

2-WORMHOLE

Consider the quotient space of \mathbb{H}^2 generated by quotienting out by a loxodromic transformation. We can set the half-plane model $\mathbb{H}^2 = \{(x, y) : y > 0\}$ so that the axis that is translated along is the $x = 0$ geodesic. The loxodromic transformation thus becomes $(x, y) \mapsto e^k(x, y)$ where k is the hyperbolic distance translated.

The resulting space is a $(1, 1)$ -surface of revolution. In particular, the subgroup of the isomorphism group made up by the loxodromic transformations in that direction by arbitrary distances is S^1 .

This quotient space can be mapped to $S^1 \times \mathbb{R}$ by $\phi : \mathbb{H}^2 \rightarrow S^1 \times \mathbb{R}$ given by $\phi(x, y) = \left(\frac{2\pi}{k} \log \sqrt{x^2 + y^2}, \frac{y}{x} \right)$. This is necessary to allow it to be generalized to an $(n, 1)$ -surface of revolution.

In addition to mapping the points, we have to be able to convert vectors between the two. The vectors used in the half plane model are set so that $(0, 1)$ points to the point at $(0, \infty)$ and $(1, 0)$ is 90° clockwise of this.

For the 2-Wormhole, at (x, y) , $(0, 1)$ should point in the direction of $(1+\epsilon)(x, y)$, and $(1, 0)$ should point 90° counterclockwise of this.

Suppose you're at point (x, y) in \mathbb{H}^2 .

Let $\theta = \arctan \frac{y}{x}$.

The vector $(0, 1)$ in wormhole coordinates should correspond to the direction of (x, y) in \mathbb{H}^2 coordinates. This is $(\cos \theta, \sin \theta)$.

The vector $(1, 0)$ in wormhole coordinates should correspond to the direction 90° counter-clockwise. This comes out to $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} = \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix}$

Using this, the matrix to convert from wormhole coordinates to \mathbb{H}^2 coordinates should be $\begin{pmatrix} -\sin \theta & \cos \theta \\ \cos \theta & \sin \theta \end{pmatrix}$. This matrix is its own inverse, so it can be used to convert either way.

The final problem is finding the rotation of a point that has moved. Since this is an orientation-reversing map, the rotation must be inverted.

Then a miracle happened.

The rotation ϕ' on the wormhole map is $-\phi - (\theta_1 - \theta_0)$ where ϕ is the rotation on the \mathbb{H}^2 map, θ_0 is $\arctan \frac{y_0}{x_0}$ where (x_0, y_0) is the initial point on \mathbb{H}^2 , and θ_1 is $\arctan \frac{y_1}{x_1}$ where (x_1, y_1) is the final point on \mathbb{H}^2 .