Pseudocodes LATEX

Daniel Hernandez, Samuel Villegas, Jose Blanco, Neller Pellegrino June 2, 2022

Algorithm 1 Aitken

```
1: READ f,g,x0,tolerance,nMax
 2: x1 \leftarrow g(x0)
 3: x2 \leftarrow g(x1)
 4: x3 \leftarrow g(x2)
 5: xi \leftarrow x1 - ((x2 - x1)^2)/(x3 - 2 * x2 + x1)
 6: fxi \leftarrow f(xi)
 7: error \leftarrow tolerance + 1
 8: counter \leftarrow 0
9: while fxi \neq 0 AND error > tolerance AND counter < nMax do
        x3Aux \leftarrow x3
10:
        x2Aux \leftarrow x2
11:
12:
        x3 \leftarrow g(x3)
        x2 \leftarrow x3Aux
13:
        x1 \leftarrow x2Aux
14:
        xiAux \leftarrow xi
15:
        xi \leftarrow x1 - ((x2 - x1)^2)/(x3 - 2 * x2 + x1)
16:
17:
        fxi \leftarrow f(xi)
18:
        error \leftarrow |xi - xiAux|
        counter \leftarrow counter + 1
19:
20: end while
21: if fxi = 0 then
        A root has been found and it is xi
22:
23: else if error \leq tolerance then
        one approach has been found and it is xi
24:
25: else
        The method fails with the maximum number of iterations given
26:
27: end if
```

Algorithm 2 Bisection

```
1: READ f, left, right, tolerance, niter
 2: fRight \leftarrow f(right)
 3: fLeft \leftarrow f(left)
 4: if fRight = 0 then
        right is a root
 6: else if fLeft = 0 then
        left is a root
 8: else if fLeft * fRight < 0 then
9:
        xmid \leftarrow (left * right)/2
        fXmid \leftarrow f(xmid)
10:
        counter \leftarrow 1
11:
        error \leftarrow tolerance + 1
12:
        while error > tolerance \text{ AND } fXmid \neq 0 \text{ AND } counter < niter
13:
    do
14:
            if fLeft * fXmid < 0 then
15:
                right \leftarrow xmid
                fRight \leftarrow fXmid
16:
            else
17:
18:
                left \leftarrow xmid
                fLeft \leftarrow fXmid
19:
20:
            end if
            xAux \leftarrow xmid
21:
            xmid \leftarrow (right + left)/2
22:
            fXmid \leftarrow f(xmid)
23:
            error \leftarrow |xmid - xAux|
24:
            counter \leftarrow counter + 1
25:
        end while
26:
        if fXmid = 0 then
27:
            xmid is a root
28:
        else if error < tolerance then
29:
            xmid is an approximation with tolerance
30:
31:
            The method fails in niter iterations
32:
        end if
33:
34: else
35:
        Bad range
36: end if
```

Algorithm 3 Crout

```
1: READ A, B
2: n \leftarrow \text{length of A}
3: lower \leftarrow matrix nxn initialized in ceros
4: upper \leftarrow identity matrix nxn
5: for j = 0...n do
6:
        for i = j...n do
7:
            sum \leftarrow 0
            for k = 0...j do
8:
                sum \leftarrow sum + lower[i][k] * upper[k][j]
9:
10:
            end for
            lower[i][j] \leftarrow A[i][j] - sum
11:
        end for
12:
        for i = j + 1...n do
13:
            sum \leftarrow 0
14:
            for k = 0...j do
15:
                sum \leftarrow sum + lower[j][k] * upper[k][i]
16:
            end for
17:
            upper[j][i] \leftarrow (A[j][j] - sum) / lower[j][j]
18:
        end for
19:
20: end for
21: Z \leftarrow regressiveSubstitution(lower|B)
22: X \leftarrow progressiveSubstitution(upper|Z)
```

Algorithm 4 Doolittle

```
1: n \leftarrow \text{length of A}
2: lower \leftarrow matrix nxn initialized in ceros
3: upper \leftarrow identity matrix nxn
4: for i = 0...n do
        for k = i...n do
5:
6:
             sum \leftarrow 0
             for j = 0...i do
7:
                 sum \leftarrow lower[i][j] * upper[j][k]
8:
9:
             end for
             upper[i][k] \leftarrow A[i][k] - sum
10:
        end for
11:
        for k = i...n do
12:
             if i = k then
13:
14:
                 lower[i][i] \leftarrow 1
             else
15:
                 sum \leftarrow 0
16:
                 \mathbf{for}\ j=0...i\ \mathbf{do}
17:
18:
                     sum \leftarrow sum + lower[k][j] * upper[j][i]
19:
                 lower[k][i] \leftarrow (A[k][i] - sum) / upper[i][i]
20:
             end if
21:
22:
        end for
23: end for
24: Z \leftarrow regressiveSubstitution(lower|B)
25: X \leftarrow progressiveSubstitution(upper|Z)
```

