Gap Penalties

CMSC 423

General Gap Penalties

AAAGAATTCA
$$VS.$$
 AAAGAATTCA $AAAGAATTCA$ $AAAGAATTCA$

These have the same score, but the second one is often more plausible.

A single insertion of "GAAT" into the first string could change it into the second.

- Now, the cost of a run of k gaps is $gap \times k$
- It might be more realistic to support general gap penalty, so that the score of a run of k gaps is $gap(k) < gap \times k$.
- Then, the optimization will prefer to group gaps together.

General Gap Penalties

AAAGAATTCA
$$VS.$$
 AAAGAATTCA $AAA---TCA$

Previous DP no longer works with general gap penalties because the score of the last character depends on details of the previous alignment:

Instead, we need to "know" how long a final run of gaps is in order to give a score to the last subproblem.

Three Matrices

We now keep 3 different matrices:

M[i,j] = score of best alignment of x[1..i] and y[1..j] ending with a character-character **match or mismatch**.

X[i,j] = score of best alignment of x[1..i] and y[1..j] ending with a **space in X**.

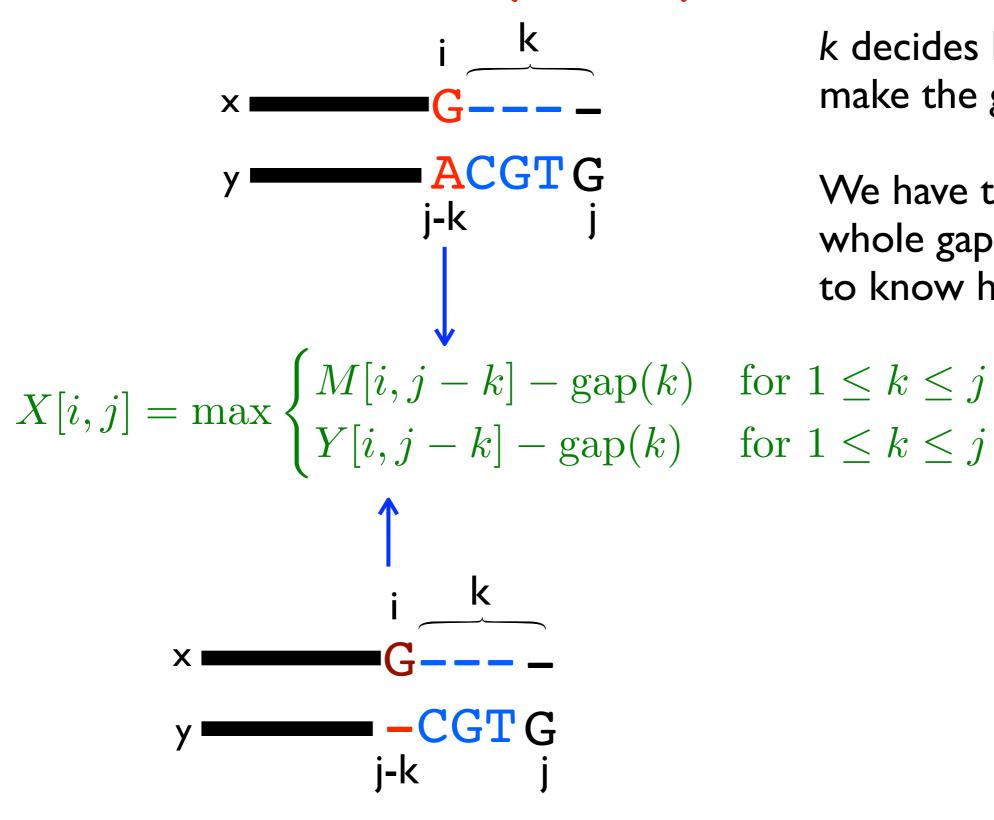
Y[i,j] =score of best alignment of x[1..i] and y[1..j] ending with a **space in Y**.

$$M[i,j] = \max \begin{cases} X[i,j] \\ M[i-1,j-1] + \text{SCORE}(x[i],y[j]) \\ Y[i,j] \end{cases}$$

$$X[i,j] = \max \begin{cases} Y[i,j-k] - gap(k) \\ M[i,j-k] - gap(k) \end{cases}$$

$$Y[i,j] = \max \begin{cases} X[i-k,j] - gap(k) \\ M[i-k,j] - gap(k) \end{cases}$$

