# Stability Conditions on Topological String Theories

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#### Overview

- Building the Category of D-branes
  - The Nonlinear Sigma Model
  - Generalizing
  - Deforming the Theory
- Restoring the Physical Theory
  - Reintroducing the Kähler Form Dependence
  - Stability Against Decay
  - The Mysterious Octahedral Axiom
- Second Examples
  Second Examples
  - Brane-Antibrane Annihilation
  - The Quintic Threefold
- 4 Bridgeland Stability
  - Definitions
  - Basic Results
- 5 Looking Forward

# Summary of the Talk

We start by considering string theory in the twisted nonlinear sigma model with target space a complex projective Calabi-Yau threefold.

The boundary conditions for this theory form a category which is equivalent to  $D^b(Coh(X))$ , independent of Kähler form.

Douglas' Π-stability reintroduces the Kähler form dependence by giving a criterion for identifying when certain unstable objects decay into others (via distinguished triangles) as a function on the moduli space of Kähler forms.

In particular, one expects the set of all stable objects at a particular point to form an Abelian category functioning as the heart of our triangulated category.

Bridgeland stability generalizes this to a mathematically rigorous statement concerned with finding the "moduli space" of hearts of our derived category.

# What Do We Mean by a Physical Theory?

The definition of a *physical theory* is hard to pin down mathematically, and we do not aim at all to be rigorous here, but for our purposes:

- A physical theory is an algebra of operators (describing the "states" of the physical theory) subject to various consistency constraints, along with n-point functions which compute observables as functions of n operators.
- Two physical theories will be considered isomorphic if their observables agree (without getting precise). We'll see an example of this later.
- A *model* is a physical method of generating the operator algebra and the *n*-point functions. Every physical theory we will review here comes from a model.

# The Nonlinear Sigma Model

Our starting point is the nonlinear sigma model, which is a physical theory describing how strings propagate in a Calabi-Yau manifold X (usually of complex dimension 3).

The theory also needs the data of a closed, real two-form B which pairs with the Kähler form to make a *complexified Kähler form* B+iJ.

Generally B enters into the computation only modulo integer shifts.

### Topological Twisting

One of the striking features of the nonlinear sigma model is the fact that it can be *topologically twisted* in two different ways.

- The A-model twisting eliminates the complex structure dependence, and the theory only depends on the topology of X and the complexified Kähler form B + iJ (in fact, only its cohomology class).
- The *B-model twisting* eliminates the dependence on B + iJ, and depends only on the complex structure of X.

# Mirror Symmetry

The phenomenon of *mirror symmetry* shows itself (albeit incompletely) in these theories in the following way:

#### **Definition**

A pair of Calabi-Yau manifolds (X, Y) is called a *mirror pair* if the topological A-model on X is isomorphic as a theory to the topological B-model on Y.

If we restrict our attention of the mirror symmetry phenomenon to the moduli spaces, we get:

### Theorem (Expected)

For a mirror pair (X,Y), there exists a local isomorphism (the mirror map isomorphism) between the moduli space of complexified Kähler forms on X and the moduli space of complex structures on Y, preserving mirror symmetry.

### The Operator Algebra Associated to the B-model

The operator algebra in the B-model is physically obtained by the process of BRST quantization on an original "classical" theory, which mathematically amounts to finding a nilpotent operator Q with  $Q^2=0$  satisfying certain properties, and taking cohomology with respect to Q.

In the case of the B-model on a Calabi-Yau manifold X, the operators start their life in  $\Omega_X^{(-p,q)}$ , and the operator Q is the  $\bar{\partial}$  operator.

Hence, the BRST quantized objects are in  $H^{(-p,q)}X = H^q(X, \bigwedge^p T_X)$ 

### Including New Data

There is a variant of the previous construction, which takes in the additional data of a holomorphic vector bundle E on X. (We might require E originally to have a holomorphic connection, but the twisted operator algebra is independent of the connection chosen).

The operators lose their -p-form dependence, and take values in  $\operatorname{End}(E)$ , hence can all be expressed as (cohomology classes of) (0,q) forms with values in  $\operatorname{End}(E)$  i.e.  $H^{(0,q)}(X,\operatorname{End}(E))$ 

### Physical Interpretation of the Vector Bundle

The modification above can take place at the level of the untwisted (non-topological) nonlinear sigma model, and the conclusion we've stated is the result of twisting and BRST quantizing this variant.

The vector bundle E enters into the calculation as a *boundary term*, and has the effect of adding a U(r)-bundle to the boundary of the string for r the rank of E.

Physicists refer to this setup as a "stack" of r Dn-branes, for n the (real) dimension of X, thinking of a rank r vector bundle as a "stack" of rank 1 vector bundles.

### Adding the Grading

Physics tells us these branes come with a grading, so we'll include as part of our data a decomposition

$$E = \bigoplus_{n \in \mathbb{Z}} E^n$$

This decomposes our space of operators into

BRST local operators 
$$=\bigoplus_{q,m,n} H^{(0,q)}(X,(E^m)^{\vee}\otimes E^n)$$

and we define the *ghost number* of a definite-graded operator to be q-m+n

# Generalizing I

We generalize more by allowing E to be a *locally free sheaf*  $\mathscr E$  of finite rank over X.

Thus  $\mathscr E$  decomposes as

$$\bigoplus_{n\in\mathbb{Z}}\mathscr{E}^n$$

with all but finitely many  $\mathcal{E}^n$  zero.

Operators now live in

BRST local operators = 
$$\bigoplus_{q,m,n} \operatorname{Ext}^q(\mathscr{E}^m,\mathscr{E}^n)$$

# Generalizing II

The data we have now assembles into a category (denoted  $T_{\mathscr{E}}(X)$ ) in a nice way.

- The *objects* are the definite-grade parts of  $\mathscr{E}$ , namely  $\{\mathscr{E}^n\}$  for all n for which  $\mathscr{E}^n$  is nontrivial (the Dn-branes of our theory)
- The morphisms from  $\mathscr{E}^m$  to  $\mathscr{E}^n$  are given by the higher Ext-groups

$$\operatorname{Hom}_{\mathsf{T}_{\mathscr{E}}(X)}(\mathscr{E}^m,\mathscr{E}^n) = \bigoplus_q \operatorname{Ext}^q(\mathscr{E}^m,\mathscr{E}^n)$$

(the operators of our theory)

Composition is given by the Yoneda pairing

$$\operatorname{Ext}^p(\mathscr{E}^\ell,\mathscr{E}^m) \otimes \operatorname{Ext}^q(\mathscr{E}^m,\mathscr{E}^n) \to \operatorname{Ext}^{p+q}(\mathscr{E}^\ell,\mathscr{E}^n)$$

# Candidate Category of All Branes

Next, let's try and assemble a category of all possible such theories.

If we vary  $\mathscr E$  over all possible graded locally free sheaves of finite rank, we get a large category containing a lot of the branes.

