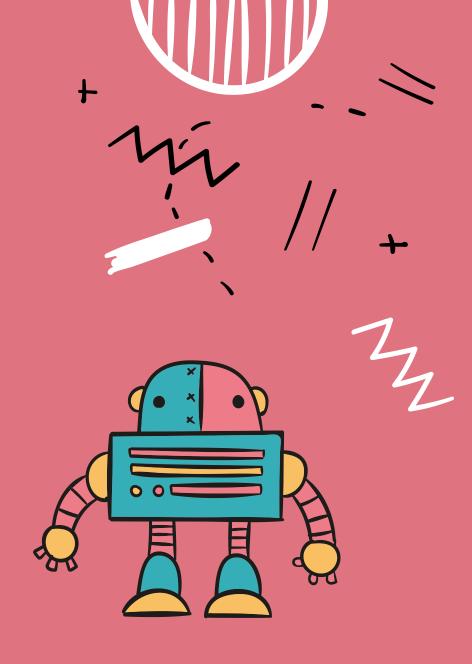




Project Description

 A downloadable software package that students can utilize to simulate Boe-Bot behaviors, thus removing the need for the physical components of the EGR 101 course.



Project Use

- Due to the pandemic, students could not do hands on coursework for EGR 101 for fear of violating COVID-19 restrictions.
- Solution was to have students purchase their own \$85 kits to do the course individually. This is obviously not comparable to what EGR 101 actually is like.
- EGR 101 Simulation attempts to emulate what being in the class is like, from putting together a bot to coding it to linefollow.

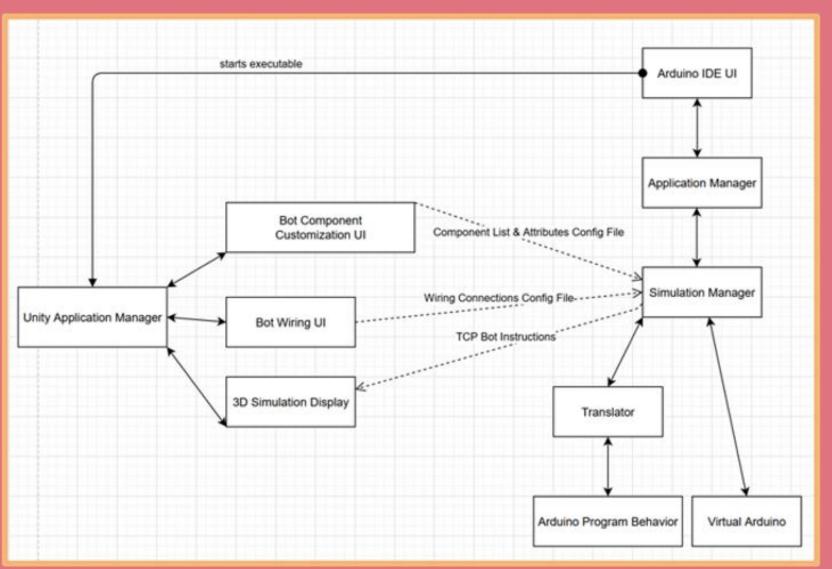
Assumptions/Dependencies

- Students are familiar with the kit and its components
- Students also understand assigned task and what to do
- Only the professor can add additional components and pieces to the kit
- The application must be able to run on different operating systems

Constraints

- Project is constrained by the kit provided to the EGR 101 students
- Cannot have functionality or components that the actual robot and kit does not have

