

Assignment #3 Lab Section #02, Group #48

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https://github.com/DanielMellen-University/ENSF338A3repo

Work Performed By Each Member

Q1: Tahmeed & Daniel

Q2: Daniel Q3:Tahmeed Q4: Daniel Q5:Tahmeed

*Whoever did the question put the question into the pdf submission. Tahmeed created the cover page and "Work Performed By Each Member" Section. Daniel created the github.

50% of work was done by Tahmeed and 50% by Daniel.

EXERCISE 1

```
import sys
class Node:
       self.data = data
       self.next = next
class Stack:
  def push(self, data):
           return None
       else:
           popped node = self.top
           self.top = popped node.next
           return popped node.data
       return self.top.data
```

```
def evaluate expression(expression):
   for token in expression.split(" "):
      hasLb = token.find("(")
       if hasLb==0:
       else:
              if hasRb==1:
               else:
       while hasRb>-1: #evaluate
           operand2 = stack.pop()
           operand1 = stack.pop()
           operator = stack.pop()
           result = None # define result outside of the if statement
           if operator == "+":
               result = operand1 + operand2
           elif operator == "-":
               result = operand1 - operand2
           elif operator == "*":
               result = operand1 * operand2
           elif operator == "/":
               result = operand1 / operand2
```

```
return stack.pop()

# Get the expression from the command line argument
expression = sys.argv[1]

# Evaluate the expression and print the result
result = evaluate_expression(expression)
print(result)
```

EXERCISE 2

```
import json
import time
import matplotlib.pyplot as plt

# Load the array and list of search tasks
with open("ex2data.json", "r") as f:
    array = json.load(f)

with open("ex2tasks.json", "r") as f:
    tasks = json.load(f)

# Define a function to perform binary search with configurable initial midpoint

def isInArray(arr, target,mI):
    startI = 0
    endI = len(arr) - 1

    while(startI < endI - 1):
        if(target < arr[mI]):
        endI = mI
        else:</pre>
```

```
startI = mI
       if (target == arr[mI]):
           return True
      mI = round((startI + endI)/2)
   if(target == arr[startI] or (target == arr[endI])):
       return True;
   return False;
def time search task(array, tasks):
   for t in tasks:
      bestTime = -1
      for mp in (range(array[0], array[len(array)-1], 10)):
               bestTime = extime;
               bestMP4t = mp;
      bestMP.append(bestMP4t)
   return bestMP;
t = 384;
print("\n" + str(t) + "\n" + str(isInArray(array, t)))
t = 385;
print("\n" + str(t) + "\n" + str(isInArray(array, t)))
z = 386;
print("\n" + str(t) + "\n" + str(isInArray(array, t)))
```

```
"""

resultsBMP = time_search_task(array, tasks);

# Produce a scatterplot of the results

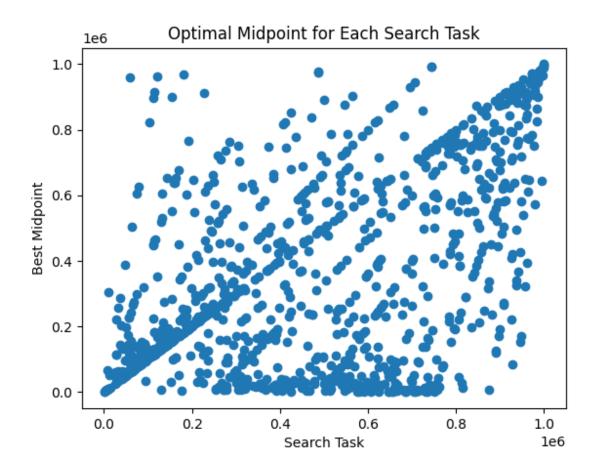
plt.scatter(tasks, resultsBMP)

plt.xlabel("Search Task")

plt.ylabel("Best Midpoint")

plt.title("Optimal Midpoint for Each Search Task")

plt.show()
```



The choice of initial midpoint affects the performance because it determines the number of binary searches. Expected dependence is diagonal from bottom left to top right - initial midpoint is roughly equal to search target. In my plot, we can also see that there are multiple lines starting in the bottom left resp. top right

corner. This can be explained by using 10 as a midpoint step to reduce the number of iterations and runtime.

EXERCISE 3

1.

When a Python list (dynamic array) is full, the strategy is to double the size of the existing array. When the list's length equals its allocated size (as determined by the ob size and allocated fields), the PyList Resize() function is called to double the allocated size.

