

Method 2

The general linear model

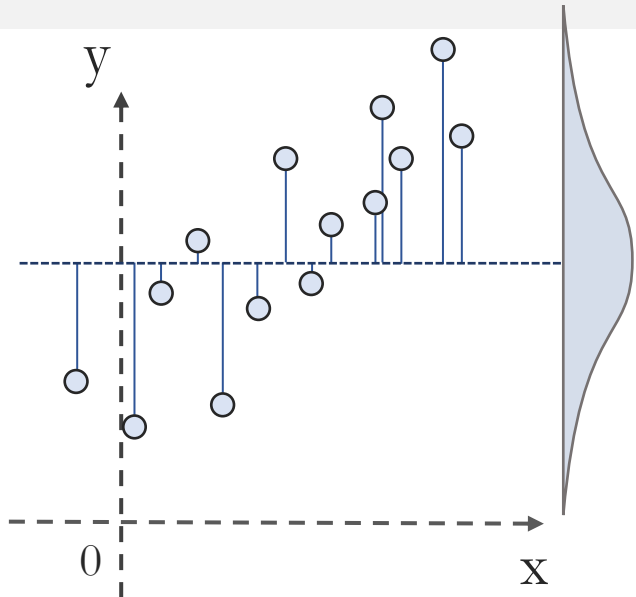
The General Linear Model

BSc Program in Cognitive Science
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The background features a collection of circles in various sizes and colors, including orange, red, pink, and purple. These circles are scattered across the slide, with some appearing to follow dashed lines that create a sense of movement or trajectory. The overall aesthetic is modern and abstract.

Conceptual foundations and history of the GLM

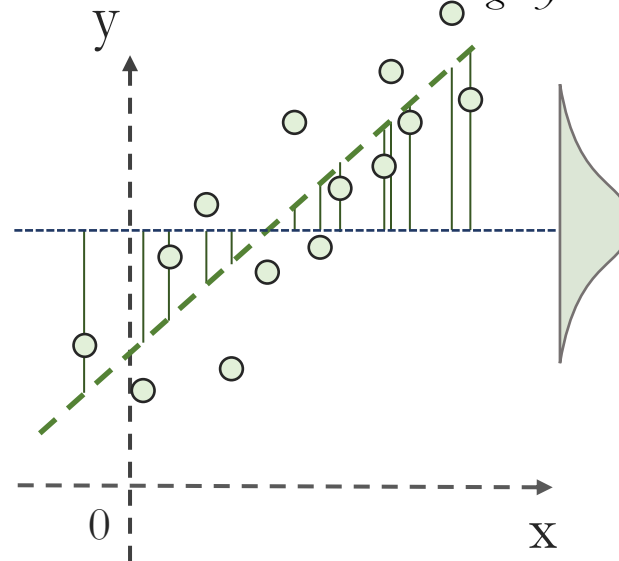
Where I messed up



$$TSS = \sum_{i=1}^n (y_i - \bar{y})^2$$

Total Sum of Squares (TSS, or SST)

« *Mal nommer un objet, c'est ajouter au malheur de ce monde.* »
 “To call things by incorrect names is to add to the world’s misery.”

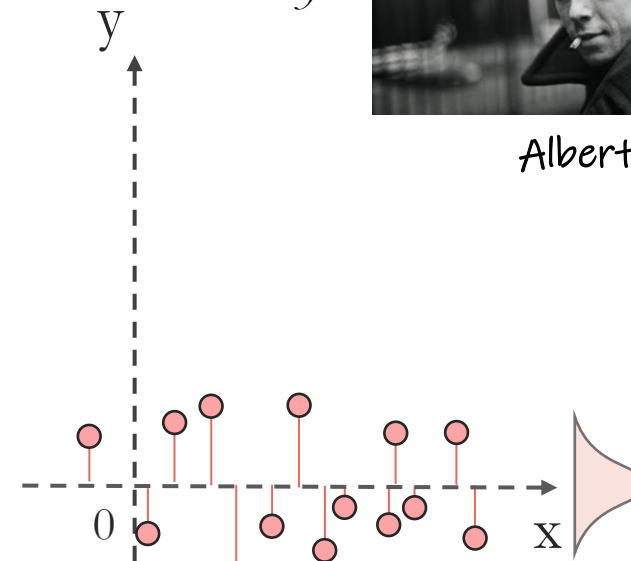


$$ESS = \sum_{i=1}^n (\hat{y}_i - \bar{y})^2$$

Explained Sum of Squares (ESS)
 or Model Sum of Squares
 or Sum of Squares due to Regression (SSR)