Algorithm 5 Incremental Search

```
1: READ f, x0, delta, niter
2: fx0 \leftarrow f(x0)
3: if fx0 = 0 then
        x0 is a root
5: else
6:
        x1 \leftarrow x0 + delta
7:
        counter \leftarrow 1
        fx1 \leftarrow f(x1)
        while fx0 * fx1 > 0 AND counter > niter do
9:
            x0 \leftarrow x1
10:
11:
            fx0 \leftarrow fx1
            x1 \leftarrow x0 + delta
12:
13:
            fx1 \leftarrow f(x1)
14:
            counter \leftarrow counter + 1
        end while
15:
        if fx1 = 0 then
16:
            x1 is a root
17:
        else if fx0 * fx1 < 0 then
18:
19:
            there is a root between x0 and x1
        else
20:
            the method fails in niter iterations
21:
        end if
22:
23: end if
```

```
Algorithm 6 Muller
```

```
1: READ f, x0, tolerance, nMax
 2: fx0 \leftarrow f(x0)
 3: fx1 \leftarrow f(x1)
 4: x1 \leftarrow (x0 + x1)/2
 5: fx2 \leftarrow f(x2)
 6: h0 \leftarrow x1 - x0
 7: h1 \leftarrow x2 - x1
 8: delta0 \leftarrow (fx1 - fx0)/h0
9: delta1 \leftarrow (fx2 - fx1)/h1
10: a \leftarrow (delta1 - delta0)/(h1 - h0)
11: b \leftarrow a * h1 + delta1
12: c \leftarrow fx2
13: xi \leftarrow x^2 + (-2*c)/(b + (b/|b|)*\sqrt{b^2 - 4*a*c})
14: fxi \leftarrow f(xi)
15: error \leftarrow tolerance + 1
16: counter \leftarrow 0
17: while fx1 \neq 0 AND error > tolerance AND counter < nMax do
18:
        x2Aux \leftarrow x2
        x1Aux \leftarrow x1
19:
        x2 \leftarrow xi
20:
        x1 \leftarrow x2Aux
21:
        x0 \leftarrow x1Aux
22:
23:
        fx0 \leftarrow f(x0)
        fx1 \leftarrow f(x1)
24:
        fx2 \leftarrow f(x2)
25:
        h0 \leftarrow x1 - x0
26:
        h1 \leftarrow x2 - x1
27:
        delta0 \leftarrow (fx1 - fx0)/h0
28:
        delta1 \leftarrow (fx2 - fx1)/h1
29:
        a \leftarrow (delta1 - delta0)/(h1 - h0)
30:
        b \leftarrow a*h1 + delta1
31:
        c \leftarrow fx2
32:
        xi \leftarrow x2 + (-2*c)/(b + (b/|b|)*\sqrt{b^2 - 4*a*c})
33:
        fxi \leftarrow f(xi)
34:
        error \leftarrow tolerance + 1
35:
        counter \leftarrow counter + 1
36:
37: end while
38: if fxi = 0 then
         A root has been found and it is xi
39:
    else if error \leq tolerance then
         One approach has been found and it is xi
41:
42: else
        The method fails with the maximum number of iterations given
43:
44: end if
```

