

# Gap Penalties

CMSC 423

# General Gap Penalties

AAAGAATTCA  
A-A-A-T-CA

vs.

AAAGAATTCA  
AAA-----TCA

These have the same score, but the second one is often more plausible.

A single insertion of “GAAT” into the first string could change it into the second.

- Now, the cost of a run of  $k$  gaps is  $gap \times k$
- It might be more realistic to support general gap penalty, so that the score of a run of  $k$  gaps is **gap**( $k$ )  $< gap \times k$ .
- Then, the optimization will prefer to group gaps together.

# General Gap Penalties

AAAGAATTCA  
A-A-A-T-CA

vs.

AAAGAATTCA  
AAA-----TCA

Previous DP no longer works with general gap penalties because the score of the last character depends on details of the previous alignment:

AAAGAAC  
AAA-----

vs.

AAAGAAATC  
AAA-----

Instead, we need to “know” how long a final run of gaps is in order to give a score to the last subproblem.

# Three Matrices

We now keep 3 different matrices:

$M[i,j]$  = score of best alignment of  $x[1..i]$  and  $y[1..j]$  ending with a character-character **match or mismatch**.

$X[i,j]$  = score of best alignment of  $x[1..i]$  and  $y[1..j]$  ending with a **space in X**.

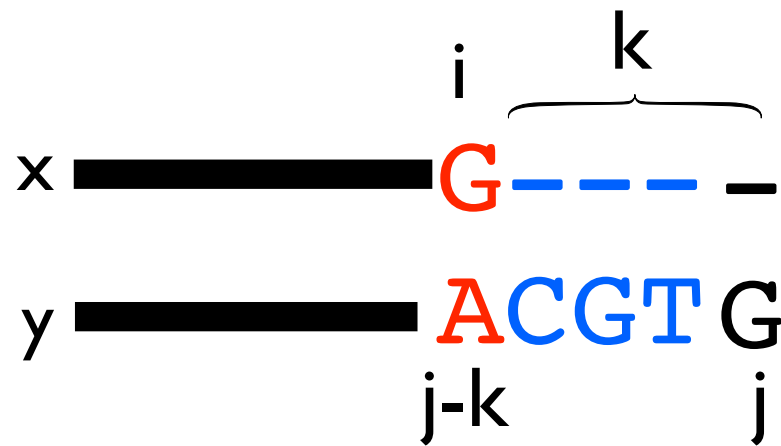
$Y[i,j]$  = score of best alignment of  $x[1..i]$  and  $y[1..j]$  ending with a **space in Y**.

$$M[i, j] = \max \begin{cases} X[i, j] \\ M[i - 1, j - 1] + \text{SCORE}(x[i], y[j]) \\ Y[i, j] \end{cases}$$

$$X[i, j] = \max \begin{cases} Y[i, j - k] - \text{gap}(k) \\ M[i, j - k] - \text{gap}(k) \end{cases}$$

$$Y[i, j] = \max \begin{cases} X[i - k, j] - \text{gap}(k) \\ M[i - k, j] - \text{gap}(k) \end{cases}$$

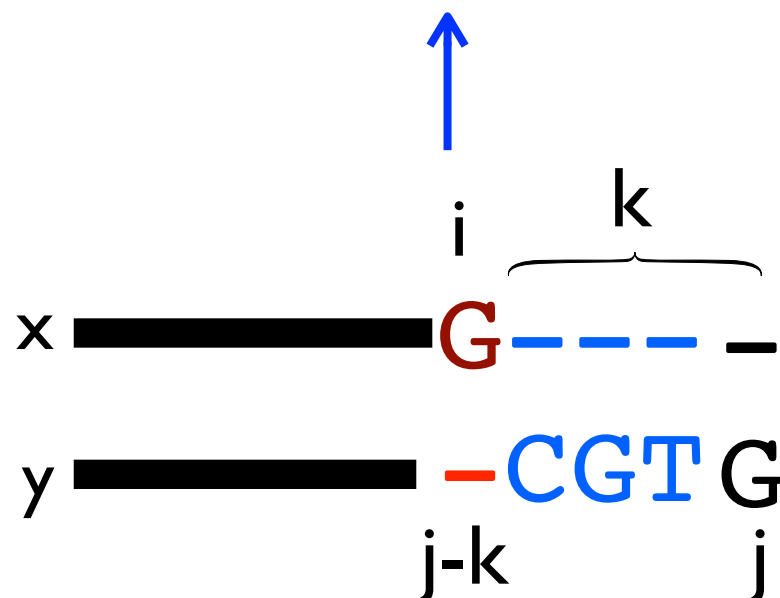
# The X (and Y) matrices



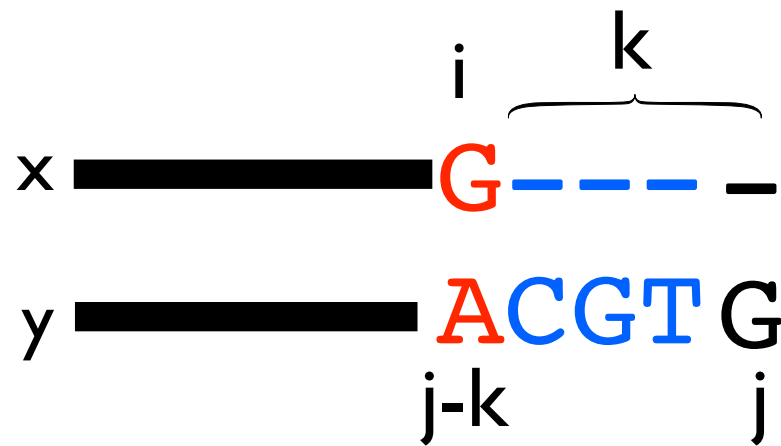
$k$  decides how long to make the gap.

We have to make the whole gap at once in order to know how to score it.

$$X[i, j] = \max \begin{cases} M[i, j - k] - \text{gap}(k) & \text{for } 1 \leq k \leq j \\ Y[i, j - k] - \text{gap}(k) & \text{for } 1 \leq k \leq j \end{cases}$$



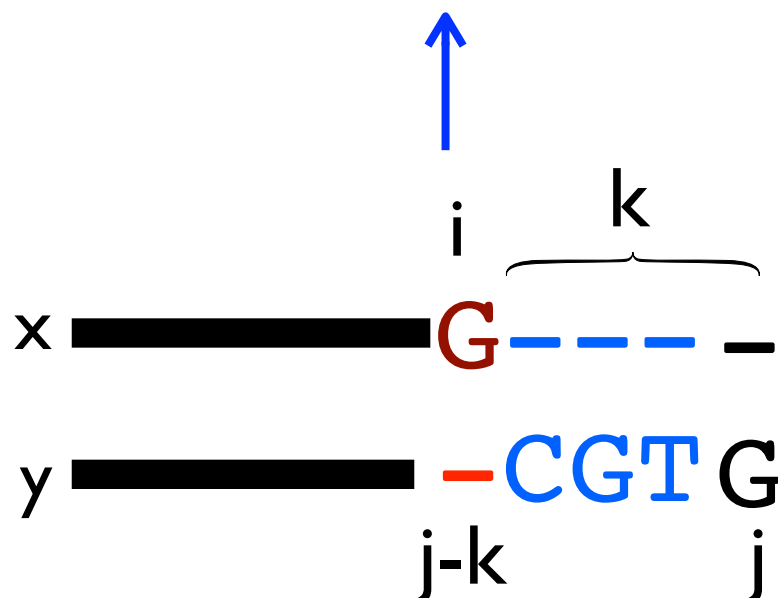
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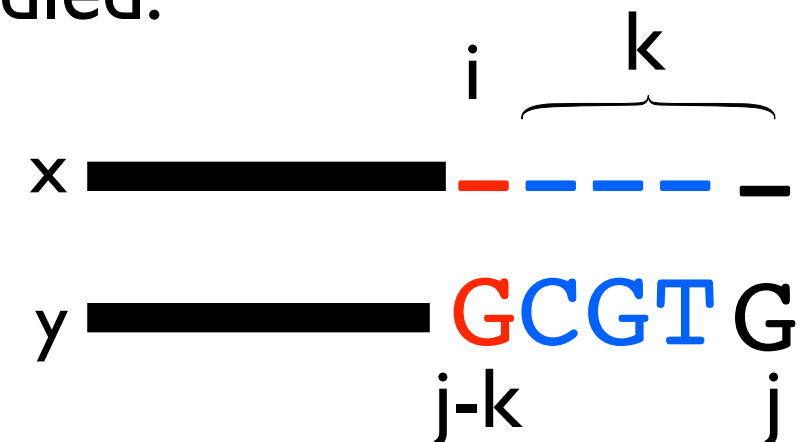
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This case is automatically handled.



