

# *Analysing Urban Mobility Systems from Different Perspectives: a Multi-Level Schema*

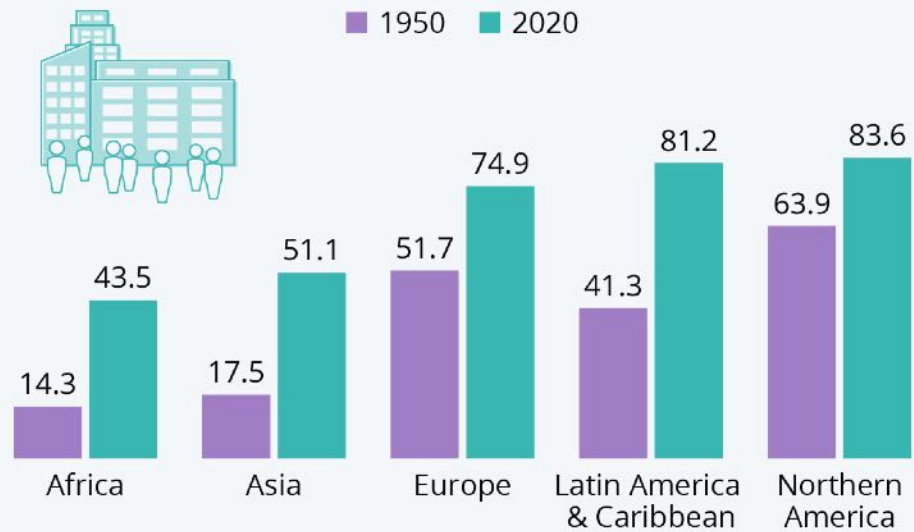
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## Then & Now Urban Population Worldwide

Share of the urban population by continent in 1950 and 2020 (in percent)



Source: U.N. Population Division

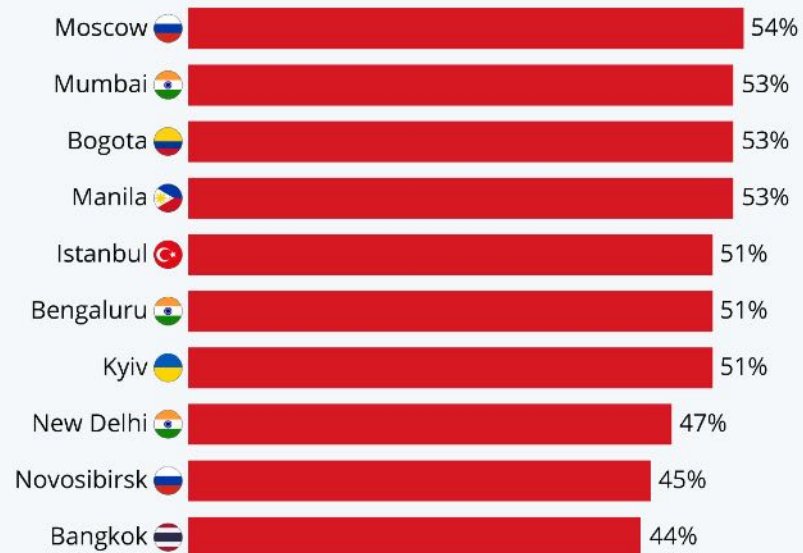


statista

# Urbanization worldwide

## The Cities With The Worst Traffic Congestion

Cities with the highest average traffic congestion levels in 2020\*



\* 0% = uncongested free flow of traffic - e.g. 35% congestion means the extra travel time is 35% more than the average trip in uncongested conditions.

Source: TomTom Traffic Index



statista

# Urbanization and traffic

# STREET SPACE FOR 60 PEOPLE



Press office, City of Münster, Germany

“The way  
we move”...  
and traffic  
implications

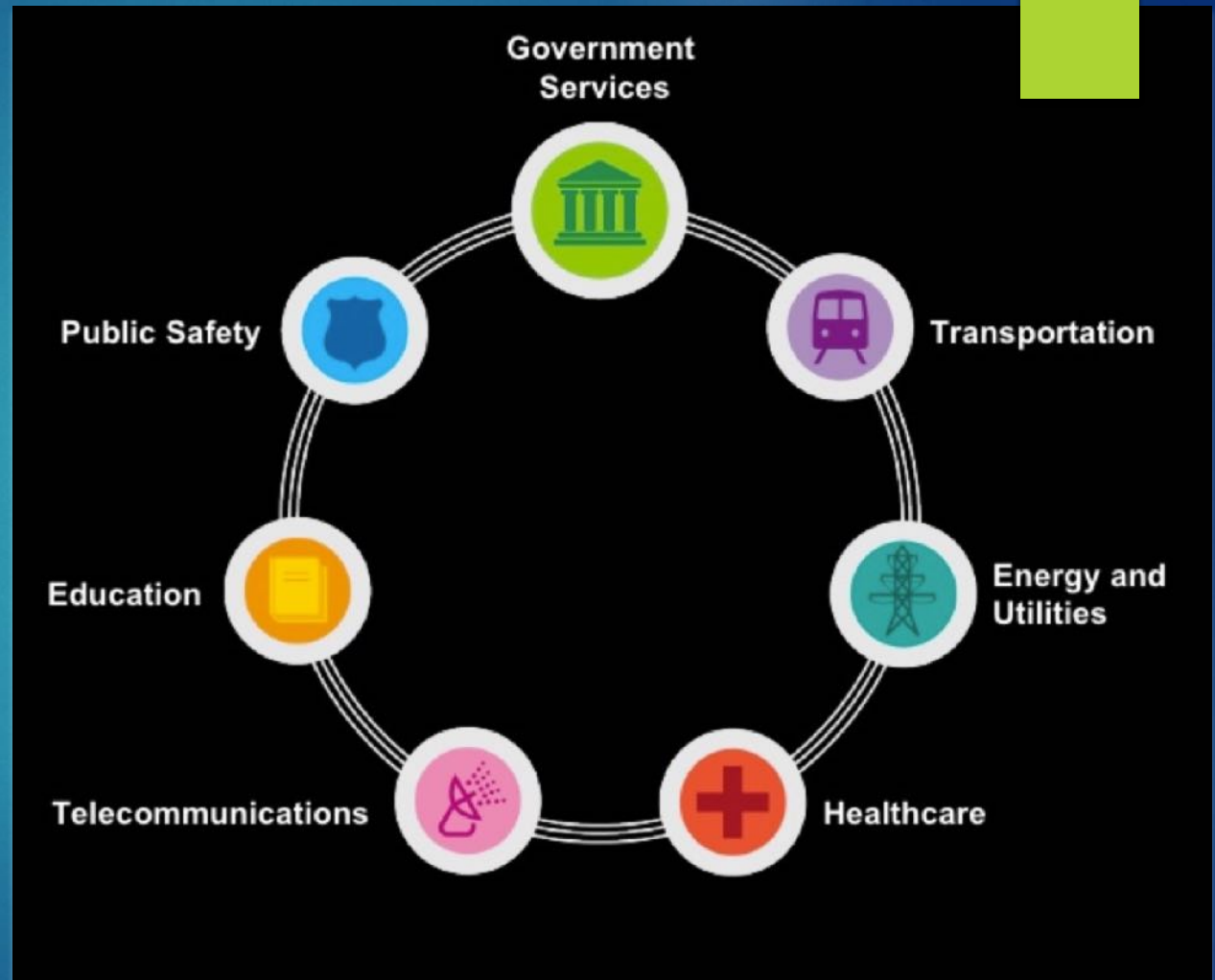
# “The way we move”... and traffic implications





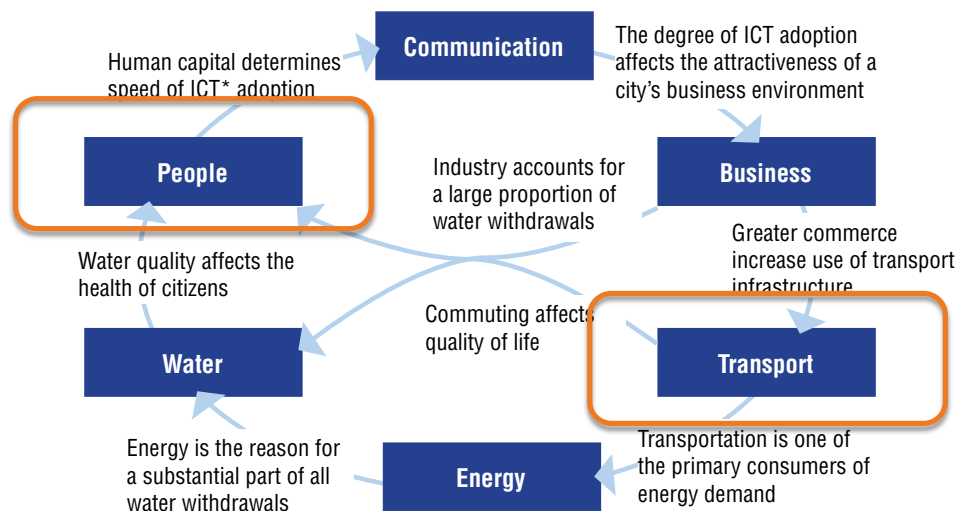
# Smart cities to the rescue?

- ▶ The concept is getting a bit long in the tooth...
- ▶ But even though it was abused initially the perspective makes sense and should be pursued

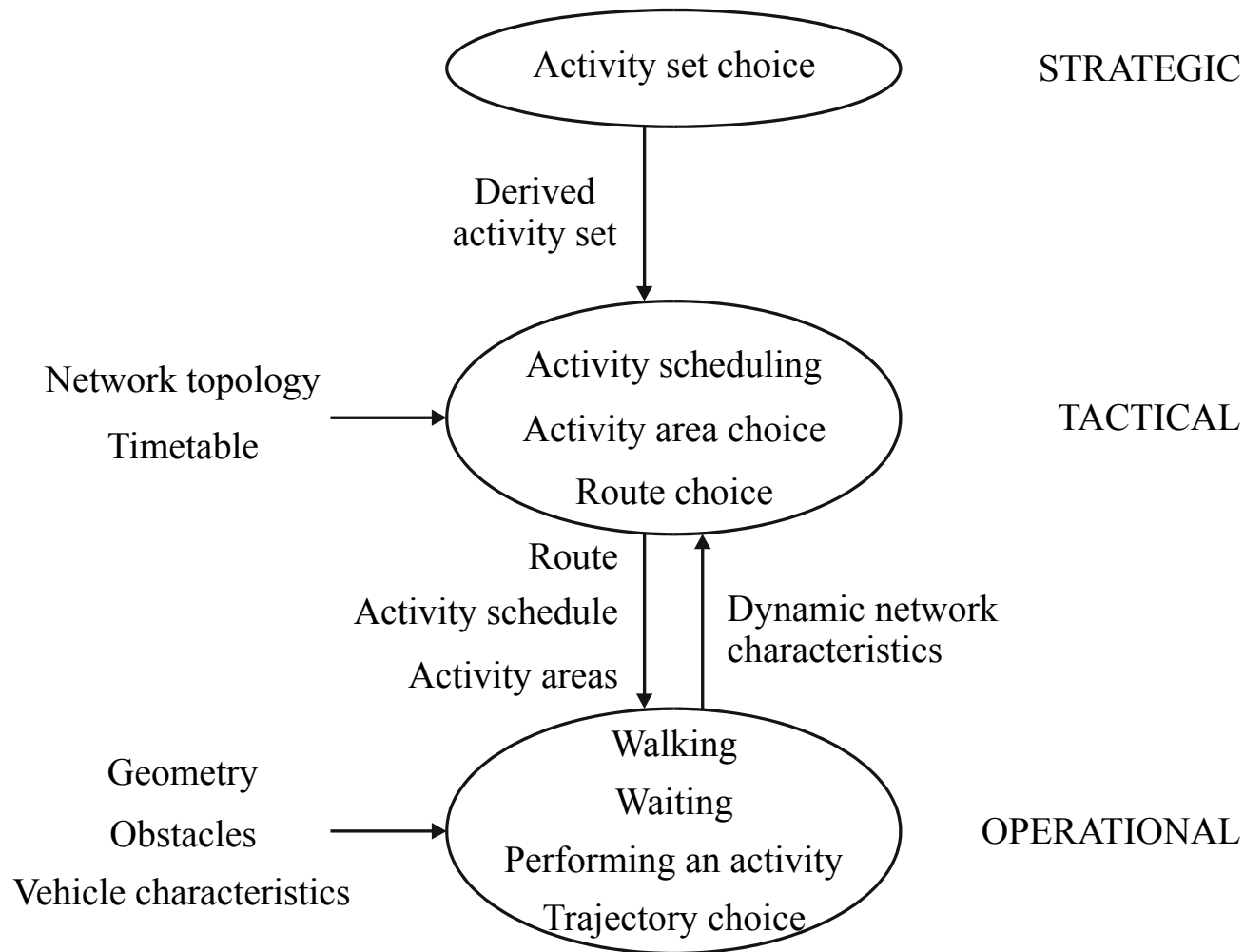


# Smart cities to the rescue?

Sample of interrelationships between core city systems.