Algorithm 7 Multiple root

```
1: READ f, f1, f2, x0, tolerance, nMax
2: xi \leftarrow x0
3: fxi \leftarrow f(xi)
 4: if fx = 0 then
        A root has been found and it is xi
 6: else
        counter \leftarrow 0
7:
        f1xi \leftarrow f1(xi)
8:
        f2xi \leftarrow f2(xi)
9:
        error \leftarrow tolerance + 1
10:
        det \leftarrow (f1xi^2) - (fxi * f2xi)
11:
        while fxi \neq 0 AND error > tolerance AND counter < nMAx do
12:
            xiAux \leftarrow xi
13:
            xi \leftarrow xi - ((fxi * f1xi)/((f1xi^2) - (fxi * f2xi)))
14:
            fxi \leftarrow f(xi)
15:
            f1xi \leftarrow f1(xi)
16:
            f2xi \leftarrow f2(xi)
17:
            error \leftarrow |xi - xiAux|
18:
            det \leftarrow (f1xi^2) - (fxi * f2xi)
19:
            counter \leftarrow counter + 1
20:
        end while
21:
        if fxi = 0 then
22:
            A root has been found and it is xi
23:
        else if error \leq tolerance then
24:
            One approach has been found and it is xi
25:
        else
26:
            The method fails with the maximum number of iterations given
27:
28:
        end if
29: end if
```

```
Algorithm 8 Newton
```

```
1: READ f, fder, tolerance, x0, niter
 2: fx \leftarrow f(x0)
 3: dfx \leftarrow fder(x0)
 4: counter \leftarrow 1
5: error \leftarrow tolerance + 1
 6: while error > tolerance \text{ AND } fx \neq 0 \text{ AND } counter < niter do
        x1 \leftarrow x0 - (fx/dfx)
        fx \leftarrow f(x1)
        dfx \leftarrow fder(x1)
        error \leftarrow |x1 - x0|
10:
        x0 \leftarrow x1
11:
12:
        counter \leftarrow counter + 1
13: end while
14: if fx = 0 then x0 is a root
15: else if error < tolerance then
        x1 is a root approximation with tolerance tolerance
17: elseth method fails in niter iterations
18: end if
```

Algorithm 9 Vandermonde

```
1: READ x, y

2: n \leftarrow findVectorLength(x)

3: A \leftarrow generateMatrixofOnes(n)

4: for i = 1...n do

5: for j = 1...n - 1 do

6: A_{ij} \leftarrow x_i^{n-j}

7: end for

8: end for

9: xSolution \leftarrow solveLinearEquation(A, y)

10: xSolution is the coefficient vector
```

Algorithm 10 gaussian Elimination

```
1: READ A, b
2: m \leftarrow concatenateMatrices(A, b)
3: for i = 1...n - 1 do
       if m_{ii} == 0 then
           Error when executing the method: division by 0
5:
6:
           return
       end if
7:
       for j = 1 + 1...n do
8:
           m_i \leftarrow m_i - (m_i * (m_{ii}/m_{ii}))
9:
       end for
10:
11: end for
12: x \leftarrow backwardSubstitution(m)
```

Algorithm 11 partialPivoting

```
1: READ A, b
2: m \leftarrow concatenateMatrices(A, b)
3: for i = 1...n - 1 do
       ChangeRows(m, i)
       if m_{ii} == 0 then
6:
           Error when executing the method: division by 0
           return
7:
       end if
8:
9:
       for j = 1 + 1...n do
           m_j \leftarrow m_j - (m_i * (m_{ji}/m_{ii}))
10:
       end for
11:
12: end for
13: x \leftarrow backwardSubstitution(m)
```

Algorithm 12 totalPivoting

```
1: READ A, b
2: m \leftarrow concatenateMatrices(A, b)
3: for i = 1...n - 1 do
       ChangeRowsAndColumns(m, i)
       if m_{ii} = 0 then
5:
           Error when executing the method: division by 0
6:
           return
7:
8:
       end if
       for j = 1 + 1...n do
9:
           m_j \leftarrow m_j - (m_i * (m_{ji}/m_{ii}))
10:
       end for
11:
12: end for
13: x \leftarrow backwardSubstitution(m)
```

Algorithm 13 simpleLu

```
1: READ A, b

2: [U, L] \leftarrow foundMatrixUandL(A)

3: z \leftarrow progressiveSubstitution(L, b)

4: x \leftarrow backwardSubstitution(U, z)

5: x is the vector solution
```

Algorithm 14 PivotLu

```
1: READ A, b

2: [U, L, P] \leftarrow foundMatrixUandLandPWithPartialPivoting(A)

3: Bn \leftarrow P * b

4: z \leftarrow progressiveSubstitution(L, Bn)

5: x \leftarrow backwardSubstitution(U, z)

6: x is the vector solution
```

Algorithm 15 Compound Trapeze

```
1: READ a, b, f, n
 2: deltaX \leftarrow (b-a)/n
3: A \leftarrow 0
4: for i = 0...n do
        xi \leftarrow a + i * deltaX
        fxi \leftarrow f(xi)
6:
 7:
        if i > 0 AND i < n then
            fxi \leftarrow 2 * fxi
9:
        end if
        A \leftarrow A + fxi
10:
11: end for
12: A \leftarrow A * (deltaX/2)
13: A is the result of the integral
```