# The M Matrix

We now keep 3 different matrices:

$M[i,j]$  = score of best alignment of  $x[1..i]$  and  $y[1..j]$  ending with a character-character **match or mismatch**.

$X[i,j]$  = score of best alignment of  $x[1..i]$  and  $y[1..j]$  ending with a **space in X**.

$Y[i,j]$  = score of best alignment of  $x[1..i]$  and  $y[1..j]$  ending with a **space in Y**.

$$M[i, j] = \max \begin{cases} X[i, j] \\ M[i - 1, j - 1] + \text{SCORE}(x[i], y[j]) \\ Y[i, j] \end{cases}$$

Gaps start and end in the  $M$  matrix.

# Running Time for Gap Penalties

$$M[i, j] = \max \begin{cases} X[i, j] \\ M[i - 1, j - 1] + \text{SCORE}(x[i], y[j]) \\ Y[i, j] \end{cases}$$

$$X[i, j] = \max \begin{cases} Y[i, j - k] - \text{gap}(k) \\ M[i, j - k] - \text{gap}(k) \end{cases}$$

$$Y[i, j] = \max \begin{cases} X[i - k, j] - \text{gap}(k) \\ M[i - k, j] - \text{gap}(k) \end{cases}$$

Final score is  $\max \{M[n, m], X[n, m], Y[n, m]\}$ .

How do you do the traceback?

Runtime:

- Assume  $|X| = |Y| = n$  for simplicity:  $3n^2$  subproblems
- $2n^2$  subproblems take  $O(n)$  time to solve (because we have to try all  $k$ )

$\Rightarrow O(n^3)$  total time



# Affine Gap Penalties

- $O(n^3)$  for general gap penalties is usually too slow...
- We can still encourage spaces to group together using a special case of general penalties called *affine gap penalties*:
  - $gap\_start$  = the cost of starting a gap
  - $gap\_extend$  = the cost of extending a gap by one more space
- Same idea of using 3 matrices, but now we don't need to search over all gap lengths, we just have to know whether we are starting a new gap or not.

$$gap(k) = -(\sigma + (k - 1) * \epsilon)$$

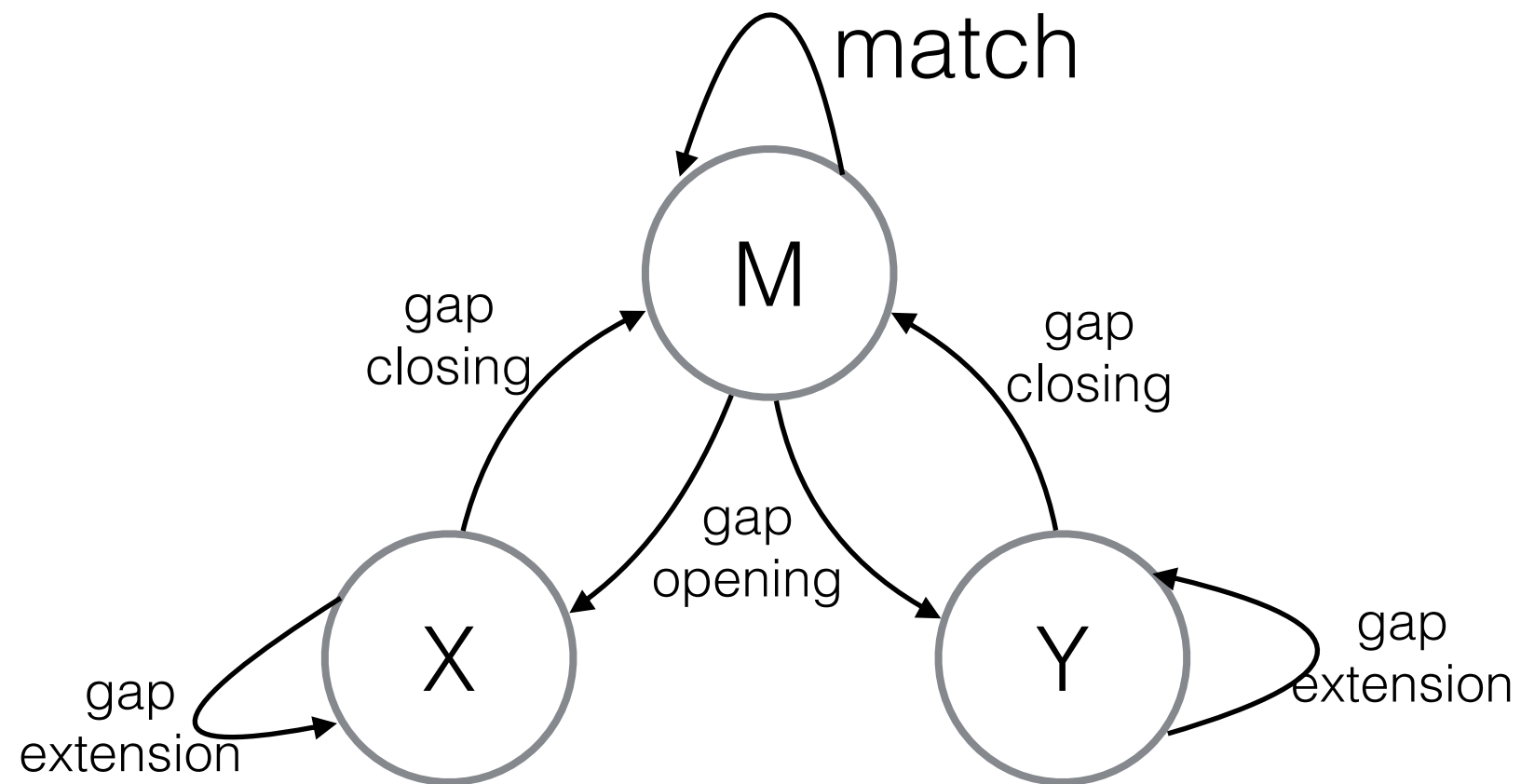
# Affine Gap Penalties

$$M[i, j] = \max \begin{cases} X[i, j] & \text{gap closing} \\ M[i, j] + \text{SCORE}(x[i], y[j]) \\ Y[i, j] \end{cases}$$

$$X[i, j] = \begin{cases} X[i, j-1] - \epsilon & \text{gap extension} \\ M[i, j-1] - \sigma & \text{gap opening} \end{cases}$$

$$Y[i, j] = \begin{cases} Y[i-1, j] - \epsilon \\ M[i-1, j] - \sigma \end{cases}$$

# Affine gap algorithm as a finite state machine



# Affine Gap Runtime

- $3mn$  subproblems
- Each one takes constant time
- Total runtime  $O(mn)$ :
  - back to the run time of the basic running time.

## Traceback

- Arrows now can point between matrices.
- The possible arrows are given, as usual, by the recurrence.
  - E.g. What arrows are possible leaving a cell in the M matrix?

