Comp Vision: Robot Vision - CSCI 442 001 201730



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Due February 22nd

Two part assignment.....using Python and OpenCV you need to do the following two parts (it can be two different applications, or one).

Part One:

Tracking an object

Steps to do it properly.....

- 1. Capture live video from Webcam
- 2. Display live video
- 3. convert to HSV
- 4. Display the HSV video
- 5. Click on HSV video and capture the values at that location, and a few other local values
 - 1. use a MouseCallback
- 6. Using Sliders create scalers for the min and max values you want to track
 - 1. a Scalar will be a numpy array (np.array) that takes 3 values for minH, minS, and minV......then a second scalar to catch the other three Max values
 - 2. createTrackbar with a callback method to set your variables
- 7. Us the inRange method to find the values between the scalars from HSV image and the result will go to a grayscale image.
- 8. dilate, erode the grayscale image to get a better representation of the object
- 9.

Part Two

Detect Motion

The Steps I took in the example I showed in class.

<u>Video Explanation</u> (this shows it working in Visual Studio, but we're using Python, I'll show that in class).

- 1. Capture an image
- 2. Create blank images:
 - 1. grayscale image with proper dimensions
 - 2. 32f, 3 channel image
 - 3. a capture clone we'll call image1
 - 4. One to hold the difference
- 3. while loop
- 4. grab new frame
 - 1 I brightened image a bit first which helped

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- 1. I originalea mage a on moi winen neipea
- 5. blur image
- 6. take running average of frame: accumulateWeighted
- 7. swap running average to same format as frame: convertScaleAbs
- 8. Take difference
- 9. convert to grayscale
- 10. threshhold grayscale (low number)
- 11. blur grayscale
- 12. threshhold grayscale (high number)
- 13. find contours: findContours
- 14. Use contours to find significant blobs,

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