

3. Math primer and preface to Deep Learning

3.3 Matrix factorization and decomposition

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Index

- Introduction to Matrix Decomposition
- Common Types of Matrix Factorization
- Uses for Matrix Decomposition



Introduction to Matrix Decomposition



Introduction to Matrix Decomposition

Matrix decomposition, also called **matrix factorization**, is the factorization of a matrix into the product of two or more matrices.

- This process helps to optimize solving systems of linear equations; and
- It helps finding eigenvalues and eigenvectors.



Common Types of Matrix Factorization



Common Types of Matrix Factorization

The **LU (Lower, Upper) decomposition** factors a matrix $\mathbf{A} = \mathbf{LU}$ into a lower triangular \mathbf{L} and an upper triangular \mathbf{U} matrix.

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix} \times \begin{bmatrix} u_{11} & u_{12} & u_{13} \\ 0 & u_{22} & u_{23} \\ 0 & 0 & u_{33} \end{bmatrix}$$

The factorization improves the process of repeatedly solving a system of linear equations.



Common Types of Matrix Factorization

The **QR decomposition** is the factorization of a matrix $\mathbf{A} = \mathbf{QR}$, where \mathbf{Q} is an orthogonal matrix and \mathbf{R} is an upper triangular matrix. \mathbf{A} does not need to be a square matrix.

$$\mathbf{A} = \begin{bmatrix} q_{11} & q_{12} & q_{13} & \dots \\ q_{21} & q_{22} & q_{23} & \dots \\ q_{31} & q_{32} & q_{33} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix} \times \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots \\ 0 & a_{22} & a_{23} & \dots \\ 0 & 0 & a_{33} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

It's an important step for solving linear least squares problems, for computing the eigenvalues and eigenvectors of a matrix and for the SVD decomposition.



Common Types of Matrix Factorization

The **singular value decomposition, or SVD**, is a generalization of the eigendecomposition for a **A** non-square matrix. **A** = **U****Σ****V**^t where **U** and **V**^t are orthogonal matrices and called the left and right singular vectors of **A** and **Σ** is a diagonal matrix with positive real numbers on the diagonal known as the singular values of **A**.

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \\ a_{41} & a_{42} & a_{43} \\ a_{51} & a_{52} & a_{53} \end{bmatrix} = \begin{bmatrix} u_{11} & u_{12} & u_{13} & 0 & 0 \\ u_{21} & u_{22} & u_{23} & 0 & 0 \\ u_{31} & u_{32} & u_{33} & 0 & 0 \\ u_{41} & u_{42} & u_{43} & 0 & 0 \\ u_{51} & u_{52} & u_{53} & 0 & 0 \end{bmatrix} \times \begin{bmatrix} \sigma_{11} & 0 & 0 \\ 0 & \sigma_{22} & 0 \\ 0 & 0 & \sigma_{33} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} v_{11} & v_{21} & v_{31} \\ v_{12} & v_{22} & v_{32} \\ v_{13} & v_{23} & v_{33} \end{bmatrix}$$

$$A_{m \times n} = U_{m \times m} \Sigma_{m \times n} V_{n \times n}^t \text{ where } m > n$$



Common Types of Matrix Factorization

The **singular value decomposition, or SVD**, is a generalization of the eigendecomposition for a **A** non-square matrix. **A** = **U****Σ****V**^t where **U** and **V**^t are orthogonal matrices and called the left and right singular vectors of **A** and **Σ** is a diagonal matrix with positive real numbers on the diagonal known as the singular values of **A**.

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} & a_{15} \\ a_{21} & a_{22} & a_{23} & a_{24} & a_{25} \\ a_{31} & a_{32} & a_{33} & a_{34} & a_{35} \end{bmatrix} = \begin{bmatrix} u_{11} & u_{12} & u_{13} \\ u_{21} & u_{22} & u_{23} \\ u_{31} & u_{32} & u_{33} \end{bmatrix} \times \begin{bmatrix} \sigma_{11} & 0 & 0 & 0 & 0 \\ 0 & \sigma_{22} & 0 & 0 & 0 \\ 0 & 0 & \sigma_{33} & 0 & 0 \end{bmatrix} \times \begin{bmatrix} v_{12} & v_{22} & v_{32} & v_{42} & v_{52} \\ v_{11} & v_{21} & v_{31} & v_{41} & v_{51} \\ v_{13} & v_{32} & v_{33} & v_{43} & v_{53} \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$A_{m \times n} = U_{m \times m} \Sigma_{m \times n} V_{n \times n}^t \text{ where } m < n$$



Uses for Matrix Decomposition



Uses for Matrix Decomposition

In an overdetermined linear system, a system with more equations than the number of variables, **linear least squares (LLS)** is a method for finding the best-fit solution which minimizes the difference between the data and the corresponding modeled values.