# Recap

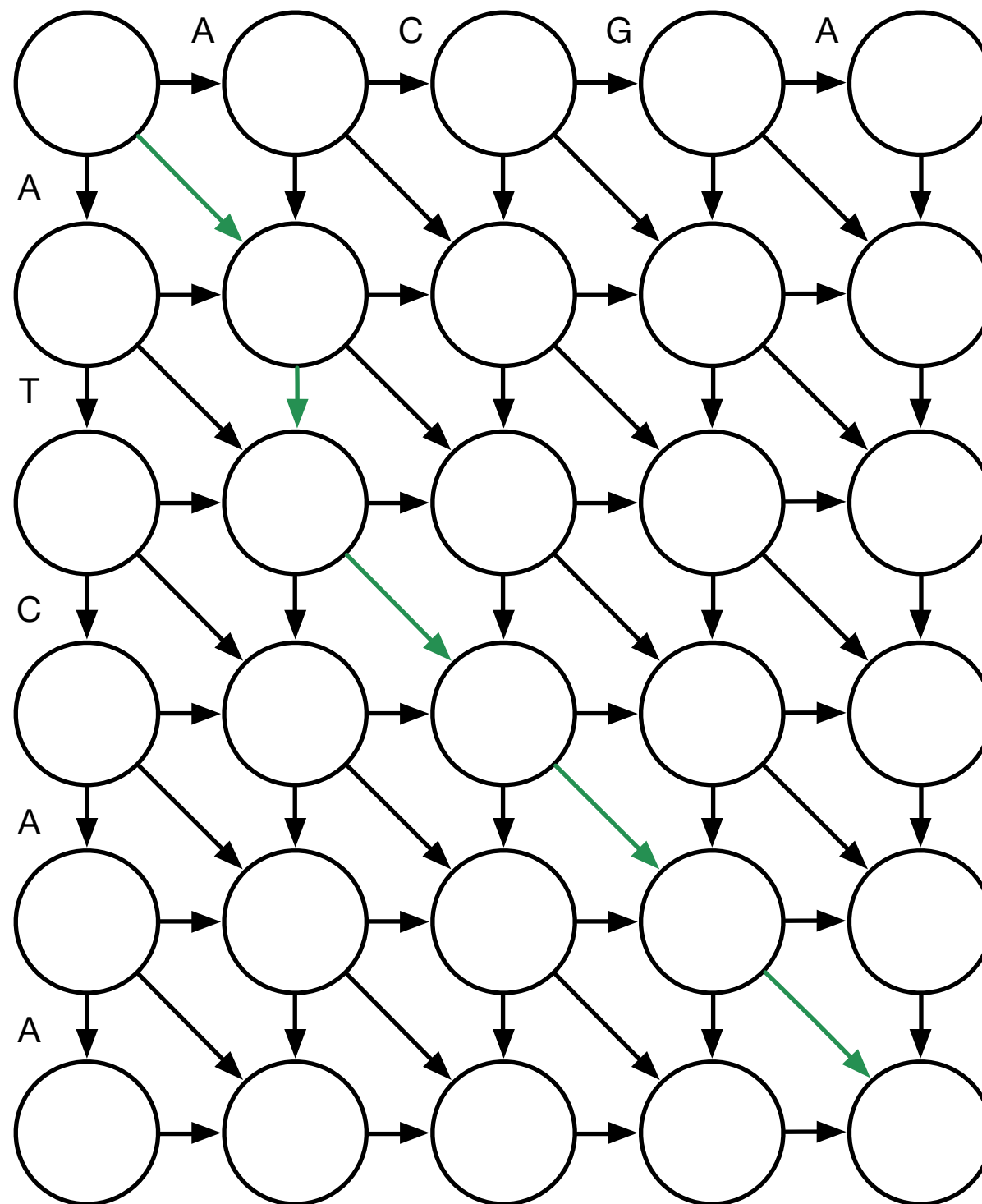
- Local alignment: extra “0” case.
- General gap penalties require 3 matrices and  $O(n^3)$  time.
- Affine gap penalties require 3 matrices, but only  $O(n^2)$  time.

# Global Alignment in Linear Space

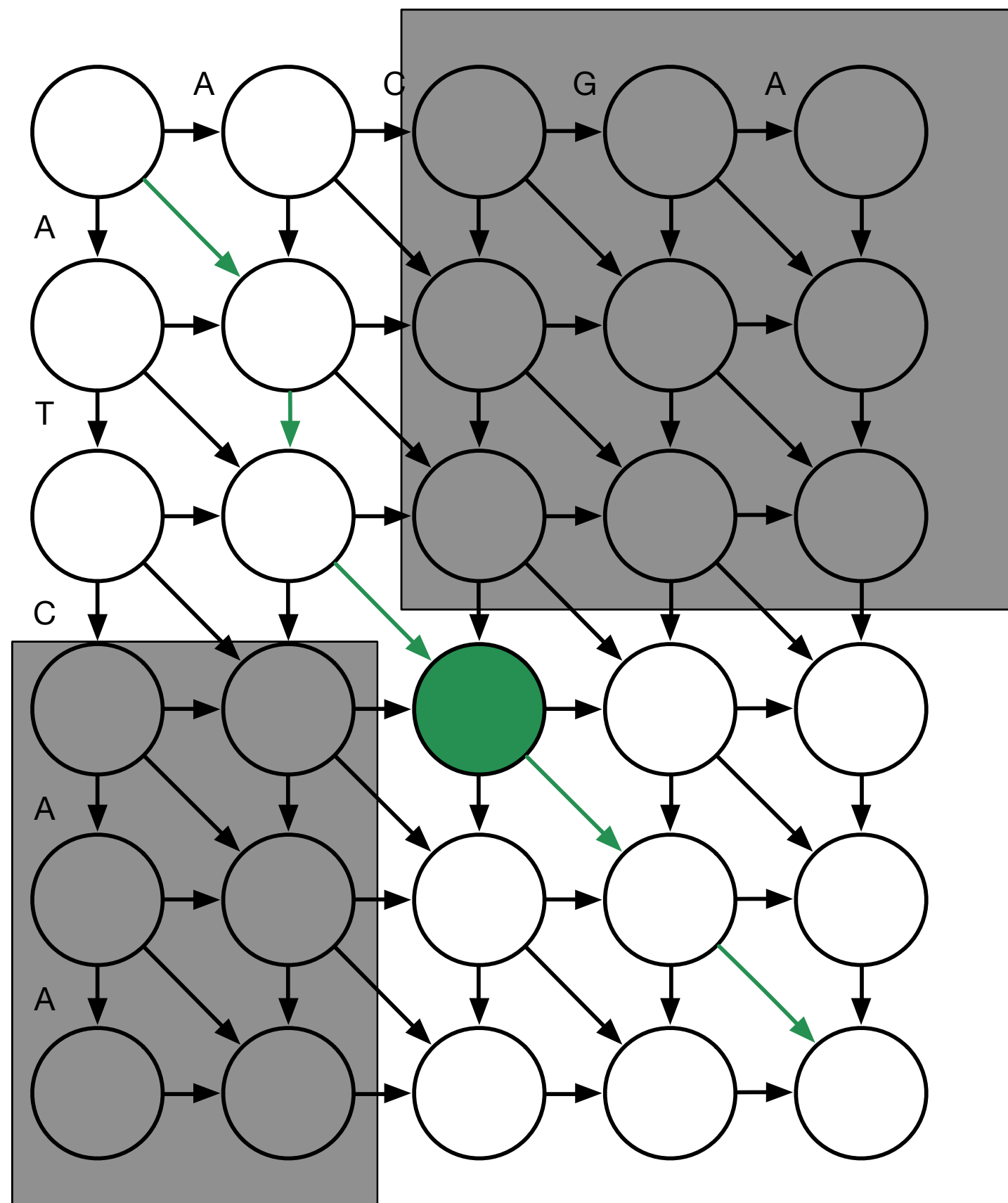
- Algorithm by Hirschberg (1975): <http://dl.acm.org/citation.cfm?doid=360825.360861>
- Recall: Dynamic programming algorithms discussed so have  $O(nm)$  time and space complexity
- Key idea:
  - We can get the optimal alignment *score* in space  $O(n)$ .
  - Can we *reconstruct* the optimal alignment in space  $O(n)$ ?