*\*Note: ICT=Information and communications technology.  
Source: IBM Center for Economic Development analysis.*



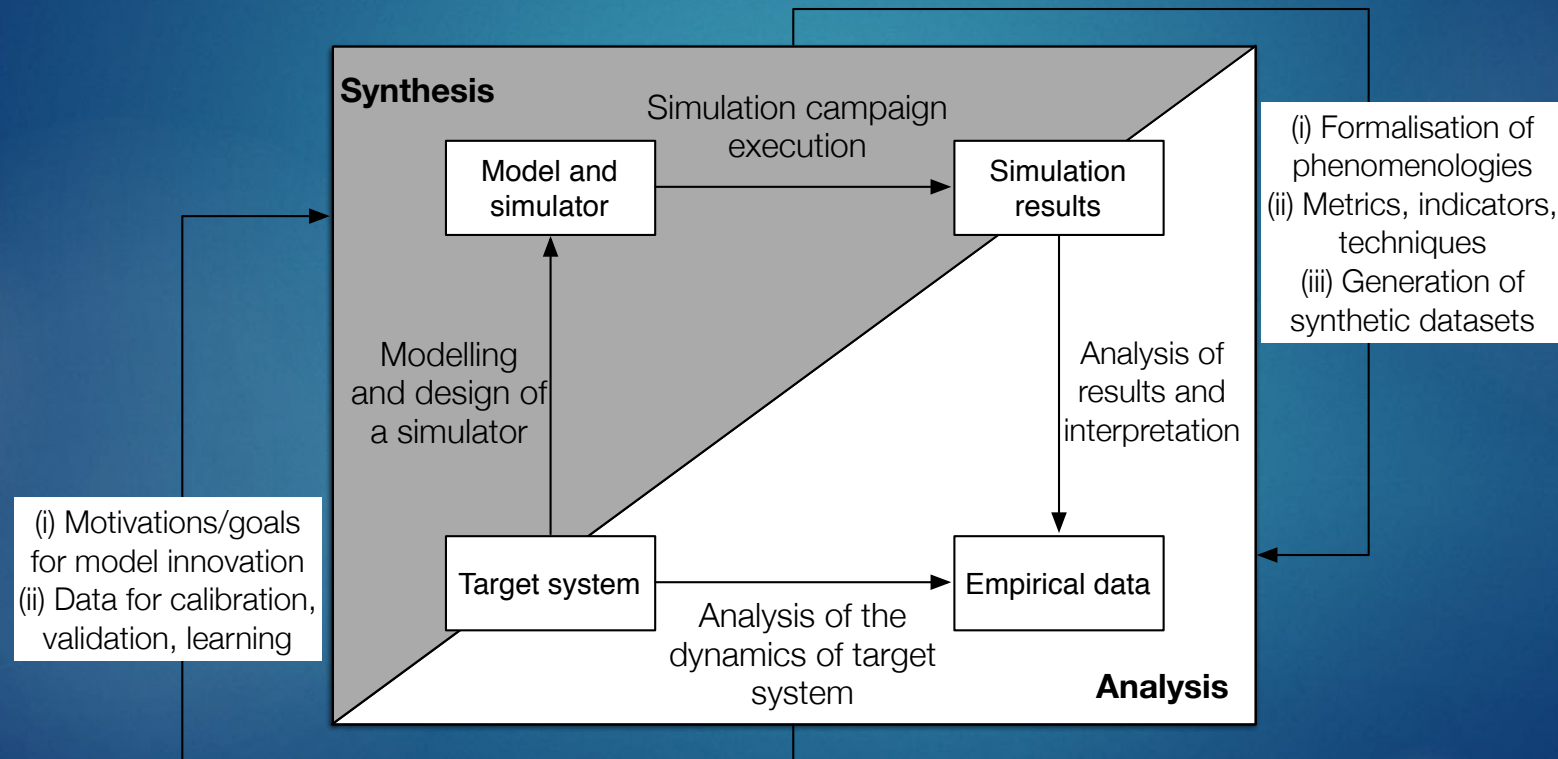
# How to look at traffic systems?

Michon, J. A. (1985). A critical view of driver behavior models: what do we know, what should we do?. *Human behavior and traffic safety*, 485-524.

Hoogendoorn, S.P., P.H.L. Bovy & W. Daamen (2001). Microscopic pedestrian wayfinding and dynamics modelling, In: M. Schreckenberg & S. Sharma, (eds.), *Pedestrian and Evacuation Dynamics*, Springer, Berlin, 123-154.



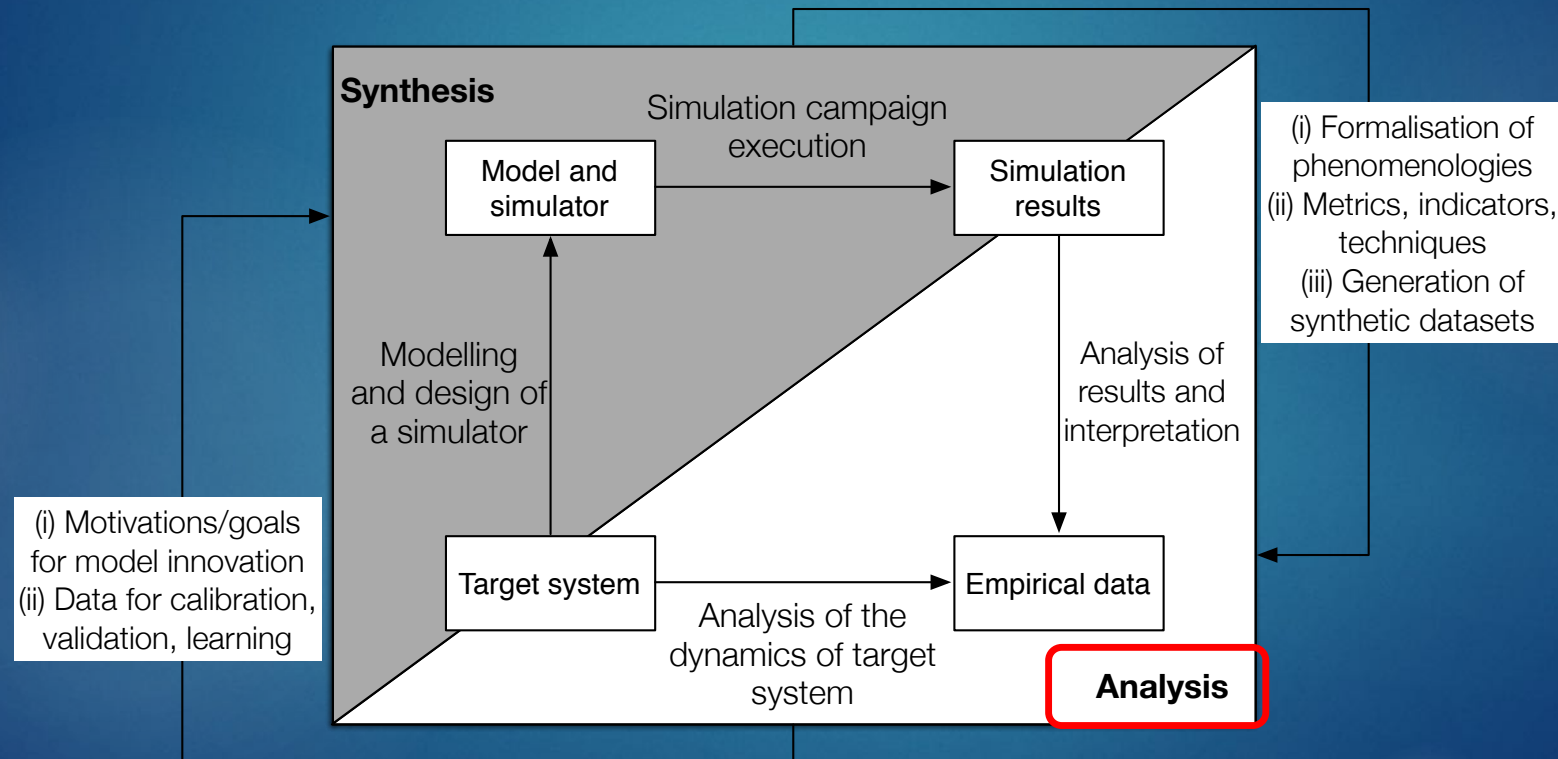
# Studying traffic systems: analysis and synthesis



# Micro scale analyses



# Studying crowds: analysis and synthesis (modeling and simulation)





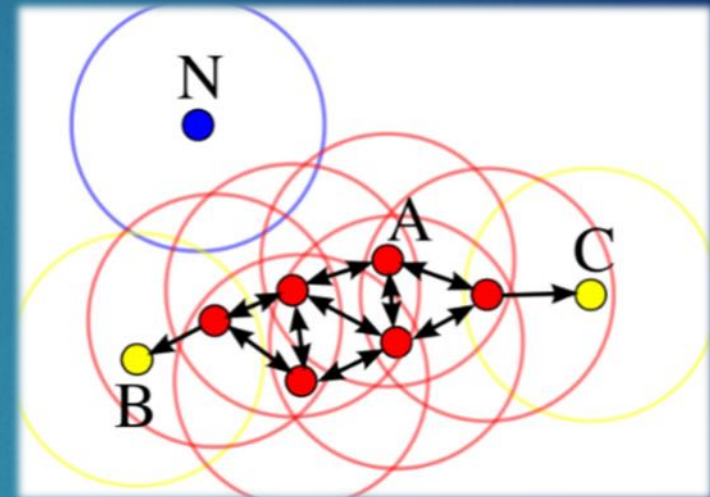
# Clustering for lane identification and characterization



- ▶ Bi-directional flows are generally characterized by the formation of **lanes**
- ▶ Few approaches proposed means of automated identification and quantitative characterization of this phenomenon
  - ▶ Order parameter [Rex & Loewen, 2007]
  - ▶ Clustering analysis [Hoogendoorn & Daamen, 2005]
  - ▶ Rotation measurement [Feliciani & Nishinari, 2016]

# DBScan [Ester, Kriegel, Sander and Xu, 1996]

- ▶ DBSCAN (**D**ensity-**B**ased **S**patial **C**lustering of **A**pplications with **N**oise)
- ▶ Unsupervised learning algorithm based on the concept of density
- ▶ Parameters of the base version:  $\epsilon$ , *minPoints*
- ▶ Clusters determined through the concept of neighborhood:
  - ▶ if distance between 2 points is less than  $\epsilon$ , they are neighbors
  - ▶ when one point has at least *minPoints* neighbors it is a **core point**
  - ▶ a cluster is defined as the set of neighboring core points, plus neighboring points (**border points**)
  - ▶ Remaining points are considered **noise**