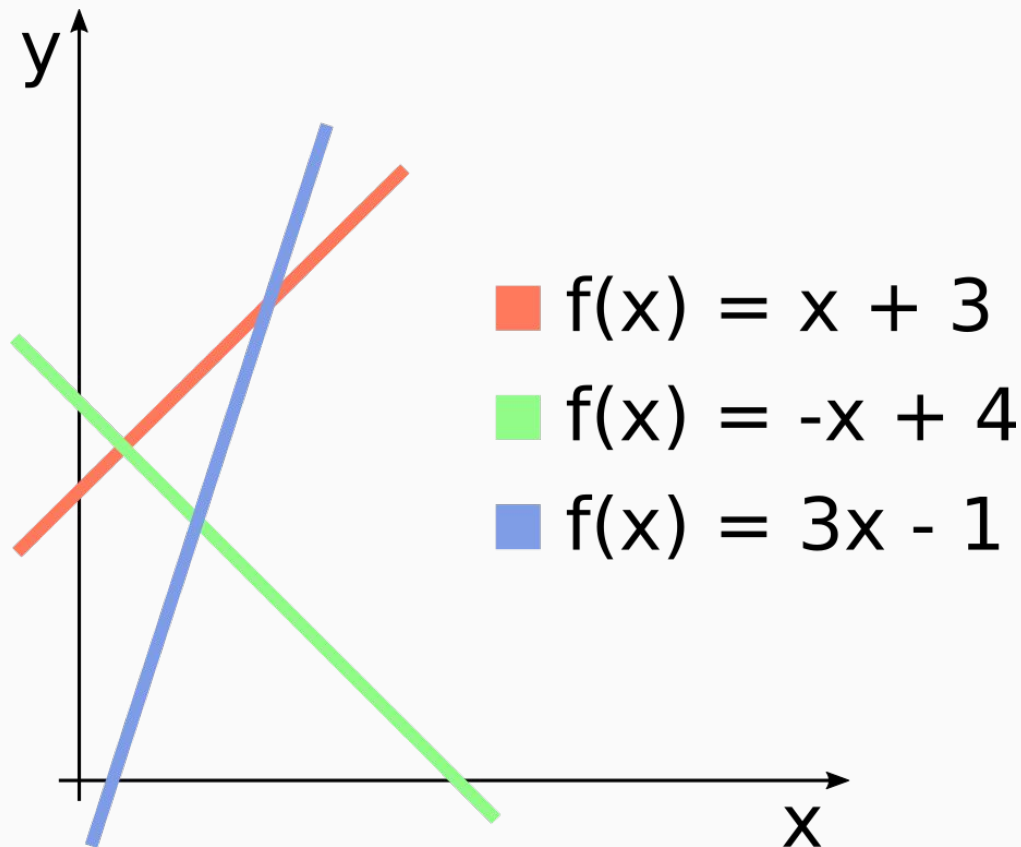


Uses for Matrix Decomposition

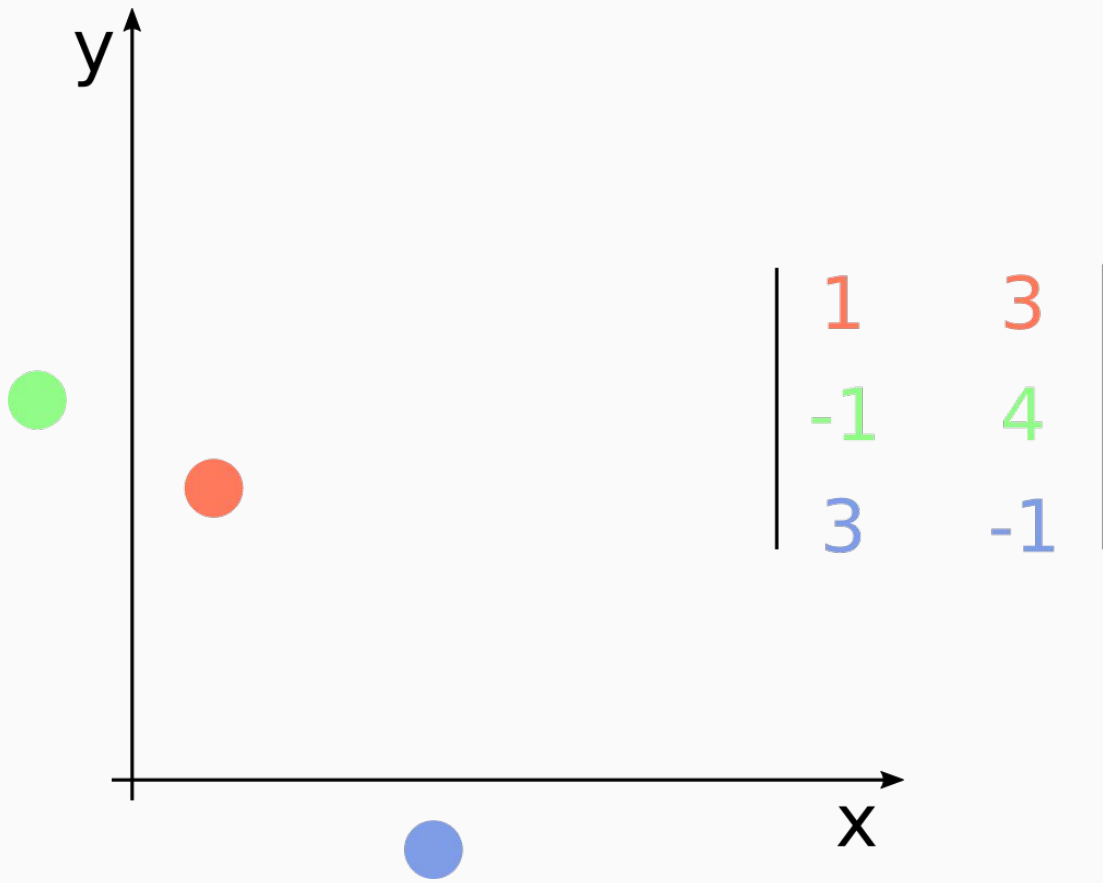
On its turn, **principal component analysis (PCA)** is used to find the best fitting line that minimizes the distance from all data