



# Test Training on Functional Testing

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Région de  
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GOBIERNO  
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openETCS

Marc Behrens

Braunschweig, 04.06.2014

## Welcome

- Internet is available via Wifi: „DLR- Sfr - Gastzugang“
- *No password required*

# WP4 Training Agenda Day 1 – part 1

**09:00 - 09:20 Welcome – Marc Behrens**

**09:20 - 10:00 Introduction into the structure of Subset-026 - Marc Behrens**

**10:00 - 10:30 Introduction to braking curves and user story (speed and distance monitoring) - Alex Nitsch**

**10:30 - 10:45 Question and Answers on braking curves - All Participants & Alex Nitsch**

**10:45 - 11:00 Coffee break**

**11:00 - 11:20 What does „Braking curves mean to a railway operator“ – Marc Behrens**

**11:20 - 11:50 Presentation of the example RT- Tester SysML model - Cécile Braunstein**

**11:50 - 12:00 Question and Answers on the example model on braking curves - All Participants & Cécile Braunstein**

**12:00 - 13:00 lunch @cantina**

# WP4 Training Agenda Day 1 – part 2

## Practical Part Building 103 "Besprechungsraum"

**13:00 - 13:30 Introduction into RT-Tester on software testing environment - Uwe Schulze**

**13:30 - 17:30 - All Participants & Uwe Schulze and Cécile Braunstein**

- Installation
- Tools set up
- Project creation
- Test generation
- Test execution

**17:30 - 18:30 Feedback**

**Dinner at the local brewery starting from 19h30**

**Schadt's Brauerei Gasthaus**

**Marstall 2**

**38100 Braunschweig**

# WP4 Training Agenda Day 2

**09:00 - 10:45 - 1st session Hands on session test modelling in groups on realistic system testing environment (Speed and distance monitoring Model) - Uwe Schulze and Cécile Braunstein**

**10:45 - 11:00 Coffee break**

**11:00 - 12:45 - 2nd session Hands on session test modelling in groups on realistic system testing environment (Using the Braking Curve Model) - Uwe Schulze and Cécile Braunstein**

**12:45 - 13:45 - lunch**

**13:45 - 14:15 - Presenting results and feedback on model and test generation**

**Session: How to go on**

**14:15 - 14:30 Other approaches and how to combine the benefits?**

**14:30 - 14:50 How to co- simulate with other approaches: CPNTools - Christian Stahl**

**14:50 - 15:00 Feedback and sum up - How to provide a common workflow? - Marc Behrens**

## Legal Base

- Technical Specification for Interoperability (TSI-CCS)
- Proposed by the ERA (European Railway Agency)
- Decided on and Published by the European Commission
  
- Current Version of the TSI-CCS:
  - **2012/88/EU (complete Version)**
  - **2012/696/EU (Amendment with the current documents)**
    - Annex A contains the current legal reference of Subset-026 valid for Baseline 2 and 3
  - **Baseline 2 as well as Baseline 3 are current legal standards**
  - **Within openETCS Baseline 3 is used**



## Chapters of Subset-026

|   |                 |
|---|-----------------|
| ■ Chapter 1 Introduction                        | No of Req.: 0   |
| ■ Chapter 2 Basic System Description            | No of Req.: 0   |
| ■ Chapter 3 Principles                          | No of Req.: 737 |
| ■ Chapter 4 Modes and Transitions               | No of Req.: 720 |
| ■ Chapter 5 Procedures                          | No of Req.: 487 |
| ■ Chapter 6 Management of older System Versions | No of Req.: 200 |
| ■ Chapter 7 ERTMS/ETCS language                 | No of Req.: 708 |
| ■ Chapter 8 Messages                            | No of Req.: 166 |

**Number of Requirements according to the Subset-076 Traceability.**

# Principles of Subset-026

- **Generalization: Subset-026 describes general principles and processes**
- **The general principles are then limited by special cases and procedures**
  - *E.g. degraded situations*

***Subset-026-5.4.5.2 to be applied on the Start of Mission***

***“The SoM flowchart described in section 5.4.3 only includes the main paths and does not exhaustively cover the various operational situations, which could occur while performing the SoM procedure (e.g. when revised instructions are given to the driver or when the driver needs to re-enter already captured data).”***

