







Nomenclature

$\ \cdot\ $		Euclidean Norm on \mathbb{R}^d	
$\langle \cdot, \cdot \rangle$		Scalar product on \mathbb{R}^d	
$\mathbb{R}_{\geq 0}$		Positive real numbers	
λ^d		Lebesgue measure on \mathbb{R}^d	
\mathcal{B}^d		Borel σ -algebra on \mathbb{R}^d	
$\text{Pot}(\cdot)$		Power set of a set	
$ \cdot $		Cardinality of a set	
$\mathcal{L}(\mu)$		μ -integrable functions	

TODO: Motivation for Optimal Transport & recall some definitions from measure theory

Let (X, \mathcal{A}) be a measurable space and $\mu, \tilde{\mu}$ measures on X . We say that μ is absolutely continuous with respect to $\tilde{\mu}$, if 

$$\tilde{\mu}(A) = 0 \Rightarrow \mu(A) = 0 \quad \forall A \in \mathcal{A}.$$

and denote this by $\mu \ll \tilde{\mu}$. Let (X, \mathcal{A}, μ) be a measure space and (Y, \mathcal{U}) a measurable space. For a measurable function $T : X \rightarrow Y$, we denote by $T_{\#}\mu$ the pushforward measure on Y induced by T , i.e 

$$T_{\#}\mu(B) = \mu(T^{-1}(B)) \quad \forall B \in \mathcal{U}.$$

TODO:


For a given finite set $S \subset \mathbb{R}^d$, we want to study the following problem:
Given two probability spaces $(\mathbb{R}^d, \mathcal{B}^d, \mu)$ and $(S, \text{Pot}(S), \nu)$, we want to minimize

$$\int_{\mathbb{R}^d} \|x - T(x)\|^2 d\mu \tag{0.1}$$

over all measurable maps $T : \mathbb{R}^d \rightarrow S$ satisfying $T_{\#}\mu = \nu$.

Recall that as $(S, \text{Pot}(S), \nu)$ is a finite probability space, we can write ν as a finite sum of Dirac measures

$$\nu = \sum_{s \in S} \nu_s \delta_s \quad \text{where } \nu_s \in \mathbb{R}_{\geq 0} \text{ and such that } \sum_{s \in S} \nu_s = 1. \tag{0.2}$$

Thus, the problem we are considering translates to finding a measurable map T that minimizes the functional in (0.1) and such that we have $\mu(T^{-1}(s)) = \nu_s$ for all $s \in S$. For any $s \in S$, we will call $\mu(T^{-1}(s))$ the capacity of s . 

TODO: ** Prove existence and uniqueness of a solution

As shown in [AHA], finding a measurable map that minimizes the above functional is



equivalent to finding the maximum of a concave function and thus, can be solved with standard optimization methods. The formulation of this optimization problem is done in two steps. First, we find a minimizer over all measurable functions with the same capacities. This optimal solution T_W is inspired geometrically and constructed using a predefined *weight vector* W .

The next step will consist in adapting this weight vector, such that the condition $T_{W\#}\mu = \nu$ is fulfilled.

The motivation behind this approach is inspired geometrically by studying a generalization of *Voronoi diagrams*. For clarity, we recall the definition of these diagrams and review the necessary concepts needed for this approach.

Definition 0.1 (Voronoi Diagrams). Let $S \subset \mathbb{R}^d$ be a finite set. We define for every point $s \in S$

$$\text{reg}(s) := \{x \in \mathbb{R}^d : \|x - s\| \leq \|x - \tilde{s}\| \quad \forall \tilde{s} \in S \setminus \{s\}\}.$$

We call this the *region* (or cell) of the point s . The partition of \mathbb{R}^d created by the union of the regions of all points is called the *Voronoi diagram* of S .

Remark. Note that the partition of \mathbb{R}^d generated by the Voronoi diagram is given by convex regions. Such a partition induces naturally a map $T : \mathbb{R}^d \rightarrow S$, which assigns each point in \mathbb{R}^d the corresponding point in S of the cell where it is located, i.e

$$T(x) = s \quad \Leftrightarrow \quad x \in \text{reg}(s). \quad (0.3)$$

By definition, some points in \mathbb{R}^d may belong to more than one region. By convention, T assigns those points an arbitrary one in S of the region where it is located. We call T , the by the Voronoi diagram induced assignment.