The X (and Y) matrices



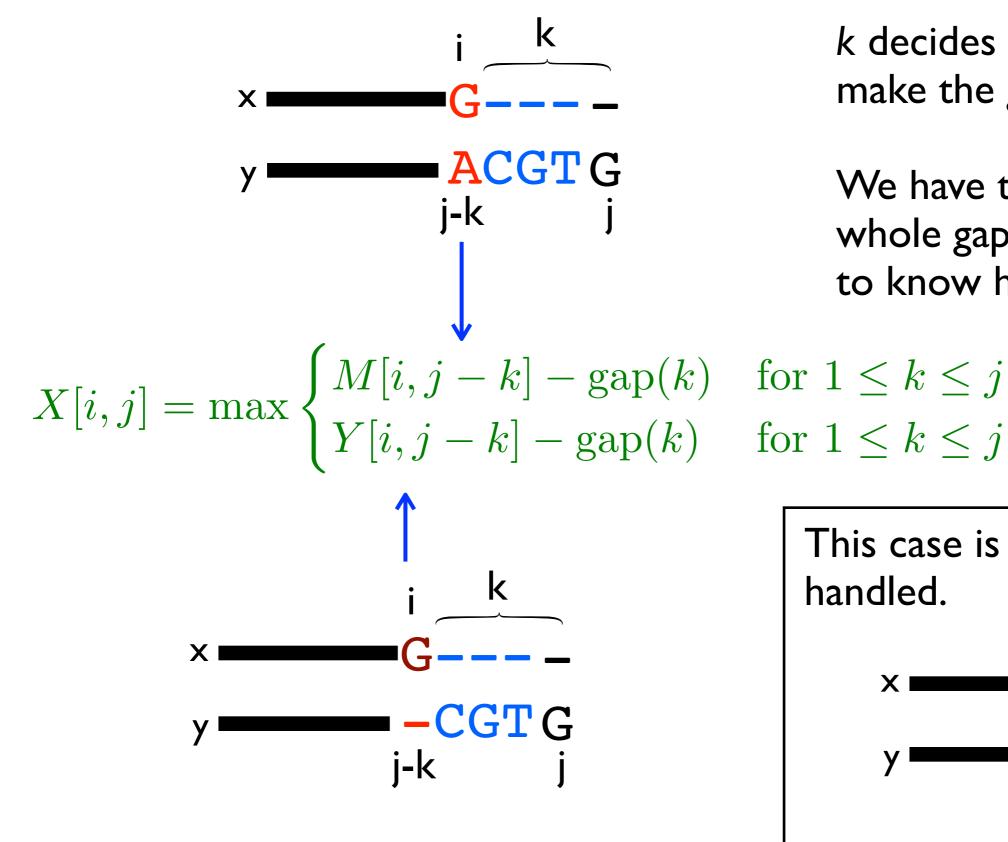
k decides how long to make the gap.

We have to make the whole gap at once in order to know how to score it.

for
$$1 \le k \le j$$

for $1 \le k \le j$

The X (and Y) matrices

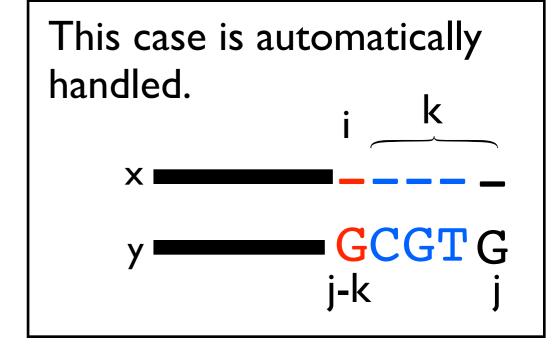


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for
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The M Matrix

We now keep 3 different matrices:

M[i,j] = score of best alignment of x[1..i] and y[1..i] ending with a character-character **match or mismatch**.

X[i,j] = score of best alignment of x[1..i] and y[1..j] ending with a **space in X**.

Y[i,j] =score of best alignment of x[1..i] and y[1..j] ending with a **space in Y**.

$$M[i,j] = \max \begin{cases} X[i,j] \\ M[i-1,j-1] + \text{SCORE}(x[i],y[j]) \\ Y[i,j] \end{cases}$$

Gaps start and end in the M matrix.

Running Time for Gap Penalties

$$M[i,j] = \max \begin{cases} X[i,j] \\ M[i-1,j-1] + \text{SCORE}(x[i],y[j]) \\ Y[i,j] \end{cases}$$

$$X[i,j] = \max \begin{cases} Y[i,j-k] - gap(k) \\ M[i,j-k] - gap(k) \end{cases}$$

$$Y[i,j] = \max \begin{cases} X[i-k,j] - gap(k) \\ M[i-k,j] - gap(k) \end{cases}$$

Final score is max {M[n,m], X[n,m],Y[n,m]}.

How do you do the traceback?

