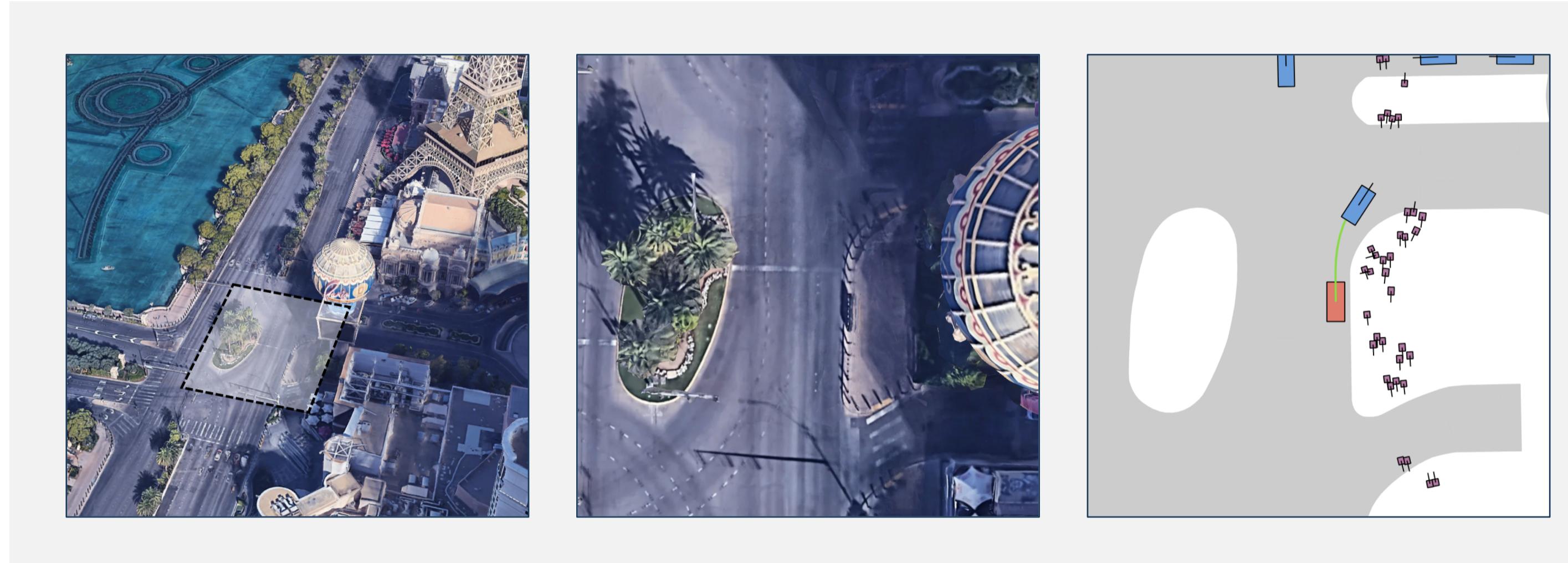


Common Misconceptions in Vehicle Motion Planning

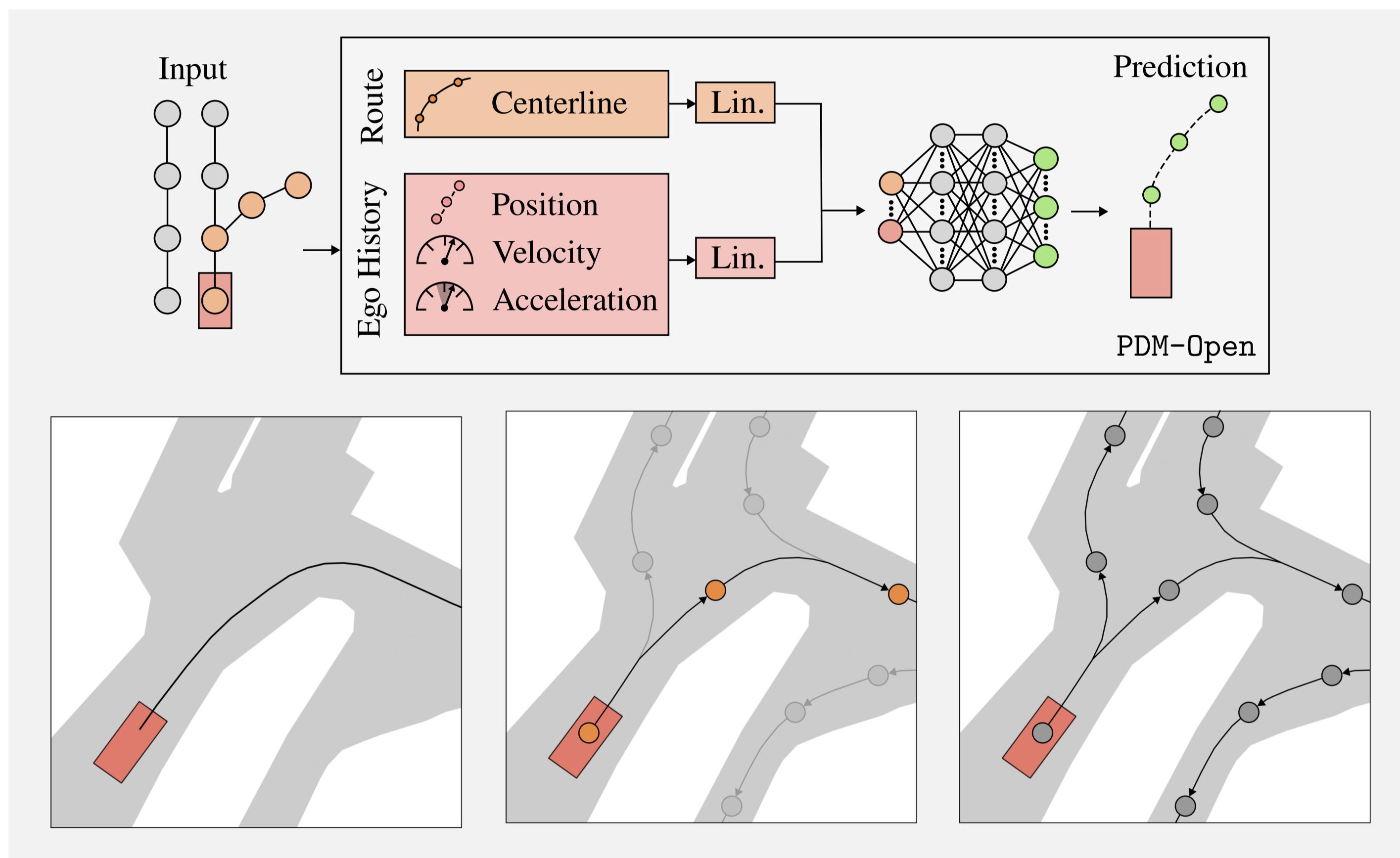
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¹University of Tübingen, ²Tübingen AI Center, ³Robert Bosch GmbH