A generalization of the presented concepts arise when using another distance function for the definition of the regions. One application of this, amounts to using the *power function with weights* W which we now define.

Definition 0.2 (Power function). Let $S \subset \mathbb{R}^d$ be a finite set and $W : S \rightarrow \mathbb{R}$ a function on S . The power function with weights W is defined as

$$\text{pow}_W(x, s) := \|x - s\|^2 - W(s).$$

We call W the *weight function* on S .

Remark. For simplicity of notation we will write sometimes the weight function $W : S \rightarrow \mathbb{R}$ as a vector in $\mathbb{R}^{|S|}$. We will then call W the *weight vector* on S .

As in the case of Voronoi diagrams, we can define regions on \mathbb{R}^d by using the power function with weights W . For a point $s \in S$ we call

$$\text{reg}_W(s) := \{x \in \mathbb{R}^d : \text{pow}_W(x, s) \leq \text{pow}_W(x, \tilde{s}) \quad \forall \tilde{s} \in S \setminus \{s\}\}$$

the *power region* (or power cell) of s with weights W . Power regions also create a partition of \mathbb{R}^d which is called the *power diagram* of S with weights W .

The geometric intuition behind the definition of power diagrams becomes clear by looking at spheres around $s \in S$ with positive radius

$$\mathbb{S}_{\sqrt{W}}^{d-1}(s) := \{x \in \mathbb{R}^d : \|x - s\| = \sqrt{W(s)}\}$$

whenever $W : S \rightarrow \mathbb{R}_{>0}$. The power function $\text{pow}(\cdot, s)$ for a fixed $s \in S$, returns a negative (resp. positive) value, whenever $x \in \mathbb{R}^d$ is inside (resp. outside) the sphere $\mathbb{S}_{\sqrt{W}}^{d-1}(s)$ and zero when $s \in \mathbb{S}_{\sqrt{W}}^{d-1}(s)$. Thus, increasing (resp. decreasing) the values of the weights $W(s)$ on each point s would expand (resp. shrink) the power cells.

Remark. Unlike Voronoi diagrams, the power cells of a point $s \in S$ may not contain the point s or even may be empty. Nevertheless, the power diagram still partitions \mathbb{R}^d in a convex polyhedron.

By replacing reg with reg_W in (0.3) we obtain a map $T_W : \mathbb{R}^d \rightarrow S$ depending on the weight vector W . Similarly as with Voronoi diagrams, we assign those points sharing different cells, an arbitrarily point $s \in S$ of those shared regions. We call this map, the *power assignment* of S with weights W .

Power assignments have a natural optimization property, since by definition it holds

$$(T_W(x) = s \Leftrightarrow x \in \text{reg}_W(s)) \Leftrightarrow T_W(x) = \min_{s \in S} \|x - s\|^2 - W(s) \quad (0.4)$$

for all points $x \in \mathbb{R}^d$ which don't share different regions. In fact, power functions even minimize the functional (0.1) for a fixed predefined weight vector W . We will prove this in Lemma 0.4. As a consequence, the natural question which remains to be clarified is how to fix a choice of the weight vector W , such that it fulfills the condition $T_{W\#}\mu = \nu$.

We recall the change of variables theorem from the measure theory.

Theorem (change of variables). *Let (X, \mathcal{A}, μ) be a measure space, (Y, \mathcal{U}) a measurable space and $T : X \rightarrow Y$ a measurable function. For a measurable function $f : Y \rightarrow \mathbb{R}^d$ we have $f \in \mathcal{L}(T_{\#}\mu) \Leftrightarrow f \circ T \in \mathcal{L}(\mu)$ and when one of this statements is true then*

$$\int_{T^{-1}(B)} f \, dT_{\#}\mu = \int_B f \circ T \, d\mu \quad \text{for all } B \in \mathcal{U}. \quad (0.5)$$