We could even allow sheaves supported on submanifolds, yielding the category  $\operatorname{Coh}(X)_{\mathbb{Z}}$  of  $\mathbb{Z}$ -graded coherent sheaves on X, enlarged by allowing the hom-sets to be the total Ext group  $\bigoplus_q \operatorname{Ext}^q(-,-)$ .

These are referred to as Dp-branes, for p the dimension of the support of the coherent sheaf.

# Physical Interpretation of Dp-branes

Since the branes enter in to the calculation as boundary terms, if the brane  $\mathscr E$  does not have  $\operatorname{Supp}(\mathscr E)=X$ , we must force the boundary of the string to be restricted to  $\operatorname{Supp}(\mathscr E)$ .

This amounts to imposing Dirichlet boundary conditions on the endpoints of the string, hence the name D-brane, or Dirichlet-brane.

# Assembling the Category of All Branes

We've seen that the category of all branes considered so far has

- Objects: Coherent sheaves on X, graded by  $\mathbb{Z}$ .
- Morphisms: Higher Ext-groups

$$\operatorname{Hom}(\mathscr{E}^m,\mathscr{F}^n) = \bigoplus_{q} \operatorname{Ext}^q(\mathscr{E}^m,\mathscr{F}^n)$$

where q - m + n is the ghost number of the map.

#### Question

Does this category include all possible D-branes?

To answer this question, we need to look at deformations of our theory.

### The Deformation of Q

Let's return to the setup of a single coherent sheaf  $\mathscr E$  with grading

$$\mathscr{E} = \bigoplus_{n} \mathscr{E}^{n}$$

We can deform the theory by deforming the BRST operator Q.

The allowed changes are of the form  ${\it Q}={\it Q}_0+\delta{\it Q}$  with  ${\it Q}_0$  the original BRST symmetry, and

$$\delta Q = t\varphi := d$$

for  $\varphi$  some element of the operator algebra.

The physics demands that Q have definite ghost number 1, so we restrict to  $\varphi$  with ghost number 1. Such operators are called *marginal*.

#### Candidates for Deformation

The candidate ghost number 1 operators live in

$$\operatorname{Ext}^0(\mathscr{E}^n,\mathscr{E}^{n+1})$$
 $\operatorname{Ext}^1(\mathscr{E}^n,\mathscr{E}^n)$ 
 $\vdots$ 
 $\operatorname{Ext}^k(\mathscr{E}^n,\mathscr{E}^{n+1-k})$ 

The operators in  $\operatorname{Ext}^1(\mathscr{E}^n,\mathscr{E}^n)$  yield first-order deformations of  $\mathscr{E}^n$ , and add nothing new.

The operators in  $\operatorname{Ext}^0(\mathscr{E}^n,\mathscr{E}^{n+1})$  are worth examining in more detail.

### The Ext<sup>0</sup> Deformations

Deforming by an element of  $\operatorname{Ext}^0(\mathscr{E}^n,\mathscr{E}^{n+1})$  yields a new theory with branes specified by

- a finite collection of coherent sheaves  $\mathscr{E}^n$  of finite rank  $(n \in \mathbb{Z})$
- maps  $d_n \in \operatorname{Ext}^0(\mathscr{E}^n, \mathscr{E}^{n+1})$

### Consequences

The new BRST symmetry is now

$$Q = Q_0 + d$$

$$d = \bigoplus_n d_n$$

$$d_n : \mathscr{E}^n \to \mathscr{E}^{n+1}$$

In order for this to be a valid deformation, we need  $Q^2 = 0$ 

$$Q^{2} = \{Q, Q\}$$

$$= Q_{0}^{2} + \{Q_{0}, d\} + \{d, Q_{0}\} + d^{2}$$

$$= 0 + 2\{Q_{0}, d\} + d^{2}$$

Since  $d = t\varphi$ , and  $\varphi$  is  $Q_0$ -closed,  $\{Q_0, d\} = 0$ .

Hence  $d^2 = 0$  for the theory to be consistent.

### The Category of Bounded Complexes

An object in our category of branes now corresponds to a bounded complex of coherent sheaves and the category looks more like  $Ch^b(Coh(X))$ .

Deforming Q has the effect of deforming the BRST cohomology, which can be recomputed using a spectral sequence argument. As it turns out, the ghost number p operators between  $\mathscr{E}^{\bullet}$  and  $\mathscr{F}^{\bullet}$  are given by the *hyperext* 

$$\mathsf{Hom}_{\mathsf{T}(X)}(\mathscr{E}^{\bullet},\mathscr{F}^{\bullet}) = \bigoplus_{p} \mathsf{Ext}^{p}(\mathscr{E}^{\bullet},\mathscr{F}^{\bullet})$$

### Computing Hyperext

The hyperext groups are typically computed using an injective resolution  $\mathscr{F} \to \mathscr{I}$ , and taking cohomology of the internal hom complex

$$\mathsf{Ext}^p(\mathscr{E}^\bullet,\mathscr{F}^\bullet) = H^p([\mathscr{E}^\bullet,\mathscr{I}^\bullet])$$

where

$$[\mathscr{E}^{\bullet},\mathscr{F}^{\bullet}]^p = \bigoplus_n \mathsf{Hom}(\mathscr{E}^n,\mathscr{I}^{n+p})$$

# The New Category

Combining all this data yields a category  $\widetilde{K^b}(\operatorname{Coh}(X))$  with

- Objects are bounded complexes of coherent sheaves, now denoted as e.g. & with the gradings dropped
- Morphisms are given by the total hyperext groups

$$\mathsf{Hom}_{\widetilde{K^b}(\mathsf{Coh}(X))}(\mathscr{E},\mathscr{F}) = \bigoplus_{p} \mathsf{Ext}^p(\mathscr{E},\mathscr{F})$$

# When Are Two Objects the Same?

Two object (branes)  $\mathcal{E}_1$  and  $\mathcal{E}_2$  are considered *physically identical* if the ext groups can't tell them apart. That is, if and only if

$$\begin{split} \operatorname{Ext}^{\rho}(\mathscr{E}_1,\mathscr{F}) &\cong \operatorname{Ext}^{\rho}(\mathscr{E}_2,\mathscr{F}) \text{ and } \\ \operatorname{Ext}^{\rho}(\mathscr{F},\mathscr{E}_1) &\cong \operatorname{Ext}^{\rho}(\mathscr{F},\mathscr{E}_2) \end{split}$$

This condition is necessary and sufficient to guarantee the n-point functions for operators involving  $\mathcal{E}_1$ , when replaced with  $\mathcal{E}_2$ , do not change.

The resulting category obtained from  $\widetilde{K^b}(\operatorname{Coh}(X))$  by modding out by this equivalence will be denoted  $\mathbf{T}(X)$  (the category of *topological field theories* on X).

### Consequences

Consider  $f: \mathscr{E}_1 \to \mathscr{E}_2$  a quasi-isomorphism (induces isomorphisms on cohomology).