Albert Camus



$$RSS = \sum_{i=1}^n (\hat{\epsilon}_i)^2 = \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

Residual Sum of Squares (RSS)
 or Sum of Squared Residuals (SSR)
 or Sum of Squared Estimate of Errors (SSE)

Residuals

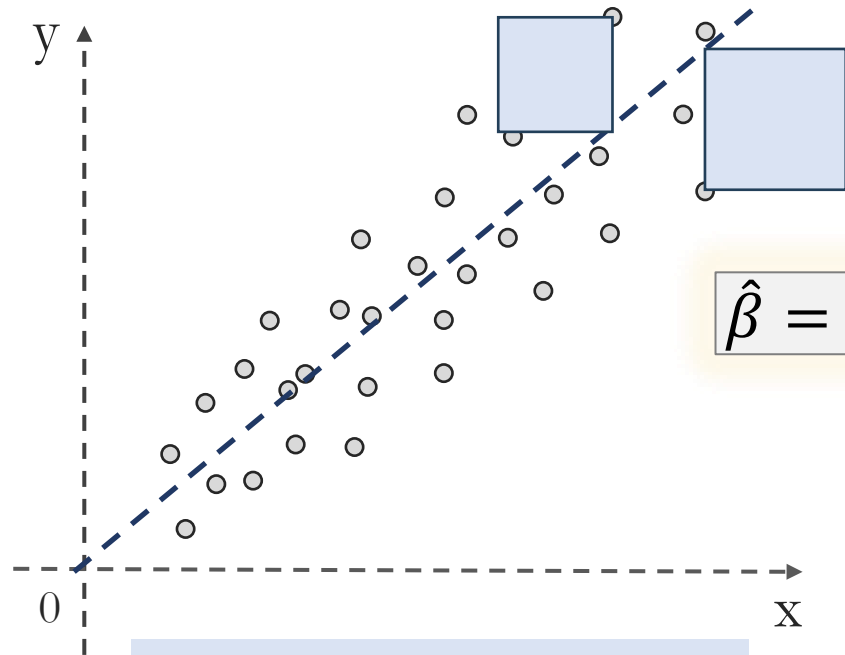
$$r_i = y_i - (\hat{\alpha} + \hat{\beta}x_i)$$