Proof. Measure theory, e.g p.191 [J.E] □

Remark 0.3. Note that as the power region of a point $s \in S \subset \mathbb{R}^d$ is either an empty set or a convex polyhedra, it is measurable with respect to the Lebesgue measure λ^d on \mathbb{R}^d . Denoting by $\overset{\circ}{B}$ the interior of a set $B \in \mathcal{B}$ with respect to the standard topology, it holds

$$\lambda^d(\text{reg}(s)) = \lambda^d(\text{reg}^\circ(s)).$$

For a probability measure $(\mathbb{R}^d, \mathcal{B}^d, \mu)$ such that $\mu \ll \lambda^d$, we have then

$$\mu(\text{reg}(s)) = \mu(\text{reg}^\circ(s)) \quad \text{and} \quad \sum_{s \in S} \mu(\text{reg}(s)) = 1.$$

Lemma 0.4. Let $(\mathbb{R}^d, \mathcal{B}, \mu)$ be a probability space, such that $\mu \ll \lambda^d$. Let S be a finite subset of \mathbb{R}^d with weights W and $\zeta : S \rightarrow \mathbb{R}_{\geq 0}$ be a function on S . Then, the power assignment T_W minimizes

$$\int_{\mathbb{R}^d} \|x - T(x)\|^2 d\mu$$

over all measurable maps $T : \mathbb{R}^d \rightarrow S$ with capacities $\mu(T^{-1}(s)) = \zeta(s)$ for all $s \in S$.

Proof. Using the minimality condition (0.4) of power assignments, it holds

$$\text{pow}_W(x, T_W(x)) \leq \text{pow}_W(x, s)$$



for all $s \in S$. Consequently, T_W minimizes

$$\int_{\mathbb{R}^d} \text{pow}_W(x, T(x)) d\mu = \int_{\mathbb{R}^d} \|x - T(x)\|^2 d\mu - \int_{\mathbb{R}^d} \omega(T(x)) d\mu$$

over all measurable maps $T : \mathbb{R}^d \rightarrow S$. Using the fact that $\mathbb{R}^d = \bigcup_{s \in S} \text{reg}(s)$ together with remark 0.3, we obtain

$$\begin{aligned} \int_{\mathbb{R}^d} \omega(T(x)) d\mu &= \sum_{s \in S} \int_{\text{reg}(s)} W(T(x)) d\mu \\ &\stackrel{(0.5)}{=} \sum_{s \in S} \int_s W dT_{\#}\mu \\ &= \sum_{s \in S} \mu(T^{-1}(s)) W(s) \\ &= \sum_{s \in S} \zeta(s) W(s) \end{aligned}$$

which is constant for a fixed ζ and W . □



The natural question to handle next, is how to choose W , such that the condition $T_{W\#}\mu = \nu$ holds. As we will show below, this question can be equivalently formulated as finding the maximum concave function. In order to achieve this, we first recall the original setting of our original problem and introduce some definitions.

Let $(\mathbb{R}^d, \mathcal{B}, \mu)$ and $(S, \text{Pot}(S), \nu)$ be two probability spaces such that $\mu \ll \lambda^d$. As in Equation (0.2), we write $\nu = \sum_{s \in S} \nu_s \delta_s$ as a finite sum of Dirac measures. For $\mathcal{F} := \{f : \mathbb{R}^d \rightarrow S : f \text{ is measurable}\}$, define

$$L : \mathcal{F} \times \mathbb{R}^{|S|} \rightarrow \mathbb{R}, \quad (T, W) \mapsto \int_{\mathbb{R}^d} \text{pow}_W(x, T(x)) d\mu.$$

This map has important properties, which we will show and then transfer them to the concave function of our reformulated problem. For a map $T \in \mathcal{F}$, let

$$\zeta_T : S \rightarrow \mathbb{R}, \quad s \mapsto \mu(T^{-1}(s))$$

Let \mathbf{c} be the vector of capacities induced by T and

$$Q : \mathcal{F} \rightarrow \mathbb{R}, \quad T \mapsto \int_{\mathbb{R}^d} \|x - T(x)\|^2 d\mu$$

be the functional that we want to study. As shown in Lemma 0.4, it holds

$$L(T, W) = Q(T) - \langle \zeta_T, W \rangle.$$

And hence, $L(T, \cdot)$ defines a linear function on $\mathbb{R}^{|S|}$ for a fixed $T \in \mathcal{T}$. Recall that for a given $W \in \mathbb{R}^{|S|}$ and a power assignment T_W , we have $\text{pow}_W(x, T_W(x)) \leq \text{pow}_W(x, s)$ for all $s \in S$. Consequently, for a fixed $W \in \mathbb{R}^d$ we must have

$$T_W(W) = \arg \min_{T \in \mathcal{F}} L(T, W). \quad (0.6)$$

We claim that

$$f : \mathbb{R}^{|S|} \rightarrow \mathbb{R}^d, \quad W \mapsto L(T_W, W) = L_{T_W}(W)$$

is concave.