**→ When modelling the Subset-026 all relevant exceptions have to be known.**



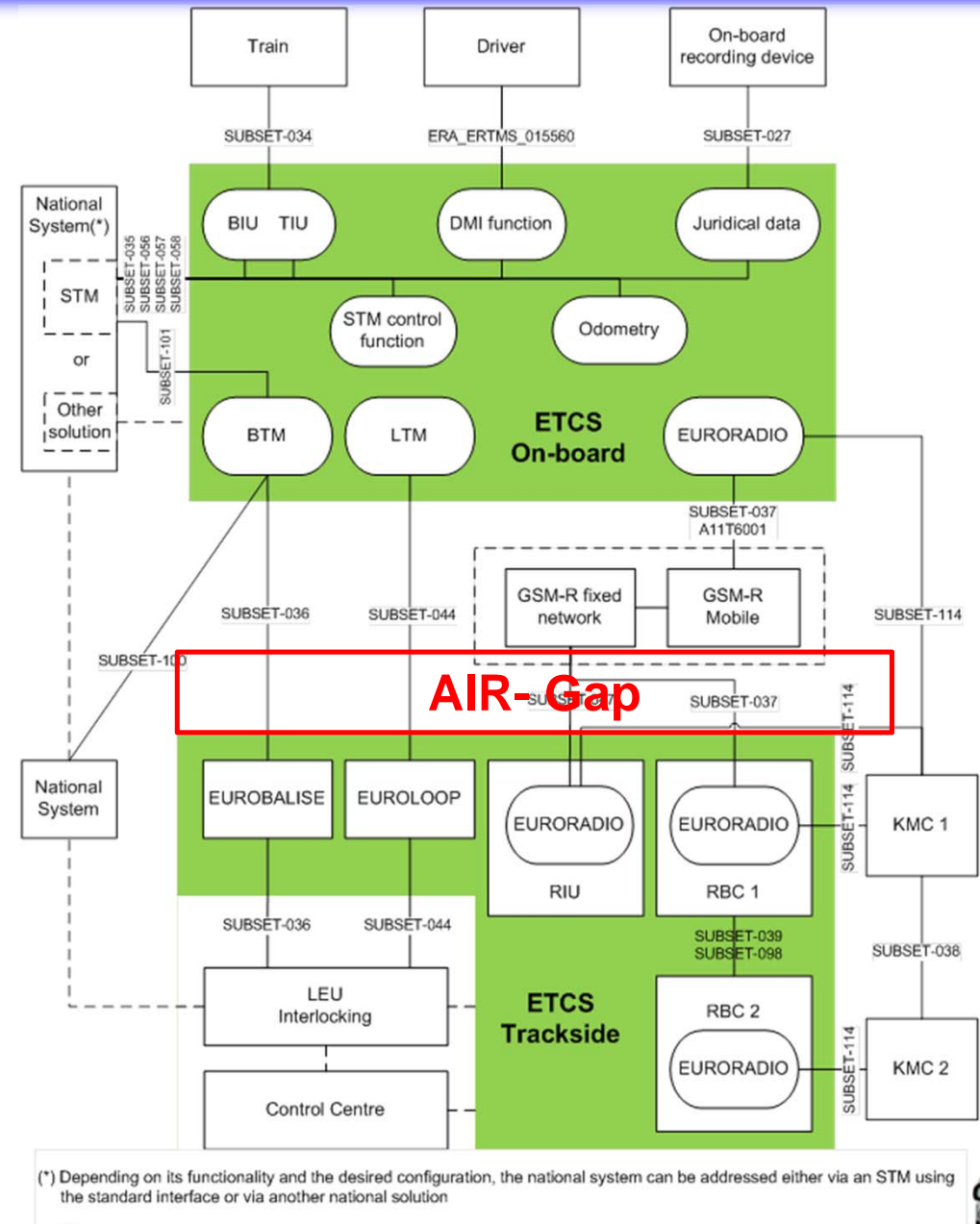
# Introduction into the structure of Subset-026

## Chapter 2 Principles

### Question

- How to understand the reference architecture?
- What is the Air-Gap?