Algorithm 16 Simpson 1/3

```
1: READ a, b, f, n
2: deltaX \leftarrow (b-a)/n
3: A \leftarrow 0
4: for i = 0...n do
        xi \leftarrow a + i * deltaX
        fxi \leftarrow f(xi)
6:
        if i > 0 AND i < n then
 7:
            if i \mod 2 == 0 then
8:
                fxi \leftarrow 2 * fxi
9:
10:
            else
                 fxi \leftarrow 4 * fxi
11:
            end if
12:
13:
        end if
        A \leftarrow A + fxi
14:
15: end for
16: A \leftarrow A * (deltaX/3)
17: A is the result of the integral
```

Algorithm 17 Simpson 3/8

```
1: READ a, b, f, n
2: deltaX \leftarrow (b-a)/n
3: A \leftarrow 0
4: for i = 0...n do
        xi \leftarrow a + i * deltaX
6:
        fxi \leftarrow f(xi)
        if i > 0 AND i < n then
7:
            if i \mod 3 == 0 then
                 fxi \leftarrow 2 * fxi
9:
            else
10:
                 fxi \leftarrow 3 * fxi
11:
            end if
12:
        end if
13:
        A \leftarrow A + fxi
14:
15: end for
16: A \leftarrow A * (3 * deltaX/8)
17: A is the result of the integral
```

Algorithm 18 Steffensen

```
1: READ f, x0, tolerance, nMax
2: for i = 1...nMax do
       x1 \leftarrow f(x0)
       x2 \leftarrow f(x1)
4:
       denominator \leftarrow (x2 - x1) - (x1 - x0)
5:
       if absoluteValue(denominator) < 10e - 16 then
6:
7:
           Error during method execution: division by 0
           return
8:
       end if
9:
       xi \leftarrow x2 - ((x2 - x1)^2)/denominator
10:
       if absoluteValue(xi - x2) < tolerance then
11:
           xi is an approximation
12:
13:
           return
14:
       end if
       x0 \leftarrow xi
16: end for
17: xi is an approximation
```

Algorithm 19 Jacobi

```
1: READ A, b, x, iter, tol
 2: if foundDeterminant(A) then
       The determinant is zero, the problem has no unique solution.
 4:
       return
 5: end if
6: d \leftarrow findDiagOfMatrix(A)
 7: p \leftarrow findUpperTriangular(A)
 8: o \leftarrow findLowerTriangular(A)
9: l \leftarrow d - o
10: u \leftarrow d - p
11: T \leftarrow findInverseOfMatrix(d) * (l + u)
12: re \leftarrow foundSpectralRadius(T)
13: if re > 1 then
14:
       Spectral radius greater than 1: the method does not converge.
       return
15:
16: end if
17: C \leftarrow findInverseOfMatrix(d) * b
18: i \leftarrow 0
19: err \leftarrow tol + 1
20: while err > toli < iter do
       xi \leftarrow T * x + C
22:
       err \leftarrow findNormOfVector(xi - x)
       x \leftarrow xi
23:
       i \leftarrow i + 1
24:
25: end while
26: if i >= iter then
       The method fails with the maximum number of iterations given
27:
28:
       return
29: end if
30: x is an approximation with tolerance
```

Algorithm 20 Gauss - Seidel

```
1: READ A, b, x, iter, tol
 2: if foundDeterminant(A) then
       The determinant is zero, the problem has no unique solution.
 4:
       return
 5: end if
6: d \leftarrow findDiagOfMatrix(A)
 7: p \leftarrow findUpperTriangular(A)
 8: o \leftarrow findLowerTriangular(A)
9: l \leftarrow d - o
10: u \leftarrow d - p
11: T \leftarrow findInverseOfMatrix(d-l) * u
12: re \leftarrow foundSpectralRadius(T)
13: if re > 1 then
14:
       Spectral radius greater than 1: the method does not converge.
       return
15:
16: end if
17: C \leftarrow findInverseOfMatrix(d-l) * b
18: i \leftarrow 0
19: err \leftarrow tol + 1
20: while err > toli < iter do
       xi \leftarrow T * x + C
22:
       err \leftarrow findNormOfVector(xi - x)
       x \leftarrow xi
23:
       i \leftarrow i + 1
24:
25: end while
26: if i >= iter then
       The method fails with the maximum number of iterations given
27:
28:
       return
29: end if
30: x is an approximation with tolerance
```