Architectural Diagram



Major Sub-Systems

4



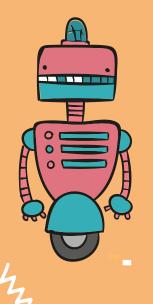
Design/Wiring Interface

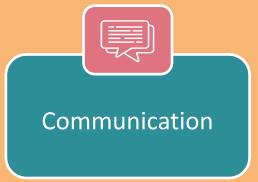


Arduino IDE

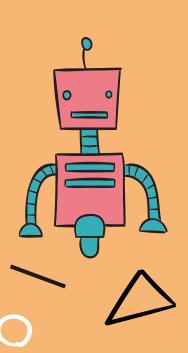


Arduino Emulation



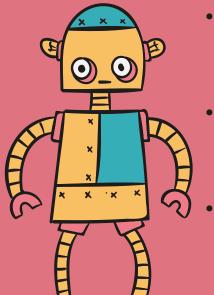




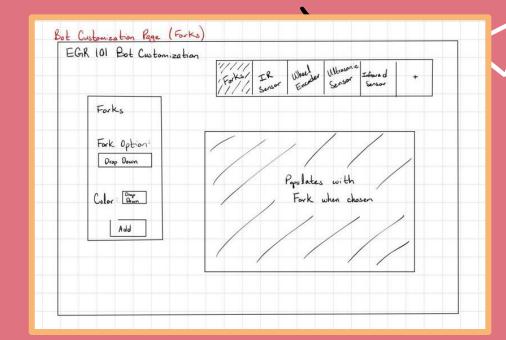


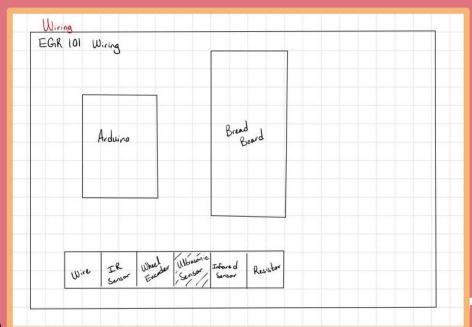


Design/Wiring Interface



- Design GUI driven to emulate 3dimensional hardware components
- Students can customize their bot (color, sensors, frame, etc.)
- Students can digitally wire components to a virtual Arduino or breadboard
- Using Unity + C# to design GUI base