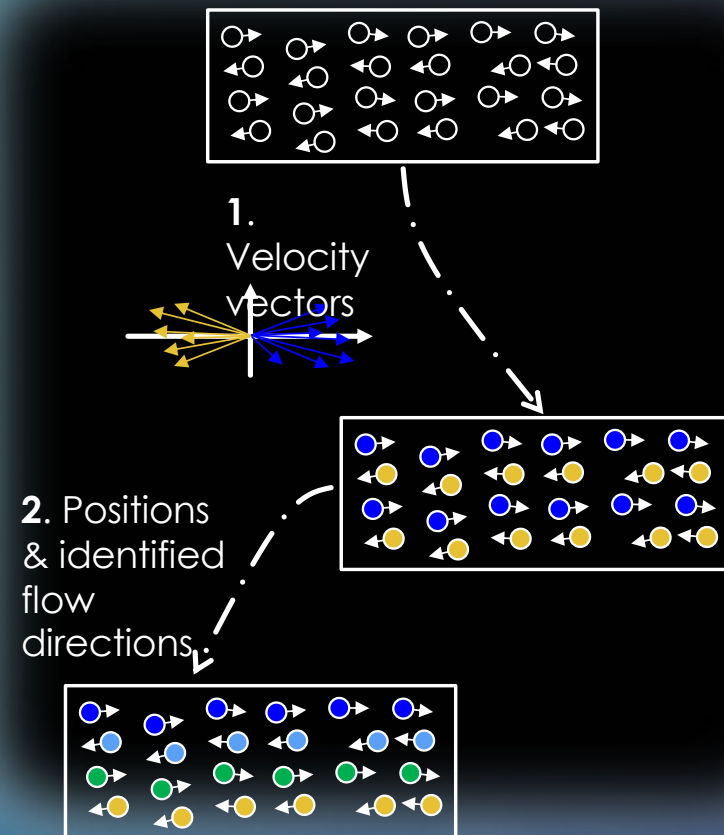


The choice of a suitable *distance metric* is crucial, just as the values for parameters

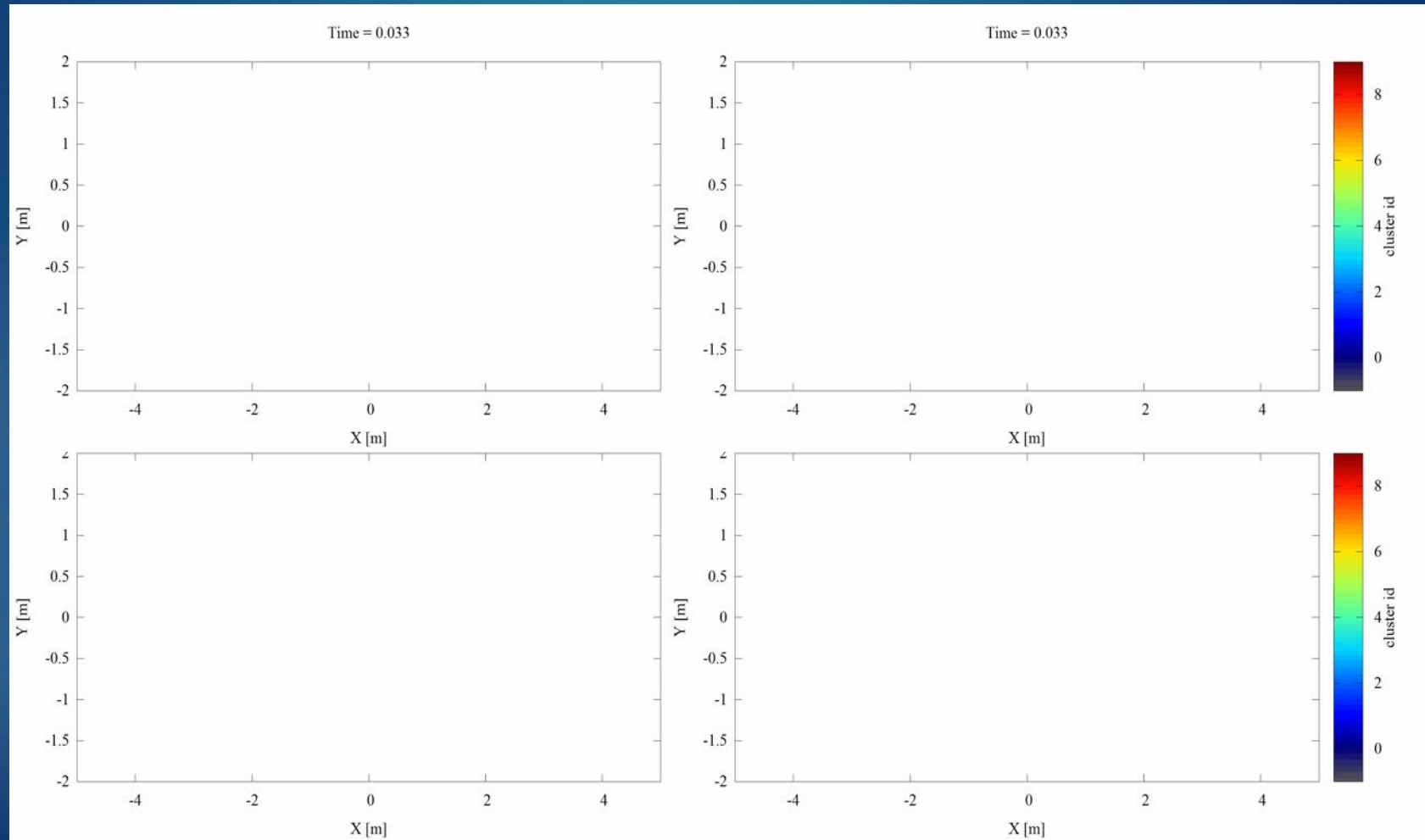


# A two step DBSCAN approach

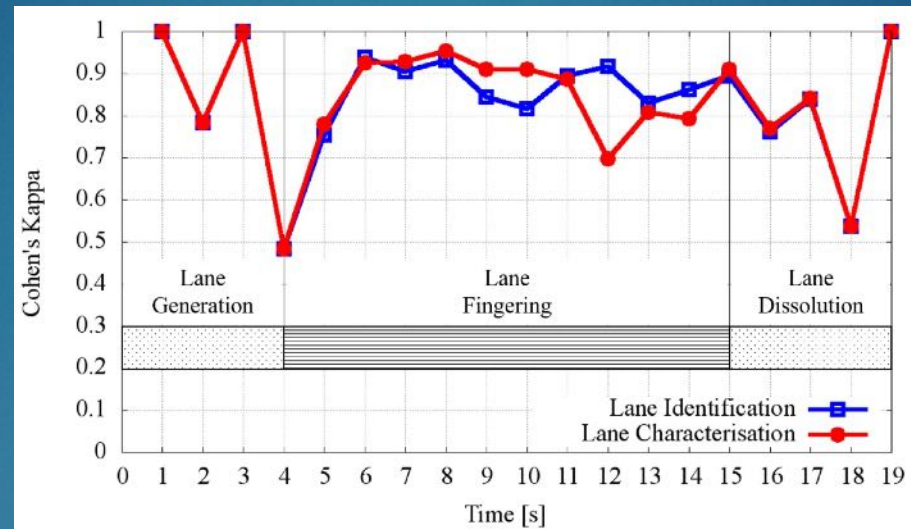
- ▶ We employed a two step clustering approach
  - ▶ The first application of DBSCAN considers velocity vectors to separate main flows according to the direction
  - ▶ The second one further subdivides clusters achieved from the previous step according also to positions
- ▶ Different distance metrics, essentially evaluating in step (i) angle among velocities and in step (ii) distance among pedestrians (discounted for velocity – the preceding person can be a little more far away than person on the side)
- ▶ Overall 4 parameters (different  $\varepsilon$  and *minPoints* in the two steps)



# Achieved results

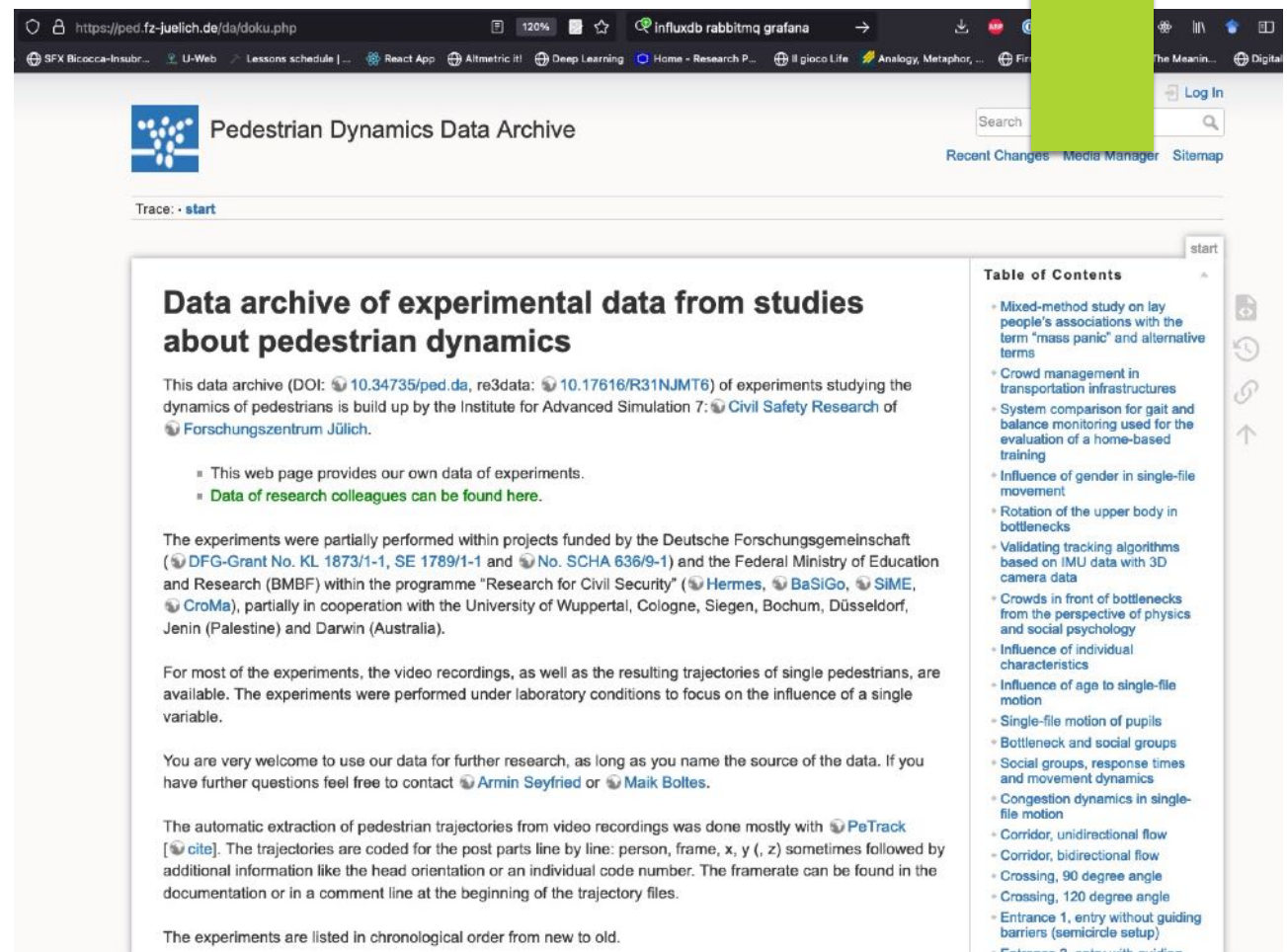


# Agreement with human annotator



- ▶ Cohen's Kappa coefficient is used to measure the level of inter-rater agreement between two coders in classifying a certain subject
- ▶ Pedestrians have been classified considering:
  - ▶ their condition of belonging or not to any lane (i.e. *gross classification* – *lane identification*)
  - ▶ their belonging to a certain lane (i.e. *granular classification* – *lane characterization*)

Where to get  
data to  
analyze?



The screenshot shows a web browser displaying the 'Pedestrian Dynamics Data Archive' website. The URL in the address bar is <https://ped.fz-juelich.de/da/doku.php>. The website has a blue header with the logo and title. A search bar is in the top right. Below the header, there's a 'Trace: start' link. The main content area features a title 'Data archive of experimental data from studies about pedestrian dynamics' and a paragraph about the data archive's origin at the Institute for Advanced Simulation 7 and Civil Safety Research of Forschungszentrum Jülich. It lists two bullet points: 'This web page provides our own data of experiments.' and 'Data of research colleagues can be found here.' followed by a paragraph about funding from the Deutsche Forschungsgemeinschaft and the Federal Ministry of Education and Research. Another paragraph states that video recordings and trajectories are available. A welcome message for researchers is followed by contact information for Armin Seyfried and Maik Boltes. A paragraph mentions the use of PeTrack for trajectory extraction. The final paragraph states that experiments are listed in chronological order from new to old. On the right side, there is a 'Table of Contents' with a list of topics including mixed-method studies, crowd management, system comparisons, gender influence, rotation of the upper body, validating tracking algorithms, crowds in front of bottlenecks, individual characteristics, age influence, single-file motion, pupil motion, bottlenecks and social groups, social groups and movement dynamics, congestion dynamics, corridor flow, crossing angles, and entrance setups.