Lookup: Subset-026-2.5.3

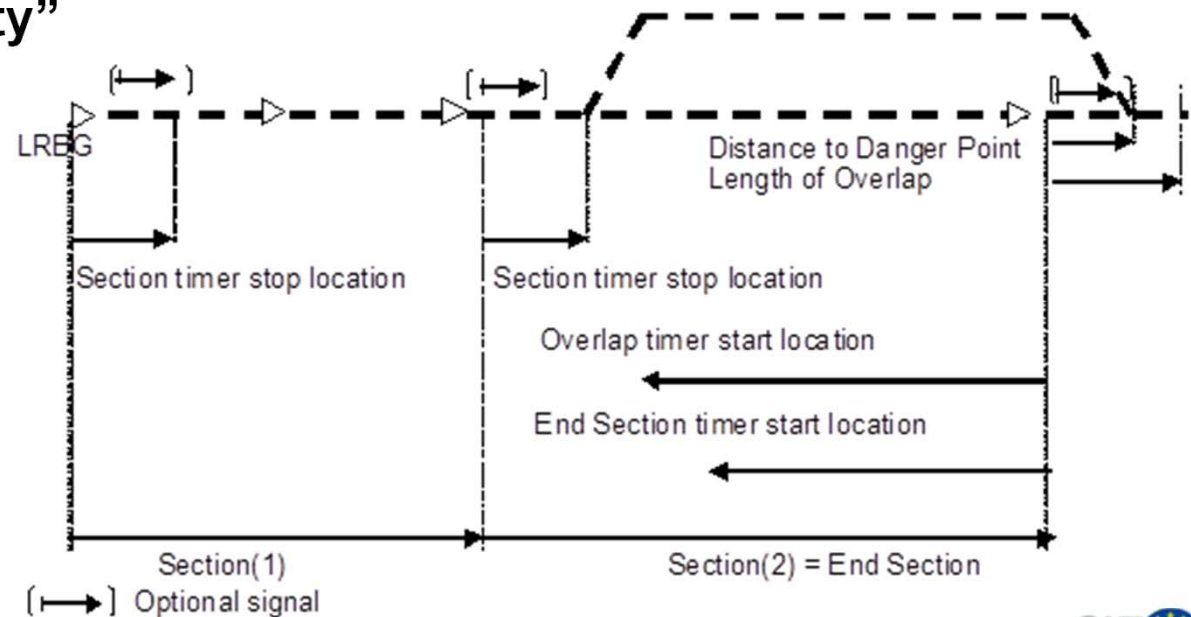


### Question

- What are the general principles for balise, radio, train position ...?
- What are the special functions?
- What is a movement authority?
- How is speed and distance monitoring (braking curves) defined?

Lookup:

Subset-026-3.8 “Movement Authority”



### Question

- How are the different modes defined, which responsibility is with the system, which with the driver? Subset-026-4.4
- For which mode is which DMI function active? Subset-026-4.7
- Under which special conditions are information accepted?  
Subset-026-4.8
- “Accepted information depending on the level and transmission media”  
Subset-026-4.8.3
- “What happens to accepted and stored information when entering a given level” Subset-026-4.9
- When is which Information deleted or to be revalidated? “What happens to accepted and stored information when entering a given mode”  
Subset-026-4.10