Here is the relevant code from the PyList Resize() function in Python's C implementation:

```
new_allocated = (new_size >> 3) + (new_size < 9 ? 3 : 6);
items = (PyObject **)PyMem_RENEW(PyObject *, items, new_allocated);
```

The new allocated size is calculated as (new size >> 3) + (new size 9? 3: 6), which doubles the existing array size. After that, the PyMem RENEW() function is called to resize the array and allocate memory for the new items. The growth factor is approximately 1.125 (1 + 1/8). The new size of the array is calculated by adding the current size of the array, one-eighth of the current size, and a small number (3 or 6) based on whether the current size is less than 9 or not.

2.

```
ex3.3py:
import sys

def main():
    test_list = []
    prev_capacity = 0

for i in range(64):
    test_list.append(i)
    current_capacity = sys.getsizeof(test_list) - sys.getsizeof([])
    if current_capacity!= prev_capacity:
        print(f"Capacity changed at {i + 1} elements. New capacity: {current_capacity}

bytes.")
    prev_capacity = current_capacity
```

```
if __name__ == "__main__":
    main()
```

This code creates an empty list lst and expands it by appending integers ranging from 0 to 63. The code computes the list's current capacity for each new integer appended to the list using the formula (sys.getsizeof(lst) - 64) / 8. To calculate the number of elements that can be stored in the list, subtract the fixed overhead of the list object (64 bytes) from the list's size in bytes and divide by 8 (the size of a pointer on most systems).

If the new capacity differs from the previous capacity, the code prints a message to the console using the print capacity() function, which computes and prints the capacity. The program's output should indicate when the list's capacity changes as a result of the dynamic array growing algorithm.

EXERCISE 4

```
ex3.4.py:
```

```
import threading
import time
import random

class Queue:
    def __init__(self, capacity):
        self.capacity = capacity
        self.size = 0
        self.front = 0
        self.rear = -1
        self.buffer = [None] * capacity
        self.lock = threading.Lock()
        self.not full = threading.Condition(self.lock)
```

```
self.not_empty = threading.Condition(self.lock)
  def enqueue(self, data):
     with self.not full:
       while self.size == self.capacity:
          self.not full.wait(1)
       if self.size < self.capacity:
          self.rear = (self.rear + 1) % self.capacity
          self.buffer[self.rear] = data
          self.size += 1
          self.not_empty.notify()
  def dequeue(self):
     with self.not_empty:
       while self.size == 0:
          self.not empty.wait(1)
       if self.size > 0:
          data = self.buffer[self.front]
          self.front = (self.front + 1) % self.capacity
          self.size -= 1
          self.not full.notify()
          return data
def producer(q):
  while True:
     data = random.randint(1, 10)
     time.sleep(data)
     q.enqueue(data)
def consumer(q):
  while True:
     data = random.randint(1, 10)
     time.sleep(data)
     print(q.dequeue())
if __name__ == "__main__":
  q = Queue(10)
```

EXERCISE 5

1. G

In the worst case, the time complexity of the processdata() function is $O(n^2)$, where n is the length of the input list li. When all of the elements of li are less than or equal to 5, the best case time complexity is O(n). Because the nested loop is always executed when at least one element of li is greater than 5, the average case time complexity is also $O(n^2)$.

Because it iterates over each element of li, the outer loop has a time complexity of O(n). The inner loop also has a time complexity of O(n), since it iterates over each element of li for each element that is greater than 5. As a result, the function's overall time complexity is $O(n^2)$.

2. G

Because there are no elements greater than 5, the best case time complexity of the processdata() function is already O(n). However, the worst-case and average-case time complexity can be improved by exiting the inner loop once a larger element is discovered. In the worst and average cases, a modified version of the processdata() function achieves O(n log n) time complexity. This modified code breaks out of the inner loop as soon as an element greater than li[i] is found, reducing the number of iterations required in the worst and average cases.

```
def processdata(li):
  for i in range(len(li)):
    if li[i] > 5:
       for j in range(len(li)):
       if li[j] > li[i]:
            break
       li[i] *= 2
```

3.

a. Code for inefficient implementation of search in a sorted array:

```
def linear_search(arr, x):
    for i in range(len(arr)):
        if arr[i] == x:
        return i
    return -1
```

This implementation iterates through the input array in a linear search until the target value x is found. This algorithm's worst-case time complexity is O(n), where n is the length of the input array and and an average-case time complexity of O(n/2).

Code for implementing search in a sorted array efficiently:.

```
def binary_search(arr, x):
  low = 0
  high = len(arr) - 1
  while low <= high:</pre>
```

```
mid = (low + high) // 2
if arr[mid] == x:
    return mid
elif arr[mid] < x:
    low = mid + 1
else:
    high = mid - 1
return -1
```

This implementation conducts a binary search through the input array, dividing the search space in half with each iteration. This algorithm's worst-case time complexity is O(log n), where n is the length of the input array.