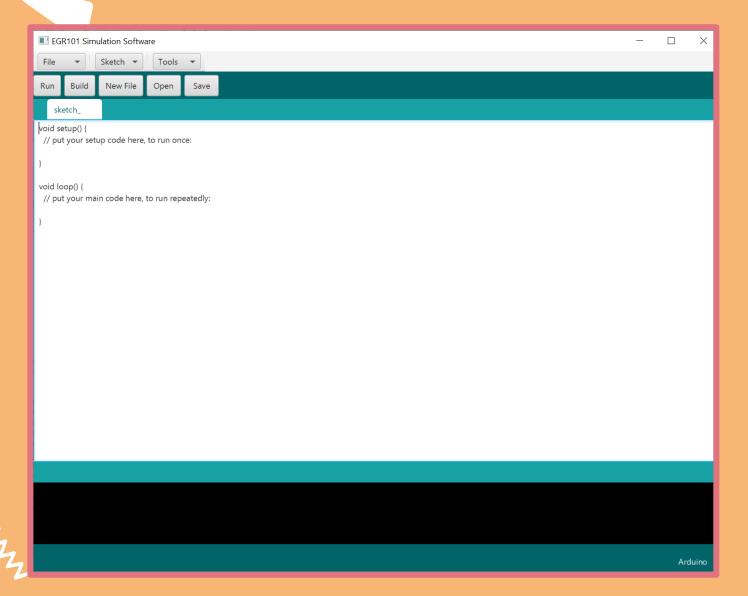






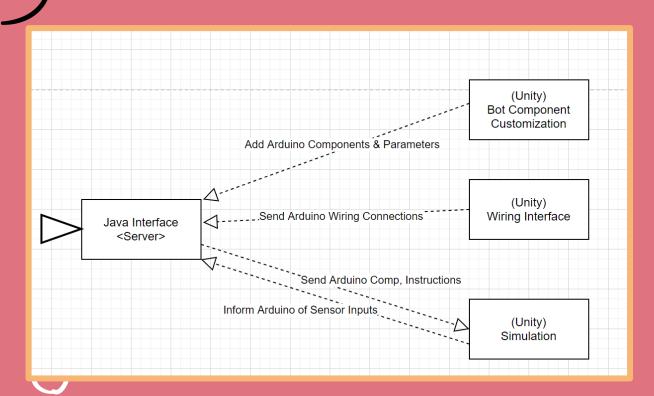
Arduino IDE



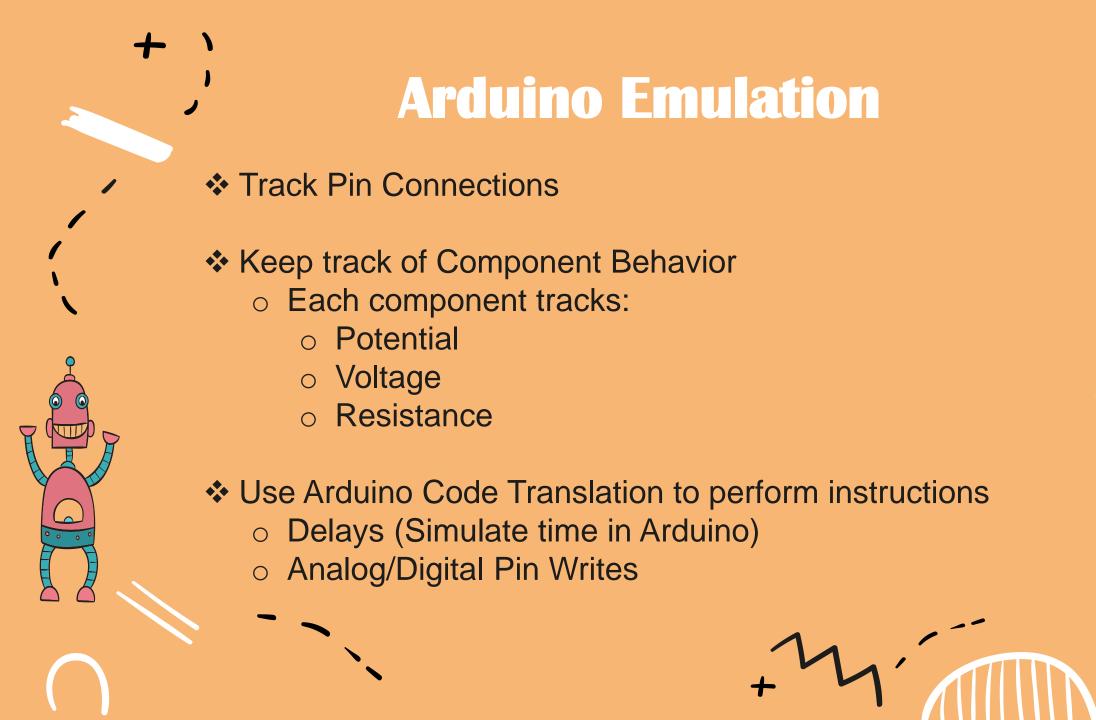


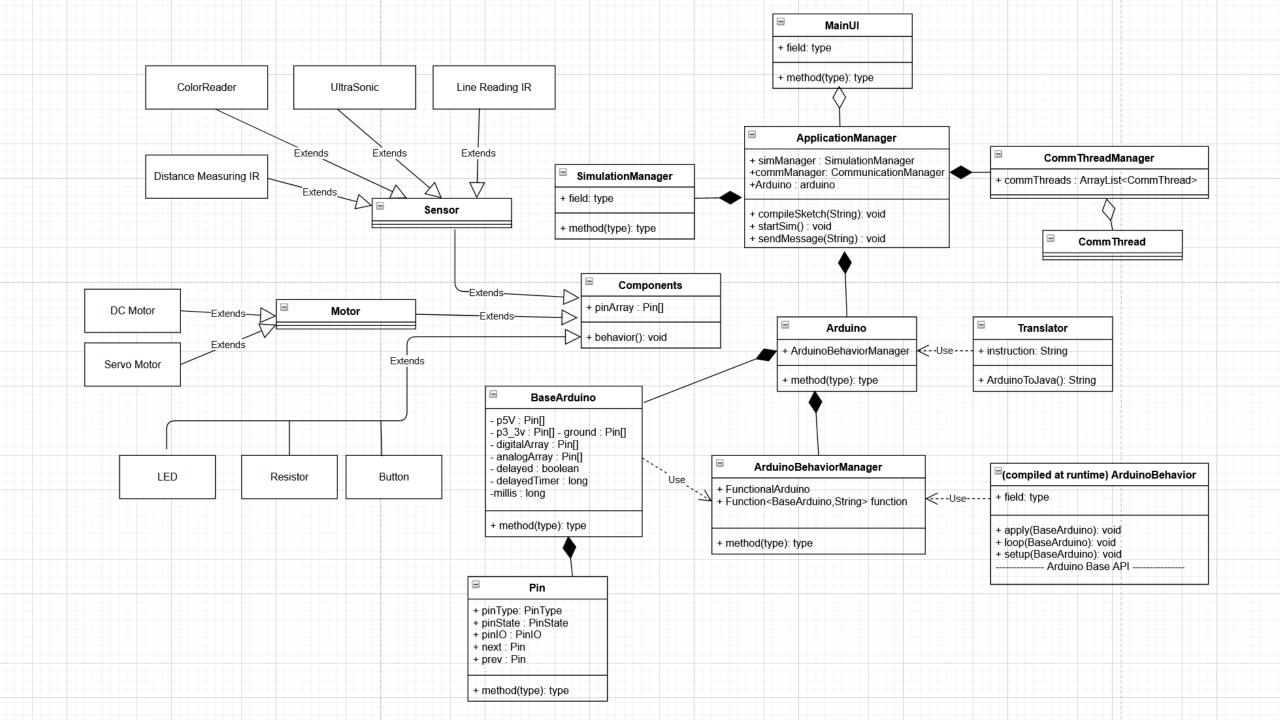
- Mimics all functionality of the Arduino interface
- Arduino code can be entered and will be translated into Java to be compiled
- This will connect to the wiring and robot components