Its mapping cone complex Cone(f) is therefore acyclic (cohomology zero), and from the spectral sequence, we have for arbitrary  $\mathscr{F}$ 

$$\operatorname{Ext}^p(\operatorname{Cone}(f),\mathscr{F})\cong\operatorname{Ext}^p(\mathscr{F},\operatorname{Cone}(f))\cong 0$$

Hence

$$\operatorname{Ext}^p(\mathscr{E}_1,\mathscr{F})\cong\operatorname{Ext}^p(\mathscr{E}_2,\mathscr{F})$$

(and vice versa) from the long exact sequence of cohomology.

# Mapping From the Derived Category

We have a functor  $G: \mathsf{Ch}^b(\mathsf{Coh}(X)) \to \mathsf{T}(X)$  sending an object to itself, and a morphism to its homotopy class modulo physical equivalence in  $\mathsf{T}(X)$ .

This sends quasi-isomorphisms to isomorphisms in T(X), so it factors through the derived category  $D^b(\operatorname{Coh}(X))$  (bounded, since it maps from bounded chain complexes) and we get a map

$$G: D^b(\mathsf{Coh}(X)) \to \mathsf{T}(X)$$

# Locating the Derived Category

Consider the subcategory  $T_0(X)$  with the same objects as T(X), but morphisms in degree zero only.

It turns out  $G: D^b(Coh(X)) \to T_0(X)$  is an equivalence of categories.

### Summary

The total topological field theory category on X, T(X), contains morphisms of all degrees with

$$\mathsf{Hom}_{\mathsf{T}(X)}(\mathscr{E},\mathscr{F}) = \bigoplus_{p} \mathsf{Ext}^{p}(\mathscr{E},\mathscr{F})$$

modulo physical equivalence.

We can flatten this category to  $T_0(X)$  by considering only the degree-zero morphisms, with

$$\mathsf{Hom}_{\mathsf{T}_0(X)}(\mathscr{E},\mathscr{F}) = \mathsf{Ext}^0(\mathscr{E},\mathscr{F})$$

modulo physical equivalence.

This category is equivalent to  $D^b(Coh(X))$  the bounded derived category of coherent sheaves on X.

# Many Physical Theories, One Topological Theory

The physical theory depends critically on the complexified Kähler form B+iJ, but BRST quantization and twisting eliminated this dependence.

The critical question:

#### Question

Can we identify the objects in  $T_0(X)$  that correspond to physical branes in a particular physical theory?

Here, a physical brane is, roughly, an admissible boundary term that one can add to the untwisted nonlinear sigma model. Recall that the image of such a term after twisting and taking BRST cohomology lies in  $T_0(X)$ .

# BPS States and Central Charge

Our motivating example: E a holomorphic vector bundle over X. In effective physics where X is integrated out, E produces a BPS particle which can be studied.

If we consider the effective physics, E has a quantity, the *central charge* associated to it, computed as

$$Z(E) = Q_i(E)\Pi^i$$

where  $Q_i(E)$  is a charge vector for E and  $\Pi^i$  depends on the geometry of X.

# The Central Charge

In our case, this yields (near the large-volume limit)

$$Z(E) = \int_X \exp(-(B+iJ)) \operatorname{ch}(E) \sqrt{\operatorname{td}(T_X)} + \operatorname{Quantum Corrections}$$

More generally, we expect there to exist a group homomorphism

$$Z:K(X)\to\mathbb{C}$$

from the Grothendieck group of  $D^b(\operatorname{Coh}(X))$  to  $\mathbb C$ 

# Adding in the $\mathbb{R}$ -grading

Fixing B + iJ near the large-volume limit, we can now associate a real number to each vector bundle over X defined as

$$\xi(E) = \frac{1}{\pi} \log(Z(E))$$

This is the  $\mathbb{R}$ -grade of the vector bundle E, and in general is only defined mod 2.

### Physical Interpretation

We can interpret the complex number  $\mathcal{Z}(E)$  as encoding two quantities:

- The mass of the BPS brane is ||Z(E)||
- The particular  $\mathcal{N}=1\subset\mathcal{N}=2$  supersymmetry preserved by E is encoded in  $\arg(Z(E))$ .

# Extending the $\mathbb{R}$ -grading

We'll demand that  $\xi(E)$  vary continuously with B+iJ, so long as E lies in a certain class of objects called the  $\Pi$ -stable objects of the theory.

Hence, we expect stability to be a function of points in the path space for the moduli space for B + iJ.

We'll also extend the  $\mathbb{R}$ -grading to the deformed boundary conditions (complexes of locally free sheaves) by

$$Z(\mathscr{E}^{\bullet}) = \sum_{n} (-1)^{n} \mathscr{E}^{n}$$

By analysis of the A-model picture, we also demand

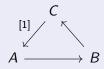
$$\xi(\mathscr{E}[n]) = \xi(\mathscr{E}) + n$$

# What Are the Stable Objects?

We "define" the  $\Pi$ -stable objects at a point B+iJ in the complexified Kähler moduli space to be as:

### Definition (Circular!)

Suppose B is an object of  $T_0(X)$ , and we've picked a point B+iJ in the complexified Kähler moduli space. Then, B is said to be  $\Pi$ -stable at B+iJ if, for all distinguished triangles of the form



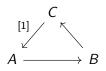
with A and C  $\Pi$ -stable, we have

$$\xi(A) < \xi(B) < \xi(C)$$

# What Are the Stable Objects?

By shifting triangles around, we can rephrase this definition:

For a distinguished triangle



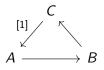
we have:

- C is stable against decay to A[1] and B if  $\xi(B) < \xi(A) + 1$
- ullet C is marginally stable against decay to A[1] and B if  $\xi(B)=\xi(A)+1$

### Some Clarification on Notation

### Summary of stability conditions:

• Decay Product Notation: For the triangle



B is stable against decay to A and B if

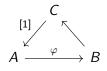
$$\xi(A) < \xi(B) < \xi(C)$$

(think of B as an extension of C by A)

### Some Clarification on Notation

Summary of stability conditions:

• Mapping Cone Notation: For the triangle



C is stable against decay to B and A[1] if

$$\xi(B) - \xi(A) < 1$$

i.e.  $\varphi$  has degree between 0 and 1 (think of C as the mapping cone of  $\varphi$ , and when  $\varphi$  has degree between 0 and 1 it becomes tachyonic)

# Physical Interpretation: Tachyon Condensation

Suppose C is a bound state of A[1] and B. This means that  $C = \mathsf{Cone}(\varphi: A \to B)$ .

Physically, this corresponds to  $\varphi$  being a "tachyonic" state (a state with negative mass) which means the theory with  $\varphi$  as a state will flow to one in which  $\varphi$  binds A[1] and B together.

# Walls of Marginal Stability

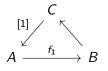
Suppose we start at a point where C is marginally stable against decay to A[1] and B. We'll say that this point lies on the ms-wall for C.