Algorithm 21 SOR

```
1: READ A, b, x, iter, tol, w
 2: \mathbf{if} \ foundDeterminant(A) \ \mathbf{then}
        The determinant is zero, the problem has no unique solution.
 4:
 5: end if
 6: d \leftarrow findDiagOfMatrix(A)
 7: p \leftarrow findUpperTriangular(A)
 8: o \leftarrow findLowerTriangular(A)
 9: l \leftarrow d - o
10: u \leftarrow d - p
11: T \leftarrow findInverseOfMatriz(D - w * l) * [(1 - w)d + w * u]
12: re \leftarrow foundSpectralRadius(T)
13: if re > 1 then
14:
       Spectral radius greater than 1: the method does not converge.
15:
       return
16: end if
17: C \leftarrow w * findInverseOfMatrix(D - w * l) * b
18: i \leftarrow 0
19: err \leftarrow tol + 1
20: while err > toli < iter do
       xi \leftarrow T * x + C
21:
22:
       err \leftarrow findNormOfVector(xi - x)
23:
        x \leftarrow xi
       i \leftarrow i+1
24:
25: end while
26: if i >= iter then
        The method fails with the maximum number of iterations given
27:
        return
29: end if
30: x is an approximation with tolerance
```

Algorithm 22 Euler

```
1: READ f, xi, yi, xf, h

2: n \leftarrow (xf - xi)/h

3: for i = 0; i < n; i + + do

4: y1 \leftarrow f(xi, yi)

5: hy1 \leftarrow h * y1

6: newarray.push([xi, y1])

7: yi \leftarrow yi + hy1

8: xi \leftarrow xi + h

9: end for

10: return
```

Algorithm 23 Lineal Spline

```
1: READ x, y
2: create a square matrix of 0s x.length
3: create a matrix of 0s x.length by 1
4: m \leftarrow 2 * (n-1)
5: z \leftarrow 0
6: for i = 1; i < x.length; i + + do
        zerosA[i][z] \leftarrow x[i]
        zerosA[i][z+1] \leftarrow 1
       z \leftarrow z + 2
9:
        zerosB[i][z] \leftarrow y[i]
10:
11: end for
12: zerosA[0][0] = x[0]
13: zerosA[0][1] = 1
14: zerosB[0][0] = y[0]
15: for i = 1; i < x.length - 1; i + + do
        zerosA[x.length-1+1][z] \leftarrow x[i]
16:
       zerosA[x.length-1+1][z+2] \leftarrow -x[i]
17:
        zerosA[x.length-1+1][z+1] \leftarrow 1
18:
19:
       zerosA[x.length-1+1][z+3] \leftarrow -1
       z \leftarrow z + 2
20:
        zerosB[x.length-1+1][0] \leftarrow 0
21:
22: end for
23: return
```

Algorithm 24 Cuadratic Spline

```
1: READ x, y
 2: create a square matrix of 0s x.length
 3: create a matrix of 0s x.length by 1
 4: m \leftarrow 3 * (n-1)
 5: z \leftarrow 0
 6: for i = 1; i < x.length; i + + do
        zerosA[i][z] \leftarrow x[i]^2
 7:
        zerosA[i][z+1] \leftarrow x[i]
        zerosA[i][z+2] \leftarrow 1
        z \leftarrow z + 3
10:
        zerosB[i][0] \leftarrow y[i]
11:
12: end for
13: zerosA[0][0] = x[0]^2
14: zerosA[0][1] = x[0]^1
15: zerosA[0][2] = 1
16: zerosB[0][0] = y[0]
17: z \leftarrow 0
18: for i = 1; i < x.length - 1; i + + do
        zerosA[x.length-1+1][z] \leftarrow x[i]^2
19:
20:
        zerosA[x.length-1+1][z+1] \leftarrow x[i]
        zerosA[x.length-1+1][z+2] \leftarrow 1
21:
        zerosA[x.length-1+1][z+3] \leftarrow -(x[i]^2)
22:
        zerosA[x.length-1+1][z+4] \leftarrow -x[i]
23:
        zerosA[x.length-1+1][z+5] \leftarrow -1
24:
        z \leftarrow z + 3
25:
        zerosB[x.length-1+1][0] \leftarrow 0
26:
27: end for
28: z \leftarrow 0
29: for i = 2; i < x.length - 1; i + + do
        zerosA[2*x.length-4+1][z] \leftarrow x[i-1]*2
30:
31:
        zerosA[2*x.length-4+1][z+1] \leftarrow 1
        zerosA[2*x.length-4+1][z+2] \leftarrow 0
32:
        zerosA[2*x.length - 4 + 1][z + 3] \leftarrow -(x[i - 1]*2)
33:
        zerosA[2*x.length-4+1][z+4] \leftarrow -1
34:
        zerosA[2*x.length-4+1][z+5] \leftarrow 0
35:
        z \leftarrow z + 3
36:
37: end for
38: zerosA[m-1][0] = 2
39: zerosB[m-1][0] = 0
40: return
```