Communication



- Java Application will act as a server
- Simulated Arduino will send component info to 3D Unity simulation
- 3D Unity Wiring Interface will send wiring info to the simulated Arduino
- Bot Customization will send component addition and design to simulated Arduino

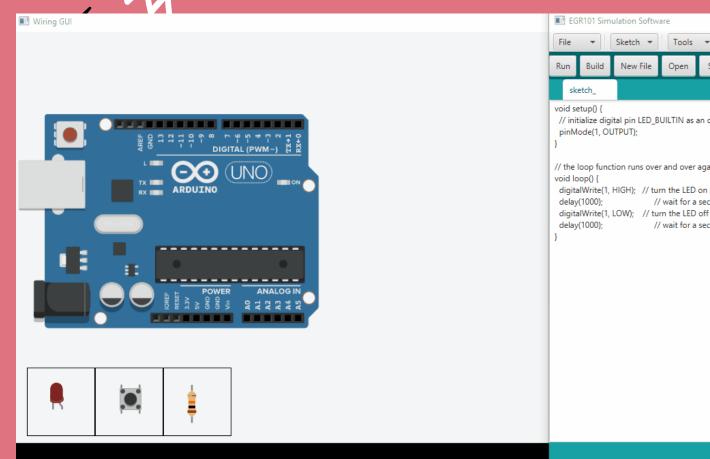






Demo 1: Simple LED Blink Test --





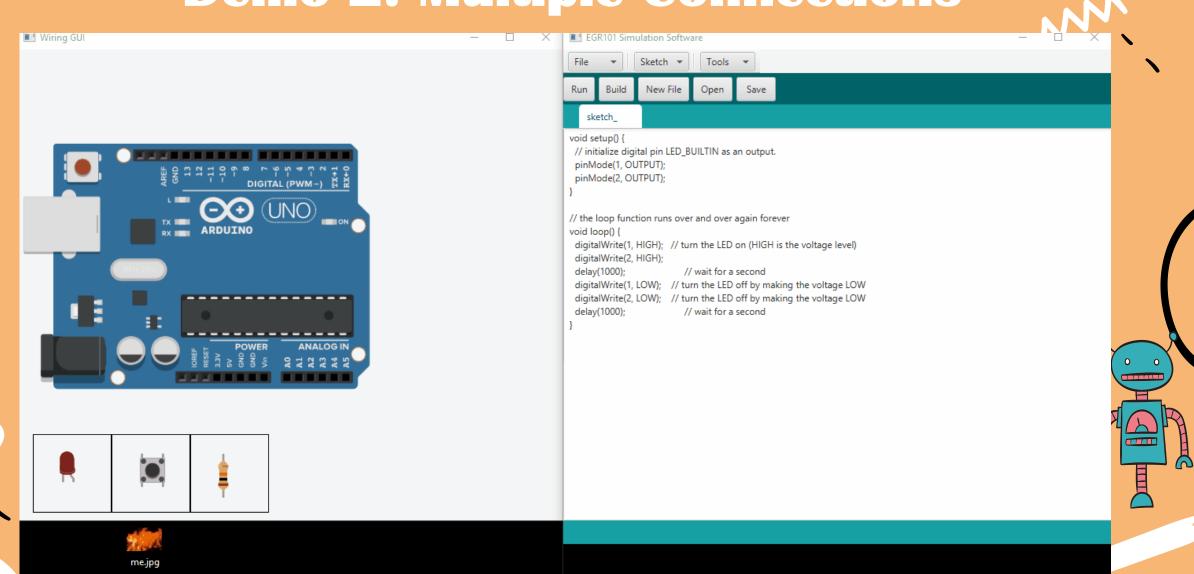
```
EGRIOI Simulation Software

File Sketch Dopen Save

sketch_

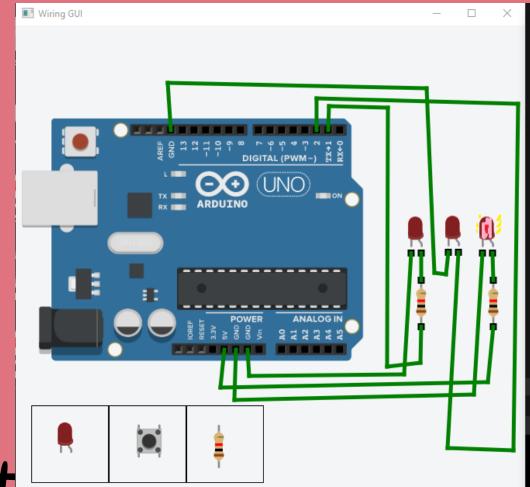
void setup() {
// initialize digital pin LED_BUILTIN as an output.
pinMode(1, OUTPUT);
}
}
// the loop function runs over and over again forever
void loop() {
digitalWrite(1, HIGH); // turn the LED on (HIGH is the voltage level)
delay(1000); // wait for a second
digitalWrite(1, LOW); // turn the LED off by making the voltage LOW
delay(1000); // wait for a second
}
```