If we move around, one of three things could happen:

- We could stay on the ms-wall, and the gradings of A, B, and C will not change
- We could leave the ms-wall in the direction of C becoming stable, in which case the map  $\phi:A\to B$  becomes tachyonic and condenses A[1] and B into C
- We could leave the ms-wall in the other direction, making  $\xi(B)-\xi(A)-1>0$  which forces the grade shift on the other two maps of the triangle to go negative, resulting in the CFT breaking and C no longer representing a stable object

## Multiple Decay Channels

Setup:  $C = \text{Cone}(f_1 : A \to B)$  has a potential decay into A[1] and B, and  $B = \text{Cone}(f_2 : E \to F)$  has a potential decay into E[1] and F.





### Multiple Decay Channels

Start at a point  $P_0$  where both C and B are stable, with  $P_1$  a point where neither are stable.

Consider two paths  $\gamma_1$  and  $\gamma_2$  from  $P_0$  to  $P_1$ , with  $\gamma_1$  crossing the ms-wall for C first, followed by the ms-wall for B, and vice versa for  $\gamma_2$ 

# Moving Around

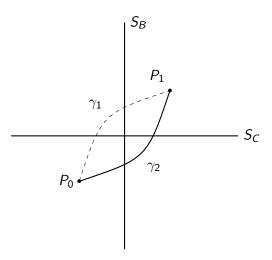


Figure: Two possible paths around a point where two ms-walls cross. If the theory only depends on the homotopy class of paths, *C* should destabilize in both cases

# Multiple Decay Channels

At  $P_0$  we have the following triangles

$$\begin{array}{ccc}
C & & \\
 & \swarrow & & \\
A & \longrightarrow & B
\end{array}$$

• 
$$\xi(B) - \xi(A) \le 1$$

• 
$$\xi(C) = \xi(B)$$

with  $\xi(B) - \xi(A) = 1$  on the C ms-wall

$$E \xrightarrow{[1]} F$$

• 
$$\xi(F) - \xi(E) \le 1$$
  
•  $\xi(B) = \xi(F)$ 

$$\bullet \ \xi(B) = \xi(F)$$

with  $\xi(F) - \xi(E) = 1$  on the B ms-wall.

### An Apparent Contradiction

If we follow the path  $\gamma_1$  across the C ms-wall, we conclude that C is unstable at  $P_1$  along the path  $\gamma_1$ .

Suppose instead we take the  $\gamma_2$  path, where B destabilizes first. Since B is no longer stable, we can't draw any conclusions from the ABC triangle.

Hence, C could remain stable along  $\gamma_2$ , which isn't great.

# The Octahedral Axiom for the Derived Category

It turns out that this setup satisfies the hypotheses for the octahedral axiom for triangulated categories.

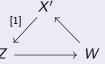
#### **Axiom**

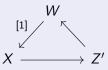
For any two distinguished triangles sharing the same vertex





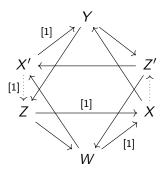
there exists an object W and two more distinguished triangles





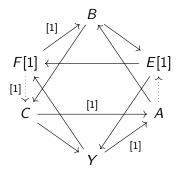
Making the "octahedral diagram" commute.

# The Octahedral Diagram



## Our Example

In our example of A, B, C, E, and F we have

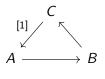


for Y the new object.

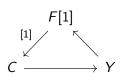
### Tracking the Gradings

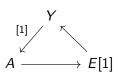
Suppose we start with everything marginally stable, and  $\xi(A) = \varphi$ . By the definition of marginally stable, we can compute the stability angles of everything else:

Object	Angle
Α	$\varphi$
В	arphi+1
С	arphi+1
Ε	$\varphi$
E[1]	$\varphi + 1$
F	arphi+1
F[1]	$\varphi$ + 2
Y	arphi+1





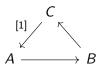


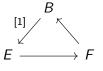


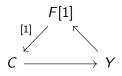
### Letting B Decay

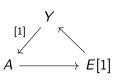
Let's vary the Kähler form to allow B to decay. This means  $\xi(F)-\xi(E)>1$  and since the grading of B doesn't change (its set by A) we get (for  $\alpha,\beta,\gamma>0$ )

Object	Angle
Α	$\varphi$
В	arphi+1
С	arphi+1
Ε	$\varphi - \alpha$
E[1]	$\varphi + 1 - \alpha$
F	$\varphi + 1 + \beta$
F[1]	$\varphi$ + 2 + $\beta$
Y	$\varphi + 1 - \gamma$









# Examining the New Decay Channels

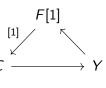
The first triangle has

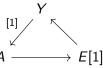
$$\xi(F[1]) - \xi(Y) = 1 + \beta + \gamma > 1$$

which destabilizes C, as desired! The second triangle has

$$\xi(E[1]) - \xi(A) = 1 - \alpha < 1$$

which stabilizes Y in this decay channel.

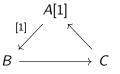


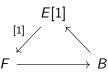


Hence, we expect the set of stable branes to be dependent only on the homotopy class of path from a known basepoint, and thus well-defined on the universal cover of the moduli space for B + iJ.

# Describing the Decay

Finally, observe that in the space where both B and C are unstable, we have unstable triangles





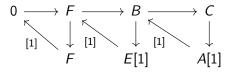
describing C decaying into B and A[1], and B decaying into F and E[1]

$$\xi(B) > \xi(C) > \xi(A[1])$$

$$\xi(F) > \xi(B) > \xi(E[1])$$

### The Filtration

This is summarized in a generalized filtration of C as



describing how C decays. If the angles are tracked, we get

$$\xi(F) > \xi(E[1]) > \xi(A[1])$$

A main conjecture is that the  $\Pi$ -stable objects at any point in the moduli space are rich enough to allow such a filtration for any object.

### Summary

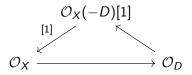
- The  $\mathbb{R}$ -grade of a stable object is given by the argument of its value under the central charge function.
- It is really defined locally around a point where the stable objects are already known, and is expected to be well-defined on points in the universal cover.
- Π stability suggests the existence of filtrations of any object in the derived category into extensions of stable objects.

### The Antibrane

#### **Definition**

For any brane  $\mathscr{E} \in T_0(X)$ , its *antibrane* is its image under the left shift functor. That is,  $\mathscr{E}[1]$ .

Branes and anti-branes tend to annihilate:



describes  $\mathcal{O}_X$  and  $\mathcal{O}_X(-D)$  forming the bound state  $\mathcal{O}_D$ .

In the large volume limit this triangle is stable in the sense that

$$\xi(\mathcal{O}_X) < \xi(\mathcal{O}_D) < \xi(\mathcal{O}_X(-D)[1])$$

### An Explicit Mirror Pair: The Quintic Threefold

Consider a quintic hypersurface  $X \hookrightarrow \mathbb{P}^4_{\mathbb{C}}$ . It has a mirror pair Y given by a  $(\mathbb{Z}_5)^3$  orbifold of a quintic with general equation

$$x_0^5 + x_1^5 + x_2^5 + x_3^5 + x_4^5 - 5\psi x_0 x_1 x_2 x_3 x_4$$

The parameter  $\psi$  encodes the complex structure of Y, whose moduli space is one-dimensional. We'll set  $z=(5\psi)^{-5}$  as a more natural coordinate.