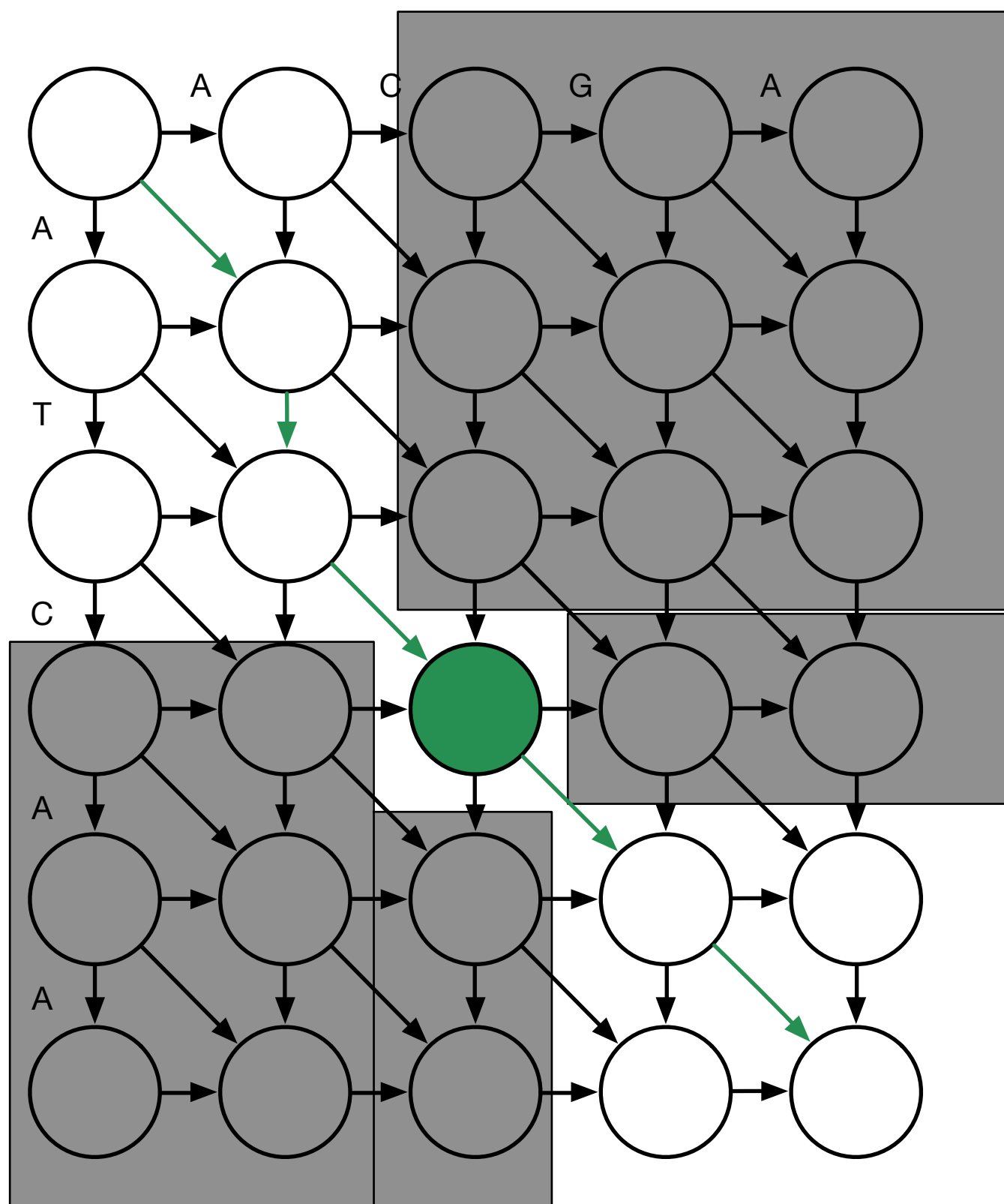
# Global Alignment in Linear Space

- Algorithm by Hirschberg (1975): <http://dl.acm.org/citation.cfm?doid=360825.360861>
- Recall: Dynamic programming algorithms discussed so have  $O(nm)$  time and space complexity
- Key idea:
  - We can get the optimal alignment *score* in space  $O(n)$ .
  - Can we *reconstruct* the optimal alignment in space  $O(n)$ ?
    - Use recursion (divide and conquer) to do reconstruction.









Score:

ATCAA

A-CGA

= Score:

ATC

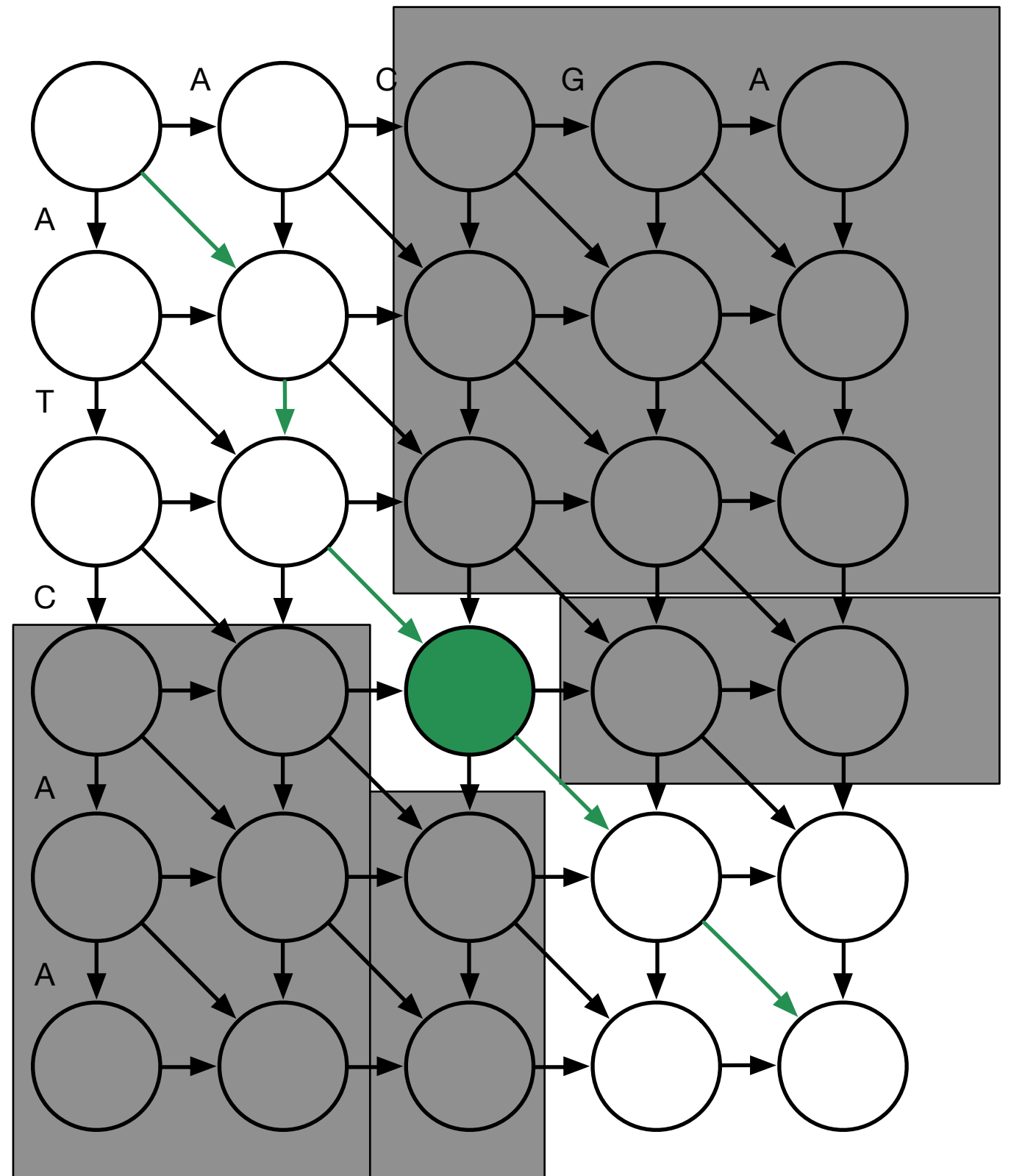
A-C

+ Score:

AA

GA

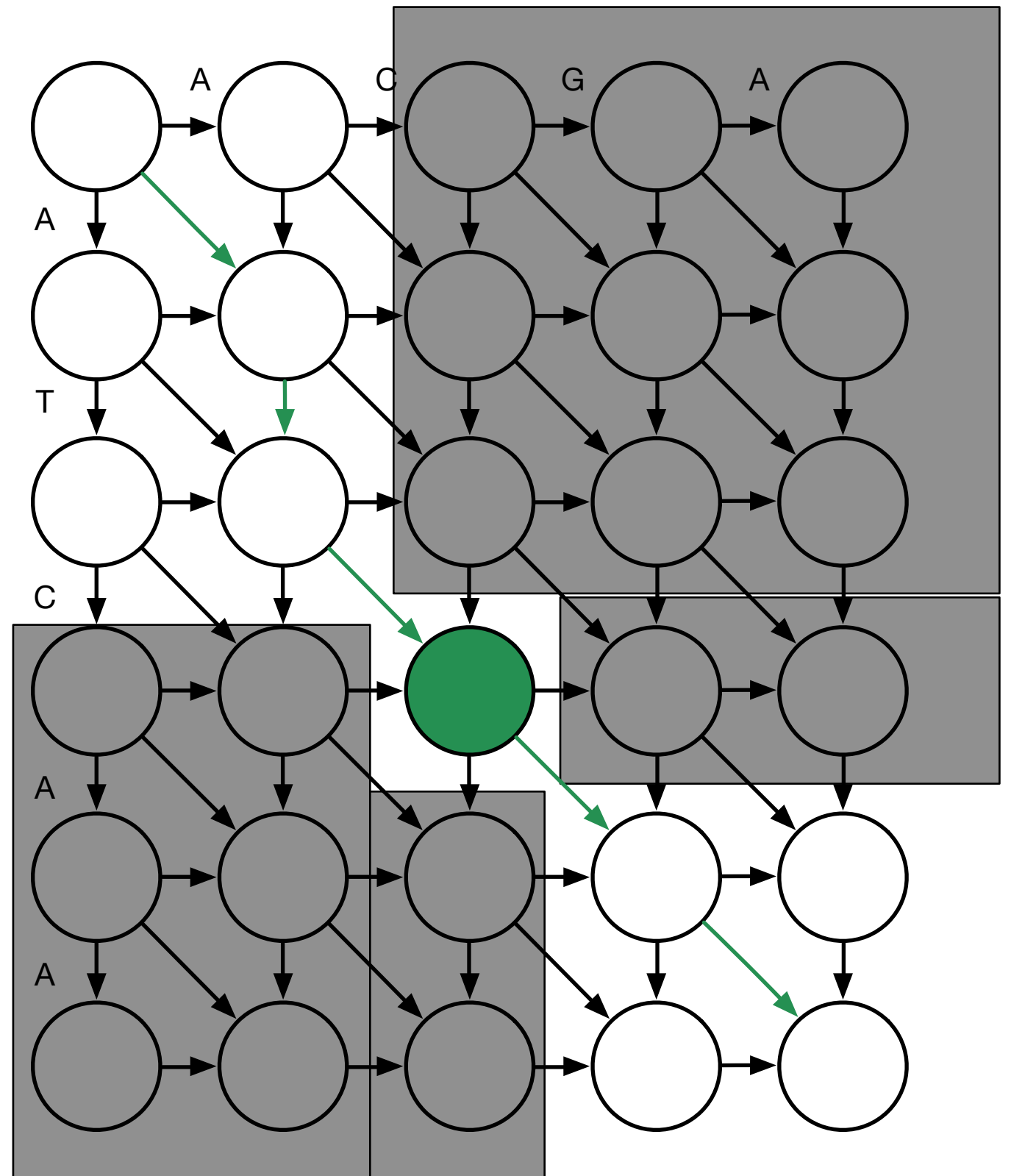
*Assuming we know  
that optimal alignment  
goes through this node*



Generally:

$$\text{SCORE}(x_{0n}, y_{0m}) = \max_t \left[ \text{SCORE}(x_{0t}, y_{0\frac{m}{2}}) + \text{SCORE}(x_{tn}, y_{\frac{m}{2}m}) \right]$$

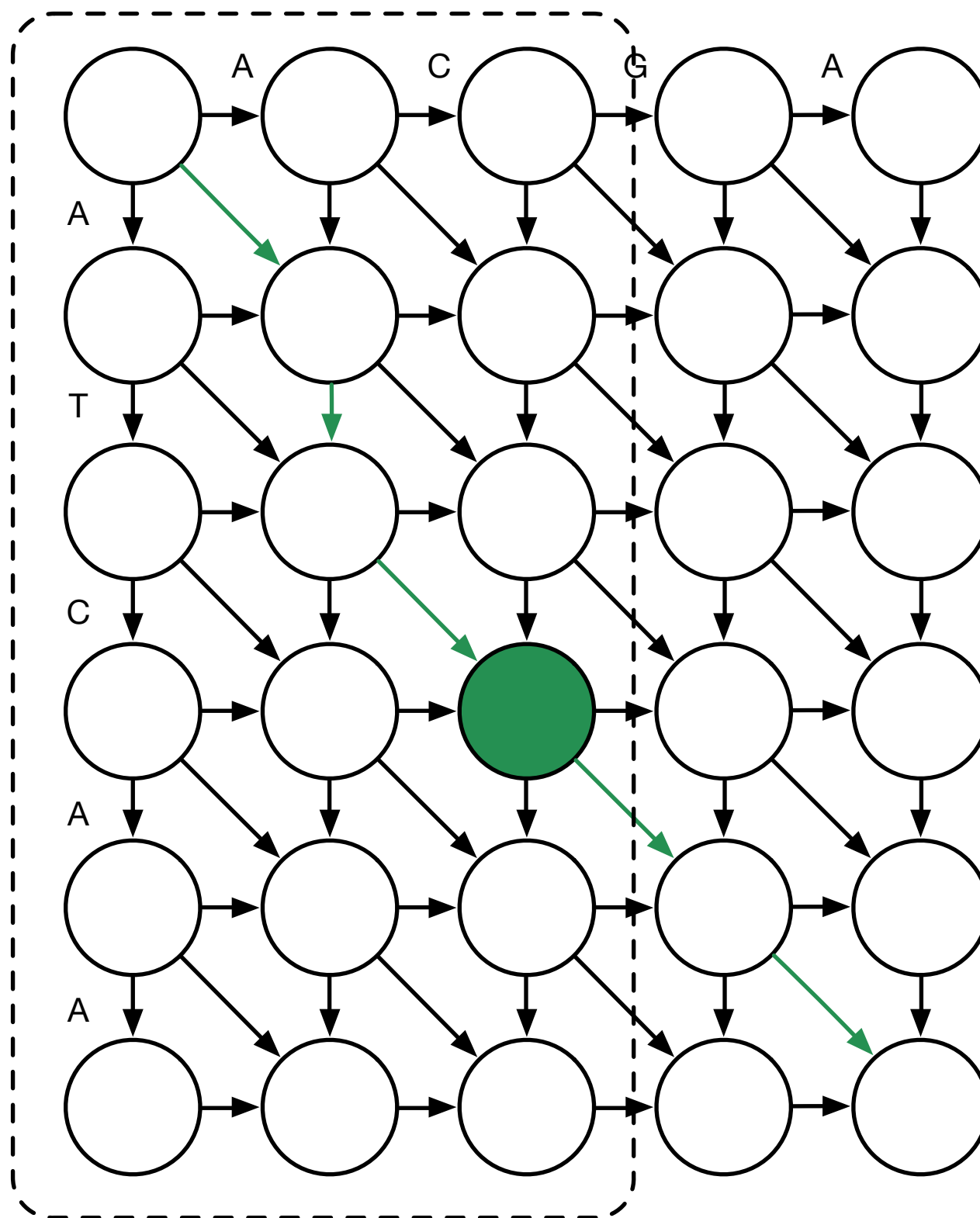
$x_{ij}$ : substring starting at position  $i$  ending at position  $j$



