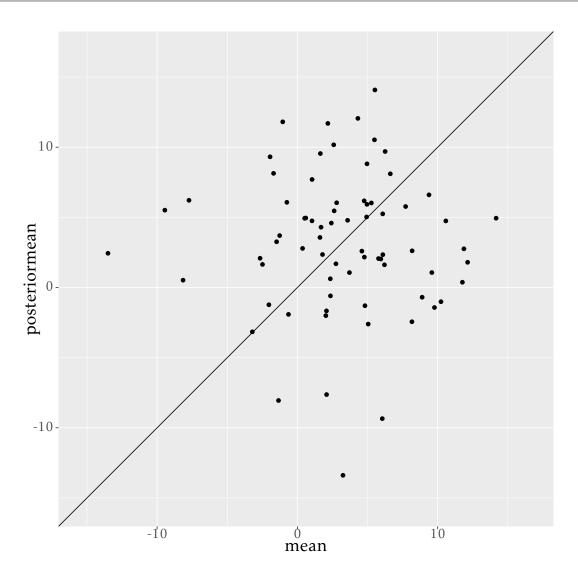
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for \ (j \ in \ 1:J) \{lambda.X1.X5[j] = delta[2] * lambda0.X1[k_qj[1,j]] * lambda0.X5[k_qj[5,j]]; \}
 for (j in 1:J){lambda.X2.X3[j]=delta[2]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]];}
 for (j in 1:J){lambda.X2.X4[j]=delta[2]*lambda0.X2[k_qj[2,j]]*lambda0.X4[k_qj[4,j]];}
 for (j in 1:J){lambda.X2.X5[j]=delta[2]*lambda0.X2[k_qj[2,j]]*lambda0.X5[k_qj[5,j]];}
 for (j in 1:J){lambda.X3.X4[j]=delta[2]*lambda0.X3[k_qj[3,j]]*lambda0.X4[k_qj[4,j]];}
 for (j in 1:J){lambda.X3.X5[j]=delta[2]*lambda0.X3[k_qj[3,j]]*lambda0.X5[k_qj[5,j]];}
 for (j in 1:J){\{1ambda.X4.X5[j]=delta[2]*lambda0.X4[k_qj[4,j]]*lambda0.X5[k_qj[5,j]];\}}
 for \ (j \ in \ 1:J) \{lambda.X1.X2.X3[j] = delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k
 for (j in 1:J){\{1ambda.X1.X2.X4[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]
 for (j in 1:J){\{1ambda.X1.X2.X5[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]
 for (j in 1:J){\{1ambda.X1.X3.X4[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]
 for (j in 1:J){1ambda.X1.X3.X5[j]=delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]
 for \ (j \ in \ 1:J) \{lambda.X1.X4.X5[j] = delta[3]*lambda0.X1[k_qj[1,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k
 for (j in 1:J){1ambda.X2.X3.X4[j]=delta[3]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]
 for (j in 1:J){1ambda.X2.X3.X5[j]=delta[3]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]
 for \ (j \ in \ 1:J) \{lambda.X2.X4.X5[j] = delta[3]*lambda0.X2[k\_qj[2,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k\_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k
 for (j in 1:J){1ambda.X3.X4.X5[j]=delta[3]*lambda0.X3[k_qj[3,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]*lambda0.X4[k_qj[4,j]]
 for (j in 1:J){\{lambda.X1.X2.X3.X4[j]=delta[4]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1
 for (j in 1:J){\{lambda.X1.X2.X3.X5[j]=delta[4]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1,j]]*lambda0.X1[k_qj[1
 for (j in 1:J){lambda.X1.X2.X4.X5[j]=delta[4]*lambda0.X1[k qj[1,j]]*lambda0.X2[k qj[2,j]]*la
for \ (j \ in \ 1:J)\{lambda.X1.X3.X4.X5[j]=delta[4]*lambda0.X1[k\_qj[1,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k\_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k_qj[3,j]]*lambda0.X3[k