The mirror map then sets  $B + iJ := t = \frac{1}{2\pi i} \log(z) + O(z)$  expressing the invariance of B under an integer shift.

## The Moduli Space of Y

Some points in the moduli space to consider:

- The point z = 0 is mirror to the large-radius limit of X
- The point  $z = \infty$  is mirror to the "Gepner point" of X
- The point z = 1 is mirror to the "conifold point" of X

# The Central Charge

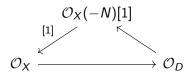
In this case near the large-radius limit we can compute the stability angles of all the line bundles on X coming from  $\mathbb{P}^4$ .

$$\xi(\mathcal{O}_X(N)) = \frac{1}{\pi} \arg(5(N - B - iJ)^3)$$
$$= \frac{3}{\pi} \theta_N - 3$$

for  $\theta_N$  the angle between the positive real axis and B+iJ-(N+i0)

# One Decay Channel

We have the potential decay channel



for any map  $f: \mathcal{O}_X(-N) \to \mathcal{O}_X$ , with D the vanishing locus of f.

This D4-brane  $\mathcal{O}_D$  is stable against decay into the D6-brane  $\mathcal{O}_X$  and the anti-D6-brane  $\mathcal{O}_X(-N)[1]$  when

$$\xi(\mathcal{O}_X) - \xi(\mathcal{O}_X(-N)) < 1$$

or when  $\theta_0 - \theta_{-N} < \frac{\pi}{3}$ 

# Lines of Marginal Stability

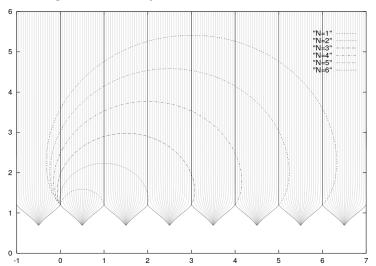


Figure: Borrowed from a paper of Aspinwall and Douglas (hep-th/0110071), the brane  $\mathcal{O}_D$  is *stable* above the line in the *t*-plane.

# A New Boundary Condition

Let

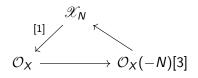
$$f \in \text{Hom}(\mathcal{O}_X(-N), \mathcal{O}_X) \cong \text{Hom}(\mathcal{O}_X, \mathcal{O}_X(N)) \cong H^0(\mathcal{O}_X(N))$$

By Serre duality, we get a map

$$f^\vee \in H^3(\mathcal{O}_X(-N)) \cong \operatorname{Ext}^3(\mathcal{O}_X, \mathcal{O}_X(-N)) \cong \operatorname{Hom}(\mathcal{O}_X, \mathcal{O}_X(-N)[3])$$

Define  $\mathscr{X}_N = \mathsf{Cone}(f^{\vee})$ 

# A New Decay Channel?



When is  $\mathscr{X}_N$  stable? This happens when

$$\xi(\mathcal{O}_X(-N)) + 3 - \xi(\mathcal{O}_X) < 1$$

This is *unstable* in the large-radius limit

# A Description of the New Object

By following the mapping cone construction we determine that  $\mathscr{X}_N$  is quasi-isomorphic to the complex

$$0 \longrightarrow \mathscr{I}_0 \longrightarrow \mathscr{I}_1 \longrightarrow \mathscr{I}_2 \oplus \mathcal{O}_X \longrightarrow \dots$$

for  $\mathscr{I}_{\bullet}$  an injective resolution of  $\mathcal{O}_X(-N)$ .

As long as this map is nontrivial,  $\mathscr{X}_m$  is not quasi-isomorphic to a single coherent sheaf, or even a direct sum of them!

# Formalizing Stability

Bridgeland distills this phenomenon of stability in what is now known as a Bridgeland stability condition on a triangulated category  $\mathcal{T}$ .

#### Definition

A Bridgeland stability condition on a triangulated category  $\mathcal T$  is the data of a group homomorphism

$$Z:K(\mathcal{T}) \to \mathbb{C}$$

(the *central charge function*), along with a choice of full additive subcategories  $\mathcal{P}(\phi)$  for all  $\phi \in \mathbb{R}$ , such that they satisfy the axioms...

# Formalizing Stability

#### Definition

- $\ldots(Z,\mathcal{P})$  satisfies the axioms
  - For every  $E \in \mathcal{P}(\phi)$ , we have  $Z(E) = m(E) \exp(i\pi\phi)$  for  $m(E) \in \mathbb{R}^+$
  - $\mathcal{P}(\phi+1)=\mathcal{P}(\phi)[1]$  for all  $\phi$
  - If  $\phi_1 > \phi_2$  and  $A_j \in \mathcal{P}(\phi_j)$ , then

$$\mathsf{Hom}_{\mathcal{T}}(A_1,A_2)=0$$

• Every object  $E \in \mathcal{T}$  admits a *Harder-Narasimhan* filtration with respect to  $(Z, \mathcal{P})$ 

### Harder-Narasimhan Filtrations

#### Definition

A Harder-Narasimhan Filtration of an object E with respect to a stability condition  $(Z, \mathcal{P})$  is a finite sequence  $\phi_1 > \phi_2 > \cdots > \phi_n$  of real numbers, and a filtration

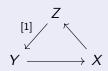
with  $A_i \in \mathcal{P}(\phi_i)$  and all triangles distinguished.

Stability can also be understood in terms of hearts of  $\mathcal{T}$ .

### **Definition**

A *t-structure* on a triangulated category  $\mathcal{T}$  is a choice of two strictly full subcategories  $\mathcal{T}_{\geq 0}$  and  $\mathcal{T}_{< 0}$  such that

- $\bullet$   $\mathcal{T}_{\geq 0}$  is closed under suspension, and  $\mathcal{T}_{\leq 0}$  is closed under looping
- $\bullet \ \operatorname{\mathsf{Hom}}(X,Y[-1]) = 0 \ \text{for all} \ X \in \mathcal{T}_{\geq 0} \ \text{and} \ Y \in \mathcal{T}_{\leq 0}$
- ullet Every object  $X\in\mathcal{T}$  sits in a distinguished triangle



with  $Y \in \mathcal{T}_{\geq 0}$  and  $Z \in \mathcal{T}_{\leq 0}[-1]$ 

## An Example

The standard example of a t-structure on the derived category  $\mathcal{D}(\mathcal{A})$  is given by

$$D(\mathcal{A})_{\geq 0} = \{ A^{\bullet} \in D(\mathcal{A}) \mid H^{i}(A^{\bullet}) = 0 \text{ for all } i < 0 \}$$
$$D(\mathcal{A})_{\leq 0} = \{ A^{\bullet} \in D(\mathcal{A}) \mid H^{i}(A^{\bullet}) = 0 \text{ for all } i > 0 \}$$

Given a t-structure on  $\mathcal{T}$ , we can pick out an Abelian category that generates it.