<https://ped.fz-juelich.de/da/doku.php>



# Urban scale analyses





# From micro to urban scale

“Urban informatics is the study, design, and practice of urban experiences across different urban contexts that are created by new opportunities of real-time, ubiquitous technology and the augmentation that mediates the physical and digital layers of people networks and urban infrastructures.”

Foth, Choi, Satchell (2011). Urban informatics.

“The use of information and communications technology to better understand metropolitan needs, challenges, and opportunities.”

McKinsey on Society (2012). Emerging Trends in Urban Informatics.

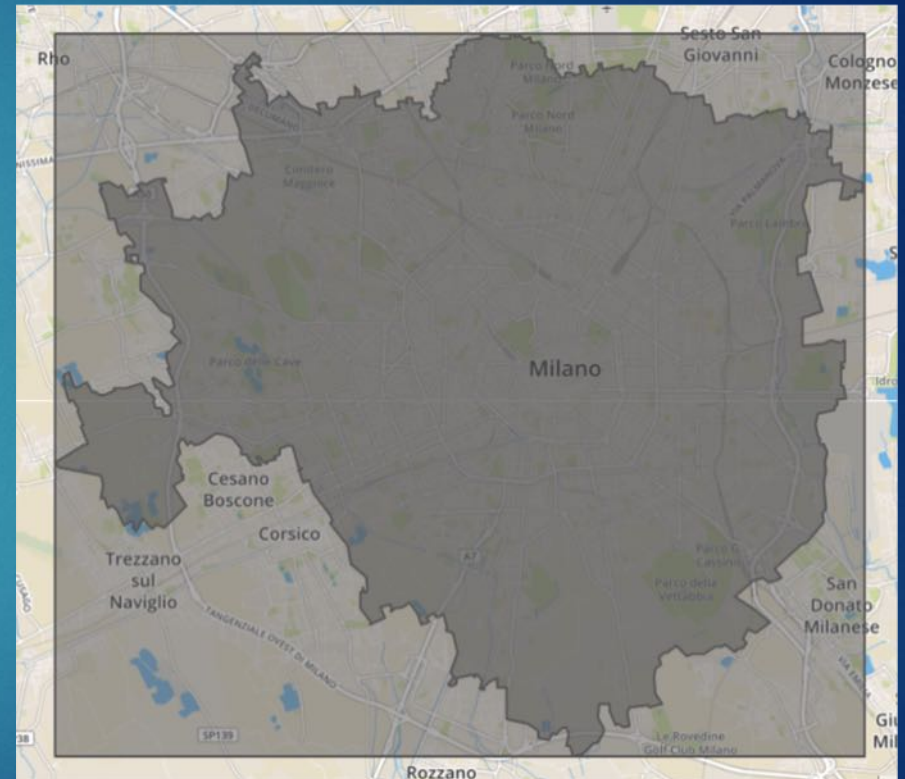
“Urban informatics uses data to better understand how cities work. This understanding can remedy a wide range of issues affecting the everyday lives of citizens and the long-term health and efficiency of cities — from morning commutes to emergency preparedness to air quality.”

Center for Urban Science and Progress (2013). What is Urban Informatics?



# Enabling data and technologies

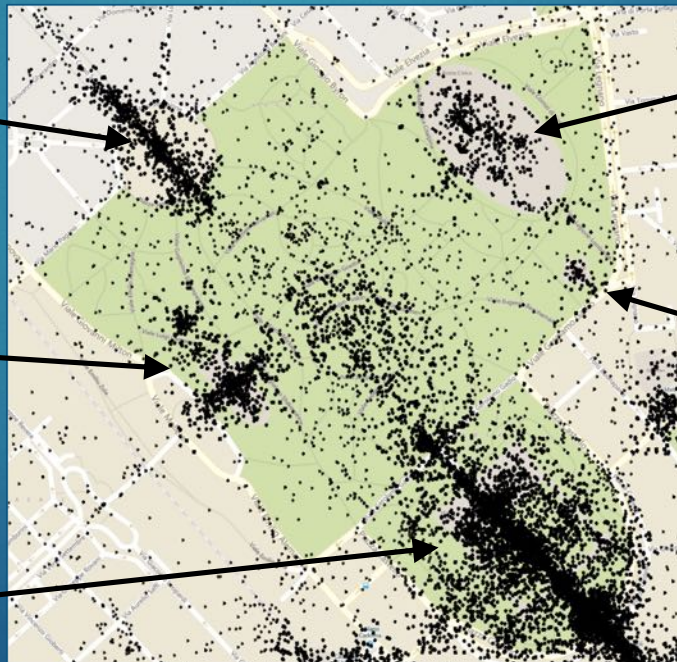
- ▶ Sources:
  - ▶ Flickr
  - ▶ Foursquare
- ▶ Crawling process within the city of Milano:
  - ▶  $\approx 450\,000$  Flickr photos
    - ▶ metadata: e.g. geo coordinates, tags, takenDate
    - ▶ 4 067 314 total photo tags
  - ▶  $\approx 50\,000$  Foursquare points of interest
    - ▶ metadata: e.g. geo coordinates, categories
    - ▶ 56 406 total POI categories
- ▶ QGIS (Quantum GIS)





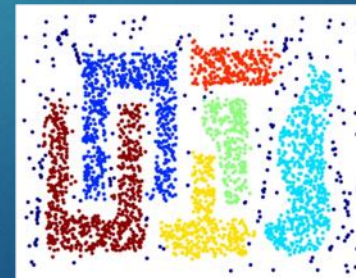
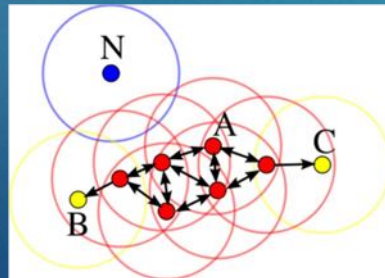
# Identification of the entities within the city

Basic idea: a *potentially interesting entity* within the city should generate a significant activity related to the associated area in the considered social media (i.e. Flickr and Foursquare).

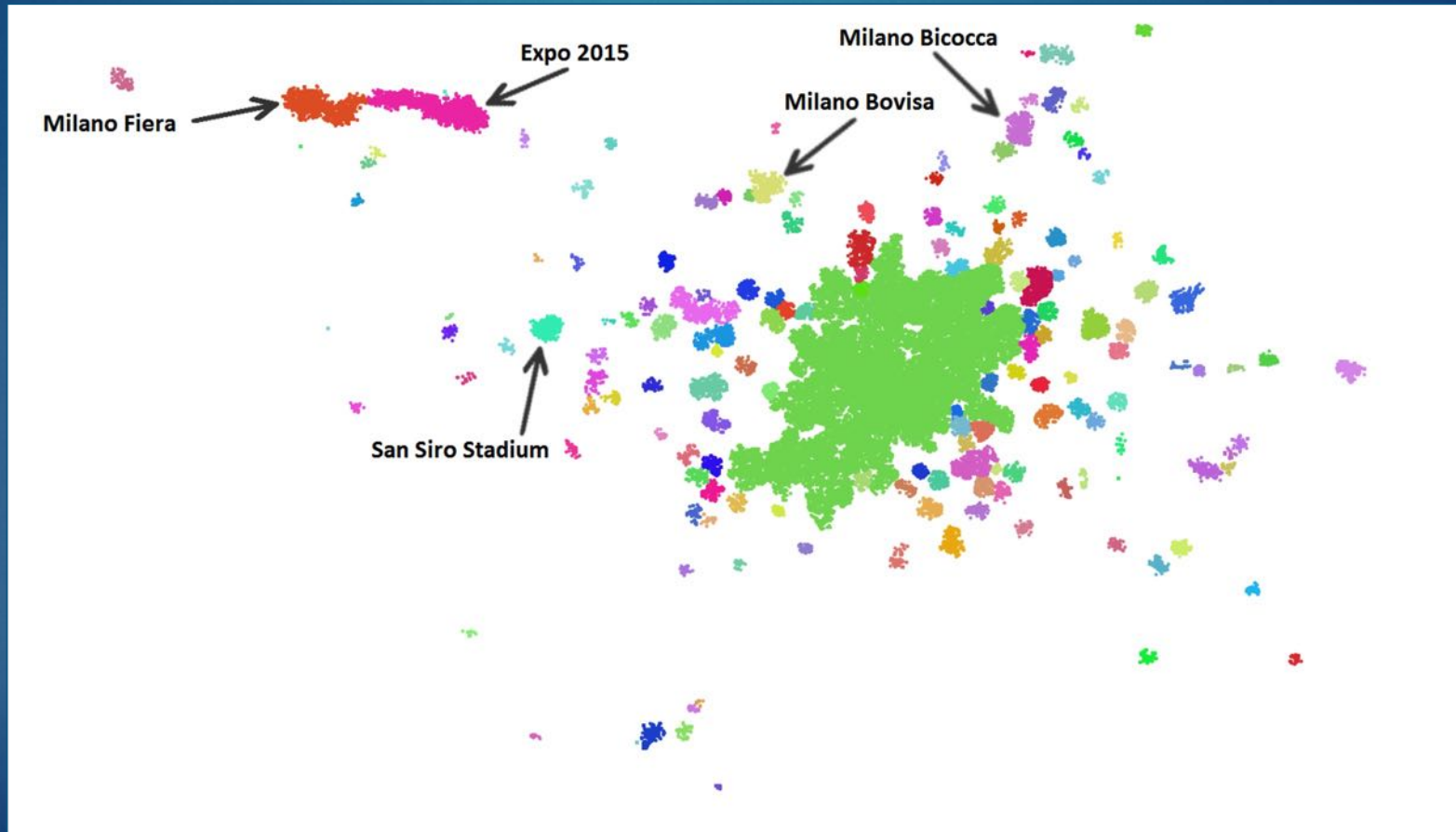


# Identification of the entities: clustering

- ▶ Clustering is the process of identifying natural groupings (i.e. clusters) within multidimensional data based on some similarity measure.
- ▶ Density-based clustering algorithm: it allows to search for regions of high density (i.e. *city areas where there are many photos or POIs*) that are separated by regions of lower density (i.e. *city areas where there are few/none photos or POIs*).
- ▶ DBSCAN satisfies our requirements:
  - ▶ unknown number of clusters to identify → not required
  - ▶ good efficiency on large databases →  $O(n \log n)$
  - ▶ discovery of clusters with arbitrary shape