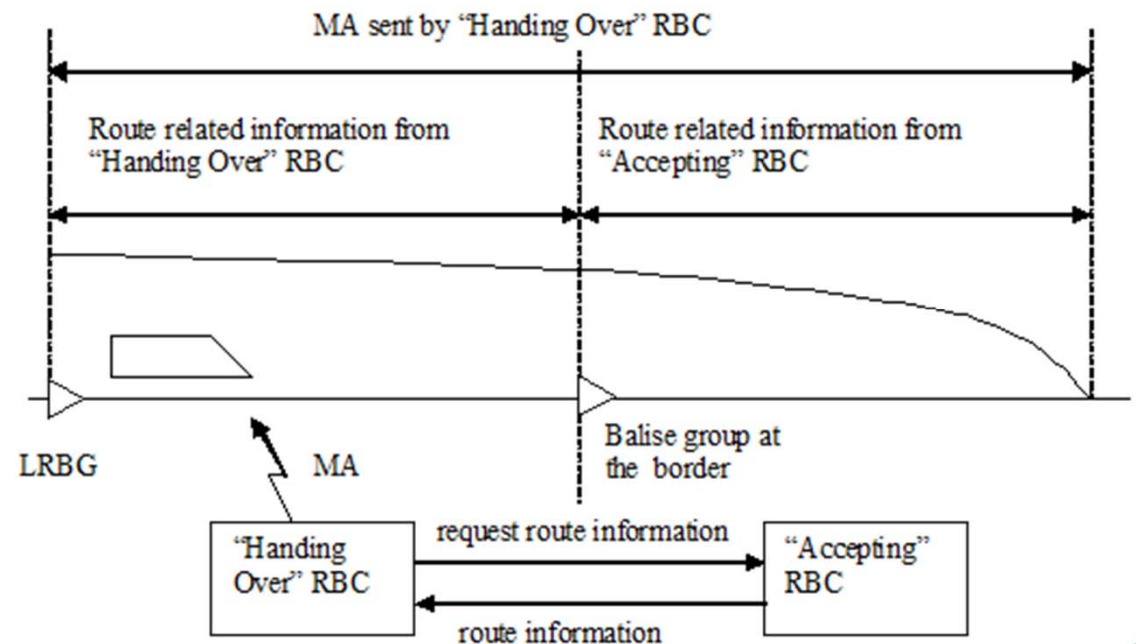
### Question

- How is the Start of Mission/ End of Mission defined?
- When does the OBU request a MA?
- How does shunting, override, train trip, changing train orientation, RBC/RBC handover, track conditions, limited supervision work?

Lookup:

Subset-026-5.15

RBC/RBC Handover



### Question

- How are compatible and incompatible system versions defined?
- What are the requirements for on-board and trackside when dealing with older versions?
- Principle: The on-board has to fulfil all requirements relevant for the version (for BL3 it has to understand BL2).

Lookup:

#### Subset-026-7.5.1.7.9 „M\_VERSION“

| Name        | Version of ETCS system   |
|-------------|--|
| Description | This gives the version of the ETCS system<br><br>Each part indicates the first and second number of the version respectively. <ul style="list-style-type: none"><li>- The first number distinguishes not compatible versions. (The three MSB's)</li><li>- The second number indicates compatibility within a version X. (The four LSB's)</li></ul> |
| 000 XXXX    | Previous versions according to e.g. EEIG SRS, UIC A200 SRS   |
| 001 0000    | Version 1.0, introduced in SRS 1.2.0 and re-used in SRSs 2.0.0, 2.2.2, 2.3.0   |
| 001 0001    | Version 1.1, introduced in SRS 3.3.0   |
| 001 0010    | Not valid  |
| ...         |  |
| 001 1111    | Not valid  |
| 010 0000    | Version 2.0, introduced in SRS 3.3.0   |
| 010 0001    | Reserved for future use (this is a valid value)  |
| ...         | ...  |
| 111 1111    | Reserved for future use (this is a valid value)  |

### Question

- Which variables are contained in the radio-, balise- and loop-air-gap packages?
- What is the meaning of the variables?
- Which Variables can be nationally set.

### Structure:

- Packages are divided into „Track to Train“ and „Train to Track“

### Lookup:

Subset-026-7.4.2.1.1 „Packet Number 3: National Values”

Subset-026-7.5.1.75.1 „M\_NVEBCL”

## Question

- Which packets are contained in which radio air-gap message?

## Structure:

- Messages are divided into „Track to Train“ and „Train to Track“

### Lookup: Subset-026-8.7.2 Message 3: Movement Authority

| Field No. | VARIABLE                           | Remarks   |
|-----------|------------------------------------|-----------|
| 1.        | NID_MESSAGE                        |           |
| 1.        | L_MESSAGE                          |           |
| 1.        | T_TRAIN                            |           |
| 1.        | M_ACK                              |           |
| 1.        | NID_LRBG                           |           |
| 1.        | Level 2/3<br>Movement<br>Authority | Packet 15 |
| 1.        | Optional packets                   |           |