### Definition

The *heart* of a triangulated category  $\mathcal{T}$  equipped with a t-structure is the intersection

$$\mathcal{T}^{\heartsuit} := \mathcal{T}_{\geq 0} \cap \mathcal{T}_{\leq 0}$$

### **Theorem**

For  $\mathcal T$  as above, the heart  $\mathcal T^\heartsuit$  is an Abelian category with  $D(\mathcal T^\heartsuit)=\mathcal T$ 

The second type of stability we can demand is on the heart of  ${\mathcal T}$ 

### **Definition**

A stability function on an Abelian category  $\ensuremath{\mathcal{A}}$  is the data of a group homomorphism

$$Z:K(\mathcal{A})\to\mathbb{C}$$

such that for all nonzero objects  $E \neq 0$  in A, we have

$$Z(E) \in \mathbb{H}$$

the upper-half plane of  $\mathbb{C}$ .

This allows us to define the *phase* of an object  $E \in \mathcal{A}$  as

$$\phi(E)=rac{1}{\pi}\operatorname{arg}(Z(E))\in(0,1]$$

One of the main theorems of Bridgeland's original paper is this:

#### **Theorem**

The data of a Bridgeland stability condition on  $\mathcal{T}$  is equivalent to the data of a t-structure on  $\mathcal{T}$  and a stability function on  $\mathcal{T}^{\heartsuit}$  for which every element of  $\mathcal{T}^{\heartsuit}$  admits a Harder-Narasimhan filtration in  $\mathcal{T}^{\heartsuit}$ .

A stability condition can be understood as "picking out a heart" for  $\mathcal{T}$  which allows objects in  $\mathcal{T}^\heartsuit$  to be decomposed into extensions of stable objects with respect to the central charge.

## The Big Result

The set of all stability conditions (satisfying a certain finiteness condition) is denoted  $Stab(\mathcal{T})$ , and forms a complex manifold.

#### **Theorem**

The space  $\mathsf{Stab}(\mathcal{T})$  admits a natural metric turning it into a topological space

### **Theorem**

For each connected component  $\Sigma \subset \operatorname{Stab}(\mathcal{T})$ , there is a linear subspace  $V(\Sigma) \subset \operatorname{Hom}_{\mathbb{Z}}(K(\mathcal{T}),\mathbb{C})$  with a natural norm along with a local homeomorphism  $\mathcal{Z}: \Sigma \to V(\Sigma)$  mapping a stability condition to its central charge.

# Symmetries of the Stability Manifold

The manifold Stab(T) admits two natural group actions:

- The group  $GL_2^+(\mathbb{R})$  the universal cover of  $GL_2^+(\mathbb{R})$  acts on  $\operatorname{Stab}(\mathcal{T})$  on the right
- ullet The group  $\operatorname{Aut}(\mathcal{T})$  of exact autoequivalences of  $\mathcal{T}$  acts on the left by isometries

Furthermore, these actions commute.

#### Explicit Worked Examples

Bridgeland stability has been studied extensively recently, and certain complex manifolds have been shown to admit Bridgeland stability conditions explicitly (this is definitely not a complete list):

- The elliptic curve
- K3 surfaces
- General smooth projective surfaces
- ullet The total space of  $\mathcal{O}_{\mathbb{P}^2}(-3)$

- Fano threefolds
- Abelian threefolds
- Kummer threefolds
- The quintic threefold

# Explicit Worked Examples

Π-stability has also been studied in the following cases (again, non-exhaustive):

- The quintic threefold
- The flop transition
- the  $\mathbb{C}^3/\mathbb{Z}^3$  orbifold
- Certain quiver gauge theories (McKay correspondence)
- Vanishing del Pezzo surfaces (more general rational surfaces in a  $CY_3$  as well)
- Landau-Ginzburg models
- the elliptic curve (via matrix factorizations)

#### An Incongruity

Analysis in the special case where  $\mathcal{T}=D^b(\mathsf{Coh}(X))$  for X a simply-connected Calabi-Yau threefold shows that the tangent space to the moduli space of complexified Kähler forms on X (which we expect to parameterize stability conditions) is  $H^{(1,1)}(X)$ 

However, the tangent space to Stab(X) at a point is

$$T_{\mathsf{Stab}(X)} = \bigoplus_{p} H^{(p,p)}(X)$$

Hence, extra data is needed to find the Kähler form moduli space inside Stab(X).

# Homological Mirror Symmetry

A conjecture of Konstevich suggests that mirror symmetry extends to an equivalence of triangulated categories between the A-model category of branes, and the B-model category of branes on the other side.

The A-model category is the *Fukaya category*, which carries an  $A_{\infty}$  structure, and the conjecture implies that a nontrivial  $A_{\infty}$  structure on  $D^b(\operatorname{Coh}(X))$  may play a role in the story. It has been shown that the  $A_{\infty}$  deformations of  $D^b(\operatorname{Coh}(X))$  for X a complex projective variety has a tangent space identified with

$$\bigoplus_{p,q} H^p\left(X,\bigwedge^q T_X\right)$$

One might expect for mirror pairs (X, Y) the  $A_{\infty}$  deformations of  $D^b(Coh(X))$  correspond to deformations of stability conditions on  $D^b(Coh(Y))$ .

#### Higher Categories

Recently, the theory of  $\infty$ -categories has been formalized, which is a more natural setting for derived categories to be in.

Many of the constructions performed in building the category T(X) have natural  $\infty$ -category analogues, and in particular  $A_{\infty}$  categories are naturally phrased in these terms.

Moreover, every derived category arises as the flattening of a stable  $\infty$ -category which arises canonically from the dg-category of chain complexes.

#### Potential Directions

A possible short-term goal would be to recast this talk in the language of  $\infty$ -categories, and examine  $A_{\infty}$  deformations.

I would also like to examine known stability manifolds and compare them to complexified Kähler moduli spaces

Finally, I would like to further explore the "wall-crossing" phenomenon of the flop transition. One expects the hearts of  $\mathscr T$  to tile the moduli space/stability manifold, and such phenomena are seen in e.g. the gauged linear sigma model

Thank you for your time!

#### Notation

Throughout this part of the talk, I'll use the following notation (subscripts omitted when context makes it clear):

Symbol	Meaning
$\Omega^k_{X,\mathbb{R}}$	Sheaf of real k-forms on X
$\Omega^{k}_{X,\mathbb{C}}$	$\Omega_{X,\mathbb{R}}\otimes\mathbb{C}$ the sheaf of complex $k$ -forms on $X$
$\Omega_X^{(p,q)}$	The $(p,q)$ part of the Hodge decomposition of $\Omega^k_{X,\mathbb{C}}$
$T_X$	The complexified tangent bundle of $X$
$T_X^{(1,0)}, T_X^{(0,1)}$	The (anti)holomorphic tangent bundle of $X$
$\Omega_X^{(-p,q)}$	$igwedge^p \mathcal{T}_X^{(1,0)} \otimes \Omega_X^{(0,q)}$ as sheaves
$K_X$	The canonical bundle on X

Appendix A

The Nonlinear Sigma Model

87 / 108

When we refer to a field theory, we mean the following data:

- A manifold M (the *spacetime*) on which the fields lie (usually taken to be  $\mathbb{R}^{3,1}$  for Minkowski space, or  $\mathbb{R}^1$  for a classical particle)
- A collection of *fields*, which are specified by choosing vector bundles over M with connection. A field is either a section of (a power of) the tangent bundle, or a connection on a principal bundle, or a section of an associated bundle.
- An action functional, which takes in a configuration of fields and spits out a number.