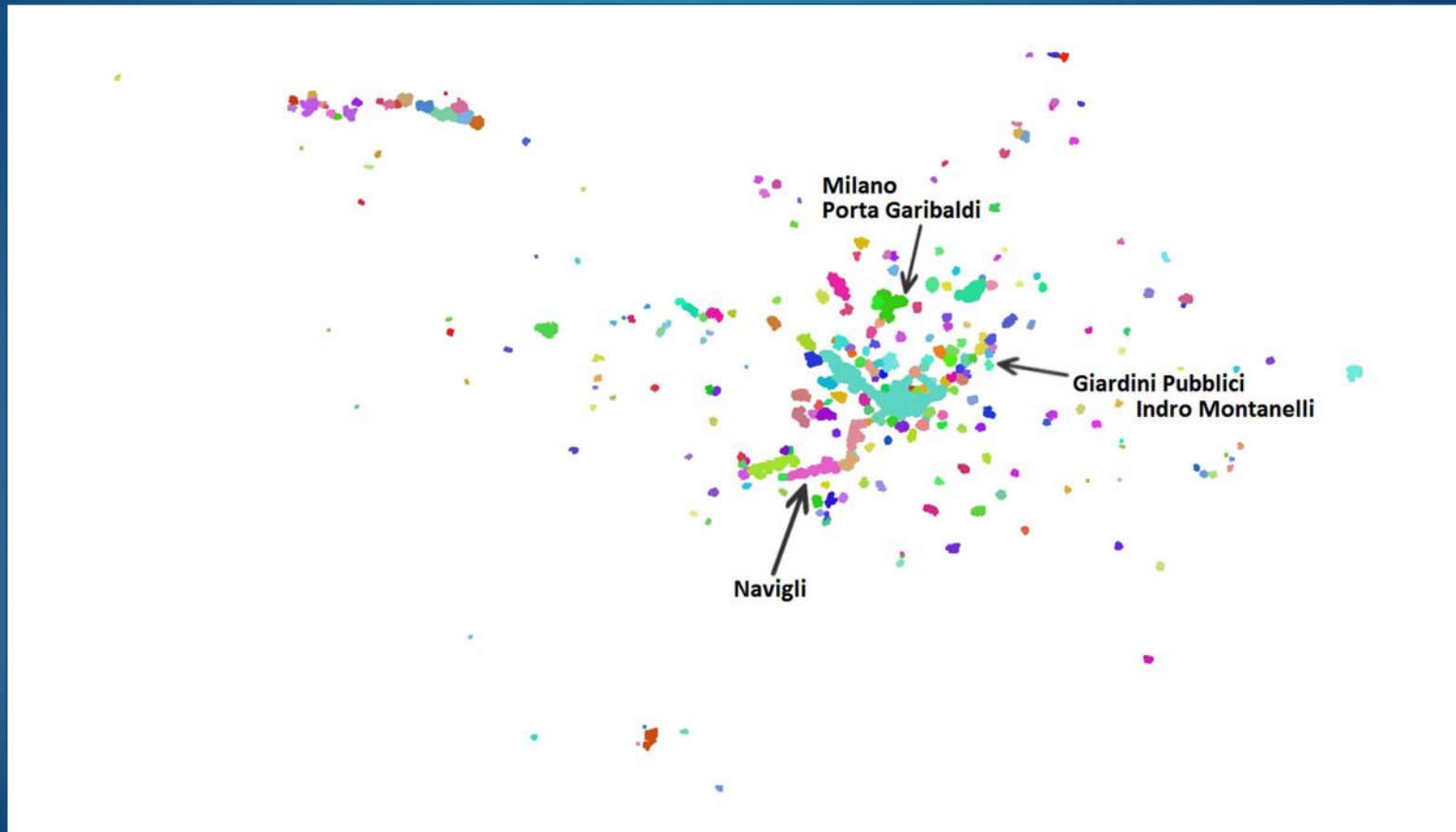


# Identification of the entities: which parameters?

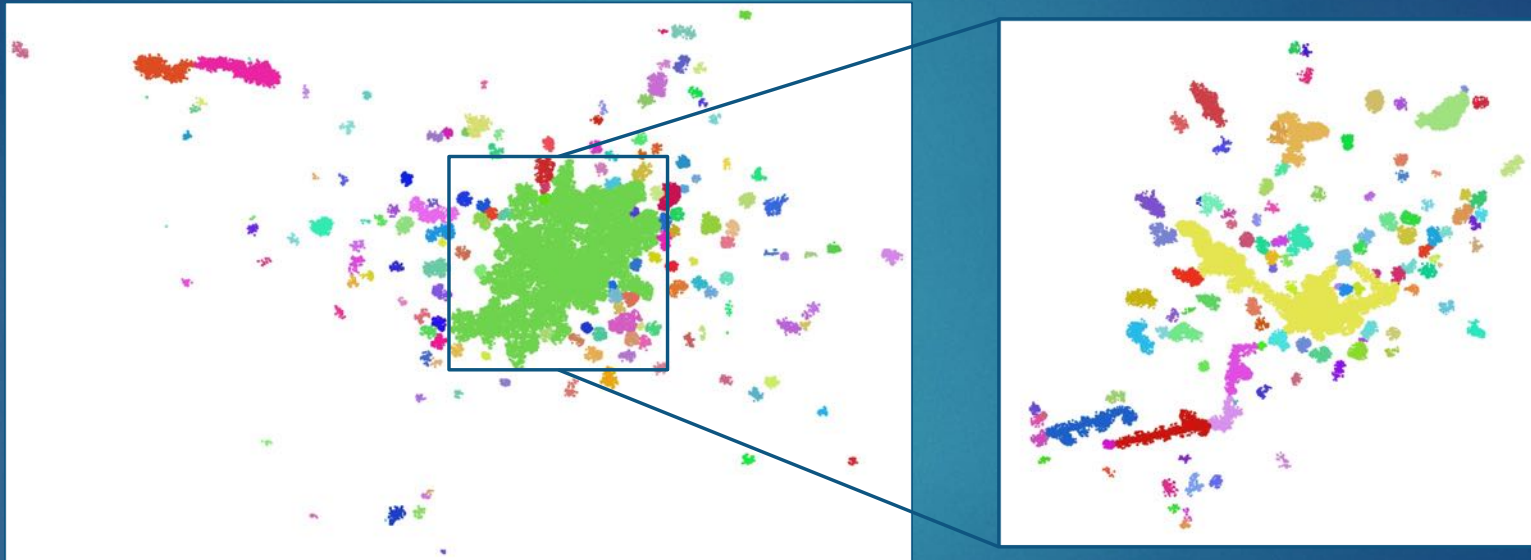




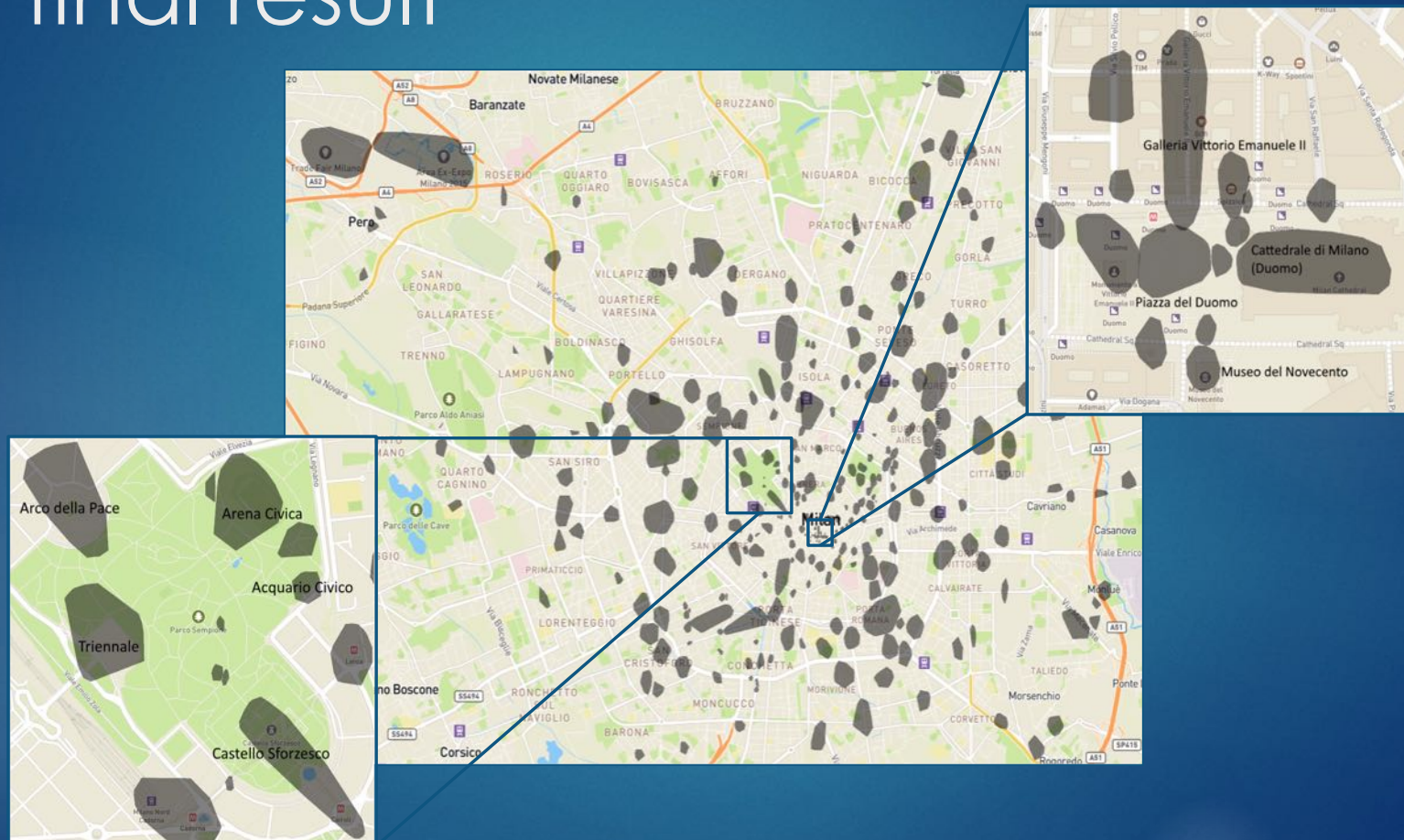
# Identification of the entities: which parameters?



# Identification of the entities: iterative approach



The first two authors have been involved in the development of the *Journal of Management Inquiry* since its inception. The third author has been involved in the development of the journal since 1996. The authors have been involved in the development of the journal since its inception. The authors have been involved in the development of the journal since its inception.



# Identification of the entities: quantitative evaluation

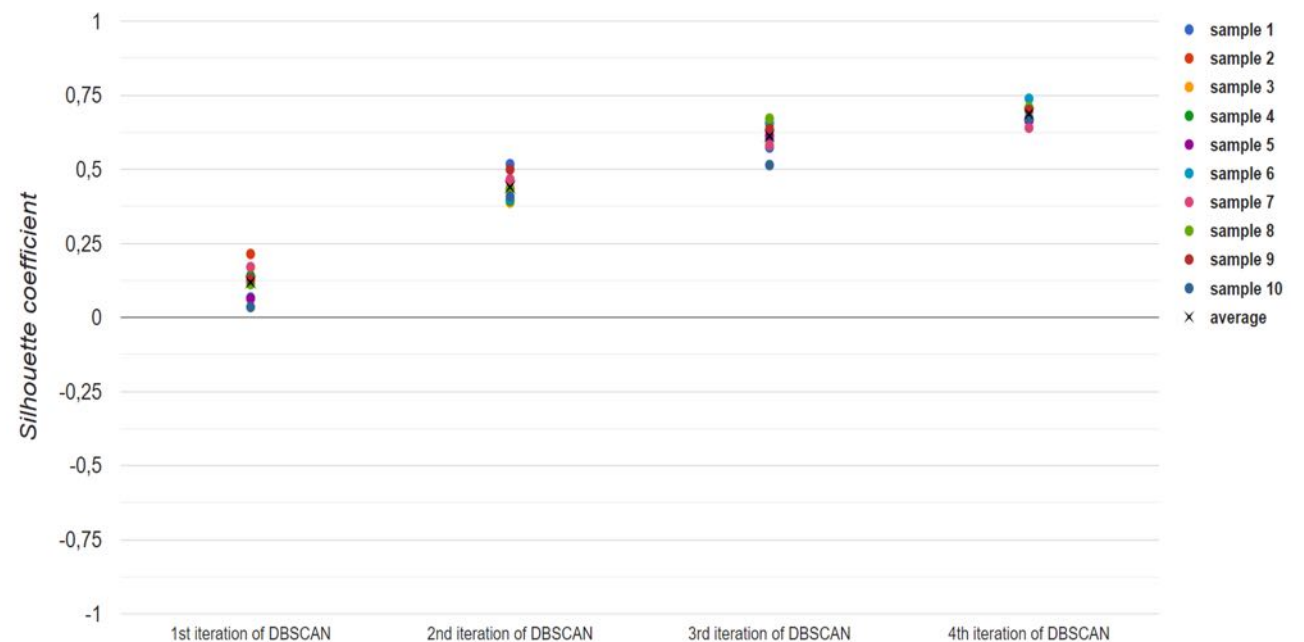
Silhouette Coefficient: internal index that reflects both the *compactness* and the *separation* of clusters.

