

$$\theta_h = 0$$

$$H_i = \begin{bmatrix} -\cos \theta_h & \sin \theta_h & (-x_f \sin \theta_h + x_r \sin \theta_h - y_f \cos \theta_h + y_r \cos \theta_h) & 0 & 0 & \dots \\ -\sin \theta_h & -\cos \theta_h & (x_f \cos \theta_h - x_r \cos \theta_h - y_f \sin \theta_h + y_r \sin \theta_h) & 0 & 0 & \dots \\ \cos \theta_h & -\sin \theta_h & & & & \\ \dots & \sin \theta_h & \cos \theta_h & & & \end{bmatrix}$$