Runtime:

- Assume |X| = |Y| = n for simplicity: $3n^2$ subproblems
- 2n² subproblems take O(n) time to solve (because we have to try all k)

$$\Rightarrow$$
 O(n³) total time

Affine Gap Penalties

- $O(n^3)$ for general gap penalties is usually too slow...
- We can still encourage spaces to group together using a special case of general penalties called affine gap penalties:

gap_start = the cost of starting a gap
gap_extend = the cost of extending a gap by one more space

 Same idea of using 3 matrices, but now we don't need to search over all gap lengths, we just have to know whether we are starting a new gap or not.

$$gap(k) = -(\sigma + (k-1) * \epsilon)$$

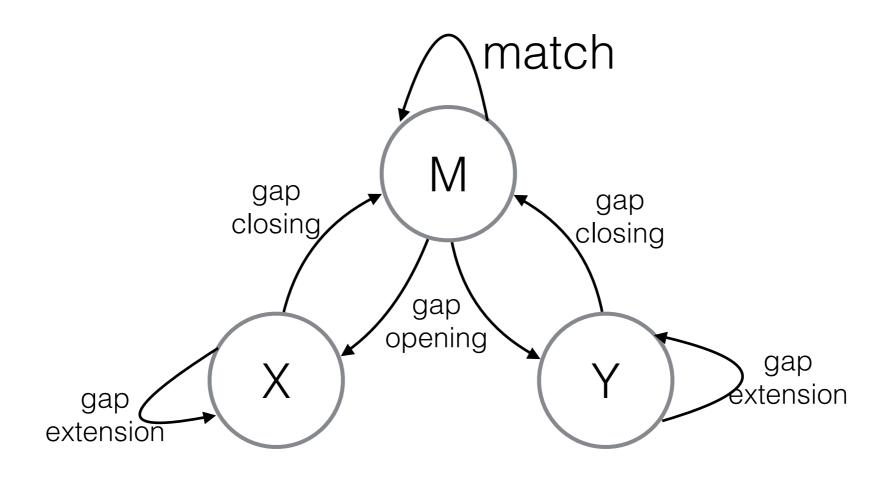
Affine Gap Penalties

$$M[i,j] = \max \begin{cases} X[i,j] \text{ gap closing} \\ M[i-1,j-1] + \text{SCORE}(x[i],y[j]) \\ Y[i,j] \end{cases}$$

$$X[i,j] = \max egin{cases} X[i,j-1] - \epsilon & \text{gap extension} \ M[i,j-1] - \sigma & \text{gap opening} \end{cases}$$

$$Y[i,j] = \max \begin{cases} Y[i-1,j] - \epsilon \\ M[i-1,j] - \sigma \end{cases}$$

Affine gap algorithm as a finite state machine



Affine Gap Runtime

- 3mn subproblems
- Each one takes constant time
- Total runtime O(mn):
 - back to the run time of the basic running time.

Traceback

- Arrows now can point between matrices.
- The possible arrows are given, as usual, by the recurrence.
 - E.g. What arrows are possible leaving a cell in the M matrix?

Recap

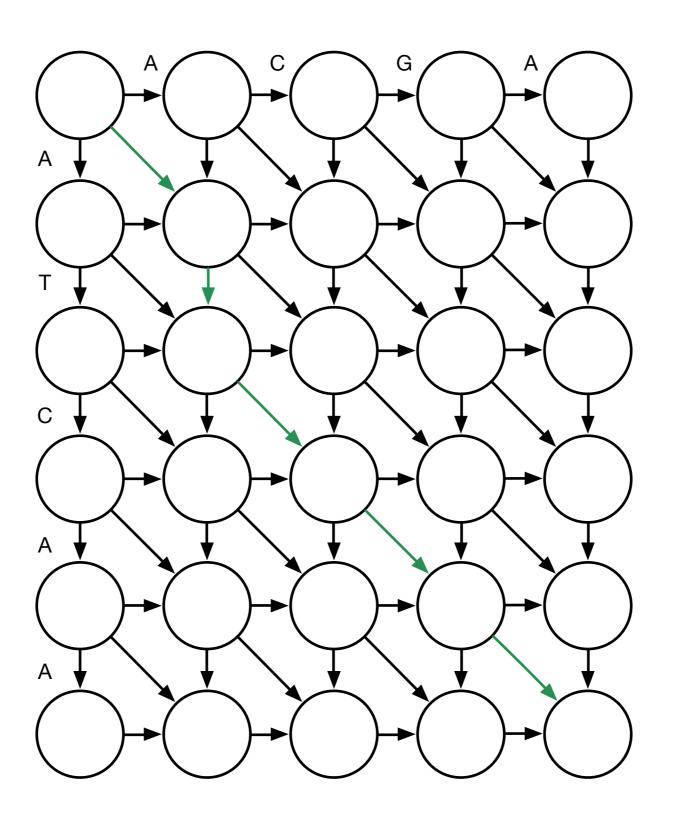
- Local alignment: extra "0" case.
- General gap penalties require 3 matrices and $O(n^3)$ time.
- Affine gap penalties require 3 matrices, but only $O(n^2)$ time.