Proof. Let $\alpha \in [0, 1]$ and $W_1, W_2 \in \mathbb{R}^{|S|}$, then

$$\begin{aligned} f(\alpha W_1 + (1 - \alpha)W_2) &= L_{T_{\alpha W_1 + (1 - \alpha)W_2}}(\alpha W_1 + (1 - \alpha)W_2) \\ &= L_{T_{\alpha W_1 + (1 - \alpha)W_2}}(\alpha W_1) + L_{T_{\alpha W_1 + (1 - \alpha)W_2}}((1 - \alpha)W_2) \\ &\stackrel{(0.6)}{\geq} L_{T_{\alpha W_1}}(\alpha W_1) + L_{T_{(1 - \alpha)W_2}}((1 - \alpha)W_2) \\ &= \alpha L_{T_{\alpha W_1}}(W_1) + (1 - \alpha) L_{T_{(1 - \alpha)W_2}}(W_2) \\ &\stackrel{(0.6)}{\geq} \alpha L_{T_{W_1}}(W_1) + (1 - \alpha) L_{T_{W_2}}(W_2) = \alpha f(W_1) + (1 - \alpha) f(W_2) \end{aligned}$$

□

TODO: Prove formally that f is smooth

f is smooth and the gradient of f at W is given by $\nabla f(W) = -\zeta_{T_W}$. Recall that because of Lemma 0.4, to solve our problem (0.1) we need to find a weight vector W^* satisfying $T_{W^*}(\mu) = \nu$. In other words, it should hold $\mu(T_{W^*}^{-1}(s)) = \nu_s$ for all $s \in S$.

Consider now the function

$$H : \mathbb{R}^{|S|} \rightarrow \mathbb{R}, \quad W \mapsto f(W) + \langle \nu, W \rangle = \langle \nu - \zeta_{T_W}, W \rangle + Q(T_W).$$


This function is concave and differentiable as a sum of concave differentiable functions. Furthermore we have $\nabla H(W) = \nu - \zeta_{T_W}$ and hence also

$$T_{W\#}\mu(s) = \mu(T_W^{-1}(s)) = \nu_s \quad \forall s \in S \quad \Leftrightarrow \quad \zeta_{T_W} = \nu \quad \Leftrightarrow \quad \nabla H(W) = 0.$$

Thus we see that finding a solution of our original problem is in deed equivalent to

finding a maximum of the concave function H . We can compute

$$\begin{aligned}\frac{\partial H}{W(s)} &= \frac{\partial f(W)}{W(s)} + \frac{\partial \langle \nu, W \rangle}{W(s)} \\ &= -\mu(T_W^{-1}(s)) + W(s) \\ &= -\mu(\text{reg}(s)) + W(s).\end{aligned}$$

This optimization problem has a probabilistic interpretation. If we realize X as a random variable of distribution μ , i.e $X \sim \mu$. Then, defining 

$$h_W^\nu(x) := \min_{s \in S} \|x - s\|^2 - W(s) + \langle W, \nu \rangle = \|x - T_W(x)\|^2 - W(s) + \langle W, \nu \rangle,$$

we have

$$\begin{aligned}\mathbb{E}[h_W^\nu(X)] &= \int_{\mathbb{R}^d} \min_{s \in S} \|X - s\|^2 - W(s) \, d\mu + \int_{\mathbb{R}^d} \langle W, \nu \rangle \, d\mu \\ &= \int_{\mathbb{R}^d} \|x - T_W(X)\|^2 - W(s) \, d\mu + \langle W, \nu \rangle = H(W).\end{aligned}$$

In other words, our problem can be stated as minimizing the expected value of $h_W^\nu(X)$. 