Algorithm 25 Cubic Spline

```
1: READ x, y
 2: create a square matrix of 0s x.length
 3: create a matrix of 0s x.length by 1
 4: m \leftarrow 4 * (n-1)
 5: z \leftarrow 0
 6: for i = 1; i < x.length; i + + do
        zerosA[i][z] \leftarrow x[i]^3
 7:
        zerosA[i][z+1] \leftarrow x[i]^2
        zerosA[i][z+2] \leftarrow x[i]
9:
10:
        zerosA[i][z+3] \leftarrow 1
        z \leftarrow z + 4
11:
        zerosB[i][0] \leftarrow y[i]
12:
13: end for
14: zerosA[0][0] = x[0]^3
15: zerosA[0][1] = x[0]^2
16: zerosA[0][2] = x[0]
17: zerosA[0][3] = 1
18: zerosB[0][0] = y[0]
19: z \leftarrow 0
20: for i = 2; i < x.length; i + + do
        zerosA[2*x.length-2+i][z] \leftarrow (x[i-1]^3)
21:
        zerosA[2*x.length - 2 + i][z + 1] \leftarrow x[i - 1]^2
22:
        zerosA[2*x.length - 2 + i][z + 2] \leftarrow x[i - 1]
23:
        zerosA[2*x.length - 2 + i][z + 3] \leftarrow 1
24:
        zerosA[2*x.length - 2 + i][z + 4] \leftarrow -(x[i - 1]^3)
25:
        zerosA[2*x.length - 2 + i][z + 5] \leftarrow -(x[i - 1]^2)
26:
        zerosA[2*x.length-2+i][z+6] \leftarrow -x[i-1]
27:
        zerosA[2*x.length-2+i][z+7] \leftarrow -1
28:
        z \leftarrow z + 4
29:
        zerosB[x.length - 1 + i][0] \leftarrow 0
30:
31: end for
32: z \leftarrow 0
33: for i = 2; i < x.length; i + + do
        zerosA[2*x.length - 4 + i][z] \leftarrow (x[i-1]^2)*3
34:
        zerosA[2*x.length-4+i][z+1] \leftarrow x[i-1]*2
35:
        zerosA[2*x.length-4+i][z+2] \leftarrow 1
36:
        zerosA[2*x.length-4+i][z+3] \leftarrow 0
37:
        zerosA[2*x.length - 4 + i][z + 4] \leftarrow -((x[i - 1]^2)*3)
38:
        zerosA[2*x.length - 4 + i][z + 5] \leftarrow -(x[i - 1]*2)
39:
        zerosA[2*x.length-4+i][z+6] \leftarrow -1
40:
        zerosA[2*x.length-4+i][z+7] \leftarrow 0
41:
        z \leftarrow z + 4
42:
        zerosB[2*x.length - 3 + i][0] \leftarrow 0
43:
44: end for
```

```
45: z \leftarrow 0
46: for i = 2; i < x.length; i + + do
       zerosA[3*x.length - 6 + i][z] \leftarrow x[i-1]*6
       zerosA[3*x.length-6+i][z+1] \leftarrow 2
48:
       zerosA[3*x.length - 6 + i][z + 2] \leftarrow 0
49:
       zerosA[3*x.length - 6 + i][z + 3] \leftarrow 0
50:
       zerosA[3*x.length - 6 + i][z + 4] \leftarrow -(x[i - 1]*6)
51:
52:
       zerosA[3*x.length-6+i][z+5] \leftarrow -2
       zerosA[3*x.length - 6 + i][z + 6] \leftarrow 0
53:
       zerosA[3*x.length - 6 + i][z + 7] \leftarrow 0
54:
55:
       z \leftarrow z + 4
       zerosB[2*x.length - 2 + i][0] \leftarrow 0
56:
57: end for
58: zerosA[m-2][0] = x[0] * 6
59: zerosA[m-2][0] = 2
60: zerosA[m-1][0] = x[x.length-1] * 6
61: zerosA[m-1][0] = 2
62: zerosB[m-1][0] = 0
63: zerosB[m-2][0] = 0
64: return
```