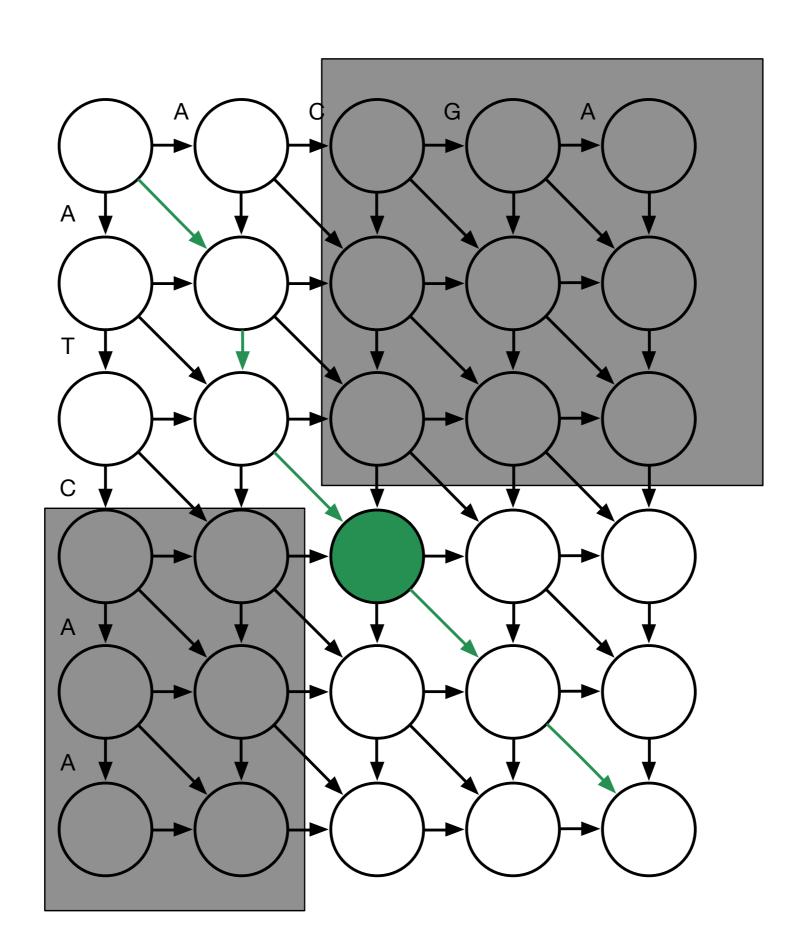
Global Alignment in Linear Space

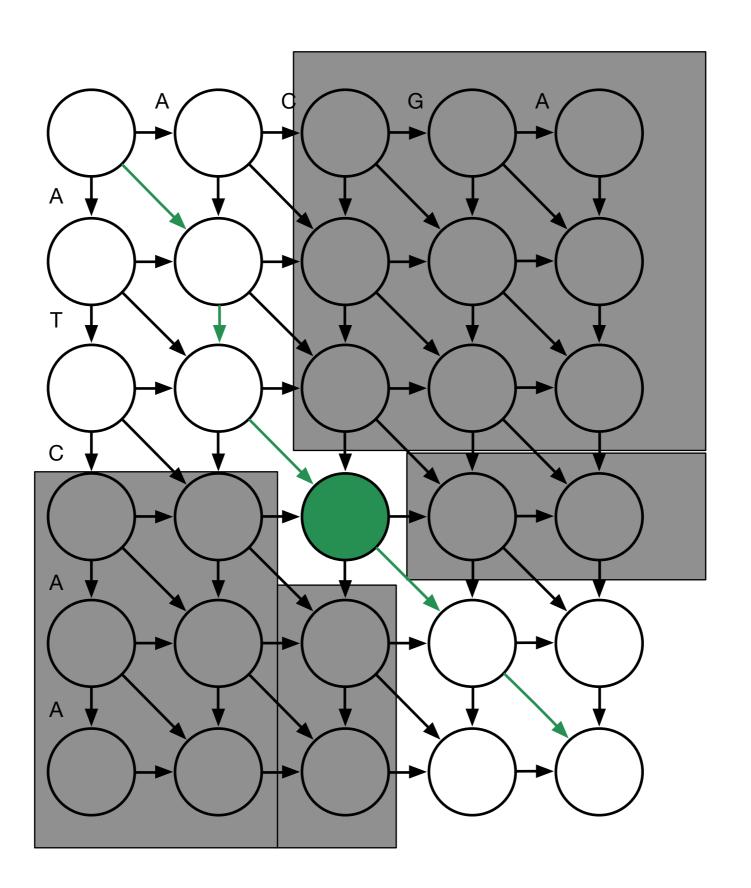
- Algorithm by Hirschberg (1975): http://dl.acm.org/citation.cfm?
 doid=360825.360861
- Recall: Dynamic programming algorithms discussed so have O(nm) time and space complexity
- Key idea:
 - We can get the optimal alignment score in space O(n).
 - Can we reconstruct the optimal alignment in space O(n)?