We know how to  
calculate first term,  
what about second term?

$$s_{n,m} = \max_t \left[ s_{t, \frac{m}{2}} + \text{SCORE}(x_{tn}, y_{\frac{m}{2}m}) \right]$$

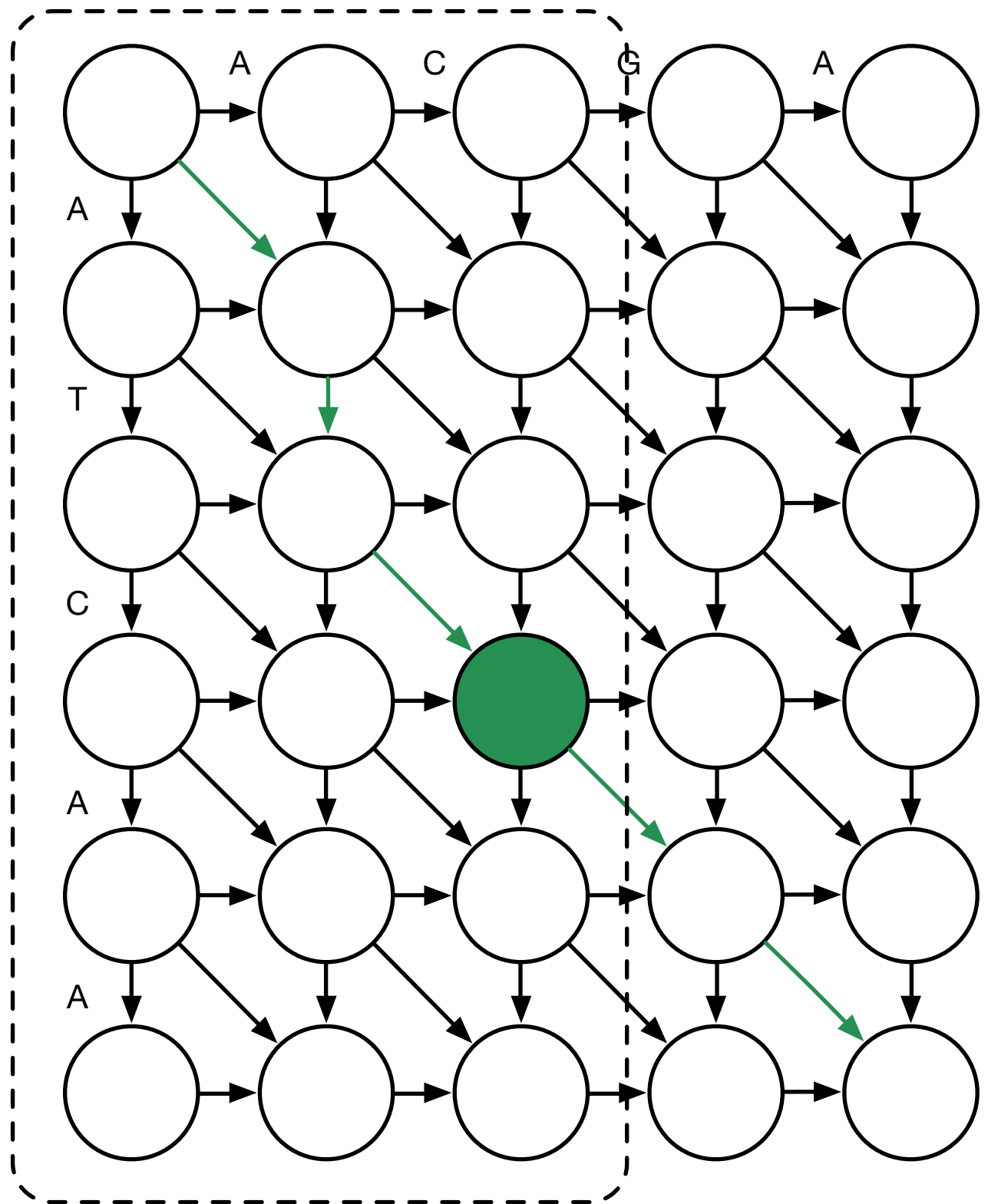
$x_{ij}$ : substring starting  
at position  $i$  ending at  
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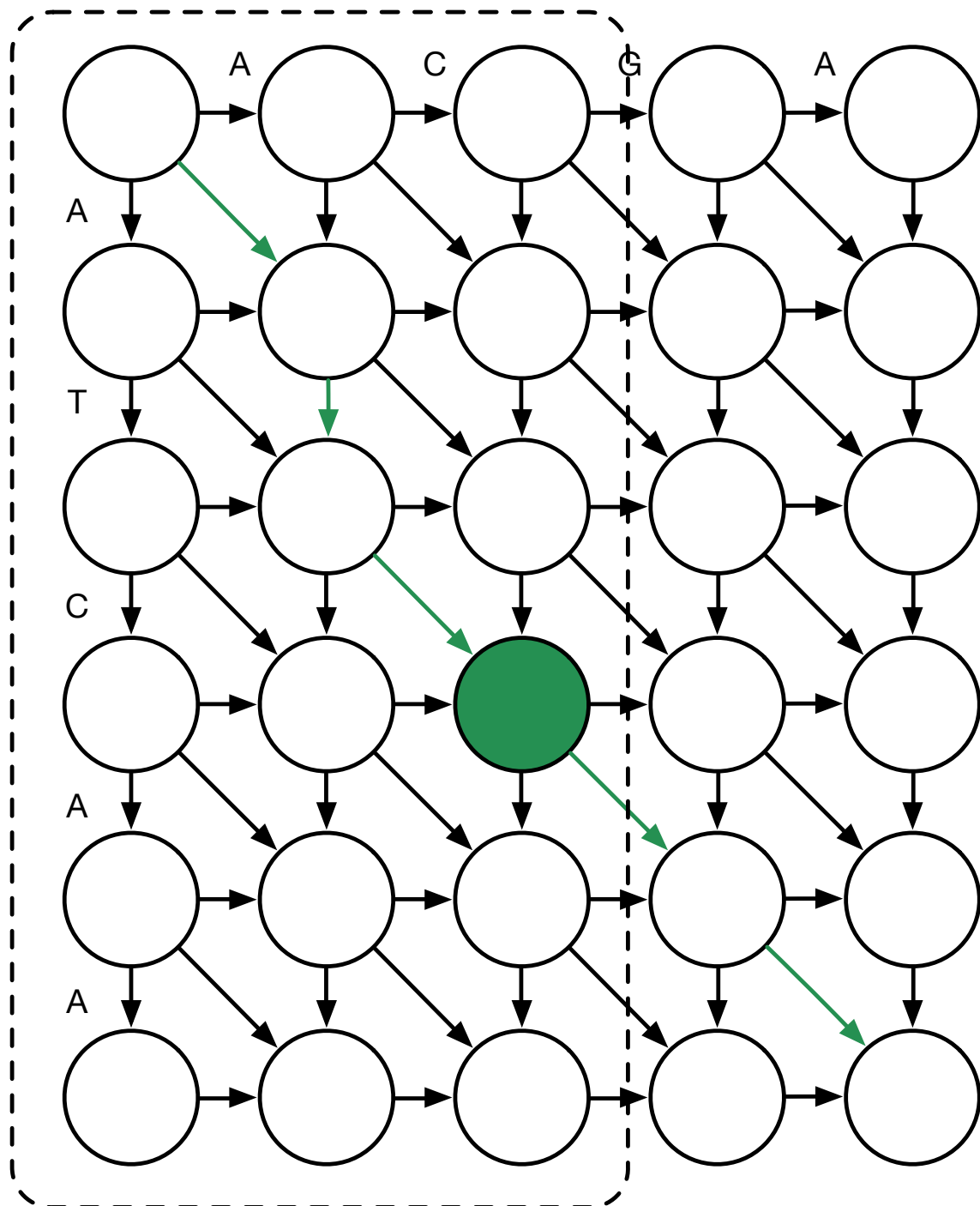


We know how to  
calculate first term,  
what about second term?