88 / 108

In classical mechanics, the goal is to find the configuration of fields that extremizes the action.

#### Example

Take  $M = \mathbb{R}^{3,1}$  with a single scalar field  $\varphi$ , and action of the form

$$S\left[\varphi\right] = \int_{M} \left(\frac{1}{2} \partial_{\mu} \varphi \partial^{\mu} \varphi - \frac{1}{2} m^{2} \varphi\right) dx^{4}$$

This is extremized at  $(\partial^2 - m^2) \varphi = 0$ , which is the equation for a relativistic free particle of mass m.

In quantum mechanics, the story changes a bit, and the fields get a new interpretation as elements of some  $C^*$  algebra acting on the *Hilbert space* of states

This algebra gets extra structure in the form of the *n*-point functions

$$\langle 0|\varphi(x_n),\ldots,\varphi(x_1)|0\rangle=N\int [D\varphi]\,\varphi(x_n)\ldots\varphi(x_1)\exp(iS[\varphi])$$

where the integral is the *path integral* over the configuration space for  $\varphi$ . There's some non-commutative subtlety going on here that we'll skip over.

So, a specification of the spacetime M, the fields  $\varphi$ , and the action S completely determines the physical theory (the  $C^*$  algebra of fields and the n-point functions)

Note that this association is typically not injective, as many different actions could lead to the same physical theory. Adding in a field whose equations of motion are constantly zero is a trivial example.

# The Physical Nonlinear Sigma Model

The nonlinear  $\Sigma$  model is the starting point. The data of a nonlinear  $\Sigma$  model is:

- The worldsheet  $\Sigma$ , a Riemann surface functioning as spacetime (possibly with boundary)
- The target space X, a Calabi-Yau manifold (usually of  $\mathbb{C}$ -dimension 3) which is smooth over  $\mathbb{C}$ .
- A Complexified Kähler form B + iJ on X, which is the data of a Kähler form J and a closed, real-valued two form B.
- A choice of a square root of the canonical bundle K on  $\Sigma$ , denoted  $\sqrt{K}$ .
- a smooth map  $f: \Sigma \to X$

Actually, when computing, we really want to integrate over all  $\Sigma$ , all B+iJ, and all f due to quantization

# The Physical Nonlinear Sigma Model

This data assembles to a physical theory by specifying the following fermionic fields:

Field	Bundle
$\psi_+^i$	$\sqrt{K} \otimes f^*(T_X^{(1,0)})$
$\psi_+^{\bar{i}}$	$\sqrt{K} \otimes f^*(T_X^{(0,1)})$
$\psi^i$	$\int \overline{\sqrt{K}} \otimes f^*(T_X^{(1,0)}) \mid$
$\psi_{-}^{\bar{i}}$	$\overline{\sqrt{K}} \otimes f^*(T_X^{(0,1)})$

including as well the bosonic fields  $x^i, x^{\bar{i}}$  given by the coordinates of f and the pullback of the complexified Kähler form on X.

# The Physical Nonlinear Sigma Model

The action is the last bit of information, and it is given by

$$S[\Sigma, f, \psi] = \int_{\Sigma} \left( \frac{1}{2} (g_{IJ} + iB_{IJ}) \partial_{z} x^{I} \partial_{z} x^{J} + \frac{\sqrt{-1}}{2} g_{i\bar{i}} \psi_{-}^{\bar{i}} D_{z} \psi_{-}^{i} + \frac{\sqrt{-1}}{2} g_{i\bar{i}} \psi_{+}^{\bar{i}} D_{z} \psi_{+}^{i} + (R_{i\bar{i}j\bar{j}} \psi_{+}^{i} \psi_{+}^{\bar{i}} \psi_{-}^{j} \psi_{-}^{\bar{j}}) \right) d^{2}z$$

where I,J run across all coordinates, i,j runs across holomorphic coordinates, and  $\bar{i},\bar{j}$  runs across antiholomorphic coordinates

# Topologically Twisting the Sigma Model

The *B-model topologically twisted theory* tensors the fermionic fields with  $\sqrt{K}$ , its conjugate, and their duals.

The new fields take values in

Field	Bundle
$\psi_+^i$	$K\otimes f^*(T_X^{(1,0)})$
$\psi_+^{\bar{i}}$	$f^*(T_X^{(0,1)})$
$\psi^i$	$\overline{K} \otimes f^*(T_X^{(1,0)})$
$\psi^{ar{i}}$	$f^*(T_X^{(0,1)})$

From this, we get the summed fields that enter explicitly into the action:

$$\begin{split} \eta^{\bar{i}} &= \psi_{+}^{\bar{i}} + \psi_{-}^{\bar{i}} \in f^{*}T_{X}^{(0,1)} \\ \rho^{i} &= \psi_{+}^{i} + \psi_{-}^{i} \in \Gamma(\Omega_{\Sigma,\mathbb{C}}^{1} \otimes f^{*}(T_{X}^{(1,0)})) \\ \theta_{i} &= g_{\bar{i}i} \left( \psi_{+}^{\bar{i}} - \psi_{-}^{\bar{i}} \right) \in f^{*}\Omega_{X}^{(0,1)} \end{split}$$

#### The Modified Action

The new action with this twisting is given by

$$S[\Sigma, f, \eta, \rho, \theta] = \int_{\Sigma} \left( g_{IJ} \partial x^{I} \bar{\partial} x^{J} + i \eta^{\bar{i}} \left( D_{z} \rho_{\bar{z}}^{i} + D_{\bar{z}} \rho_{z}^{i} \right) + i \theta_{i} \left( D_{\bar{z}} \rho_{z}^{i} - D_{z} \rho_{\bar{z}}^{i} \right) + R_{i\bar{i}j\bar{j}} \rho_{z}^{i} \rho_{\bar{z}}^{j} \eta^{\bar{i}} \theta_{k} g^{k\bar{j}} \right) d^{2}z$$

# The Supersymmetry Generator

This action in this form is invariant under an infinitesimal *supersymmetry* generated by

$$\begin{split} \delta x^i &= 0 \\ \delta x^{\bar{i}} &= i\alpha\eta^{\bar{i}} \\ \delta \psi_+^i &= -\alpha\partial x^i \\ \delta \psi_+^{\bar{i}} &= -i\alpha\psi_-^{\bar{j}}\Gamma_{\bar{j}\bar{k}}^{\bar{i}}\psi_+^{\bar{k}} \\ \delta \psi_-^i &= -\alpha\bar{\partial}x^i \\ \delta \psi_-^{\bar{i}} &= -i\alpha\psi_+^{\bar{j}}\Gamma_{\bar{j}\bar{k}}^{\bar{i}}\psi_-^{\bar{k}} \end{split}$$

where  $\alpha$  is an infinitesimal section of  $\sqrt{K}^*$ .