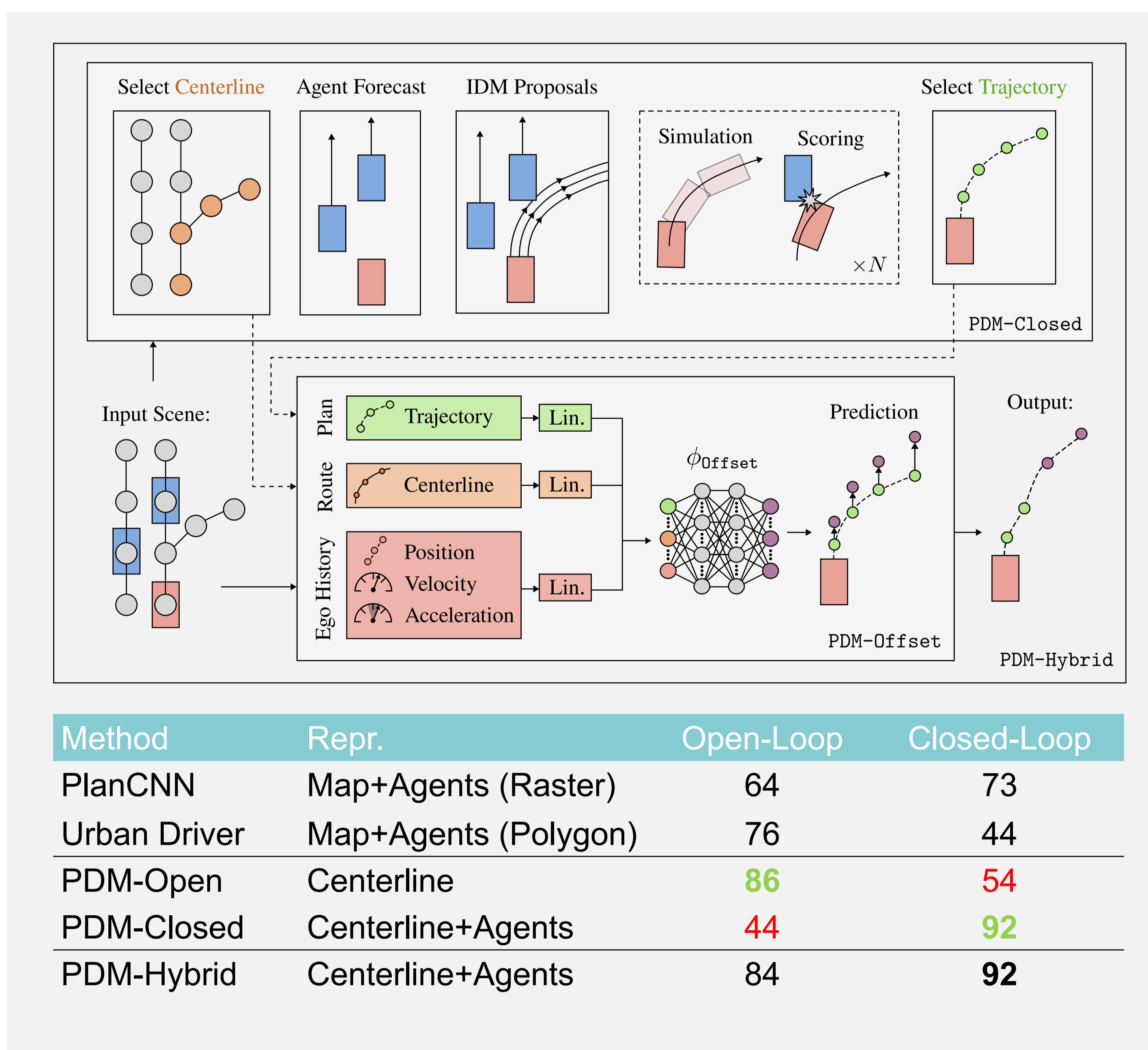
nuPlan Challenge: Data-Driven Simulation



Centerline-Conditioned Learned Ego-Forecasting



Combining Learned and Rule-Based Planning



#1. A route centerline is all you need

#2. Rule-based beat learned planners in closed-loop driving

#3. The planning and ego-forecasting task are misaligned