Experiment code (search in a sorted array):

```
import numpy as np
import matplotlib.pyplot as plt
import random
import time
def linear_search(arr, x):
  for i in range(len(arr)):
     if arr[i] == x:
        return i
  return -1
def binary search(arr, x):
  low, high = 0, len(arr) - 1
  while low <= high:
     mid = (low + high) // 2
     if arr[mid] == x:
        return mid
     elif arr[mid] < x:
        low = mid + 1
     else:
```

```
high = mid - 1
  return -1
arr = [i for i in range(1000)]
x = random.randint(0, 999)
linear times = []
binary_times = []
for i in range(100):
  start time = time.time()
  linear search(arr, x)
  end time = time.time()
  linear times.append(end time - start time)
  start time = time.time()
  binary search(arr, x)
  end time = time.time()
  binary times.append(end time - start time)
print("Linear search times:")
print(f"min={min(linear times):.6f} avg={sum(linear times)/len(linear times):.6f}")
print("Binary search times:")
print(f"min={min(binary times):.6f}
avg={sum(binary_times)/len(binary_times):.6f}")
```

This code creates an array of 1000 integers and a search target value x. It then runs 100 searches using both the linear and binary search algorithms, timing each one and saving the elapsed time in a list. Finally, the code displays the shortest and longest search times for each algorithm.

The program's output should show the shortest and longest search times for both algorithms over 100 trials. On large inputs, the binary search algorithm (which has worst-case time complexity O(log n)) should be much faster than the linear search algorithm (which has worst-case time complexity O(n)).

b. Code for inefficient implementation of priority queue insertion and extraction:

```
class PriorityQueue:
    def __init__(self):
        self.queue = []

def insert(self, priority, item):
        self.queue.append((priority, item))

def extract_min(self):
    if len(self.queue) == 0:
        return None
    min_index = 0
    for i in range(len(self.queue)):
        if self.queue[i][0] < self.queue[min_index][0]:</pre>
```

```
min_index = i
return self.queue.pop(min_index)[1]
```

Efficient implementation for insertion in and extraction from priority queue:

```
import heapq

class PriorityQueue:
    def __init__(self):
        self.queue = []
        self.index = 0

    def insert(self, priority, item):
        heapq.heappush(self.queue, (priority, self.index, item))
        self.index += 1

    def extract_min(self):
        if len(self.queue) == 0:
            return None
        return heapq.heappop(self.queue)[2]
```

ex3.5.b.py:

```
import random
import time
import heapq
import matplotlib.pyplot as plt

def inefficient_insert(queue, element):
    queue.append(element)
    queue.sort(reverse=True)
```

```
def inefficient_extract(queue):
  return queue.pop()
def efficient insert(queue, element):
  heapq.heappush(queue, element)
def efficient extract(queue):
  return heapq.heappop(queue)
def time_experiment(num_elements, num_trials):
  inefficient_times = []
  efficient times = []
  for in range(num trials):
     data = [random.randint(0, 1000) for _ in range(num_elements)]
     # Inefficient implementation
     inefficient queue = []
     start time = time.time()
     for item in data:
       inefficient insert(inefficient queue, item)
     for in range(num elements):
       inefficient extract(inefficient queue)
     inefficient times.append(time.time() - start time)
     # Efficient implementation
     efficient queue = []
     start time = time.time()
     for item in data:
       efficient insert(efficient queue, item)
     for in range(num elements):
       efficient extract(efficient queue)
     efficient_times.append(time.time() - start_time)
  return inefficient_times, efficient_times
def main():
```

```
num_elements = 1000
num_trials = 100

inefficient_times, efficient_times = time_experiment(num_elements, num_trials)

plt.hist(inefficient_times, bins=20, alpha=0.5, label="Inefficient")
plt.hist(efficient_times, bins=20, alpha=0.5, label="Efficient")
plt.xlabel("Time (s)")
plt.ylabel("Frequency")
plt.legend(loc="upper right")
plt.title("Priority Queue Insertion and Extraction: Inefficient vs Efficient")
plt.show()

print(f"Inefficient avg: {sum(inefficient_times) / num_trials:.6f}s")
print(f"Efficient avg: {sum(efficient_times) / num_trials:.6f}s")

if __name__ == "__main__":
    main()
```

In this code, the inefficient implementation has a time complexity of $O(n^2)$ for insertion and extraction combined (O(nlog(n)) for insertion and O(n) for extraction), while the efficient implementation has a time complexity of O(nlog(n)) for insertion and extraction combined (O(log(n))) for each operation). The experiment times the execution of both implementations on large inputs (1000 elements) and plots the distribution of measured values across multiple measurements (100 measurements per task). It also prints the average time for each implementation.