points to a line going through these points.



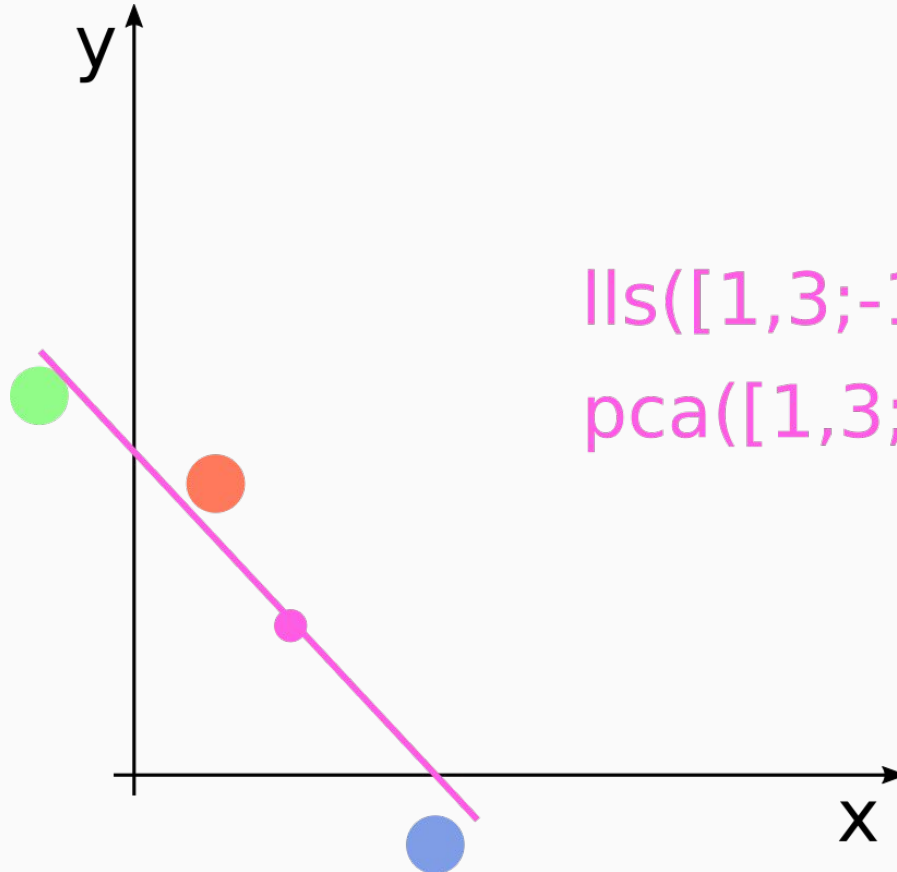
Uses for Matrix Decomposition



Uses for Matrix Decomposition



Uses for Matrix Decomposition



$\text{ls}([1,3;-1,4;3,-1],v)$

$\text{pca}([1,3;-1,4;3,-1])$