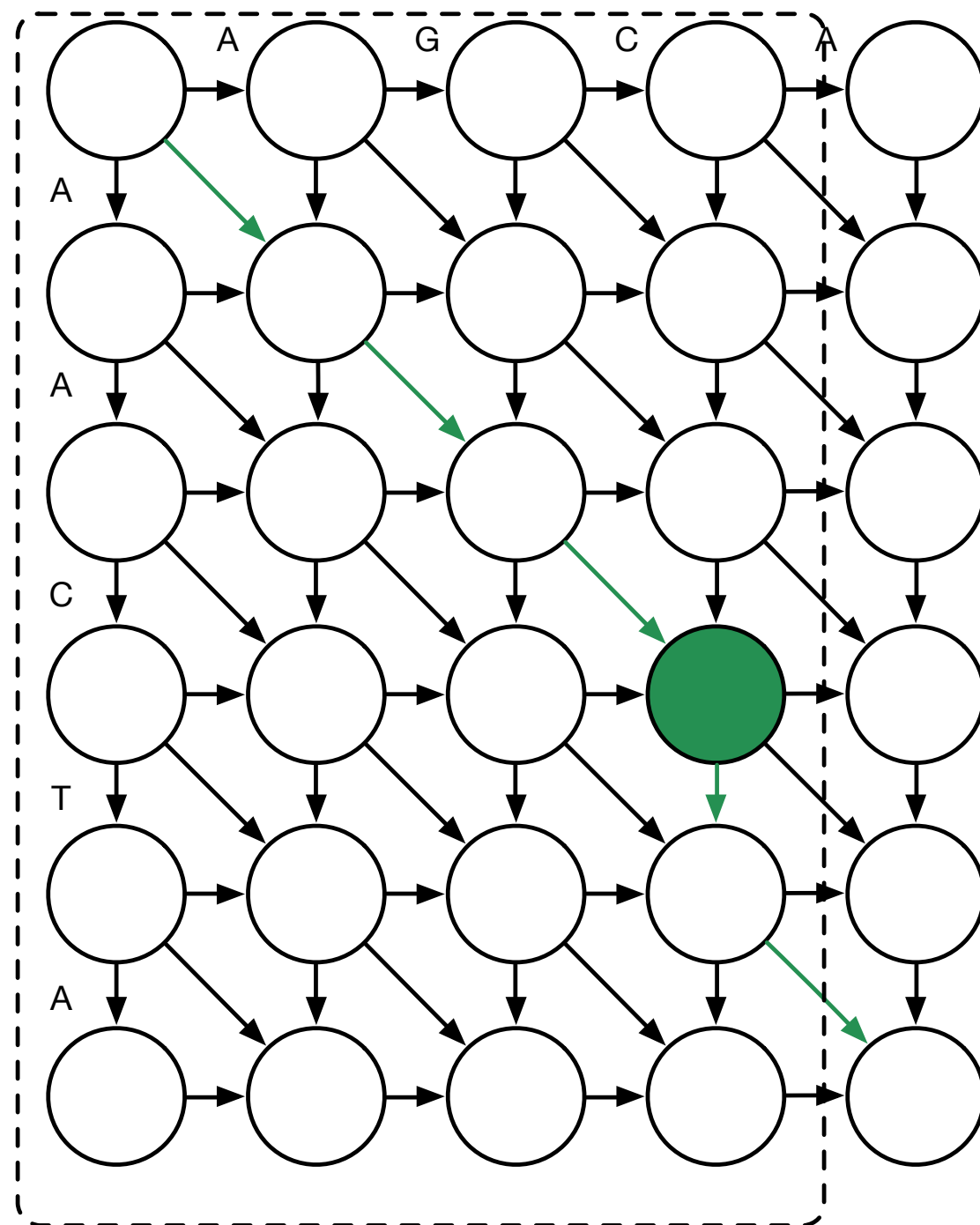
Score is invariant  
to string reversal:

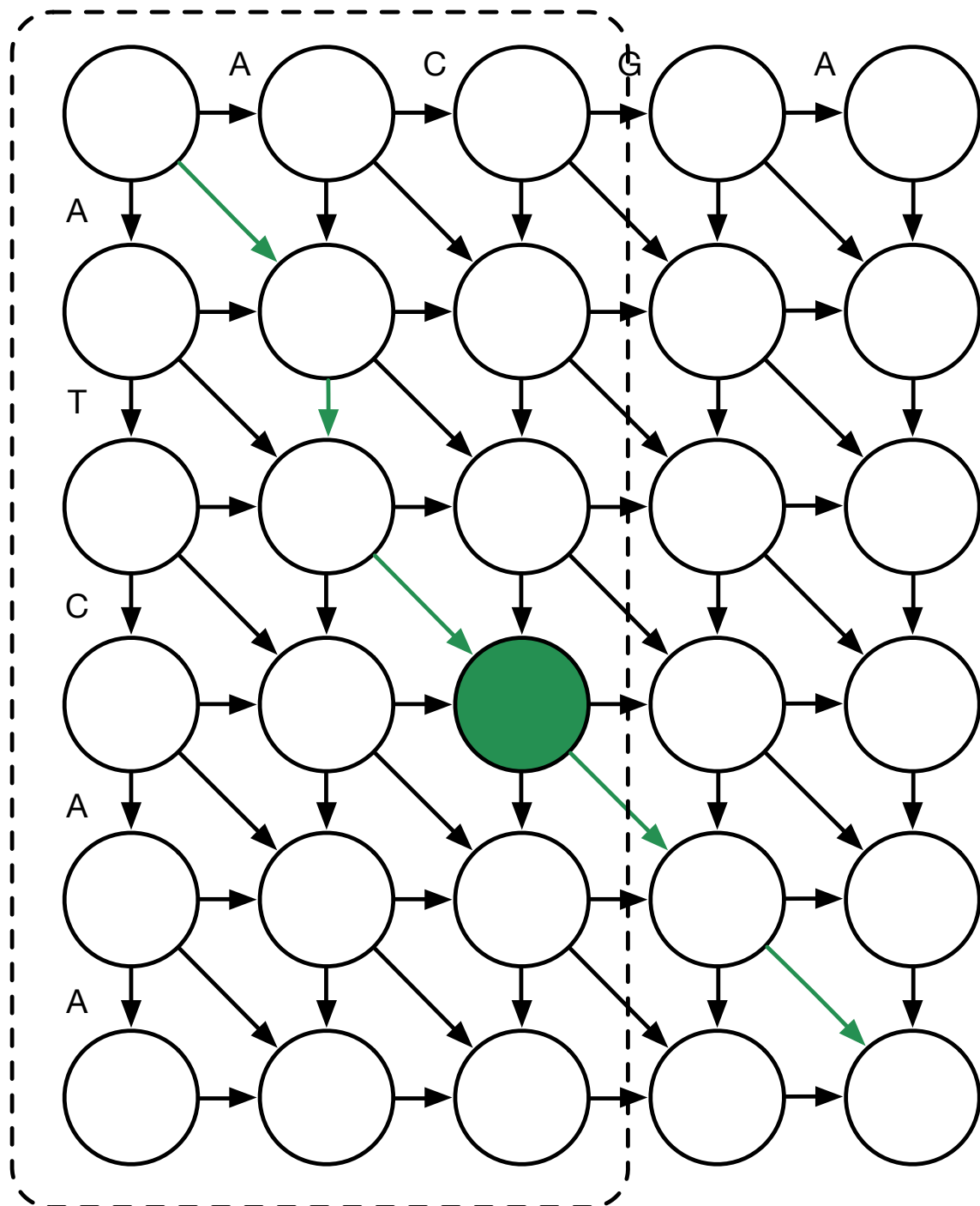
$$\text{SCORE}(x_{ij}, y_{kl}) = \text{SCORE}(x_{ji}, y_{lk})$$