 for (j in 1:J){lambda.X2.X3.X4.X5[j]=delta[4]*lambda0.X2[k_qj[2,j]]*lambda0.X3[k_qj[3,j]]*la
 for (j in 1:J){lambda.X1.X2.X3.X4.X5[j]=delta[5]*lambda0.X1[k_qj[1,j]]*lambda0.X2[k_qj[2,j]]
 for(k in 1:K q[1]){lambda0.X1[k]~dnorm(0,1)}
 for (k \text{ in } 1:K_q[2]) \{lambda 0.X2[k]^d norm(0,1)\}
 for (k \text{ in } 1:K_q[3]) \{lambda0.X3[k]^a dnorm(0,1)\}
 for(k in 1:K_q[4]){lambda0.X4[k]~dnorm(0,1)}
 for(k in 1:K q[5]){lambda0.X5[k]~dnorm(0,1)}
 for(1 in 1:Q){delta[1]~dnorm(0,1)}
 sigma=abs(sigmarel)
 sigma_y=abs(sigma_yrel)
 sigma_yrel~dt(0,1/sqrt(5),1)
 sigmarel^{\sim}dt(0,1,1)
alpha0^{\sim}dnorm(0,.1)
                               What it does:
                      set.seed(2)
                     GG < -Generate_all(N=1000, Q=4, p=5)
                     GG$XX$K_q
                      gibbs.samples<-Trangucci.fit(GG)
```

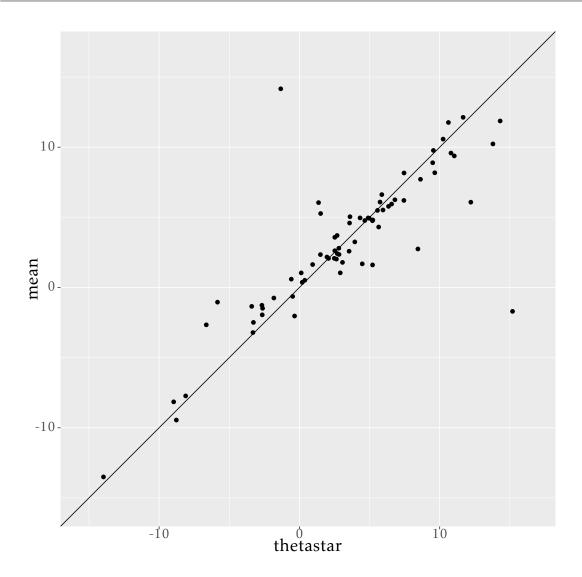
[1] 3 2 3 4

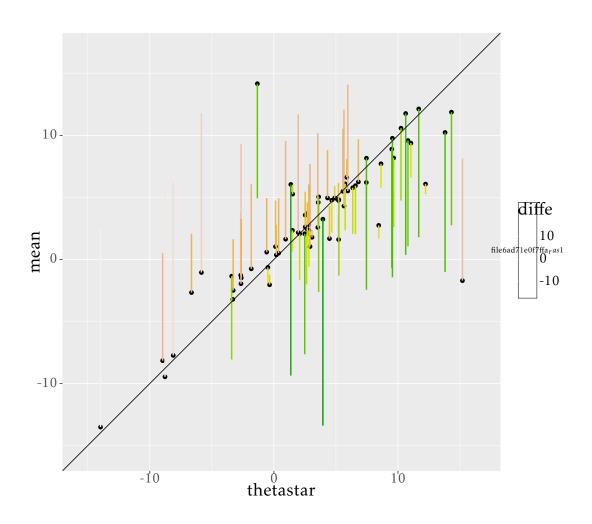
```
 X = \text{data.frame} (j=1:GG\$XX\$J, \text{thetastar} = GG\$ \text{thetastar}, \textbf{t} (gibbs.samples[[1]]\$BUGS \text{output}\$ \text{sims.} \\ \text{list}\$ \text{thetastar} [sample (nrow (gibbs.samples[[1]]\$BUGS \text{output}\$ \text{sims.list}\$ \text{thetastar}), 100) \\ ,])) \\ \text{names} (X[3:ncol(X)]) <-\text{paste0} ("rep", 1: (ncol(X)-2)) \\ XX <-\text{reshape2} :: \text{melt} (X, \text{id.vars} = \text{c} ("j", "\text{thetastar}"), \text{value.name} = "sample") \\ \text{graph1} <-\text{ggplot} (XX, \text{aes} (x=\text{thetastar}, y=\text{sample})) + \text{geom\_point} () + \text{geom\_abline} (\text{slope} = 1, \text{intercept} = 0) + \\ \end{aligned}
```

```
geom_point(aes(x=thetastar,y=thetastar,colour="red"))
XXX < -plyr:: ddply(cbind(GG\$XX\$Xd,y=GG\$y[,1]), ~ \texttt{Strata, function(d)} \\ \{data.frame(mean=mean(d,y), fine (d,y), fine (d,y
YYY<-data.frame(thetastar=GG$thetastar,posteriormean=as.vector(gibbs.samples[[2]]$
           BUGSoutput$mean$thetastar),GG$XX$Strata)
ZZZ<-merge(XXX,YYY,by="Strata")</pre>
ZZZ<-ZZZ[order(ZZZ$thetastar),]
ZZZ$ j <- 1: nrow(ZZZ)
ZZZ$diffe<-ZZZ$posteriormean-ZZZ$mean
graph5<-ggplot(ZZZ,aes(x=thetastar,</pre>
                                                                                                                             y=mean))+geom_point()+geom_segment(aes(x =
           thetastar, y =mean , xend = thetastar, yend = posteriormean,colour=diffe),linejoin="