Algorithm 26 Lagrange

```
1: READ x, y
2: yp \leftarrow 0
3: p \leftarrow 0
4: for i = 1; i < x.length; i + + do
        p \leftarrow 1
        for j = 1; i < x.length; j + + do
6:
            if i! = j then
7:
                p \leftarrow p * (xp - x[j])/(x[i] - x[j])
8:
            end if
9:
        end for
10:
        yp \leftarrow yp + p * y[i]
11:
12: end for
13: return
```

Algorithm 27 Divided Diferences

```
1: READ x, y
2: create a square matrix of 0s x.length
3: w \leftarrow 0
4: for i = 1; i < x.length; i + + do
       z \leftarrow i
        while y.length > z do
6:
           aux1 \leftarrow (zerosarray[z][w] - zerosarray[z-1][w]) / (x[z] - x[z-i])
7:
           zerosarray[z][i] = aux1
8:
           z \leftarrow z + 1
9:
10:
       end while
       w \leftarrow z + 1
12: end for
13: return
```

Algorithm 28 Fixed Point

```
1: READ f, g, x0, tol, iter
2: \mathbf{for} \ i = 0; i < tol; i + + \mathbf{do}
3: x1 \leftarrow x0 \text{ evaluated on } g
4: \mathbf{if} \ x1 == x0 \text{ evaluated on } f \text{ OR abs}(x1-x0) < \text{tol } \mathbf{then}
5: Break
6: \mathbf{end} \ \mathbf{if}
7: x0 \leftarrow x0 - x1
8: \mathbf{end} \ \mathbf{for}
9: return
```

Algorithm 29 Secant

```
1: READ f, x0, x1, tol, iter
2: y0 \leftarrow x0 evaluated on f
3: if y0 == 0 then
        return
5: else
        y1 \leftarrow x1 evaluated on f
        counter \leftarrow 0
7:
8:
        error \leftarrow tol + 1
        density \leftarrow y1 - y0
9:
        while error > tol \ y1! = 0 \ counter < iter do
10:
             x2 \leftarrow x1 - ((y1 * (x1 - x0))/density)
11:
             error \leftarrow abs((x2-x1)/x2)
12:
             x0 \leftarrow x1
13:
14:
             y0 \leftarrow y1
15:
             x1 \leftarrow x2
16:
             y1 \leftarrow \mathbf{x}1 evaluated on f
             density \leftarrow y1 - y0
17:
             counter \leftarrow counter + 1
18:
        end while
19:
        if error < tol then
20:
21:
             return root
        end if
22:
```

```
Algorithm 30 Trisection
```

```
1: READ f, left, right, tolerance, niter
 2: fRight \leftarrow f(right)
 3: fLeft \leftarrow f(left)
 4: counter \leftarrow 0
 5: if fRight == 0 then
        right is a root
   else if fLeft == 0 then
        left is a root
   else if fLeft * fRigth < 0 then
10:
        xmid1 \leftarrow left + (right - left)/3
        xmid2 \leftarrow right - (right - left)/3
11:
12:
        fXmid1 \leftarrow f(xmid1)
        fXmid2 \leftarrow f(xmid2)
13:
14:
        counter \leftarrow 1
15:
        error1 \leftarrow tolerance + 1
        error2 \leftarrow tolerance + 1
16:
        while error1 > tolerance AND error2 > tolerance AND
17:
    fXmid1! = 0 AND fXmid2! = 0 AND counter < niter do
18:
            if fLeft * fXmid1 < 0 then
19:
                right \leftarrow xmid1
                fRight \leftarrow fXmid1
20:
            else if fXmid1 * fXmid2 < 0 then
21:
                left \leftarrow xmid1
22:
                fLeft \leftarrow fXmid1
23:
                right \leftarrow xmid2
24:
                fRight \leftarrow fXmid2
25:
            else
26:
27:
                left \leftarrow xmid2
                fLeft \leftarrow fXmid2
28:
            end if
29:
30:
            xAux1 \leftarrow xmid1
            xAux2 \leftarrow xmid2
31:
32:
            xmid1 \leftarrow left + (right - left)/3
            fXmid1 \leftarrow f(xmid1)
33:
            xmid2 \leftarrow right - (right - left)/3
34:
            fXmid2 \leftarrow f(xmid2)
35:
36:
            error1 \leftarrow absoluteValue(xmid1 - xAux1)
            error2 \leftarrow absoluteValue(xmid2 - xAux2)
37:
            counter \leftarrow counter + 1
38:
        end while
39:
```

```
40: if fXmid1 == 0 then
       xmid1 is a root
41:
42: else if fXmid2 == 0 then
       xmid2 is a root
43:
44: else if error1 < tolerance then
       xmid1 is an approximation with tolerance tolerance
45:
46: else if error2 < tolerance then
       xmid2 is an approximation with tolerance tolerance
47:
48: else
       The method fails in niter iterations
49:
50: end if
51:
52: return = 0
```