Global Alignment in Linear Space

- Algorithm by Hirschberg (1975): http://dl.acm.org/citation.cfm?
 doid=360825.360861
- Recall: Dynamic programming algorithms discussed so have O(nm) time and space complexity
- Key idea:
 - We can get the optimal alignment score in space O(n).
 - Can we reconstruct the optimal alignment in space O(n)?
 - Use recursion (divide and conquer) to do reconstruction.







Score:

ATCAA

A-CGA

= Score:

ATC

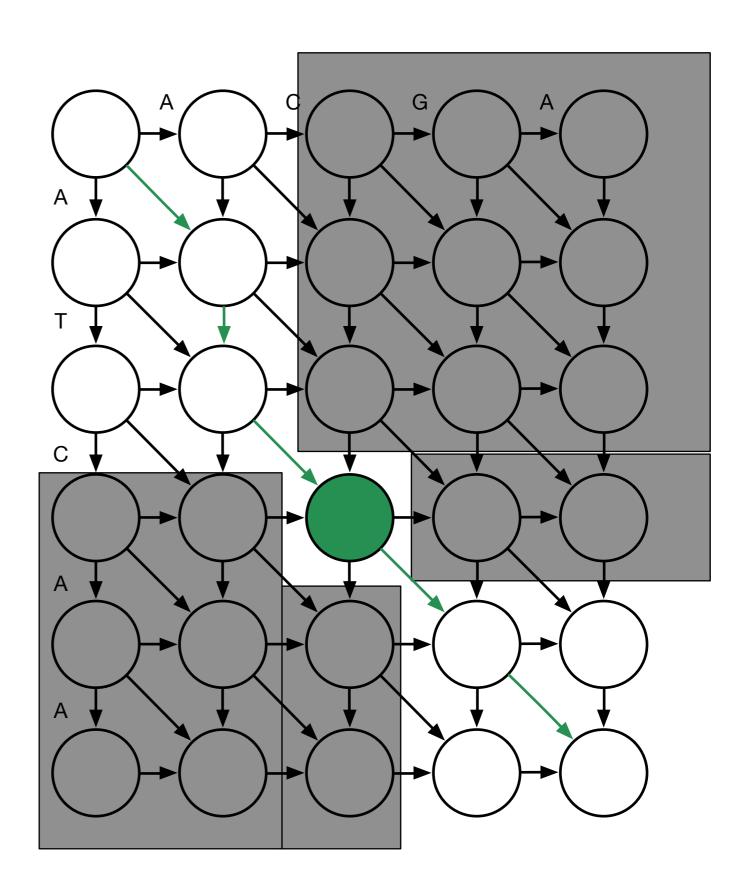
A-C

+ Score:

AA

GA

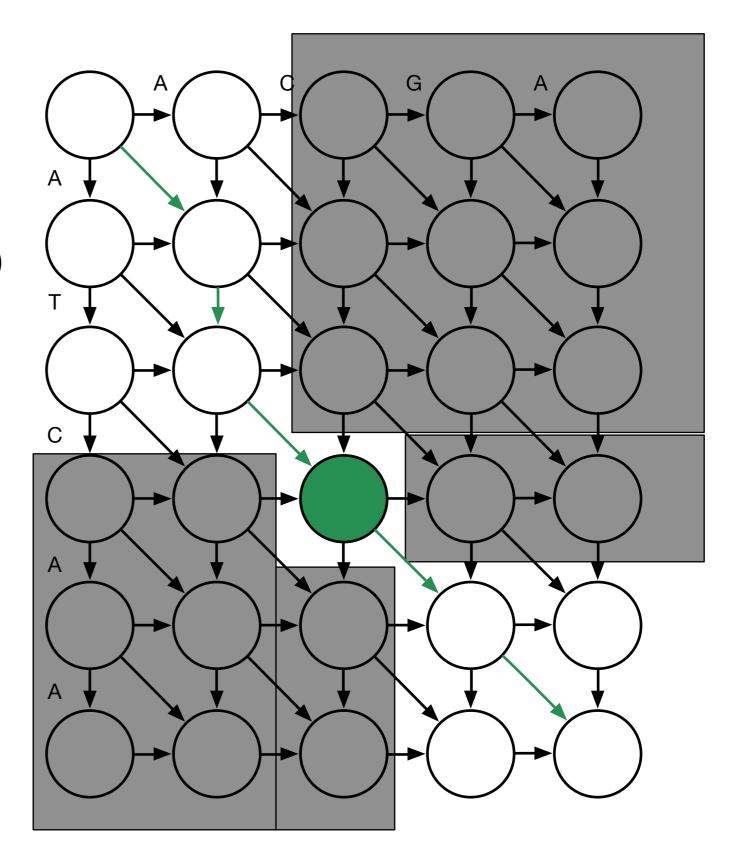
Assuming we know that optimal alignment goes through this node



Generally:

$$SCORE(x_{0n}, y_{0m}) = \max_{t} \left[SCORE(x_{0t}, y_{0\frac{m}{2}}) + SCORE(x_{tn}, y_{\frac{m}{2}m}) \right]$$

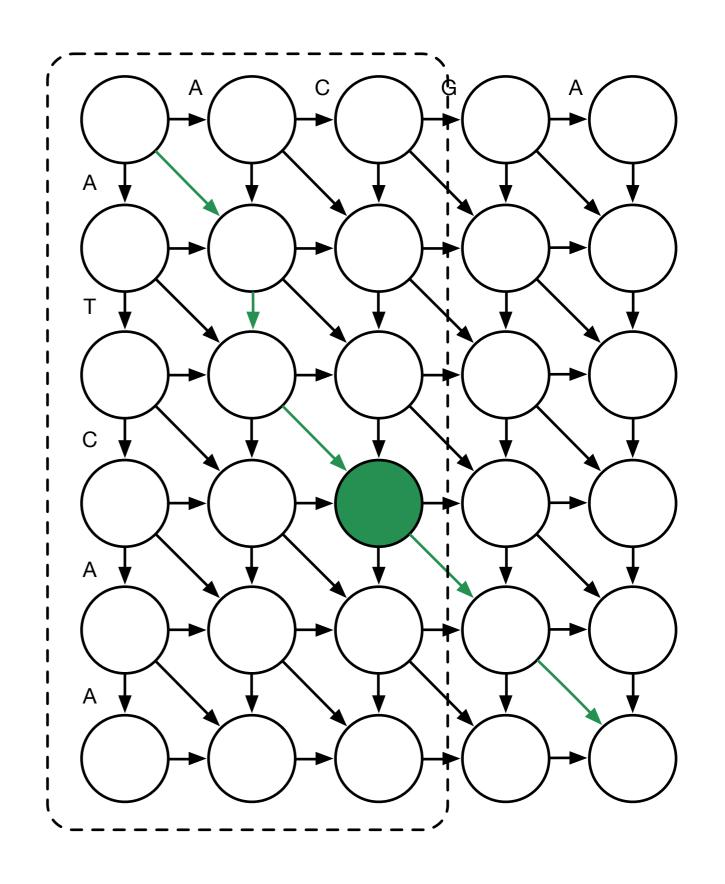
x_{ij}: substring starting at position *i* ending at position *j*



We know how to calculate first term, what about second term?

$$s_{n,m} = \max_{t} \left[s_{t,\frac{m}{2}} + \text{SCORE}(x_{tn}, y_{\frac{m}{2}m}) \right]$$