Formally, considering an object  $o \in C_i$  where  $1 \leq i \leq k$  and  $k$  is the number of clusters:

$$a(o) = \frac{\sum_{o' \in C_i, o' \neq o} \text{dist}(o, o')}{|C_i| - 1}$$

$$b(o) = \min_{C_j: 1 \leq j \leq k, j \neq i} \left\{ \frac{\sum_{o' \in C_j} \text{dist}(o, o')}{|C_j|} \right\}$$

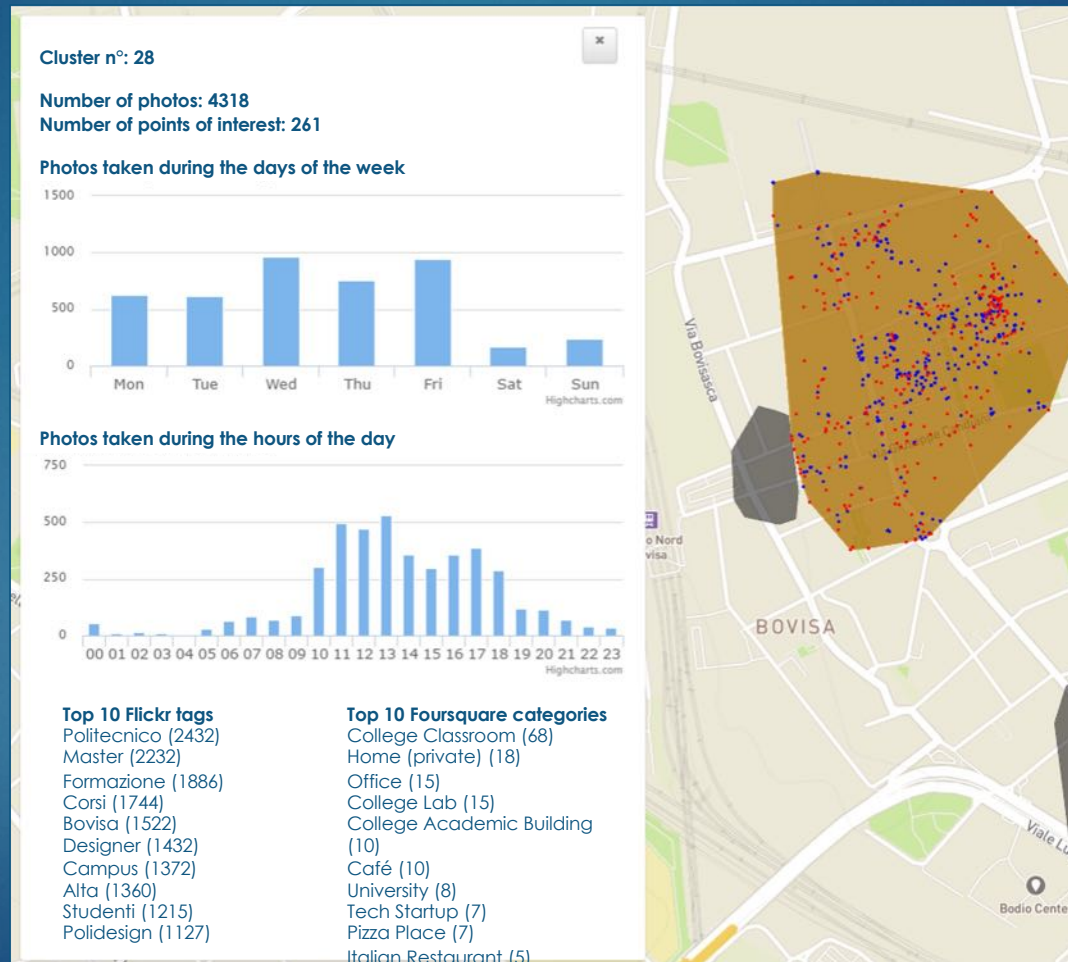
$$s(o) = \frac{b(o) - a(o)}{\max\{a(o), b(o)\}}$$



Each sample set contains 5 000 randomly selected elements (about 1% of the dataset)



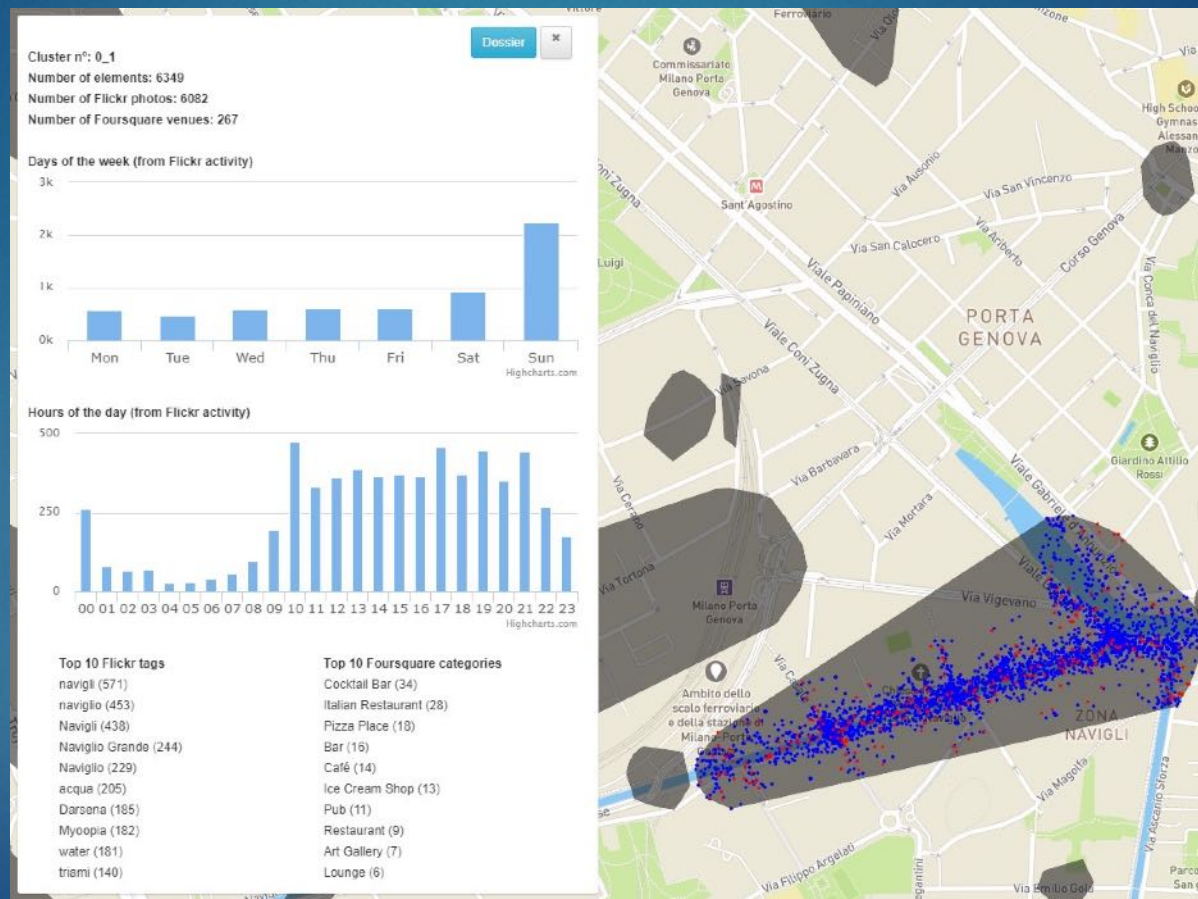
# Characterization of the identified entities