Algorithm 31 False position

```
1: READ f, xi, xs, tolerance, nMax
2: fxi \leftarrow f(xi)
3: fxs \leftarrow f(xs)
 4: if fxi == 0 then
       xi is a root
 6: else if fxs == 0 then
        xs is a root
   else if fxi < fxs then
       xm \leftarrow (xi) - ((fxi * (xi - xs))/(fxi - fxs))
9:
        fxm \leftarrow f(xm)
10:
       error \leftarrow tolerance + 1
11:
12:
        counter \leftarrow 1
        while fxm! == 0error > tolerance counter <= nMax do
13:
           if fxi * fxm < 0 then
14:
               xs \leftarrow xm
15:
16:
               fxs \leftarrow fxm
17:
           else
               xi \leftarrow xm
18:
               fxi \leftarrow fxm
19:
           end if
20:
            xAux \leftarrow xm
21:
22:
           xm \leftarrow (xi) - ((fxi * (xi - xs))/(fxi - fxs))
            fxm \leftarrow f(xm)
23:
24:
            error \leftarrow (absoluteValue(xm - xAux)/xm)
            counter \leftarrow counter + 1
25:
        end while
26:
       if fxm == 0 then
27:
            xm is a root
28:
        else if error <= tolerance then
29:
30:
           xm is an approximation to a root with a tolerance tolerance
        else
31:
           Failure in nMax iterations
32:
33:
        end if
34: end if
```

```
Algorithm 32 Heun
```

```
1: READ f, x, y, h, n

2: counter \leftarrow 0

3: while counter \leq n do

4: k1 \leftarrow f(x, y)

5: k2 \leftarrow f(x + h, y + (k1 * h))

6: y \leftarrow y + ((k1 * k2) * (h/2))

7: x \leftarrow x + h

8: counter \leftarrow counter + 1

9: end while
```

Algorithm 33 Cholesky

```
1: READ A, B

2: n \leftarrow \text{lenth of A}

3: lower \leftarrow \text{matrix nxn initialized in ceros}

4: \mathbf{for} \ j = 0...n \ \mathbf{do}

5: \mathbf{for} \ i = 0...j - 1 \ \mathbf{do}

6: lower[i][j] \leftarrow (A[i][j] - \sum_{k=0}^{i-1} lower[k][i] * lower[k][j])/lower[i][i]

7: \mathbf{end} \ \mathbf{for}

8: lower[i][j] \leftarrow \sqrt{A[j][j] - \sum_{k=0}^{i-1} lower[k][j]^2}

9: \mathbf{end} \ \mathbf{for}

10: uppper \leftarrow lower^T

11: Z \leftarrow regressiveSubstitution(lower|B)

12: X \leftarrow progressiveSubstitution(upper|Z)
```

Algorithm 34 Tridiagonal

```
1: READ A, B, C, D
2: N \leftarrow \text{length of D}
3: C[0] \leftarrow C[0]/B[0]
4: D[0] \leftarrow D[0]/B[0]
5: for i = 1...N do
        aux \leftarrow B[i] - (A[i] * C[i-1])
        C[i] \leftarrow C[i]/aux
        D[i] \leftarrow (D[i] - A[i] * D[i-1])/aux
9: end for
10: x \leftarrow \text{vector of length N}
11: for i = 0...N do
        x[i] \leftarrow 0
13: end for
14: x[n-1] \leftarrow D[N-1]
15: for i = 0...N - 1 do
        x[i][i] - C[i] * x[i+1]
17: end for
18: returnx
```