# The Supersymmetry Generator

The *supersymmetry operator Q* is defined by

$$\{Q(\alpha), W\} = \delta W$$

for any field W.

The action now becomes

$$S[\Sigma, f, \eta, \rho, \theta] = i \int_{\Sigma} \{Q, \mathcal{D}\} + U$$

$$\mathcal{D} = g_{j\bar{k}} \left( \rho_z^j \bar{\partial} x^{\bar{k}} \right)$$

$$U = \int_{\Sigma} \left( -\theta_j D \rho^j - \frac{i}{2} R_{j\bar{j}k\bar{k}} \rho^j \rho^k \eta^{\bar{j}} \theta^{\bar{k}} \right)$$

This action is invariant under deformation of the Kähler form, up to a Q-exact term.

# Operators in Q-Cohomology

Local operators can be built up from our fields via products. Starting with

$$A = d\bar{z}^{\bar{j}_1} \dots d\bar{z}^{\bar{j}_q} A^{\bar{i}_1 \dots \bar{i}_p}_{\bar{j}_1 \dots \bar{j}_q} \partial_{\bar{i}_1} \dots \partial_{\bar{i}_p}$$

a (0,q)-form with values in  $\bigwedge^p T_X^{(1,0)}$ 

We have:

$$W[A] = \eta^{\bar{j}_1} \dots \eta^{\bar{j}_q} A^{\bar{i}_1 \dots \bar{i}_p}_{\bar{j}_1 \dots \bar{j}_q} \theta_{\bar{i}_1 \dots \bar{i}_p}$$

an operator.

If we assemble all these W maps together, we get a big map

$$\bigoplus W: \bigoplus_{p,q} \Gamma(\Omega_X^{(-p,q)}) \to (\mathsf{local\ operators\ in\ the\ CFT})$$

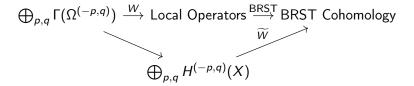
# Q-Cohomology on Operators

The effect of Q on W[A] is

$${Q, W[A]} = W[\bar{\partial}A]$$

Passing to Q-cohomology (BRST quantization) amounts to considering operators that are Q-closed modulo those that are Q-exact.

This allows us to factor W as



Upshot:  $\widetilde{W}$  is an isomorphism!

#### A New Action Term

New data we can add: a vector bundle E on X with connection 1-form A and field strength (curvature) F.

For each connected boundary  $C_k$  of  $\Sigma$  we can add a new term to the action:

$$S_{C_k} = \oint_{C_k} \left( f^*(A) - \sqrt{-1} \eta^{\bar{i}} F_{\bar{i}j} \rho^j \right)$$

For this to remain supersymmetric (Q-invariant) we need A to be holomorphic, so that F is purely of type (1,1)

$$F \in \Gamma(\Omega_X^{(1,1)} \otimes \operatorname{End}(E))$$

Hence, E must be a holomorphic vector bundle with connection.

#### **New Operators**

The new operators are now (-p, q)-forms on X with values in  $\operatorname{End}(E)$ . Furthermore, we have the relation

$$\theta_j = g_{j\bar{k}} \left( \psi_+^{\bar{k}} - \psi_-^{\bar{k}} \right) = F_{j\bar{k}} \eta^{\bar{k}}$$

and hence we can move all terms in the local operator to  $\boldsymbol{\eta}$  terms, so the operators are of the form

BRST local operators = 
$$\bigoplus_{q} H^{(0,q)}(X, \operatorname{End}(E))$$

The number q associated to an operator is called the *ghost number* of the operator

#### Summary

Our theory now has the following data:

- A target space X, assumed to be Calabi-Yau, with a complexified Kähler form B+iJ
- A Riemann surface  $\Sigma$  with boundary components  $\partial \Sigma = \sum_k C_k$
- A holomorphic vector bundle E with connection
- A ring of local BRST operators  $H^{(0,q)}(X, \text{End}(E))$

This is the data of a topological sigma model with a Dn-brane for n the (real) dimension of X

More generally, Dp-branes are vector bundles supported on complex submanifolds of (real) dimension  $\boldsymbol{p}$  along with the reasonable generalization of the above picture

Appendix B

Computation of BRST Quantization of Complexes

#### Computing the New BRST Operators

Let  $(\mathscr{E}^{\bullet}, d^{E})$  and  $(\mathscr{F}^{\bullet}, d^{F})$  be objects in  $\mathsf{Ch}^{b}(\mathsf{Coh}(X))$  i.e. bounded complexes of coherent sheaves.

The sheaf Hom gives us a double complex

#### Computing the new BRST Operators

We form the total complex by summing across antidiagonals

$$\ldots \stackrel{d_{-1}}{\to} \mathscr{H}\!\mathit{em}^{\,0}(\mathscr{E}^{\bullet},\mathscr{F}^{\bullet}) \stackrel{d_0}{\to} \mathscr{H}\!\mathit{em}^{\,1}(\mathscr{E}^{\bullet},\mathscr{F}^{\bullet}) \stackrel{d_1}{\to} \ldots$$

where

$$\mathcal{H}\mathit{om}^{\,p}(\mathcal{E}^{\,\bullet},\mathcal{F}^{\,\bullet}) = \bigoplus_{n} \mathcal{H}\mathit{om}(\mathcal{E}^{\,n},\mathcal{F}^{\,n+p})$$

is the grade-p part of the sheaf internal hom for Ch(Coh(X)) and

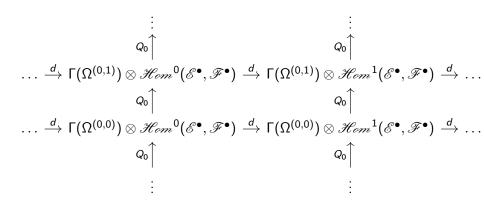
$$d_n = d_n^E + d_n^F$$

with  $d^E$  and  $d^F$  anticommuting.

#### Computing the Cohomology

This is the sequence on which d operates, and we need to tensor this with the sequence on which  $Q_0$  operates and take the resulting cohomology.

The relevant double complex is:



# Computing the Cohomology

This double complex is handled explicitly by a spectral sequence described by

$$E_2^{p,q} = H^p(X, H^q(\mathcal{H}_{om}^{\bullet}(\mathcal{E}^{\bullet}, \mathcal{F}^{\bullet}))) \implies H_Q^{p+q}$$

which yields our desired Q-cohomology.

This spectral sequence abuts to the hyperext of the complexes

$$H^n_Q(\mathscr{E}^{ullet},\mathscr{F}^{ullet})=\operatorname{Ext}^n(\mathscr{E}^{ullet},\mathscr{F}^{ullet})$$

In particular,  $\operatorname{Ext}^0(\mathscr{E}^\bullet,\mathscr{F}^\bullet)$  are homotopy classes of maps between  $\mathscr{E}^\bullet$  and  $\mathscr{F}^\bullet$  of degree zero.