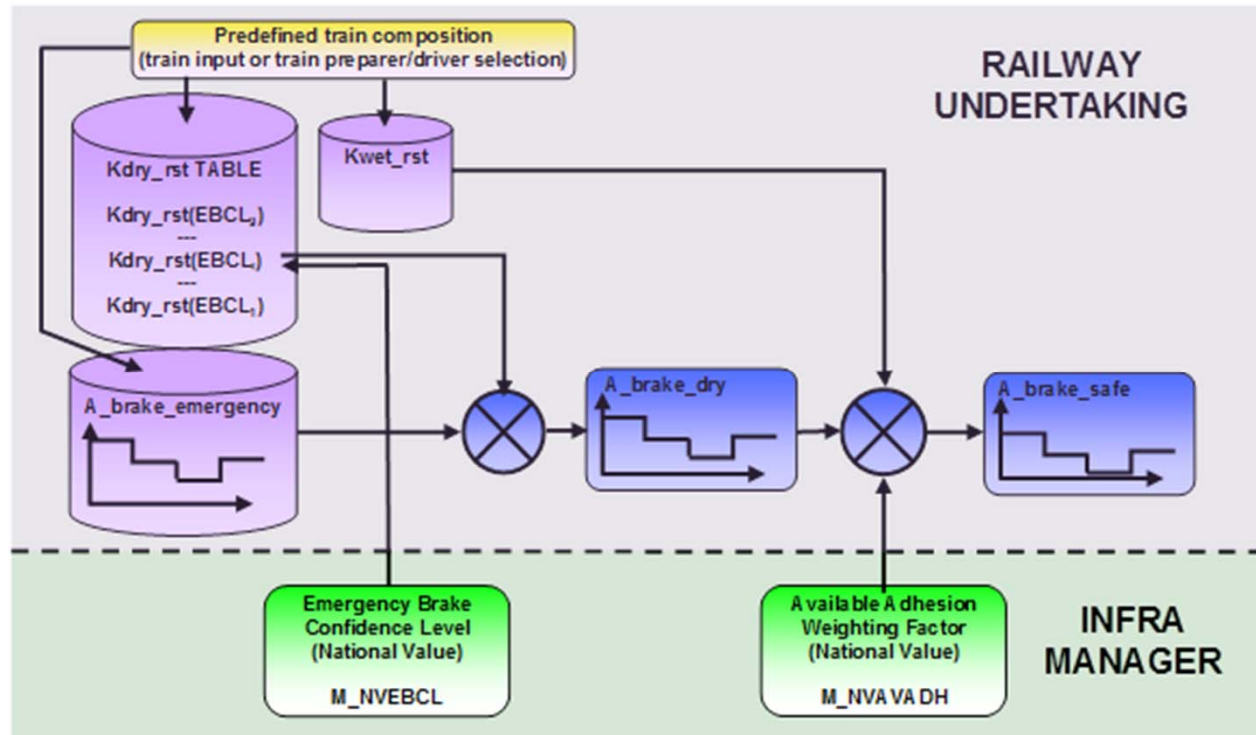
**Thank you for your attention!**



## What does „Braking curves mean to a railway operator“

Figures from „ ERA\_ERTMS\_040026”  
Introduction to ETCS Braking curves

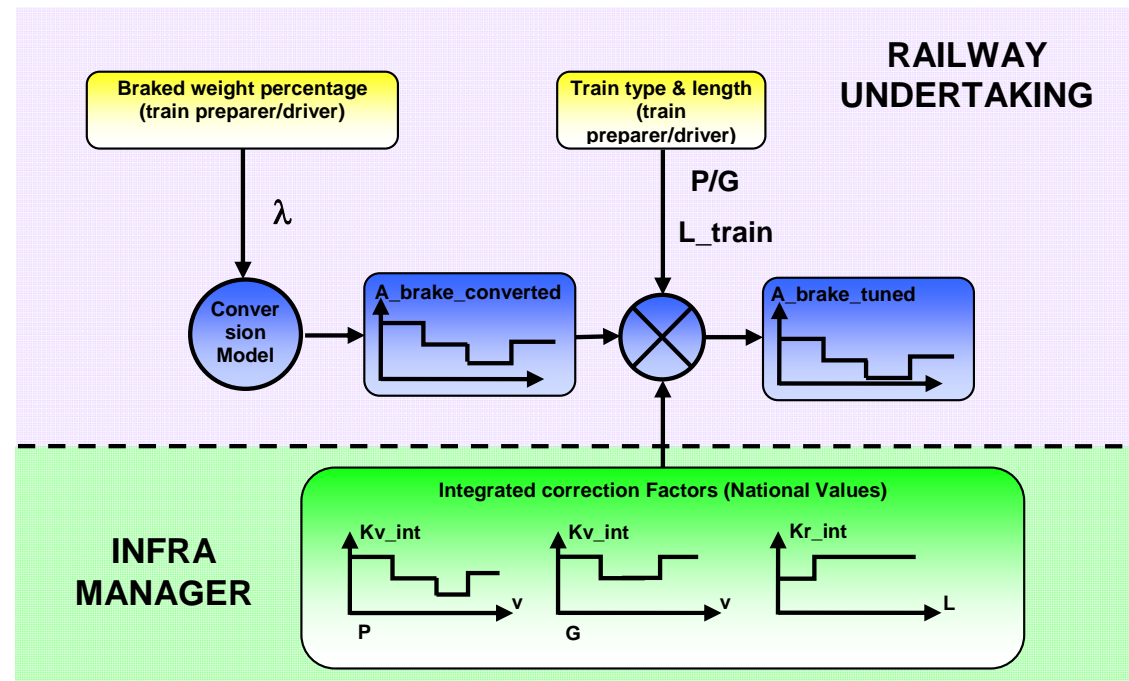
# Gamma Trains – Responsibility factors



**Figure 6: Rolling stock correction factors for Gamma trains – split of responsibility RU/IM**

**Specific to Gamma Trains: finite number of predefined compositions, on-board automatically preconfigured data/ -is selectable**