Politecnico di Milano Bovisa

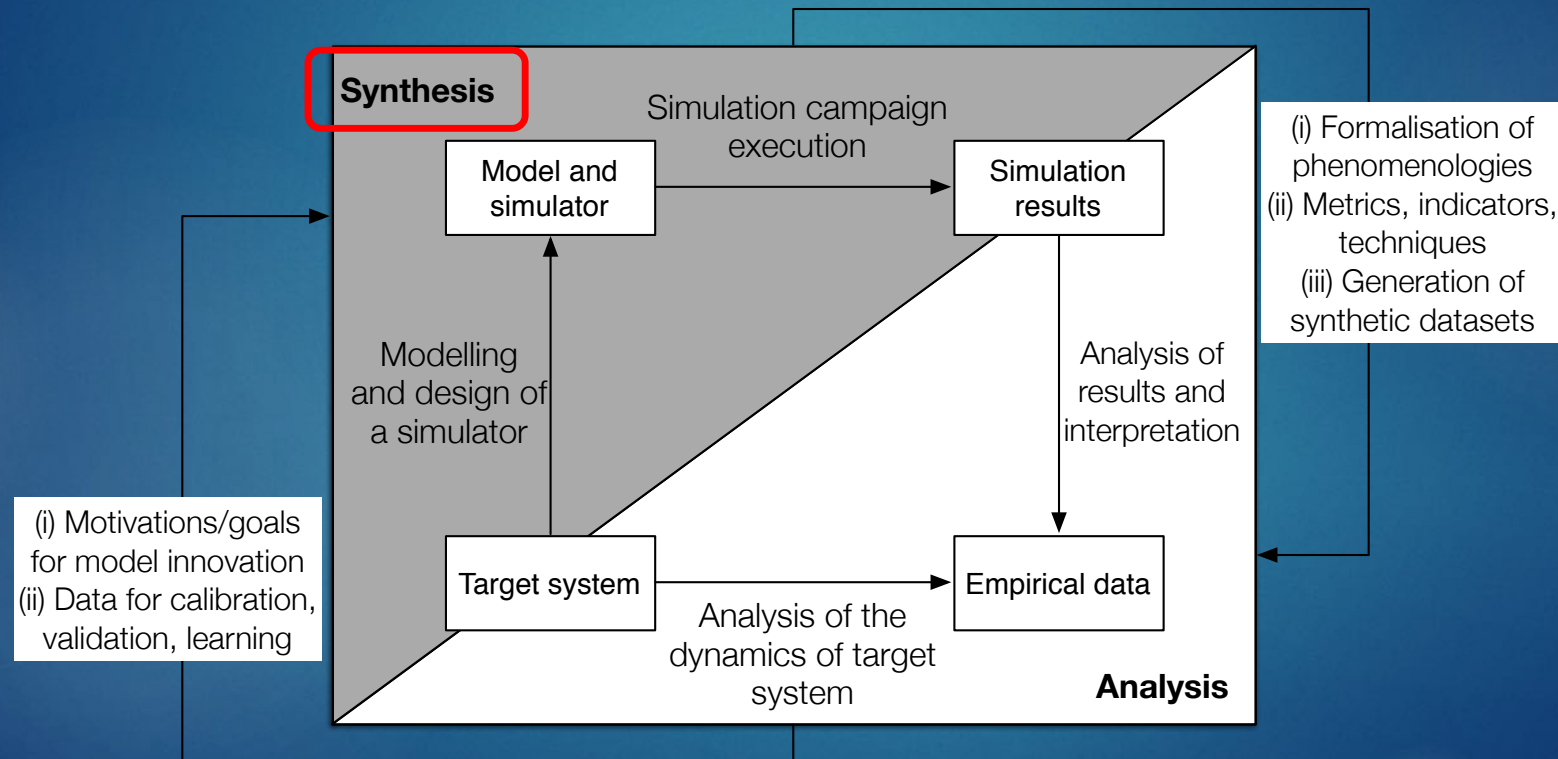


# Characterization of the identified entities

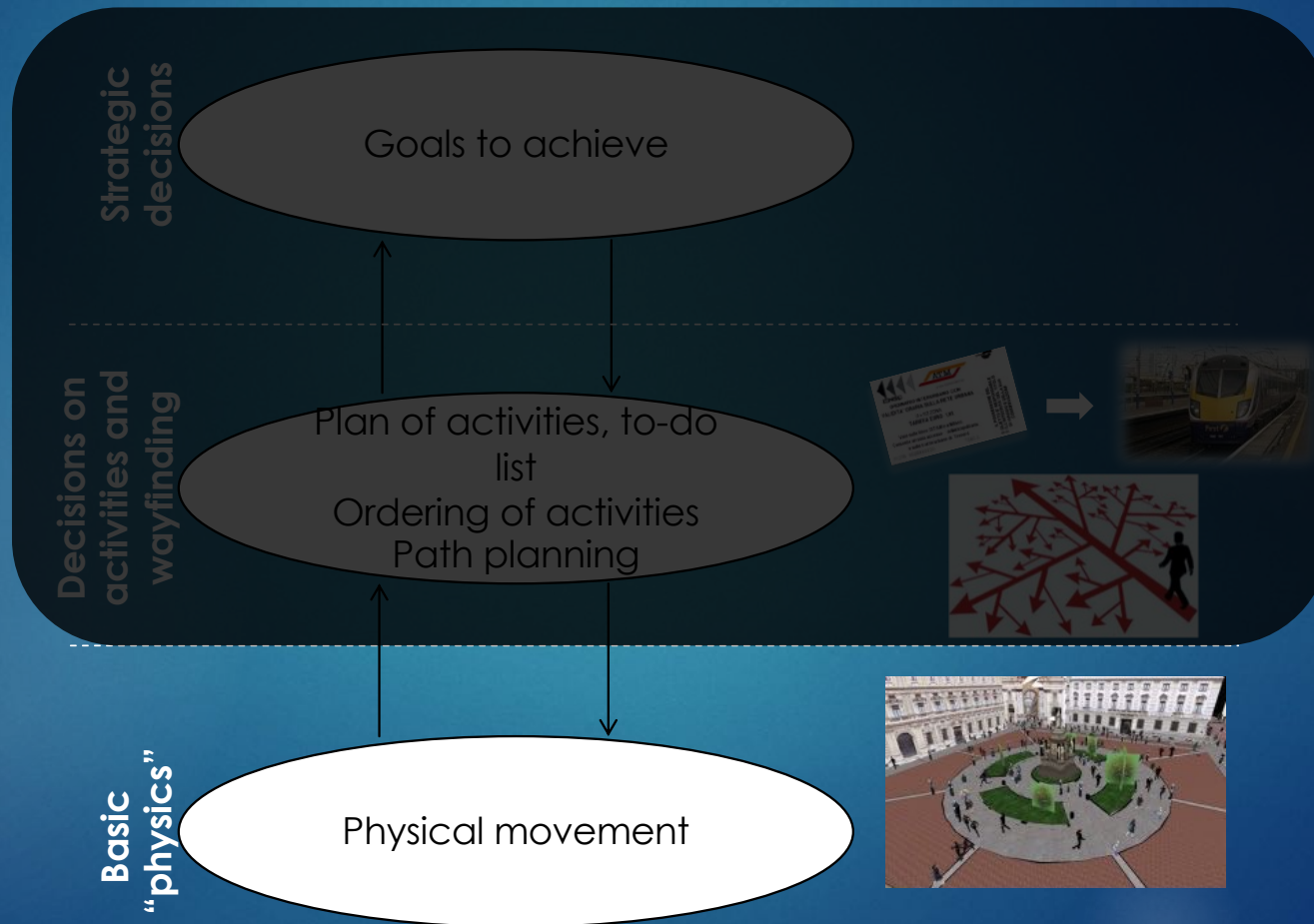


Navigli area

# Studying crowds: analysis and synthesis (modeling and simulation)



# What types of decisions we need to consider?

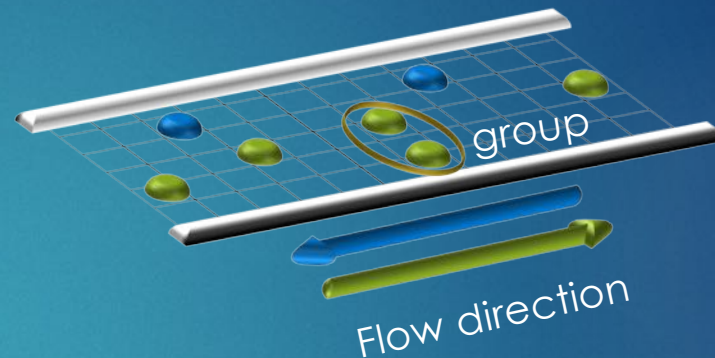




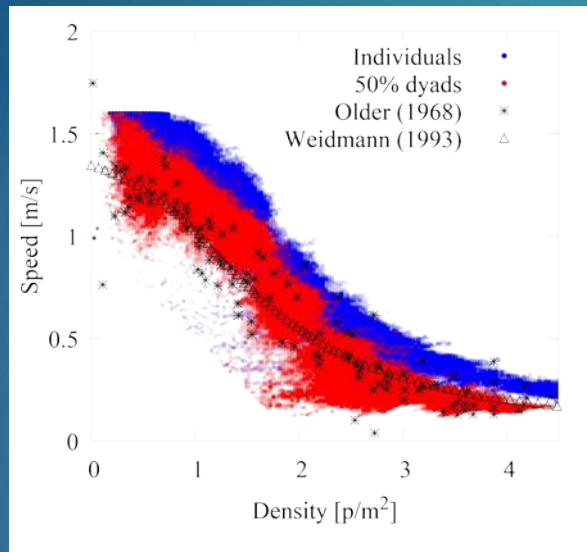
# Physical movement

Considered aspects :

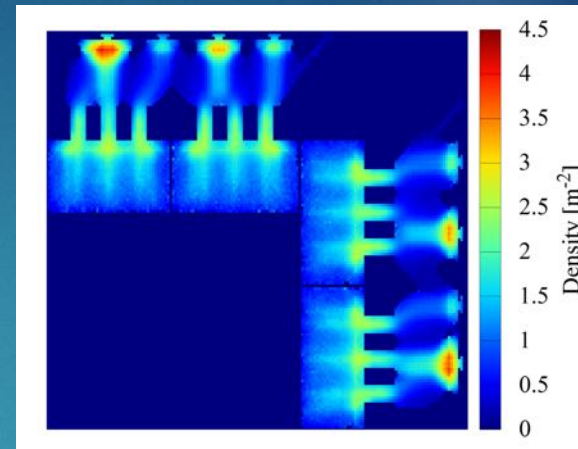
- a) Goal of movement
- b) Obstacles
- c) Members of own group
- d) Other pedestrians
- e) Current direction



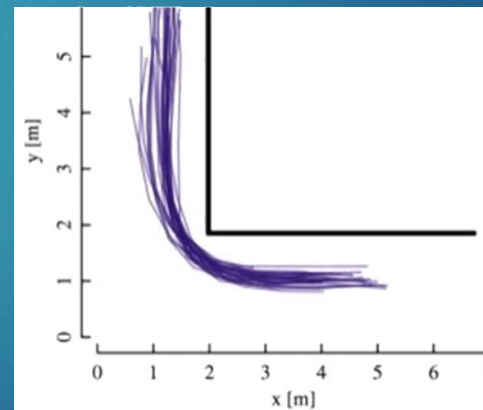
# Validation



1. Fundamental diagram

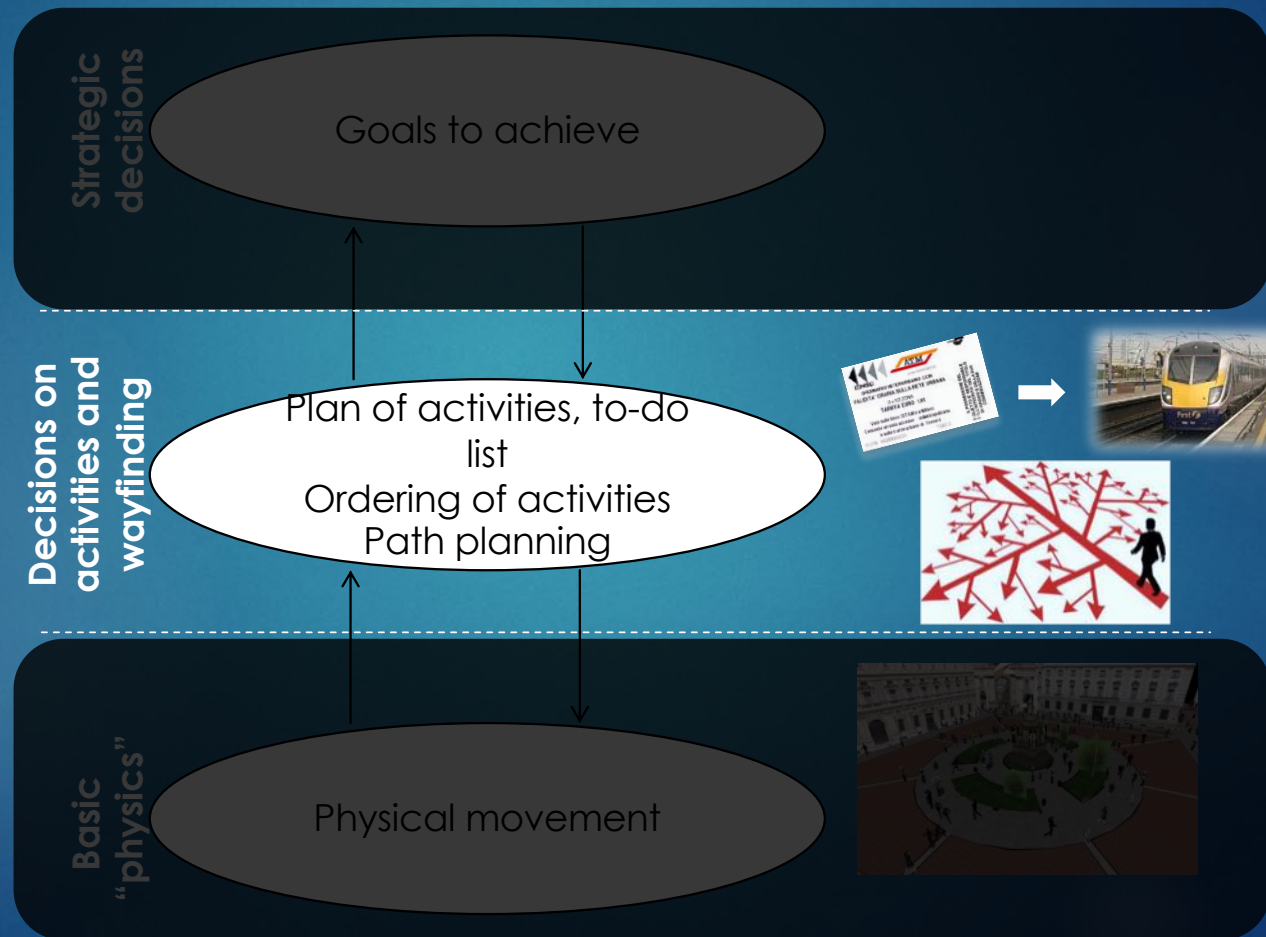


2. Local density maps



3. Trajectories and space utilization

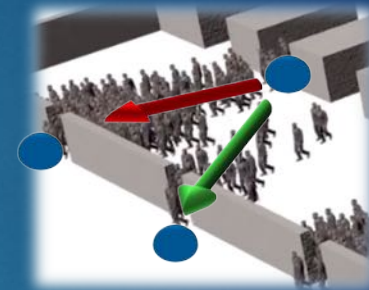
# Virtual crowds – different decisions and levels