          mitre",size=1)+geom_abline(slope=1,intercept=0) +
         scale_colour_gradientn(colours = terrain.colors(10))
r<-ggplot_build(graph5)$layout$panel_params[[1]]$x.range
s<-ggplot_build(graph5)$layout$panel_params[[1]]$y.range
t < -c(min(r[1],s[1]),max(r[2],s[2]))
graph5<-graph5+coord_equal(xlim=t,ylim=t)</pre>
graph4<-ggplot(ZZZ,aes(x=thetastar,
                                                                                                                              y=mean))+geom_point()+geom_abline(slope=1,
           intercept=0)+coord_equal(xlim=t,ylim=t)
graph2<-ggplot(ZZZ,aes(x=thetastar,y=posteriormean))+geom_point()+geom_abline(slope=1,
           intercept=0)+coord_equal(xlim=t,ylim=t)+geom_smooth()
                                                                                                             y=posteriormean))+geom_point()+geom_abline(slope=1,
graph3<-ggplot(ZZZ,aes(x=mean,</pre>
           intercept=0)+coord_equal(xlim=t,ylim=t)
graph6 < -ggplot(reshape2::melt(ZZZ[c("j","thetastar","mean","posteriormean")], id.vars=c("mean","posteriormean")], id.vars=c("mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean","mean",
           j")),aes(x=j,y=value,colour=variable))+geom_line()
graph7<-ggplot(reshape2::melt(ZZZ[c("j","thetastar","posteriormean")],id.vars=c("j")),
          aes(x=j,y=value,colour=variable))+geom_line()
         geom_vline(xintercept=GG$hyper$sigma,colour="red")
         geom_vline(xintercept=GG$hyper$sigma_y,colour="red")
         geom_vline(xintercept=GG$lambda$`3`[1],colour="red")
         geom\_vline (xintercept = GG\$lambda\$`3`[1], colour = "red")
                geom_vline(xintercept=GG$hyper$delta[2],colour="red")
                geom_vline(xintercept=GG$hyper$delta[3],colour="red")
ggplot(X,aes(x,y))+geom_point()+geom_abline(intercept=0,slope=1)
```









### Step 2

same thing with Stan

### Step 3

- 1. Design a sampling scheme that favors some cells
- 2. Compute Trangucci estimator for  $\theta$  for the r = 30 realisations.

### Step 4

- 1. Use another model to generate the population, a model that does not fit the current one, to fail the product structure.
- 2. Look at predictions for pop total.

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1. Assume the following model:

2.

4

# **BAYESIAN COMPUTATIONS**