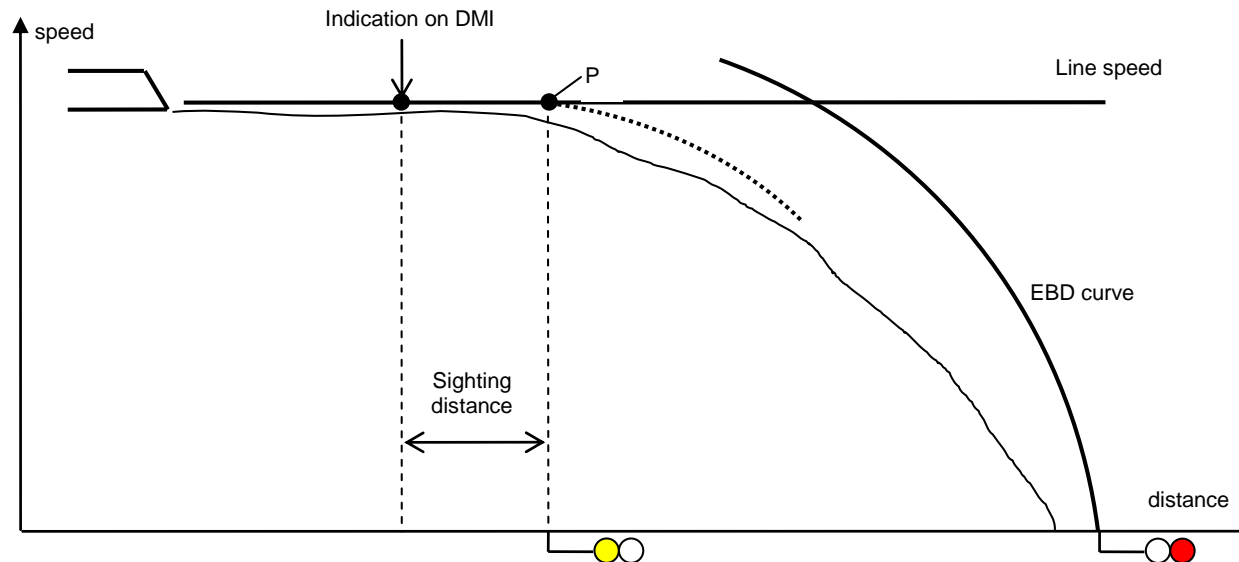
# Lambda Train – Responsibility factors



**Figure 7: Integrated correction factors for lambda trains**

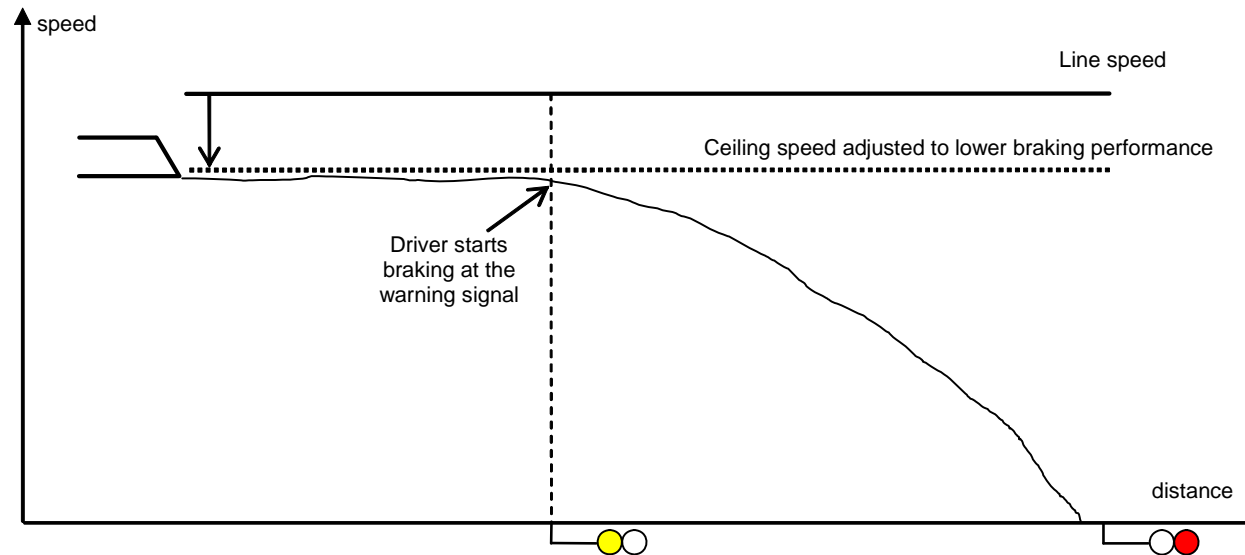
**Specific to Lambda Trains:** The braked weight percentage of the train is obtained by dividing the sum of the braked weight of all the individual vehicles.

# Old Principles: Train fitting to the line



***Figure 8: Train braking performance fitting the line (warning signal location and line speed), analogy between Cab signalling and Lineside signalling,***

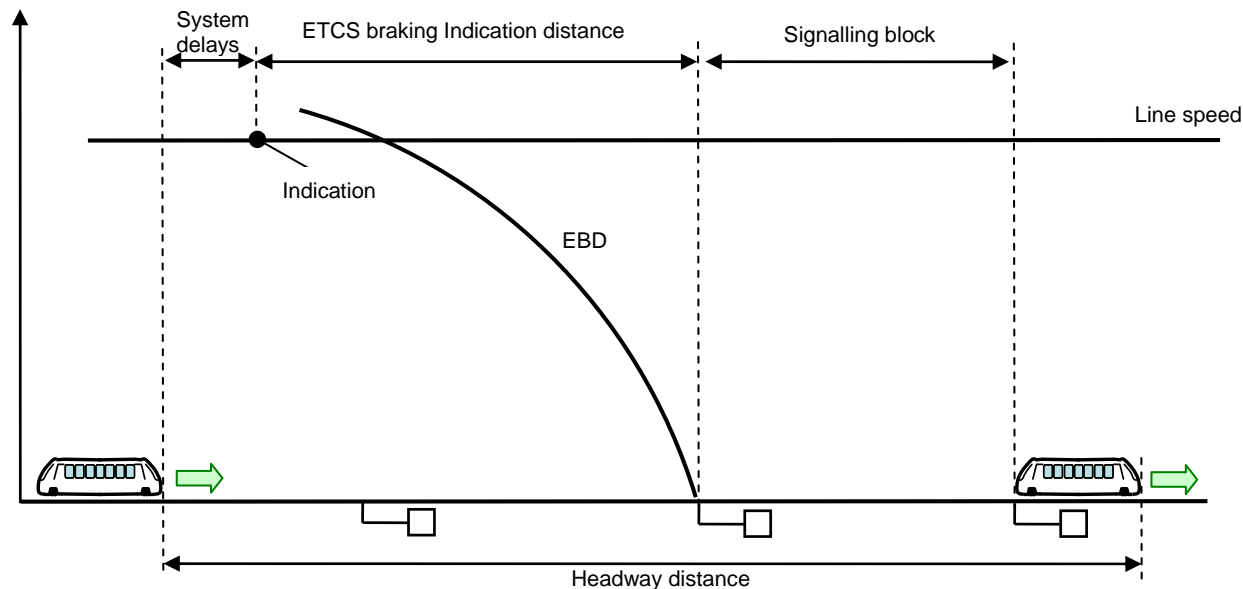
# Lower train braking performance



***Figure 9: Lower train braking performance,  
Lineside signalling without ETCS***

→ Performance of track is reduced: To brake at a correct distance with lineside signalling, the permitted speed to drive is reduced

# Better train braking performance



**Figure 11: Contribution of the ETCS braking curve to the headway**

→ Cab Signalling allows shorter headway

→ more trains can be drive over the same track during a fixed timeslot

**Thank you for your attention!**