Errors

$$\epsilon_i = y_i - (\alpha + \beta x_i)$$

Towards Bayesian Data Analysis

Ordinary Least Squares

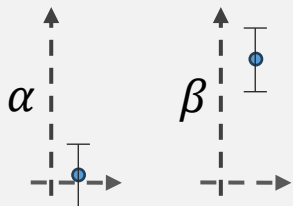


$$\hat{\beta} = (X^t X)^{-1} X^t y$$



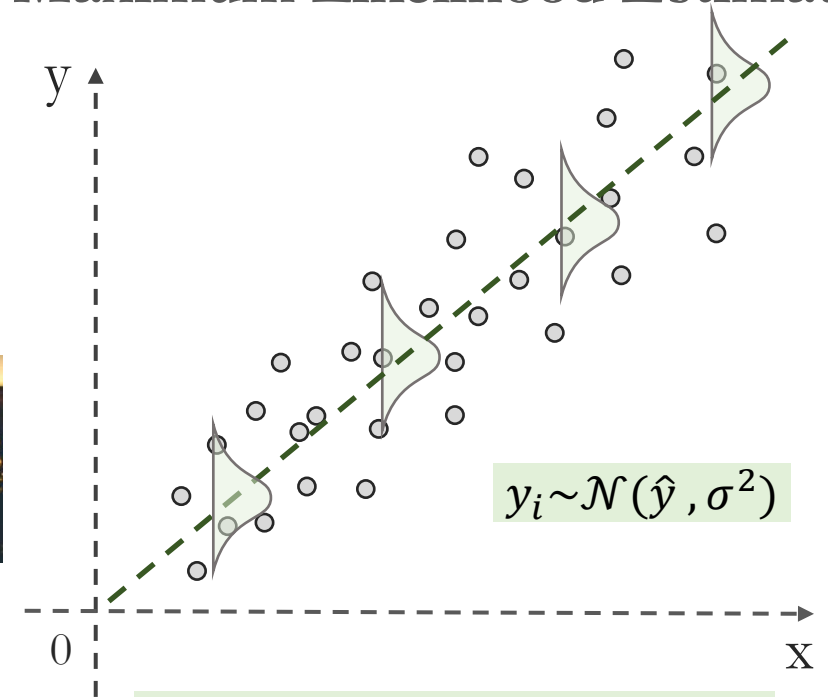
$$\min_{\alpha, \beta} \sum_{i=1}^n (y_i - (\alpha + \beta x_i))^2$$

Adding a standard error



If the errors from the linear model are independent and normally distributed, then the **least squares estimate** is also the **maximum likelihood estimate**.

Maximum Likelihood Estimate



$$y_i \sim \mathcal{N}(\hat{y}, \sigma^2)$$

$$\max_{\alpha, \beta} \prod_{i=1}^n \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{1}{2} \left(\frac{y_i - (\alpha + \beta x_i)}{\sigma} \right)^2}$$

$$\rightarrow \max_{\alpha, \beta} \sum_{i=1}^n -\ln(\sigma \sqrt{2\pi}) - \frac{1}{2} \left(\frac{y_i - (\alpha + \beta x_i)}{\sigma} \right)^2$$

Propagation of uncertainty

$$P(\beta|y) \propto P(y|\beta)P(\beta)$$

Likelihood

Prior

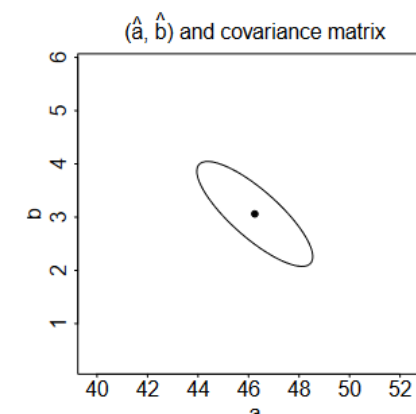
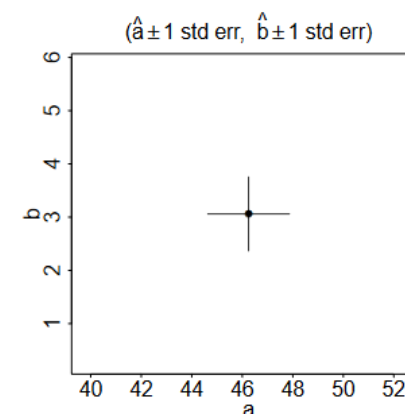
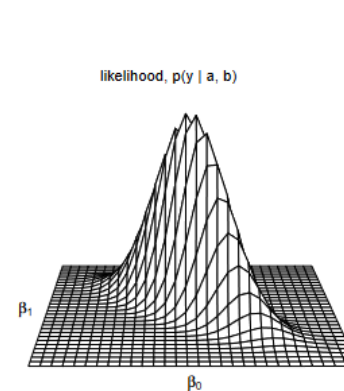
$$P(\beta|y) = \frac{P(y|\beta)P(\beta)}{P(y)}$$

Marginal probability

$$\int P(y|\beta)P(\beta)d\beta$$

Bayesian inference helps us:

- Propagate uncertainties across parameters using probability and simulations
- Add prior information about expected values



Fixed Parameters

Parameters with a Distribution