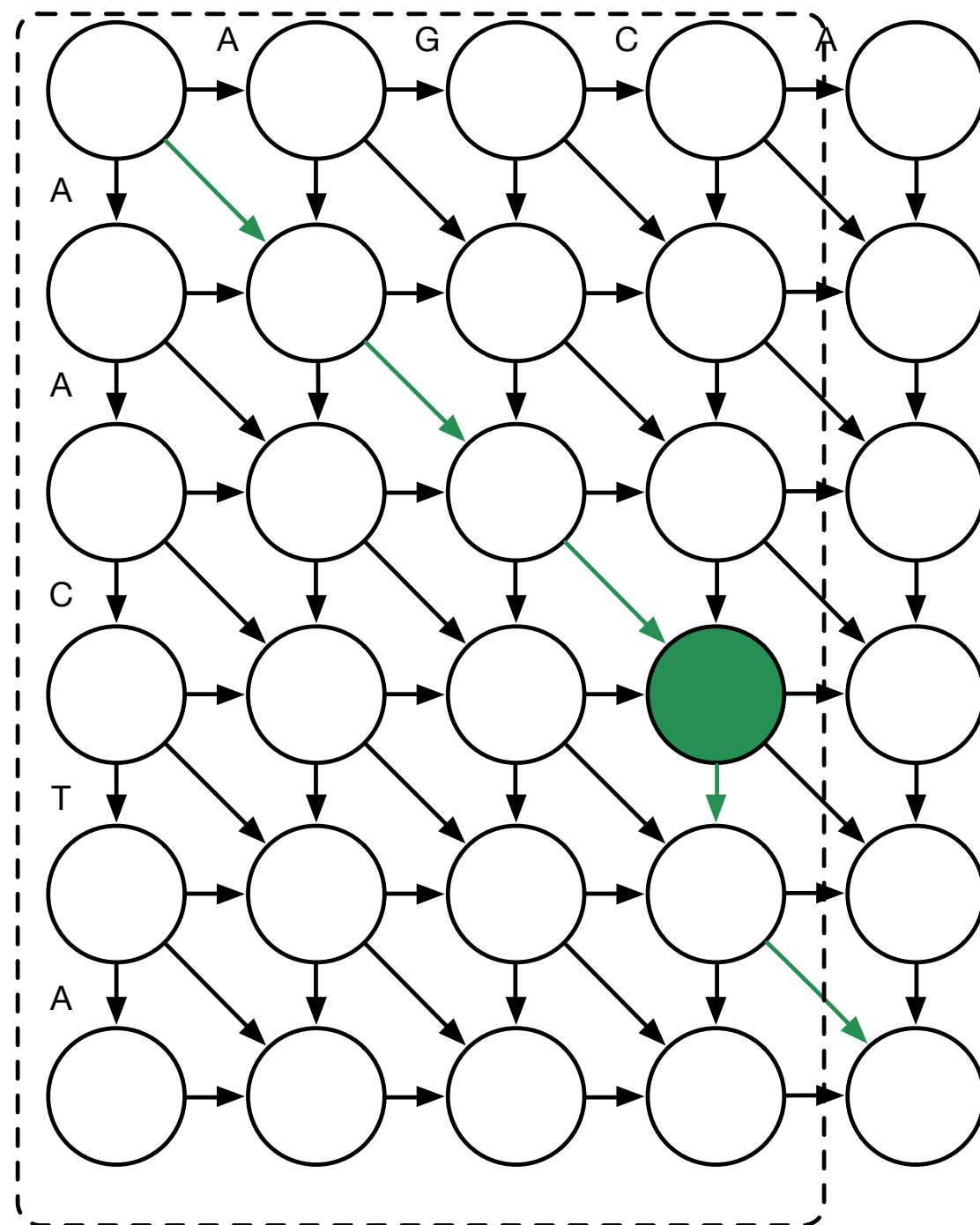


Reversed!



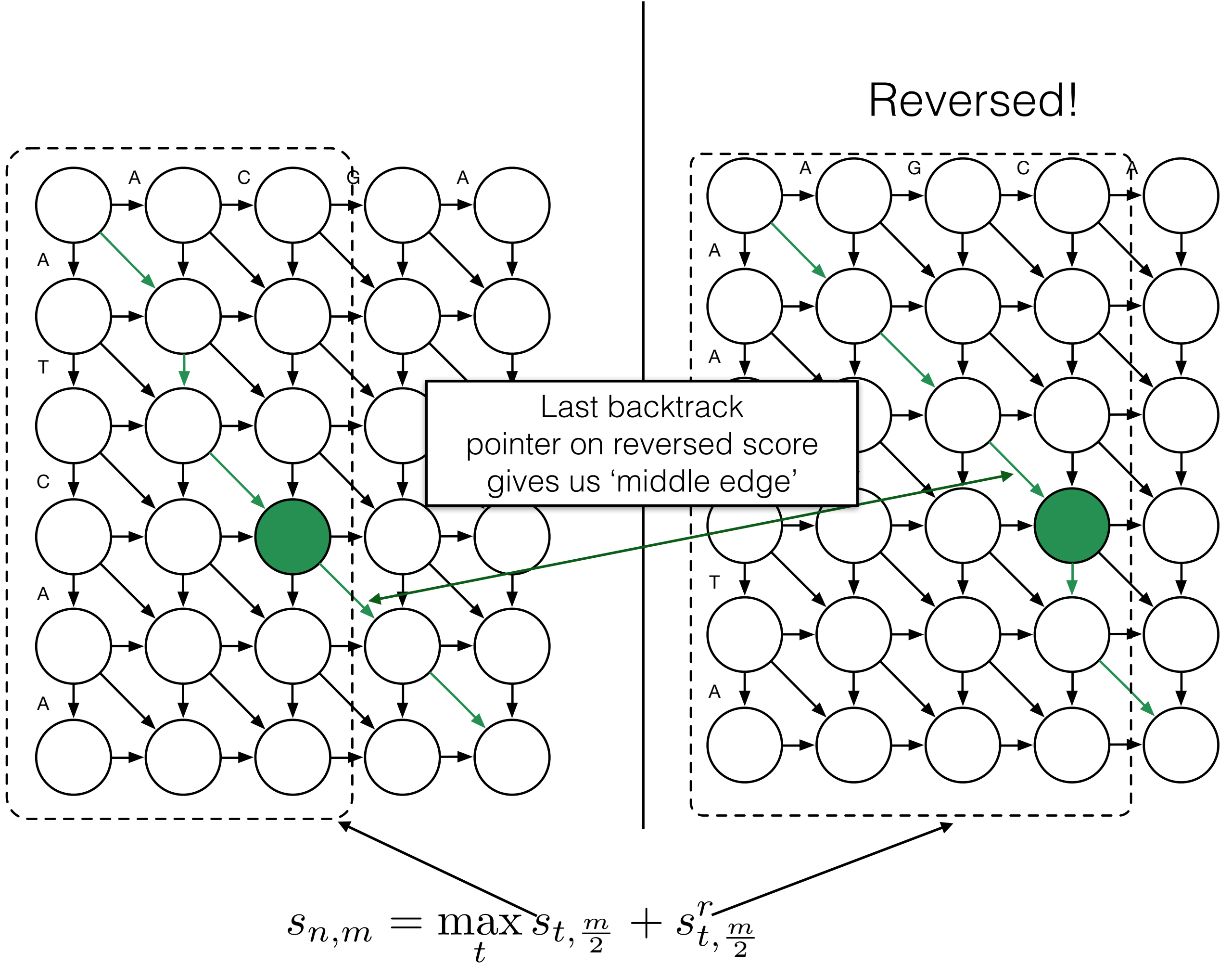


Reversed!



$$s_{n,m} = \max_t s_{t, \frac{m}{2}} + s_{t, \frac{m}{2}}^r$$





# Analysis

- Space:  $O(n)$  for two columns required to compute score
- Time:  $O(nm)$  to compute all scores (there is some  $O(n)$  double counting)
- After finding 'middle edge', we have two  $O(nm/4)$  problems:
  - solve each in linear space
  - solve each in  $O(nm/4)$  time
  - so  $O(nm/2)$  time
- Overall we have  $O(nm + nm/2 + nm/4 + nm/8 + \dots) = O(nm)$