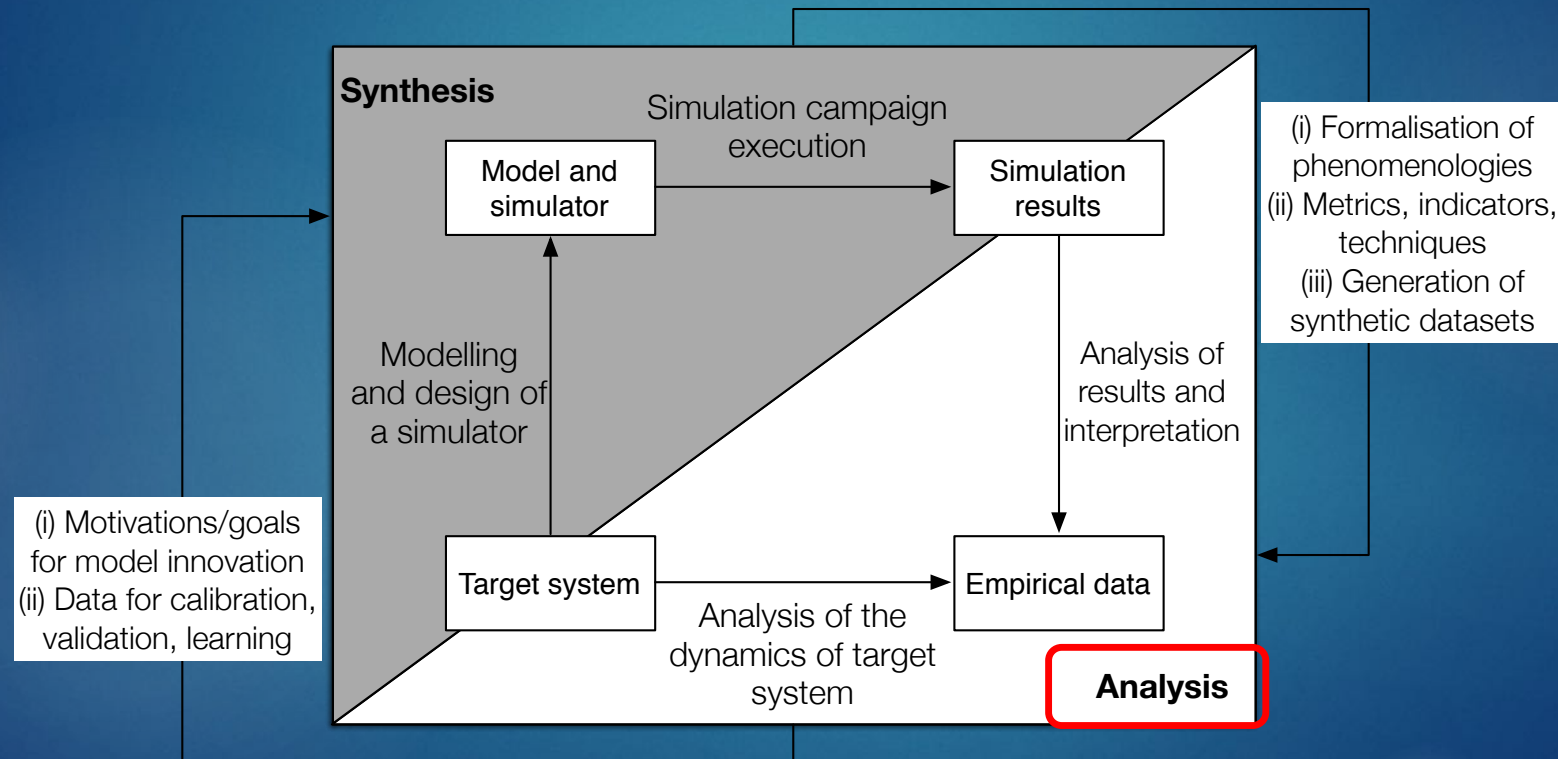


# Wayfinding: alternative approaches

- ▶ Iterative approaches based on concepts of optimality/equilibrium
  - ▶ Local considerations (what I perceive here and now)
  - ▶ Global, although not current information (e.g. I know that generally at 5:30pm tangenziale is congested)
- ▶ Decision models based on currently available information, not requiring iterative executions of a model, possibly employing results of spatial cognition researches, insights from observations and experiments with pedestrians

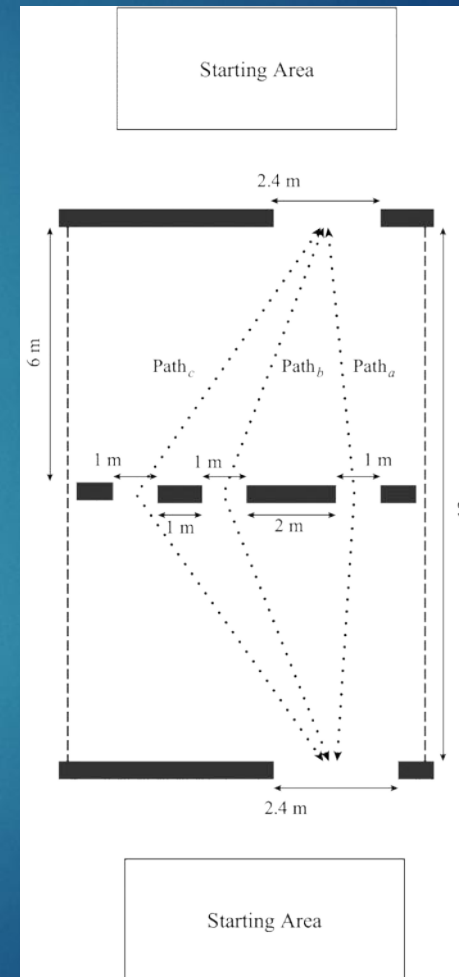


# Studying crowds: analysis and synthesis (modeling and simulation)



# Experimental observations of wayfinding (1)

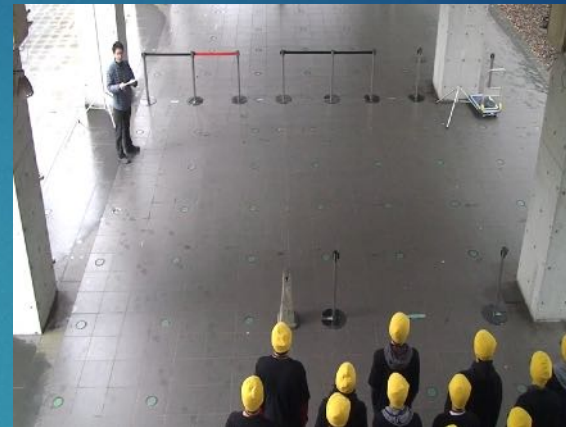
- ▶ 46 male students participated
- ▶ Aiming to analyze the **impact of congested paths in the route choice**
- ▶ Three possible paths, activated according to the procedure:
  1. only  $Path_a$  (to analyze completion times)
  2. two openings,  $Path_a$  and  $Path_b$
  3. two openings,  $Path_a$  and  $Path_c$
  4. all paths
- ▶ 4 iterations per procedure
- ▶ Participants have been asked to reach the opposite side
- ▶ Both sides of the scene were used as entrance/exit



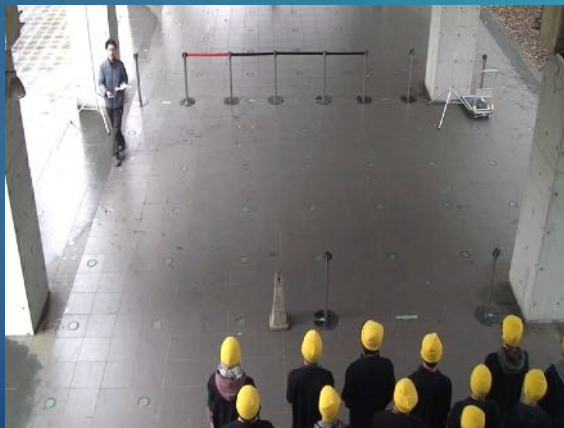


# Experimental observations of wayfinding (2)

- Pedestrians choosing longer paths ( $Path_b$  and  $Path_c$ ) generally enter the area before the gates on the left side (right in the reversed direction) → **length of path**
- Pedestrians choosing longer paths generally do so after some preceding ones have perceivably chosen the best path → **avoiding congestion**
- When choosing  $Path_c$ , many participants seem to follow persons before them → **following behavior**



Procedure 2



Procedure 3

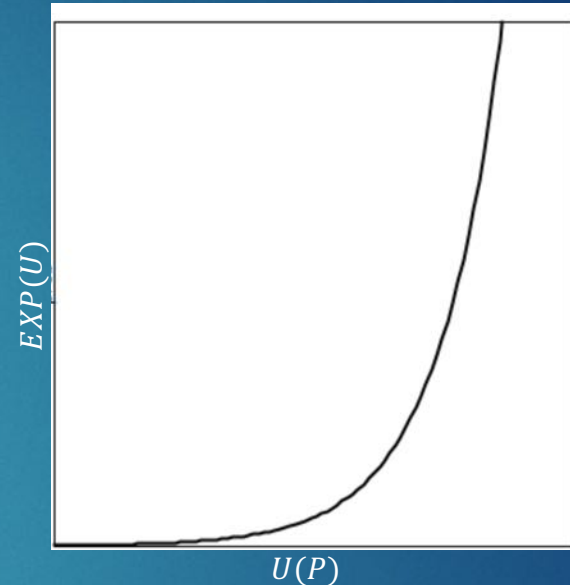


Procedure 4

# The route choice model – the utility function

- The probability to choose a path is exponentially dependent on the utility:

$$Prob(P) = N \cdot e^{U(P)}$$



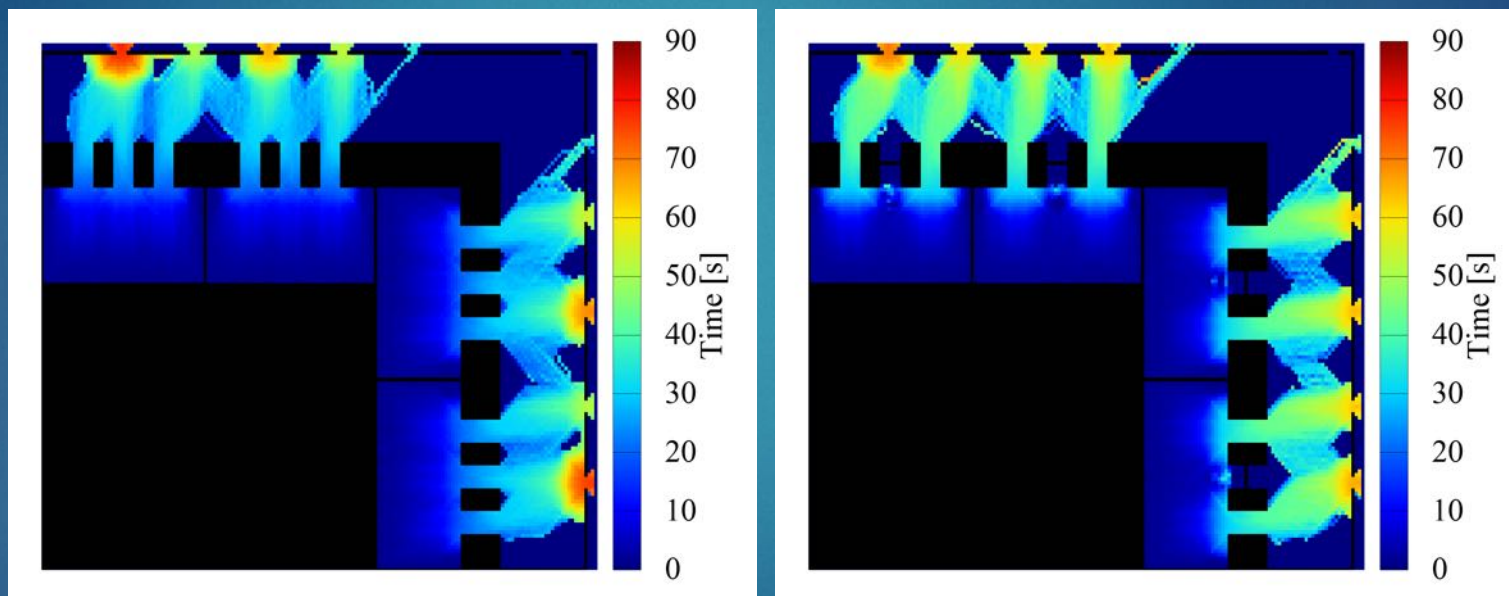
- The utility describes three evaluation components:

$$U(P) = \kappa_{tt} Eval_{tt}(P) - \kappa_q Eval_q(P) + \kappa_f Eval_f(P)$$

- The calibration is possible through the triple  $(\kappa_{tt}, \kappa_q, \kappa_f)$

# Putting it all together

Evacuation time maps







## So what can be done about innovative mobility?

- ▶ These examples were a bit borderline, not exactly central to the topic, but useful to show how the methods can help
- ▶ Lots of things can be done more centrally:
  - ▶ Improve the performance of current services (e.g. Cai, Y., Ong, G. P., & Meng, Q. (2022). Dynamic bicycle relocation problem with broken bicycles. *Transportation Research Part E: Logistics and Transportation Review*, 165, 102877)
  - ▶ Foresee and make what-if scenarios on slightly novel systems (Castagna, A., Guériau, M., Vizzari, G., & Dusparic, I. (2021). Demand-responsive rebalancing zone generation for reinforcement learning-based on-demand mobility. *AI Communications*, 34(1), 73-88)
  - ▶ Study the demand, the potential acceptance for novel approaches...
- ▶ It takes a bit of creativity and passion

Thank you!

Giuseppe Vizzari