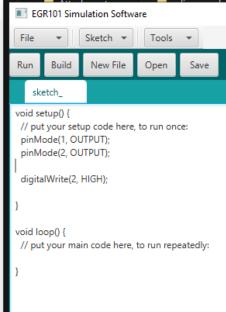
Demo 2: Multiple Connections





- LEDs won't light up if raw 5V is not placed with a resistor
- LEDs won't light up if there's no digital Write (on a digital Pin)
- LEDs won't light up if there's no ground





Project Timeline

+ 4



10/28

12/2

Sprint 1

Sprint 2

Sprint 3

- Initial GUI for bot customization
- Initial GUI for Arduino IDE
- Arduino emulation can handle simple circuits
- Able to translate Arduino code into Java code

- Arduino IDE should be fully styled
- Arduino emulation includes all necessary components
- Functional wiring GUI

- Fully functional 3D Boe-Bot simulation
- Fully functional bot customization

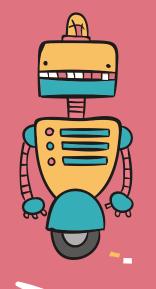






Lessons Learned

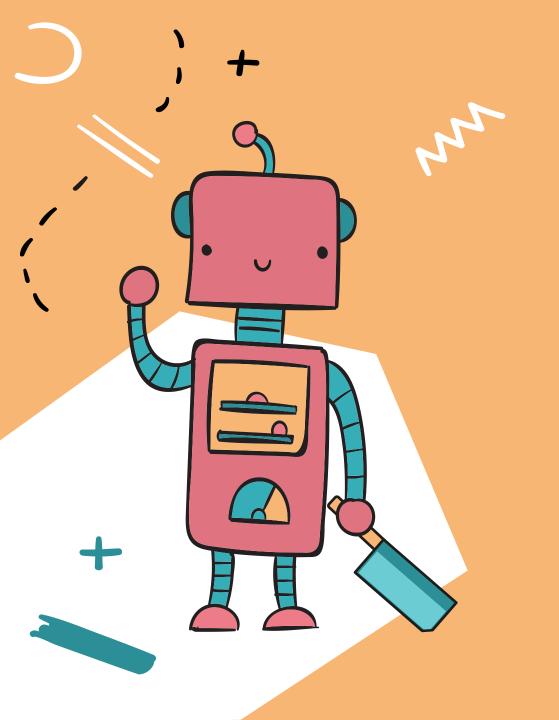
- Need a form of Java/C# styling standard
- Should start defining method and class signature documentation through JavaDoc
- Properly utilizing tools like ZenHub is greatly beneficial
- Need to improve estimating time to reach project goals
- More structure and direction with team meetings











Thank you for watching our presentation!

Questions?