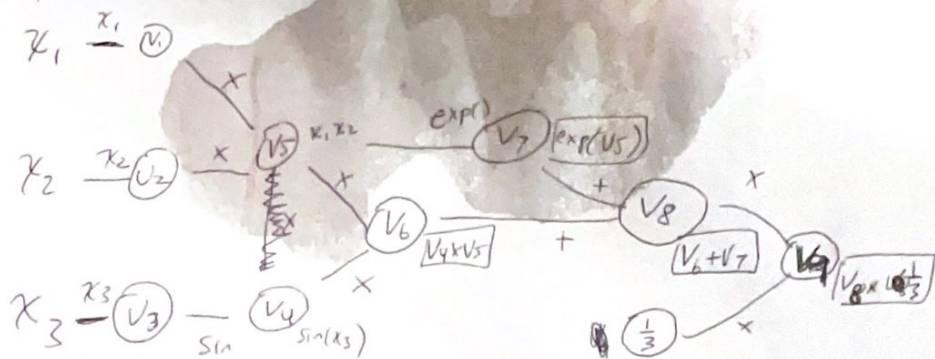


a)



$$\frac{1}{3}(x_1 x_2 \sin(x_3) + e^{x_1 x_2})$$

b)

$$v_1 = x_1$$

$$v_2 = x_2$$

$$v_3 = x_3$$

$$v_4 = \sin(v_3)$$

$$v_5 = v_1 \times v_2$$

$$v_6 = v_4 \times v_5$$

$$v_7 = \exp(v_5)$$

$$v_8 = v_6 + v_7$$

$$y = v_9 = \frac{1}{3} \cdot v_8$$

c)  $v_1 = 1$

$$v_2 = 0$$

$$v_3 = 0$$

$$v_4 = \sin(0)$$

$$v_5 = 1 \times 0 = 0$$

$$v_6 = \sin(0) \times 0 = 0$$

$$v_7 = \exp(0) = 1$$

$$v_8 = 0 + 1 = 1$$

$$y = v_9 = \frac{1}{3} \times 1 = \frac{1}{3}$$

d)

$$\begin{aligned} z_1 &= \frac{dy}{dx_1} = \frac{dy}{dv_5} \cdot \frac{dv_5}{dx_1} = \frac{1}{3}(v_1 + 1)e^{v_5} \cdot v_2 \\ z_2 &= \frac{dy}{dx_2} = \frac{dy}{dv_5} \cdot \frac{dv_5}{dx_2} = \frac{1}{3}(v_1 + 1)e^{v_5} \cdot v_1 \\ z_3 &= \frac{dy}{dx_3} = \frac{dy}{dv_4} \cdot \frac{dv_4}{dx_3} = \frac{1}{3}(1 + v_7) \cdot v_5 \cdot \cos(v_3) \\ z_4 &= \frac{dy}{dv_3} = \frac{dy}{dv_4} \cdot \frac{dv_4}{dv_3} = \frac{1}{3}(1 + v_7) \cdot v_5 \\ z_5 &= \frac{dy}{dv_5} = \frac{dy}{dv_6} \cdot \frac{dv_6}{dv_5} = \frac{1}{3}(v_6 + 1)e^{v_5} \\ z_6 &= \frac{dy}{dv_6} = \frac{dy}{dv_7} \cdot \frac{dv_7}{dv_6} = \frac{1}{3}(1 + v_7) \\ z_7 &= \frac{dy}{dv_7} = \frac{dy}{dv_8} \cdot \frac{dv_8}{dv_7} = \frac{1}{3} \\ z_8 &= \frac{dy}{dv_8} = \frac{dy}{dv_9} \cdot \frac{dv_9}{dv_8} = \frac{1}{3} \\ z_9 &= \frac{dy}{dv_9} = 1 \end{aligned}$$