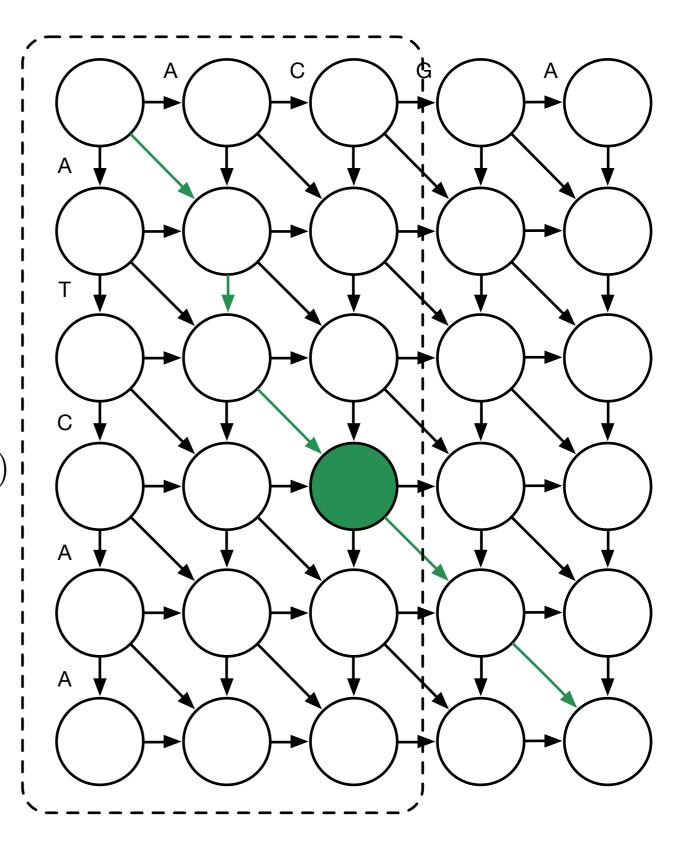
 x_{ij} : substring starting at position i ending at position j



We know how to calculate first term, what about second term?

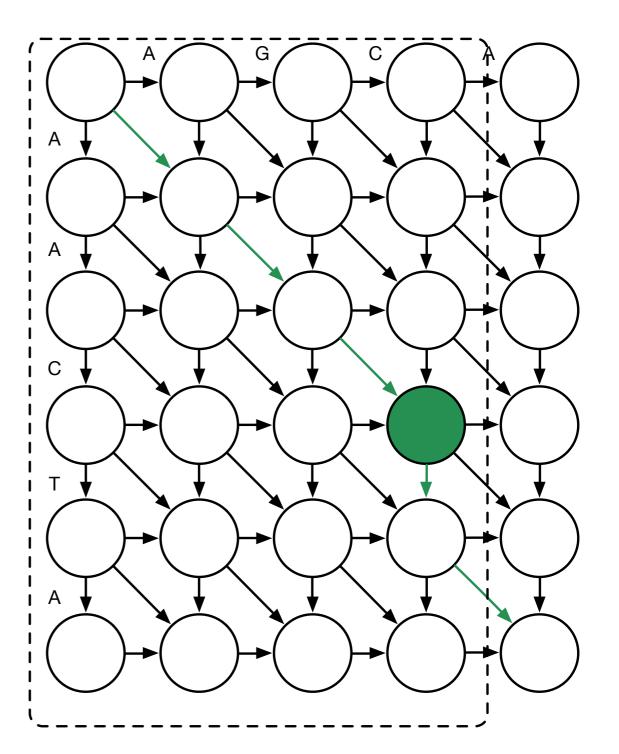
Score is invariant to string reversal:

 $SCORE(x_{ij}, y_{kl}) = SCORE(x_{ji}, y_{lk})$

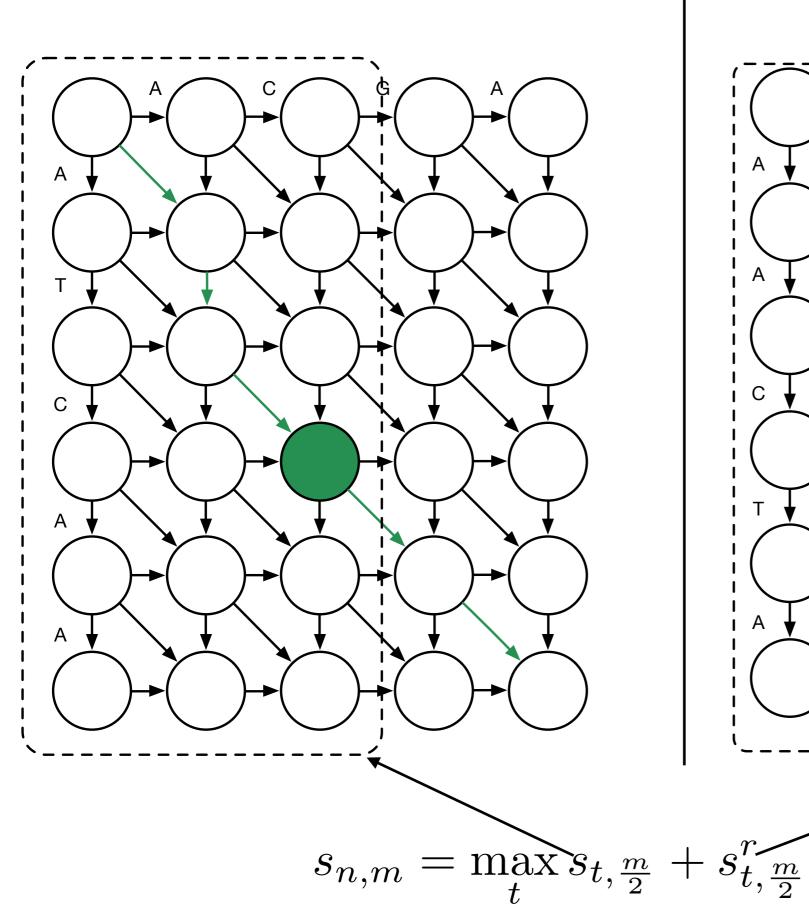


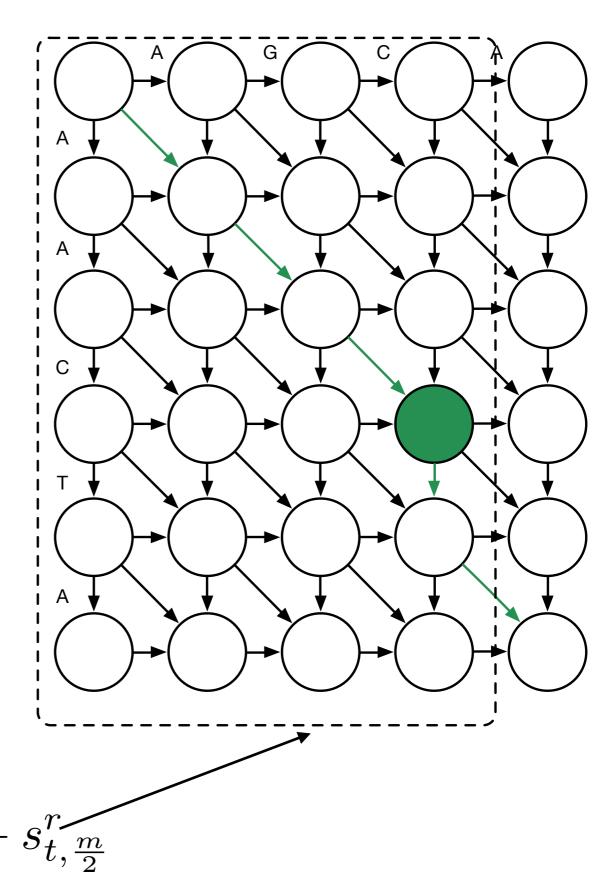
С

Reversed!



Reversed!

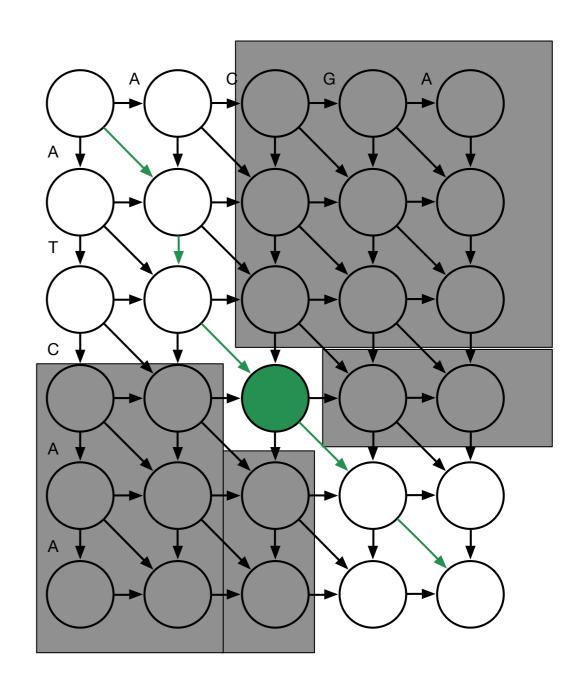




Reversed! Last backtrack pointer on reversed score gives us 'middle edge' $s_{n,m} = \max_{t} s_{t,\frac{m}{2}} + s_{t,\frac{m}{2}}^{r}$

Analysis

- Space: O(n) for two columns required to compute score
- Time: O(nm) to compute all scores (there is some O(n) double counting)
- After finding 'middle edge', we have two O(nm/4) problems:
 - solve each in linear space
 - solve each in O(nm/4) time
 - so O(nm/2) time
- Overall we have O(nm + nm/2 + nm/4 + nm/8 +...) = O(nm)



LCS Example

```
TTAACGAG
  0 0 0 0 0
T 0 1 2 2 2
A 0 1 2 3 3
A 0 1 2 3 4 4
T 0 1 2 3 4
T 0 1 2 3 4
C 0 1 2 3 4
A 0 1 2 3 4 5
```